Collective Communication

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Overview

• Introduces the most important collective communication operations within MPI

Discusses their MPI application interfaces

Collective calls I

- So far discussed: point-to-point communication
 - One sending process
 - One receiving process
- Often required: Communication in a group of processes
- Examples:
 - Distribution of simulation parameters
 - Averages of distributed data structures

Collective calls II

- All collective calls can be built up of point-to-point calls
- On a well tuned system you should not be able to beat the performance of a collective using MPI point-to-point
 - Some systems offer dedicated hardware for collectives (e.g. IBM BlueGene L and P)¹
- Whenever there is a collective: Use it
- There are no non-blocking collective calls in MPI 2.x
 - Introduced in MPI 3.0

Collective and point-to-point calls differences

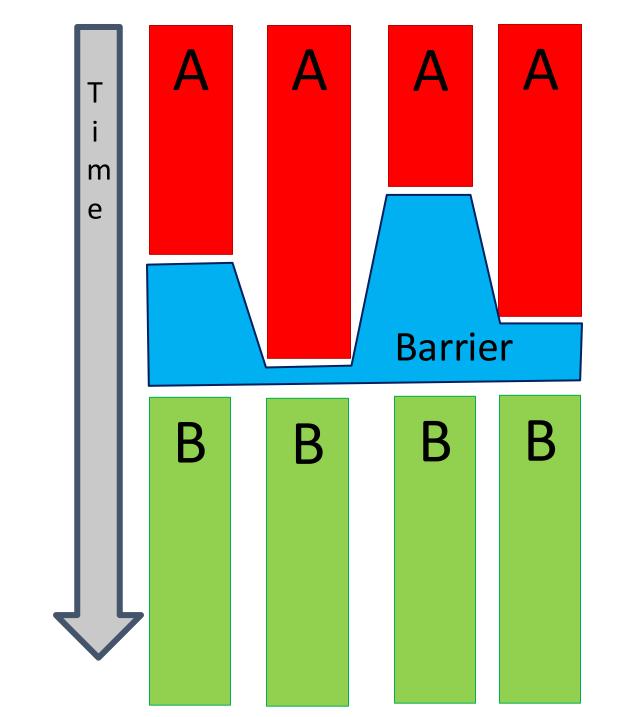
- The collective function must be called by all the processes
- Arguments passed to the collective functions by the processes need to match their counterparts (for instance, the root rank)
- Point-to-point calls use tags and communicators to establish message transfer.
 Collective calls are matched by the order in which they appear
- Don't use the same buffer for input and output

Barrier

Program (each Proc:)

```
Call calc_A()
Call barrier(comm)
Call calc_B()
```

Tasks wait in barrier until last finished
 calc A



MPI_Barrier

In C:

```
int MPI_Barrier(MPI_Comm comm)
```

In Fortran 90:

```
MPI BARRIER (COMM, IERROR)
```

INTEGER:: COMM, IERROR

In Python:

```
comm.barrier()
```

- Typically no good reason to use, except
 - Performance measurement/Benchmarking
 - Single sided communication not in this course

In C	In Fortran
#include "mpi.h"	program main
#include <stdio.h></stdio.h>	use mpi
int main(int argc, char *argv[])	implicit none
{	
int myrank, numprocs, ierr;	integer myrank, numprocs, ierr, my_comm
MPI_Comm my_comm;	call MPI_INIT(ierr)
MPI_Init(&argc,&argv);	my_comm = MPI_COMM_WORLD
my_comm = MPI_COMM_WORLD;	call MPI_COMM_RANK(my_comm, myrank, ierr)
MPI_Comm_size(my_comm,&numprocs);	call MPI_COMM_SIZE(my_comm, numprocs, ierr)
MPI_Comm_rank(my_comm,&myrank);	
	call MPI_Barrier(my_comm, ierr)
<pre>ierr = MPI_Barrier(my_comm);</pre>	
	call MPI_FINALIZE(ierr)
MPI_Finalize();	
return 0;	end
}	

In Python

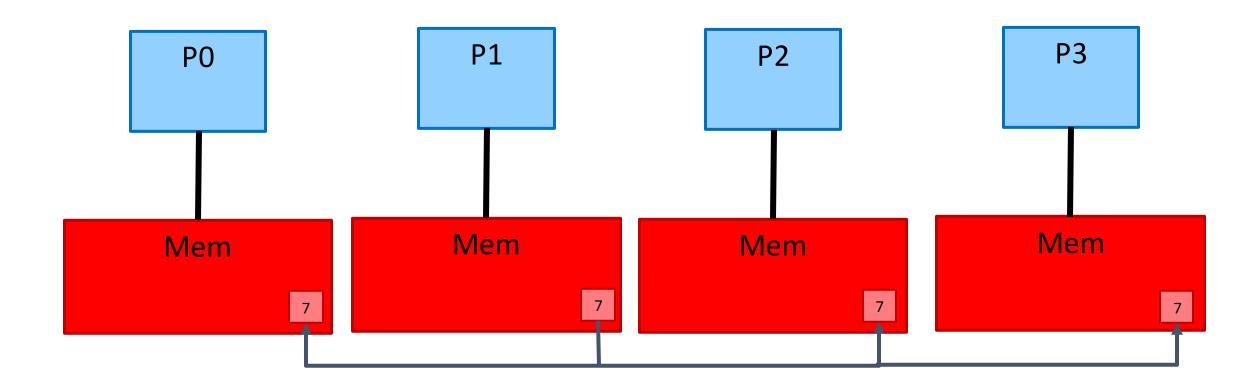
```
from mpi4py import MPI
```

```
comm = MPI.COMM_WORLD
```

```
numprocs = comm.Get_size()
myrank = comm.Get_rank()
```

comm.Barrier()

Broadcast



MPI_Bcast in C

- buf: address of buffer (send on root, receive else)
- count: number of data
- datatype: type of data
- root: root rank rank of task sending data
- comm: communicator every task in comm gets data

Remark: Depending on your rank, this is a send or receive

MPI_Bcast in Fortran 90

```
MPI_BCAST(BUF, COUNT, DATATYPE, ROOT, COMM, & IERROR)
```

<type>:: BUF

INTEGER:: COUNT, DATATYPE, ROOT, COMM, IERROR

• buf: buffer (send on root, receive else)

• count: number of data

• datatype: type of data

root: root rank – rank of task sending data

• comm: communicator – every task in comm gets data

Remark: Depending on your rank, this is a send or receive

bcast in Python

```
comm.bcast(obj, root=root)
```

- obj: the Python object to broadcast
- root: root rank rank of task sending data

Remark: Depending on your rank, this is a send or receive

The Python object will be returned by bcast. Example:

```
data = comm.bcast(data, root=0)
```

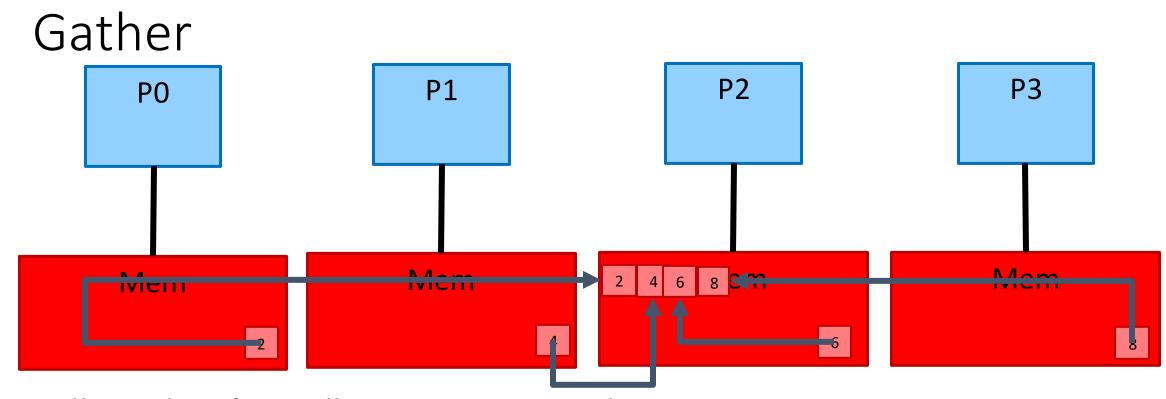
In C	In Fortran
<pre>#include "mpi.h" #include <stdio.h> int main(int argc, char *argv[]) {</stdio.h></pre>	program main use mpi implicit none
<pre>int myrank, numprocs, ierr, alpha; MPI_Comm my_comm; MPI_Init(&argc,&argv); my_comm = MPI_COMM_WORLD; MPI_Comm_size(my_comm,&numprocs); MPI_Comm_rank(my_comm,&myrank); if (myrank == 0) { printf("Type some integer\n"); scanf("%d", α); } MPI_Bcast(α, 1, MPI_INT, 0, my_comm); printf("Value of alpha on each rank %d\n", alpha); MPI_Finalize(); return 0; }</pre>	integer myrank, numprocs, ierr, alpha, my_comm call MPI_INIT(ierr) my_comm = MPI_COMM_WORLD call MPI_COMM_RANK(my_comm, myrank, ierr) call MPI_COMM_SIZE(my_comm, numprocs, ierr) if (myrank .eq. 0) then print *, 'Type some integer' read(*,*) alpha endif call MPI_BCAST(alpha, 1, MPI_INTEGER, 0, my_comm, ierr) print *, 'Value of alpha on each rank', alpha call MPI_FINALIZE(ierr) end

Lo Fo

- 0

In Python

```
from mpi4py import MPI
comm = MPI.COMM_WORLD
numprocs = comm.Get_size()
myrank = comm.Get_rank()
if myrank == 0:
  alpha = int(input("Type some integer:\n"))
else:
  alpha = None
alpha = comm.bcast(alpha, root=0)
print("Value of alpha on rank {:d} is: {:d} ".format(myrank,
alpha))
```



- Collects data from all processors into a large array on root
- Order: 1st all data from rank 0, followed by all data from rank 1, followed by all data from rank 2, ...
- This is not a scalable call think again if you want to use
 - On 10000 cores you easily run out of memory

MPI_Gather in C

```
int MPI_Gather(void* sendbuf, int sendcount, MPI_Datatype
  sendtype, void* recvbuf, int recvcount, MPI_Datatype
  recvtype, int root, MPI_Comm comm)
```

- sendbuf: address of send buffer
- sendcount: number of elements in send buffer
- sendtype: type of data
- recvbuf: address of receive buffer (only root)
- recvcount: number of data received from each task
- recytype: type of data
- root: root rank rank collecting the data
- comm: communicator every task has to send

MPI_Gather in Fortran 90

• SENDBUF: send buffer

• SENDCOUNT: number of elements in send buffer

• SENDTYPE: type of data

RECVBUF: receive buffer (significant only on root)

• RECVCOUNT: number of data received from each task

• RECVTYPE: type of data

• ROOT: root rank – rank collecting the data

COMM: communicator – every task has to send

gather in Python

```
comm.gather(obj, root=root)
```

- obj: the Python object to gather
- root: root rank rank collecting the data

A list will be returned by gather.

Example:

```
a = comm.Get_rank()
```

b = comm.gather(a, root=0)

b on the root rank is a list containing a from all MPI processes.

In C	In Fortran
<pre>root = 0; counts = 3; //nr. of elements to be sent/received size_recvbuf = counts * numprocs; //size receiving buffer //allocating receiving buffer: counts elements per rank if(myrank == 0) recvbuf = malloc(size_recvbuf * sizeof(float)); //initializing sending buffer float sendbuf[4]={1.0*myrank,2.0*myrank,3.0*myrank,4.0*myrank}; MPI_Gather(sendbuf,counts,MPI_FLOAT,recvbuf,counts,MPI_FLOA T,root,my_comm); if (myrank == 0) { for(i = 0; i < size_recvbuf; i++) printf("Array %.3f \n", recvbuf[i]); free(recvbuf); }</pre>	root = 0 counts =3 !nr. of elements to be sent/received size_recvbuf = counts * numprocs !size receiving buffer !allocating receiving buffer: 2 elements per rank if (myrank == 0) allocate(recvbuf(size_recvbuf)) !initializing sending buffer sendbuf = (/1.0*myrank,2.0*myrank,3.0*myrank,4.0*myrank /) call MPI_Gather(sendbuf,counts,MPI_REAL,recvbuf,counts,MPI_REAL,r oot,my_comm, ierr) if(myrank == 0) then do i=1,size_recvbuf print *, "Array", recvbuf(i) enddo deallocate (recvbuf) endif

In Python

```
from mpi4py import MPI
comm = MPI.COMM_WORLD
numprocs = comm.Get size()
myrank = comm.Get_rank()
send data = [1.0*myrank, 2.0*myrank, 3.0*myrank, 4.0*myrank]
send_count = 3
recv_data = comm.gather(send_data[:send_count], root=0)
if myrank == 0:
  for entry in recv_data:
    for number in entry:
      print("Array: {:.3f} ".format(number))
```

Deadlock in collectives

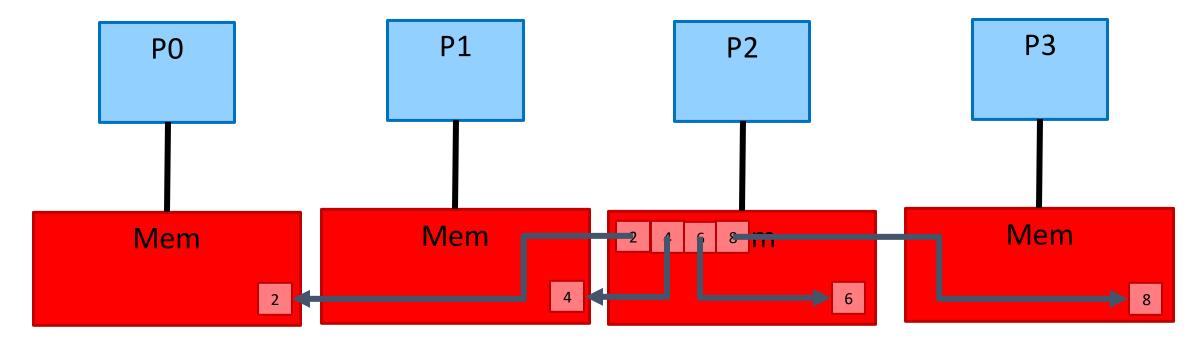
• Consider the following code snipped:

 At least on rank 6, the gather can not finish, it needs input from rank

Rank 6 will wait forever

```
if (rank /= 5) then
 call CalcA(a)
 call MPI GATHER (a, 7, &
  MPI REAL, b, 7, MPI REAL, &
  6, mcomm, merror)
else
 call CalcB(a)
endif
if (rank == 6) then
 call Vcalc(b)
endif
```

Scatter



- Distributes data from a large array on root
- Order: 1st lot of data go to rank 0, followed by all data for rank 1, followed by all data for rank 2, ...
- "Inverse" of gather
- This is not a scalable call think again if you want to use
 - On 10000 cores you easily run out of memory

MPI_Scatter in C

```
int MPI_Scatter(void* sendbuf, int sendcount,
    MPI_Datatype sendtype, void* recvbuf, int recvcount,
    MPI_Datatype recvtype, int root, MPI_Comm comm)
```

- sendbuf: address of send buffer (only root significant)
- sendcount: number of elements send to each task
- sendtype: type of data
- recybuf: address of receive buffer
- recvcount: number of data received from root
- recytype: type of data
- root: root rank rank sending the data
- comm: communicator every task receives

MPI_Scatter in Fortran 90

```
MPI_Scatter(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT,
    RECVTYPE, ROOT, COMM, IERROR)
<type>:: SENDBUF, RECVBUF
INTEGER:: SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT,
    COMM, IERROR
```

- SENDBUF: send buffer (significant only on root)
- SENDCOUNT: number of elements send to each task
- SENDTYPE: type of data
- RECVBUF: receive buffer
- RECVCOUNT: number of data received from root
- RECVTYPE: type of data
- ROOT: root rank rank sending the data
- COMM: communicator every task receives

scatter in Python

```
comm.scatter(obj, root=root)
```

- obj: The Python object (should be a list) to scatter
- root: root rank rank sending the data

obj should be a list that contains the objects to be sent to each process.

len (obj) should be equal to the number of processes.

Example:

b = comm.scatter(a, root=0)

a on the root rank should be a list containing Python objects.

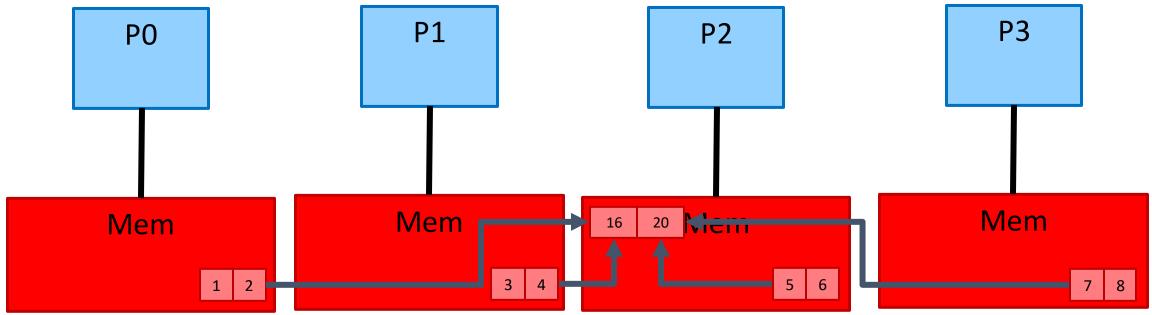
After scatter, b is the object on each process.

In C	In Fortran
float *sendbuf=NULL;	real, pointer :: sendbuf(:)
float recvbuf[4];	real recvbuf(4)
MPI_Comm my_comm;	Integer my_comm
MPI_Init(&argc,&argv);	call MPI_INIT(ierr)
my_comm = MPI_COMM_WORLD;	my_comm = MPI_COMM_WORLD
MPI_Comm_size(my_comm,&numprocs);	call MPI_COMM_RANK(my_comm, myrank, ierr)
MPI_Comm_rank(my_comm,&myrank);	call MPI_COMM_SIZE(my_comm, numprocs, ierr)
root = 0;	root = 0
counts = 3; //nr. of elements to be sent/received	counts =3 !nr. of elements to be sent/received
size_sendbuf = counts * numprocs; //size receiving buffer	size_sendbuf = counts * numprocs !size receiving buffer
if(myrank == 0) {	if (myrank == 0) then
sendbuf = malloc(size_sendbuf * sizeof(float));	allocate(sendbuf(size_sendbuf))
for(i = 0; i < size_sendbuf; i++)	do i=1,size_sendbuf
sendbuf[i] = 1.0*i;	sendbuf(i) = 1.0*i-1.0
}	enddo
NADI Conttoulous distriction and NADI FLOAT as a dest contrate NADI FLOA	endif
MPI_Scatter(sendbuf,counts,MPI_FLOAT,recvbuf,c	call MPI_Scatter (sendbuf, counts, MPI_REAL, recvbuf, counts,
T,root,my_comm);	MPI_REAL,root,my_comm, ierr)
if(myrank == 0) {	if(myrank == 0) then
free(sendbuf);	deallocate (sendbuf)
}	endif
MPI_Finalize();	Call MPI_FINALIZE(ierr)

In Python

```
from mpi4py import MPI
comm = MPI.COMM_WORLD
numprocs = comm.Get_size()
myrank = comm.Get_rank()
send count = 3
send_size = send_count * numprocs
if myrank == 0:
  send_data = []
  for i in range(numprocs):
    send_data.append([i * send_count + j for j in range(send_count)])
else:
  send_data = None
comm.scatter(send_data, root=0)
```

Reduce



- Example: Vector addition for count of 2
- Combines data from all processors into data structure on root
- This is a widely used scalable call
 - Structures on each processor task count independent

MPI_Reduce in C

```
int MPI_Reduce(void* sendbuf, void* recvbuf,
  int count, MPI_Datatype datatype, MPI_Op op,
  int root, MPI_Comm comm)
```

- sendbuf: send buffer
- recvbuf: receive buffer (significant only on root)
- count: length of send and receive buffer
- datatype: data type of data required for correct op
- op: handle of operation (more later)
- root: rank of root process
- comm: communicator, every rank contributes

Option: Constant MPI_IN_PLACE as sendbuf on root

MPI_Reduce in Fortran 90

```
MPI_REDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, ROOT, & COMM, IERROR)

<type>:: SENDBUF, RECVBUF

INTEGER:: COUNT, DATATYPE, OP, ROOT, COMM, IERROR
```

• sendbuf: send buffer

recvbuf: receive buffer (significant only on root)

• count: length of send and receive buffer

• datatype: data type of data - required for correct op

• op: handle of operation (more later)

• root: rank of root process

• comm: communicator, every rank contributes

Option: Constant MPI_IN_PLACE as sendbuf on root

Predefined reduction operations

Name	Function	MPI data types
MPI_MAX	Maximum	C integer, Fortran integer, Floating point
MPI_MIN	Minimum	C integer, Fortran integer, Floating point
MPI_SUM	Sum	C integer, Fortran integer, Floating point, Complex
MPI_PROD	Product	C integer, Fortran integer, Floating point, Complex
MPI_LAND	Logical and	C integer, Fortran logical
MPI_BAND	Bit-wise and	C integer, Fortran logical, Byte
MPI_LOR	Logical or	C integer, Fortran logical
MPI_BOR	Bit-wise or	C integer, Fortran logical, Byte
MPI_LXOR	Logical xor	C integer, Fortran logical
MPI_BXOR	Bit-wise xor	C integer, Fortran logical, Byte

reduce in Python

```
comm.reduce(obj, op=op, root=root)
```

- obj: The Python object to reduce
- op: handle of operation (more later)
- root: rank of root process

Example:

```
pi = comm.reduce(partial_pi, op=MPI.SUM, root=0)
```

Predefined reduction operations in Python

Name	Function	MPI data types
MPI.MAX	Maximum	C integer, Fortran integer, Floating point
MPI.MIN	Minimum	C integer, Fortran integer, Floating point
MPI.SUM	Sum	C integer, Fortran integer, Floating point, Complex
MPI.PROD	Product	C integer, Fortran integer, Floating point, Complex
MPI.LAND	Logical and	C integer, Fortran logical
MPI.BAND	Bit-wise and	C integer, Fortran logical, Byte
MPI.LOR	Logical or	C integer, Fortran logical
MPI.BOR	Bit-wise or	C integer, Fortran logical, Byte
MPI.LXOR	Logical xor	C integer, Fortran logical
MPI.BXOR	Bit-wise xor	C integer, Fortran logical, Byte

Quiz

Supposing that the destination rank is 0, what are the values of "b" and "d" after running the following MPI calls?

Time	Rank 0	Rank 1
0	a=0; c=2	a=1; c=3
1	MPI_Reduce(&a,&b,)	MPI_Reduce(&c,&d,)
2	MPI_Reduce(&c,&d,)	MPI_Reduce(&a,&b,)

Quiz

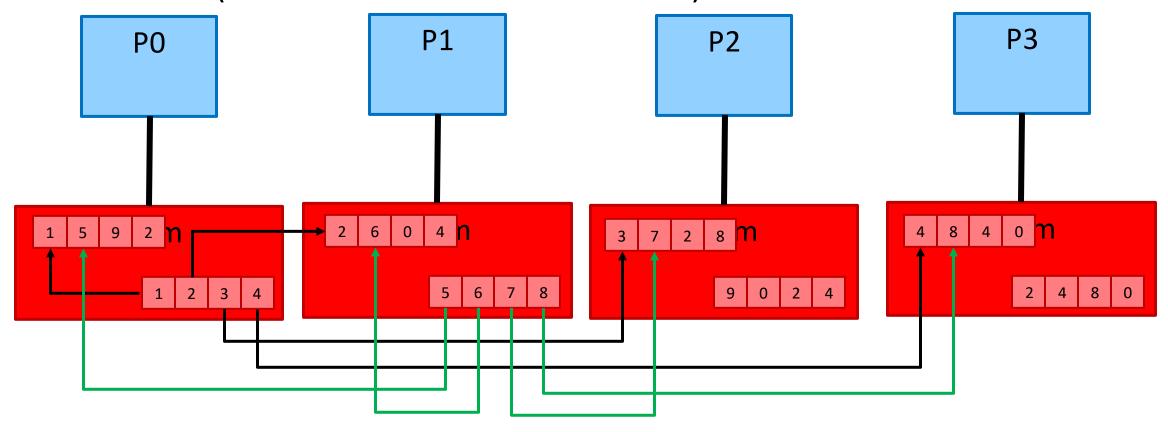
Supposing that the destination rank is 0, what are the values of "b" and "d" after running the following MPI calls?

Time	Rank 0	Rank 1
0	a=0; c=2	a=1; c=3
1	MPI_Reduce(&a,&b,)	MPI_Reduce(&c,&d,)
2	MPI_Reduce(&c,&d,)	MPI_Reduce(&a,&b,)

Solution: b=0+3=3

d=2+1=3

All-to-all (the worse of the worst)



- Every processor sends to every other processor
- 1st portion of send buffer → rank 0, 2nd portion → rank 1, etc.
- 1st portion in recv buffer \leftarrow rank 0, 2nd portion \leftarrow rank 1, etc.
- Extremely important in spectral codes, e.g. parallel FFT

MPI_Alltoall in C

```
int MPI_Alltoall(void* sendbuf, int sendcount,
    MPI_Datatype sendtype, void* recvbuf, int recvcount,
    MPI_Datatype recvtype, MPI_Comm comm)
```

- sendbuf: Address of send buffer
- sendcount: Number of elements send from each task
- sendtype: Data type of send buffer
- recybuf: Address of receive buffer
- recycount: Number of elements received f. each task
- recytype: Data type of receive buffer
- comm: Communicator, every task sends and recvs

Rem: The counts are <u>not</u> the buffer size!

MPI_Alltoall in Fortran 90

```
MPI_ALLTOALL(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF,
    RECVCOUNT, RECVTYPE, COMM, IERROR)
    <type>:: SENDBUF, RECVBUF
    INTEGER:: SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, COMM,
    IERROR
```

• sendbuf: Address of send buffer

• sendcount: Number of elements send form each task

• sendtype: Data type of send buffer

• recybuf: Address of receive buffer

• recycount: Number of elements received f. each task

• recytype: Data type of receive buffer

• comm: Communicator, every task sends and recvs

Rem: The counts are <u>not</u> the buffer size!

alltoall in Python

```
comm.alltoall(obj)
```

• obj: The Python object (should be a list)

obj should be a list that contains the objects to be sent to each process. len (obj) should be equal to the number of processes.

Example:

b = comm.alltoall(a)

a should be a list containing Python objects.

After scatter, b is a list containing the result of alltoall operation.

Variations: Allgather and Allreduce

- The are "All" versions for calls which receive only on root:
 - MPI Allgather (or comm.allgather in Python)
 - MPI Allreduce (or comm.allreduce in Python)
- Every task has a receive buffer the result is know on every task
- These calls can be thought of as
 - MPI_Gather followed by MPI_Bcast
 - MPI_Reduce followed by MPI_Bcast
- The **root** argument is omitted from the interface
- "All"-communications can take longer to complete
 - Only use them if you need them

Advanced topic: Vector collectives

The calls of this lecture: Same count on all tasks

- Vector collectives relax this condition:
 - MPI Gatherv
 - MPI Scatterv
 - MPI Allgatherv
 - MPI_Alltoallv
- These calls go beyond the scope of this course

Non blocking collectives in MPI 3.x

- Similar to non-blocking point-to-point communication:
 - Non-blocking call (e.g. MPI Ibcast) initiates communication
 - A completion call (e.g. MPI_Wait) ensures that local part of communication is finalised
 - Send buffers can be overwritten
 - Receive buffers contain data

Allows for

- Overlapping communication and calculation
- Avoiding synchronisation if MPI library avoids sync.
 - The call **MPI_Ibarrier** has to avoid synchronisation
- Avoiding dead locks (e.g. overlapping communicators)

Summary

- Discussed collective communications:
 - Barrier
 - Broadcast
 - Gather/Scatter
 - Reduction
 - Alltoall
- Variations of the above (all-version, vector-version)
- Non-blocking collective communication in MPI 3.0

Exercise 1

Create a version of your π^2 -code using collective calls

- Time the communication times
- Compare performance of the versions using
 - Point-to-point
 - Collectives

Remarks:

- You might need a barrier in the beginning of your code to absorb differences in "task wake up"
- You might need to run repeatedly

Exercise 2

Modify your *messages around a ring* code to use a collective to add the send-buffers onto rank 0

Compare the performance with original code

Exercise 3. 2D Integration

In this example, you will calculate the double integral:

$$\int_0^\pi \int_0^\pi \sin(x+y) dx dy = 0$$

One way to parallelize this calculation is to divide the integration range of one variable, let's say "x", evenly among N processes and perform the regular integration over the other variable, "y", in this case.

This problem is useful for two reasons: first, we know the exact value of the integral (0), and second, because it includes a double integral, the computation is sufficiently heavy to detect the effects of a parallel implementation.