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| CONTACT INFORMATION | <p>Address: Pudong, Shanghai, China</p> <p>☞ Wechat: nenhabkks</p> <p>☎ Tel: +86 19821254220</p> <p>🖱 Homepage: https://mq66.github.io</p> <p>✉ E-mail: mengquan@shanghaitech.edu.cn</p> |
| ACADEMIC HISTORY | <p>ShanghaiTech University Fall 2019 - Spring 2021 (expected)</p> <ul style="list-style-type: none"> • M.S. in Computer Science and Engineering • Advisor: Prof. Jingyi Yu. <p>Shandong University Fall 2015 - Spring 2019</p> <ul style="list-style-type: none"> • B.S. in Automatic Control. • Advisor: Prof. Guoliang Liu. |
| PUBLICATIONS | <ol style="list-style-type: none"> 1. Quan Meng, Anpei Chen, Haimin Luo, Minye Wu, Hao Su, Lan Xu, Xuming He, and Jingyi Yu GNeRF: GAN-Based Neural Radiance Field without Posed Camera <i>Proceedings of the IEEE/CVF International Conference on Computer Vision (ICCV), 2021</i> Oral Presentation: 3.4% We introduce GNeRF, a method that can estimate camera poses and neural radiance fields jointly when the cameras are initialized at random poses in complex scenarios (outside-in scenes, even with less texture or intense noise). We achieve this by marrying Generative Adversarial Networks (GAN) with Neural Radiance Field. 2. Quan Meng, Jiakai Zhang, Qiang Hu, Xuming He, and Jingyi Yu LGNN: A Context-Aware Line Segment Detector <i>Proceedings of the 28th ACM International Conference on Multimedia (ACM MM), 2020</i> Poster: 27.9% Existing approaches require a computationally expensive verification or postprocessing step. Our LGNN employs a deep convolutional neural network (DCNN) for proposing line segments directly, with a graph neural network (GNN) module for reasoning their connectivities. LGNN achieves comparable performance and enables time-sensitive 3D applications. |
| HONORS AND AWARDS | <ul style="list-style-type: none"> • First prices in World Robot Contest Fighting Robot Competition. 2017 • First prices (Shan Dong) in National Undergraduate Electronics Design Contest 2017, 2018 |
| TECHNICAL SKILLS | <ul style="list-style-type: none"> • <i>Softwares</i>: Linux, C/C++, Python, Java, Pytorch, Opencv, Latex, Matlab, Qt. • <i>Hardwares</i>: STM32, STC, PCB. |