

# Non-Relational Numerical Abstract Domains

MPRI 2–6: Abstract Interpretation,  
application to verification and static analysis

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# Outline

- Some **applications** of numerical domains
- Generalities, notations
- Presentation of a few **numerical abstract domains** (non-relational)
  - **sign** domains
  - **constant** domain
  - **interval** domain
  - simple **congruence** domain
- **Reduced products** of domains
- Bibliography

# Selected applications of numerical domains

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# Invariant discovery

Goal: find **intermittent** numerical **invariants**

(at each program point, properties of numerical variables true for all executions)

## Example

```
X:=[0,10]; Y:=100;
```

```
while X>=0 do
```

```
    // loop invariant?
```

```
    X:=X-1;
```

```
    Y:=Y+10
```

```
done
```

```
// value of X and Y?
```

# Invariant discovery

Goal: find **intermittent** numerical **invariants**

(at each program point, properties of numerical variables true for all executions)

## Example

```
X:=[0,10]; Y:=100;  
  //  $x \in [0, 10]$ ,  $y = 100$   
while X>=0 do  
  //  $x \in [0, 10]$ ,  $y \in [100, 200]$   
  X:=X-1;  
  //  $x \in [-1, 9]$ ,  $y \in [100, 200]$   
  Y:=Y+10  
  //  $x \in [-1, 9]$ ,  $y \in [110, 210]$   
done  
//  $x = -1$ ,  $y \in [110, 210]$ 
```

## Variable bounds

# Invariant discovery

Hope: find **the strongest intermittent** numerical **invariants**

(at each program point, **the strongest** properties of numerical variables true for all executions)

## Example

```
X:=[0,10]; Y:=100;  
  //  $x \in [0, 10], y = 100$   
while X>=0 do  
  //  $x \in [0, 10], 10x + y \in [100, 200] \cap 10\mathbb{Z}$   
  X:=X-1;  
  //  $x \in [-1, 9], 10x + y \in [90, 190] \cap 10\mathbb{Z}$   
  Y:=Y+10  
  //  $x \in [-1, 9], 10x + y \in [100, 200] \cap 10\mathbb{Z}$   
done  
//  $x = -1, y \in [110, 210] \cap 10\mathbb{Z}$ 
```

Variable bounds, linear relations and congruences

# Application: proof of absence of run-time error

delay line, in C

```
int delay[10], i;  
for (i=10; i>0; i=i-1)  
    delay[i-1] = 0;  
while (1) {  
    int y = delay[i];  
    delay[i] = input();  
    i = i+1;  
    if (i>=10) i = 0;  
    /* use y */  
}
```

Some operations are **undefined** or dangerous:

- arithmetic operations can overflow
- arrays can be accessed out of bounds

# Application: proof of absence of run-time error

delay line, in C

```
int delay[10], i;
for (i=10; i>0;  $\langle i-1 \in [-2^{31}, 2^{31}-1] \rangle$  i=i-1)
     $\langle i-1 \in [0, 9] \rangle$  delay[i-1] = 0;
while (1) {
    int y =  $\langle i \in [0, 9] \rangle$  delay[i];
     $\langle i \in [0, 9] \rangle$  delay[i] = input();
     $\langle i+1 \in [-2^{31}, 2^{31}-1] \rangle$  i = i+1;
    if (i>=10) i = 0;
    /* use y */
}
```

To prove the absence of run-time error:

- insert **verification conditions**  $\langle \cdot \rangle$  ensuring error-freedom



# Application: proof of absence of run-time error

delay line, in C

```
int delay[10], i;
for (i=10; i>0; (i ∈ [1, 10]) ⟨i - 1 ∈ [-231, 231 - 1]⟩ i=i-1)
    (i ∈ [1, 10]) ⟨i - 1 ∈ [0, 9]⟩ delay[i-1] = 0;
(i = 0) while (1) {
    int y = (i ∈ [0, 9]) ⟨i ∈ [0, 9]⟩ delay[i];
    (i ∈ [0, 9]) ⟨i ∈ [0, 9]⟩ delay[i] = input();
    (i ∈ [0, 9]) ⟨i + 1 ∈ [-231, 231 - 1]⟩ i = i+1;
    (i ∈ [1, 10]) if (i>=10) i = 0 (i ∈ [0, 9]);
    /* use y */
}
```

To prove the absence of run-time error:

- insert **verification conditions**  $\langle \cdot \rangle$  ensuring error-freedom
- infer **invariants**  $(\cdot)$
- check in the abstract that the invariants imply the conditions  
(e.g., reduces to interval inclusion in the interval domain)

# Forward-backward analysis

sign function

```
X:=[-100,100];  
if X=0 then Z:=0 else  
  Y:=X;  
  if Y < 0 then Y:=-Y;  
  Z:=X/Y  
fi
```

# Forward-backward analysis

sign function

```
X:=[-100,100]; ( $X \in [-100, 100]$ )  
if X=0 then Z:=0 else ( $X \in [-100, 100]$ )  
  Y:=X; ( $X, Y \in [-100, 100]$ )  
  if Y < 0 then Y:=-Y; ( $X \in [-100, 100], Y \in [0, 100]$ )  
  Z:=X/Y ( $X \in [-100, 100], Y \in [0, 100]$ )  
fi
```

Forward interval analysis  
(possible division by 0)

# Forward-backward analysis

## sign function

```
X:=[-100,100]; ( $\perp$ )  
if X=0 then Z:=0 else ( $X = 0$ )  
  Y:=X; ( $Y = 0$ )  
  if Y < 0 then Y:=-Y; ( $Y = 0$ )  
  Z:=X/Y ( $Y = 0$ )  
fi
```

## Backward interval analysis

- infer (tight) **necessary conditions** on **inputs** to reach a given point in a given state ( $Y = 0$  at the end of the program)
- **refine** and **focus** the result of a forward analysis (prove the absence of division by zero) [Bour93b]

# Relation analysis

store the maximum of  $X, Y, 0$  into  $Z$

max( $X, Y, Z$ )

```
Z := X ;  
if Y > Z then Z := Y ;  
if Z < 0 then Z := 0 ;
```

# Relation analysis

store the maximum of  $X, Y, 0$  into  $Z'$

max( $X, Y, Z$ )

$X' := X; Y' := Y; Z' := Z;$

$Z' := X';$

if  $Y' > Z'$  then  $Z' := Y';$

if  $Z' < 0$  then  $Z' := 0;$

- **add and rename variables:** keep a copy of input values

# Relation analysis

store the maximum of  $X, Y, 0$  into  $Z'$

max( $X, Y, Z$ )

$X' := X; Y' := Y; Z' := Z;$

$Z' := X';$

if  $Y' > Z'$  then  $Z' := Y';$

if  $Z' < 0$  then  $Z' := 0;$

$(Z' \geq X \wedge Z' \geq Y \wedge Z' \geq 0 \wedge X' = X \wedge Y' = Y)$

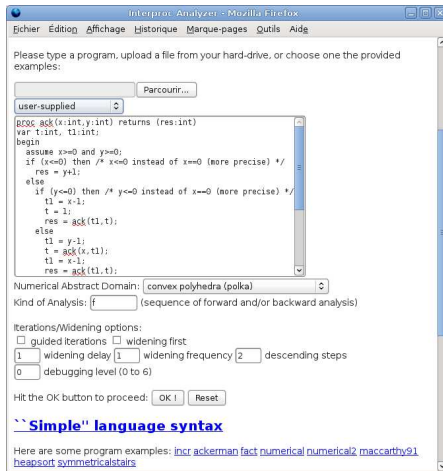
- **add and rename variables:** keep a copy of input values
- infer a **relation** between input values ( $X, Y, Z$ ) and current values ( $X', Y', Z'$ )

**Applications:** procedure summaries, modular analyses. [\[Anco10\]](#)

# Academic implementation: Apron and Interproc

Apron: **library** of numerical abstractions [Jean09]

Interproc: **on-line** analyzer for a **toy** language, based on **Apron**



<http://pop-art.inrialpes.fr/interproc/interprocweb.cgi>



# Applications to non-numerical analyses

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# Pointer offset analysis

## pointer arithmetic

```
float* p = q;  
for (i=0; i<10; i++)  
    if (...) p++;
```

$\rightsquigarrow$

## offset arithmetic

```
unsigned offp = offq;  
for (i=0; i<10; i++)  
    if (...) offp += 4;  
    ( $off_q \leq off_p \leq off_q + 4 \times i + 4$ )
```

In C, pointers can be viewed as **symbolic** integers with:

- a symbolic base
- an **integer offset** ( $off_p, off_q$ )

[Mine06]

# String analysis for C

## pointers and buffers

```
char buf[20];  
char* p;  
  
strcpy(buf, "Hello");  
p = buf+5;  
  
strcpy(p, " world!");
```

In C, strings are **pointers** to arrays of char, terminated by 0:

- **no** explicit information on **available space** (buffer length)
- **no** explicit **length** information (position of 0)
- **aliasing** is possible

⇒ source of many programming errors

# String analysis for C

## pointers and buffers

```
char buf[20]; ( $alloc_{buf} = 20$ )  
char* p;  
 $\langle alloc_{buf} \geq 6 \rangle$   
strcpy(buf, "Hello"); ( $len_{buf} = 5$ )  
p = buf+5; ( $stride_{p-buf} = 5, len_p = len_{buf} - 5, alloc_p = alloc_{buf} - 5$ )  
 $\langle alloc_p \geq 8 \rangle$   
strcpy(p, " world!"); ( $len_p = 7, len_{buf} = len_p + stride_{p-buf}$ )
```

### Analysis of correctness: [Dor01]

- instrument the program with integer **variables**  
( $alloc_p, len_p, stride_{p-q}$ )
- add code to **update** the variables ( $\cdot$ )
- add **safety assertions**  $\langle \cdot \rangle$
- infer invariants and prove that the assertions hold

# Memory shape analysis

list creation and copy into an array

```
cell *x, *head = NULL;
for (i=0; i<n; i++) {
    x = alloc();
    x->next = head; head = x;
}
 $(k \in [0, n-1] \wedge head(->next)^k->data = 0)$ 
for (i=0, x=head; x; x=x->next, i++)
    a[i] = x->data;
 $(k \in [0, n-1] \wedge a[k] = head(->next)^k->data)$ 
```

Numerical analysis on:

- program variables:  $i$ ,  $n$ , and
- instrumentation variables:  $k$ ,  $head(->next)^k->data$ ,  $a[k]$

[Vene02]

# Cost analysis

## selection sort

```
cost = 0;
for i=0 to n-2 do
  for j=i+1 to n-1 do
    if tab[i] > tab[j] then swap(tab[i],tab[j]);
    cost = cost+1
  done
done
```

To count the maximum number of instructions:

- instrument the program with a **counter**

# Cost analysis

## selection sort

```
cost = 0;
for i=0 to n-2 do ( $cost = i \times n - i \times (i + 1)/2$ )
  for j=i+1 to n-1 do ( $cost = i \times n - i \times (i + 1)/2 + j - i - 1$ )
    if tab[i] > tab[j] then swap(tab[i],tab[j]);
    cost = cost+1
  done
done
( $cost = (n + 1) \times (n - 2)/2$ )
```

To count the maximum number of instructions:

- instrument the program with a **counter**
- infer loop and exit **invariants** ( $\cdot$ )

# Dependency analysis for array indices

## multiplication of polynomials

```
for i=1 to n do
  for j=1 to n do
    v := r[i+j] •;
    ♠ r[i+j] := v + a[i] * b[j];
    t := t+1
  done
done
```

Can a **read** at **•** depend on a previous **write** from **♠**?

- add a global counter **t** (allows expressing temporal properties)
- infer an invariant set  $X \in \mathbb{Z}^3$  for  $t, i, j$
- check  $\exists((t, i, j), (t', i', j')) \in X \times X, t > t', i + j = i' + j'$

Information used by compilers to enable loop transformations [Girb06].



# Generalities and notations

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# Syntax

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# Expression syntax

## Toy language:

- fixed, **finite** set of variables  $\mathbb{V}$ ,
- **one datatype**: scalars in  $\mathbb{I}$ , with  $\mathbb{I} \in \{\mathbb{Z}, \mathbb{Q}, \mathbb{R}\}$   
(and later, floating-point numbers  $\mathbb{F}$ )
- no procedure

## arithmetic expressions:

$\text{exp}$	$::=$	$V$	variable $V \in \mathbb{V}$
		$-\text{exp}$	negation
		$\text{exp} \diamond \text{exp}$	binary operation: $\diamond \in \{+, -, \times, /\}$
		$[c, c']$	constant range, $c, c' \in \mathbb{I} \cup \{\pm\infty\}$
			$c$ is a shorthand for $[c, c]$

# Programs (structured syntax)

programs: as syntax trees

`prog ::=`

	<code>V := exp</code>	assignment
	<code>if exp <math>\bowtie</math> 0 then prog else prog fi</code>	test
	<code>while exp <math>\bowtie</math> 0 do prog done</code>	loop
	<code>prog; prog</code>	sequence
	<code><math>\epsilon</math></code>	no-op

comparison operators:  $\bowtie \in \{=, <, >, <=, >=, <>\}$ .

# Programs (as control-flow graphs)

## commands:

$\text{com}$	$::=$	$V := \text{exp}$	assignment into $V \in \mathbb{V}$
	$ $	$\text{exp} \bowtie 0$	test, $\bowtie \in \{=, <, >, <=, >=, <>\}$

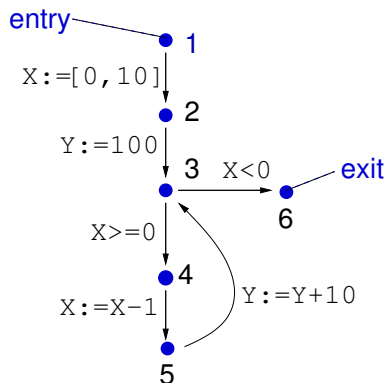
## programs: as control-flow graphs

$P \stackrel{\text{def}}{=} (L, e, x, A)$	$L$	program points (labels)
	$e$	entry point: $e \in L$
	$x$	exit point: $x \in L$
	$A$	arcs: $A \subseteq L \times \text{com} \times L$

# Example

```
1X := [0, 10] ; 2  
Y := 100 ;  
while 3X ≥ 0 do 4  
    X := X - 1 ; 5  
    Y := Y + 10  
done 6
```

structured program



control flow  
graph

# Concrete semantics

---

# Forward concrete semantics

Semantics of expressions:  $E[e]: (\mathbb{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathbb{I})$

The evaluation of  $e$  in  $\rho$  gives a **set** of values:

$$\begin{aligned}
 E[[c, c']] \rho & \stackrel{\text{def}}{=} \{x \in \mathbb{I} \mid c \leq x \leq c'\} \\
 E[[v]] \rho & \stackrel{\text{def}}{=} \{\rho(v)\} \\
 E[[-e]] \rho & \stackrel{\text{def}}{=} \{-v \mid v \in E[[e]] \rho\} \\
 E[[e_1 + e_2]] \rho & \stackrel{\text{def}}{=} \{v_1 + v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\} \\
 E[[e_1 - e_2]] \rho & \stackrel{\text{def}}{=} \{v_1 - v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\} \\
 E[[e_1 \times e_2]] \rho & \stackrel{\text{def}}{=} \{v_1 \times v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\} \\
 E[[e_1 / e_2]] \rho & \stackrel{\text{def}}{=} \{v_1 / v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho, v_2 \neq 0\}
 \end{aligned}$$



# Forward concrete semantics (cont.)

**Semantics of commands:**  $C\llbracket c \rrbracket : \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$

A **transfer function** for  $c$  defines a **relation** on environments:

$$\begin{aligned} C\llbracket v := e \rrbracket \mathcal{X} &\stackrel{\text{def}}{=} \{ \rho[ v \mapsto v ] \mid \rho \in \mathcal{X}, v \in E\llbracket e \rrbracket \rho \} \\ C\llbracket e \bowtie 0 \rrbracket \mathcal{X} &\stackrel{\text{def}}{=} \{ \rho \mid \rho \in \mathcal{X}, \exists v \in E\llbracket e \rrbracket \rho, v \bowtie 0 \} \end{aligned}$$

It relates the environments after the execution of a command to the environments before.

Complete **join morphism**:  $C\llbracket c \rrbracket \mathcal{X} = \bigcup_{\rho \in \mathcal{X}} C\llbracket c \rrbracket \{ \rho \}.$

# Forward concrete semantics (cont.)

**Semantics of programs:**  $P[(L, e, x, A)] : L \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$

$P[(L, e, x, A)] \ell$  is the **most precise invariant** at  $\ell \in L$ .

It is the **smallest** solution of a recursive equation system  $(\mathcal{X}_\ell)_{\ell \in L}$ :

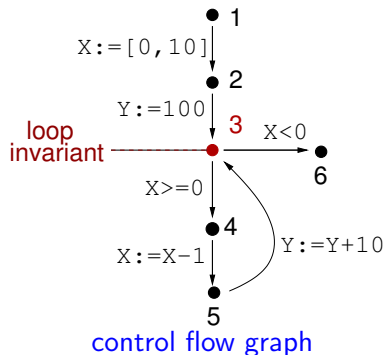
## Semantic equation system

$$\begin{aligned} \mathcal{X}_e & \quad \text{(given initial state)} \\ \mathcal{X}_{\ell \neq e} &= \bigcup_{(\ell', c, \ell) \in A} C[c] \mathcal{X}_{\ell'} \quad \text{(transfer function)} \end{aligned}$$

Tarski's Theorem: this smallest solution exists and is unique.

- $\mathcal{D} \stackrel{\text{def}}{=} (\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I}), \subseteq, \cup, \cap, \emptyset, (\mathbb{V} \rightarrow \mathbb{I}))$  is a complete lattice,
- each  $M_\ell : \mathcal{X}_\ell \mapsto \bigcup_{(\ell', c, \ell) \in A} C[c] \mathcal{X}_{\ell'}$  is monotonic in  $\mathcal{D}$ .  
 $\Rightarrow$  the solution is the least fixpoint of  $(M_\ell)_{\ell \in L}$ .

# Forward concrete semantics (example)



$$\left\{ \begin{array}{l} \mathcal{X}_1 = (\{X, Y\} \rightarrow \mathbb{Z}) \\ \mathcal{X}_2 = C[\![X := [0, 10]]\!] \mathcal{X}_1 \\ \mathcal{X}_3 = C[\![Y := 100]]\!] \mathcal{X}_2 \cup \\ \quad C[\![Y := Y + 10]]\!] \mathcal{X}_5 \\ \mathcal{X}_4 = C[\![X \geq 0]]\!] \mathcal{X}_3 \\ \mathcal{X}_5 = C[\![X := X - 1]]\!] \mathcal{X}_4 \\ \mathcal{X}_6 = C[\![X < 0]]\!] \mathcal{X}_3 \end{array} \right.$$

equation system

Loop invariant:

$$\mathcal{X}_3 = \{ \rho \mid \rho(X) \in [0, 10], 10\rho(X) + \rho(Y) \in [100, 200] \cap 10\mathbb{Z} \}$$

# Resolution

## Resolution by increasing iterations:

$$\left\{ \begin{array}{l} x_e^0 \\ x_{\ell \neq e}^0 \end{array} \right. \stackrel{\text{def}}{=} \left\{ \begin{array}{l} x_e \\ \emptyset \end{array} \right. \quad \left\{ \begin{array}{l} x_e^{n+1} \\ x_{\ell \neq e}^{n+1} \end{array} \right. \stackrel{\text{def}}{=} \left\{ \begin{array}{l} x_e \\ \bigcup_{(\ell', c, \ell) \in A} C[[c]] x_{\ell'}^n \end{array} \right.$$

Converges in  $\omega$  iterations to a least solution,  
 because each  $C[[c]]$  is continuous in the CPO  $\mathcal{D}$ .  
 (Kleene fixpoint theorem)

# Resolution (example)

$$\left\{ \begin{array}{ll}
 \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\
 \mathcal{X}_2 = C[\![X := [0, 10]]\!] \mathcal{X}_1 & \emptyset \\
 \mathcal{X}_3 = C[\![Y := 100]]\! \mathcal{X}_2 \cup C[\![Y := Y + 10]]\! \mathcal{X}_5 & \emptyset \\
 \mathcal{X}_4 = C[\![X \geq 0]]\! \mathcal{X}_3 & \emptyset \\
 \mathcal{X}_5 = C[\![X := X - 1]]\! \mathcal{X}_4 & \emptyset \\
 \mathcal{X}_6 = C[\![X < 0]]\! \mathcal{X}_3 & \emptyset
 \end{array} \right. \quad \text{iteration 0}$$

# Resolution (example)

$$\left\{ \begin{array}{ll}
 \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\
 \mathcal{X}_2 = C[\![X := [0, 10]]\!] \mathcal{X}_1 & [0, 10] \times \mathbb{Z} \\
 \mathcal{X}_3 = C[\![Y := 100]]\! \mathcal{X}_2 \cup C[\![Y := Y + 10]]\! \mathcal{X}_5 & \emptyset \\
 \mathcal{X}_4 = C[\![X \geq 0]]\! \mathcal{X}_3 & \emptyset \\
 \mathcal{X}_5 = C[\![X := X - 1]]\! \mathcal{X}_4 & \emptyset \\
 \mathcal{X}_6 = C[\![X < 0]]\! \mathcal{X}_3 & \emptyset
 \end{array} \right. \quad \text{iteration 1}$$

# Resolution (example)

$$\left\{ \begin{array}{ll}
 \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\
 \mathcal{X}_2 = C[\![X := [0, 10]]\!] \mathcal{X}_1 & [0, 10] \times \mathbb{Z} \\
 \mathcal{X}_3 = C[\![Y := 100]]\!] \mathcal{X}_2 \cup C[\![Y := Y + 10]]\!] \mathcal{X}_5 & \{(0, 100), \dots, (10, 100)\} \\
 \mathcal{X}_4 = C[\![X \geq 0]]\!] \mathcal{X}_3 & \emptyset \\
 \mathcal{X}_5 = C[\![X := X - 1]]\!] \mathcal{X}_4 & \emptyset \\
 \mathcal{X}_6 = C[\![X < 0]]\!] \mathcal{X}_3 & \emptyset
 \end{array} \right. \quad \text{iteration 2}$$

# Resolution (example)

$$\left\{ \begin{array}{ll}
 \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\
 \mathcal{X}_2 = C[\![X := [0, 10]]\!] \mathcal{X}_1 & [0, 10] \times \mathbb{Z} \\
 \mathcal{X}_3 = C[\![Y := 100]]\! \mathcal{X}_2 \cup C[\![Y := Y + 10]]\! \mathcal{X}_5 & \{(0, 100), \dots, (10, 100)\} \\
 \mathcal{X}_4 = C[\![X \geq 0]]\! \mathcal{X}_3 & \{(0, 100), \dots, (10, 100)\} \\
 \mathcal{X}_5 = C[\![X := X - 1]]\! \mathcal{X}_4 & \emptyset \\
 \mathcal{X}_6 = C[\![X < 0]]\! \mathcal{X}_3 & \emptyset
 \end{array} \right. \quad \text{iteration 3}$$



# Resolution (example)

	iteration 4
$\mathcal{X}_1 = \mathbb{Z}^2$	$\mathbb{Z}^2$
$\mathcal{X}_2 = C[X := [0, 10]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[Y := 100] \mathcal{X}_2 \cup C[Y := Y + 10] \mathcal{X}_5$	$\{(0, 100), \dots, (10, 100)\}$
$\mathcal{X}_4 = C[X \geq 0] \mathcal{X}_3$	$\{(0, 100), \dots, (10, 100)\}$
$\mathcal{X}_5 = C[X := X - 1] \mathcal{X}_4$	$\{(-1, 100), \dots, (9, 100)\}$
$\mathcal{X}_6 = C[X < 0] \mathcal{X}_3$	$\emptyset$

# Resolution (example)

$$\left\{ \begin{array}{ll}
 \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\
 \mathcal{X}_2 = C[\![X := [0, 10]]\!] \mathcal{X}_1 & [0, 10] \times \mathbb{Z} \\
 \mathcal{X}_3 = C[\![Y := 100]]\!] \mathcal{X}_2 \cup C[\![Y := Y + 10]]\!] \mathcal{X}_5 & \{ (0, 100), \dots, (10, 100), \\ & (-1, 110), \dots, (9, 110) \} \\
 \mathcal{X}_4 = C[\![X \geq 0]]\!] \mathcal{X}_3 & \{ (0, 100), \dots, (10, 100) \} \\
 \mathcal{X}_5 = C[\![X := X - 1]]\!] \mathcal{X}_4 & \{ (-1, 100), \dots, (9, 100) \} \\
 \mathcal{X}_6 = C[\![X < 0]]\!] \mathcal{X}_3 & \emptyset
 \end{array} \right. \quad \text{iteration 5}$$

# Resolution (example)

$$\left\{ \begin{array}{ll}
 \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\
 \mathcal{X}_2 = C[\![X := [0, 10]]\!] \mathcal{X}_1 & [0, 10] \times \mathbb{Z} \\
 \mathcal{X}_3 = C[\![Y := 100]]\!] \mathcal{X}_2 \cup C[\![Y := Y + 10]]\!] \mathcal{X}_5 & \{ (0, 100), \dots, (10, 100), \\
 & (-1, 110), \dots, (9, 110) \} \\
 \mathcal{X}_4 = C[\![X \geq 0]]\!] \mathcal{X}_3 & \{ (0, 100), \dots, (10, 100), \\
 & (0, 110), \dots, (9, 110) \} \\
 \mathcal{X}_5 = C[\![X := X - 1]]\!] \mathcal{X}_4 & \{ (-1, 100), \dots, (9, 100) \} \\
 \mathcal{X}_6 = C[\![X < 0]]\!] \mathcal{X}_3 & \{ (-1, 110) \}
 \end{array} \right. \quad \text{iteration 6}$$

# Resolution (example)

	iteration 7
$\mathcal{X}_1 = \mathbb{Z}^2$	$\mathbb{Z}^2$
$\mathcal{X}_2 = C[\![X := [0, 10]]\!] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[\![Y := 100]\!] \mathcal{X}_2 \cup C[\![Y := Y + 10]\!] \mathcal{X}_5$	$\{ (0, 100), \dots, (10, 100), \\ (-1, 110), \dots, (9, 110) \}$
$\mathcal{X}_4 = C[\![X \geq 0]\!] \mathcal{X}_3$	$\{ (0, 100), \dots, (10, 100), \\ (0, 110), \dots, (9, 110) \}$
$\mathcal{X}_5 = C[\![X := X - 1]\!] \mathcal{X}_4$	$\{ (-1, 100), \dots, (9, 100), \\ (-1, 110), \dots, (8, 110) \}$
$\mathcal{X}_6 = C[\![X < 0]\!] \mathcal{X}_3$	$\{ (-1, 110) \}$

# Resolution (example)

	iteration 8
$\mathcal{X}_1 = \mathbb{Z}^2$	$\mathbb{Z}^2$
$\mathcal{X}_2 = C[X := [0, 10]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[Y := 100] \mathcal{X}_2 \cup C[Y := Y + 10] \mathcal{X}_5$	$\{ (0, 100), \dots, (10, 100),$ $(-1, 110), \dots, (9, 110),$ $(-1, 120), \dots, (8, 120) \}$
$\mathcal{X}_4 = C[X \geq 0] \mathcal{X}_3$	$\{ (0, 100), \dots, (10, 100),$ $(0, 110), \dots, (9, 110) \}$
$\mathcal{X}_5 = C[X := X - 1] \mathcal{X}_4$	$\{ (-1, 100), \dots, (9, 100),$ $(-1, 110), \dots, (8, 110) \}$
$\mathcal{X}_6 = C[X < 0] \mathcal{X}_3$	$\{ (-1, 110) \}$

# Resolution (example)

	iteration 9
$\mathcal{X}_1 = \mathbb{Z}^2$	$\mathbb{Z}^2$
$\mathcal{X}_2 = C[X := [0, 10]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[Y := 100] \mathcal{X}_2 \cup C[Y := Y + 10] \mathcal{X}_5$	$\{ (0, 100), \dots, (10, 100),$ $(-1, 110), \dots, (9, 110),$ $(-1, 120), \dots, (8, 120) \}$
$\mathcal{X}_4 = C[X \geq 0] \mathcal{X}_3$	$\{ (0, 100), \dots, (10, 100),$ $(0, 110), \dots, (9, 110),$ $(0, 120), \dots, (8, 120) \}$
$\mathcal{X}_5 = C[X := X - 1] \mathcal{X}_4$	$\{ (-1, 100), \dots, (9, 100),$ $(-1, 110), \dots, (8, 110) \}$
$\mathcal{X}_6 = C[X < 0] \mathcal{X}_3$	$\{ (-1, 110), (-1, 120) \}$

# Resolution (example)

	iteration 10
$\mathcal{X}_1 = \mathbb{Z}^2$	$\mathbb{Z}^2$
$\mathcal{X}_2 = C[X := [0, 10]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[Y := 100] \mathcal{X}_2 \cup C[Y := Y + 10] \mathcal{X}_5$	$\{ (0, 100), \dots, (10, 100),$ $(-1, 110), \dots, (9, 110),$ $(-1, 120), \dots, (8, 120) \}$
$\mathcal{X}_4 = C[X \geq 0] \mathcal{X}_3$	$\{ (0, 100), \dots, (10, 100),$ $(0, 110), \dots, (9, 110),$ $(0, 120), \dots, (8, 120) \}$
$\mathcal{X}_5 = C[X := X - 1] \mathcal{X}_4$	$\{ (-1, 100), \dots, (9, 100),$ $(-1, 110), \dots, (8, 110),$ $(-1, 120), \dots, (7, 120) \}$
$\mathcal{X}_6 = C[X < 0] \mathcal{X}_3$	$\{ (-1, 110), (-1, 120) \}$

# Resolution (example)

{	$\mathcal{X}_1 = \mathbb{Z}^2$	iteration ... $\mathbb{Z}^2$
	$\mathcal{X}_2 = C[X := [0, 10]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
	$\mathcal{X}_3 = C[Y := 100] \mathcal{X}_2 \cup C[Y := Y + 10] \mathcal{X}_5$	$\{ (0, 100), \dots, (10, 100),$ $(-1, 110), \dots, (9, 110),$ $(-1, 120), \dots, (8, 120), \dots \}$
	$\mathcal{X}_4 = C[X \geq 0] \mathcal{X}_3$	$\{ (0, 100), \dots, (10, 100),$ $(0, 110), \dots, (9, 110),$ $(0, 120), \dots, (8, 120), \dots \}$
	$\mathcal{X}_5 = C[X := X - 1] \mathcal{X}_4$	$\{ (-1, 100), \dots, (9, 100),$ $(-1, 110), \dots, (8, 110),$ $(-1, 120), \dots, (7, 120), \dots \}$
	$\mathcal{X}_6 = C[X < 0] \mathcal{X}_3$	$\{ (-1, 110), (-1, 120), \dots \}$



# Backward concrete semantics

**Semantics of commands:**  $\overleftarrow{C}[[c]]: \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$

$$\begin{aligned} \overleftarrow{C}[[v := e]] \mathcal{X} &\stackrel{\text{def}}{=} \{ \rho \mid \exists v \in E[[e]] \rho, \rho[v \mapsto v] \in \mathcal{X} \} \\ \overleftarrow{C}[[e \bowtie 0]] \mathcal{X} &\stackrel{\text{def}}{=} C[[e \bowtie 0]] \mathcal{X} \end{aligned}$$

(necessary conditions on  $\rho$  to have a successor in  $\mathcal{X}$  by  $c$ )

Refinement decreasing iterations: given:

- a solution  $(\mathcal{X}_\ell)_{\ell \in L}$  of the forward system
- an output criterion  $\mathcal{Y}_x$

compute a least fixpoint by decreasing iterations [Bour93b]

$$\begin{cases} \mathcal{Y}_x^0 &\stackrel{\text{def}}{=} \mathcal{X}_x \cap \mathcal{Y}_x \\ \mathcal{Y}_{\ell \neq x}^0 &\stackrel{\text{def}}{=} \mathcal{X}_\ell \\ \mathcal{Y}_x^{n+1} &\stackrel{\text{def}}{=} \mathcal{X}_x \cap \mathcal{Y}_x \\ \mathcal{Y}_{\ell \neq x}^{n+1} &\stackrel{\text{def}}{=} \mathcal{X}_\ell \cap \left( \bigcup_{(\ell, c, \ell') \in A} \overleftarrow{C}[[c]] \mathcal{Y}_{\ell'}^n \right) \end{cases}$$

# Limit to automation

We wish to perform **automatic** numerical invariant discovery.

## Theoretical problems

- elements of  $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$  are **not computer representable**
- transfer functions  $C\llbracket c \rrbracket, \overleftarrow{C}\llbracket c \rrbracket$  are **not computable**
- lattice iterations in  $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$  are **transfinite**

**Finding the best invariant is an **undecidable** problem**

## Note:

Even when  $\mathbb{I}$  is finite, a concrete analysis is **not tractable**:

- representing elements in  $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$  in extension is expensive
- computing  $C\llbracket c \rrbracket, \overleftarrow{C}\llbracket c \rrbracket$  explicitly is expensive
- the lattice  $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$  has a large height ( $\Rightarrow$  many iterations)

# Abstraction

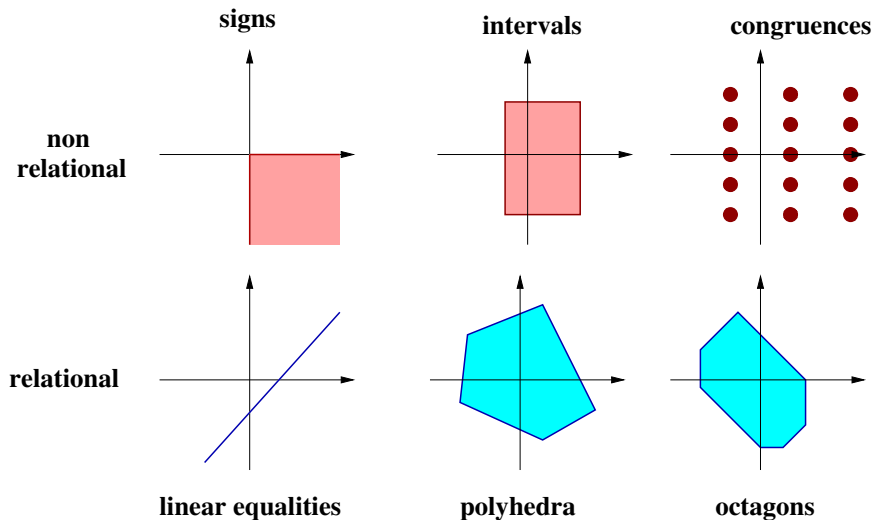
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# Numerical abstract domains

A **numerical abstract domain** is given by:

- a subset of  $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$   
(a set of environment sets)  
together with a machine encoding,
- effective and sound abstract operators,
- an iteration strategy  
ensuring convergence in finite time.

# Numerical abstract domain examples



# Numerical abstract domains (cont.)

**Representation:** given by

- a set  $\mathcal{D}^\#$  of machine-representable abstract values,
- a **partial order**  $(\mathcal{D}^\#, \sqsubseteq, \perp^\#, \top^\#)$   
relating the amount of information given by abstract values,
- a **concretization** function  $\gamma: \mathcal{D}^\# \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$   
giving a concrete meaning to each abstract element.

Required algebraic properties:

- $\gamma$  should be **monotonic** for  $\sqsubseteq$ :  $\mathcal{X}^\# \sqsubseteq \mathcal{Y}^\# \implies \gamma(\mathcal{X}^\#) \subseteq \gamma(\mathcal{Y}^\#)$ ,
- $\gamma(\perp^\#) = \emptyset$ ,
- $\gamma(\top^\#) = \mathbb{V} \rightarrow \mathbb{I}$ .

Note:  $\gamma$  need not be one-to-one.

# Numerical abstract domains (cont.)

Abstract operators: we require:

- sound, effective, abstract **transfer functions**  $C^\# \llbracket c \rrbracket$ ,  $\overleftarrow{C}^\# \llbracket c \rrbracket$  for all commands  $c$ ,
- sound, effective, abstract **set operators**  $\cup^\#$ ,  $\cap^\#$ ,
- an algorithm to decide the **ordering**  $\sqsubseteq$ .

Soundness criterion:

$F^\#$  is a **sound** abstraction of a  $n$ -ary operator  $F$  if:

$$\forall x_1^\#, \dots, x_n^\# \in D^\#, F(\gamma(x_1^\#), \dots, \gamma(x_n^\#)) \subseteq \gamma(F^\#(x_1^\#, \dots, x_n^\#))$$

Both **semantic** and **algorithmic** aspects.

# Abstract semantics

## Abstract semantic equation system

$$\mathcal{X}^\# : L \rightarrow \mathcal{D}^\#$$

$$\mathcal{X}_\ell^\# \sqsupseteq \begin{cases} \mathcal{X}_e^\# & \text{if } \ell = e \\ \bigcup_{(\ell', c, \ell) \in A} C^\# \llbracket c \rrbracket \mathcal{X}_{\ell'}^\# & \text{if } \ell \neq e \end{cases} \quad \begin{array}{l} \text{(where } \mathcal{X}_e \subseteq \gamma(\mathcal{X}_e^\#)) \\ \text{(abstract transfer function)} \end{array}$$

## Soundness Theorem

Any solution  $(\mathcal{X}_\ell^\#)_{\ell \in L}$  is a **sound over-approximation** of the concrete collecting semantics:

$$\forall \ell \in L, \gamma(\mathcal{X}_\ell^\#) \supseteq \mathcal{X}_\ell \quad \left| \quad \begin{array}{l} \text{where } \mathcal{X}_\ell \text{ is the smallest solution of} \\ \left\{ \begin{array}{ll} \mathcal{X}_e & \text{given} \\ \mathcal{X}_\ell = \bigcup_{(\ell', c, \ell) \in A} C \llbracket c \rrbracket \mathcal{X}_{\ell'} & \text{if } \ell \neq e \end{array} \right. \end{array} \right.$$



# Iteration strategy

Resolution by iterations in  $\mathcal{D}^\sharp$ :

To **effectively** solve the abstract system, we require:

- an **iteration ordering** on abstract equations  
(which equation(s) are applied at a given iteration)
- a **widening operator**  $\nabla$  to speed-up the convergence,  
if there are infinite strictly increasing chains in  $\mathcal{D}^\sharp$ .

$\nabla : (\mathcal{D}^\sharp \times \mathcal{D}^\sharp) \rightarrow \mathcal{D}^\sharp$  is a widening if:

- it is sound:  $\gamma(\mathcal{X}^\sharp) \cup \gamma(\mathcal{Y}^\sharp) \subseteq \gamma(\mathcal{X}^\sharp \nabla \mathcal{Y}^\sharp)$

- it enforces termination:

$\forall$  sequence  $(\mathcal{Y}_i^\sharp)_{i \in \mathbb{N}}$

the sequence  $\mathcal{X}_0^\sharp = \mathcal{Y}_0^\sharp$ ,  $\mathcal{X}_{i+1}^\sharp = \mathcal{X}_i^\sharp \nabla \mathcal{Y}_{i+1}^\sharp$

stabilizes in finite time:  $\exists n < \omega$ ,  $\mathcal{X}_{n+1}^\sharp = \mathcal{X}_n^\sharp$

(note:  $\exists n, \forall m \geq n$ ,  $\mathcal{X}_{m+1}^\sharp = \mathcal{X}_m^\sharp$  is **not** required)

# Abstract analysis

$\mathcal{W} \subseteq L$  is a set of **widening points** if every CFG cycle has a point in  $\mathcal{W}$ .

## Forward analysis:

$$\mathcal{X}_e^{\#0} \stackrel{\text{def}}{=} \mathcal{X}_e^{\#} \quad \text{given, such that } \mathcal{X}_e \subseteq \gamma(\mathcal{X}_e^{\#})$$

$$\mathcal{X}_{\ell \neq e}^{\#0} \stackrel{\text{def}}{=} \perp^{\#}$$

$$\mathcal{X}_{\ell}^{\#n+1} \stackrel{\text{def}}{=} \begin{cases} \mathcal{X}_e^{\#} & \text{if } \ell = e \\ \bigcup_{(\ell', c, \ell) \in A} C^{\#} \llbracket c \rrbracket \mathcal{X}_{\ell'}^{\#n} & \text{if } \ell \notin \mathcal{W}, \ell \neq e \\ \mathcal{X}_{\ell}^{\#n} \nabla \bigcup_{(\ell', c, \ell) \in A} C^{\#} \llbracket c \rrbracket \mathcal{X}_{\ell'}^{\#n} & \text{if } \ell \in \mathcal{W}, \ell \neq e \end{cases}$$

- **termination**: for some  $\delta$ ,  $\forall \ell, \mathcal{X}_{\ell}^{\#\delta+1} = \mathcal{X}_{\ell}^{\#\delta}$
- **soundness**:  $\forall \ell \in L, \mathcal{X}_{\ell} \subseteq \gamma(\mathcal{X}_{\ell}^{\#\delta})$
- can be refined by decreasing iterations with narrowing  $\Delta$  (presented later)
- here, apply every equation at each step, but other iteration scheme are possible (worklist, chaotic iterations, see [Bour93a])

# Abstract analysis (proof)

Proof of soundness:

Suppose that  $\forall \ell, \mathcal{X}_\ell^{\# \delta+1} = \mathcal{X}_\ell^{\# \delta}$ .

If  $\ell = e$ , by definition:  $\mathcal{X}_e^{\# \delta} = \mathcal{X}_e^{\#}$  and  $\mathcal{X}_e \subseteq \gamma(\mathcal{X}_e^{\# \delta})$ .

If  $\ell \neq e$ ,  $\ell \notin \mathcal{W}$ , then  $\mathcal{X}_\ell^{\# \delta} = \mathcal{X}_\ell^{\# \delta+1} = \bigcup_{(\ell', c, \ell) \in A} \mathcal{C}^{\#}[\![c]\!] \mathcal{X}_{\ell'}^{\# \delta}$ .

By soundness of  $\bigcup^{\#}$  and  $\mathcal{C}^{\#}[\![c]\!]$ ,  $\gamma(\mathcal{X}_\ell^{\# \delta}) \supseteq \bigcup_{(\ell', c, \ell) \in A} \mathcal{C}[\![c]\!] \gamma(\mathcal{X}_{\ell'}^{\# \delta})$ .

If  $\ell \neq e$ ,  $\ell \in \mathcal{W}$ , then  $\mathcal{X}_\ell^{\# \delta} = \mathcal{X}_\ell^{\# \delta+1} = \mathcal{X}_\ell^{\# \delta} \nabla \bigcup_{(\ell', c, \ell) \in A} \mathcal{C}^{\#}[\![c]\!] \mathcal{X}_{\ell'}^{\# \delta}$ .

By soundness of  $\nabla$ ,  $\gamma(\mathcal{X}_\ell^{\# \delta}) \supseteq \gamma(\bigcup_{(\ell', c, \ell) \in A} \mathcal{C}^{\#}[\![c]\!] \mathcal{X}_{\ell'}^{\# \delta})$ ,

and so we also have  $\gamma(\mathcal{X}_\ell^{\# \delta}) \supseteq \bigcup_{(\ell', c, \ell) \in A} \mathcal{C}[\![c]\!] \gamma(\mathcal{X}_{\ell'}^{\# \delta})$ .

We have proved that  $\lambda \ell. \gamma(\mathcal{X}_\ell^{\# \delta})$  is a postfixpoint of the concrete equation system. Hence, it is greater than its least solution.

# Abstract analysis (proof)

## Proof of termination:

Suppose that the iteration does not terminate in finite time.

Given a label  $\ell \in L$ , we denote by  $i_\ell^1, \dots, i_\ell^k, \dots$  the increasing sequence of unstable indices, i.e., such that  $\forall k, \mathcal{X}_\ell^{\#i_\ell^k+1} \neq \mathcal{X}_\ell^{\#i_\ell^k}$ .

As the iteration is not stable,  $\forall n, \exists \ell, \mathcal{X}_\ell^{\#n} \neq \mathcal{X}_\ell^{\#n+1}$ .

Hence, the sequence  $(i_\ell^k)_k$  is infinite for at least one  $\ell \in L$ .

We argue that  $\exists \ell \in \mathcal{W}$  such that  $(i_\ell^k)_k$  is infinite as, otherwise,

$N = \max \{ i_\ell^k \mid \ell \in \mathcal{W} \} + |L|$  is finite and satisfies:  $\forall n \geq N, \forall \ell \in L, \mathcal{X}_\ell^{\#n} = \mathcal{X}_\ell^{\#n+1}$ , contradicting our assumption.

For such a  $\ell \in \mathcal{W}$ , consider the subsequence  $\mathcal{Y}_k^\# = \mathcal{X}_\ell^{\#i_\ell^k}$  comprised of the unstable iterates of  $\mathcal{X}_\ell^\#$ .

Then  $\mathcal{Y}^{\#k+1} = \mathcal{Y}^{\#k} \nabla \mathcal{Z}^{\#k}$  for some sequence  $\mathcal{Z}^{\#k}$ .

The subsequence is infinite and  $\forall k, \mathcal{Y}^{\#k+1} \neq \mathcal{Y}^{\#k}$ , which contradicts the definition of  $\nabla$ .

Hence, the iteration must terminate in finite time.

# Abstract analysis (cont.)

## Backward refinement:

Given a forward analysis result  $\mathcal{X}^\sharp$  and an abstract output  $\mathcal{Y}_x^\sharp$ .

$$\mathcal{Y}_x^{\sharp 0} \stackrel{\text{def}}{=} \mathcal{X}_x^\sharp \cap^\sharp \mathcal{Y}_x^\sharp$$

$$\mathcal{Y}_{\ell \neq x}^{\sharp 0} \stackrel{\text{def}}{=} \mathcal{X}_\ell^\sharp$$

$$\mathcal{Y}_\ell^{\sharp n+1} \stackrel{\text{def}}{=} \begin{cases} \mathcal{X}_x^\sharp \cap^\sharp \mathcal{Y}_x^\sharp & \text{if } \ell = x \\ \mathcal{X}_\ell^\sharp \cap^\sharp \bigcup_{(\ell, c, \ell') \in A} \overleftarrow{\mathcal{C}}^\sharp \llbracket c \rrbracket \mathcal{Y}_{\ell'}^{\sharp n} & \text{if } \ell \notin \mathcal{W}, \ell \neq x \\ \mathcal{Y}_\ell^{\sharp n} \triangle (\mathcal{X}_\ell^\sharp \cap^\sharp \bigcup_{(\ell, c, \ell') \in A} \overleftarrow{\mathcal{C}}^\sharp \llbracket c \rrbracket \mathcal{Y}_{\ell'}^{\sharp n}) & \text{if } \ell \in \mathcal{W}, \ell \neq x \end{cases}$$

$\triangle$  overapproximates  $\cap$  while enforcing the convergence of **decreasing** iterations (the definition will be given later, on intervals)

Forward–backward analyses can be iterated [Bour93b].

# Exact and best abstractions: Reminders

**Galois connection:**  $(\mathcal{D}, \subseteq) \xrightleftharpoons[\alpha]{\gamma} (\mathcal{D}^\#, \sqsubseteq)$

- $\alpha, \gamma$  monotonic and  $\forall \mathcal{X}, \mathcal{Y}^\#, \alpha(\mathcal{X}) \sqsubseteq \mathcal{Y}^\# \iff \mathcal{X} \subseteq \gamma(\mathcal{Y}^\#)$
- $\Rightarrow$  elements  $\mathcal{X}$  have a **best** abstraction:  $\alpha(\mathcal{X})$
- $\Rightarrow$  operators  $F$  have a **best** abstraction:  $F^\# = \alpha \circ F \circ \gamma$

Sometimes, no  $\alpha$  exists:

- $\{\gamma(\mathcal{Y}^\#) \mid \mathcal{X} \subseteq \gamma(\mathcal{Y}^\#)\}$  has no greatest lower bound
- abstract elements with the same  $\gamma$  have no best representation

$\alpha \circ F \circ \gamma$  may still be defined for some  $F$  (partial  $\alpha$ )

**Concretization-based optimality:**

- **sound** abstraction:  $\gamma \circ F^\# \supseteq F \circ \gamma$
- **exact** abstraction:  $\gamma \circ F^\# = F \circ \gamma$
- **optimal** abstraction:  $\gamma(\mathcal{X}^\#)$  minimal in  $\{\gamma(\mathcal{Y}^\#) \mid \mathcal{X} \subseteq \gamma(\mathcal{Y}^\#)\}$

# Non-relational domains

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# Value abstract domain

Idea: start from an abstraction of **values**  $\mathcal{P}(\mathbb{I})$

Numerical value abstract domain:

$\mathcal{B}^\#$	abstract values, machine-representable
$\gamma_b: \mathcal{B}^\# \rightarrow \mathcal{P}(\mathbb{I})$	concretization
$\sqsubseteq_b$	partial order
$\perp_b^\#, \top_b^\#$	represent $\emptyset$ and $\mathbb{I}$
$\cup_b^\#, \cap_b^\#$	abstractions of $\cup$ and $\cap$
$\nabla_b$	extrapolation operator
$\alpha_b: \mathcal{P}(\mathbb{I}) \rightarrow \mathcal{B}^\#$	abstraction (optional)



# Derived abstract domain

$$\mathcal{D}^\# \stackrel{\text{def}}{=} (\mathbb{V} \rightarrow (\mathcal{B}^\# \setminus \{\perp_b^\#\})) \cup \{\perp^\#\}$$

- point-wise extension:  $\mathcal{X}^\# \in \mathcal{D}^\#$  is a vector of elements in  $\mathcal{B}^\#$   
(e.g. using arrays of size  $|\mathbb{V}|$ )
- smashed  $\perp^\#$  (avoids redundant representations of  $\emptyset$ )

Definitions on  $\mathcal{D}^\#$  derived from  $\mathcal{B}^\#$ :

$$\gamma(\mathcal{X}^\#) \stackrel{\text{def}}{=} \begin{cases} \emptyset & \text{if } \mathcal{X}^\# = \perp^\# \\ \{\rho \mid \forall v, \rho(v) \in \gamma_b(\mathcal{X}^\#(v))\} & \text{otherwise} \end{cases}$$

$$\alpha(\mathcal{X}) \stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } \mathcal{X} = \emptyset \\ \lambda v. \alpha_b(\{\rho(v) \mid \rho \in \mathcal{X}\}) & \text{otherwise} \end{cases}$$

$$\top^\# \stackrel{\text{def}}{=} \lambda v. \top_b^\#$$

# Derived abstract domain (cont.)

$$\mathcal{X}^\# \sqsubseteq \mathcal{Y}^\# \stackrel{\text{def}}{\iff} \mathcal{X}^\# = \perp^\# \vee (\mathcal{X}^\#, \mathcal{Y}^\# \neq \perp^\# \wedge \forall v, \mathcal{X}^\#(v) \sqsubseteq_b \mathcal{Y}^\#(v))$$

$$\mathcal{X}^\# \cup^\# \mathcal{Y}^\# \stackrel{\text{def}}{=} \begin{cases} \mathcal{Y}^\# & \text{if } \mathcal{X}^\# = \perp^\# \\ \mathcal{X}^\# & \text{if } \mathcal{Y}^\# = \perp^\# \\ \lambda v. \mathcal{X}^\#(v) \cup_b^\# \mathcal{Y}^\#(v) & \text{otherwise} \end{cases}$$

$$\mathcal{X}^\# \nabla \mathcal{Y}^\# \stackrel{\text{def}}{=} \begin{cases} \mathcal{Y}^\# & \text{if } \mathcal{X}^\# = \perp^\# \\ \mathcal{X}^\# & \text{if } \mathcal{Y}^\# = \perp^\# \\ \lambda v. \mathcal{X}^\#(v) \nabla_b \mathcal{Y}^\#(v) & \text{otherwise} \end{cases}$$

$$\mathcal{X}^\# \cap^\# \mathcal{Y}^\# \stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } \mathcal{X}^\# = \perp^\# \text{ or } \mathcal{Y}^\# = \perp^\# \\ \perp^\# & \text{if } \exists v, \mathcal{X}^\#(v) \cap_b^\# \mathcal{Y}^\#(v) = \perp_b^\# \\ \lambda v. \mathcal{X}^\#(v) \cap_b^\# \mathcal{Y}^\#(v) & \text{otherwise} \end{cases}$$

We will see later how to derive  $\mathcal{C}^\# \llbracket c \rrbracket$ ,  $\overleftarrow{\mathcal{C}}^\# \llbracket c \rrbracket$  using:

- abstract operators  $+_b^\#$ , ... for  $\mathcal{C}^\# \llbracket V := e \rrbracket$
- backward abstract operators  $\overleftarrow{+}_b^\#$ , ...  
for  $\overleftarrow{\mathcal{C}}^\# \llbracket V := e \rrbracket$  and  $\mathcal{C}^\# \llbracket e \bowtie 0 \rrbracket^\#$

# Cartesian abstraction

Non-relational domains “forget” all relationships between variables.

## Cartesian abstraction:

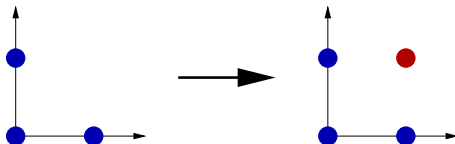
Upper closure operator  $\rho_c : \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$

$$\rho_c(\mathcal{X}) \stackrel{\text{def}}{=} \{ \rho \in \mathbb{V} \rightarrow \mathbb{I} \mid \forall \mathbf{v} \in \mathbb{V}, \exists \rho' \in \mathcal{X}, \rho(\mathbf{v}) = \rho'(\mathbf{v}) \}$$

A domain is non relational if  $\rho \circ \gamma = \gamma$ ,

i.e. it cannot distinguish between  $\mathcal{X}$  and  $\mathcal{X}'$  if  $\rho_c(\mathcal{X}) = \rho_c(\mathcal{X}')$ .

Example:  $\rho_c(\{(X, Y) \mid X \in \{0, 2\}, Y \in \{0, 2\}, X + Y \leq 2\}) = \{0, 2\} \times \{0, 2\}$ .



# Data-structures for non-relational domains

## Arrays

- $\mathcal{O}(1)$  to read or modify a variable
- $\mathcal{O}(|\mathbb{V}|)$  for a copy or a binary operator ( $\cup^\sharp$ ,  $\cap^\sharp$ , etc.)

## Functional arrays e.g.: balanced binary trees

- $\mathcal{O}(\log |\mathbb{V}|)$  to read or modify a variable
- $\mathcal{O}(1)$  to copy
- $\mathcal{O}(|\mathcal{X}^\sharp \Delta \mathcal{Y}^\sharp| \times \log |\mathbb{V}|)$  for a binary operator  $\mathcal{X}^\sharp \cup^\sharp \mathcal{Y}^\sharp$ , etc.  
( $\Delta$  is the symmetric difference)

In practice,  $|\mathcal{X}^\sharp \Delta \mathcal{Y}^\sharp| \ll |\mathbb{V}|$ .

# Generic non-relational abstract assignments

Given: **sound** abstract versions in  $\mathcal{B}^\#$  of all arithmetic operators:

$$\begin{aligned}
 [c, c']_b^\# &: \{x \mid c \leq x \leq c'\} && \sqsubseteq \gamma_b([c, c']_b^\#) \\
 -_b^\# &: \{-x \mid x \in \gamma_b(\mathcal{X}_b^\#)\} && \sqsubseteq \gamma_b(-_b^\# \mathcal{X}_b^\#) \\
 +_b^\# &: \{x+y \mid x \in \gamma_b(\mathcal{X}_b^\#), y \in \gamma_b(\mathcal{Y}_b^\#)\} && \sqsubseteq \gamma_b(\mathcal{X}_b^\# +_b^\# \mathcal{Y}_b^\#) \\
 &\vdots
 \end{aligned}$$

We can define:

- an abstract semantics of expressions:  $E^\# \llbracket e \rrbracket : \mathcal{D}^\# \rightarrow \mathcal{B}^\#$

$$\begin{aligned}
 E^\# \llbracket e \rrbracket \perp^\# &\stackrel{\text{def}}{=} \perp_b^\# \\
 \text{if } \mathcal{X}^\# \neq \perp^\# : \\
 E^\# \llbracket [c, c'] \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} [c, c']_b^\# \\
 E^\# \llbracket v \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} \mathcal{X}^\#(v) \\
 E^\# \llbracket -e \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} -_b^\# E^\# \llbracket e \rrbracket \mathcal{X}^\# \\
 E^\# \llbracket e_1 + e_2 \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} E^\# \llbracket e_1 \rrbracket \mathcal{X}^\# +_b^\# E^\# \llbracket e_2 \rrbracket \mathcal{X}^\# \\
 &\vdots
 \end{aligned}$$

# Generic non-relational abstract assignments (cont.)

We can then define:

- an abstract assignment:

$$C^\sharp[\![v := e]\!] \mathcal{X}^\sharp \stackrel{\text{def}}{=} \begin{cases} \perp^\sharp & \text{if } \mathcal{V}_b^\sharp = \perp_b^\sharp \\ \mathcal{X}^\sharp[v \mapsto \mathcal{V}_b^\sharp] & \text{otherwise} \end{cases}$$

where  $\mathcal{V}_b^\sharp = E^\sharp[\![e]\!] \mathcal{X}^\sharp$ .

Using a Galois connection  $(\alpha_b, \gamma_b)$ :

We can define **best** abstract arithmetic operators:

$$\begin{aligned} [c, c']_b^\sharp &\stackrel{\text{def}}{=} \alpha_b(\{x \mid c \leq x \leq c'\}) \\ -_b^\sharp \mathcal{X}_b^\sharp &\stackrel{\text{def}}{=} \alpha_b(\{-x \mid x \in \gamma(\mathcal{X}_b^\sharp)\}) \\ \mathcal{X}_b^\sharp +_b^\sharp \mathcal{Y}_b^\sharp &\stackrel{\text{def}}{=} \alpha_b(\{x+y \mid x \in \gamma(\mathcal{X}_b^\sharp), y \in \gamma(\mathcal{Y}_b^\sharp)\}) \\ &\vdots \end{aligned}$$

Note: in general,  $E^\sharp[\![e]\!]$  is less precise than  $\alpha_b \circ E[\![e]\!] \circ \gamma$

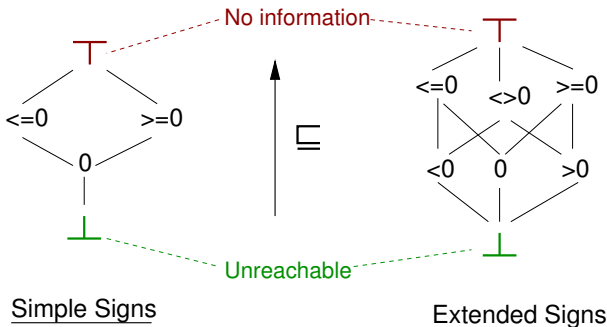
e.g.  $e = V - V$  and  $\gamma_b(\mathcal{X}^\sharp(V)) = [0, 1]$

# The sign domain

---

# The sign lattices

**Hasse diagram:** for the lattice  $(\mathcal{B}^\#, \sqsubseteq_b, \perp^\#, \top^\#)$



The extended sign domain is a refinement of the simple sign domain.

The diagram implicitly defines  $\cup^\#$  and  $\cap^\#$  as the least upper bound and greatest lower bound for  $\sqsubseteq$ .



# Operations on simple signs

Abstraction  $\alpha$ : there is a **Galois connection** between  $\mathcal{B}^\#$  and  $\mathcal{P}(\mathbb{I})$ :

$$\alpha_b(S) \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } S = \emptyset \\ 0 & \text{if } S = \{0\} \\ \geq 0 & \text{else if } \forall s \in S, s \geq 0 \\ \leq 0 & \text{else if } \forall s \in S, s \leq 0 \\ \top_b^\# & \text{otherwise} \end{cases}$$

Derived abstract arithmetic operators:

$$c_b^\# \stackrel{\text{def}}{=} \alpha_b(\{c\}) = \begin{cases} 0 & \text{if } c = 0 \\ \leq 0 & \text{if } c < 0 \\ \geq 0 & \text{if } c > 0 \end{cases}$$

$$\begin{aligned} X^\# +_b^\# Y^\# &\stackrel{\text{def}}{=} \alpha_b(\{x + y \mid x \in \gamma_b(X^\#), y \in \gamma_b(Y^\#)\}) \\ &= \begin{cases} \perp_b^\# & \text{if } X \text{ or } Y^\# = \perp_b^\# \\ 0 & \text{if } X^\# = Y^\# = 0 \\ \leq 0 & \text{else if } X^\# \text{ and } Y^\# \in \{0, \leq 0\} \\ \geq 0 & \text{else if } X^\# \text{ and } Y^\# \in \{0, \geq 0\} \\ \top_b^\# & \text{otherwise} \end{cases} \end{aligned}$$

# Operations on simple signs (cont.)

## Abstract test examples:

$$C^\# \llbracket \mathbf{x} \leq 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \left( \begin{cases} \mathcal{X}^\#[\mathbf{x} \mapsto 0] & \text{if } \mathcal{X}^\#(\mathbf{x}) \in \{0, \geq 0\} \\ \mathcal{X}^\#[\mathbf{x} \mapsto \leq 0] & \text{if } \mathcal{X}^\#(\mathbf{x}) \in \{\top_b^\#, \leq 0\} \\ \perp^\# & \text{otherwise} \end{cases} \right)$$

$$C^\# \llbracket \mathbf{x} - c \leq 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \left( \begin{cases} C^\# \llbracket \mathbf{x} \leq 0 \rrbracket \mathcal{X}^\# & \text{if } c \leq 0 \\ \mathcal{X}^\# & \text{otherwise} \end{cases} \right)$$

$$C^\# \llbracket \mathbf{x} - \mathbf{y} \leq 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \left\{ \begin{array}{ll} C^\# \llbracket \mathbf{x} \leq 0 \rrbracket \mathcal{X}^\# & \text{if } \mathcal{X}^\#(\mathbf{y}) \in \{0, \leq 0\} \\ \mathcal{X}^\# & \text{otherwise} \end{array} \right. \cap^\# \left\{ \begin{array}{ll} C^\# \llbracket \mathbf{y} \geq 0 \rrbracket \mathcal{X}^\# & \text{if } \mathcal{X}^\#(\mathbf{x}) \in \{0, \geq 0\} \\ \mathcal{X}^\# & \text{otherwise} \end{array} \right.$$

Other cases:  $C^\# \llbracket \text{expr} \bowtie 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \mathcal{X}^\#$  is always a sound abstraction.

# Simple sign analysis example

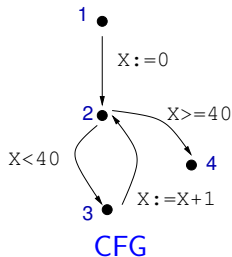
## Example analysis using the simple sign domain:

```

X:=0;
while X<40 do
  X:=X+1
done

```

Program



$$\begin{cases}
 x_2^{\#i+1} &= C^\# \llbracket X := 0 \rrbracket x_1^{\#i} \cup C^\# \llbracket X := X + 1 \rrbracket x_3^{\#i} \\
 x_3^{\#i+1} &= C^\# \llbracket X < 40 \rrbracket x_2^{\#i} \\
 x_4^{\#i+1} &= C^\# \llbracket X \geq 40 \rrbracket x_2^{\#i}
 \end{cases}$$

Iteration system

$\ell$	$x_\ell^{\#0}$	$x_\ell^{\#1}$	$x_\ell^{\#2}$	$x_\ell^{\#3}$	$x_\ell^{\#4}$	$x_\ell^{\#5}$
1	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$
2	$\perp^\#$	$X = 0$	$X = 0$	$X \geq 0$	$X \geq 0$	$X \geq 0$
3	$\perp^\#$	$\perp^\#$	$X = 0$	$X = 0$	$X \geq 0$	$X \geq 0$
4	$\perp^\#$	$\perp^\#$	$X = 0$	$X = 0$	$X \geq 0$	$X \geq 0$

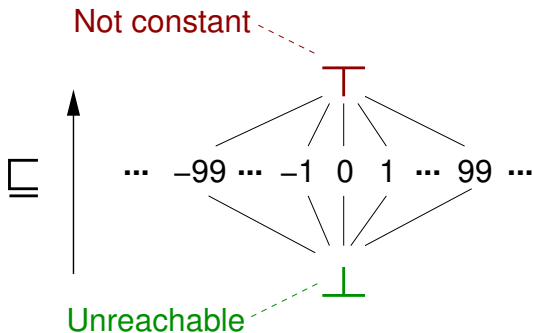
Iterations

# The constant domain

---

# The constant lattice

## Hasse diagram:



$$\mathcal{B}^\# = \mathbb{I} \cup \{T_b^\#, \perp_b^\#\}$$

The lattice is **flat** but **infinite**.

# Operations on constants

Abstraction  $\alpha$ : there is a Galois connection:

$$\alpha_b(S) \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } S = \emptyset \\ c & \text{if } S = \{c\} \\ \top_b^\# & \text{otherwise} \end{cases}$$

Derived abstract arithmetic operators:

$$\begin{aligned} c_b^\# & \stackrel{\text{def}}{=} c \\ (X^\#) +_b^\# (Y^\#) & \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } X^\# \text{ or } Y^\# = \perp_b^\# \\ \top_b^\# & \text{else if } X^\# \text{ or } Y^\# = \top_b^\# \\ X^\# + Y^\# & \text{otherwise} \end{cases} \\ (X^\#) \times_b^\# (Y^\#) & \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } X^\# \text{ or } Y^\# = \perp_b^\# \\ 0 & \text{else if } X^\# \text{ or } Y^\# = 0 \\ \top_b^\# & \text{else if } X^\# \text{ or } Y^\# = \top_b^\# \\ X^\# \times Y^\# & \text{otherwise} \end{cases} \end{aligned}$$

# Operations on constants (cont.)

## Abstract test examples:

$$C^\# \llbracket \mathbf{x} - c = 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } \mathcal{X}^\#(\mathbf{x}) \notin \{c, \top_b^\#\} \\ \mathcal{X}^\#[\mathbf{x} \mapsto c] & \text{otherwise} \end{cases}$$

$$C^\# \llbracket \mathbf{x} - \mathbf{y} - c = 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \left( \begin{cases} C^\# \llbracket \mathbf{x} - (\mathcal{X}^\#(\mathbf{y}) + c) = 0 \rrbracket \mathcal{X}^\# & \text{if } \mathcal{X}^\#(\mathbf{y}) \notin \{\perp_b^\#, \top_b^\#\} \\ \mathcal{X}^\# & \text{otherwise} \end{cases} \right) \cap^\# \left( \begin{cases} C^\# \llbracket \mathbf{y} - (\mathcal{X}^\#(\mathbf{x}) - c) = 0 \rrbracket \mathcal{X}^\# & \text{if } \mathcal{X}^\#(\mathbf{x}) \notin \{\perp_b^\#, \top_b^\#\} \\ \mathcal{X}^\# & \text{otherwise} \end{cases} \right)$$

# Constant analysis example

$\mathcal{B}^\sharp$  has **finite height**, the  $(\mathcal{X}_\ell^{\sharp i})$  **converge in finite time**.  
(even though  $\mathcal{B}^\sharp$  is infinite...)

## Analysis example:

```
X:=0; Y:=10;
while X<100 do
  Y:=Y-3;
  X:=X+Y; •
  Y:=Y+3
done
```

The constant analysis finds, at •, the invariant:  $\begin{cases} X = \top^\sharp \\ Y = 7 \end{cases}$

Note: the analysis can find constants **that do not appear syntactically** in the program.



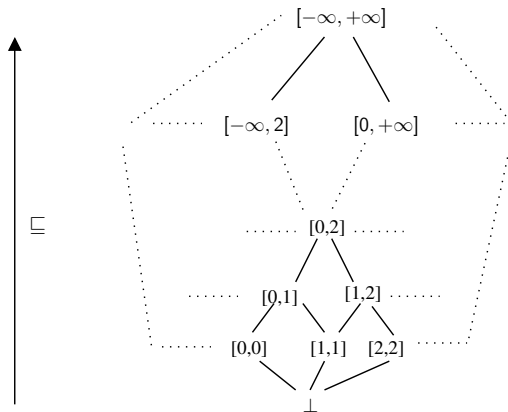
# The interval domain

---

# The interval lattice

Introduced by [Cous76].

$$\mathcal{B}^{\#} \stackrel{\text{def}}{=} \{ [a, b] \mid a \in \mathbb{I} \cup \{-\infty\}, b \in \mathbb{I} \cup \{+\infty\}, a \leq b \} \cup \{\perp_b^{\#}\}$$



Note: intervals are open at infinite bounds  $+\infty$ ,  $-\infty$ .

# The interval lattice (cont.)

## Galois connection $(\alpha_b, \gamma_b)$ :

$$\begin{aligned}\gamma_b([a, b]) &\stackrel{\text{def}}{=} \{x \in \mathbb{I} \mid a \leq x \leq b\} \\ \alpha_b(\mathcal{X}) &\stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } \mathcal{X} = \emptyset \\ [\min \mathcal{X}, \max \mathcal{X}] & \text{otherwise} \end{cases}\end{aligned}$$

If  $\mathbb{I} = \mathbb{Q}$ ,  $\alpha_b$  is not always defined...

## Partial order:

$$\begin{aligned}[a, b] \sqsubseteq_b [c, d] &\stackrel{\text{def}}{\iff} a \geq c \text{ and } b \leq d \\ &\stackrel{\text{def}}{=} \begin{cases} ] - \infty, +\infty[ \\ [\min(a, c), \max(b, d)] \end{cases} \\ [a, b] \sqcup_b^\# [c, d] &\stackrel{\text{def}}{=} [\min(a, c), \max(b, d)] \\ [a, b] \sqcap_b^\# [c, d] &\stackrel{\text{def}}{=} \begin{cases} [\max(a, c), \min(b, d)] & \text{if } \max \leq \min \\ \perp_b^\# & \text{otherwise} \end{cases}\end{aligned}$$

If  $\mathbb{I} \neq \mathbb{Q}$ , it is a **complete lattice**.

# Interval abstract arithmetic operators

$$[c, c']_b^{\#} \stackrel{\text{def}}{=} [c, c']$$

$$-_b^{\#} [a, b] \stackrel{\text{def}}{=} [-b, -a]$$

$$[a, b] +_b^{\#} [c, d] \stackrel{\text{def}}{=} [a + c, b + d]$$

$$[a, b] -_b^{\#} [c, d] \stackrel{\text{def}}{=} [a - d, b - c]$$

$$[a, b] \times_b^{\#} [c, d] \stackrel{\text{def}}{=} [\min(ac, ad, bc, bd), \max(ac, ad, bc, bd)]$$

$$[a, b] /_b^{\#} [c, d] \stackrel{\text{def}}{=} \begin{cases} \perp_b^{\#} & \text{if } c = d = 0 \\ [\min(a/c, a/d, b/c, b/d), \max(a/c, a/d, b/c, b/d)] & \text{else if } 0 \leq c \\ [-b, -a] /_b^{\#} [-d, -c] & \text{else if } d \leq 0 \\ ([a, b] /_b^{\#} [c, 0]) \cup_b^{\#} ([a, b] /_b^{\#} [0, d]) & \text{otherwise} \end{cases}$$

$$\text{where } \begin{cases} \pm\infty \times 0 = 0, & 0/0 = 0, & \forall x, x/\pm\infty = 0 \\ \forall x > 0, x/0 = +\infty, & \forall x < 0, x/0 = -\infty \end{cases}$$

Operators are **strict**:  $-_b^{\#} \perp_b^{\#} = \perp_b^{\#}$ ,  $[a, b] +_b^{\#} \perp_b^{\#} = \perp_b^{\#}$ , etc.

# Exactness and optimality: Example proofs

Proof: **exactness** of  $+_b^\#$

$$\begin{aligned}
 & \{x + y \mid x \in \gamma_b([a, b]), y \in \gamma_b([c, d])\} \\
 = & \{x + y \mid a \leq x \leq b \wedge c \leq y \leq d\} \\
 = & \{z \mid a + c \leq z \leq b + d\} \\
 = & \gamma_b([a + c, b + d]) \\
 = & \gamma_b([a, b] +_b^\# [c, d])
 \end{aligned}$$

Proof **optimality** of  $\cup_b^\#$

$$\begin{aligned}
 & \alpha_b(\gamma_b([a, b]) \cup \gamma_b([c, d])) \\
 = & \alpha_b(\{x \mid a \leq x \leq b\} \cup \{x \mid c \leq x \leq d\}) \\
 = & \alpha_b(\{x \mid a \leq x \leq b \vee c \leq x \leq d\}) \\
 = & [\min \{x \mid a \leq x \leq b \vee c \leq x \leq d\}, \max \{x \mid a \leq x \leq b \vee c \leq x \leq d\}] \\
 = & [\min(a, c), \max(b, d)] \\
 = & [a, b] \cup_b^\# [c, d]
 \end{aligned}$$

but  $\cup_b^\#$  is not exact

...

# Interval abstract tests (non-generic)

If  $\mathcal{X}^\#(X) = [a, b]$  and  $\mathcal{X}^\#(Y) = [c, d]$ , we can define:

$$\begin{aligned}
 C^\# \llbracket X - c \leq 0 \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } a > c \\ \mathcal{X}^\# [X \mapsto [a, \min(b, c)]] & \text{otherwise} \end{cases} \\
 C^\# \llbracket X - Y \leq 0 \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } a > d \\ \mathcal{X}^\# [X \mapsto [a, \min(b, d)], \\ Y \mapsto [\max(c, a), d]] & \text{otherwise} \end{cases} \\
 C^\# \llbracket e \bowtie 0 \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} \mathcal{X}^\# \quad \text{otherwise}
 \end{aligned}$$

Note: fall-back operators

- $C^\# \llbracket e \bowtie 0 \rrbracket \mathcal{X}^\# = \mathcal{X}^\#$  is always sound.
- $C^\# \llbracket X := e \rrbracket \mathcal{X}^\# = \mathcal{X}^\# [X \mapsto \top_b^\#]$  is always sound.

# Backward arithmetic and comparison operators

Given: **sound backward** arithmetic and comparison operators that **refine** their argument given a result.

i.e.

$$\mathcal{X}_b^{\#'} = \overleftarrow{\leq}_b^{\#}(\mathcal{X}_b^{\#}) \implies \{x \in \gamma_b(\mathcal{X}_b^{\#}) \mid x \leq 0\} \subseteq \gamma_b(\mathcal{X}_b^{\#'}) \subseteq \gamma_b(\mathcal{X}_b^{\#})$$

$$\mathcal{X}_b^{\#'} = \overleftarrow{+}_b^{\#}(\mathcal{X}_b^{\#}, \mathcal{R}_b^{\#}) \implies \{x \mid x \in \gamma_b(\mathcal{X}_b^{\#}), -x \in \gamma_b(\mathcal{R}_b^{\#})\} \subseteq \gamma_b(\mathcal{X}_b^{\#'}) \subseteq \gamma_b(\mathcal{X}_b^{\#})$$

$$(\mathcal{X}_b^{\#'}, \mathcal{Y}_b^{\#'}) = \overleftarrow{+}_b^{\#}(\mathcal{X}_b^{\#}, \mathcal{Y}_b^{\#}, \mathcal{R}_b^{\#}) \implies$$

$$\{x \in \gamma_b(\mathcal{X}_b^{\#}) \mid \exists y \in \gamma_b(\mathcal{Y}_b^{\#}), x + y \in \gamma_b(\mathcal{R}_b^{\#})\} \subseteq \gamma_b(\mathcal{X}_b^{\#'}) \subseteq \gamma_b(\mathcal{X}_b^{\#})$$

$$\{y \in \gamma_b(\mathcal{Y}_b^{\#}) \mid \exists x \in \gamma_b(\mathcal{X}_b^{\#}), x + y \in \gamma_b(\mathcal{R}_b^{\#})\} \subseteq \gamma_b(\mathcal{Y}_b^{\#'}) \subseteq \gamma_b(\mathcal{Y}_b^{\#})$$

⋮

Note: **best** backward operators can be designed with  $\alpha_b$ :

e.g. for  $\overleftarrow{+}_b^{\#}$ :  $\mathcal{X}_b^{\#'} = \alpha_b(\{x \in \gamma_b(\mathcal{X}_b^{\#}) \mid \exists y \in \gamma_b(\mathcal{Y}_b^{\#}), x + y \in \gamma_b(\mathcal{R}_b^{\#})\})$

# Generic backward operator construction

Synthesizing (non optimal) **backward** arithmetic operators from **forward** arithmetic operators.

$$\overleftarrow{\leq}_b^\#(x_b^\#) \stackrel{\text{def}}{=} x_b^\# \cap_b^\# ]-\infty, 0]_b^\#$$

$$\overleftarrow{=}_b^\#(x_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} x_b^\# \cap_b^\# (-_b^\# \mathcal{R}_b^\#)$$

$$\overleftarrow{+}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} (x_b^\# \cap_b^\# (\mathcal{R}_b^\# -_b^\# y_b^\#), y_b^\# \cap_b^\# (\mathcal{R}_b^\# -_b^\# x_b^\#))$$

$$\overleftarrow{-}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} (x_b^\# \cap_b^\# (\mathcal{R}_b^\# +_b^\# y_b^\#), y_b^\# \cap_b^\# (x_b^\# -_b^\# \mathcal{R}_b^\#))$$

$$\overleftarrow{/}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} (x_b^\# \cap_b^\# (\mathcal{R}_b^\# /_b^\# y_b^\#), y_b^\# \cap_b^\# (\mathcal{R}_b^\# /_b^\# x_b^\#))$$

$$\overleftarrow{\times}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} (x_b^\# \cap_b^\# (S_b^\# \times_b^\# y_b^\#), y_b^\# \cap_b^\# ((x_b^\# /_b^\# S_b^\#) \cup_b^\# [0, 0]_b^\#))$$

$$\text{where } S_b^\# = \begin{cases} \mathcal{R}_b^\# & \text{if } \mathbb{I} \neq \mathbb{Z} \\ \mathcal{R}_b^\# +_b^\# [-1, 1]_b^\# & \text{if } \mathbb{I} = \mathbb{Z} \text{ (as / rounds)} \end{cases}$$

Note:  $\overleftarrow{\diamond}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) = (x_b^\#, y_b^\#)$  is always sound (no refinement).



# Interval backward operators

Applying the generic construction to the interval domain:

$$\overleftarrow{\leq}_b^\#([a, b]) \stackrel{\text{def}}{=} \begin{cases} [a, \min(b, 0)] & \text{if } a \geq 0 \\ \perp_b^\# & \text{otherwise} \end{cases}$$

$$\overleftarrow{-}_b^\#([a, b], [r, s]) \stackrel{\text{def}}{=} [a, b] \cap_b^\# [-s, -r]$$

$$\overleftarrow{+}_b^\#([a, b], [c, d], [r, s]) \stackrel{\text{def}}{=} ([a, b] \cap_b^\# [r - d, s - c], \\ [c, d] \cap_b^\# [r - b, s - a])$$

...

# Generic non-relational abstract test

Abstract test algorithm:  $C^\# \llbracket e \bowtie 0 \rrbracket \mathcal{X}^\#$

Associate to each expression node an abstract value in  $\mathcal{B}^\#$  using **two** traversals of the expression tree:

- first, a bottom-up **evaluation** using forward operators  $\diamond_b^\#$ ,
- apply  $\overleftarrow{\bowtie} 0_b^\#$  to the root,
- then, a top-down **refinement** using backward operators  $\overleftarrow{\diamond}_b^\#$ .

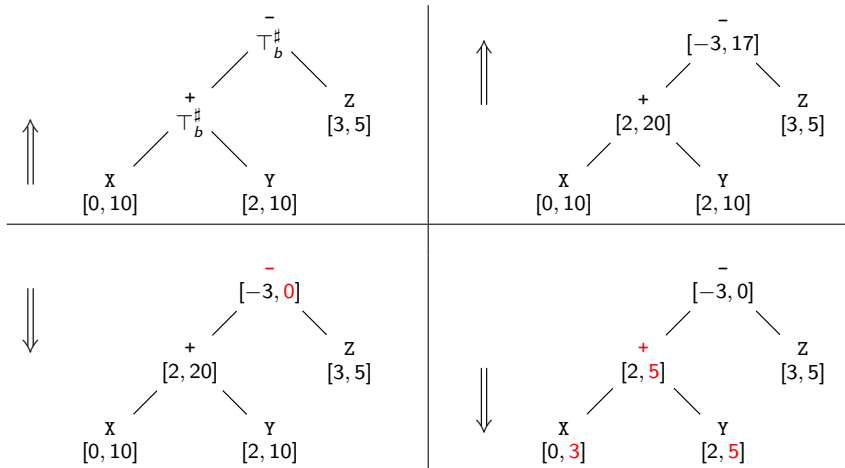
For each expression leaf, we get an abstract value  $\mathcal{V}_b^\#$ :

- for a variable  $V$ , replace  $\mathcal{X}^\#(V)$  with  $\mathcal{X}^\#(V) \cap_b^\# \mathcal{V}_b^\#$ ,
- for a constant  $[c, c']$ , check that  $[c, c']_b^\# \cap_b^\# \mathcal{V}_b^\# \neq \perp_b^\#$ ,
- $\implies$  return  $\perp^\#$  if some  $\cap_b^\# \mathcal{V}_b^\#$  returns  $\perp_b^\#$ .

Improvement: local iterations [Gran92].

# Interval test example

Example:  $C^\# \llbracket \mathbf{x + y - z \leq 0} \rrbracket \mathcal{X}^\#$   
 with  $\mathcal{X}^\# = \{ x \mapsto [0, 10], y \mapsto [2, 10], z \mapsto [3, 5] \}$



# Generic non-relational backward assignment

Abstract function:  $\overleftarrow{C}^\# \llbracket v := e \rrbracket (\mathcal{X}^\#, \mathcal{R}^\#)$

over-approximates  $\gamma(\mathcal{X}^\#) \cap \overleftarrow{C} \llbracket v := e \rrbracket \gamma(\mathcal{R}^\#)$  given:

- an abstract pre-condition  $\mathcal{X}^\#$  to refine,
- according to a given abstract post-condition  $\mathcal{R}^\#$ .

Algorithm: similar to the abstract test

- annotate **variable leaves** based on  $\mathcal{X}^\# \cap^\# (\mathcal{R}^\# [v \mapsto \top_b^\#])$ ;
- **evaluate** bottom-up using forward operators  $\diamond_b^\#$ ;
- **intersect** the root with  $\mathcal{R}^\#(v)$ ;
- **refine** top-down using backward operators  $\overleftarrow{\diamond}_b^\#$ ;
- **return**  $\mathcal{X}^\#$  **intersected** with values at variable leaves.

Note:

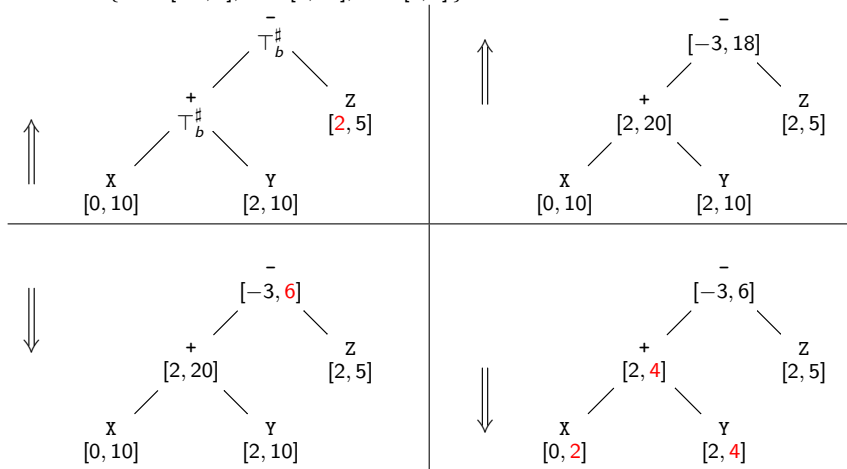
- local iterations can also be used
- fallback:  $\overleftarrow{C}^\# \llbracket v := e \rrbracket (\mathcal{X}^\#, \mathcal{R}^\#) = \mathcal{X}^\# \cap^\# (\mathcal{R}^\# [v \mapsto \top_b^\#])$

# Interval backward assignment example

**Example:**  $\overleftarrow{C}^\# \llbracket X := X + Y - Z \rrbracket (\mathcal{X}^\#, \mathcal{R}^\#)$

with  $\mathcal{X}^\# = \{ X \mapsto [0, 10], Y \mapsto [2, 10], Z \mapsto [1, 5] \}$

and  $\mathcal{R}^\# = \{ X \mapsto [-6, 6], Y \mapsto [2, 10], Z \mapsto [2, 6] \}$



# Interval widening

## Widening on non-relational domains:

Given a value widening  $\nabla_b: \mathcal{B}^\# \times \mathcal{B}^\# \rightarrow \mathcal{B}^\#$ ,  
we extend it point-wisely into a widening  $\nabla: \mathcal{D}^\# \times \mathcal{D}^\# \rightarrow \mathcal{D}^\#$ :

$$\mathcal{X}^\# \nabla \mathcal{Y}^\# \stackrel{\text{def}}{=} \lambda v. (\mathcal{X}^\#(v) \nabla_b \mathcal{Y}^\#(v))$$

## Interval widening example:

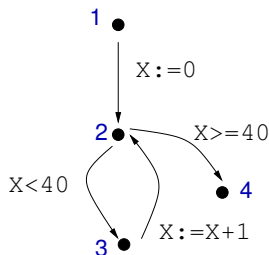
$$\perp^\# \nabla_b X^\# \stackrel{\text{def}}{=} X^\#$$

$$[a, b] \nabla_b [c, d] \stackrel{\text{def}}{=} \left[ \begin{cases} a & \text{if } a \leq c \\ -\infty & \text{otherwise} \end{cases}, \begin{cases} b & \text{if } b \geq d \\ +\infty & \text{otherwise} \end{cases} \right]$$

Unstable bounds are set to  $\pm\infty$ .

# Analysis with widening example

Analysis example with  $\mathcal{W} = \{2\}$



$\ell$	$x_\ell^{\#0}$	$x_\ell^{\#1}$	$x_\ell^{\#2}$	$x_\ell^{\#3}$	$x_\ell^{\#4}$	$x_\ell^{\#5}$
1	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$
2 $\nabla$	$\perp^\#$	$= 0$	$= 0$	$\geq 0$	$\geq 0$	$\geq 0$
3	$\perp^\#$	$\perp^\#$	$= 0$	$= 0$	$\in [0, 39]$	$\in [0, 39]$
4	$\perp^\#$	$\perp^\#$	$\perp^\#$	$\perp^\#$	$\geq 40$	$\geq 40$

More precisely, at the widening point:

$$\begin{aligned}
 x_2^{\#1} &= \perp^\# & \nabla_b ([0, 0] \cup_b \perp^\#) &= \perp^\# & \nabla_b [0, 0] &= [0, 0] \\
 x_2^{\#2} &= [0, 0] & \nabla_b ([0, 0] \cup_b \perp^\#) &= [0, 0] & \nabla_b [0, 0] &= [0, 0] \\
 x_2^{\#3} &= [0, 0] & \nabla_b ([0, 0] \cup_b [1, 1]) &= [0, 0] & \nabla_b [0, 1] &= [0, +\infty[ \\
 x_2^{\#4} &= [0, +\infty[ & \nabla_b ([0, 0] \cup_b [1, 40]) &= [0, +\infty[ & \nabla_b [0, 40] &= [0, +\infty[
 \end{aligned}$$

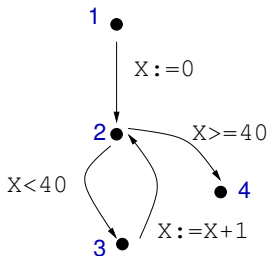
Note that the most precise interval abstraction would be

$x \in [0, 40]$  at 2, and  $x = 40$  at 4.

# Influence of the widening point and iteration strategy

## Changing $\mathcal{W}$ changes the analysis result

Example: The analysis is less precise for  $\mathcal{W} = \{3\}$ .



$\ell$	$\mathcal{X}_\ell^{\#1}$	$\mathcal{X}_\ell^{\#2}$	$\mathcal{X}_\ell^{\#3}$	$\mathcal{X}_\ell^{\#4}$	$\mathcal{X}_\ell^{\#5}$	$\mathcal{X}_\ell^{\#6}$
1	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$
2	$= 0$	$= 0$	$\in [0, 1]$	$\in [0, 1]$	$\geq 0$	$\geq 0$
3 $\nabla$	$\perp^\#$	$= 0$	$= 0$	$\geq 0$	$\geq 0$	$\geq 0$
4	$\perp^\#$	$\perp^\#$	$\perp^\#$	$\perp^\#$	$\perp^\#$	$\geq 40$

Intuition: extrapolation to  $+\infty$  is no longer contained by the tests.

## Chaotic iterations

Changing the iteration order changes the analysis result in the presence of a widening.



# Narrowing

Using a widening makes the analysis less precise.

Some precision can be retrieved by using a **narrowing**  $\Delta$ .

## Definition: narrowing $\Delta$

Binary operator  $\mathcal{D}^\# \times \mathcal{D}^\# \rightarrow \mathcal{D}^\#$  such that:

- $(x^\# \cap^\# y^\#) \sqsubseteq (x^\# \Delta y^\#) \sqsubseteq x^\#$ ,
- for all sequences  $(x_i^\#)$ , the decreasing sequence  $(y_i^\#)$

$$\text{defined by } \begin{cases} y_0^\# & \stackrel{\text{def}}{=} & x_0^\# \\ y_{i+1}^\# & \stackrel{\text{def}}{=} & y_i^\# \Delta x_{i+1}^\# \end{cases}$$

is **stationary**.

This is not the dual of a widening!

# Narrowing examples

## Trivial narrowing:

$\mathcal{X}^\# \triangle \mathcal{Y}^\# \stackrel{\text{def}}{=} \mathcal{X}^\#$  is a correct narrowing.

## Finite-time intersection narrowing:

$$\mathcal{X}^{\#i} \triangle \mathcal{Y}^\# \stackrel{\text{def}}{=} \begin{cases} \mathcal{X}^{\#i} \cap^\# \mathcal{Y}^\# & \text{if } i \leq N \\ \mathcal{X}^{\#i} & \text{if } i > N \end{cases}$$

## Interval narrowing:

$$[a, b] \triangle_b [c, d] \stackrel{\text{def}}{=} \left[ \begin{cases} c & \text{if } a = -\infty \\ a & \text{otherwise} \end{cases}, \begin{cases} d & \text{if } b = +\infty \\ b & \text{otherwise} \end{cases} \right]$$

(refine only infinite bounds)

Point-wise extension to  $\mathcal{D}^\#$ :  $\mathcal{X}^\# \triangle \mathcal{Y}^\# \stackrel{\text{def}}{=} \lambda v. (\mathcal{X}^\#(v) \triangle_b \mathcal{Y}^\#(v))$

# Iterations with narrowing

Let  $\mathcal{X}_\ell^{\#\delta}$  be the result after widening stabilisation, *i.e.*:

$$\mathcal{X}_\ell^{\#\delta} \sqsupseteq \begin{cases} \top^\# & \text{if } \ell = e \\ \bigcup_{(\ell', c, \ell) \in A} C^\# \llbracket c \rrbracket \mathcal{X}_{\ell'}^{\#\delta} & \text{if } \ell \neq e \end{cases}$$

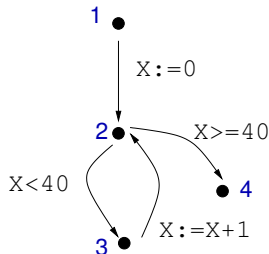
The following sequence is computed:

$$\mathcal{Y}_\ell^{\#0} \stackrel{\text{def}}{=} \mathcal{X}_\ell^{\#\delta} \quad \mathcal{Y}_\ell^{\#i+1} \stackrel{\text{def}}{=} \begin{cases} \top^\# & \text{if } \ell = e \\ \bigcup_{(\ell', c, \ell) \in A} C^\# \llbracket c \rrbracket \mathcal{Y}_{\ell'}^{\#i} & \text{if } \ell \notin \mathcal{W} \\ \mathcal{Y}_\ell^{\#i} \triangle \bigcup_{(\ell', c, \ell) \in A} C^\# \llbracket c \rrbracket \mathcal{Y}_{\ell'}^{\#i} & \text{if } \ell \in \mathcal{W} \end{cases}$$

- the sequence  $(\mathcal{Y}_\ell^{\#i})$  is **decreasing** and **converges in finite time**,
- all  $(\mathcal{Y}_\ell^{\#i})$  are **solutions of the abstract semantic system**.

# Analysis with narrowing example

**Example** with  $\mathcal{W} = \{2\}$



$\ell$	$\mathcal{Y}_\ell^{\#0}$	$\mathcal{Y}_\ell^{\#1}$	$\mathcal{Y}_\ell^{\#2}$	$\mathcal{Y}_\ell^{\#3}$
1	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$
2 $\Delta$	$\geq 0$	$\in [0, 40]$	$\in [0, 40]$	$\in [0, 40]$
3	$\in [0, 39]$	$\in [0, 39]$	$\in [0, 39]$	$\in [0, 39]$
4	$\geq 40$	$\geq 40$	$= 40$	$= 40$

Narrowing at 2 gives:

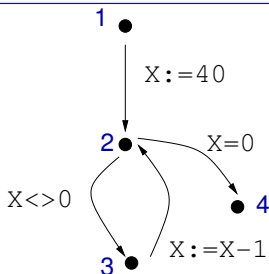
$$\begin{aligned} \mathcal{Y}_2^{\#1} &= [0, +\infty[ \Delta_b ([0, 0] \cup_b^\# [1, 40]) = [0, +\infty[ \Delta_b [0, 40] = [0, 40] \\ \mathcal{Y}_2^{\#2} &= [0, 40] \Delta_b ([0, 0] \cup_b^\# [1, 40]) = [0, 40] \Delta_b [0, 40] = [0, 40] \end{aligned}$$

Then  $\mathcal{Y}_2^{\#2} : X \in [0, 40]$  gives  $\mathcal{Y}_4^{\#3} : X = 40$ .

**We found the most precise invariants!**

# Improving the widening

## Example of imprecise analysis



$\ell$	intervals with $\nabla_b$	extended signs	intervals with $\nabla'_b$
1	$\top^\#$	$\top^\#$	$\top^\#$
2 $\nabla$	$x \leq 40$	$x \geq 0$	$x \in [0, 40]$
3	$x \leq 40$	$x > 0$	$x \in [0, 40]$
4	$x = 0$	$x = 0$	$x = 0$

The interval domain cannot prove that  $x \geq 0$  at 2,  
while the (less powerful) sign domain can!

**Solution:** improve the interval widening

$$[a, b] \nabla'_b [c, d] \stackrel{\text{def}}{=} \left[ \begin{cases} a & \text{if } a \leq c \\ 0 & \text{if } 0 \leq c < a \\ -\infty & \text{otherwise} \end{cases}, \begin{cases} b & \text{if } b \geq d \\ 0 & \text{if } 0 \geq b > d \\ +\infty & \text{otherwise} \end{cases} \right]$$

( $\nabla'_b$  checks the stability of 0)

# Widening with thresholds

## Analysis problem:

```

X:=0;
while • 1=1 do
  if [0,1]=0 then
    X:=X+1;
    if X>40 then X:=0 fi
  fi
done

```

We wish to prove that  $X \in [0, 40]$  at •.

- Widening at • finds the loop invariant  $X \in [0, +\infty[$ .  
 $\mathcal{X}_{\bullet}^{\sharp} = [0, 0] \nabla_b ([0, 0] \cup^{\sharp} [0, 1]) = [0, 0] \nabla_b [0, 1] = [0, +\infty[$

- Narrowing is unable to refine the invariant:

$$\mathcal{Y}_{\bullet}^{\sharp} = [0, +\infty[\Delta_b([0, 0] \cup^{\sharp} [0, +\infty[) = [0, +\infty[$$

(the code that limits  $X$  is not executed at every loop iteration)

# Widening with thresholds (cont.)

## Solution:

Choose a **finite set  $T$  of thresholds** containing  $+\infty$  and  $-\infty$ .

**Definition:** widening with thresholds  $\nabla_b^T$

$$[a, b] \nabla_b^T [c, d] \stackrel{\text{def}}{=} \left[ \begin{cases} a & \text{if } a \leq c \\ \max \{x \in T \mid x \leq c\} & \text{otherwise} \end{cases}, \begin{cases} b & \text{if } b \geq d \\ \min \{x \in T \mid x \geq d\} & \text{otherwise} \end{cases} \right]$$

The widening tests and stops at the first stable bound in  $T$ .

# Widening with thresholds (cont.)

## Applications:

- On the previous example, we find:  

$$X \in [0, \min \{x \in T \mid x \geq 40\}].$$
- Useful when it is **easy to find a 'good' set  $T$** .  
*Example:* array bound-checking
- Useful if an **over-approximation of the bound is sufficient**.  
*Example:* arithmetic overflow checking

**Limitations:** only works if some non- $\infty$  bound in  $T$  is stable.

*Example:* with  $T = \{5, 15\}$

<pre>while 1=1 do   X:=X+1;   if X&gt;10 then X=0 fi done</pre>	<pre>while 1=1 do   X:=X+1;   if X&lt;&gt;10 then X=0 fi done</pre>
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15 is stable

no stable bound

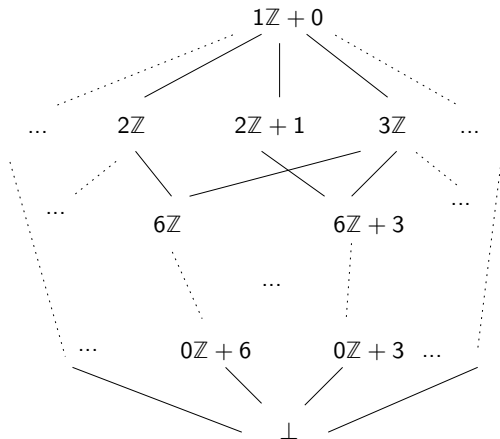


# The congruence domain

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# The congruence lattice

$$\mathcal{B}^\# \stackrel{\text{def}}{=} \{(a\mathbb{Z} + b) \mid a \in \mathbb{N}, b \in \mathbb{Z}\} \cup \{\perp^\#\}$$



Introduced by Granger [Gran89].

We take  $\mathbb{I} = \mathbb{Z}$ .

# The congruence lattice (cont.)

## Concretization:

$$\gamma_b(\mathcal{X}_b^\#) \stackrel{\text{def}}{=} \begin{cases} \{ak + b \mid k \in \mathbb{Z}\} & \text{if } \mathcal{X}_b^\# = (a\mathbb{Z} + b) \\ \emptyset & \text{if } \mathcal{X}_b^\# = \perp_b^\# \end{cases}$$

Note that  $\gamma(0\mathbb{Z} + b) = \{b\}$ .

$\gamma_b$  is **not injective**:  $\gamma_b(2\mathbb{Z} + 1) = \gamma_b(2\mathbb{Z} + 3)$ .

## Definitions:

Given  $x, x' \in \mathbb{Z}$ ,  $y, y' \in \mathbb{N}$ , we define:

- $y/y' \stackrel{\text{def}}{\iff} y \text{ divides } y' \ (\exists k \in \mathbb{N}, y' = ky)$  (note that  $\forall y: y/0$ )
- $x \equiv x' [y] \stackrel{\text{def}}{\iff} y / |x - x'|$  (in particular,  $x \equiv x' [0] \iff x = x'$ )
- $\vee$  is the LCM, extended with  $y \vee 0 \stackrel{\text{def}}{=} 0 \vee y \stackrel{\text{def}}{=} y$
- $\wedge$  is the GCD, extended with  $y \wedge 0 \stackrel{\text{def}}{=} 0 \wedge y \stackrel{\text{def}}{=} y$

$(\mathbb{N}, /, \vee, \wedge, 1, 0)$  is a **complete distributive lattice**.

# Abstract congruence operators

## Complete lattice structure on $\mathcal{B}^\sharp$ :

- $(a\mathbb{Z} + b) \sqsubseteq_b (a'\mathbb{Z} + b') \stackrel{\text{def}}{\iff} a'/a \text{ and } b \equiv b' [a']$
- $\top_b \stackrel{\text{def}}{=} (1\mathbb{Z} + 0)$
- $(a\mathbb{Z} + b) \cup_b^\sharp (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} (a \wedge a' \wedge |b - b'|)\mathbb{Z} + b$
- $(a\mathbb{Z} + b) \cap_b^\sharp (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} \begin{cases} (a \vee a')\mathbb{Z} + b'' & \text{if } b \equiv b' [a \wedge a'] \\ \perp_b^\sharp & \text{otherwise} \end{cases}$   
 $b''$  such that  $b'' \equiv b [a \vee a'] \equiv b' [a \vee a']$  is given by Bezout's Theorem.

Galois connection:  $\alpha_b(\mathcal{X}) = \bigcup_{c \in \mathcal{X}}^\sharp (0\mathbb{Z} + c)$

(up to equivalence  $a\mathbb{Z} + b \equiv a'\mathbb{Z} + b' \stackrel{\text{def}}{\iff} a = a' \wedge b \equiv b' [a]$ )

# Abstract congruence operators (cont.)

## Arithmetic operators:

$$[c, c']_b^\# \stackrel{\text{def}}{=} \begin{cases} 0\mathbb{Z} + c & \text{if } c = c' \\ \top_b^\# & \text{otherwise} \end{cases}$$

$$-_b^\# (a\mathbb{Z} + b) \stackrel{\text{def}}{=} a\mathbb{Z} + (-b)$$

$$(a\mathbb{Z} + b) +_b^\# (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} (a \wedge a')\mathbb{Z} + (b + b')$$

$$(a\mathbb{Z} + b) -_b^\# (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} (a \wedge a')\mathbb{Z} + (b - b')$$

$$(a\mathbb{Z} + b) \times_b^\# (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} (aa' \wedge ab' \wedge a'b)\mathbb{Z} + bb'$$

$$(a\mathbb{Z} + b) /_b^\# (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } a'\mathbb{Z} + b' = 0\mathbb{Z} + 0 \\ (a/|b'|)\mathbb{Z} + (b/b') & \text{if } a' = 0, b' \neq 0, b'|a, \text{ and } b'|b \\ \top_b^\# & \text{otherwise (not optimal)} \end{cases}$$

# Abstract congruence operators (cont.)

## Test operators:

$$\overleftarrow{\leq}_b^\# (a\mathbb{Z} + b) \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } a = 0, b > 0 \\ a\mathbb{Z} + b & \text{otherwise} \end{cases}$$

$$\vdots$$

Note: better than the generic  $\overleftarrow{\leq}_b^\# (\mathcal{X}_b^\#) \stackrel{\text{def}}{=} \mathcal{X}_b^\# \cap_b^\# ]-\infty, 0]_b^\# = \mathcal{X}_b^\#$

## Extrapolation operators:

- no infinite increasing chain  $\implies$  no need for  $\nabla$
- infinite decreasing chains  $\implies \Delta$  needed

$$(a\mathbb{Z} + b) \triangle_b (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} \begin{cases} a'\mathbb{Z} + b' & \text{if } a = 1 \\ a\mathbb{Z} + b & \text{otherwise} \end{cases}$$

Note:  $\mathcal{X}^\# \triangle \mathcal{Y}^\# \stackrel{\text{def}}{=} \mathcal{X}^\#$  is always a narrowing.

# Congruence analysis example

```
X:=0; Y:=2;  
while • X<40 do  
  X:=X+2;  
  if X<5 then Y:=Y+18 fi;  
  if X>8 then Y:=Y-30 fi  
done
```

We find, at •, the loop invariant  $\begin{cases} X \in 2\mathbb{Z} \\ Y \in 6\mathbb{Z} + 2 \end{cases}$

## Reduced products of domains

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# Non-reduced product of domains

## Product representation:

Cartesian product  $\mathcal{D}_{1 \times 2}^\#$  of  $\mathcal{D}_1^\#$  and  $\mathcal{D}_2^\#$ :

- $\mathcal{D}_{1 \times 2}^\# \stackrel{\text{def}}{=} \mathcal{D}_1^\# \times \mathcal{D}_2^\#$
- $\gamma_{1 \times 2}(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \stackrel{\text{def}}{=} \gamma_1(\mathcal{X}_1^\#) \cap \gamma_2(\mathcal{X}_2^\#)$
- $\alpha_{1 \times 2}(\mathcal{X}) \stackrel{\text{def}}{=} (\alpha_1(\mathcal{X}), \alpha_2(\mathcal{X}))$
- $(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \sqsubseteq_{1 \times 2} (\mathcal{Y}_1^\#, \mathcal{Y}_2^\#) \stackrel{\text{def}}{\iff} \mathcal{X}_1^\# \sqsubseteq_1 \mathcal{Y}_1^\# \text{ and } \mathcal{X}_2^\# \sqsubseteq_2 \mathcal{Y}_2^\#$

Abstract operators: performed in parallel on both components:

- $(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \cup_{1 \times 2}^\# (\mathcal{Y}_1^\#, \mathcal{Y}_2^\#) \stackrel{\text{def}}{=} (\mathcal{X}_1^\# \cup_1^\# \mathcal{Y}_1^\#, \mathcal{X}_2^\# \cup_2^\# \mathcal{Y}_2^\#)$   
and the same for  $\nabla_{1 \times 2}^\#$  and  $\Delta_{1 \times 2}^\#$
- $C^\# \llbracket c \rrbracket_{1 \times 2}(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \stackrel{\text{def}}{=} (C^\# \llbracket c \rrbracket_1(\mathcal{X}_1^\#), C^\# \llbracket c \rrbracket_2(\mathcal{X}_2^\#))$

# Non-reduced product example

The product analysis is no more precise than two separate analyses.

Example: interval-congruence product:

```

X:=1;
while X-10<=0 do
  X:=X+2
done;
•if X-12>=0 then ♦ X:=0★ fi

```

	interval	congruence	product $\gamma$
•	$X \in [11, 12]$	$X \equiv 1 [2]$	$X = 11$
♦	$X = 12$	$X \equiv 1 [2]$	$\emptyset$
★	$X = 0$	$X = 0$	$X = 0$

We **cannot** prove that the if branch is never taken!

# Fully-reduced product

## Definition:

Given the Galois connections  $(\alpha_1, \gamma_1)$  and  $(\alpha_2, \gamma_2)$  on  $\mathcal{D}_1^\#$  and  $\mathcal{D}_2^\#$  we define the **reduction operator**  $\rho$  as:

$$\rho : \mathcal{D}_{1 \times 2}^\# \rightarrow \mathcal{D}_{1 \times 2}^\#$$

$$\rho(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \stackrel{\text{def}}{=} (\alpha_1(\gamma_1(\mathcal{X}_1^\#) \cap \gamma_2(\mathcal{X}_2^\#)), \alpha_2(\gamma_1(\mathcal{X}_1^\#) \cap \gamma_2(\mathcal{X}_2^\#)))$$

$\rho$  propagates information between domains.

## Application:

We can reduce the result of each abstract operator, except  $\nabla$ :

- $(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \cup_{1 \times 2}^\# (\mathcal{Y}_1^\#, \mathcal{Y}_2^\#) \stackrel{\text{def}}{=} \rho(\mathcal{X}_1^\# \cup_1^\# \mathcal{Y}_1^\#, \mathcal{X}_2^\# \cup_2^\# \mathcal{Y}_2^\#),$
- $\mathbf{C}^\# \llbracket c \rrbracket_{1 \times 2}(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \stackrel{\text{def}}{=} \rho(\mathbf{C}^\# \llbracket c \rrbracket_1(\mathcal{X}_1^\#), \mathbf{C}^\# \llbracket c \rrbracket_2(\mathcal{X}_2^\#)).$

We refrain from reducing after a widening  $\nabla$ ,  
this may jeopardize the convergence (octagon domain example).

# Fully-reduced product example

Reduction example: between the **interval** and **congruence** domains:

$$\begin{aligned} \text{Noting: } a' &\stackrel{\text{def}}{=} \min \{ x \geq a \mid x \equiv d [c] \} \\ b' &\stackrel{\text{def}}{=} \max \{ x \leq b \mid x \equiv d [c] \} \end{aligned}$$

We get:

$$\rho_b([a, b], c\mathbb{Z} + d) \stackrel{\text{def}}{=} \begin{cases} (\perp_b^\sharp, \perp_b^\sharp) & \text{if } a' > b' \\ ([a', a'], 0\mathbb{Z} + a') & \text{if } a' = b' \\ ([a', b'], c\mathbb{Z} + d) & \text{if } a' < b' \end{cases}$$

extended point-wisely to  $\rho$  on  $\mathcal{D}^\sharp$ .

## Application:

- $\rho_b([10, 11], 2\mathbb{Z} + 1) = ([11, 11], 0\mathbb{Z} + 11)$   
(proves that the branch is never taken on our example)
- $\rho_b([1, 3], 4\mathbb{Z}) = (\perp_b^\sharp, \perp_b^\sharp)$

# Partially-reduced product

Definition: of a **partial** reduction:

any function  $\rho : \mathcal{D}_{1 \times 2}^\# \rightarrow \mathcal{D}_{1 \times 2}^\#$  such that:

$$(\mathcal{Y}_1^\#, \mathcal{Y}_2^\#) = \rho(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \implies \begin{cases} \gamma_{1 \times 2}(\mathcal{Y}_1^\#, \mathcal{Y}_2^\#) = \gamma_{1 \times 2}(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \\ \gamma_1(\mathcal{Y}_1^\#) \subseteq \gamma_1(\mathcal{X}_1^\#) \\ \gamma_2(\mathcal{Y}_2^\#) \subseteq \gamma_2(\mathcal{X}_2^\#) \end{cases}$$

Useful when:

- there is no Galois connection, or
- a full reduction exists but is expensive to compute.

Partial reduction example:

$$\rho(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \stackrel{\text{def}}{=} \begin{cases} (\perp^\#, \perp^\#) & \text{if } \mathcal{X}_1^\# = \perp^\# \text{ or } \mathcal{X}_2^\# = \perp^\# \\ (\mathcal{X}_1^\#, \mathcal{X}_2^\#) & \text{otherwise} \end{cases}$$

(works on all domains)

For more complex examples, see [Blan03].

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