

Program Semantics

MPRI 2–6: Abstract Interpretation,
application to verification and static analysis

Antoine Miné

year 2015–2016

course 03

23 September 2015

Discuss several **flavors of concrete semantics**:

- **independently** from programming languages (transition systems)
- defined in a **constructive** way (as fixpoints)
- **compare** their expressive power (link by abstractions)

Plan:

- introduction: classic examples of program semantics
- transition systems
- state semantics (forward and backward)
- trace semantics (finite and infinite)
- relational semantics
- state and trace properties

Flavors of program semantics

Small-step operational semantics of the λ -calculus

Goal:

Illustrate through a simple example (λ -calculus) different flavors and levels of semantics.

They feature some notion of states and transitions.

\implies justifies transition systems as a universal model of semantics

Example: λ -calcul

syntax: λ -terms

t	$::=$	x	(variable)
	$ $	$\lambda x. t$	(abstraction)
	$ $	$t u$	(application)

Small-step operational semantics of the λ -calculus

Small-step operational semantics: (call-by-value)

$$\frac{}{(\lambda x.M)N \rightsquigarrow M[x/N]} \qquad \frac{M \rightsquigarrow M'}{M N \rightsquigarrow M' N} \qquad \frac{N \rightsquigarrow N'}{M N \rightsquigarrow M N'}$$

Models program execution as a sequence of term-rewriting \rightsquigarrow exposing each transition (low level).

Big-step operational semantics of the λ -calculus

Big-step operational semantics: (call-by-value)

$$\frac{}{\lambda x.M \Downarrow \lambda x.M} \qquad \frac{M \Downarrow \lambda x.L \quad N \Downarrow V_2 \quad L[x/V_2] \Downarrow V_1}{M N \Downarrow V_1}$$

$t \Downarrow u$ associates to a term t its full evaluation u ,
abstracting away intermediate steps (higher level).

Denotational semantics of the λ -calculus

Denotational semantics:

$$\begin{array}{lll}
 \llbracket x \rrbracket_{\rho} & \stackrel{\text{def}}{=} & \rho(x) \\
 \llbracket t \ u \rrbracket_{\rho} & \stackrel{\text{def}}{=} & \llbracket t \rrbracket_{\rho}(\llbracket u \rrbracket_{\rho}) \\
 \llbracket \lambda x. t \rrbracket_{\rho} & \stackrel{\text{def}}{=} & \lambda v. \llbracket t \rrbracket_{\rho[x \mapsto v]}
 \end{array}$$

The semantics $\llbracket t \rrbracket_{\rho}$ of a term t in an environment ρ is given as an element of a Scott domain \mathcal{D} .

- \mathcal{D} should satisfy the domain equation: $\mathcal{D} \simeq \mathcal{D} \xrightarrow{c} \mathcal{D}_{\perp}$
(CPO \mathcal{D} closed by continuous functions from \mathcal{D} to the lifted CPO \mathcal{D}_{\perp})
- The semantics of a program function is a mathematical function.
(very high level)

Abstract machine semantics of the λ -calculus

Krivine abstract machine: (call-by-value)

- variables in λ -terms are replaced with De Bruijn indices
($x \mapsto$ number of nested λ to reach λx)
- λ -terms are compiled into sequences of instructions:

$$\begin{array}{lll}
 \mathcal{I} & \stackrel{\text{def}}{=} & \textit{Grab} \mid \textit{Access}(\mathbb{Z}) \mid \textit{Push}(\mathcal{I}) \mid \mathcal{I}; \mathcal{I} \\
 \llbracket \cdot \rrbracket & \in & t \rightarrow \mathcal{I} \\
 \llbracket n \rrbracket & \stackrel{\text{def}}{=} & \textit{Access}(n) \\
 \llbracket \lambda N \rrbracket & \stackrel{\text{def}}{=} & \textit{Grab}; \llbracket N \rrbracket \\
 \llbracket N M \rrbracket & \stackrel{\text{def}}{=} & \textit{Push}(\llbracket M \rrbracket); \llbracket N \rrbracket
 \end{array}$$

Abstract machine semantics of the λ -calculus

- instructions are executed over configurations (C, e, s)
 - C : sequence of instructions to execute
 - e : environment
 - s : stack = list of pairs of (C, e) (closures)

with transitions:

- $\langle \text{Access}(0) \cdot C, (C_0, e_0) \cdot e, s \rangle \rightarrow \langle C_0, e_0, s \rangle$
- $\langle \text{Access}(n+1) \cdot C, (C_0, e_0) \cdot e, s \rangle \rightarrow \langle \text{Access}(n), e, s \rangle$
- $\langle \text{Push}(C') \cdot C, e, s \rangle \rightarrow \langle C, e, (C', e) \cdot s \rangle$
- $\langle \text{Grab} \cdot C, e, (C_0, e_0) \cdot s \rangle \rightarrow \langle C, (s_0, e_0) \cdot e, s \rangle$

\Rightarrow very low level. (but very efficient)

Transition systems

Transition systems: definition

Language-neutral formalism to discuss about program semantics.

Transition system: (Σ, τ)

- set of states Σ ,
(memory states, λ -terms, configurations, etc., generally infinite)
- transition relation $\tau \subseteq \Sigma \times \Sigma$.

(Σ, τ) is a general form of small-step operational semantics.

$(\sigma, \sigma') \in \tau$ is noted $\sigma \rightarrow \sigma'$:

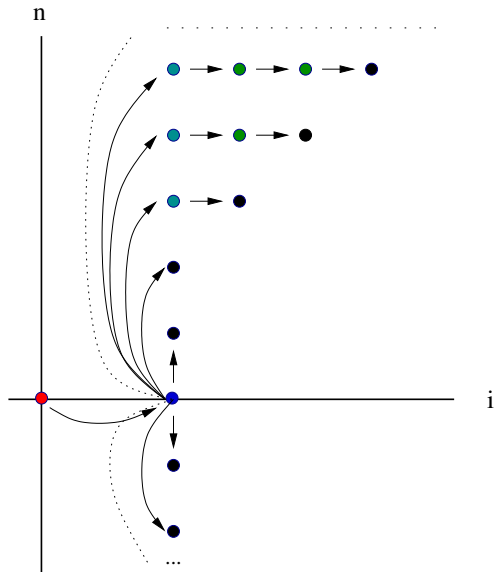
starting in state σ , after an execution step, we can go to state σ' .

Transition system: example

```

i ← 2;
n ←  $[-\infty, +\infty]$ ;
while i < n do
  if ? then
    i ← i + 1
  
```

$\Sigma \stackrel{\text{def}}{=} \{i, n\} \rightarrow \mathbb{Z}$



From programs to transition systems

Example: on a simple imperative language.

Language syntax

${}^{\ell}stat^{\ell}$	$::=$	${}^{\ell}X \leftarrow expr^{\ell}$	(assignment)
		${}^{\ell}if\ expr \bowtie 0\ then\ {}^{\ell}stat^{\ell}$	(conditional)
		${}^{\ell}while\ {}^{\ell}expr \bowtie 0\ do\ {}^{\ell}stat^{\ell}$	(loop)
		${}^{\ell}stat; {}^{\ell}stat^{\ell}$	(sequence)

- $X \in \mathbb{V}$, where \mathbb{V} is a finite set of program variables,
- $\ell \in \mathcal{L}$ is a finite set of control labels,
- $\bowtie \in \{=, \leq, \dots\}$, the syntax of $expr$ is left undefined.
(see next course)

Program states: $\Sigma \stackrel{\text{def}}{=} \mathcal{L} \times \mathcal{E}$ are composed of:

- a **control** state in \mathcal{L} ,
- a **memory** state in $\mathcal{E} \stackrel{\text{def}}{=} \mathbb{V} \rightarrow \mathbb{R}$.

From programs to transition systems

Transitions: $\tau[\ell stat \ell'] \subseteq \Sigma \times \Sigma$ is defined by induction on the syntax.

Assuming that expression semantics is given as $E[e] : \mathcal{E} \rightarrow \mathcal{P}(\mathbb{R})$.
(see next course)

$$\tau[\ell^1 X \leftarrow e \ell^2] \stackrel{\text{def}}{=} \{ (\ell^1, \rho) \rightarrow (\ell^2, \rho[X \mapsto v]) \mid \rho \in \mathcal{E}, v \in E[e] \rho \}$$

$$\begin{aligned} \tau[\ell^1 \text{if } e \bowtie 0 \text{ then } \ell^2 s \ell^3] &\stackrel{\text{def}}{=} \\ &\{ (\ell^1, \rho) \rightarrow (\ell^2, \rho) \mid \rho \in \mathcal{E}, \exists v \in E[e] \rho : v \bowtie 0 \} \cup \\ &\{ (\ell^1, \rho) \rightarrow (\ell^3, \rho) \mid \rho \in \mathcal{E}, \exists v \in E[e] \rho : v \not\bowtie 0 \} \cup \tau[\ell^2 s \ell^3] \end{aligned}$$

$$\begin{aligned} \tau[\ell^1 \text{while } \ell^2 e \bowtie 0 \text{ do } \ell^3 s \ell^4] &\stackrel{\text{def}}{=} \\ &\{ (\ell^1, \rho) \rightarrow (\ell^2, \rho) \mid \rho \in \mathcal{E} \} \cup \\ &\{ (\ell^2, \rho) \rightarrow (\ell^3, \rho) \mid \rho \in \mathcal{E}, \exists v \in E[e] \rho : v \bowtie 0 \} \cup \\ &\{ (\ell^2, \rho) \rightarrow (\ell^4, \rho) \mid \rho \in \mathcal{E}, \exists v \in E[e] \rho : v \not\bowtie 0 \} \cup \tau[\ell^3 s \ell^2] \end{aligned}$$

$$\tau[\ell^1 s_1; \ell^2 s_2 \ell^3] \stackrel{\text{def}}{=} \tau[\ell^1 s_1 \ell^2] \cup \tau[\ell^2 s_2 \ell^3]$$

State semantics

States and state operators

Initial, final, blocking states

Transition systems (Σ, τ) are often enriched with:

- $\mathcal{I} \subseteq \Sigma$ a set of distinguished **initial** states,
- $\mathcal{F} \subseteq \Sigma$ a set of distinguished **final** states.

(e.g., limit observation to executions starting in an initial state and ending in a final state)

Blocking states \mathcal{B} :

- states with **no successor** $\mathcal{B} \stackrel{\text{def}}{=} \{ \sigma \mid \forall \sigma' \in \Sigma: \sigma \not\rightarrow \sigma' \},$
- model correct program termination and program errors, (correct exit, program stuck, unhandled exception, etc.)
- often include (or equal) final states \mathcal{F} .

Note: we can always remove blocking states by completing τ :

$\tau' \stackrel{\text{def}}{=} \tau \cup \{ (\sigma, \sigma) \mid \sigma \in \mathcal{B} \}. \quad (\text{add self-loops})$

Post-image, pre-image

Forward and backward images, in $\mathcal{P}(\Sigma) \rightarrow \mathcal{P}(\Sigma)$:

- **successors:** (forward, post-image)
 $\text{post}_\tau(S) \stackrel{\text{def}}{=} \{ \sigma' \mid \exists \sigma \in S : \sigma \rightarrow \sigma' \}$
- **predecessors:** (backward, pre-image)
 $\text{pre}_\tau(S) \stackrel{\text{def}}{=} \{ \sigma \mid \exists \sigma' \in S : \sigma \rightarrow \sigma' \}$

post_τ and pre_τ are complete \cup -morphisms in $(\mathcal{P}(\Sigma), \subseteq, \cup, \cap, \emptyset, \Sigma)$.

$$(\text{post}_\tau(\cup_{i \in I} S_i) = \cup_{i \in I} \text{post}_\tau(S_i), \text{pre}_\tau(\cup_{i \in I} S_i) = \cup_{i \in I} \text{pre}_\tau(S_i))$$

post_τ and pre_τ are strict. $(\text{post}_\tau(\emptyset) = \text{pre}_\tau(\emptyset) = \emptyset)$

We have: $\text{pre}_\tau(S) = \cup \{ \text{pre}_\tau(\{s\}) \mid s \in S \}$ and $\text{post}_\tau(S) = \cup \{ \text{post}_\tau(\{s\}) \mid s \in S \}$.

Dual images

Dual post-images and pre-images:

- $\widetilde{\text{pre}}_\tau(S) \stackrel{\text{def}}{=} \{ \sigma \mid \forall \sigma': \sigma \rightarrow \sigma' \implies \sigma' \in S \}$
(states such that all successors satisfy S)
- $\widetilde{\text{post}}_\tau(S) \stackrel{\text{def}}{=} \{ \sigma' \mid \forall \sigma: \sigma \rightarrow \sigma' \implies \sigma \in S \}$
(states such that all predecessors satisfy S)

$\widetilde{\text{pre}}_\tau$ and $\widetilde{\text{post}}_\tau$ are complete \cap -morphisms and not strict.

Correspondences between images and dual images

$$\begin{aligned}
 \text{post}_\tau(S) &\stackrel{\text{def}}{=} \{ \sigma' \mid \exists \sigma \in S : \sigma \rightarrow \sigma' \} \\
 \text{pre}_\tau(S) &\stackrel{\text{def}}{=} \{ \sigma \mid \exists \sigma' \in S : \sigma \rightarrow \sigma' \} \\
 \widetilde{\text{pre}}_\tau(S) &\stackrel{\text{def}}{=} \{ \sigma \mid \forall \sigma' : \sigma \rightarrow \sigma' \implies \sigma' \in S \} \\
 \widetilde{\text{post}}_\tau(S) &\stackrel{\text{def}}{=} \{ \sigma' \mid \forall \sigma : \sigma \rightarrow \sigma' \implies \sigma \in S \}
 \end{aligned}$$

We have the following correspondences:

- inverse

$$\text{pre}_\tau = \text{post}_{(\tau^{-1})} \quad \text{post}_\tau = \text{pre}_{(\tau^{-1})}$$

$$\widetilde{\text{pre}}_\tau = \widetilde{\text{post}}_{(\tau^{-1})} \quad \widetilde{\text{post}}_\tau = \widetilde{\text{pre}}_{(\tau^{-1})}$$

$$(\text{where } \tau^{-1} \stackrel{\text{def}}{=} \{ (\sigma, \sigma') \mid (\sigma', \sigma) \in \tau \})$$

Correspondences between images and dual images

$$\begin{aligned}
 \text{post}_\tau(S) &\stackrel{\text{def}}{=} \{ \sigma' \mid \exists \sigma \in S : \sigma \rightarrow \sigma' \} \\
 \text{pre}_\tau(S) &\stackrel{\text{def}}{=} \{ \sigma \mid \exists \sigma' \in S : \sigma \rightarrow \sigma' \} \\
 \widetilde{\text{pre}}_\tau(S) &\stackrel{\text{def}}{=} \{ \sigma \mid \forall \sigma' : \sigma \rightarrow \sigma' \implies \sigma' \in S \} \\
 \widetilde{\text{post}}_\tau(S) &\stackrel{\text{def}}{=} \{ \sigma' \mid \forall \sigma : \sigma \rightarrow \sigma' \implies \sigma \in S \}
 \end{aligned}$$

We have the following correspondences:

- **Galois connections**

$$(\mathcal{P}(\Sigma), \subseteq) \xrightleftharpoons[\text{post}_\tau]{\widetilde{\text{pre}}_\tau} (\mathcal{P}(\Sigma), \subseteq) \text{ and}$$

$$(\mathcal{P}(\Sigma), \subseteq) \xrightleftharpoons[\text{pre}_\tau]{\widetilde{\text{post}}_\tau} (\mathcal{P}(\Sigma), \subseteq).$$

proof:

$$\begin{aligned}
 \text{post}_\tau(A) \subseteq B &\iff \{ \sigma' \mid \exists \sigma \in A : \sigma \rightarrow \sigma' \} \subseteq B \iff (\forall \sigma \in A : \sigma \rightarrow \\
 \sigma' \implies \sigma' \in B) &\iff (A \subseteq \{ \sigma \mid \forall \sigma' : \sigma \rightarrow \sigma' \implies \sigma' \in B \}) \iff A \subseteq \\
 \widetilde{\text{pre}}_\tau(B); &\text{ other directions are similar.}
 \end{aligned}$$

Deterministic systems

Determinism:

- (Σ, τ) is **deterministic** if $\forall \sigma \in \Sigma: |\text{post}_\tau(\{\sigma\})| = 1$,
(every state has a single successor, no blocking state)
- most transition systems are **non-deterministic**.
(e.g., effect of input $X \leftarrow [0, 10]$, program termination)

We have the following correspondences:

- $\forall S: \mathcal{B} \subseteq \widetilde{\text{pre}}_\tau(S) \subseteq \text{pre}_\tau(S) \cup \mathcal{B}$.
When $\mathcal{B} = \emptyset$, then $\widetilde{\text{pre}}_\tau(S) \subseteq \text{pre}_\tau(S)$.
- If τ is deterministic, then $\mathcal{B} = \emptyset$,
 $\text{pre}_\tau = \widetilde{\text{pre}}_\tau$ and $\text{post}_\tau = \widetilde{\text{post}}_\tau$.

Reachability state semantics

Forward reachability

$\mathcal{R}(\mathcal{I})$: states **reachable from \mathcal{I}** in the transition system

$$\begin{aligned}\mathcal{R}(\mathcal{I}) &\stackrel{\text{def}}{=} \{ \sigma \mid \exists n \geq 0, \sigma_0, \dots, \sigma_n: \sigma_0 \in \mathcal{I}, \sigma = \sigma_n, \forall i: \sigma_i \rightarrow \sigma_{i+1} \} \\ &= \bigcup_{n \geq 0} \text{post}_{\tau}^n(\mathcal{I})\end{aligned}$$

(reachable \iff reachable from \mathcal{I} in n steps of τ for some $n \geq 0$)

$\mathcal{R}(\mathcal{I})$ can be expressed in **fixpoint form**:

$$\mathcal{R}(\mathcal{I}) = \text{lfp } F_{\mathcal{R}} \text{ where } F_{\mathcal{R}}(S) \stackrel{\text{def}}{=} \mathcal{I} \cup \text{post}_{\tau}(S)$$

($F_{\mathcal{R}}$ shifts S and adds back \mathcal{I})

Alternate characterization: $\mathcal{R} = \text{lfp}_{\mathcal{I}} G_{\mathcal{R}}$ where $G_{\mathcal{R}}(S) \stackrel{\text{def}}{=} S \cup \text{post}_{\tau}(S)$.

($G_{\mathcal{R}}$ shifts S by τ and accumulates the result with S)

(proofs on next slide)

Forward reachability: proof

proof: of $\mathcal{R}(\mathcal{I}) = \text{lfp } F_{\mathcal{R}}$ where $F_{\mathcal{R}}(S) \stackrel{\text{def}}{=} \mathcal{I} \cup \text{post}_{\tau}(S)$

$(\mathcal{P}(\Sigma), \subseteq)$ is a CPO and post_{τ} is continuous, hence $F_{\mathcal{R}}$ is continuous:
 $F_{\mathcal{R}}(\cup_{i \in I} A_i) = \cup_{i \in I} F_{\mathcal{R}}(A_i)$.

By Kleene's theorem, $\text{lfp } F_{\mathcal{R}} = \cup_{n \in \mathbb{N}} F_{\mathcal{R}}^n(\emptyset)$.

We prove by recurrence on n that: $\forall n: F_{\mathcal{R}}^n(\emptyset) = \cup_{i < n} \text{post}_{\tau}^i(\mathcal{I})$.
 (states reachable in less than n steps)

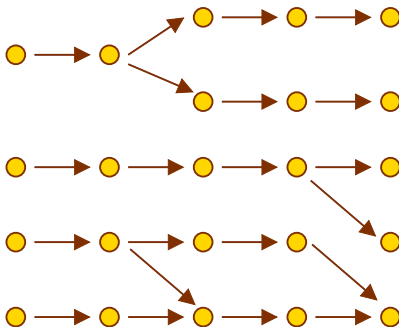
- $F_{\mathcal{R}}^0(\emptyset) = \emptyset$
- assuming the property at n ,

$$\begin{aligned}
 F_{\mathcal{R}}^{n+1}(\emptyset) &= F_{\mathcal{R}}(\cup_{i < n} \text{post}_{\tau}^i(\mathcal{I})) \\
 &= \mathcal{I} \cup \text{post}_{\tau}(\cup_{i < n} \text{post}_{\tau}^i(\mathcal{I})) \\
 &= \mathcal{I} \cup \cup_{i < n} \text{post}_{\tau}(\text{post}_{\tau}^i(\mathcal{I})) \\
 &= \mathcal{I} \cup \cup_{1 \leq i < n+1} \text{post}_{\tau}^i(\mathcal{I}) \\
 &= \cup_{i < n+1} \text{post}_{\tau}^i(\mathcal{I})
 \end{aligned}$$

Hence: $\text{lfp } F_{\mathcal{R}} = \cup_{n \in \mathbb{N}} F_{\mathcal{R}}^n(\emptyset) = \cup_{i \in \mathbb{N}} \text{post}_{\tau}^i(\mathcal{I}) = \mathcal{R}(\mathcal{I})$.

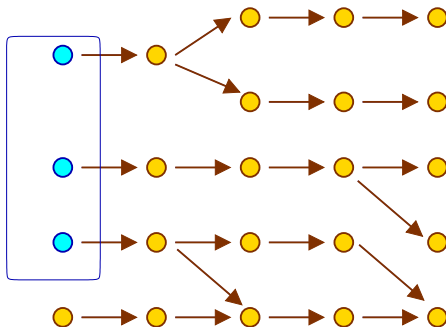
The proof is similar for the alternate form, given that $\text{lfp}_{\mathcal{I}} G_{\mathcal{R}} = \cup_{n \in \mathbb{N}} G_{\mathcal{R}}^n(\mathcal{I})$ and
 $G_{\mathcal{R}}^n(\mathcal{I}) = F_{\mathcal{R}}^{n+1}(\emptyset) = \cup_{i \leq n} \text{post}_{\tau}^i(\mathcal{I})$.

Forward reachability: graphical illustration



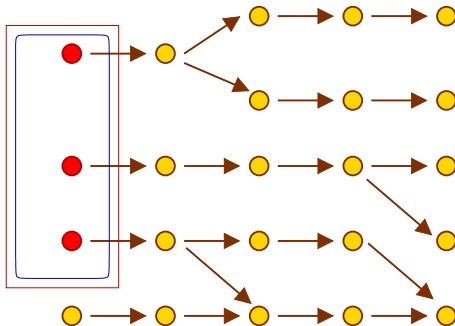
Transition system.

Forward reachability: graphical illustration



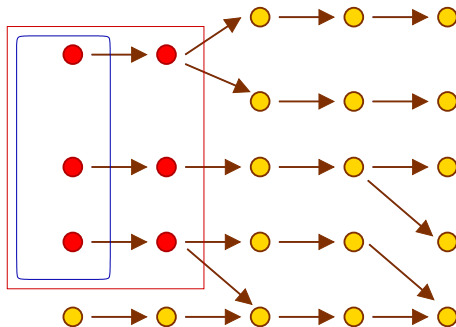
Initial states \mathcal{I} .

Forward reachability: graphical illustration



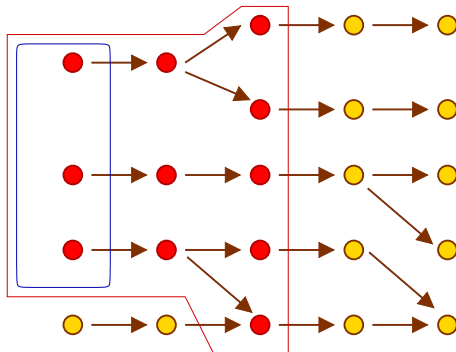
Iterate $F_{\mathcal{R}}^1(\mathcal{I})$.

Forward reachability: graphical illustration



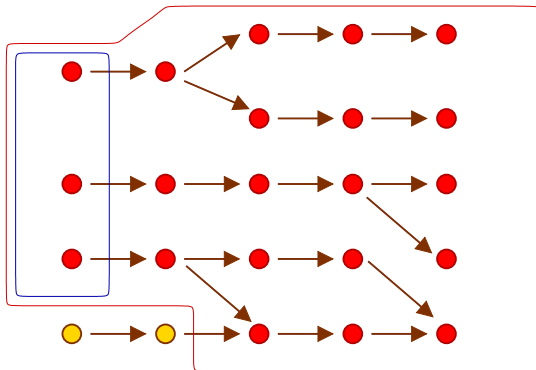
Iterate $F_{\mathcal{R}}^2(\mathcal{I})$.

Forward reachability: graphical illustration



Iterate $F_{\mathcal{R}}^3(\mathcal{I})$.

Forward reachability: graphical illustration



States reachable from \mathcal{I} : $\mathcal{R}(\mathcal{I}) = F_{\mathcal{R}}^5(\mathcal{I})$.

Forward reachability: applications

- Infer the set of possible states at program end: $\mathcal{R}(\mathcal{I}) \cap \mathcal{F}$.

example

```
•  $i \leftarrow 0$ ;  
  while  $i < 100$  do  
     $i \leftarrow i + 1$ ;  
     $j \leftarrow j + [0, 1]$   
  done •
```

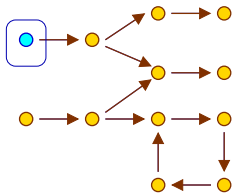
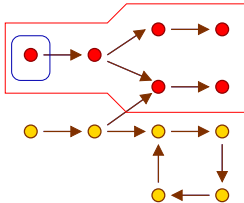
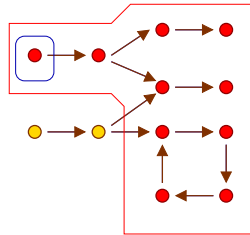
- initial states \mathcal{I} : $j \in [0, 10]$ at control state •,
 - final states \mathcal{F} : any memory state at control state •,
 - $\implies \mathcal{R}(\mathcal{I}) \cap \mathcal{F}$: control at •, $i = 100$, and $j \in [0, 110]$.
-
- Prove the absence of run-time error: $\mathcal{R}(\mathcal{I}) \cap \mathcal{B} \subseteq \mathcal{F}$.
(never block except when reaching the end of the program)

Multiple forward fixpoints

Recall: $\mathcal{R}(\mathcal{I}) = \text{lfp } F_{\mathcal{R}}$ where $F_{\mathcal{R}}(S) \stackrel{\text{def}}{=} \mathcal{I} \cup \text{post}_{\mathcal{T}}(S)$.

Note that $F_{\mathcal{R}}$ may have **several** fixpoints.

Example:

Initial state \mathcal{I} 
$$\mathcal{R}(\mathcal{I}) = \text{lfp } F_{\mathcal{R}}$$
 $\text{gfp } F_{\mathcal{R}}$

Exercise:

Compute all the fixpoints of $G_{\mathcal{R}}(S) \stackrel{\text{def}}{=} S \cup \text{post}_{\tau}(S)$ on this example.

Forward reachability equation system

By partitioning forward reachability wrt. control states, we retrieve the equation system form of program semantics.

Control state partitioning

We assume $\Sigma \stackrel{\text{def}}{=} \mathcal{L} \times \mathcal{E}$; note that: $\mathcal{P}(\Sigma) \simeq \mathcal{L} \rightarrow \mathcal{P}(\mathcal{E})$.

We have a Galois **isomorphism**:

$$(\mathcal{P}(\Sigma), \subseteq) \stackrel{\gamma_{\mathcal{L}}}{\underset{\alpha_{\mathcal{L}}}{\rightleftarrows}} (\mathcal{L} \rightarrow \mathcal{P}(\mathcal{E}), \dot{\subseteq})$$

- $X \dot{\subseteq} Y \stackrel{\text{def}}{\iff} \forall \ell \in \mathcal{L}: X(\ell) \subseteq Y(\ell)$
- $\alpha_{\mathcal{L}}(S) \stackrel{\text{def}}{=} \lambda \ell. \{ \rho \mid (\ell, \rho) \in S \}$
- $\gamma_{\mathcal{L}}(X) \stackrel{\text{def}}{=} \{ (\ell, \rho) \mid \ell \in \mathcal{L}, \rho \in X(\ell) \}$

Note that: $\alpha_{\mathcal{L}} \circ \gamma_{\mathcal{L}} = \gamma_{\mathcal{L}} \circ \alpha_{\mathcal{L}} = id$. (no abstraction)

Forward reachability equation system: example

Idea: compute $\alpha_{\mathcal{L}}(\mathcal{R}(\mathcal{I})) : \mathcal{L} \rightarrow \mathcal{P}(\mathcal{E})$

- introduce **variables**: $\mathcal{X}_{\ell} = (\alpha_{\mathcal{L}}(\mathcal{R}(\mathcal{I})))(\ell) \in \mathcal{P}(\mathcal{E})$,
- decompose the fixpoint equation $F_{\mathcal{R}}(S) = \mathcal{I} \cup \text{post}_{\tau}(S)$ on \mathcal{L} :
 $\alpha_{\mathcal{L}} \circ F_{\mathcal{R}} \circ \gamma_{\mathcal{L}}$ gives an **equation system** on $(\mathcal{X}_{\ell})_{\ell \in \mathcal{L}}$.

Example:

$\ell 1$	$i \leftarrow 2;$	$\mathcal{X}_1 = \mathcal{I}_1$
$\ell 2$	$n \leftarrow [-\infty, +\infty];$	$\mathcal{X}_2 = C[i \leftarrow 2] \mathcal{X}_1$
$\ell 3$	while	$\mathcal{X}_3 = C[n \leftarrow [-\infty, +\infty]] \mathcal{X}_2$
$\ell 4$	$i < n$ do	$\mathcal{X}_4 = \mathcal{X}_3 \cup \mathcal{X}_7$
$\ell 5$	if $[0, 1] = 0$ then	$\mathcal{X}_5 = C[i < n] \mathcal{X}_4$
$\ell 6$	$i \leftarrow i + 1$	$\mathcal{X}_6 = \mathcal{X}_5$
$\ell 7$		$\mathcal{X}_7 = \mathcal{X}_5 \cup C[i \leftarrow i + 1] \mathcal{X}_6$
$\ell 8$		$\mathcal{X}_8 = C[i \geq n] \mathcal{X}_4$

- initial states $\mathcal{I} \stackrel{\text{def}}{=} \{(\ell 1, \rho) \mid \rho \in \mathcal{I}_1\}$ for some $\mathcal{I}_1 \subseteq \mathcal{E}$,
- $C[\cdot] : \mathcal{P}(\mathcal{E}) \rightarrow \mathcal{P}(\mathcal{E})$ model assignments and tests (see next slide).

Forward reachability equation system: construction

We derive the equation system $eq(\ell^{stat^{\ell'}})$ from the program syntax $\ell^{stat^{\ell'}}$ by induction:

$$eq(\ell^1 X \leftarrow e^{\ell^2}) \stackrel{\text{def}}{=} \{ \mathcal{X}_{\ell^2} = C[X \leftarrow e] \mathcal{X}_{\ell^1} \}$$

$$eq(\ell^1 \text{if } e \bowtie 0 \text{ then } \ell^2 s^{\ell^3}) \stackrel{\text{def}}{=} \{ \mathcal{X}_{\ell^2} = C[e \bowtie 0] \mathcal{X}_{\ell^1}, \mathcal{X}_{\ell^3} = \mathcal{X}_{\ell^3'} \cup C[e \nmid \bowtie 0] \mathcal{X}_{\ell^1} \} \cup eq(\ell^2 s^{\ell^3'})$$

$$eq(\ell^1 \text{while } \ell^2 e \bowtie 0 \text{ do } \ell^3 s^{\ell^4}) \stackrel{\text{def}}{=} \{ \mathcal{X}_{\ell^2} = \mathcal{X}_{\ell^1} \cup \mathcal{X}_{\ell^4'}, \mathcal{X}_{\ell^3} = C[e \bowtie 0] \mathcal{X}_{\ell^2}, \mathcal{X}_{\ell^4} = C[e \nmid \bowtie 0] \mathcal{X}_{\ell^2} \} \cup eq(\ell^3 s^{\ell^4'})$$

$$eq(\ell^1 s_1; \ell^2 s_2^{\ell^3}) \stackrel{\text{def}}{=} eq(\ell^1 s_1^{\ell^2}) \cup (\ell^2 s_2^{\ell^3})$$

where:

- $\mathcal{X}^{\ell^3'}$, $\mathcal{X}^{\ell^4'}$ are fresh variables storing intermediate results
- $C[X \leftarrow e] \mathcal{X} \stackrel{\text{def}}{=} \{ \rho[X \mapsto v] \mid \rho \in \mathcal{X}, v \in E[e] \rho \}$
 $C[e \bowtie 0] \mathcal{X} \stackrel{\text{def}}{=} \{ \rho \in \mathcal{X} \mid \exists v \in E[\rho] \rho : v \bowtie 0 \}$

Co-reachability state semantics

Backward reachability

$\mathcal{C}(\mathcal{F})$: states **co-reachable from \mathcal{F}** in the transition system:

$$\begin{aligned}\mathcal{C}(\mathcal{F}) &\stackrel{\text{def}}{=} \{ \sigma \mid \exists n \geq 0, \sigma_0, \dots, \sigma_n: \sigma = \sigma_0, \sigma_n \in \mathcal{F}, \forall i: \sigma_i \rightarrow \sigma_{i+1} \} \\ &= \bigcup_{n \geq 0} \text{pre}_{\tau}^n(\mathcal{F})\end{aligned}$$

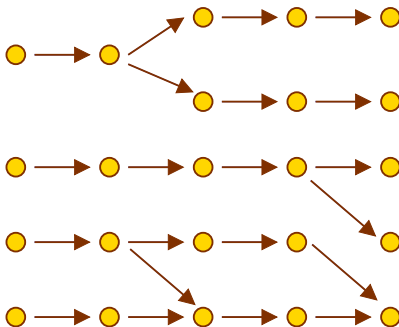
$\mathcal{C}(\mathcal{F})$ can also be expressed in **fixpoint form**:

$$\mathcal{C}(\mathcal{F}) = \text{lfp } F_{\mathcal{C}} \text{ where } F_{\mathcal{C}}(S) \stackrel{\text{def}}{=} \mathcal{F} \cup \text{pre}_{\tau}(S)$$

Alternate characterization: $\mathcal{C}(\mathcal{F}) = \text{lfp}_{\mathcal{I}} G_{\mathcal{C}}$ where $G_{\mathcal{C}}(S) = \mathcal{F} \cup \text{pre}_{\tau}(S)$

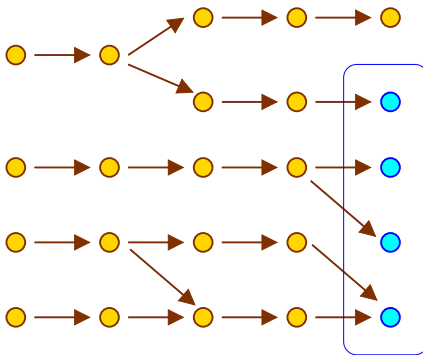
Justification: $\mathcal{C}(\mathcal{F})$ in τ is exactly $\mathcal{R}(\mathcal{F})$ in τ^{-1} .

Backward reachability: graphical illustration



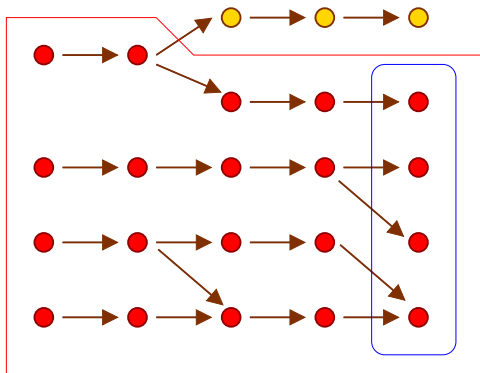
Transition system.

Backward reachability: graphical illustration



Final states \mathcal{F} .

Backward reachability: graphical illustration



States co-reachable from \mathcal{F} .

Backward reachability: applications

- $I \cap C(\mathcal{B} \setminus \mathcal{F})$

Initial states that have at least one erroneous execution.

program

```

•  $j \leftarrow 0;$ 
  while  $i > 0$  do
     $i \leftarrow i - 1;$ 
     $j \leftarrow j + [0, 10]$ 
  done •
  
```

- initial states \mathcal{I} : $i \in [0, 100]$ at •
- final states \mathcal{F} : any memory state at •
- blocking states \mathcal{B} : final, or $j > 200$ at any location
- $I \cap C(\mathcal{B} \setminus \mathcal{F})$: at •, $i > 20$

- $I \cap (\Sigma \setminus C(\mathcal{B}))$

Initial states that necessarily cause the program to loop.

- **Iterate** forward and backward analyses interactively
 \implies abstract debugging [Bour93].

Backward reachability equation system: example

Principle:

Use $(\mathcal{P}(\Sigma), \subseteq) \xleftrightarrow[\alpha_{\mathcal{L}}]{\gamma_{\mathcal{L}}} (\mathcal{L} \rightarrow \mathcal{P}(\mathcal{E}), \dot{\subseteq})$ on $F_{\mathcal{C}}(S) \stackrel{\text{def}}{=} \mathcal{F} \cup \text{pre}_{\tau}(S)$ to derive an **equation system** $\alpha_{\mathcal{L}} \circ F_{\mathcal{C}} \circ \gamma_{\mathcal{L}}$.

Example:

$\ell 1$	$i \leftarrow 2;$	$\mathcal{X}_1 = \mathcal{C}[\![i \rightarrow 2]\!] \mathcal{X}_2$
$\ell 2$	$n \leftarrow [-\infty, +\infty];$	$\mathcal{X}_2 = \mathcal{C}[\![n \rightarrow [-\infty, +\infty]]\!] \mathcal{X}_3$
$\ell 3$	while	$\mathcal{X}_3 = \mathcal{X}_4$
$\ell 4$	$i < n$	$\mathcal{X}_4 = \mathcal{C}[\![i < n]\!] \mathcal{X}_5 \cup \mathcal{C}[\![i \leq n]\!] \mathcal{X}_8$
$\ell 5$	if	$\mathcal{X}_5 = \mathcal{X}_6 \cup \mathcal{X}_7$
	$[0, 1] = 0$	$\mathcal{X}_6 = \mathcal{C}[\![i \rightarrow i + 1]\!] \mathcal{X}_7$
	then	$\mathcal{X}_7 = \mathcal{X}_4$
	$\ell 6$	$\mathcal{X}_8 = \mathcal{F}_8$
	$i \leftarrow i + 1$	
$\ell 7$		
$\ell 8$		

- final states $\mathcal{F} \stackrel{\text{def}}{=} \{(\ell 8, \rho) \mid \rho \in \mathcal{F}_8\}$ for some $\mathcal{F}_8 \subseteq \mathcal{E}$,
- $\mathcal{C}[\![X \rightarrow e]\!] \mathcal{X} \stackrel{\text{def}}{=} \{\rho \mid \exists v \in \mathcal{E}[\![e]\!] \rho[X \mapsto v] \in \mathcal{X}\}.$

Pre-condition state semantics

Sufficient preconditions

$\mathcal{S}(\mathcal{Y})$: states with executions **staying** in \mathcal{Y} .

$$\begin{aligned}\mathcal{S}(\mathcal{Y}) &\stackrel{\text{def}}{=} \{ \sigma \mid \forall n \geq 0, \sigma_0, \dots, \sigma_n : (\sigma = \sigma_0 \wedge \forall i: \sigma_i \rightarrow \sigma_{i+1}) \implies \sigma_n \in \mathcal{Y} \} \\ &= \bigcap_{n \geq 0} \widetilde{\text{pre}}_{\tau}^n(\mathcal{Y})\end{aligned}$$

$\mathcal{S}(\mathcal{Y})$ can be expressed in **fixpoint** form:

$$\mathcal{S}(\mathcal{Y}) = \text{gfp } F_{\mathcal{S}} \text{ where } F_{\mathcal{S}}(S) \stackrel{\text{def}}{=} \mathcal{Y} \cap \widetilde{\text{pre}}_{\tau}(S)$$

proof sketch: similar to that of $\mathcal{R}(\mathcal{I})$, in the dual.

$F_{\mathcal{S}}$ is continuous in the dual CPO $(\mathcal{P}(\Sigma), \supseteq)$, because $\widetilde{\text{pre}}_{\tau}$ is:

$$F_{\mathcal{S}}(\bigcap_{i \in I} A_i) = \bigcap_{i \in I} F_{\mathcal{S}}(A_i).$$

By Kleene's theorem in the dual, $\text{gfp } F_{\mathcal{S}} = \bigcap_{n \in \mathbb{N}} F_{\mathcal{S}}^n(\Sigma)$.

We would prove by recurrence that $F_{\mathcal{S}}^n(\Sigma) = \bigcap_{i < n} \widetilde{\text{pre}}_{\tau}^i(\mathcal{Y})$.

Sufficient preconditions and reachability

Correspondence with reachability:

We have a **Galois connection**:

$$(\mathcal{P}(\Sigma), \subseteq) \xleftrightarrow[\mathcal{R}]{\mathcal{S}} (\mathcal{P}(\Sigma), \subseteq)$$

- $\mathcal{R}(\mathcal{I}) \subseteq \mathcal{Y} \iff \mathcal{I} \subseteq \mathcal{S}(\mathcal{Y})$
- so $\mathcal{S}(\mathcal{Y}) = \bigcup \{X \mid \mathcal{R}(X) \subseteq \mathcal{Y}\}$

($\mathcal{S}(\mathcal{Y})$ is the largest initial set whose reachability is in \mathcal{Y})

We retrieve Dijkstra's **weakest liberal preconditions**.

(proof sketch on next slide)

Sufficient preconditions and reachability (proof)

proof sketch:

Recall that $\mathcal{R}(\mathcal{I}) = \text{lfp}_{\mathcal{I}} G_{\mathcal{R}}$ where $G_{\mathcal{R}}(S) = S \cup \text{post}_{\tau}(S)$.

Likewise, $\mathcal{S}(\mathcal{Y}) = \text{gfp}_{\mathcal{Y}} G_{\mathcal{S}}$ where $G_{\mathcal{S}}(S) = S \cap \widetilde{\text{pre}}_{\tau}(S)$.

Recall the Galois connection $(\mathcal{P}(\Sigma), \subseteq) \xleftrightarrow[\text{post}_{\tau}]{\widetilde{\text{pre}}_{\tau}} (\mathcal{P}(\Sigma), \subseteq)$.

As a consequence $(\mathcal{P}(\Sigma), \subseteq) \xleftrightarrow[G_{\mathcal{R}}]{G_{\mathcal{S}}} (\mathcal{P}(\Sigma), \subseteq)$.

The Galois connection can be lifted to fixpoint operators:

$(\mathcal{P}(\Sigma), \subseteq) \xleftrightarrow[x \mapsto \text{lfp}_x G_{\mathcal{R}}]{x \mapsto \text{gfp}_x G_{\mathcal{S}}} (\mathcal{P}(\Sigma), \subseteq)$.

Exercise: complete the proof sketch.

Sufficient preconditions: application

Initial states such that **all executions** are correct:

$$\mathcal{I} \cap \mathcal{S}(\mathcal{F} \cup (\Sigma \setminus \mathcal{B})).$$

(the only blocking states reachable from initial states are final states)

program

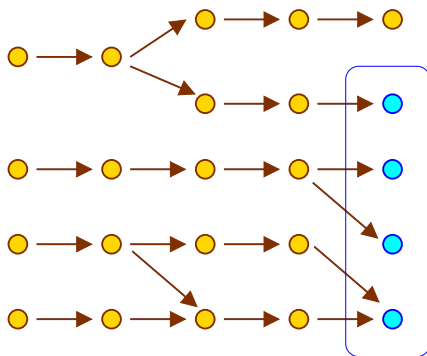
```

•  $i \leftarrow 0;$ 
  while  $i < 100$  do
     $i \leftarrow i + 1;$ 
     $j \leftarrow j + [0, 1]$ 
  done •
  
```

- initial states \mathcal{I} : $j \in [0, 10]$ at •
- final states \mathcal{F} : any memory state at •
- blocking states \mathcal{B} : final, or $j > 105$ at any location
- $\mathcal{I} \cap \mathcal{S}(\mathcal{F} \cup (\Sigma \setminus \mathcal{B}))$: at •, $i \in [0, 5]$
(note that $\mathcal{I} \cap \mathcal{C}(\mathcal{F} \cup (\Sigma \setminus \mathcal{B}))$ gives \mathcal{I})

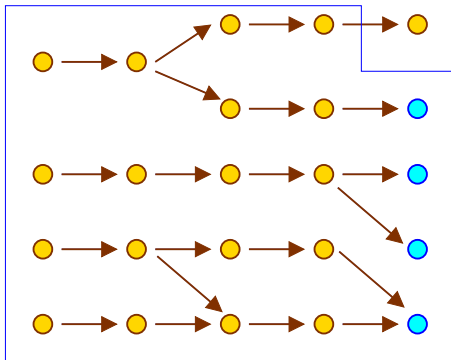
Applications: infer contracts; optimize (hoist) tests;
infer counter-examples.

Sufficient preconditions: graphical illustration



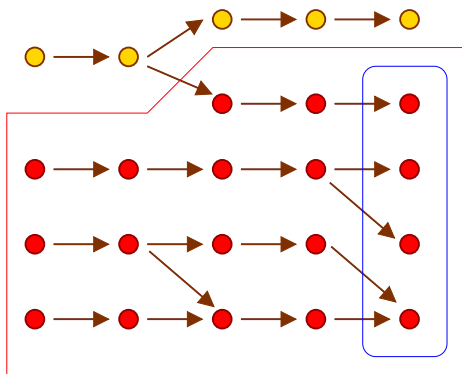
Final states \mathcal{F} .

Sufficient preconditions: graphical illustration



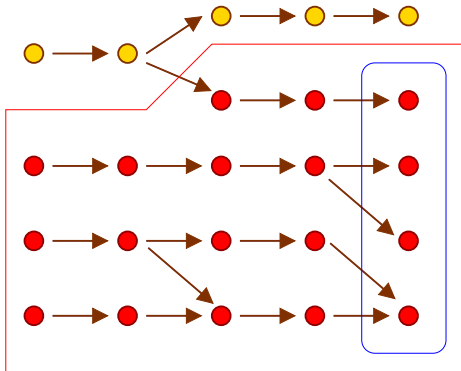
Set of final or non-blocking states $\mathcal{Y} = \mathcal{F} \cup (\Sigma \setminus \mathcal{B})$.

Sufficient preconditions: graphical illustration

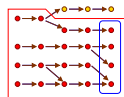


Sufficient preconditions $\mathcal{S}(\mathcal{Y})$.

Sufficient preconditions: graphical illustration



Sufficient preconditions $\mathcal{S}(\mathcal{Y})$.



$\mathcal{C}(\mathcal{F})$

$$\mathcal{S}(\mathcal{Y}) \subset \mathcal{C}(\mathcal{F})$$

Sufficient precondition equation system: example

Principle:

use $(\mathcal{P}(\Sigma), \subseteq) \xleftrightarrow[\alpha_{\mathcal{L}}]{\gamma_{\mathcal{L}}} (\mathcal{L} \rightarrow \mathcal{P}(\mathcal{E}), \dot{\subseteq})$ on $F_S(S) \stackrel{\text{def}}{=} \mathcal{Y} \cap \widetilde{\text{pre}}_{\tau}(S)$

to derive an **equation system** $\alpha_{\mathcal{L}} \circ F_S \circ \gamma_{\mathcal{L}}$

Example:

```

ℓ1 i ← 2;
ℓ2 n ← [-∞, +∞];
ℓ3 while ℓ4 i < n do
    ℓ5 if [0, 1] = 0 then
        ℓ6 i ← i + 1
    ℓ7
ℓ8

```

$$\begin{aligned}
 \mathcal{X}_1 &= \overleftarrow{C} \llbracket i \leftarrow 2 \rrbracket \mathcal{X}_2 \\
 \mathcal{X}_2 &= \overleftarrow{C} \llbracket n \leftarrow [-\infty, +\infty] \rrbracket \mathcal{X}_3 \\
 \mathcal{X}_3 &= \mathcal{X}_4 \\
 \mathcal{X}_4 &= \overleftarrow{C} \llbracket i < n \rrbracket \mathcal{X}_5 \cap \overleftarrow{C} \llbracket i \leq n \rrbracket \mathcal{X}_8 \\
 \mathcal{X}_5 &= \mathcal{X}_6 \cap \mathcal{X}_7 \\
 \mathcal{X}_6 &= \overleftarrow{C} \llbracket i \leftarrow i + 1 \rrbracket \mathcal{X}_7 \\
 \mathcal{X}_7 &= \mathcal{X}_4 \\
 \mathcal{X}_8 &= \mathcal{F}_8
 \end{aligned}$$

- “stay in” states $\mathcal{Y} \stackrel{\text{def}}{=} \{ (\ell, \rho) \mid \ell \neq \ell 8 \vee \rho \in \mathcal{F}_8 \}$ for some $\mathcal{F}_8 \subseteq \mathcal{E}$,
- $\overleftarrow{C} \llbracket \cdot \rrbracket$ is the Galois adjoint of $C \llbracket \cdot \rrbracket$.

Trace semantics

Traces and trace operations

Sequences, traces

Trace: sequence of elements from Σ

- ϵ : empty trace (unique)
- σ : trace of length 1 (assimilated to a state)
- $\sigma_0, \dots, \sigma_{n-1}$: trace of length n
- $\sigma_0, \dots, \sigma_n, \dots$: infinite trace (length ω)

Trace sets:

- Σ^n : the set of traces of length n
- $\Sigma^{\leq n} \stackrel{\text{def}}{=} \bigcup_{i \leq n} \Sigma^i$: the set of traces of length at most n
- $\Sigma^* \stackrel{\text{def}}{=} \bigcup_{i \in \mathbb{N}} \Sigma^i$: the set of finite traces
- Σ^ω : the set of infinite traces
- $\Sigma^\infty \stackrel{\text{def}}{=} \Sigma^* \cup \Sigma^\omega$: the set of all traces

Trace operations

Operations on traces:

- **length**: $|t| \in \mathbb{N} \cup \{\omega\}$ of a trace $t \in \Sigma^\infty$
- **concatenation** \cdot
 - $(\sigma_0, \dots, \sigma_n) \cdot (\sigma'_0, \dots) \stackrel{\text{def}}{=} \sigma_0, \dots, \sigma_n, \sigma'_0, \dots$
(append to a finite trace)
 - $t \cdot t' \stackrel{\text{def}}{=} t$ if $t \in \Sigma^\omega$ (append to an infinite trace does nothing)
 - $\epsilon \cdot t \stackrel{\text{def}}{=} t \cdot \epsilon \stackrel{\text{def}}{=} t$ (ϵ is neutral)
- **junction** \frown
 - $(\sigma_0, \dots, \sigma_n) \frown (\sigma'_0, \sigma'_1, \dots) \stackrel{\text{def}}{=} \sigma_0, \dots, \sigma_n, \sigma'_1, \dots$ when $\sigma_n = \sigma'_0$
undefined if $\sigma_n \neq \sigma'_0$
 - $\epsilon \frown t$ and $t \frown \epsilon$ are undefined
 - $t \frown t' \stackrel{\text{def}}{=} t$, if $t \in \Sigma^\omega$

Trace operations (cont.)

Extension to **sets of traces**:

- $A \cdot B \stackrel{\text{def}}{=} \{a \cdot b \mid a \in A, b \in B\}$
- $A \frown B \stackrel{\text{def}}{=} \{a \frown b \mid a \in A, b \in B, a \frown b \text{ defined}\}$
- $A^0 = \{\epsilon\}$ (neutral element for \cdot)
 $A^{n+1} \stackrel{\text{def}}{=} A \cdot A^n,$
 $A^\omega \stackrel{\text{def}}{=} A \cdot A \cdot \dots$
 $A^* \stackrel{\text{def}}{=} \bigcup_{n < \omega} A^n,$
 $A^\infty \stackrel{\text{def}}{=} \bigcup_{n \leq \omega} A^n$
- $A^{\frown 0} = \Sigma$ (neutral element for \frown)
 $A^{\frown n+1} \stackrel{\text{def}}{=} A \frown A^{\frown n},$
 $A^{\frown \omega} \stackrel{\text{def}}{=} A \frown A \frown \dots$
 $A^{\frown *} \stackrel{\text{def}}{=} \bigcup_{n < \omega} A^{\frown n},$
 $A^{\frown \infty} \stackrel{\text{def}}{=} \bigcup_{n \leq \omega} A^{\frown n}$

Note: $A^n \neq \{a^n \mid a \in A\}$, $A^{\frown n} \neq \{a^{\frown n} \mid a \in A\}$ when $|A| > 1$

Distributivity of junction

- \frown distributes over finite and infinite \cup :

$$A \frown (\cup_{i \in I} B_i) = \cup_{i \in I} (A \frown B_i) \text{ and}$$

$$(\cup_{i \in I} A_i) \frown B = \cup_{i \in I} (A_i \frown B)$$

where I can be finite or infinite.

- \frown distributes finite \cap but **not infinite \cap**

example:

$$\{a^\omega\} \frown (\cap_{n \in \mathbb{N}} \{a^m \mid n \geq m\}) = \{a^\omega\} \frown \emptyset = \emptyset \text{ but}$$

$$\cap_{n \in \mathbb{N}} (\{a^\omega\} \frown \{a^m \mid n \geq m\}) = \cap_{n \in \mathbb{N}} \{a^\omega\} = \{a^\omega\}$$

- but, if $A \subseteq \Sigma^*$, then $A \frown (\cap_{i \in I} B_i) = \cap_{i \in I} (A \frown B_i)$
even for infinite I

Note: concatenation \cdot distributes infinite \cap and \cup .

Traces of a transition system

Execution traces:

Non-empty sequences of states linked by the transition relation τ .

- can be **finite** (in $\mathcal{P}(\Sigma^*)$) or **infinite** (in $\mathcal{P}(\Sigma^\omega)$)
- can be anchored at initial states, or final states, or none

Atomic traces:

- \mathcal{I} : initial states \simeq set of traces of length **1**
- \mathcal{F} : final states \simeq set of traces of length **1**
- τ : transition relation \simeq set of traces of length **2**
($\{ \sigma, \sigma' \mid \sigma \rightarrow \sigma' \}$)

(as $\Sigma \simeq \Sigma^1$ and $\Sigma \times \Sigma \simeq \Sigma^2$)

Finite trace semantics

Prefix trace semantics

$\mathcal{T}_p(\mathcal{I})$: partial, finite **execution traces** starting in \mathcal{I} .

$$\begin{aligned}\mathcal{T}_p(\mathcal{I}) &\stackrel{\text{def}}{=} \{ \sigma_0, \dots, \sigma_n \mid n \geq 0, \sigma_0 \in \mathcal{I}, \forall i: \sigma_i \rightarrow \sigma_{i+1} \} \\ &= \bigcup_{n \geq 0} \mathcal{I} \frown (\tau \frown^n)\end{aligned}$$

(traces of length n , for any n , starting in \mathcal{I} and following τ)

$\mathcal{T}_p(\mathcal{I})$ can be expressed in **fixpoint form**:

$$\mathcal{T}_p(\mathcal{I}) = \text{lfp } F_p \text{ where } F_p(T) \stackrel{\text{def}}{=} \mathcal{I} \cup T \frown \tau$$

(F_p appends a transition to each trace, and adds back \mathcal{I})

(proof on next slide)

Prefix trace semantics: proof

proof of: $\mathcal{T}_p(\mathcal{I}) = \text{lfp } F_p$ where $F_p(T) = \mathcal{I} \cup T \frown \tau$

Similar to the proof of $\mathcal{R}(\mathcal{I}) = \text{lfp } F_{\mathcal{R}}$ where $F_{\mathcal{R}}(S) \stackrel{\text{def}}{=} \mathcal{I} \cup \text{post}_{\tau}(S)$.

F_p is continuous in a CPO $(\mathcal{P}(\Sigma^*), \subseteq)$:

$F_p(\bigcup_{i \in I} T_i) = \mathcal{I} \cup (\bigcup_{i \in I} T_i) \frown \tau = \mathcal{I} \cup (\bigcup_{i \in I} T_i \frown \tau) = \bigcup_{i \in I} (\mathcal{I} \cup T_i \frown \tau)$,
hence (Kleene), $\text{lfp } F_p = \bigcup_{n \geq 0} F_p^n(\emptyset)$

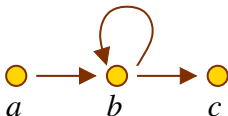
We prove by recurrence on n that $\forall n: F_p^n(\emptyset) = \bigcup_{i < n} \mathcal{I} \frown \tau \frown^i$:

- $F_p^0(\emptyset) = \emptyset$,
- $F_p^{n+1}(\emptyset) = \mathcal{I} \cup F_p^n(\emptyset) \frown \tau = \mathcal{I} \cup (\bigcup_{i < n} \mathcal{I} \frown \tau \frown^i) \frown \tau = \mathcal{I} \cup \bigcup_{i < n} (\mathcal{I} \frown \tau \frown^{i+1}) = \bigcup_{i < n+1} \mathcal{I} \frown \tau \frown^i$.

Thus, $\text{lfp } F_p = \bigcup_{n \in \mathbb{N}} F_p^n(\emptyset) = \bigcup_{n \in \mathbb{N}} \bigcup_{i < n} \mathcal{I} \frown \tau \frown^i = \bigcup_{i \in \mathbb{N}} \mathcal{I} \frown \tau \frown^i$.

Note: we also have $\mathcal{T}_p(\mathcal{I}) = \text{lfp}_{\mathcal{I}} G_p$ where $G_p(T) = T \cup T \frown \tau$.

Prefix trace semantics: graphical illustration



$$\mathcal{I} \stackrel{\text{def}}{=} \{a\}$$

$$\tau \stackrel{\text{def}}{=} \{(a, b), (b, b), (b, c)\}$$

Iterates: $\mathcal{T}_p(\mathcal{I}) = \text{lfp } F_p$ where $F_p(T) \stackrel{\text{def}}{=} \mathcal{I} \cup T \cap \tau$.

- $F_p^0(\emptyset) = \emptyset$
- $F_p^1(\emptyset) = \mathcal{I} = \{a\}$
- $F_p^2(\emptyset) = \{a, ab\}$
- $F_p^3(\emptyset) = \{a, ab, abb, abc\}$
- $F_p^n(\emptyset) = \{a, ab^i, ab^j c \mid i \in [1, n-1], j \in [1, n-2]\}$
- $\mathcal{T}_p(\mathcal{I}) = \cup_{n \geq 0} F_p^n(\emptyset) = \{a, ab^i, ab^j c \mid i \geq 1\}$

Prefix trace semantics: expressive power

The prefix trace semantics is the collection of **finite observations** of program executions.

\implies Semantics of **testing**.

Limitations:

- no information on **infinite** executions,
(we will add infinite traces later)
- can bound maximal execution time: $\mathcal{T}_p(\mathcal{I}) \subseteq \Sigma^{\leq n}$
but cannot bound **minimal execution time**.
(we will consider maximal traces later)

Abstracting traces into states

Idea: view state semantics as abstractions of traces semantics.

We have a **Galois embedding** between finite traces and states:

$$(\mathcal{P}(\Sigma^*), \subseteq) \overset{\gamma_p}{\underset{\alpha_p}{\rightleftarrows}} (\mathcal{P}(\Sigma), \subseteq)$$

- $\alpha_p(T) \stackrel{\text{def}}{=} \{ \sigma \in \Sigma \mid \exists \sigma_0, \dots, \sigma_n \in T : \sigma = \sigma_n \}$
(last state in traces in T)
- $\gamma_p(S) \stackrel{\text{def}}{=} \{ \sigma_0, \dots, \sigma_n \in \Sigma^* \mid \sigma_n \in S \}$
(traces ending in a state in S)

(proof on next slide)

Abstracting traces into states (proof)

proof of: (α_p, γ_p) forms a Galois embedding.

Instead of the definition $\alpha(c) \subseteq a \iff c \subseteq \gamma(a)$, we use the alternate characterization of Galois connections: α and γ are monotonic, $\gamma \circ \alpha$ is extensive, and $\alpha \circ \gamma$ is reductive.

Embedding means that, additionally, $\alpha \circ \gamma = id$.

- α_p, γ_p are \cup -morphisms, hence monotonic
- $(\gamma_p \circ \alpha_p)(T)$

$$= \{ \sigma_0, \dots, \sigma_n \mid \sigma_n \in \alpha_p(T) \}$$

$$= \{ \sigma_0, \dots, \sigma_n \mid \exists \sigma'_0, \dots, \sigma'_m \in T : \sigma_n = \sigma'_m \}$$

$$\supseteq T$$
- $(\alpha_p \circ \gamma_p)(S)$

$$= \{ \sigma \mid \exists \sigma_0, \dots, \sigma_n \in \gamma_p(S) : \sigma = \sigma_n \}$$

$$= \{ \sigma \mid \exists \sigma_0, \dots, \sigma_n : \sigma_n \in S, \sigma = \sigma_n \}$$

$$= S$$

Abstracting prefix traces into reachability

Recall that:

- $\mathcal{T}_p(\mathcal{I}) = \text{lfp } F_p$ where $F_p(T) \stackrel{\text{def}}{=} \mathcal{I} \cup T \cap \tau$,
- $\mathcal{R}(\mathcal{I}) = \text{lfp } F_{\mathcal{R}}$ where $F_{\mathcal{R}}(S) \stackrel{\text{def}}{=} \mathcal{I} \cup \text{post}_{\tau}(S)$,
- $(\mathcal{P}(\Sigma^*), \subseteq) \xrightleftharpoons[\alpha_p]{\gamma_p} (\mathcal{P}(\Sigma), \subseteq)$.

We have: $\alpha_p \circ F_p = F_{\mathcal{R}} \circ \alpha_p$;

by fixpoint transfer, we get: $\alpha_p(\mathcal{T}_p(\mathcal{I})) = \mathcal{R}(\mathcal{I})$.

(proof on next slide)

Abstracting prefix traces into reachability (proof)

proof: of $\alpha_p \circ F_p = F_{\mathcal{R}} \circ \alpha_p$

$$\begin{aligned}
 & (\alpha_p \circ F_p)(T) \\
 &= \alpha_p(\mathcal{I} \cup T \frown \tau) \\
 &= \{ \sigma \mid \exists \sigma_0, \dots, \sigma_n \in \mathcal{I} \cup T \frown \tau : \sigma = \sigma_n \} \\
 &= \mathcal{I} \cup \{ \sigma \mid \exists \sigma_0, \dots, \sigma_n \in T \frown \tau : \sigma = \sigma_n \} \\
 &= \mathcal{I} \cup \{ \sigma \mid \exists \sigma_0, \dots, \sigma_n \in T : \sigma_n \rightarrow \sigma \} \\
 &= \mathcal{I} \cup \text{post}_{\tau}(\{ \sigma \mid \exists \sigma_0, \dots, \sigma_n \in T : \sigma = \sigma_n \}) \\
 &= \mathcal{I} \cup \text{post}_{\tau}(\alpha_p(T)) \\
 &= (F_{\mathcal{R}} \circ \alpha_p)(T)
 \end{aligned}$$

Abstracting traces into states (example)

program

```
j ← 0;  
i ← 0;  
while i < 100 do  
  i ← i + 1;  
  j ← j + [0, 1]  
done
```

- **prefix trace** semantics:
i and j are **increasing** and $0 \leq j \leq i \leq 100$
- **forward reachable state** semantics:
 $0 \leq j \leq i \leq 100$

⇒ the abstraction **forgets the ordering of states**.

Prefix closure

Prefix partial order: \preceq on Σ^∞

$$x \preceq y \stackrel{\text{def}}{\iff} \exists u \in \Sigma^\infty : x \cdot u = y$$

(Σ^∞, \preceq) is a CPO, while (Σ^*, \preceq) is not complete.

Prefix closure: $\rho_p : \mathcal{P}(\Sigma^\infty) \rightarrow \mathcal{P}(\Sigma^\infty)$

$$\rho_p(T) \stackrel{\text{def}}{=} \{ u \mid \exists t \in T : u \preceq t, u \neq \epsilon \}$$

ρ_p is an upper closure operator on $\mathcal{P}(\Sigma^\infty \setminus \{\epsilon\})$.

(monotonic, extensive $T \subseteq \rho_p(T)$, idempotent $\rho_p \circ \rho_p = \rho_p$)

The **prefix** trace semantics is **closed by prefix**:

$$\rho_p(\mathcal{T}_p(\mathcal{I})) = \mathcal{T}_p(\mathcal{I}).$$

(note that $\epsilon \notin \mathcal{T}_p(\mathcal{I})$, which is why we disallowed ϵ in ρ_p)

Ordering abstraction

Another **Galois embedding** between finite traces and states:

$$(\mathcal{P}(\Sigma^*), \subseteq) \overset{\gamma_o}{\underset{\alpha_o}{\rightleftarrows}} (\mathcal{P}(\Sigma), \subseteq)$$

- $\alpha_o(T) \stackrel{\text{def}}{=} \{ \sigma \mid \exists \sigma_0, \dots, \sigma_n \in T, i \leq n : \sigma = \sigma_i \}$
(set of all states appearing in some trace in T)
- $\gamma_o(S) \stackrel{\text{def}}{=} \{ \sigma_0, \dots, \sigma_n \mid n \geq 0, \forall i \leq n : \sigma_i \in S \}$
(traces composed of elements from S)

proof sketch:

α_o and γ_o are monotonic, and $\alpha_o \circ \gamma_o = id$.

$$\begin{aligned} (\gamma_o \circ \alpha_o)(T) &= \{ \sigma_0, \dots, \sigma_n \mid \forall i \leq n : \exists \sigma'_0, \dots, \sigma'_m \in T, j \leq m : \sigma_i = \sigma'_j \} \\ &\supseteq T. \end{aligned}$$

Ordering abstraction

We have: $\alpha_o(\mathcal{T}_p(\mathcal{I})) = \mathcal{R}(\mathcal{I})$.

proof:

We have $\alpha_o = \alpha_p \circ \rho_p$ (i.e.: a state is in a trace if it is the last state of one of its prefix).

Recall the prefix trace abstraction into states: $\mathcal{R}(\mathcal{I}) = \alpha_p(\mathcal{T}_p(\mathcal{I}))$ and the fact that the prefix trace semantics is closed by prefix: $\rho_p(\mathcal{T}_p(\mathcal{I})) = \mathcal{T}_p(\mathcal{I})$.

We get $\alpha_o(\mathcal{T}_p(\mathcal{I})) = \alpha_p(\rho_p(\mathcal{T}_p(\mathcal{I}))) = \alpha_p(\mathcal{T}_p(\mathcal{I})) = \mathcal{R}(\mathcal{I})$.

alternate proof: generalized fixpoint transfer

Recall that $\mathcal{T}_p(\mathcal{I}) = \text{lfp } F_p$ where $F_p(T) \stackrel{\text{def}}{=} \mathcal{I} \cup T \cap \tau$ and $\mathcal{R}(\mathcal{I}) = \text{lfp } F_{\mathcal{R}}$ where $F_{\mathcal{R}}(S) \stackrel{\text{def}}{=} \mathcal{I} \cup \text{post}_{\tau}(S)$, but $\alpha_o \circ F_p = F_{\mathcal{R}} \circ \alpha_o$ does not hold in general, so, fixpoint transfer theorems do not apply directly.

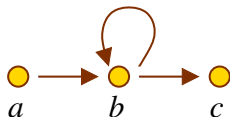
However, $\alpha_o \circ F_p = F_{\mathcal{R}} \circ \alpha_o$ holds for sets of traces closed by prefix. By induction, the Kleene iterates a_p^n and $a_{\mathcal{R}}^n$ involved in the computation of $\text{lfp } F_p$ and $\text{lfp } F_{\mathcal{R}}$ satisfy $\forall n: \alpha_o(a_p^n) = a_{\mathcal{R}}^n$, and so $\alpha_o(\text{lfp } F_p) = \text{lfp } F_{\mathcal{R}}$.

Suffix trace semantics

Similar results on the **suffix** trace semantics:

- $\mathcal{T}_s(\mathcal{F}) \stackrel{\text{def}}{=} \{ \sigma_0, \dots, \sigma_n \mid n \geq 0, \sigma_n \in \mathcal{F}, \forall i: \sigma_i \rightarrow \sigma_{i+1} \}$
(traces following τ and ending in a state in \mathcal{F})
- $\mathcal{T}_s(\mathcal{F}) = \bigcup_{n \geq 0} \tau \frown^n \mathcal{F}$
- $\mathcal{T}_s(\mathcal{F}) = \text{lfp } F_s$ where $F_s(T) \stackrel{\text{def}}{=} \mathcal{F} \cup \tau \frown T$
(F_s prepends a transition to each trace, and adds back \mathcal{F})
- $\alpha_s(\mathcal{T}_s(\mathcal{F})) = \mathcal{C}(\mathcal{F})$
where $\alpha_s(T) \stackrel{\text{def}}{=} \{ \sigma \mid \exists \sigma_0, \dots, \sigma_n \in T: \sigma = \sigma_0 \}$
- $\rho_s(\mathcal{T}_s(\mathcal{F})) = \mathcal{T}_s(\mathcal{F})$
where $\rho_s(T) \stackrel{\text{def}}{=} \{ u \mid \exists t \in \Sigma^\infty: t \cdot u \in T, u \neq \epsilon \}$
(closed by suffix)
- $\alpha_o(\mathcal{T}_s(\mathcal{F})) = \mathcal{C}(\mathcal{F})$

Suffix trace semantics: graphical illustration



$$\mathcal{F} \stackrel{\text{def}}{=} \{c\}$$

$$\tau \stackrel{\text{def}}{=} \{(a, b), (b, b), (b, c)\}$$

Iterates: $\mathcal{T}_s(\mathcal{F}) = \text{lfp } F_s$ where $F_s(T) \stackrel{\text{def}}{=} \mathcal{F} \cup \tau \cap T$.

- $F_s^0(\emptyset) = \emptyset$
- $F_s^1(\emptyset) = \mathcal{F} = \{c\}$
- $F_s^2(\emptyset) = \{c, bc\}$
- $F_s^3(\emptyset) = \{c, bc, bbc, abc\}$
- $F_s^n(\emptyset) = \{c, b^i c, ab^j c \mid i \in [1, n-1], j \in [1, n-2]\}$
- $\mathcal{T}_s(\mathcal{F}) = \bigcup_{n \geq 0} F_s^n(\emptyset) = \{c, b^i c, ab^j c \mid i \geq 1\}$

Finite partial trace semantics

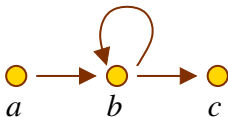
\mathcal{T} : all finite partial finite execution traces.

(not necessarily starting in \mathcal{I} or ending in \mathcal{F})

$$\begin{aligned}\mathcal{T} &\stackrel{\text{def}}{=} \{ \sigma_0, \dots, \sigma_n \mid n \geq 0, \forall i: \sigma_i \rightarrow \sigma_{i+1} \} \\ &= \bigcup_{n \geq 0} \Sigma \frown \tau \frown^n \\ &= \bigcup_{n \geq 0} \tau \frown^n \frown \Sigma\end{aligned}$$

- $\mathcal{T} = \mathcal{T}_p(\Sigma)$, hence $\mathcal{T} = \text{lfp } F_{p*}$ where $F_{p*}(T) \stackrel{\text{def}}{=} \Sigma \cup T \frown \tau$
(prefix partial traces from any initial state)
- $\mathcal{T} = \mathcal{T}_s(\Sigma)$, hence $\mathcal{T} = \text{lfp } F_{s*}$ where $F_{s*}(T) \stackrel{\text{def}}{=} \Sigma \cup \tau \frown T$
(suffix partial traces to any final state)
- $F_{p*}^n(\emptyset) = F_{s*}^n(\emptyset) = \bigcup_{i < n} \Sigma \frown \tau \frown^i = \bigcup_{i < n} \tau \frown^i \frown \Sigma = \mathcal{T} \cap \Sigma^{<n}$
- $\mathcal{T}_p(\mathcal{I}) = \mathcal{T} \cap (\mathcal{I} \cdot \Sigma^*)$ (restricted initial states)
- $\mathcal{T}_s(\mathcal{F}) = \mathcal{T} \cap (\Sigma^* \cdot \mathcal{F})$ (restricted final states)

Partial trace semantics: graphical illustration



$$\tau \stackrel{\text{def}}{=} \{(a, b), (b, b), (b, c)\}$$

Iterates: $\mathcal{T}(\Sigma) = \text{lfp } F_{p*}$ where $F_{p*}(T) \stackrel{\text{def}}{=} \Sigma \cup T \cap \tau$.

- $F_{p*}^0(\emptyset) = \emptyset$
- $F_{p*}^1(\emptyset) = \Sigma = \{a, b, c\}$
- $F_{p*}^2(\emptyset) = \{a, b, c, ab, bb, bc\}$
- $F_{p*}^3(\emptyset) = \{a, b, c, ab, bb, bc, abb, abc, bbb, bbc\}$
- $F_{p*}^n(\emptyset) = \{ab^i, ab^j c, b^i c, b^k \mid i \in [0, n-1], j \in [1, n-2], k \in [1, n]\}$
- $\mathcal{T} = \cup_{n \geq 0} F_{p*}^n(\emptyset) = \{ab^i, ab^j c, b^i c, b^j \mid i \geq 0, j > 1\}$

(using $F_{s*}(T) \stackrel{\text{def}}{=} \Sigma \cup \tau \cap T$, we get the exact same iterates)

Abstracting partial traces to prefix traces

Idea: anchor partial traces at initial states \mathcal{I} .

We have a Galois connection:

$$(\mathcal{P}(\Sigma^*), \subseteq) \xrightleftharpoons[\alpha_{\mathcal{I}}]{\gamma_{\mathcal{I}}} (\mathcal{P}(\Sigma^*), \subseteq)$$

- $\alpha_{\mathcal{I}}(T) \stackrel{\text{def}}{=} T \cap (\mathcal{I} \cdot \Sigma^*)$ (keep only traces starting in \mathcal{I})
- $\gamma_{\mathcal{I}}(T) \stackrel{\text{def}}{=} T \cup ((\Sigma \setminus \mathcal{I}) \cdot \Sigma^*)$ (add all traces not starting in \mathcal{I})

We then have: $\mathcal{T}_p(\mathcal{I}) = \alpha_{\mathcal{I}}(\mathcal{T})$.

(similarly $\mathcal{T}_s(\mathcal{F}) = \alpha_{\mathcal{F}}(\mathcal{T})$ where $\alpha_{\mathcal{F}}(T) \stackrel{\text{def}}{=} T \cap (\Sigma^* \cdot \mathcal{F})$)

(proof on next slide)

Abstracting partial traces to prefix traces (proof)

proof

$\alpha_{\mathcal{I}}$ and $\gamma_{\mathcal{I}}$ are monotonic.

$$(\alpha_{\mathcal{I}} \circ \gamma_{\mathcal{I}})(T) = (T \cup (\Sigma \setminus \mathcal{I}) \cdot \Sigma^*) \cap \mathcal{I} \cdot \Sigma^* = T \cap \mathcal{I} \cdot \Sigma^* \subseteq T.$$

$$(\gamma_{\mathcal{I}} \circ \alpha_{\mathcal{I}})(T) = (T \cap \mathcal{I} \cdot \Sigma^*) \cup (\Sigma \setminus \mathcal{I}) \cdot \Sigma^* = T \cup (\Sigma \setminus \mathcal{I}) \cdot \Sigma^* \supseteq T.$$

So, we have a Galois connection.

A direct proof of $\mathcal{T}_p(\mathcal{I}) = \alpha_{\mathcal{I}}(\mathcal{T})$ is straightforward, by definition of \mathcal{T}_p , $\alpha_{\mathcal{I}}$, and \mathcal{T} .

We can also retrieve the result by fixpoint transfer.

$$\mathcal{T} = \text{lfp } F_{p^*} \text{ where } F_{p^*}(T) \stackrel{\text{def}}{=} \Sigma \cup T \cap \mathcal{T}.$$

$$\mathcal{T}_p = \text{lfp } F_p \text{ where } F_p(T) \stackrel{\text{def}}{=} \mathcal{I} \cup T \cap \mathcal{T}.$$

$$\text{We have: } (\alpha_{\mathcal{I}} \circ F_{p^*})(T) = (\Sigma \cup T \cap \mathcal{T}) \cap (\mathcal{I} \cdot \Sigma^*) =$$

$$\mathcal{I} \cup ((T \cap \mathcal{T}) \cap (\mathcal{I} \cdot \Sigma^*)) = \mathcal{I} \cup ((T \cap (\mathcal{I} \cdot \Sigma^*)) \cap \mathcal{T}) = (F_p \circ \alpha_{\mathcal{I}})(T).$$

Maximal trace semantics

Maximal traces

Maximal traces: $\mathcal{M}_\infty \in \mathcal{P}(\Sigma^\infty)$

- sequences of states linked by the transition relation τ ,
- start in any state ($\mathcal{I} = \Sigma$),
- either finite and **stop in a blocking state** ($\mathcal{F} = \mathcal{B}$),
- or **infinite**.

(maximal traces cannot be “extended”
by adding a new transition in τ at their end)

$$\mathcal{M}_\infty \stackrel{\text{def}}{=} \left\{ \sigma_0, \dots, \sigma_n \in \Sigma^* \mid \sigma_n \in \mathcal{B}, \forall i < n: \sigma_i \rightarrow \sigma_{i+1} \right\} \cup \left\{ \sigma_0, \dots, \sigma_n, \dots \in \Sigma^\omega \mid \forall i < \omega: \sigma_i \rightarrow \sigma_{i+1} \right\}$$

(can be anchored at \mathcal{I} and \mathcal{F} as: $\mathcal{M}_\infty \cap (\mathcal{I} \cdot \Sigma^\infty) \cap ((\Sigma^* \cdot \mathcal{F}) \cup \Sigma^\omega)$)

Partitioned fixpoint formulation of maximal traces

Goal: we look for a fixpoint characterization of \mathcal{M}_∞ .

We consider separately finite and infinite maximal traces.

- Finite traces:

From the suffix partial trace semantics, recall:

$$\mathcal{M}_\infty \cap \Sigma^* = \mathcal{T}_s(\mathcal{B}) = \text{lfp } F_s$$

where $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \frown T$ in $(\mathcal{P}(\Sigma^*), \subseteq)$.

- Infinite traces:

Additionally, we will prove: $\mathcal{M}_\infty \cap \Sigma^\omega = \text{gfp } G_s$

where $G_s(T) \stackrel{\text{def}}{=} \tau \frown T$ in $(\mathcal{P}(\Sigma^\omega), \subseteq)$.

(proof on next slide)

Partitioned fixpoint formulation of maximal traces (proof)

proof: of $\mathcal{M}_\infty \cap \Sigma^\omega = \text{gfp } G_s$ where $G_s(T) \stackrel{\text{def}}{=} \tau \smallfrown T$ in $(\mathcal{P}(\Sigma^\omega), \subseteq)$.

G_s is continuous in $(\mathcal{P}(\Sigma^\omega), \supseteq)$: $G_s(\cap_{i \in I} T_i) = \cap_{i \in I} G_s(T_i)$.

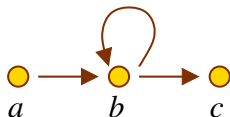
By Kleene's theorem in the dual: $\text{gfp } G_s = \cap_{n \in \mathbb{N}} G_s^n(\Sigma^\omega)$.

We prove by recurrence on n that $\forall n: G_s^n(\Sigma^\omega) = \tau \smallfrown^n \Sigma^\omega$:

- $G_s^0(\Sigma^\omega) = \Sigma^\omega = \tau \smallfrown^0 \Sigma^\omega$,
- $G_s^{n+1}(\Sigma^\omega) = \tau \smallfrown G_s^n(\Sigma^\omega) = \tau \smallfrown (\tau \smallfrown^n \Sigma^\omega) = \tau \smallfrown^{n+1} \Sigma^\omega$.

$$\begin{aligned}
 \text{gfp } G_s &= \cap_{n \in \mathbb{N}} \tau \smallfrown^n \Sigma^\omega \\
 &= \{ \sigma_0, \dots \in \Sigma^\omega \mid \forall n \geq 0: \sigma_0, \dots, \sigma_{n-1} \in \tau \smallfrown^n \} \\
 &= \{ \sigma_0, \dots \in \Sigma^\omega \mid \forall n \geq 0: \forall i < n: \sigma_i \rightarrow \sigma_{i+1} \} \\
 &= \mathcal{M}_\infty \cap \Sigma^\omega
 \end{aligned}$$

Infinite trace semantics: graphical illustration



$$\mathcal{B} \stackrel{\text{def}}{=} \{c\}$$

$$\tau \stackrel{\text{def}}{=} \{(a, b), (b, b), (b, c)\}$$

Iterates: $\mathcal{M}_\infty \cap \Sigma^\omega = \text{gfp } G_s$ where $G_s(T) \stackrel{\text{def}}{=} \tau \cap T$.

- $G_s^0(\Sigma^\omega) = \Sigma^\omega$
- $G_s^1(\Sigma^\omega) = ab\Sigma^\omega \cup bb\Sigma^\omega \cup bc\Sigma^\omega$
- $G_s^2(\Sigma^\omega) = abb\Sigma^\omega \cup bbb\Sigma^\omega \cup abc\Sigma^\omega \cup bbc\Sigma^\omega$
- $G_s^3(\Sigma^\omega) = abbb\Sigma^\omega \cup bbbb\Sigma^\omega \cup abbc\Sigma^\omega \cup bbbc\Sigma^\omega$
- $G_s^n(\Sigma^\omega) = \{ab^n t, b^{n+1} t, ab^{n-1} ct, b^n ct \mid t \in \Sigma^\omega\}$
- $\mathcal{M}_\infty \cap \Sigma^\omega = \bigcap_{n \geq 0} G_s^n(\Sigma^\omega) = \{ab^\omega, b^\omega\}$

Least fixpoint formulation of maximal traces

Idea: To get a fixpoint formulation for whole \mathcal{M}_∞ ,
merge finite and infinite maximal trace fixpoint forms.

Fixpoint fusion

$\mathcal{M}_\infty \cap \Sigma^*$ is best defined on $(\Sigma^*, \subseteq, \cup, \cap, \emptyset, \Sigma^*)$.

$\mathcal{M}_\infty \cap \Sigma^\omega$ is best defined on $(\Sigma^\omega, \supseteq, \cap, \cup, \Sigma^\omega, \emptyset)$.

We mix them into a **new** complete lattice $(\Sigma^\infty, \sqsubseteq, \sqcup, \sqcap, \perp, \top)$:

- $A \sqsubseteq B \stackrel{\text{def}}{\iff} (A \cap \Sigma^*) \subseteq (B \cap \Sigma^*) \wedge (A \cap \Sigma^\omega) \supseteq (B \cap \Sigma^\omega)$
- $A \sqcup B \stackrel{\text{def}}{=} ((A \cap \Sigma^*) \cup (B \cap \Sigma^*)) \cup ((A \cap \Sigma^\omega) \cap (B \cap \Sigma^\omega))$
- $A \sqcap B \stackrel{\text{def}}{=} ((A \cap \Sigma^*) \cap (B \cap \Sigma^*)) \cup ((A \cap \Sigma^\omega) \cup (B \cap \Sigma^\omega))$
- $\perp \stackrel{\text{def}}{=} \Sigma^\omega$
- $\top \stackrel{\text{def}}{=} \Sigma^*$

In this lattice, $\mathcal{M}_\infty = \text{lfp } F_s$ where $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \frown T$.

(proof on next slides)

Fixpoint fusion theorem

Theorem: fixpoint fusion

If $X_1 = \text{lfp } F_1$ in $(\mathcal{P}(\mathcal{D}_1), \sqsubseteq_1)$ and $X_2 = \text{lfp } F_2$ in $(\mathcal{P}(\mathcal{D}_2), \sqsubseteq_2)$

and $\mathcal{D}_1 \cap \mathcal{D}_2 = \emptyset$,

then $X_1 \cup X_2 = \text{lfp } F$ in $(\mathcal{P}(\mathcal{D}_1 \cup \mathcal{D}_2), \sqsubseteq)$ where:

- $F(X) \stackrel{\text{def}}{=} F_1(X \cap \mathcal{D}_1) \cup F_2(X \cap \mathcal{D}_2),$
- $A \sqsubseteq B \iff (A \cap \mathcal{D}_1) \sqsubseteq_1 (B \cap \mathcal{D}_1) \wedge (A \cap \mathcal{D}_2) \sqsubseteq_2 (B \cap \mathcal{D}_2).$

proof:

We have:

$F(X_1 \cup X_2) = F_1((X_1 \cup X_2) \cap \mathcal{D}_1) \cup F_2((X_1 \cup X_2) \cap \mathcal{D}_2) = F_1(X_1) \cup F_2(X_2) = X_1 \cup X_2,$
hence $X_1 \cup X_2$ is a fixpoint of F .

Let Y be a fixpoint. Then $Y = F(Y) = F_1(Y \cap \mathcal{D}_1) \cup F_2(Y \cap \mathcal{D}_2)$, hence,
 $Y \cap \mathcal{D}_1 = F_1(Y \cap \mathcal{D}_1)$ and $Y \cap \mathcal{D}_1$ is a fixpoint of F_1 . Thus, $X_1 \sqsubseteq_1 Y \cap \mathcal{D}_1$. Likewise,
 $X_2 \sqsubseteq_2 Y \cap \mathcal{D}_2$. We deduce that $X = X_1 \cup X_2 \sqsubseteq (Y \cap \mathcal{D}_1) \cup (Y \cap \mathcal{D}_2) = Y$, and so, X
is F 's least fixpoint.

note: we also have $\text{gfp } F = \text{gfp } F_1 \cup \text{gfp } F_2$.

Least fixpoint formulation of maximal traces (proof)

proof: of $\mathcal{M}_\infty = \text{lfp } F_s$ where $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \cap T$.

We have:

- $\mathcal{M}_\infty \cap \Sigma^* = \text{lfp } F_s$ in $(\mathcal{P}(\Sigma^*), \subseteq)$,
- $\mathcal{M}_\infty \cap \Sigma^\omega = \text{lfp } G_s$ in $(\mathcal{P}(\Sigma^\omega), \supseteq)$ where $G_s(T) \stackrel{\text{def}}{=} \tau \cap T$,
- in $\mathcal{P}(\Sigma^\infty)$, we have

$$F_s(A) = (F_s(A) \cap \Sigma^*) \cup (F_s(A) \cap \Sigma^\omega) = F_s(A \cap \Sigma^*) \cup G_s(A \cap \Sigma^\omega).$$

So, by fixpoint fusion in $(\mathcal{P}(\Sigma^\infty), \sqsubseteq)$, we have:

$$\mathcal{M}_\infty = (\mathcal{M}_\infty \cap \Sigma^*) \cup (\mathcal{M}_\infty \cap \Sigma^\omega) = \text{lfp } F_s.$$

Greatest fixpoint formulation of finite maximal traces

Actually, a fixpoint formulation in $(\Sigma^\infty, \subseteq)$ also exists.

Alternate fixpoint for **finite** maximal traces:

We saw that $\mathcal{M}_\infty \cap \Sigma^* = \text{lfp } F_s$
 where $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \cap T$ in $(\mathcal{P}(\Sigma^*), \subseteq)$.

Additionally, we have $\mathcal{M}_\infty \cap \Sigma^* = \text{gfp } F_s$ in $(\mathcal{P}(\Sigma^*), \subseteq)$.

(F_s has a unique fixpoint in $(\mathcal{P}(\Sigma^*), \subseteq)$.)

(proof on next slide)

Greatest fixpoint formulation of finite maximal traces

proof: of $\mathcal{M}_\infty \cap \Sigma^* = \text{gfp } F_s$ where $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \frown T$.

F_s is continuous in the dual $(\mathcal{P}(\Sigma^*), \supseteq)$: $F_s(\cap_{i \in I} A_i) = \cap_{i \in I} F_s(A_i)$.

By Kleene's theorem in the dual $(\mathcal{P}(\Sigma^*), \supseteq)$, we get: $\text{gfp } F_s = \cap_{n \in \mathbb{N}} F_s^n(\Sigma^*)$.

We prove by recurrence on n that $\forall n: F_s^n(\Sigma^*) = (\cup_{i < n} \tau \frown^i \frown \mathcal{B}) \cup (\tau \frown^n \frown \Sigma^*)$: i.e., $F_s^n(\Sigma^*)$ are the maximal finite traces of length at most $n - 1$, and the partial traces of length exactly n followed by any sequence of states:

- $F_s^0(\Sigma^*) = \Sigma^* = \tau \frown^0 \frown \Sigma^*$
- $F_s(F_s^n(\Sigma^*)) = \mathcal{B} \cup (\tau \frown F_s^n(\Sigma^*))$

$$= \mathcal{B} \cup \tau \frown ((\cup_{i < n} \tau \frown^i \frown \mathcal{B}) \cup (\tau \frown^n \frown \Sigma^*))$$

$$= \mathcal{B} \cup (\cup_{i < n} \tau \frown \tau \frown^i \frown \mathcal{B}) \cup (\tau \frown \tau \frown^n \frown \Sigma^*)$$

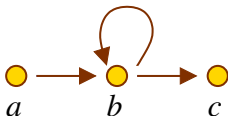
$$= \mathcal{B} \cup (\cup_{1 \leq i \leq n+1} \tau \frown^i \frown \mathcal{B}) \cup (\tau \frown^{n+1} \frown \Sigma^*)$$

$$= (\cup_{i < n+1} \tau \frown^i \frown \mathcal{B}) \cup (\tau \frown^{n+1} \frown \Sigma^*)$$

We get:

$$\cap_{n \in \mathbb{N}} F_s^n(\Sigma^*) = \cap_{n \in \mathbb{N}} ((\cup_{i < n} \tau \frown^i \frown \mathcal{B}) \cup (\tau \frown^n \frown \Sigma^*)) = \cup_{n \in \mathbb{N}} \tau \frown^n \frown \mathcal{B} = \mathcal{M}_\infty \cap \Sigma^*.$$

Greatest fixpoint of finite traces: graphical illustration



$$\mathcal{B} \stackrel{\text{def}}{=} \{c\}$$

$$\tau \stackrel{\text{def}}{=} \{(a, b), (b, b), (b, c)\}$$

Iterates: $\mathcal{M}_\infty \cap \Sigma^* = \text{gfp } F_s$ where $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \cap T$.

- $F_s^0(\Sigma^*) = \Sigma^*$
- $F_s^1(\Sigma^*) = \{c\} \cup ab\Sigma^* \cup bb\Sigma^* \cup bc\Sigma^*$
- $F_s^2(\Sigma^*) = \{bc, c\} \cup abb\Sigma^* \cup bbb\Sigma^* \cup abc\Sigma^* \cup bbc\Sigma^*$
- $F_s^3(\Sigma^*) = \{abc, bbc, bc, c\} \cup abbb\Sigma^* \cup bbbb\Sigma^* \cup abbc\Sigma^* \cup bbbc\Sigma^*$
- $F_s^n(\Sigma^*) = \{ab^i c, b^j c \mid i \in [1, n-2], j \in [0, n-1]\} \cup \{ab^n t, b^{n+1} t, ab^{n-1} ct, b^n ct \mid t \in \Sigma^*\}$
- $\mathcal{M}_\infty \cap \Sigma^* = \bigcap_{n \geq 0} F_s^n(\Sigma^*) = \{ab^i c, b^j c \mid i \geq 1, j \geq 0\}$

Greatest fixpoint formulation of maximal traces

From:

- $\mathcal{M}_\infty \cap \Sigma^* = \text{gfp } F_s$ in $(\mathcal{P}(\Sigma^*), \subseteq)$ where $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \cap T$
- $\mathcal{M}_\infty \cap \Sigma^\omega = \text{gfp } G_s$ in $(\mathcal{P}(\Sigma^\omega), \subseteq)$ where $G_s(T) \stackrel{\text{def}}{=} \tau \cap T$

we deduce: $\mathcal{M}_\infty = \text{gfp } F_s$ in $(\mathcal{P}(\Sigma^\infty), \subseteq)$.

proof: similar to $\mathcal{M}_\infty = \text{lfp } F_s$ in $(\mathcal{P}(\Sigma^\infty), \sqsubseteq)$, by fixpoint fusion.

Partial trace semantics

Finite and infinite partial trace semantics

Idea: complete partial traces \mathcal{T} with infinite traces.

\mathcal{T}_∞ : all finite and infinite sequences of states
linked by the transition relation τ :

$$\mathcal{T}_\infty \stackrel{\text{def}}{=} \left\{ \sigma_0, \dots, \sigma_n \in \Sigma^* \mid \forall i < n: \sigma_i \rightarrow \sigma_{i+1} \right\} \cup \left\{ \sigma_0, \dots, \sigma_n, \dots \in \Sigma^\omega \mid \forall i < \omega: \sigma_i \rightarrow \sigma_{i+1} \right\}$$

(partial finite traces do not necessarily end in a blocking state)

Fixpoint form similar to \mathcal{M}_∞ :

- $\mathcal{T}_\infty = \text{lfp } F_{s*}$ in $(\mathcal{P}(\Sigma^\infty), \sqsubseteq)$ where $F_{s*}(T) \stackrel{\text{def}}{=} \Sigma \cup \tau \cap T$,
- $\mathcal{T}_\infty = \text{gfp } F_{s*}$ in $(\mathcal{P}(\Sigma^\infty), \subseteq)$.

proof: similar to the proofs of $\mathcal{M}_\infty = \text{gfp } F_s$ and $\mathcal{M}_\infty = \text{lfp } F_s$.

Finite trace abstraction

Finite partial traces \mathcal{T} are an **abstraction** of all partial traces \mathcal{T}_∞ .

We have a **Galois embedding**:

$$(\mathcal{P}(\Sigma^\infty), \sqsubseteq) \xleftrightarrow[\alpha_*]{\gamma_*} (\mathcal{P}(\Sigma^*), \subseteq)$$

- \sqsubseteq is the fused ordering on $\Sigma^* \cup \Sigma^\omega$:

$$A \sqsubseteq B \stackrel{\text{def}}{\iff} (A \cap \Sigma^*) \subseteq (B \cap \Sigma^*) \wedge (A \cap \Sigma^\omega) \supseteq (B \cap \Sigma^\omega)$$

- $\alpha_*(T) \stackrel{\text{def}}{=} T \cap \Sigma^*$

(remove infinite traces)

- $\gamma_*(T) \stackrel{\text{def}}{=} T$

(embedding)

- $\mathcal{T} = \alpha_*(\mathcal{T}_\infty)$

(proof on next slide)

Finite trace abstraction (proof)

proof:

We have Galois embedding because:

- α_* and γ_* are monotonic,
- given $T \subseteq \Sigma^*$, we have $(\alpha_* \circ \gamma_*)(T) = T \cap \Sigma^* = T$,
- $(\gamma_* \circ \alpha_*)(T) = T \cap \Sigma^* \sqsubseteq T$, as we only remove infinite traces.

Recall that $\mathcal{T}_\infty = \text{lfp } F_{s*}$ in $(\mathcal{P}(\Sigma^\infty), \sqsubseteq)$ and $\mathcal{T} = \text{lfp } F_{s*}$ in $(\mathcal{P}(\Sigma^*), \subseteq)$, where $F_{s*}(T) \stackrel{\text{def}}{=} \Sigma \cup T \cap \tau$.

As $\alpha_* \circ F_{s*} = F_{s*} \circ \alpha_*$ and $\alpha_*(\emptyset) = \emptyset$, we can apply the fixpoint transfer theorem to get $\alpha_*(\mathcal{T}_\infty) = \mathcal{T}$.

Finite trace abstraction (proof)

alternate proof:

It is also possible to use the characterizations $\mathcal{T}_\infty = \text{gfp } F_{s*}$ in $(\mathcal{P}(\Sigma^\infty), \subseteq)$ and $\mathcal{T} = \text{gfp } F_{s*}$ in $(\mathcal{P}(\Sigma^*), \subseteq)$, and use a fixpoint transfer theorem for greatest fixpoints. Similarly to the fixpoint transfer for least fixpoints, this theorem uses the constructive version of Tarski's theorem, but in the dual: \mathcal{T}_∞ is the limit of transfinite iterations $a_0 = \Sigma^\infty$, $a_{n+1} = F_{s*}(a_n)$, and $a_n = \bigcap \{ a_m \mid m < n \}$ for transfinite ordinals, while \mathcal{T} is the limit of a similar iteration from $a'_0 = \Sigma^*$. We conclude by noting that $a'_0 = \alpha_*(a_0)$, $\alpha_* \circ F_{s*} = F_{s*} \circ \alpha_*$, and α_* is co-continuous: $\alpha_*(\bigcap_{i \in I} T_i) = \bigcap_{i \in I} \alpha_*(T_i)$.

Note that, while the adjoint of α_* for \sqsubseteq was $\gamma_*(T) \stackrel{\text{def}}{=} T$, the adjoint for \subseteq is $\gamma'_*(T) \stackrel{\text{def}}{=} T \cup \Sigma^\omega$.

Prefix abstraction

Idea: complete **maximal** traces by adding (non-empty) **prefixes**.

We have a Galois connection:

$$(\mathcal{P}(\Sigma^\infty \setminus \{\epsilon\}), \subseteq) \xrightleftharpoons[\alpha_\preceq]{\gamma_\preceq} (\mathcal{P}(\Sigma^\infty \setminus \{\epsilon\}), \subseteq)$$

- $\alpha_\preceq(T) \stackrel{\text{def}}{=} \{t \in \Sigma^\infty \setminus \{\epsilon\} \mid \exists u \in T: t \preceq u\}$

(set of all non-empty prefixes of traces in T)

-

$$\gamma_\preceq(T) \stackrel{\text{def}}{=} \{t \in \Sigma^\infty \setminus \{\epsilon\} \mid \forall u \in \Sigma^\infty \setminus \{\epsilon\}: u \preceq t \implies u \in T\}$$

(traces with non-empty prefixes in T)

proof:

α_\preceq and γ_\preceq are monotonic.

$$(\alpha_\preceq \circ \gamma_\preceq)(T) = \{t \in T \mid \rho_P(t) \subseteq T\} \subseteq T \quad (\text{prefix-closed trace sets}).$$

$$(\gamma_\preceq \circ \alpha_\preceq)(T) = \rho_P(T) \supseteq T.$$

Abstraction from maximal traces to partial traces

Finite and infinite **partial traces** \mathcal{T}_∞ are an **abstraction** of **maximal traces** \mathcal{M}_∞ : $\mathcal{T}_\infty = \alpha_{\preceq}(\mathcal{M}_\infty)$.

proof:

Firstly, \mathcal{T}_∞ and $\alpha_{\preceq}(\mathcal{M}_\infty)$ coincide on infinite traces. Indeed, $\mathcal{T}_\infty \cap \Sigma^\omega = \mathcal{M}_\infty \cap \Sigma^\omega$ and α_{\preceq} does not add infinite traces, so: $\mathcal{T}_\infty \cap \Sigma^\omega = \alpha_{\preceq}(\mathcal{M}_\infty) \cap \Sigma^\omega$.

We now prove that they also coincide on finite traces. Assume

$\sigma_0, \dots, \sigma_n \in \alpha_{\preceq}(\mathcal{M}_\infty)$, then $\forall i < n: \sigma_i \rightarrow \sigma_{i+1}$, so, $\sigma_0, \dots, \sigma_n \in \mathcal{T}_\infty$.

Assume $\sigma_0, \dots, \sigma_n \in \mathcal{T}_\infty$, then it can be completed into a maximal trace, either finite or infinite, and so, $\sigma_0, \dots, \sigma_n \in \alpha_{\preceq}(\mathcal{M}_\infty)$.

Note: no fixpoint transfer applies here.

Finite prefix abstraction

We can abstract directly from **maximal traces** \mathcal{M}_∞ to **finite partial traces** \mathcal{T} .

Consider the following Galois connection:

$$(\mathcal{P}(\Sigma^\infty \setminus \{\epsilon\}), \subseteq) \xrightleftharpoons[\alpha_{*\preceq}]{\gamma_{*\preceq}} (\mathcal{P}(\Sigma^* \setminus \{\epsilon\}), \subseteq)$$

- $\alpha_{*\preceq}(T) \stackrel{\text{def}}{=} \{t \in \Sigma^* \setminus \{\epsilon\} \mid \exists u \in T : t \preceq u\}$
(set of all non-empty prefixes of traces T)
- $\gamma_{*\preceq}(T) \stackrel{\text{def}}{=} \{t \in \Sigma^\infty \setminus \{\epsilon\} \mid \forall u \in \Sigma^* \setminus \{\epsilon\} : u \preceq t \implies u \in T\}$
(traces with non-empty prefixes in T)

We have $\mathcal{T} = \alpha_{*\preceq}(\mathcal{M}_\infty)$.

(proof on next slide)

Finite prefix abstraction (proof)

proof:

$\alpha_{*\underline{\preceq}}$ and $\gamma_{*\underline{\preceq}}$ are monotonic.

$(\alpha_{*\underline{\preceq}} \circ \gamma_{*\underline{\preceq}})(T) = \{t \in T \mid \rho_p(t) \subseteq T\} \subseteq T$ (prefix-closed trace sets).

$(\gamma_{*\underline{\preceq}} \circ \alpha_{*\underline{\preceq}})(T) = \rho_p(T) \cup \{t \in \Sigma^\omega \mid \forall u \in \Sigma^*: u \preceq t \implies u \in \rho_p(T)\} \supseteq T$.

As $\alpha_{*\underline{\preceq}} = \alpha_* \circ \alpha_{\underline{\preceq}}$,

we have: $\alpha_{*\underline{\preceq}}(\mathcal{M}_\infty) = \alpha_*(\alpha_{\underline{\preceq}}(\mathcal{M}_\infty)) = \alpha_*(\mathcal{T}_\infty) = \mathcal{T}$.

Remarks:

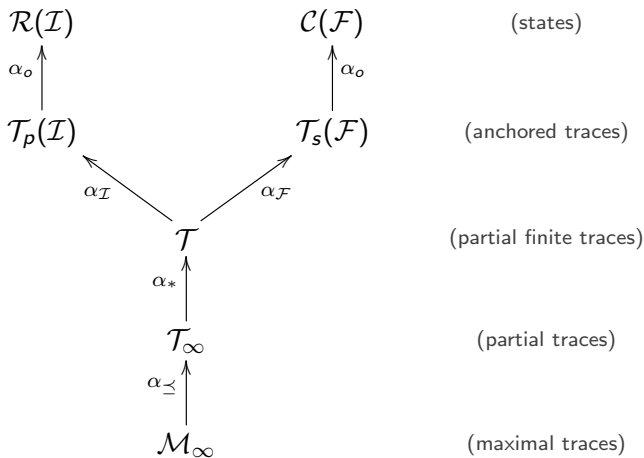
- $\gamma_{*\underline{\preceq}} \circ \alpha_{*\underline{\preceq}} \neq id$
it closes trace sets by **limits of finite traces**.

- $\gamma_{*\underline{\preceq}} \neq \gamma_{\underline{\preceq}} \circ \gamma_*$

this is because $\gamma_*(T) \stackrel{\text{def}}{=} T$ is the adjoint of α_* in $(\mathcal{P}(\Sigma^\infty), \sqsubseteq)$, while we need to compose $\alpha_{\underline{\preceq}}$ with the adjoint of α_* in $(\mathcal{P}(\Sigma^\infty), \subseteq)$, which is

$\gamma'_*(T) \stackrel{\text{def}}{=} T \cup \Sigma^\omega$.

(Partial) hierarchy of semantics



Relational semantics

Big-step semantics

Finite big-step semantics

Pairs of states linked by a sequence of transitions in τ .

$$\mathcal{BS} \stackrel{\text{def}}{=} \{ (\sigma_0, \sigma_n) \in \Sigma \times \Sigma \mid n \geq 0, \exists \sigma_1, \dots, \sigma_{n-1} : \forall i < n : \sigma_i \rightarrow \sigma_{i+1} \}$$

(symmetric and transitive closure of τ)

Fixpoint form:

$$\mathcal{BS} = \text{lfp } F_B$$

$$\text{where } F_B(R) \stackrel{\text{def}}{=} id \cup \{ (\sigma, \sigma'') \mid \exists \sigma' : (\sigma, \sigma') \in R, \sigma' \rightarrow \sigma'' \}.$$

Relational abstraction

Relational abstraction: allows skipping intermediate steps.

We have a Galois embedding:

$$(\mathcal{P}(\Sigma^*), \subseteq) \overset{\gamma_{io}}{\underset{\alpha_{io}}{\rightleftarrows}} (\mathcal{P}(\Sigma \times \Sigma), \subseteq)$$

- $\alpha_{io}(T) \stackrel{\text{def}}{=} \{ (\sigma, \sigma') \mid \exists \sigma_0, \dots, \sigma_n \in T : \sigma = \sigma_0, \sigma' = \sigma_n \}$
(first and last state of a trace in T)
- $\gamma_{io}(R) \stackrel{\text{def}}{=} \{ \sigma_0, \dots, \sigma_n \in \Sigma^* \mid \exists (\sigma, \sigma') \in R : \sigma = \sigma_0, \sigma' = \sigma_n \}$
(traces respecting the first and last states from R)

proof sketch:

γ_{io} and α_{io} are monotonic.

$$(\gamma_{io} \circ \alpha_{io})(T) = \{ \sigma_0, \dots, \sigma_n \mid \exists \sigma'_0, \dots, \sigma'_m \in T : \sigma_0 = \sigma'_0, \sigma_n = \sigma'_m \}.$$

$$(\alpha_{io} \circ \gamma_{io})(R) = R.$$

Finite big-step semantics as an abstraction

The finite big-step semantics is an **abstraction** of the finite trace semantics: $\mathcal{BS} = \alpha_{io}(\mathcal{T})$.

proof sketch: by fixpoint transfer.

We have $\mathcal{T} = \text{lfp } F_{p*}$ where $F_{p*}(T) \stackrel{\text{def}}{=} \Sigma \cup T \cap \tau$.

Moreover, $F_B(R) \stackrel{\text{def}}{=} id \cup \{ (\sigma, \sigma'') \mid \exists \sigma' : (\sigma, \sigma') \in R, \sigma' \rightarrow \sigma'' \}$.

Then, $\alpha_{io} \circ F_{p*} = F_B \circ \alpha_{io}$ because $\alpha_{io}(\Sigma) = id$ and $\alpha_{io}(T \cap \tau) = \{ (\sigma, \sigma'') \mid \exists \sigma' : (\sigma, \sigma') \in \alpha_{io}(T) \wedge \sigma' \rightarrow \sigma'' \}$.

By fixpoint transfer: $\alpha_{io}(\mathcal{T}) = \text{lfp } F_B$.

We have a similar result using $F_{s*}(T) \stackrel{\text{def}}{=} \Sigma \cup \tau \cap T$ and

$F'_B(R) \stackrel{\text{def}}{=} id \cup \{ (\sigma, \sigma'') \mid \exists \sigma' : (\sigma', \sigma'') \in R \wedge \sigma \rightarrow \sigma' \}$.

Finite big-step semantics (example)

program

```
 $i \leftarrow [0, +\infty];$   
while  $i > 0$  do  
   $i \leftarrow i - [0, 1];$   
done
```

Finite big-step semantics \mathcal{BS} : $\{ (\rho, \rho') \mid 0 \leq \rho'(i) \leq \rho(i) \}$.

Denotational semantics

Denotational semantics (relation form)

In the **denotational semantics**, we forget all the intermediate steps and only **keep the input / output relation**:

- $(\sigma, \sigma') \in \Sigma \times \mathcal{B}$: **finite** execution starting in σ , stopping in σ' ,
- (σ, \spadesuit) : **non-terminating** execution starting in σ .

Construction by abstraction: of the maximal trace semantics \mathcal{M}_∞ .

$$(\mathcal{P}(\Sigma^\infty), \subseteq) \overset{\gamma_d}{\underset{\alpha_d}{\rightleftarrows}} (\mathcal{P}(\Sigma \times (\Sigma \cup \{\spadesuit\})), \subseteq)$$

- $\alpha_d(T) \stackrel{\text{def}}{=} \alpha_{io}(T \cap \Sigma^*) \cup \{(\sigma, \spadesuit) \mid \exists t \in \Sigma^\omega : \sigma \cdot t \in T\}$
- $\gamma_d(R) \stackrel{\text{def}}{=} \gamma_{io}(R \cap (\Sigma \times \Sigma)) \cup \{\sigma \cdot t \mid (\sigma, \spadesuit) \in R, t \in \Sigma^\omega\}$
(extension of $(\alpha_{io}, \gamma_{io})$ to infinite traces)

The denotational semantics is $\mathcal{DS} \stackrel{\text{def}}{=} \alpha_d(\mathcal{M}_\infty)$.

Denotational fixpoint semantics

Idea: as \mathcal{M}_∞ , separate terminating and non-terminating behaviors, and use a fixpoint fusion theorem.

We have: $\mathcal{DS} = \text{lfp } F_d$

in $(\mathcal{P}(\Sigma \times (\Sigma \cup \{\spadesuit\})), \sqsubseteq^*, \sqcup^*, \sqcap^*, \perp^*, \top^*)$, where

- $\perp^* \stackrel{\text{def}}{=} \{(\sigma, \spadesuit) \mid \sigma \in \Sigma\}$
- $\top^* \stackrel{\text{def}}{=} \{(\sigma, \sigma') \mid \sigma, \sigma' \in \Sigma\}$
- $A \sqsubseteq^* B \iff ((A \cap \top^*) \subseteq (B \cap \top^*)) \wedge ((A \cap \perp^*) \supseteq (B \cap \perp^*))$
- $A \sqcup^* B \stackrel{\text{def}}{=} ((A \cap \top^*) \cup (B \cap \top^*)) \cup ((A \cap \perp^*) \cap (B \cap \perp^*))$
- $A \sqcap^* B \stackrel{\text{def}}{=} ((A \cap \top^*) \cap (B \cap \top^*)) \cup ((A \cap \perp^*) \cup (B \cap \perp^*))$
- $F_d(R) \stackrel{\text{def}}{=} \{(\sigma, \sigma) \mid \sigma \in \mathcal{B}\} \cup \{(\sigma, \sigma'') \mid \exists \sigma': \sigma \rightarrow \sigma' \wedge (\sigma', \sigma'') \in R\}$

Denotational fixpoint semantics (proof)

proof:

We cannot use directly a fixpoint transfer on $\mathcal{M}_\infty = \text{lfp } F_s$ in $(\mathcal{P}(\Sigma^\infty), \sqsubseteq)$ because our Galois connection (α_d, γ_d) uses the \subseteq order, not \sqsubseteq .

Instead, we use fixpoint transfer separately on finite and infinite executions, and then apply fixpoint fusion.

Recall that $\mathcal{M}_\infty \cap \Sigma^* = \text{lfp } F_s$ in $(\mathcal{P}(\Sigma^*), \subseteq)$ where $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \cap T$ and $\mathcal{M}_\infty \cap \Sigma^\omega = \text{gfp } G_s$ in $(\mathcal{P}(\Sigma^\omega), \subseteq)$ where $G_s(T) \stackrel{\text{def}}{=} \cup \tau \cap T$.

For finite execution, we have $\alpha_d \circ F_s = F_d \circ \alpha_d$ in $\mathcal{P}(\Sigma^*) \rightarrow \mathcal{P}(\Sigma \times \Sigma)$.

We can apply directly fixpoint transfer and get that: $\mathcal{DS} \cap (\Sigma \times \Sigma) = \text{lfp } F_d$.

Denotational fixpoint semantics (proof cont.)

proof sketch: for infinite executions

We have $\alpha_d \circ G_s = G_d \circ \alpha_d$ in $\mathcal{P}(\Sigma^\omega) \rightarrow \mathcal{P}(\Sigma \times \{\spadesuit\})$, where

$$G_d(R) \stackrel{\text{def}}{=} \{(\sigma, \sigma'') \mid \exists \sigma' : \sigma \rightarrow \sigma' \wedge (\sigma', \sigma'') \in R\}.$$

The fixpoint theorem for gfp we used in the alternate proof of $\mathcal{T} = \alpha_*(\mathcal{T}_\infty)$ does not apply here because α_d is not co-continuous: $\alpha_d(\bigcap_{i \in I} S_i) = \bigcap_{i \in I} \alpha_d(S_i)$ does not hold; consider for example: $I = \mathbb{N}$ and $S_i = \{a^n b^\omega \mid n > i\}$: $\bigcap_{i \in \mathbb{N}} S_i = \emptyset$, but

$$\forall i : \alpha_d(S_i) = \{(a, \spadesuit)\}.$$

We use instead a fixpoint transfer based on Tarski's theorem.

We have $\text{gfp } G_s = \bigcup \{X \mid X \subseteq G_s(X)\}$.

Thus, $\alpha_d(\text{gfp } G_s) = \alpha_d(\bigcup \{X \mid X \subseteq G_s(X)\}) = \bigcup \{\alpha_d(X) \mid X \subseteq G_s(X)\}$ as α_d is a complete \cup morphism. The proof is finished by noting that the commutation

$\alpha_d \circ G_s = G_d \circ \alpha_d$ and the Galois embedding (α_d, γ_d) imply that

$$\{\alpha_d(X) \mid X \subseteq G_s(X)\} = \{\alpha_d(X) \mid \alpha_d(X) \subseteq G_d(\alpha_d(X))\} = \{Y \mid Y \subseteq G_d(Y)\}.$$

(the complete proof can be found in [\[Cous02\]](#))

Denotational semantics (example)

program

```
 $i \leftarrow [0, +\infty];$   
while  $i > 0$  do  
   $i \leftarrow i - [0, 1];$   
done
```

Denotational semantics \mathcal{DS} :

$$\{(\rho, \rho') \mid \rho(i) \geq 0 \wedge \rho'(i) = 0\} \cup \{(\rho, \spadesuit) \mid \rho(i) \geq 0\}.$$

(quite different from the big-step semantics)

Denotational semantics (functional form)

Note: denotational semantics are often presented as functions, not relations

This is possible using the following Galois **isomorphism**:

$$(\mathcal{P}(\Sigma \times (\Sigma \cup \{\spadesuit\})), \sqsubseteq^*) \overset{\gamma_{df}}{\underset{\alpha_{df}}{\rightleftarrows}} (\Sigma \rightarrow \mathcal{P}(\Sigma \cup \{\spadesuit\}), \dot{\sqsubseteq}^*)$$

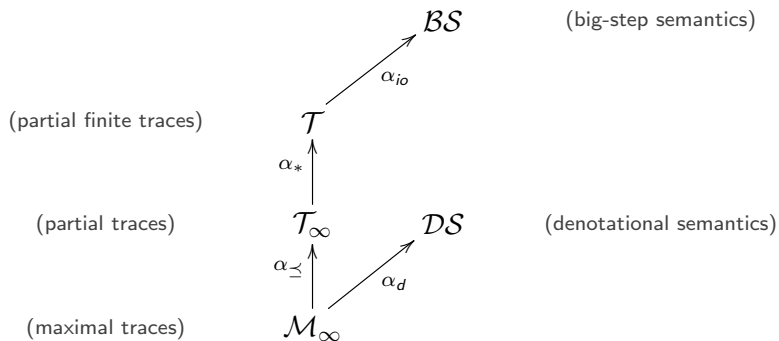
- $\alpha_{df}(R) \stackrel{\text{def}}{=} \lambda\sigma. \{ \sigma' \mid (\sigma, \sigma') \in R \}$
- $\gamma_{df}(f) \stackrel{\text{def}}{=} \{ (\sigma, \sigma') \mid \sigma' \in f(\sigma) \}$
- $f \dot{\sqsubseteq}^* g \iff \forall \sigma: (f(\sigma) \cap \Sigma \subseteq g(\sigma) \cap \Sigma) \wedge (\spadesuit \in g(\sigma) \implies \spadesuit \in f(\sigma))$

We get that: $\alpha_{df}(\mathcal{DS}) = \text{lfp } F'_d$ where

$$F'_d(f) \stackrel{\text{def}}{=} (\alpha_{df} \circ F_d \circ \gamma_{df})(f) = (\lambda\sigma. \{ \sigma \mid \sigma \in \mathcal{B} \}) \dot{\cup} (f \circ \text{post}_\tau).$$

(proof by fixpoint transfer, as $F'_d \circ \alpha_{df} = F_d \circ \alpha_{df}$)

Another part of the hierarchy of semantics



See [Cou82] for more semantics in this diagram.

State properties

State properties

State property: $P \in \mathcal{P}(\Sigma)$.

Verification problem: $\mathcal{R}(\mathcal{I}) \subseteq P$.

(all the states reachable from \mathcal{I} are in P)

Examples:

- absence of blocking: $P \stackrel{\text{def}}{=} \Sigma \setminus \mathcal{B}$,
- the variables remain in a safe range,
- dangerous program locations cannot be reached.

Invariance proof method

Invariance proof method: find an inductive invariant $I \subseteq \Sigma$

- $I \subseteq I$
(contains initial states)
- $\forall \sigma \in I: \sigma \rightarrow \sigma' \implies \sigma' \in I$
(invariant by program transition)

that implies the desired property: $I \subseteq P$.

Link with the state semantics $\mathcal{R}(I)$:

Given $F_{\mathcal{R}}(S) \stackrel{\text{def}}{=} I \cup \text{post}_{\tau}(S)$, we have $F_{\mathcal{R}}(I) \subseteq I$
 $\implies I$ is a post-fixpoint of $F_{\mathcal{R}}$.

Recall that $\mathcal{R}(I) = \text{lfp } F_{\mathcal{R}}$
 $\implies \mathcal{R}(I)$ is the tightest inductive invariant.

Hoare logic proof method

Idea:

- annotate program points with **local state invariants** in $\mathcal{P}(\Sigma)$
- use logic rules to prove their correctness

$$\begin{array}{c}
 \frac{}{\{P[e/X]\} X \leftarrow e \{P\}} \quad \frac{\{P\} \text{stat}_1 \{R\} \quad \{R\} \text{stat}_2 \{Q\}}{\{P\} \text{stat}_1; \text{stat}_2 \{Q\}} \\
 \\
 \frac{\{P \wedge b\} \text{stat} \{Q\} \quad P \wedge \neg b \Rightarrow Q}{\{P\} \text{if } b \text{ then stat } \{Q\}} \quad \frac{\{P \wedge b\} \text{stat} \{P\}}{\{P\} \text{while } b \text{ do stat } \{P \wedge \neg b\}} \\
 \\
 \frac{\{P\} \text{stat} \{Q\} \quad P' \Rightarrow P \quad Q \Rightarrow Q'}{\{P'\} \text{stat} \{Q'\}}
 \end{array}$$

Link with the state semantics $\mathcal{R}(\mathcal{I})$:

Equivalent to an **invariant proof**, **partitioned** by program location.

Any **post-fixpoint** of $\alpha_{\mathcal{L}} \circ F_{\mathcal{R}} \circ \gamma_{\mathcal{L}}$ gives valid Hoare triples.

$\alpha_{\mathcal{L}}(\mathcal{R}(\mathcal{I})) = \text{lfp}(\alpha_{\mathcal{L}} \circ F_{\mathcal{R}} \circ \gamma_{\mathcal{L}})$ gives the tightest Hoare triples.

Weakest liberal precondition proof methods

Idea: Start with a postcondition $\mathcal{F} \in \mathcal{P}(\Sigma)$
and compute preconditions backwards $P \Rightarrow wlp(stat, Q)$

- $wlp(X \leftarrow e, Q) \stackrel{\text{def}}{=} Q[e/X]$
- $wlp((stat_1; stat_2), Q) \stackrel{\text{def}}{=} wlp(stat_1, wlp(stat_2, Q))$
- $wlp(\text{if } b \text{ then } stat, Q) \stackrel{\text{def}}{=} (b \Rightarrow wlp(stat, Q)) \wedge (\neg b \Rightarrow Q)$
- $wlp(\text{while } b \text{ do } stat, Q) \stackrel{\text{def}}{=} I \wedge ((I \wedge b) \Rightarrow wlp(stat, I)) \wedge ((I \wedge \neg b) \Rightarrow Q)$
(where the loop invariant I is generally provided by the user)

($P \Rightarrow wlp(stat, Q)$ is equivalent to $\{P\} stat \{Q\}$)

Link with the state semantics $\mathcal{S}(\mathcal{Y})$:

(recall $\mathcal{S}(\mathcal{Y}) = \text{gfp } F_{\mathcal{S}}$ where $F_{\mathcal{S}}(S) \stackrel{\text{def}}{=} \mathcal{Y} \cap \widetilde{\text{pre}}_{\tau}(S)$)

Equivalent to **sufficient preconditions**, **partitioned** by location:

any **pre-fixpoint** of $\alpha_{\mathcal{L}} \circ F_{\mathcal{S}} \circ \gamma_{\mathcal{L}}$ gives valid liberal preconditions;

$\alpha_{\mathcal{L}}(\mathcal{S}(\mathcal{F})) = \text{gfp}(\alpha_{\mathcal{L}} \circ F_{\mathcal{R}} \circ \gamma_{\mathcal{L}})$ gives the weakest liberal preconditions while inferring loop invariants!

Trace properties

Trace properties

Trace property: $P \in \mathcal{P}(\Sigma^\infty)$

Verification problem: $\mathcal{M}_\infty \cap (\mathcal{I} \cdot \Sigma^\infty) \subseteq P$

(or, equivalently, as $\mathcal{M}_\infty \subseteq P'$ where $P' \stackrel{\text{def}}{=} P \cup ((\Sigma \setminus \mathcal{I}) \cdot \Sigma^\infty)$)

Examples:

- **termination**: $P \stackrel{\text{def}}{=} \Sigma^*$,
- **non-termination**: $P \stackrel{\text{def}}{=} \Sigma^\omega$,
- any **state property** $S \subseteq \Sigma$: $P \stackrel{\text{def}}{=} S^\infty$,
- **maximal execution time**: $P \stackrel{\text{def}}{=} \Sigma^{\leq k}$,
- **minimal execution time**: $P \stackrel{\text{def}}{=} \Sigma^{\geq k}$,
- **ordering**, e.g.: $P \stackrel{\text{def}}{=} (\Sigma \setminus \{b\})^* \cdot a \cdot \Sigma^* \cdot b \cdot \Sigma^\infty$.
(a and b occur, and a occurs before b)

Safety properties

Idea: a safety property P models that “nothing bad ever occurs”

- P is provable by exhaustive testing;
(observe the prefix trace semantics: $\mathcal{T}_p(\mathcal{I}) \subseteq P$)
- P is disprovable by finding a single finite execution not in P .

Examples:

- any **state property**: $P \stackrel{\text{def}}{=} S^\infty$ for $S \subseteq \Sigma$,
- **ordering**: $P \stackrel{\text{def}}{=} \Sigma^\infty \setminus ((\Sigma \setminus \{a\})^* \cdot b \cdot \Sigma^\infty)$,
(no b can appear without an a before,
but we can have only a , or neither a nor b)
(not a state property)
- but **termination** $P \stackrel{\text{def}}{=} \Sigma^*$ is **not** a safety property.
(disproving requires exhibiting an *infinite* execution)

Definition of safety properties

Reminder: finite prefix abstraction (simplified to allow ϵ)

$$(\mathcal{P}(\Sigma^\infty), \subseteq) \xleftrightarrow[\alpha_{*\preceq}]{\gamma_{*\preceq}} (\mathcal{P}(\Sigma^*), \subseteq)$$

- $\alpha_{*\preceq}(T) \stackrel{\text{def}}{=} \{t \in \Sigma^* \mid \exists u \in T: t \preceq u\}$
- $\gamma_{*\preceq}(T) \stackrel{\text{def}}{=} \{t \in \Sigma^\infty \mid \forall u \in \Sigma^*: u \preceq t \implies u \in T\}$

The associated upper closure $\rho_{*\preceq} \stackrel{\text{def}}{=} \gamma_{\preceq} \circ \alpha_{\preceq}$ is:

$\rho_{*\preceq} = \lim \circ \rho_P$ where:

- $\rho_P(T) \stackrel{\text{def}}{=} \{u \in \Sigma^\infty \mid \exists t \in T: u \preceq t\},$
- $\lim(T) \stackrel{\text{def}}{=} T \cup \{t \in \Sigma^\omega \mid \forall u \in \Sigma^*: u \preceq t \implies u \in T\}.$

Definition: $P \in \mathcal{P}(\Sigma^\infty)$ is a **safety property** if $P = \rho_{*\preceq}(P).$

Definition of safety properties (examples)

Definition: $P \subseteq \mathcal{P}(\Sigma^\infty)$ is a **safety property** if $P = \rho_{*\preceq}(P)$.

Examples and counter-examples:

- state property $P \stackrel{\text{def}}{=} S^\infty$ for $S \subseteq \Sigma$:

$$\rho_P(S^\infty) = \lim(S^\infty) = S^\infty \implies \text{safety};$$

- termination $P \stackrel{\text{def}}{=} \Sigma^*$:

$$\rho_P(\Sigma^*) = \Sigma^*, \text{ but } \lim(\Sigma^*) = \Sigma^\infty \neq \Sigma^* \implies \text{not safety};$$

- even number of steps $P \stackrel{\text{def}}{=} (\Sigma^2)^\infty$:

$$\rho_P((\Sigma^2)^\infty) = \Sigma^\infty \neq (\Sigma^2)^\infty \implies \text{not safety}.$$

Proving safety properties

Invariance proof method: find an inductive invariant I

- set of finite traces $I \subseteq \Sigma^*$
- $\mathcal{I} \subseteq I$
(contains traces reduced to an initial state)
- $\forall \sigma_0, \dots, \sigma_n \in I: \sigma_n \rightarrow \sigma_{n+1} \implies \sigma_0, \dots, \sigma_n, \sigma_{n+1} \in I$
(invariant by program transition)

and implies the desired property: $I \subseteq P$.

Link with the finite prefix trace semantics $\mathcal{T}_p(\mathcal{I})$:

An inductive invariant is a post-fixpoint of F_p : $F_p(I) \subseteq I$

where $F_p(T) \stackrel{\text{def}}{=} \mathcal{I} \cup T \cap \tau$.

$\mathcal{T}_p(\mathcal{I}) = \text{lfp } F_p$ is the tightest inductive invariant.

Correctness of the invariant method for safety

Soundness:

if P is a safety property and an inductive invariant I exists
then: $\mathcal{M}_\infty \cap (\mathcal{I} \cdot \Sigma^\infty) \subseteq P$

proof:

Using the Galois connection between \mathcal{M}_∞ and \mathcal{T} , we get:

$$\begin{aligned} \mathcal{M}_\infty \cap (\mathcal{I} \cdot \Sigma^\infty) &\subseteq \rho_{*\preceq}(\mathcal{M}_\infty \cap (\mathcal{I} \cdot \Sigma^\infty)) = \gamma_{*\preceq}(\alpha_{*\preceq}(\mathcal{M}_\infty \cap (\mathcal{I} \cdot \Sigma^\infty))) = \\ &\gamma_{*\preceq}(\alpha_{*\preceq}(\mathcal{M}_\infty) \cap (\mathcal{I} \cdot \Sigma^*)) = \gamma_{*\preceq}(\mathcal{T} \cap (\mathcal{I} \cdot \Sigma^*)) = \gamma_{*\preceq}(\mathcal{T}_p(\mathcal{I})). \end{aligned}$$

Using the link between invariants and the finite prefix trace semantics, we have:

$$\mathcal{T}_p(\mathcal{I}) \subseteq I \subseteq P.$$

As P is a safety property, $P = \gamma_{*\preceq}(P)$, so, $\gamma_{*\preceq}(\mathcal{T}_p(\mathcal{I})) \subseteq \gamma_{*\preceq}(P) = P$, and so,

$$\mathcal{M}_\infty \cap (\mathcal{I} \cdot \Sigma^\infty) \subseteq P.$$

Completeness: an inductive invariant always exists

proof: $\mathcal{T}_p(\mathcal{I})$ provides an inductive invariant.

Disproving safety properties

Proof method:

A safety property P can be **disproved** by constructing a **finite prefix of execution** that does not satisfy the property:

$$\mathcal{M}_\infty \cap (\mathcal{I} \cdot \Sigma^\infty) \not\subseteq P \implies \exists t \in \mathcal{T}_P(\mathcal{I}) : t \notin P$$

proof:

By contradiction, assume that no such trace exists, i.e., $\mathcal{T}_P(\mathcal{I}) \subseteq P$.

We proved in the previous slide that this implies $\mathcal{M}_\infty \cap (\mathcal{I} \cdot \Sigma^\infty) \subseteq P$.

Examples:

- disproving a **state property** $P \stackrel{\text{def}}{=} S^\infty$:
 \implies find a partial execution containing a state in $\Sigma \setminus S$;
- disproving an **order property** $P \stackrel{\text{def}}{=} \Sigma^\infty \setminus ((\Sigma \setminus \{a\})^* \cdot b \cdot \Sigma^\infty)$
 \implies find a partial execution where b appears and not a .

Liveness properties

Idea: **liveness property** $P \in \mathcal{P}(\Sigma^\infty)$

Liveness properties model that “something good eventually occurs”

- P cannot be proved by testing
(if nothing good happens in a prefix execution,
it can still happen in the rest of the execution)
- disproving P requires exhibiting an infinite execution not in P

Examples:

- **termination**: $P \stackrel{\text{def}}{=} \Sigma^*$,
- **inevitability**: $P \stackrel{\text{def}}{=} \Sigma^* \cdot a \cdot \Sigma^\infty$,
(a eventually occurs in all executions)
- state properties are **not** liveness properties.

Definition of liveness properties

Definition: $P \in \mathcal{P}(\Sigma^\infty)$ is a **liveness property** if $\rho_{*\sqcup}(P) = \Sigma^\infty$.

Examples and counter-examples:

- termination $P \stackrel{\text{def}}{=} \Sigma^*$:

$$\rho_P(\Sigma^*) = \Sigma^* \text{ and } \lim(\Sigma^*) = \Sigma^\infty \implies \text{liveness};$$

- inevitability: $P \stackrel{\text{def}}{=} \Sigma^* \cdot a \cdot \Sigma^\infty$

$$\rho_P(P) = P \cup \Sigma^* \text{ and } \lim(P \cup \Sigma^*) = \Sigma^\infty \implies \text{liveness};$$

- state property $P \stackrel{\text{def}}{=} S^\infty$ for $S \subseteq \Sigma$:

$$\rho_P(S^\infty) = \lim(S^\infty) = S^\infty \neq \Sigma^\infty \text{ if } S \neq \Sigma \implies \text{not liveness};$$

- maximal execution time $P \stackrel{\text{def}}{=} \Sigma^{\leq k}$:

$$\rho_P(\Sigma^{\leq k}) = \lim(\Sigma^{\leq k}) = \Sigma^{\leq k} \neq \Sigma^\infty \implies \text{not liveness};$$

- the only property which is both safety and liveness is Σ^∞ .

Proving liveness properties

Variance proof method: (informal definition)

Find a **decreasing quantity** until something good happens.

Example: termination proof

- find $f : \Sigma \rightarrow \mathcal{S}$ where $(\mathcal{S}, \sqsubseteq)$ is **well-ordered**;
(f is called a “ranking function”)
- $\sigma \in \mathcal{B} \implies f = \min \mathcal{S}$;
- $\sigma \rightarrow \sigma' \implies f(\sigma') \sqsubset f(\sigma)$.

(f counts the number of steps remaining before termination)

Disproving liveness properties

Property:

If P is a liveness property, then $\forall t \in \Sigma^*: \exists u \in P: t \preceq u$.

proof:

By definition of liveness, $\rho_{*\preceq}(P) = \Sigma^\infty$, so $t \in \rho_{*\preceq}(P) = \lim(\alpha_P(P))$.

As $t \in \Sigma^*$ and \lim only adds infinite traces, $t \in \alpha_P(P)$.

By definition of α_P , $\exists u \in P: t \preceq u$.

Consequence:

- liveness cannot be disproved by testing.

Trace topology

Topology on X , defined by

- a family $\mathcal{C} \subseteq \mathcal{P}(X)$ of **closed sets**
 - $c, c' \in \mathcal{C} \implies c \cup c' \in \mathcal{C}$ (closed by finite unions)
 - $\mathcal{C} \subseteq \mathcal{C} \implies \cap \{c \mid c \in \mathcal{C}\} \in \mathcal{C}$ (closed by intersections)
- **open sets** \mathcal{O} are derived from closed sets:
 $\mathcal{O} \stackrel{\text{def}}{=} \{X \setminus c \mid c \in \mathcal{C}\}$
 (closed by unions and finite intersections)
 (we can alternatively define a topology by \mathcal{O} , and derive \mathcal{C} from \mathcal{O})

Definition: we define a topology on traces by setting:

- $X \stackrel{\text{def}}{=} \Sigma^\infty$
- $\mathcal{C} \stackrel{\text{def}}{=} \{P \in \mathcal{P}(\Sigma^\infty) \mid P \text{ is a safety property}\}$

Closure and density

Topological closure: $\rho : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$

- $\rho(x) \stackrel{\text{def}}{=} \bigcap \{ c \in \mathcal{C} \mid x \subseteq c \};$
 (ρ is an upper closure operator in $(\mathcal{P}(X), \subseteq)$)
 ($\rho(x) = x \iff x \in \mathcal{C}$)
- on our trace topology, $\rho = \rho_* \preceq$.

Dense sets:

- $x \subseteq X$ is dense if $\rho(x) = X$;
- on our trace topology, dense sets are **liveness properties**.

Decomposition theorem

Theorem: decomposition on a topological space

Any set $x \subseteq X$ is the **intersection** of a **closed** set and a **dense** set.

proof:

We have $x = \rho(x) \cap (x \cup (X \setminus \rho(x)))$. Indeed:

$$\rho(x) \cap (x \cup (X \setminus \rho(x))) = (\rho(x) \cap x) \cup (\rho(x) \cap (X \setminus \rho(x))) = \rho(x) \cap x = x \text{ as } x \subseteq \rho(x).$$

- $\rho(x)$ is closed
- $x \cup (X \setminus \rho(x))$ is dense because:

$$\begin{aligned} \rho(x \cup (X \setminus \rho(x))) &\supseteq \rho(x) \cup \rho(X \setminus \rho(x)) \\ &\supseteq \rho(x) \cup (X \setminus \rho(x)) \\ &= X \end{aligned}$$

Consequence: on trace properties

Every trace property is the **conjunction** of a **safety** property and a **liveness** property.

(proving a trace property can be decomposed into a soundness proof and a liveness proof)

Beyond trace properties

Some verification problems cannot be expressed as $\mathcal{M}_\infty \subseteq P$

Examples:

- **Program equivalence**

Do two programs (Σ, τ_1) and (Σ, τ_2) have the exact same executions?
i.e., $\mathcal{M}_\infty[\tau_1] = \mathcal{M}_\infty[\tau_2]$

- **Non-interference**

Does changing the initial value of X change its final value?

$$\forall \sigma_0, \dots, \sigma_n \in \mathcal{M}_\infty : \forall \sigma'_0 : \sigma_0 \equiv \sigma'_0 \implies$$

$$\exists \sigma'_0, \dots, \sigma'_m \in \mathcal{M}_\infty : \sigma'_m \equiv \sigma_m$$

$$\text{where } (\ell, \rho) \equiv (\ell', \rho') \iff \ell = \ell' \wedge \forall V \neq X : \rho(V) = \rho'(V)$$

New verification problem: $\mathcal{M}_\infty \in H$ where $H \in \mathcal{P}(\mathcal{P}(\Sigma^\infty))$

- generalizes trace properties: $\mathcal{M}_\infty \subseteq P$ reduces to $\mathcal{M}_\infty \in \mathcal{P}(P)$;
- program equivalence is $\mathcal{M}_\infty[\tau_1] \in \{\mathcal{M}_\infty[\tau_2]\}$; etc.

Reading assignment: hyperproperties.

Bibliography

Bibliography

[Bour93] **F. Bourdoncle.** *Abstract debugging of higher-order imperative languages.* In PLDI, 46-55, ACM Press, 1993.

[Cous02] **P. Cousot.** *Constructive design of a hierarchy of semantics of a transition system by abstract interpretation.* In Theoretical Comp. Sc., 277(1-2):47-103.

[Plot81] **G. Plotkin.** *The origins of structural operational semantics.* In J. of Logic and Algebraic Prog., 60:60-61, 1981.