

1 Example Applications of Pool Models

2 Reducing Model Complexity

- The Carbon Cycle example
- Asking Simpler Questions
- Answer Questions more simply

3 Compartmental Systems

4 Generalization to non Well Mixed Systems

- Population Dynamics

Pool Models

An Introduction

Markus Müller, Holger Metzler, Carlos Sierra

August 13, 2019

Max Planck Institute
for Biogeochemistry



- What are pool models?
- Why do we need them?
- What can they be used for?
 - ▶ What is needed?
 - ▶ What can we learn from them?

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Outline

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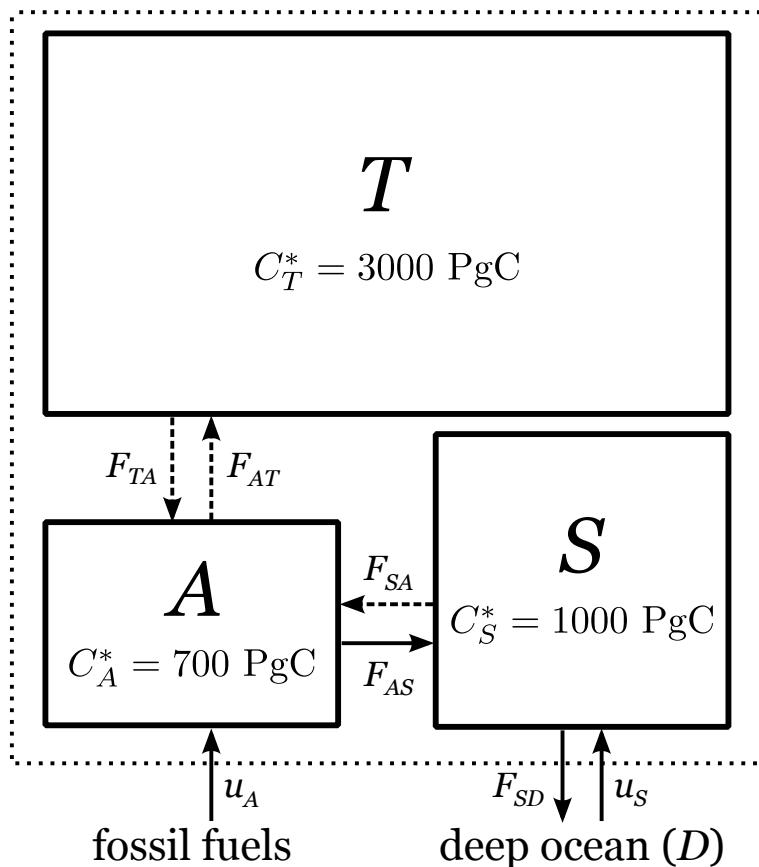
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- The Carbon Cycle example
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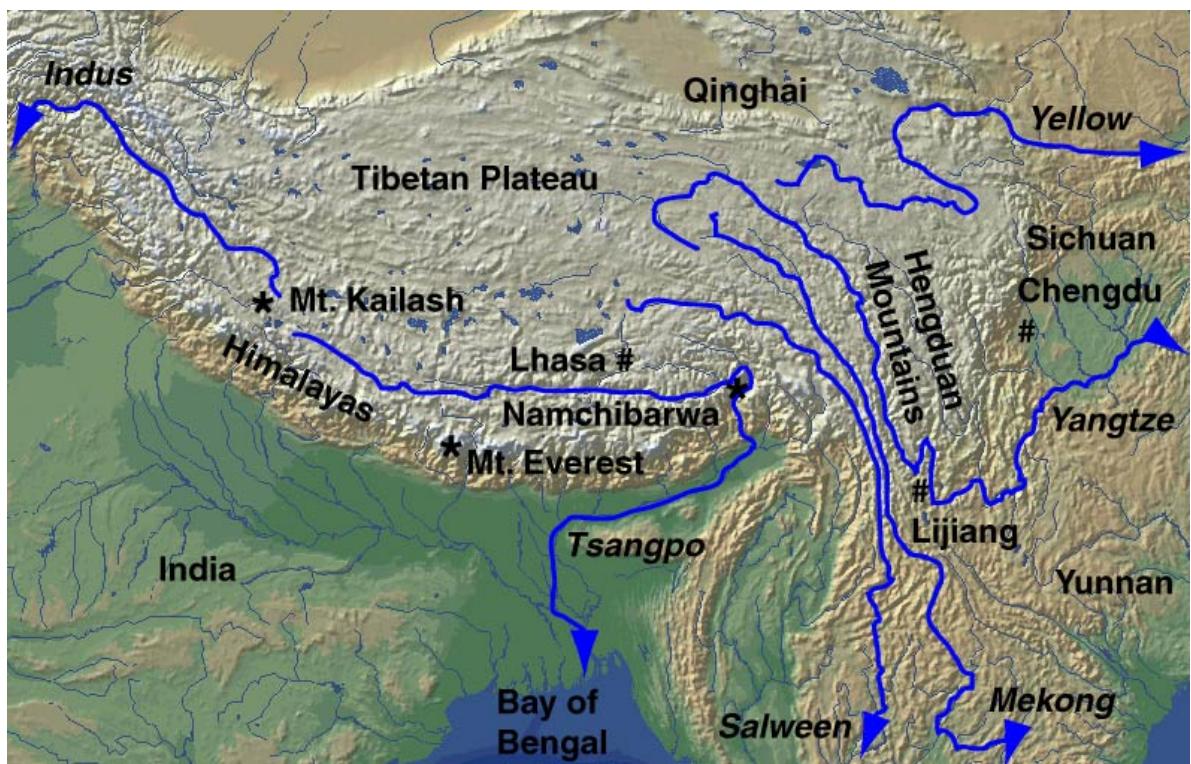
3 Compartmental Systems

4 Generalization to non Well Mixed Systems

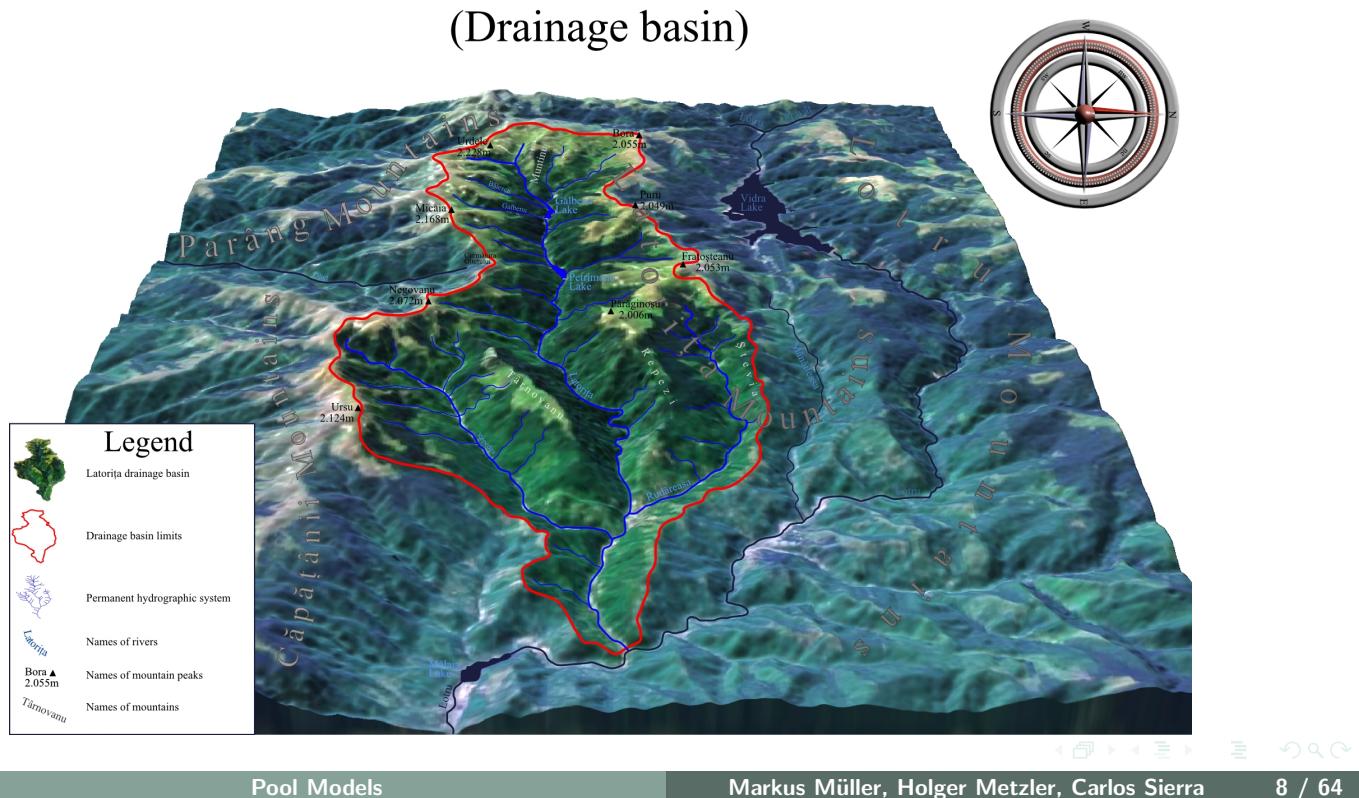
- Population Dynamics



Hydrology Watersheds



Latorița River, tributary of the Lotru River (Drainage basin)

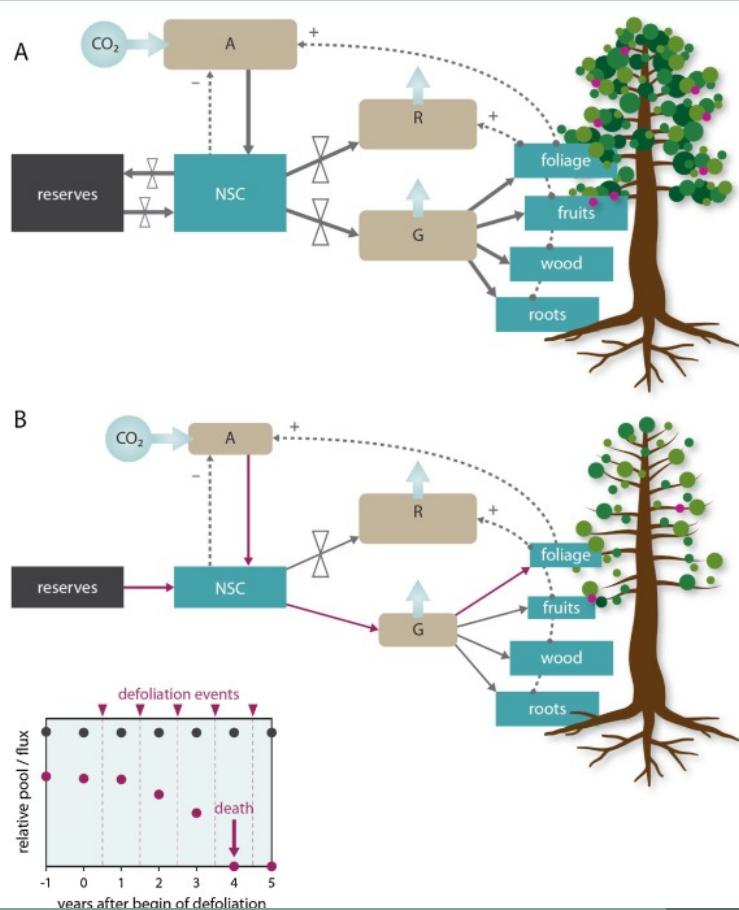


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Plant Physiology/ Carbon allocation

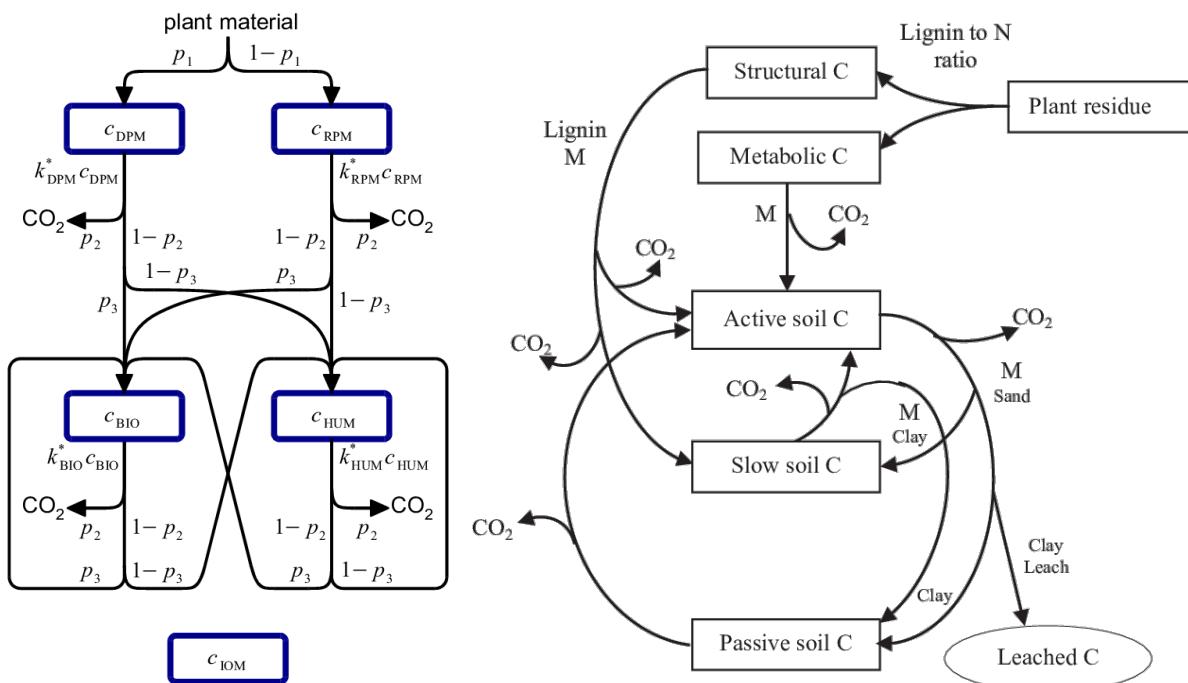


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Organic Matter Decomposition / Soil Models

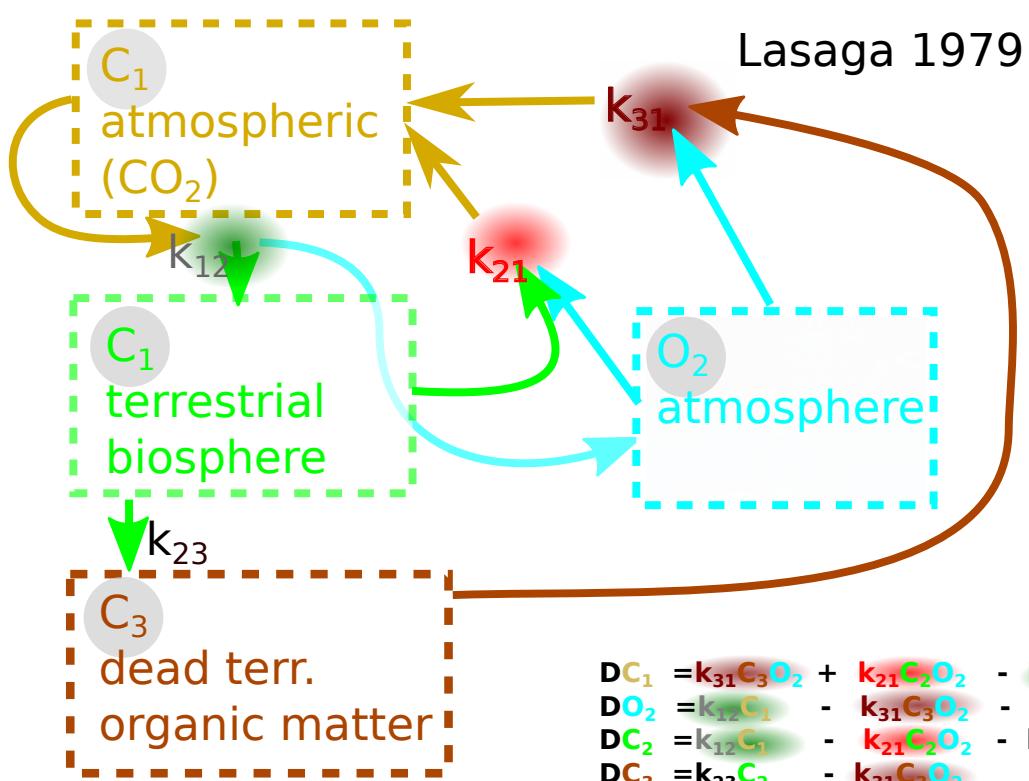


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Ecosystem Models

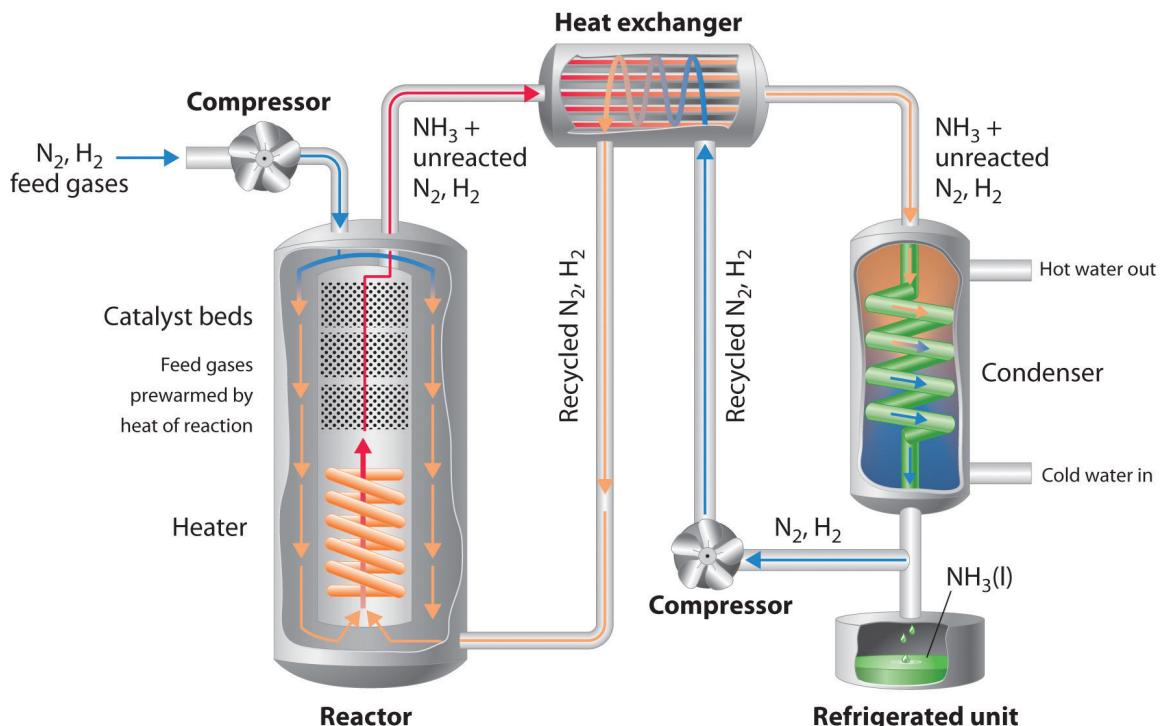


Pool Models

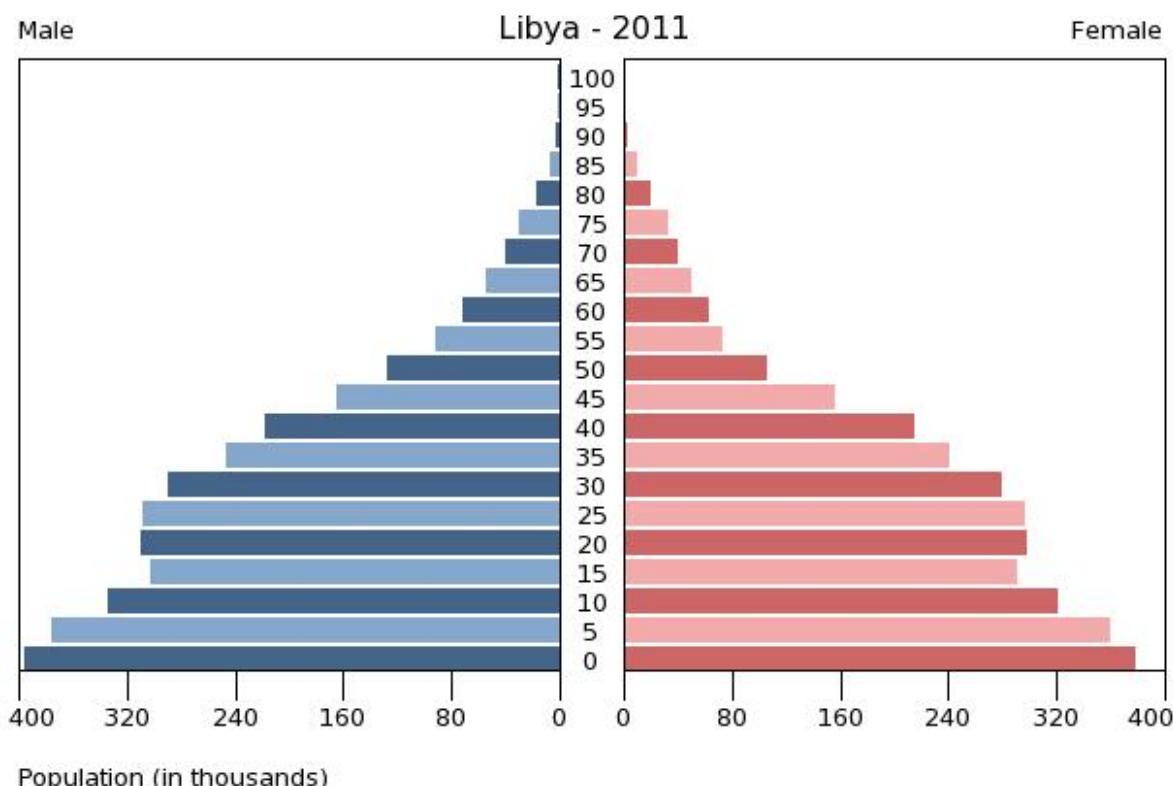
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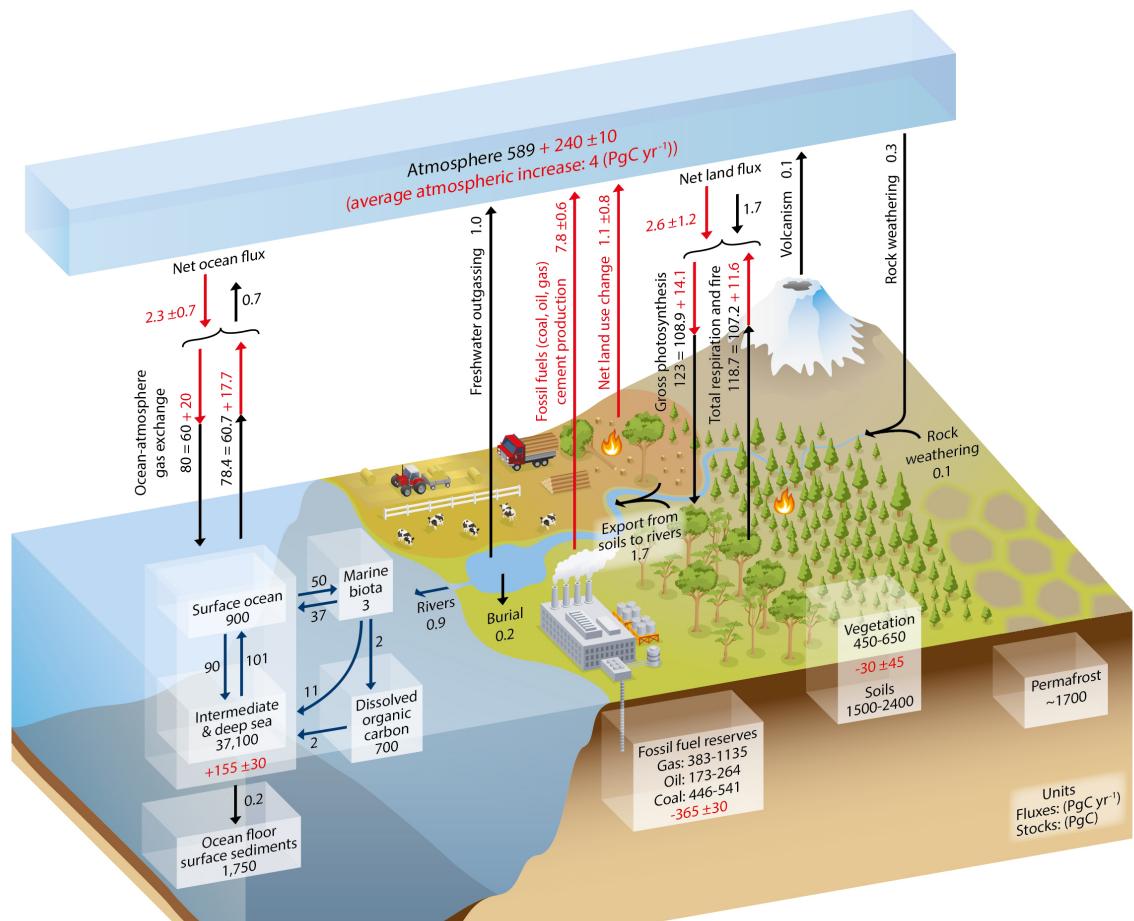
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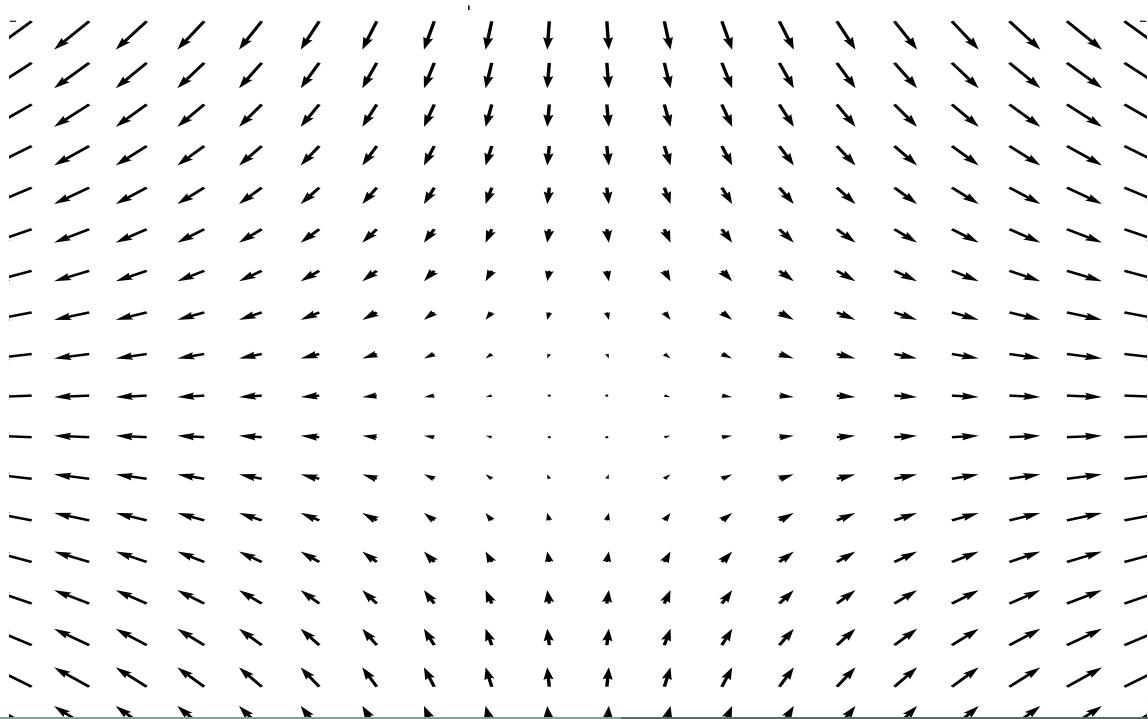
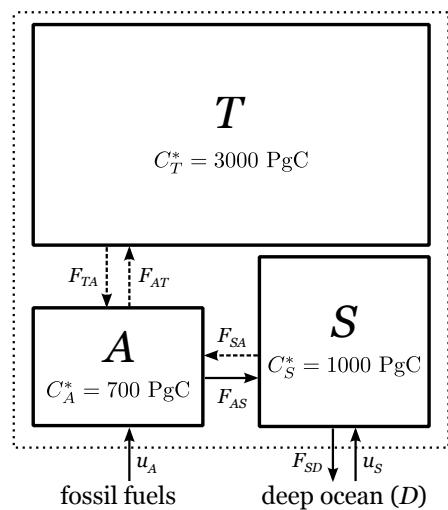
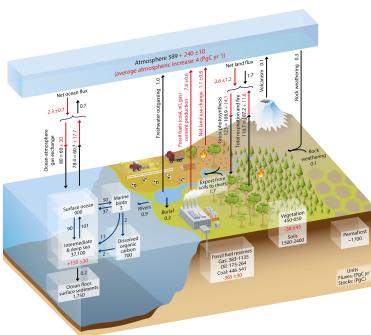
Chemical Reactors

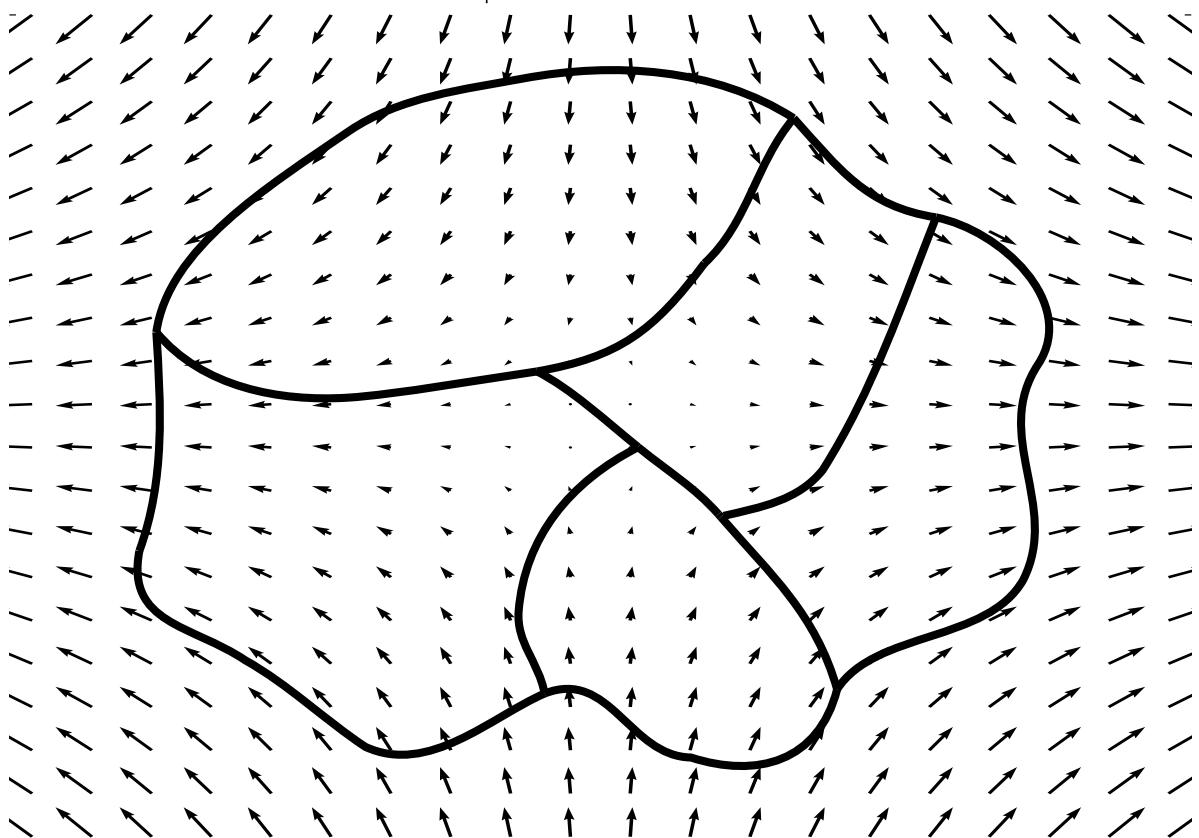
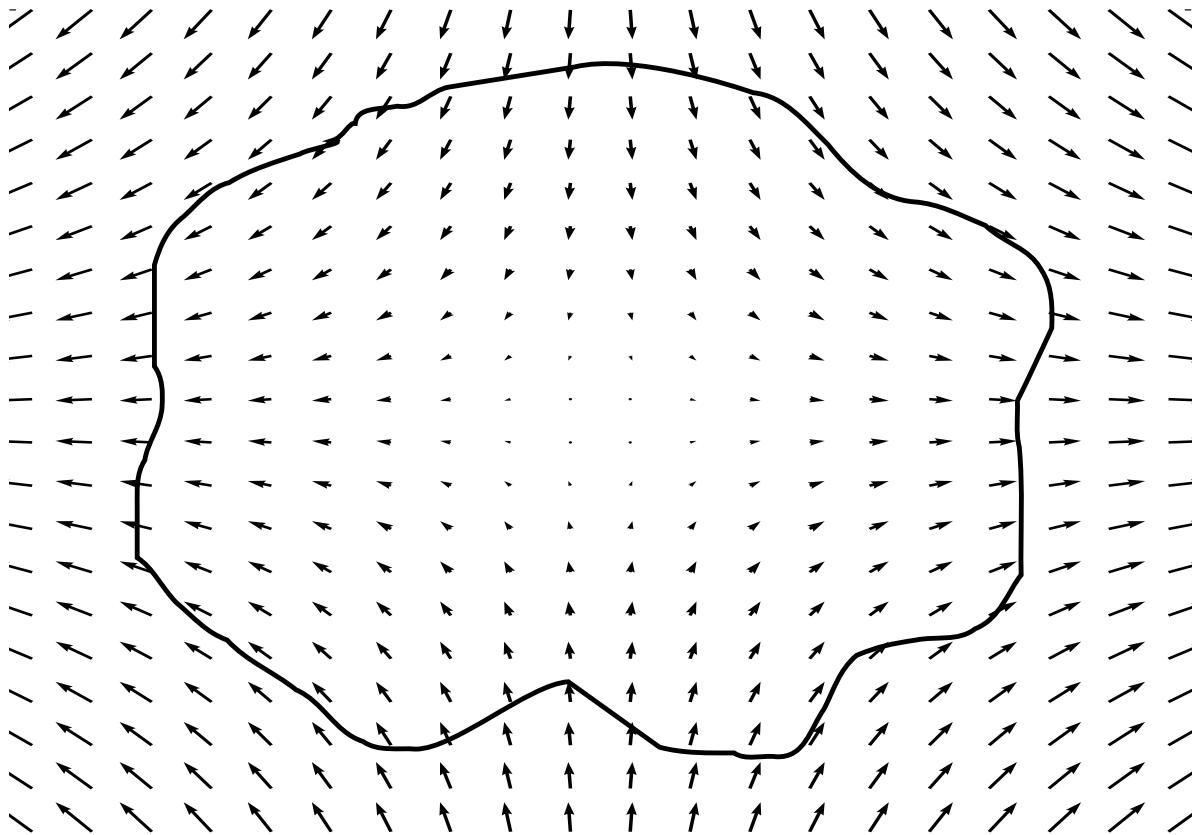


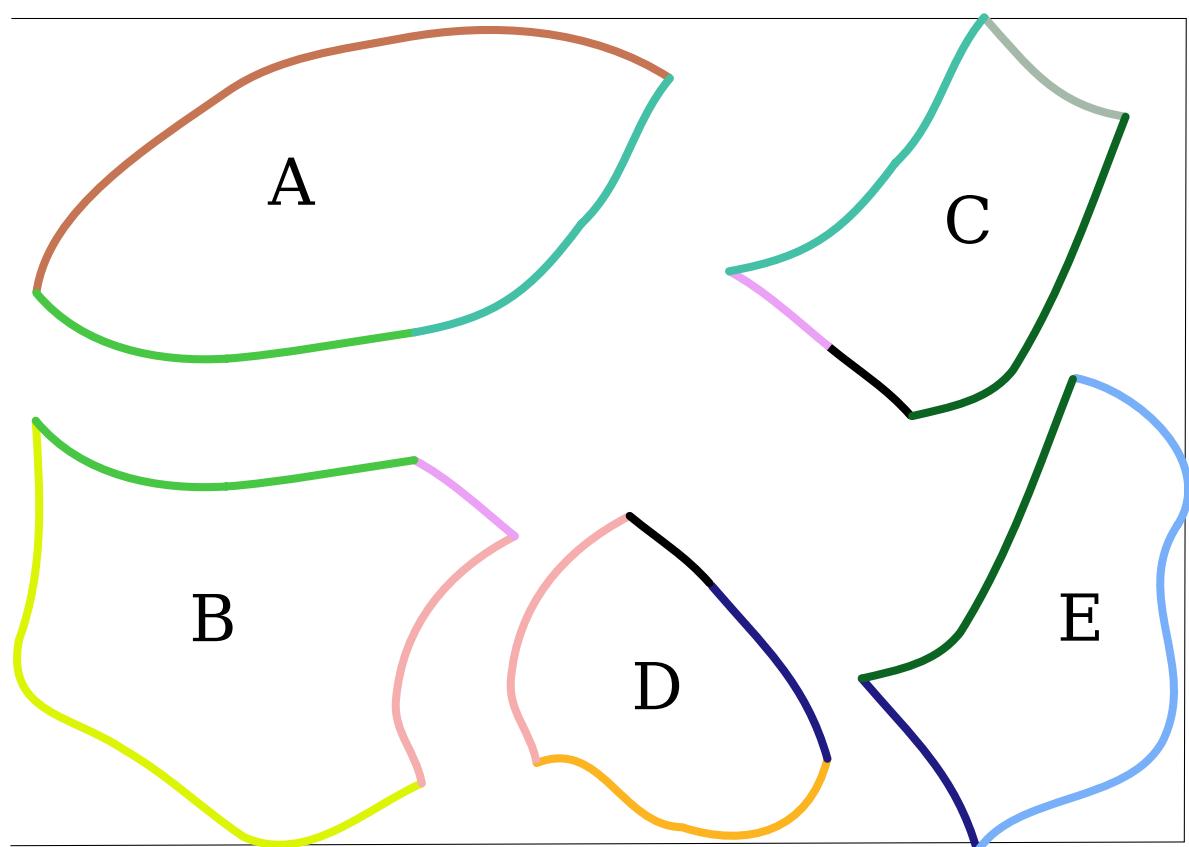
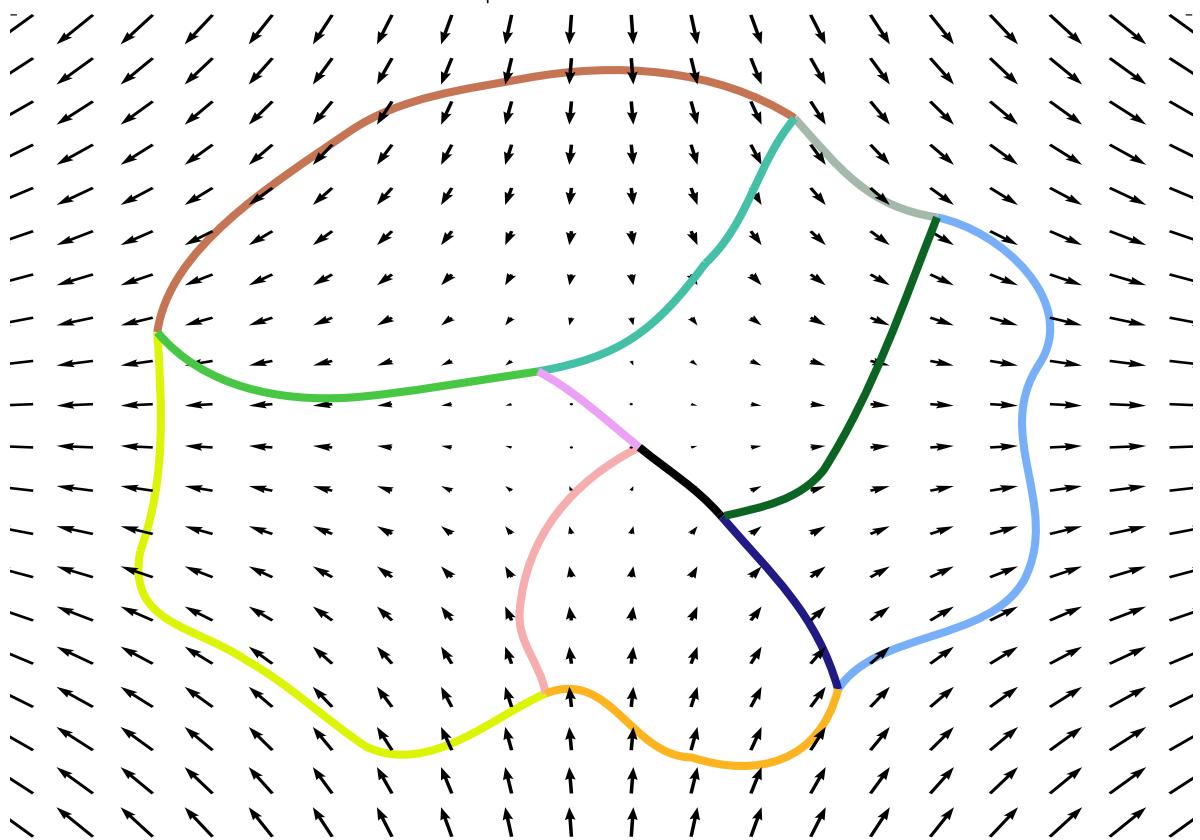
Population Dynamics

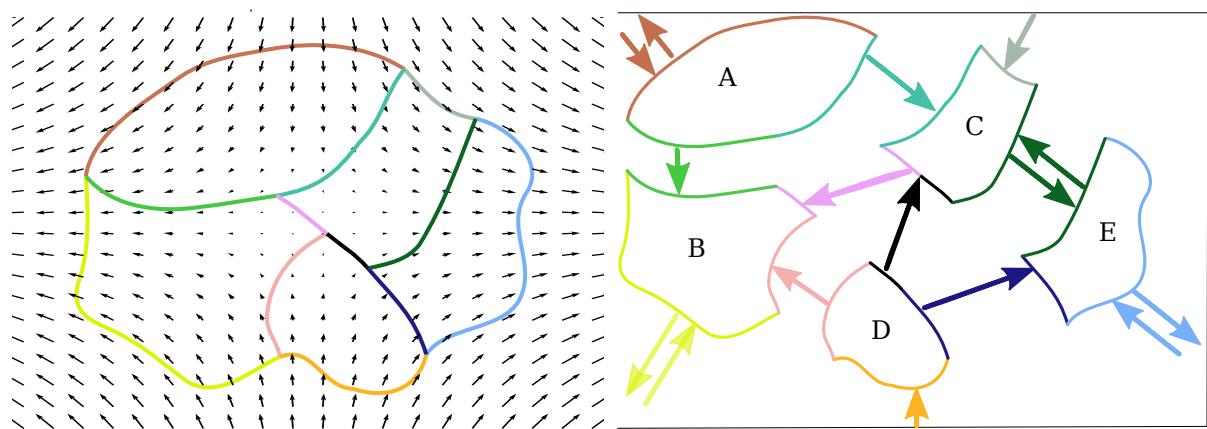
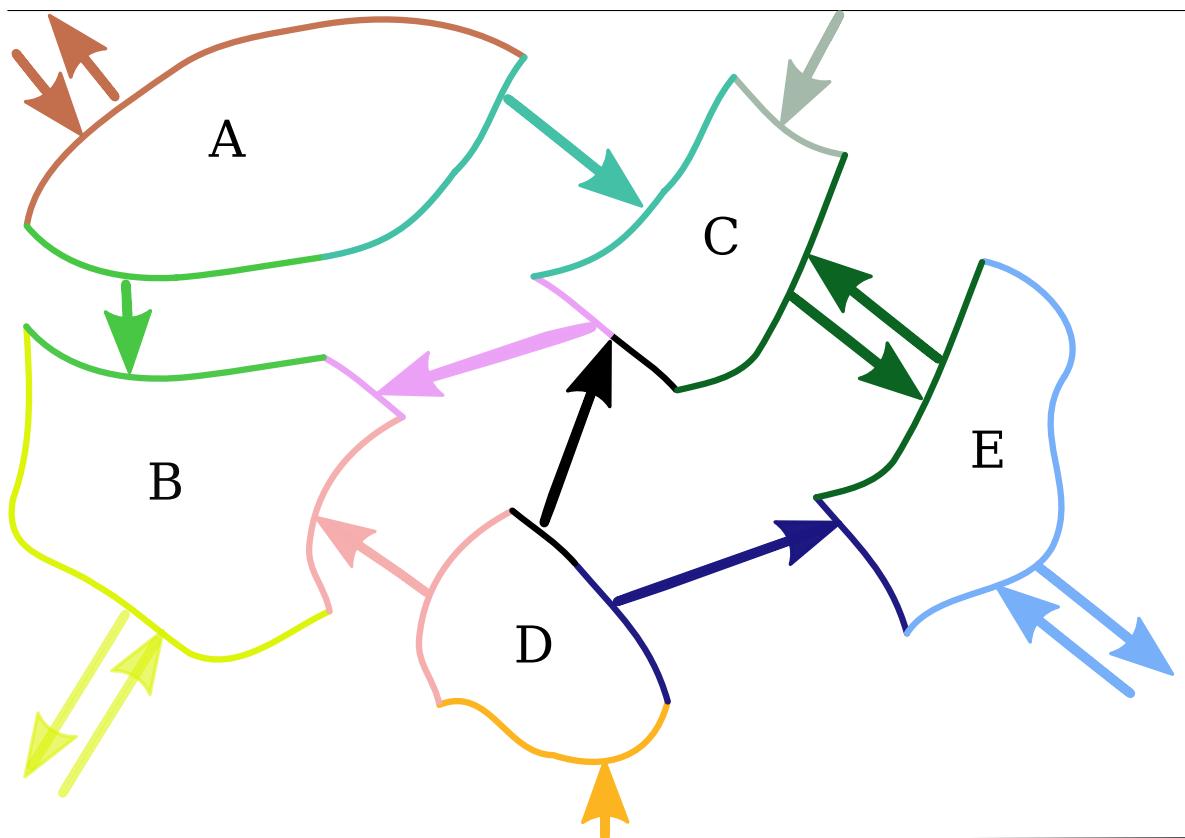


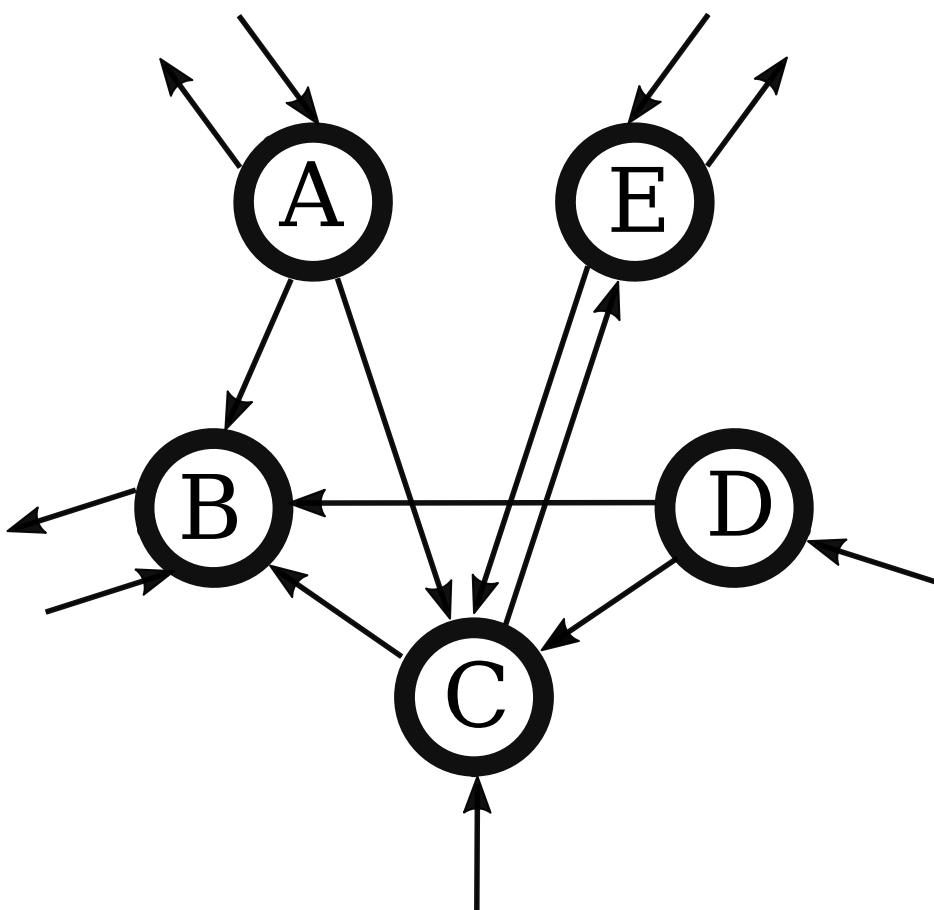
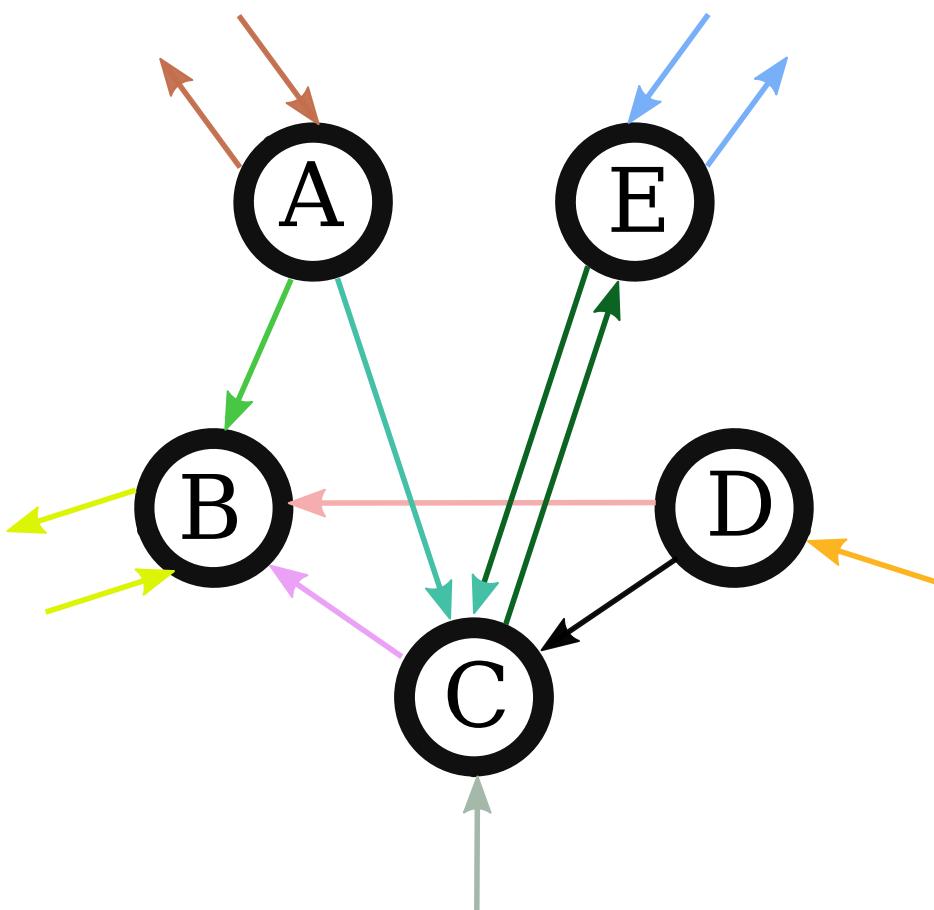


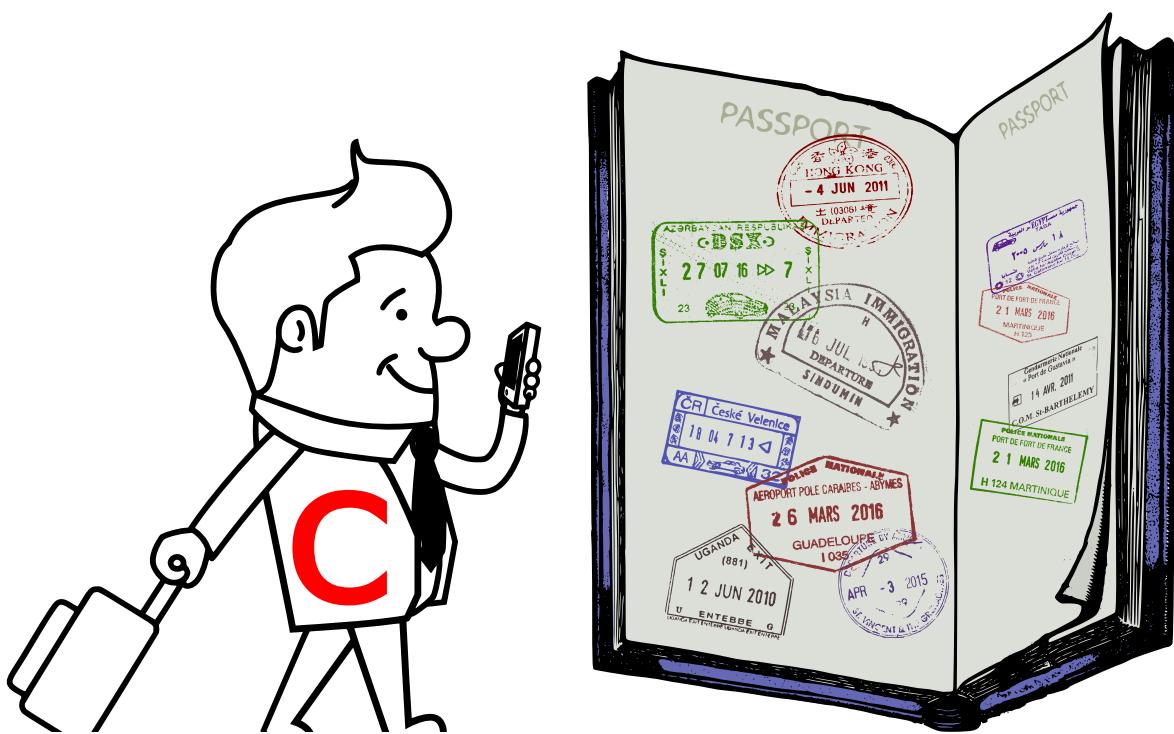








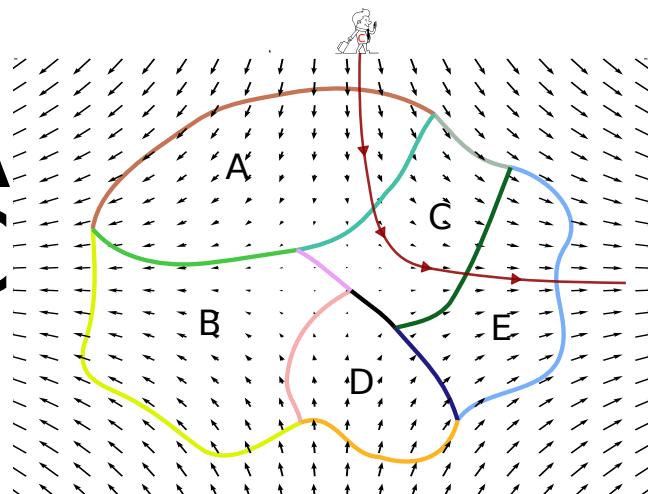




t,x,y,z

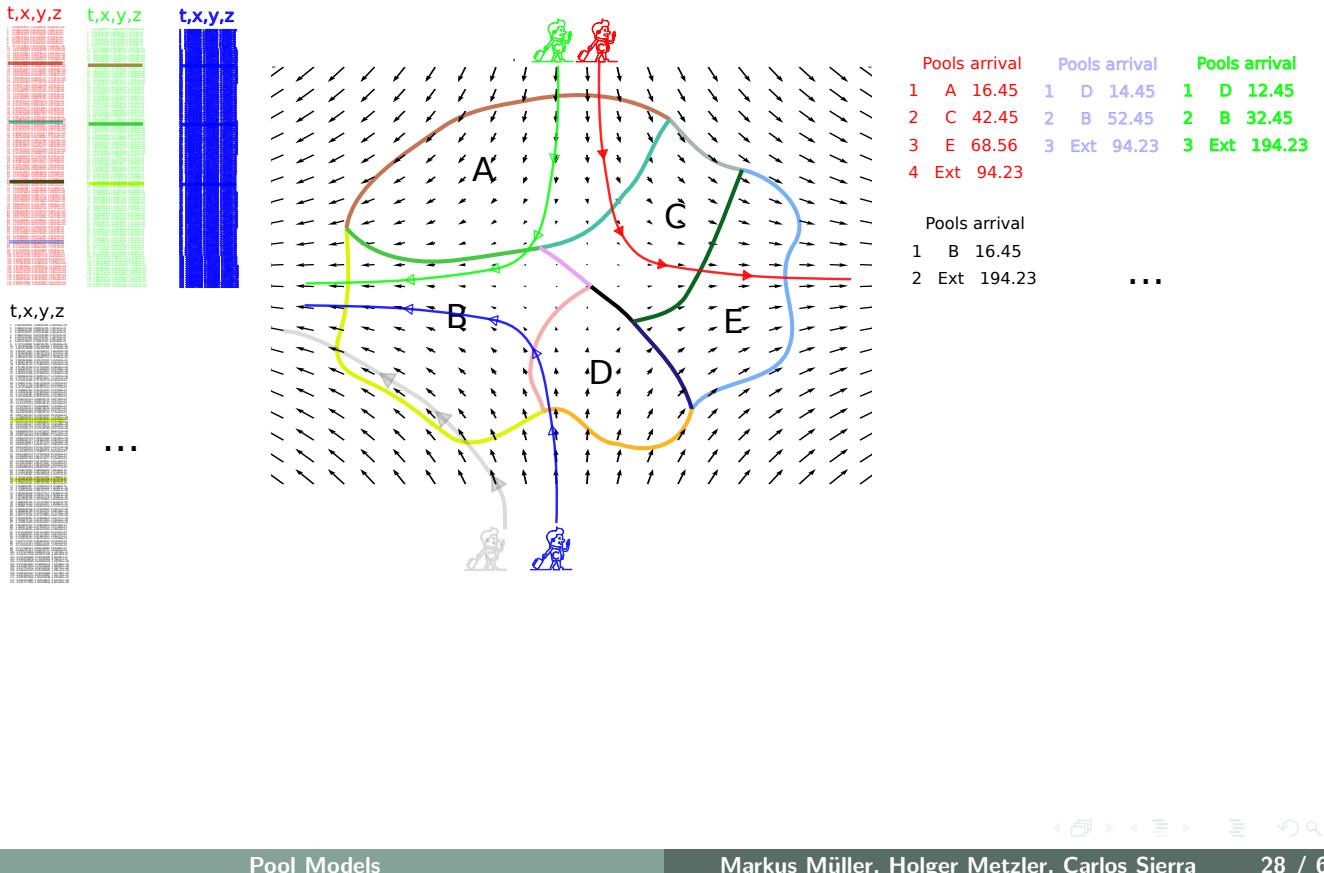
0.000000000	0.000000000	0.000000000
0.000000000	0.000000000	0.000000000
0.000000000	0.000000000	0.000000000
0.000000000	0.000000000	0.000000000
0.000000000	0.000000000	0.000000000

ACE

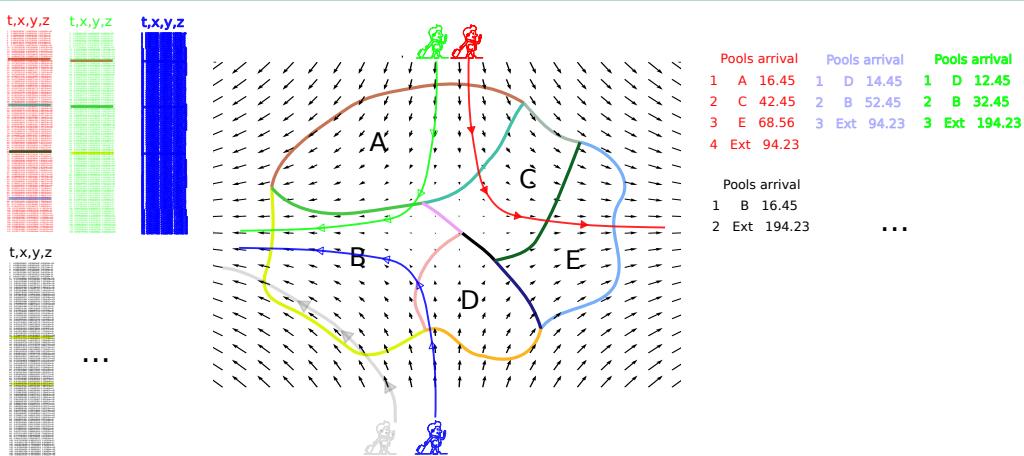


Pools arrival

1	A	16.45
2	C	42.45
3	E	68.56
4	Ext	94.23
...		

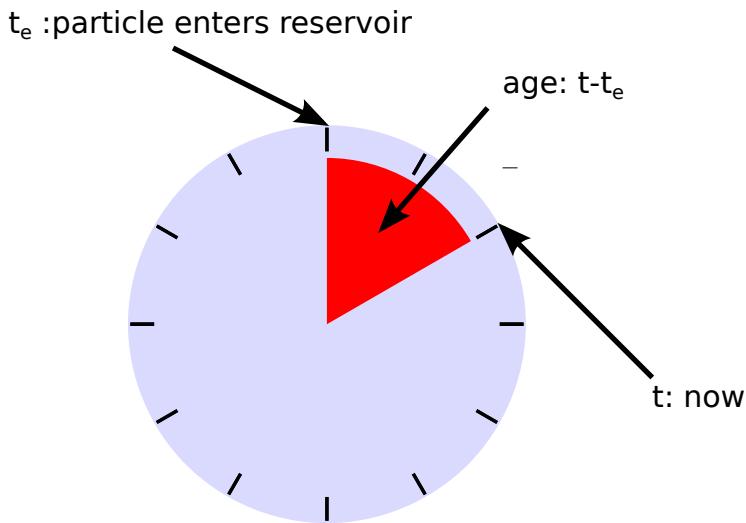


Possible Descriptive Statistics



- number / mass of particles in pool A, B, ...
- average time spent in a pool A ,B...
- average time spent in the whole system
- average time of particles spent between pool C and E under the assumption of having entered by pool D (weird but possible...)
- deathrate of pool A.

Age of a Particle

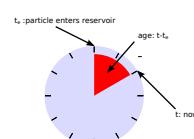


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Pool Models

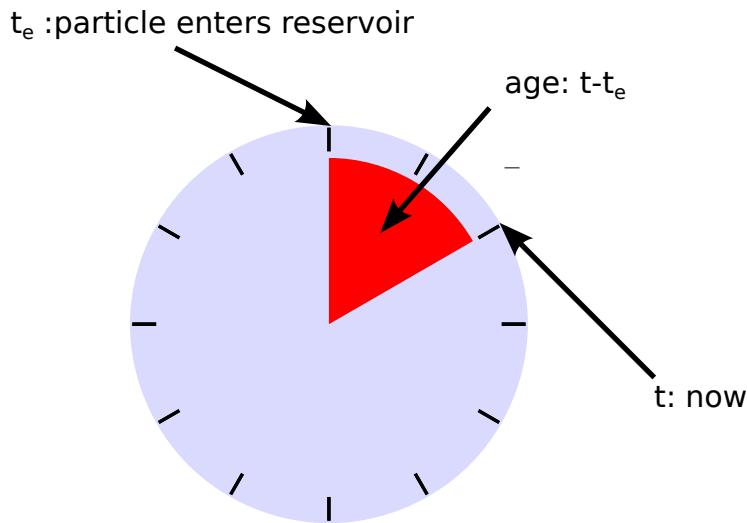
- └ Reducing Model Complexity
 - └ Asking Simpler Questions
 - └ Age of a Particle

Age of a Particle



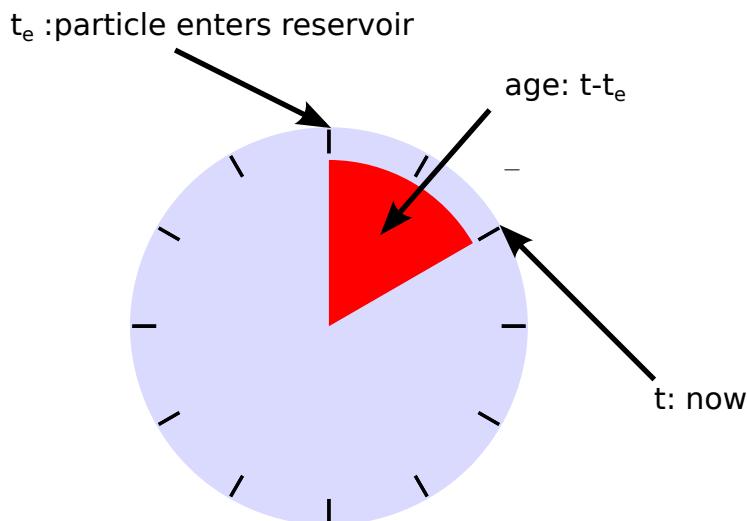
We can define the age of a particle with respect to the reservoir as the time it has spent in it. In the case of the human population this refers to the age in common sense. But in general the age refers not to the time of creation but to the time the reservoir was entered. If the reservoir in question is e.g. the soil and the particle a ^{14}C atom that entered the soil 5 minutes ago it is at least possible that the atom is as old as the universe while its age with respect to the soil is only 5 minutes

Age of a Particle



- The “age” is always defined in *context* of the reservoir

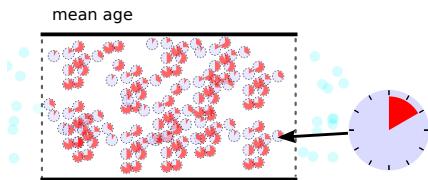
Age of a Particle



- The “age” can not be negative!

Mean Age

- Which set of particles to use for the average?
proposition: *all* particles that are in the reservoir at the given time.
→ usually depends on input rates as well as the dynamics of the system.



$$\bar{a}(t) = \frac{a_1 + a_2 + \dots + a_N}{N}$$

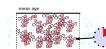
With $N = N(t)$ the number of all particles in the reservoir at time t .

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Pool Models
└ Reducing Model Complexity
 └ Asking Simpler Questions
 └ Mean Age

Mean Age

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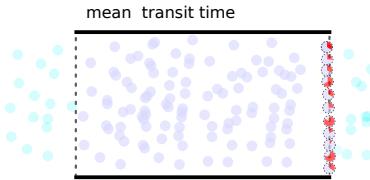


$$\bar{a}(t) = \frac{a_1 + a_2 + \dots + a_N}{N}$$

With $N = N(t)$ the number of all particles in the reservoir at time t .

To compute the average age of the population of the world at a given time we would have to ask everybody how old he is and then compute the mean value. If we treat this room as a reservoir everybody would have started a stopwatch entering the room, press the stop button now and we would have to add all the times and divide them by the number of people.

Mean Transit Time



$$\bar{t}_r(t) = \frac{a_1 + a_2 + \cdots + a_{n_o}}{n_o}$$

With $n_o = n_o(t)$ the number of particles **just leaving** at time t

- Can be time dependent as well

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Pool Models
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Mean Transit Time

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With $n_o = n_o(t)$ the number of particles **just leaving** at time t
Can be time dependent as well

In the example of the world population it would be sufficient to observe the grave yards. We would investigate the birth date of every person who dies and compute the average of the live spans. We ignore all the people still alive and concentrate only on the people just dying. In this room it would be hard to compute the average transit time right now, because nobody is leaving at the moment. (dropping off to sleep does not count as leaving). But we could after the talk. Every person would press the stop bottom at its watch in the moment she passes the door. If two or more people would leave in the same moment we could compute the average of the times. It is also

Mean Transit Time

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With $n_o = n_o(t)$ the number of particles **just leaving** at time t

- Can be time dependent as well
- Includes only the subset of particles that are just leaving at the given time. (Can only be computed when there is an output stream)

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Pool Models

- └ Reducing Model Complexity
 - └ Asking Simpler Questions
 - └ Mean Transit Time

Mean Transit Time

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Differences between mean age and mean transit time



- Includes **all** particles that are in the reservoir at the given time.
- Directly coupled to input rates
- Includes only the subset of particles that are **just leaving** at the given time.
- Indirectly coupled to inputs

Iteration over all particles

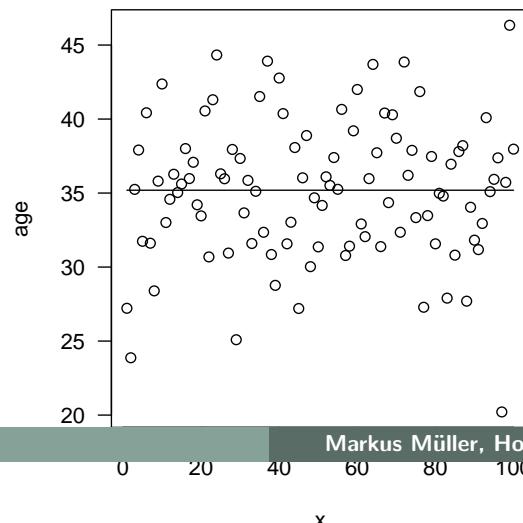
- ① To compute the mean transit time we have to identify the particles **just leaving**.
- ② Ask every leaving particle when it entered and compute its age.
- ③ Iterate over all particles and compute the average of their ages.

Iteration over all particles

- ➊ To compute the mean transit time we have to identify the particles just leaving.
- ➋ Ask every leaving particle when it entered and compute its age.
- ➌ Iterate over all particles and compute the average of their ages.

$$\bar{t}_r(t) = \frac{a_1 + a_2 + \cdots + a_{n_o}}{n_o}$$

With $n_o = n_o(t)$ the number of particles just leaving at time t



Iteration over all ages

- ➊ as above
- ➋ as above + make a histogram of all ages
- ➌ iterate over all ages and compute their weighted average

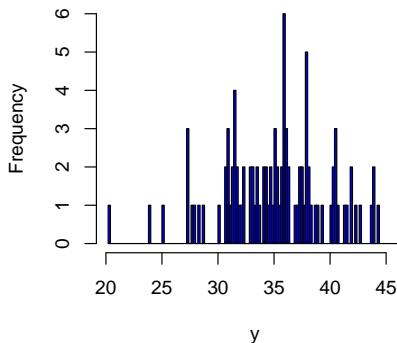
Iteration over all ages

- ① as above
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- ③ iterate over all ages and compute their weighted average

$$\bar{t}_r(t) = \frac{a_1 n_{a_1} + a_2 n_{a_2} + \cdots + a_n n_{a_n}}{n_o}$$

With $n_o = n_o(t) = n_{a_1} + n_{a_2} + \cdots + n_{a_n}$

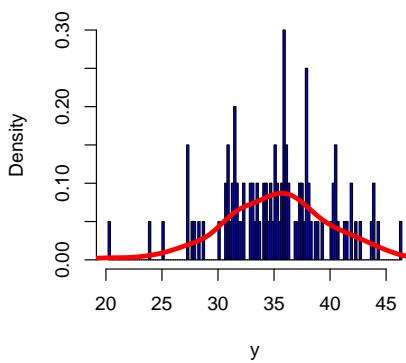
Histogram of y



Integration over a density

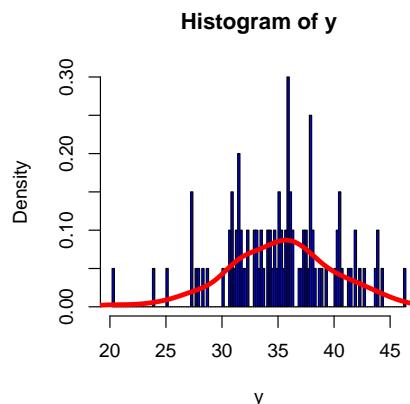
$$\begin{aligned}\bar{t}_r(t) &= \lim_{n \rightarrow \infty} \frac{a_1 n_{a_1} + a_2 n_{a_2} + \cdots + a_n n_{a_n}}{n_o} \\ &= \lim_{n \rightarrow \infty} \sum_{\text{minage}}^{\text{maxage}} a \frac{n(a)}{n_o} da \\ &= \int_{\text{minage}}^{\text{maxage}} a \psi(a) da\end{aligned}$$

Histogram of y

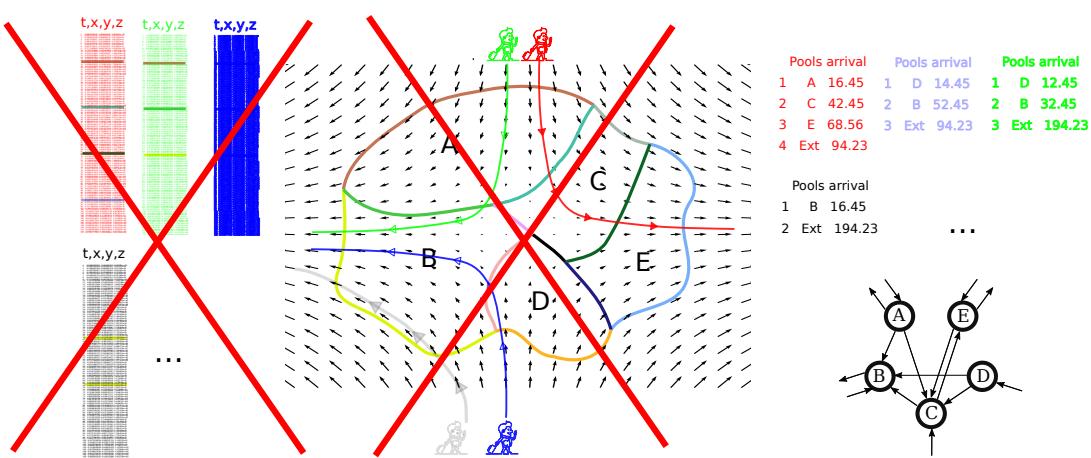


Same procedure for age density

$$\begin{aligned}
 \bar{a}(t) &= \lim_{n \rightarrow \infty} \frac{a_1 n_{a_1} + a_2 n_{a_2} + \cdots + a_n n_{a_n}}{n_p} \\
 &= \lim_{n \rightarrow \infty} \sum_{\text{minage}}^{\text{maxage}} a \frac{n(a)}{n_p} da \\
 &= \int_{\text{minage}}^{\text{maxage}} a \phi(a) da
 \end{aligned}$$



Possible Predictive Statistics ?



- Could we make a rule to predict the number of particles exiting from Pool E at time using only the particle passports? (Assuming that the exit from E is not recorded.)
- Could we make a rule to predict the age distribution of particles exiting from Pool E at time using only the particle passports? (Assuming again that the exit from E is not recorded.)

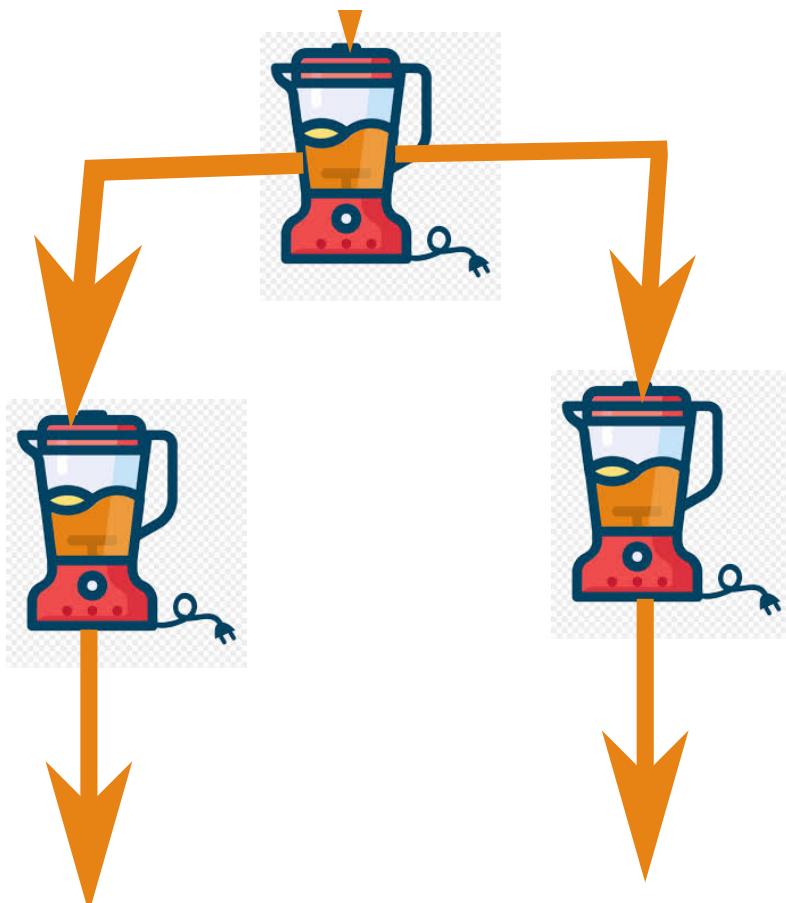
Intermediate Summary

- ① Pool descriptions condense complex information to a time series of pool changes.(A series of stamps in the passport)
- ② There are many possible statistics on sets of these time series, usually related to numbers of particles and times. (e.g. the number of particles in a pool,
- ③ Pool **Models** predict = model some of these **exclusively** with respect to the information obtainable from (all) passports.
- ④ The most common even disregard most of the information in the passports.

The simplest pool systems



The simplest pool systems are well mixed



Pool Models

Markus Müller, Holger Metzler, Carlos Sierra

Only the number of particles per Pool counts ...

	Pools arrival		Pools arrival		Pools arrival
1	A 16.45	1	D 14.45	1	D 12.45
2	C 42.45	2	B 52.45	2	B 32.45
3	E 68.56	3	Ext 94.23	3	Ext 194.23
4	Ext 94.23				

	Pools arrival
1	B 16.45
2	Ext 194.23
	...

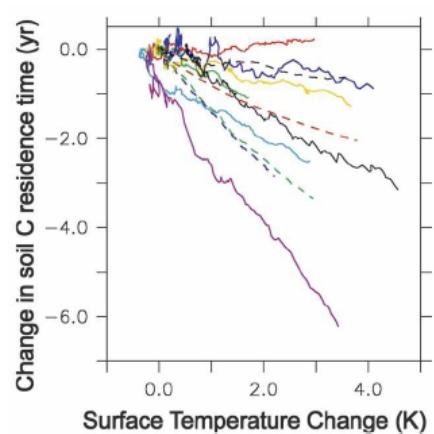
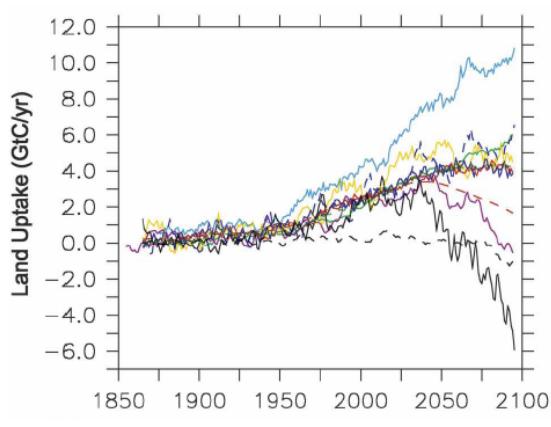
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Pools arrival			Pools arrival			Pools arrival		
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3	E	68.56	3	Ext	94.23	3	Ext	194.23
4	Ext	94.23						

Pools arrival

1	B	16.45
2	Ext	194.23
		...

Diverse model predictions



?

Model comparison

Key quantities

Model comparison

Key quantities

■ transit time

- ▶ the time that particles need to travel through the system
- ▶ exit time - entry time

Key quantities

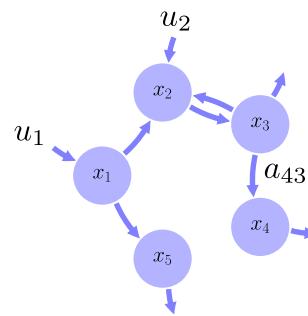
- **transit time**
 - ▶ the time that particles need to travel through the system
 - ▶ exit time - entry time
- **system age**
 - ▶ for particles in the system
 - ▶ current time - entry time

Key quantities

- **transit time**
 - ▶ the time that particles need to travel through the system
 - ▶ exit time - entry time
- **system age**
 - ▶ for particles in the system
 - ▶ current time - entry time
- **compartment age**
 - ▶ system age of particles in a compartment

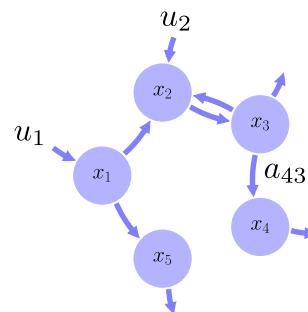
Linear autonomous compartmental models

$$\frac{d}{dt} \mathbf{x}(t) = A \mathbf{x}(t) + \mathbf{u}$$



Linear autonomous compartmental models

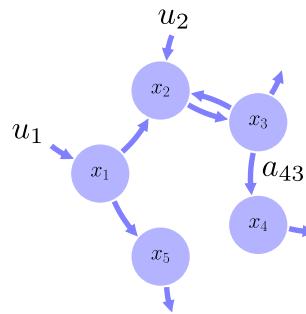
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$\mathbf{x}(t)$ vector of compartment content (e.g. C) at time t

Linear autonomous compartmental models

$$\frac{d}{dt} \mathbf{x}(t) = A \mathbf{x}(t) + \mathbf{u}$$

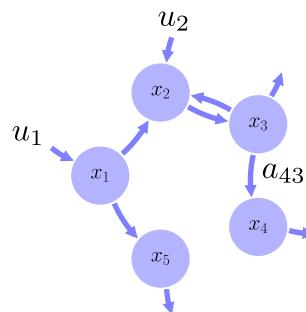


$\mathbf{x}(t)$ vector of compartment content (e.g. C) at time t

\mathbf{u} constant input vector

Linear autonomous compartmental models

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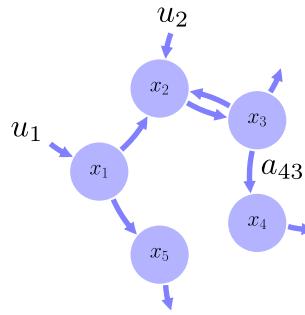
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\mathbf{u} constant input vector

$A = (a_{ij})$ compartmental matrix

Linear autonomous compartmental models

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$\mathbf{x}(t)$ vector of compartment content (e.g. C) at time t

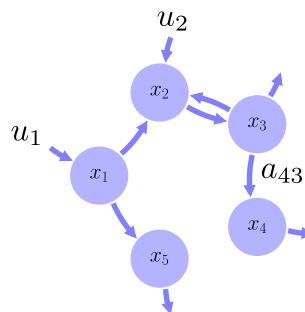
\mathbf{u} constant input vector

$A = (a_{ij})$ compartmental matrix

$a_{ij} (i \neq j)$ fractional transfer coefficients,
rate of flow from compartment j to compartment i

Linear autonomous compartmental models

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$\mathbf{x}(t)$ vector of compartment content (e.g. C) at time t

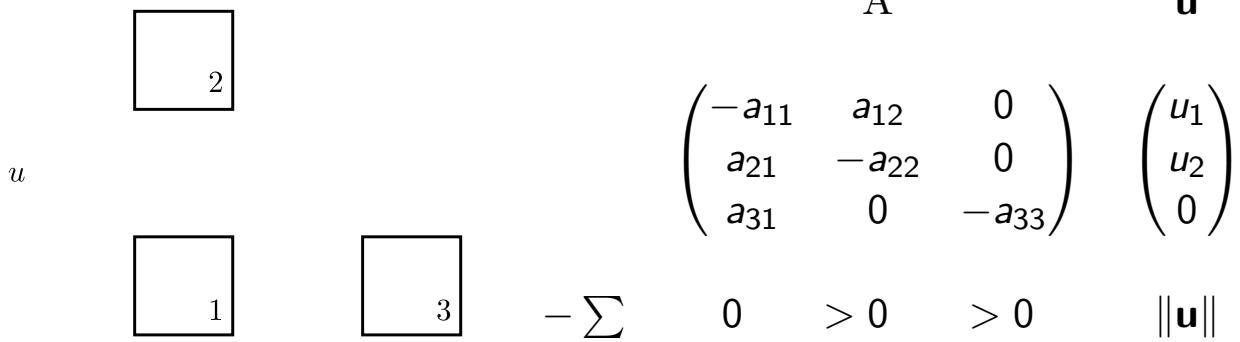
\mathbf{u} constant input vector

$A = (a_{ij})$ compartmental matrix

$a_{ij} (i \neq j)$ fractional transfer coefficients,
rate of flow from compartment j to compartment i
 $-a_{ii} > 0$ rate of flow out of compartment i

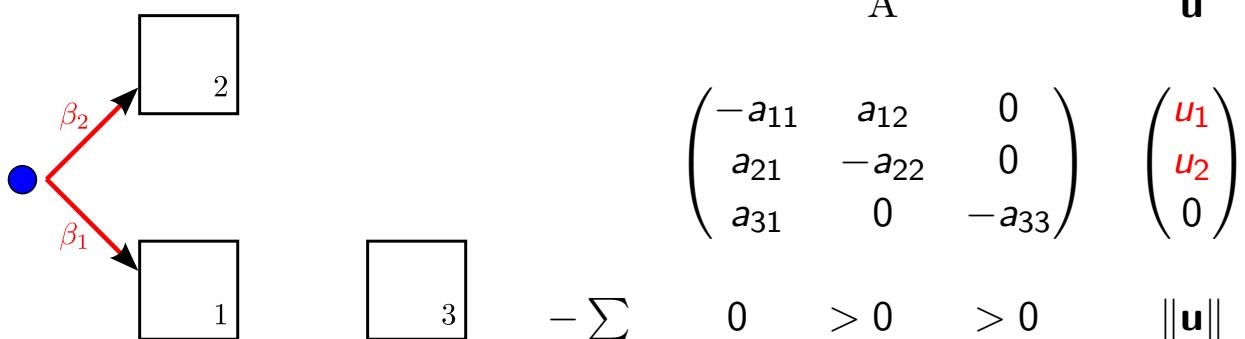
A particle travels

$$\frac{d}{dt} \mathbf{x}(t) = \mathbf{A} \mathbf{x}(t) + \mathbf{u}$$



A particle travels

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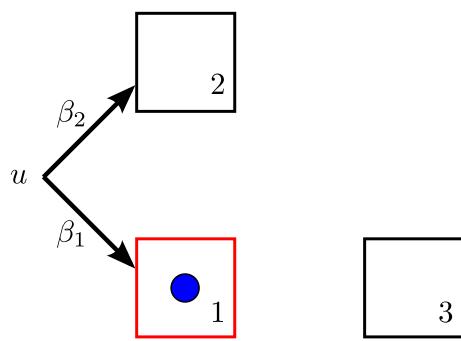


$$\beta_1 = \frac{u_1}{u_1+u_2} \quad \beta_2 = \frac{u_2}{u_1+u_2}$$

$$T_0 = 0$$

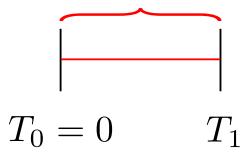
A particle travels

$$\frac{d}{dt} \mathbf{x}(t) = \mathbf{A} \mathbf{x}(t) + \mathbf{u}$$



$$\begin{array}{ccc} \mathbf{A} & & \mathbf{u} \\ \left(\begin{array}{ccc} -\mathbf{a}_{11} & \mathbf{a}_{12} & 0 \\ \mathbf{a}_{21} & -\mathbf{a}_{22} & 0 \\ \mathbf{a}_{31} & 0 & -\mathbf{a}_{33} \end{array} \right) & & \left(\begin{array}{c} \mathbf{u}_1 \\ \mathbf{u}_2 \\ 0 \end{array} \right) \\ -\sum & 0 & > 0 & > 0 & \|\mathbf{u}\| \end{array}$$

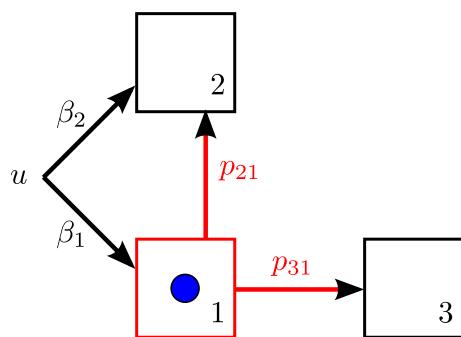
$$T_1 \sim \text{Exp}(a_{11})$$



$$T_0 = 0 \quad T_1$$

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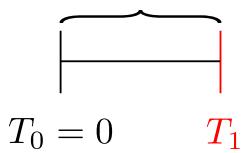
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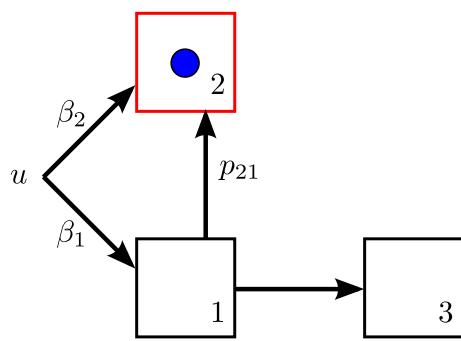
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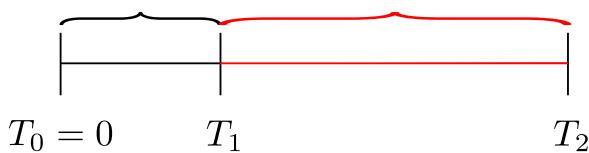
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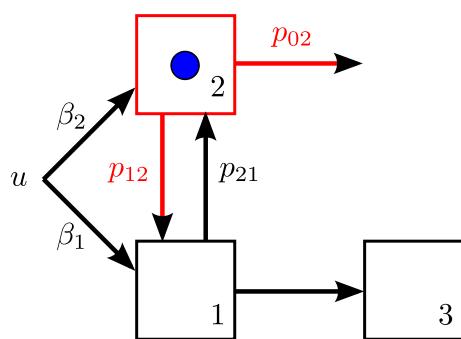
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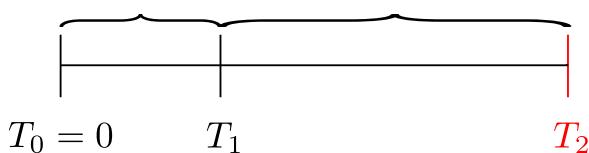


$$\begin{array}{ccccc} & & \mathbf{A} & & \mathbf{u} \\ & & \left(\begin{array}{ccc} -a_{11} & \color{red}{a_{12}} & 0 \\ a_{21} & -a_{22} & 0 \\ a_{31} & \color{red}{0} & -a_{33} \end{array} \right) & & \left(\begin{array}{c} u_1 \\ u_2 \\ 0 \end{array} \right) \\ -\sum & & 0 & > 0 & > 0 \\ & & & & \|\mathbf{u}\| \end{array}$$

$$p_{12} = \frac{a_{12}}{a_{22}} \quad p_{02} = 1 - \frac{a_{12}}{a_{22}}$$

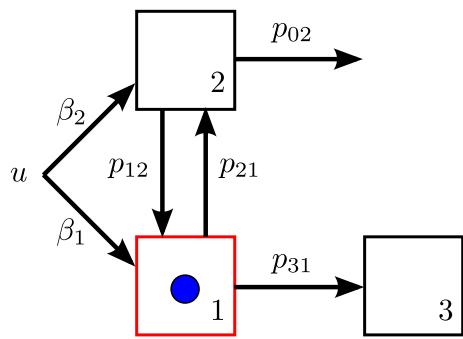
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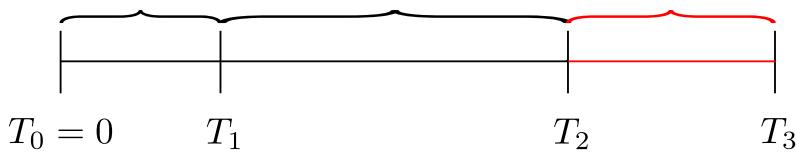


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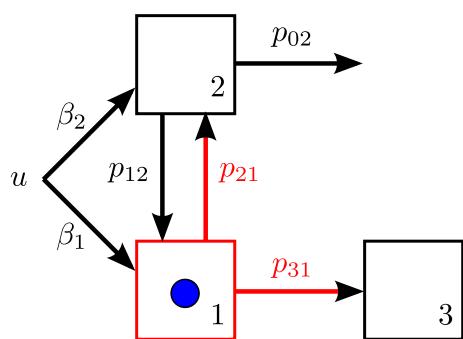
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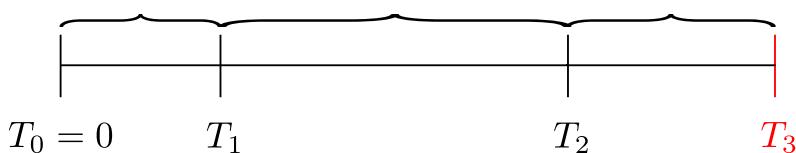
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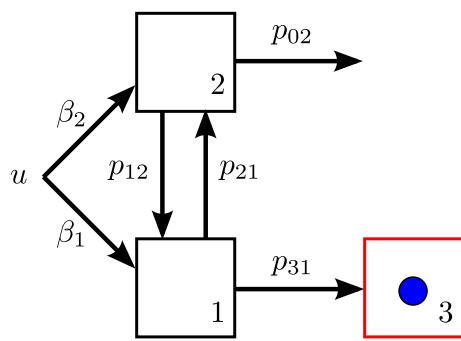
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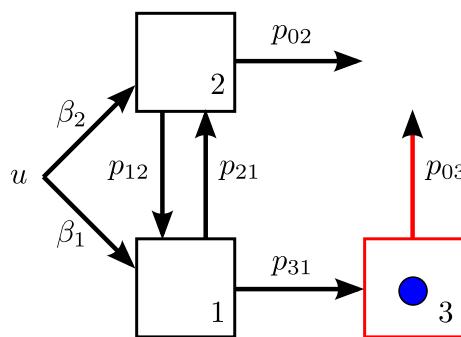
$$T_2 - T_1 \sim \text{Exp}(a_{22})$$

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$$p_{03} = 1$$

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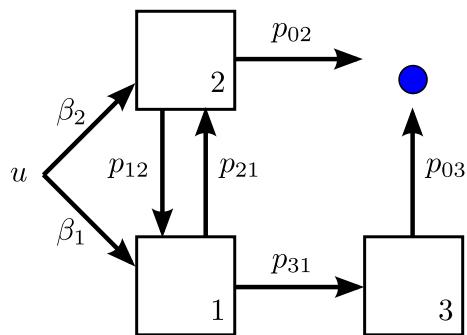
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$$A = \begin{pmatrix} -a_{11} & a_{12} & 0 \\ a_{21} & -a_{22} & 0 \\ a_{31} & 0 & -a_{33} \end{pmatrix}, \quad \mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \\ 0 \end{pmatrix}$$

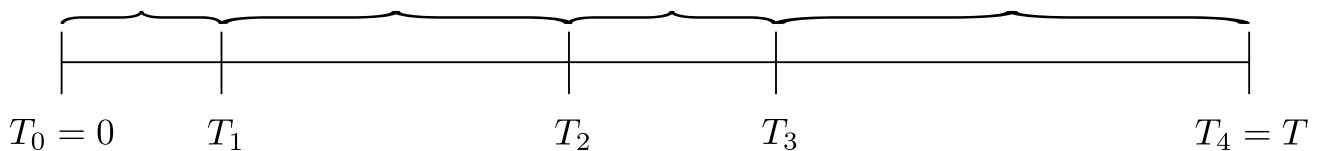
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Transit time distribution

- transit time computation:

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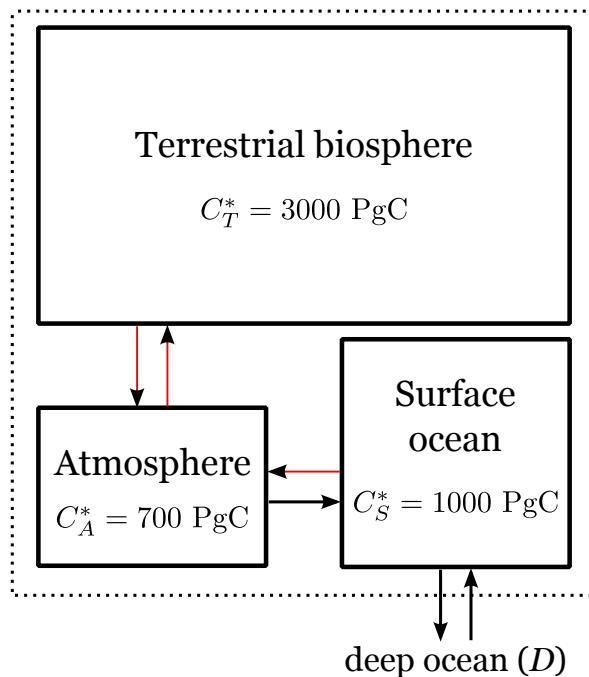
→ $T \sim \text{PH}(\beta, A)$

General, simple, explicit formulas

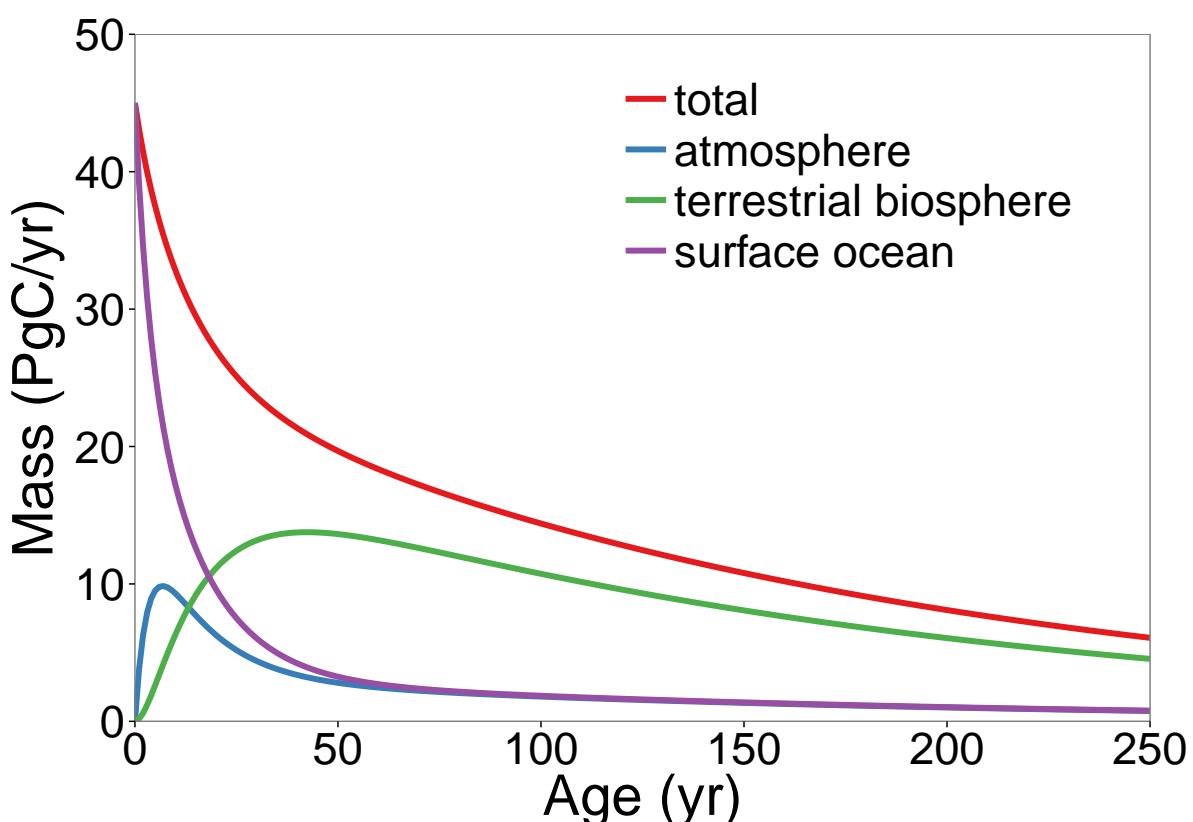
- phase-type distribution is well known:
 - ▶ probability density
 - ▶ cumulative distribution function
 - ▶ quantiles
 - ▶ mean and higher order moments
 - ★ $\mathbb{E}[T] = \|A^{-1} \beta\| = \frac{\|\mathbf{x}^*\|}{\|\mathbf{u}\|}$ (mean transit time)
- system age is also phase-type distributed
 - ▶ parameters $\eta := \frac{\mathbf{x}^*}{\|\mathbf{x}^*\|}, A$
- probability density of compartmental age
 - ▶ $f_a(y) = (X^*)^{-1} e^{yA} \mathbf{u}$

Application to a nonlinear carbon cycle model

Nonlinear model in steady state [?] with three compartments



Equilibrium age densities



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mass with age $t-s$ at time t

$$\Rightarrow \underbrace{\Phi(t, t-a) \mathbf{u}(t-a)}$$

mass with age a at time t

The state transition operator Φ

- solution to the matrix ordinary differential equation

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→ we can always obtain it (at least numerically)

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$$\begin{aligned} \text{mass in the system} \\ \text{at time } t \text{ with age } a &= \begin{cases} \text{remainings from input, } a < t \\ \text{at time } t-a \\ \text{remainings from initial content } \mathbf{x}^0 \text{ with initial, } a \geq t \\ \text{age } a-t \end{cases} \\ &= \begin{cases} \Phi(t, t-a) \mathbf{u}(t-a), & a < t, \\ \Phi(t, 0) \mathbf{p}^0(a-t), & a \geq t \end{cases} \end{aligned}$$

- \mathbf{p}^0 is a given age distribution of the initial content vector \mathbf{x}^0

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- **mean transit time $\neq \frac{\text{stock}}{\text{flux}}$**

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 - ▶ plug the solution $\tilde{\mathbf{x}}$ into \mathbf{A} :

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- **linearization along a solution trajectory**

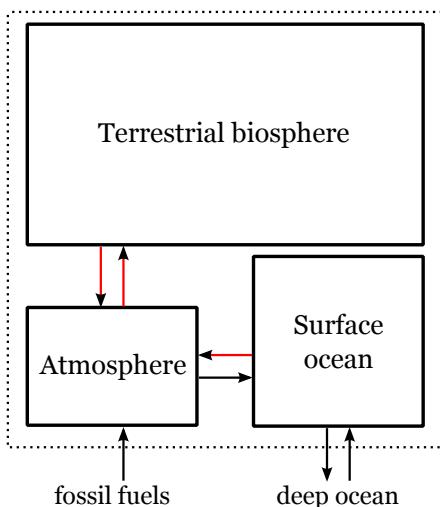
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$$\tilde{A}(t) := A(\tilde{\mathbf{x}}(t), t)$$

→ **linear** nonautonomous system

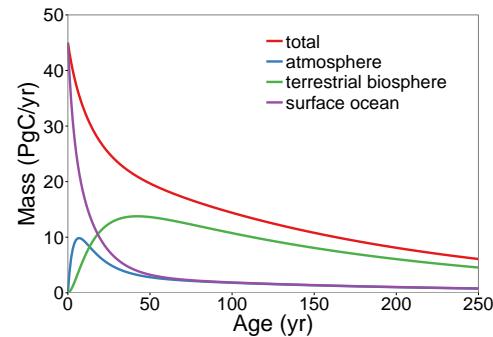
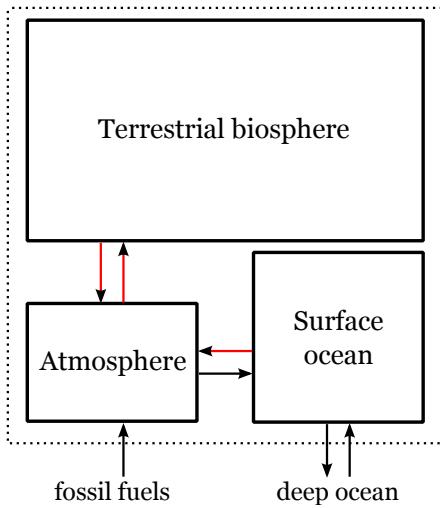
$$\frac{d}{dt} \mathbf{x}(t) = \tilde{A}(t) \mathbf{x}(t) + \mathbf{u}(t)$$

A global carbon cycle model



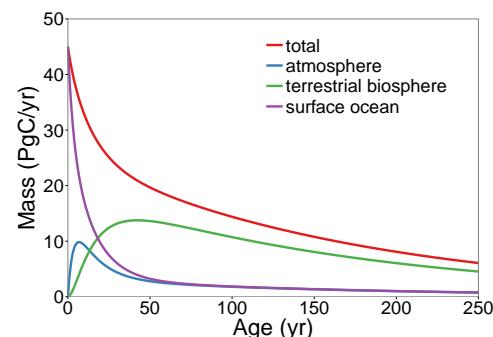
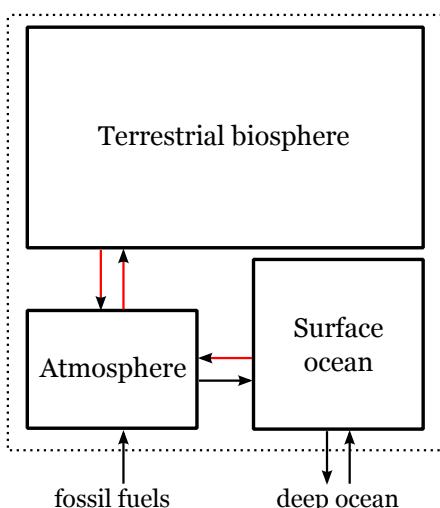
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Equilibrium age densities in 1765

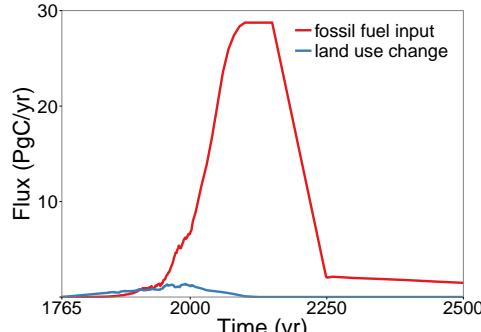


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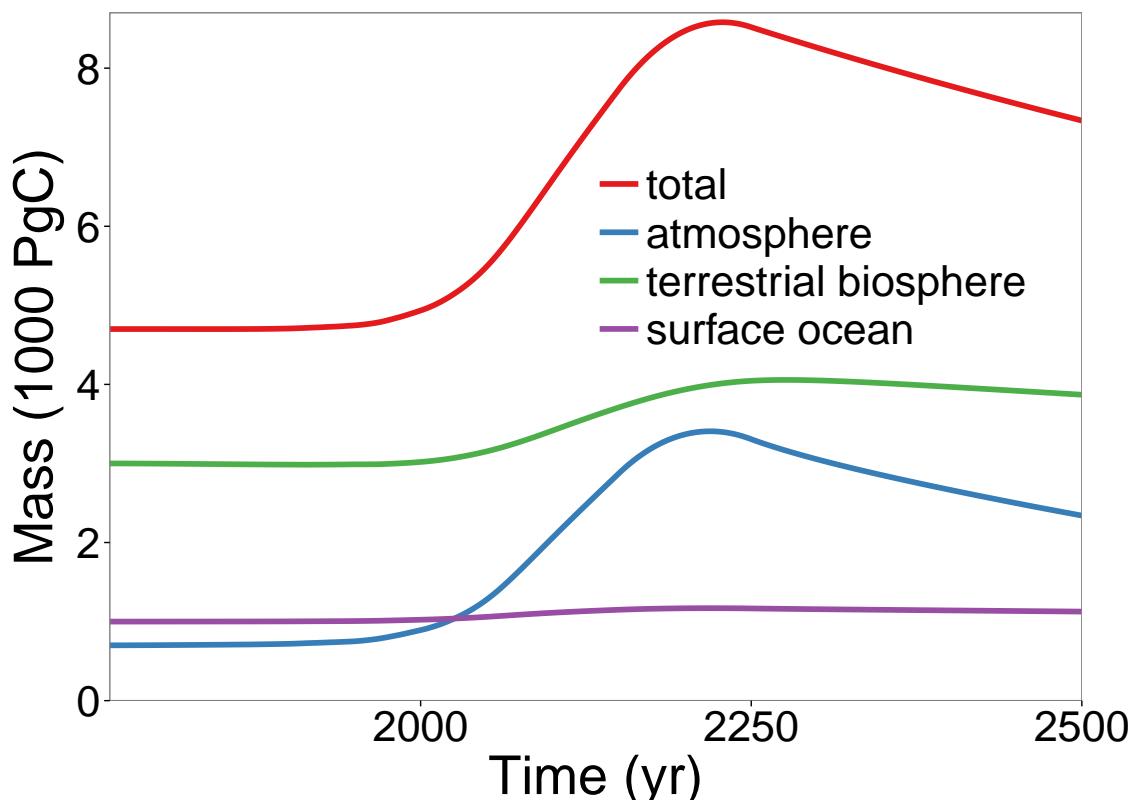
Equilibrium age densities in 1765



RCP8.5 scenario



Time-dependent carbon contents

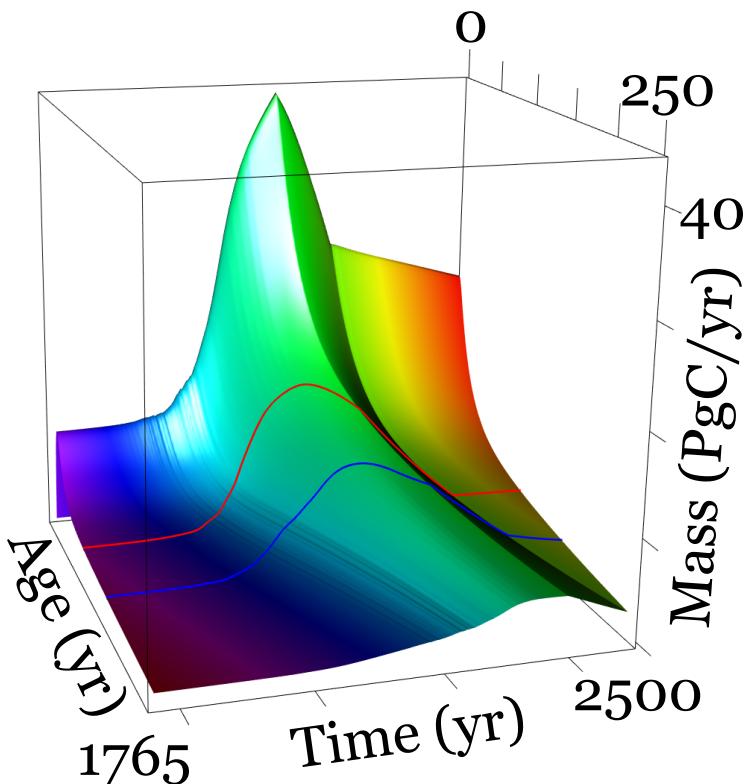


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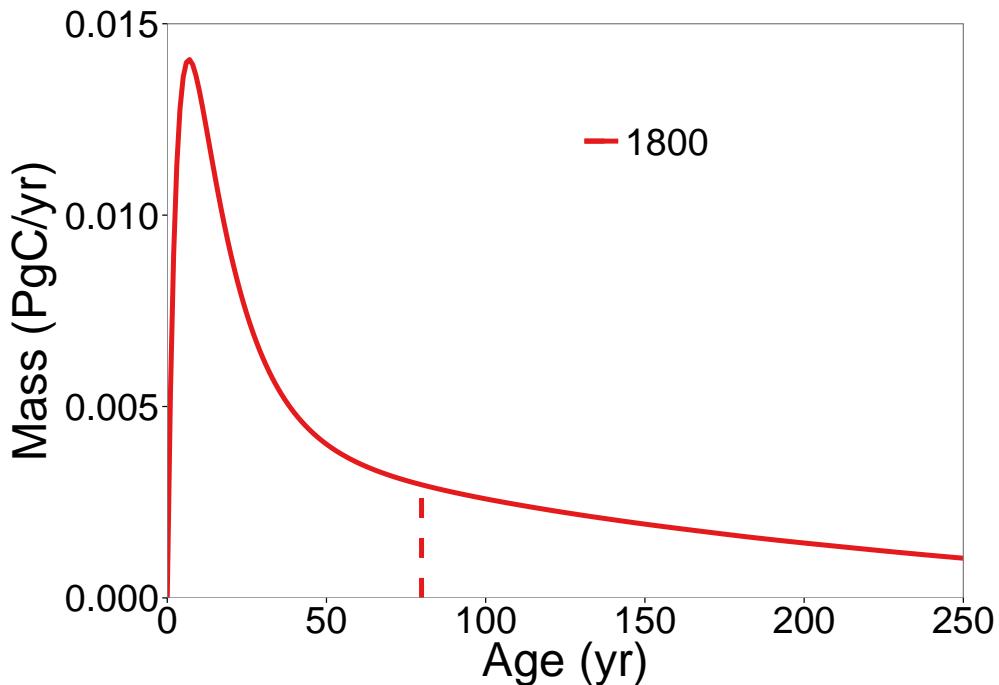


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2. **Future commitment:** If we allow a pulse of 1 PgC to be emitted today, how long will a significant fraction of this excess remain in the system?

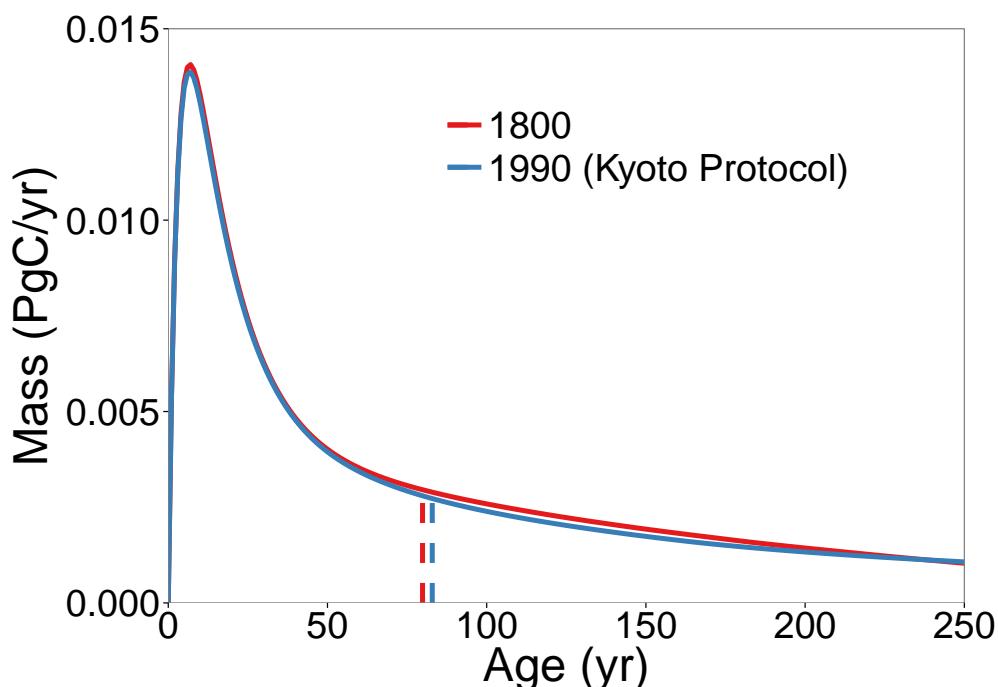
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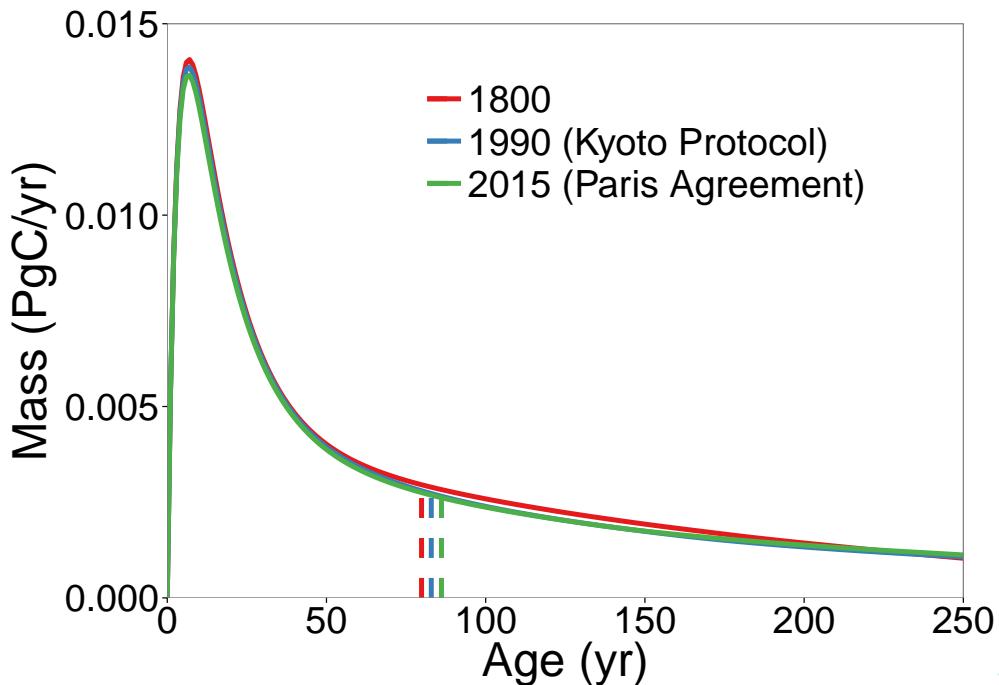
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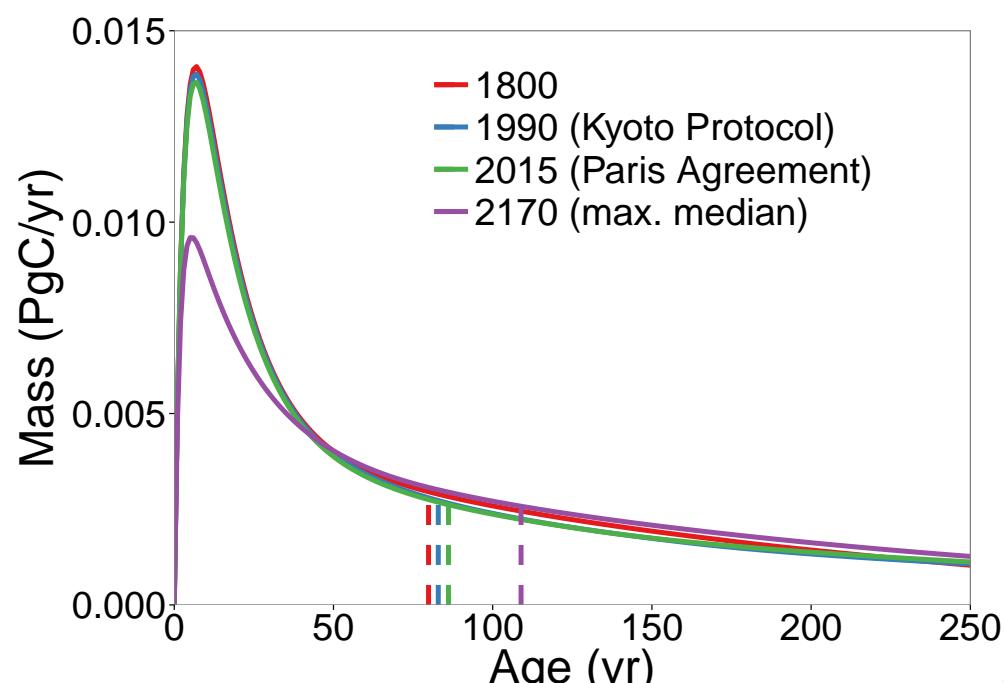
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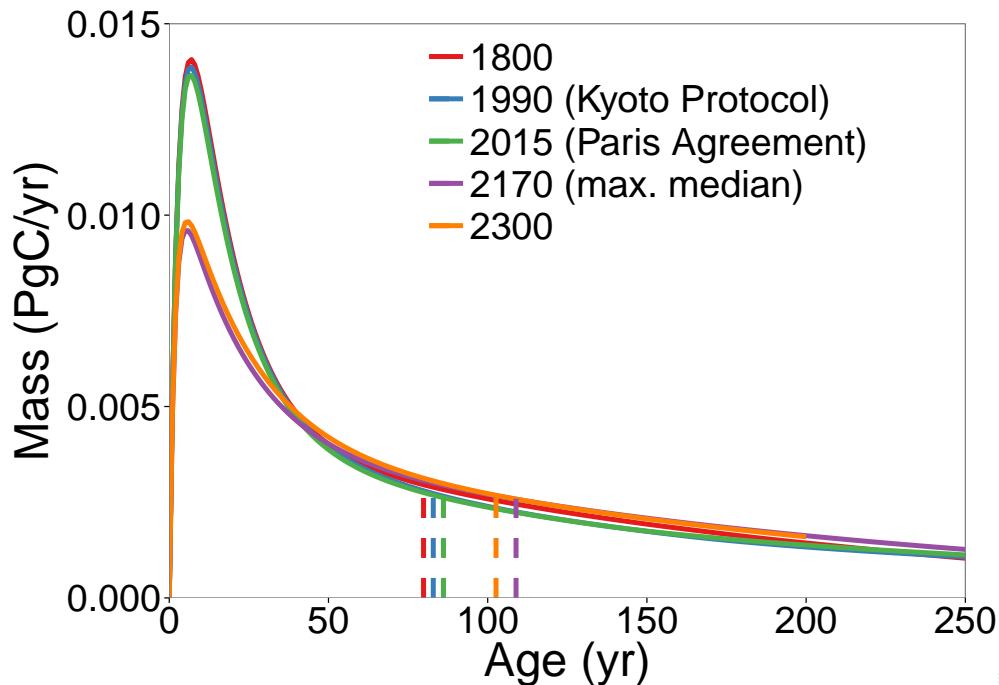
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Pool Models

Markus Müller, Holger Metzler, Carlos Sierra

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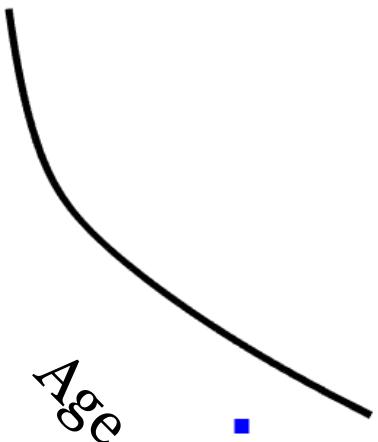
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- **two Python packages**
 - ▶ (symbolic) computation of age and transit time properties for autonomous systems in steady state
 - ★ <http://github.com/goujou/LAPM>
 - ▶ (numerical) computation of age and transit time properties for nonlinear nonautonomous systems



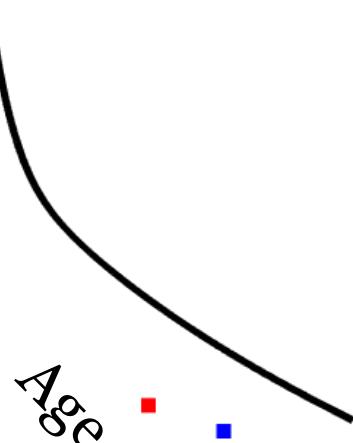
System age



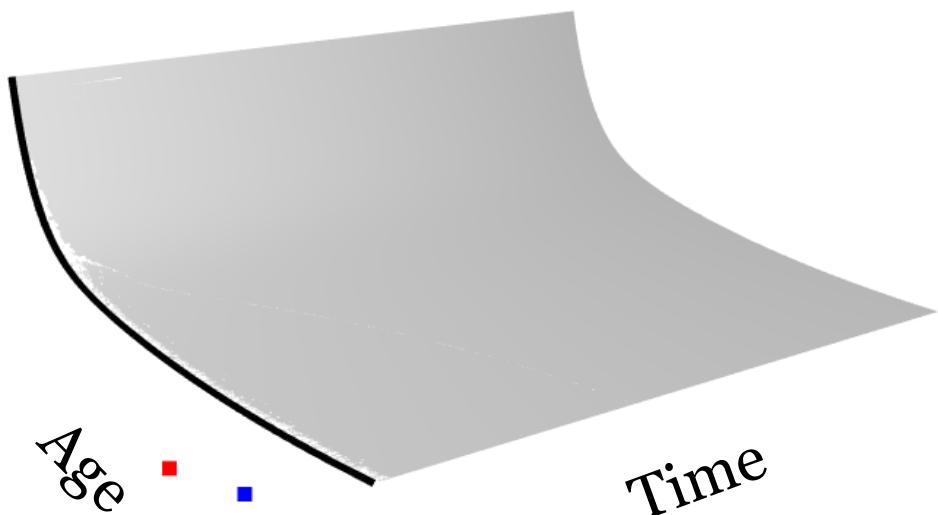
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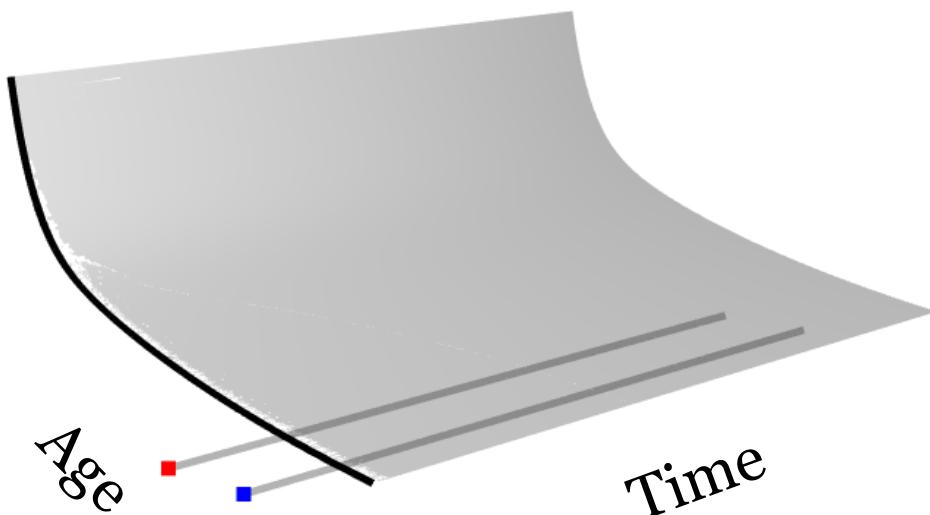
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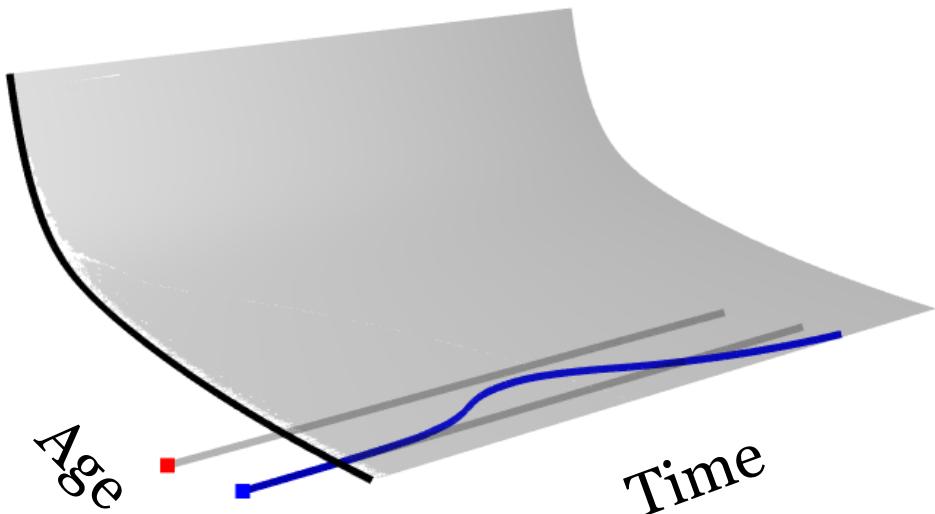
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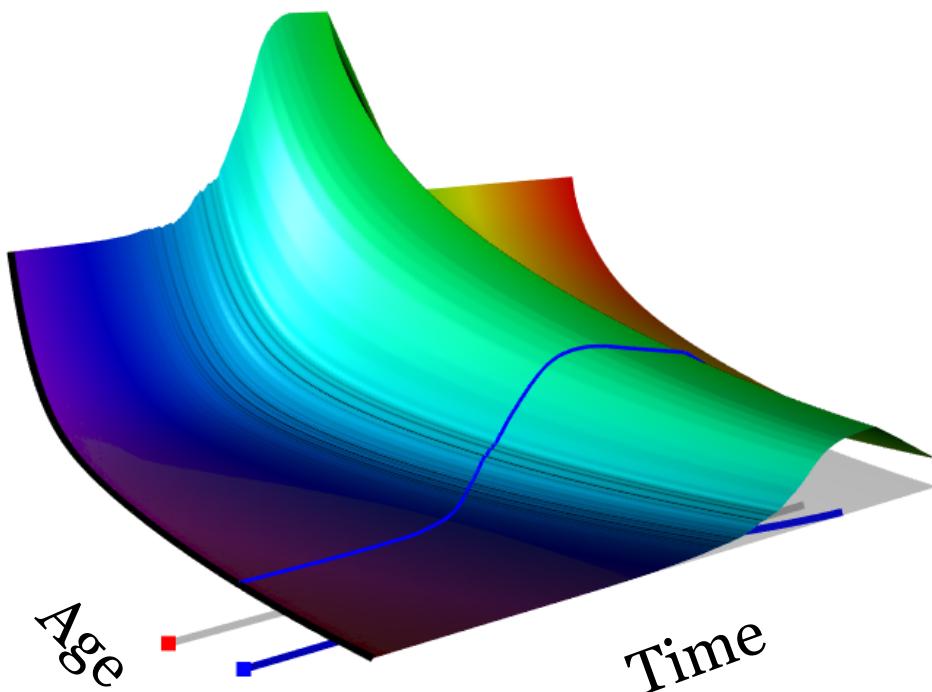
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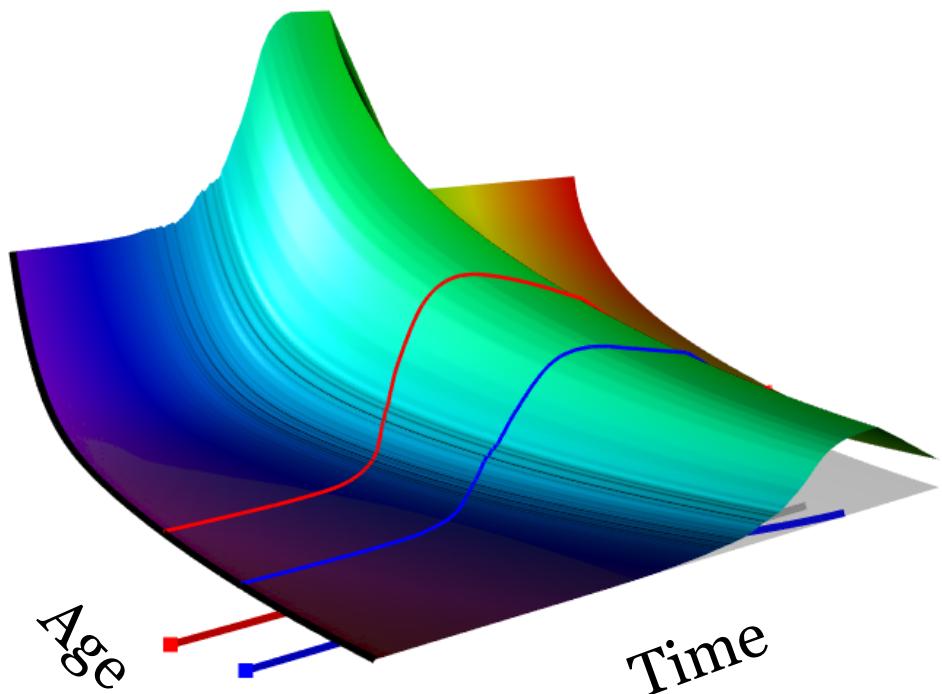
System age



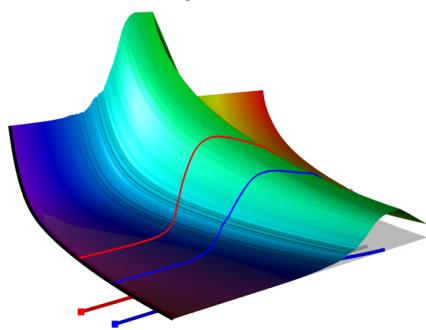
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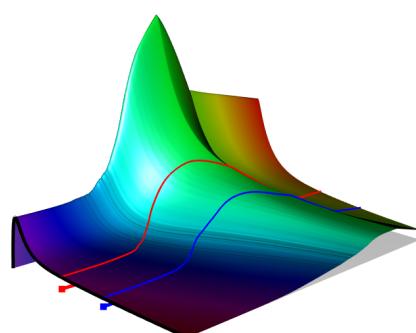
System age



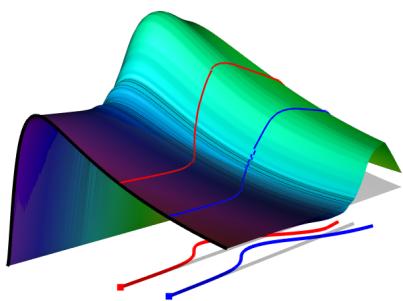
System



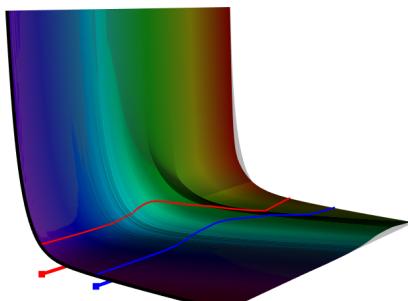
Atmosphere

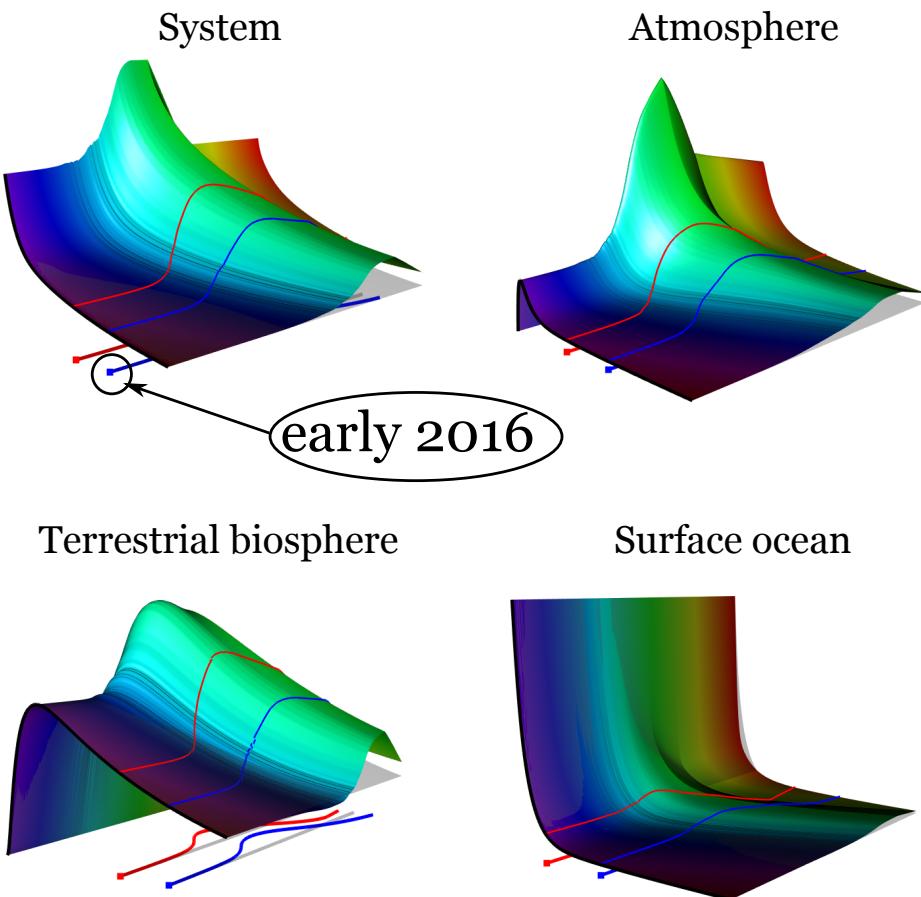


Terrestrial biosphere

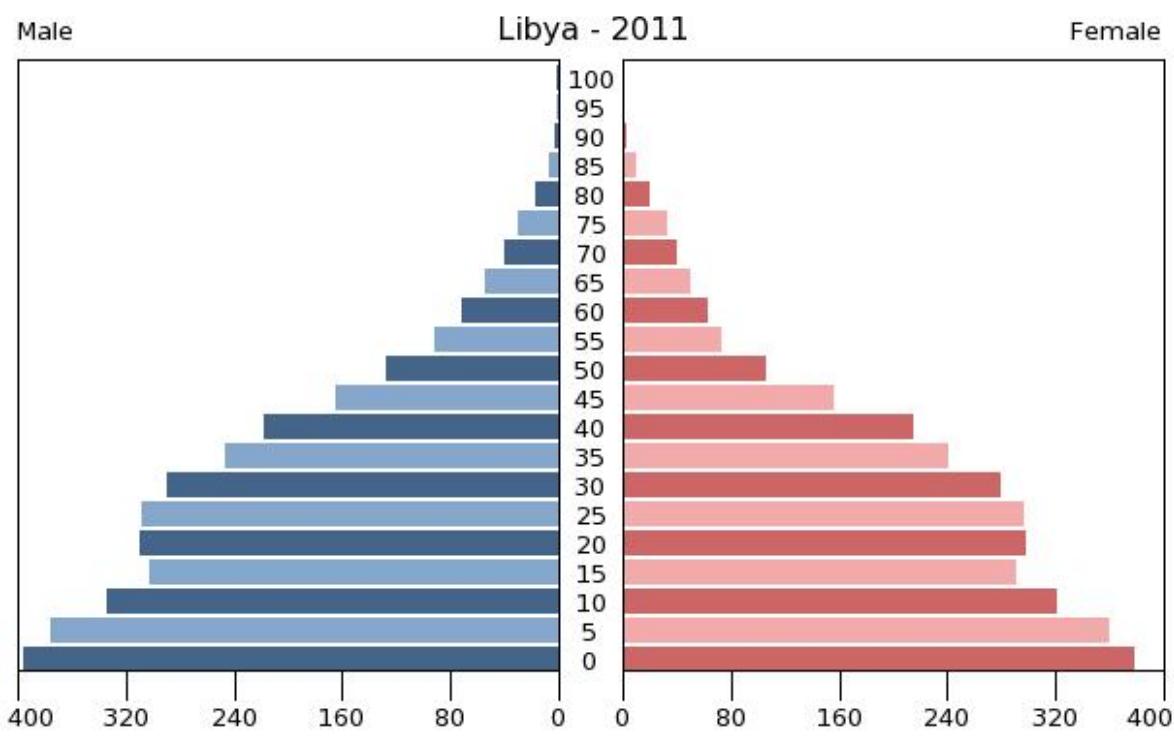


Surface ocean





Population Dynamics $\phi(a)$



distribution varies with time. $\phi(a) = \phi(a, t)$

McKendrick–von Foerster Equation

- original:

$$\frac{\partial \phi}{\partial a} + \frac{\partial \phi}{\partial t} = m(a)\phi$$

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- in compartmental systems

$$\frac{\partial \phi}{\partial a} + \frac{\partial \phi}{\partial t} = m(\textcolor{red}{t})\phi$$

$m(\textcolor{red}{t})$ depends only on time $\textcolor{red}{t}$.

Thanks

Funding



bibliography