MA3105: Comparing Cubic Spline with the Linear Spline and the Lagrangian polynomial

Rudra Mukhopadhyay

November 24, 2021

Contents

1	Aim	1
2	First algorithm in action	2
	2.1 The algorithm given by Atkinson, K. (1978)	2
	2.2 Gauging the accuracy while implementing the algorithm	2
	2.2.1 Interpolating a linear function	2
	2.2.2 Comparison with a solved example in Atkinson, 2nd ed	2
	2.3 Considering $f(x) = e^x$ on $\Omega = [-1, 1]$	3
	2.3.1 Interpolation using natural cubic	3
	2.3.2 Comparing with the linear spline	3
3	Second algorithm in action	5
	3.1 Comparing with Lagrangian of degree $n-1$	6
	3.2 Considering a trigonometric function on $\Omega = [0, \pi]$	6
4	Conclusion	7

1 Aim

A counter-intuitive result was noticed after comparing the error in a natural cubic spline to that in a linear spline, for the function $e^x, x \in [-1, 1]$. The linear spline error appeared to undergo a faster convergence than the cubic spline, even though the infinity norm error bound in both the cases is given by $\mathcal{O}(h^2), h := \frac{b-a}{n-1}$ where n is the number of knots in an interval $\Omega = [a, b]$.

In this report, I have tried to re-explore the situation and trouble-shoot the set-up. It is examined if the code used contains any manual mistake. An algorithm to estimate the clamped spine, with the first derivative being clamped, has been used.

2 First algorithm in action

2.1 The algorithm given by Atkinson, K. (1978)

The algorithm used is described briefly underneath.

- 1. $s \in C^2(\Omega)$ be the whole cubic spline on Ω , such that $s = s_{[x_i,x_{i+1}]}$ on $[x_i,x_{i+1}], i = 1,\ldots,n-1$.
- **2.** $\sigma_i := s''(x_i)i = 1, \ldots, n$.
- 3. s'' is linear on $[x_i, x_{i+1}] \implies s''(x) = \frac{x_{i+1} x}{h_i} \sigma_i + \frac{x x_i}{h_i} \sigma_{i+1}, h_i := x_{i+1} x_i$.
- 4. s'' is continuous. Thus, $h_{i+1}\sigma_i + 2(h_{i+2} + h_{i+1})\sigma_{i+1} + h_{i+2}\sigma_{i+2} = 6\left(\frac{f(x_{i+2}) f(x_{i+1})}{h_{i+2}} \frac{f(x_{i+1}) f(x_i)}{h_{i+1}}\right), x = 2, \ldots, n-2$. This, along with $\sigma_0 = \sigma_n = 0$, constitute the tridiagonal system.
- 5. The system of linear equations is solved using Thomas algorithm.
- 6. Integrating s'' twice yields s' and s respectively.
- 7. Using (i)s' is continuous, (ii)s is continuous, $(iii)s(x_i) = f(x_i)$ and some algebraic manipulations, an expression for $s(x, \sigma)$ [Ref: Pg 150, Atkinson (3rd ed)] is derived.
- 8. Substitute the value of σ_i in the expression for s.

2.2 Gauging the accuracy while implementing the algorithm

2.2.1 Interpolating a linear function

On $\Omega = [0,1]$ I have taken x = linspace(0, 1, n), y = x, while n = 5:5:30. The error is presented below. I consider another case, with $\Omega = [100, 120]$, just so that the

n	$ f-s _{\infty}$	$ f-s _2$
5	0.000000	0.000000
10	0.000000	0.000000
15	0.000000	0.000000
20	0.000000	0.000000
25	0.000000	0.000000
30	0.000000	0.000000

Table 1: On
$$\Omega = [0, 1], f(x) = x$$

low error value is not attributed to small x(i), y(i) values. It is thus concluded that the program runs accurately for a linear function.

2.2.2 Comparison with a solved example in Atkinson, 2nd ed

In this portion, I take under consideration one solved example (Example 4.3.1, page 151) in *An Introduction to Numerical Analysis (2nd ed.)* by Atkinson, K.

Given $x = \begin{bmatrix} 1 & 2 & 3 & 4 \end{bmatrix}$, $y = \begin{bmatrix} 1 & 1/2 & 1/3 & 1/4 \end{bmatrix}$, it is obvious that the original function $f(x) = \frac{1}{x}, x \in [1, 4]$. Using n = 4, I implement the code and report the deviation on

n	$ f-s _{\infty}$	$ f-s _2$
5	0.000000	0.000000
10	0.000000	0.000000
15	0.000000	0.000000
20	0.000000	0.000004
25	0.000000	0.000000
30	0.000000	0.000000

Table 2: On $\Omega = [100, 120], f(x) = x$

the interval $\Omega = [1, 4]$. Here s_1 represents the spline estimation given by Atkinson, K. and s_2 represents the interpolation found by my code.

$$||s_1 - s_2||_{\infty} = 1.665 \cdot 10^{-15}$$

 $||s_1 - s_2||_2 = 6.128 \cdot 10^{-15}$

I claim that the error/ deviation of the order -15 is solely caused by floating point approximation. Thus, the result obtained by my code agrees with that given by Atkinson, K.

2.3 Considering $f(x) = e^x$ on $\Omega = [-1, 1]$

2.3.1 Interpolation using natural cubic

I have interpolated the function on Ω , with n=5:5:40. One instance (with n=20 is plotted.

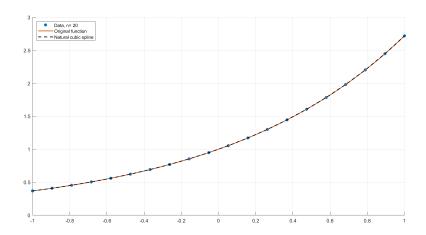


Figure 1: Interpolating natural cubic on Ω , for the given f

2.3.2 Comparing with the linear spline

The errors are estimated and presented below. s_L denotes the linear spline, whereas s_N refers to the natural cubic spline.

In the second table are presented the ratio $r := \epsilon_{n+1}/\epsilon_n$, where ϵ_n denotes the error with n number of knots and ϵ_n is either $L_{\infty}(r_{\infty})$ or $L_2(r_2)$ norm error.

n	$ f-s_L _{\infty}$	$ f-s_N _{\infty}$	$ f-s_L _2$	$ f-s_N _2$
5	0.066617	0.048949	0.428488	0.276201
10	0.015034	0.013057	0.085609	0.069094
15	0.006460	0.005902	0.035438	0.030806
20	0.003567	0.003340	0.019251	0.017352
25	0.002261	0.002146	0.012068	0.011112
30	0.001537	0.001474	0.008267	0.007720
35	0.001141	0.001099	0.006014	0.005673
40	0.000845	0.000816	0.004571	0.004344

Table 3: Comparing the L_{∞} and L_2 error

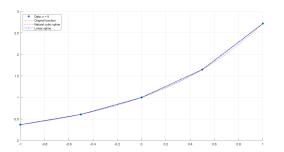
n	r_{∞}^{L}	r_{∞}^{N}	r_2^L	r_2^N
10	4.430915	3.748837	5.005196	3.997496
15	2.327467	2.212152	2.415736	2.242852
20	1.810970	1.767133	1.840851	1.775395
25	1.577389	1.556223	1.595191	1.561476
30	1.470864	1.455658	1.459872	1.439444
35	1.347339	1.341709	1.374452	1.360800
40	1.350981	1.346761	1.315722	1.305978

Table 4: Ratio: $||f - s_j||_{\rho}^{n+1}/||f - s_j||_{\rho}^n$

As evident from the tables given, the value of error, for both the norms, is lower in the natural cubic spline interpolation. This contradicts the result I showed in the presentation. The mistake most probably lied in the usage of the mesh. Possibly, while calculating the error values, the mesh used in the linear spline case, to estimate the interpolated values, was different from that used in the cubic spline case. Note that, the ratio estimated is similar in both the cases. This can be justified by the fact that linear as well as natural cubic spline has an error bound of $\mathcal{O}(h^2)$.

Given below two figures, showing the linear spline, the cubic spline as well as the original function in the same plot.

In the second figure, behaviours of these functions are shown over the interval [0, 0.5]. While plotting, I have used n = 5 in this particular case.



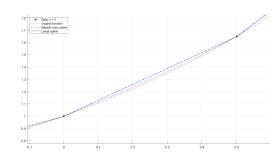


Figure 2: Plotting s_L, s_N and f

3 Second algorithm in action

In the presentation, I presented the clamped condition given by $s''(x_1) = f''(x_1)$; $s''(x_n) = f''(x_n)$. There was no significant improvement in the interpolating spline. Thus, here I discuss the second clamping constraint, given by $s'(x_1) = f'(x_1)$; $s'(x_n) = f'(x_n)$.

I have used the algorithm given by Burden, R. and Faires, J. D. in *Numerical Analysis* (10th ed.). The corresponding Matlab file is uploaded on the GitHub repository mentioned at the bottom of this page 1 .

The error is noted below.

n	$ f-s_N _{\infty}$	$ f-s_C _{\infty}$	$ f-s_N _2$	$ f-s_C _2$
5	0.048949	0.000396	0.276201	0.002078
10	0.013057	0.000017	0.069094	0.000078
15	0.005902	0.000003	0.030806	0.000013
20	0.003340	0.000001	0.017352	0.000004
25	0.002146	0.000000	0.011112	0.000002
30	0.001474	0.000000	0.007720	0.000001
35	0.001099	0.000000	0.005673	0.000000
40	0.000816	0.000000	0.004344	0.000000

Table 5: Comparing natural cubic spline (s_N) with clamped cubic spline (s_C)

The fact that the error bound in the clamped cubic is given by $\mathcal{O}(h^4)$ is reflected here, when the first derivative clamping is used. A significant improvement can be noted. A plot containing the natural, clamped cubic spline and the original function is provided below.

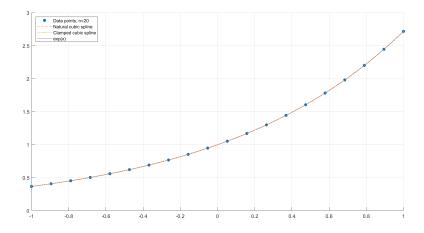


Figure 3: s_N, s_C and $f = e^x$ over Ω . n = 20.

¹https://github.com/MR-dot-15/MA3105-Numerical-Analysis-/blob/main/cubic_spline1.m

3.1 Comparing with Lagrangian of degree n-1

In this subsection I have tried to compare the clamped cubic spline with the Lagrangian interpolating polynomial of degree n-1. As given by the error bound- $||f-P_n||_{\infty} \leq \mathcal{O}(h^{n-1})$, a Lagrangian polynomial is supposed to be more accurate than any spline. On the interval $\Omega = [-1,1]$, I estimated s_C and P_n , with n varying in $\{4,6,\ldots,20\}$. While plotting the interpolates, I have used a mesh with 200 x-values on Ω .

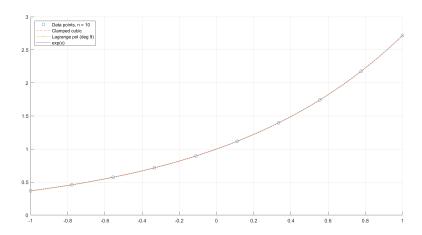


Figure 4: s_C , P_n and $f = e^x$ on Ω

The error values are presented in the following table.

n	$ f-s_C _{\infty}$	$ f-P_n _{\infty}$	$ f-s_C _2$	$ f-P_n _2$
4	0.001193	0.009983	0.006714	0.076627
6	0.000167	0.000112	0.000835	0.000650
8	0.000045	0.000001	0.000214	0.000004
10	0.000017	0.000000	0.000078	0.000000
12	0.000007	0.000000	0.000035	0.000000
14	0.000004	0.000000	0.000018	0.000000
16	0.000002	0.000000	0.000010	0.000000
18	0.000001	0.000000	0.000006	0.000000
20	0.000001	0.000000	0.000004	0.000000

Table 6: Comparing the error in clamped cubic spline and the Lagrangian polynomial

As obvious from Table-6, Lagrangian polynomial converges to faster than the clamped cubic. It can be better shown using the ratio of two consecutive errors.

3.2 Considering a trigonometric function on $\Omega = [0, \pi]$

In order to extend the comparison, I consider here the function $f = \sin x$, on the interval $[0, \pi]$. Three different interpolation techniques, namely clamped cubic spline (s_C) , linear spline (s_L) and Lagrangian polynomial (P_n) have been implemented. Table-7 contains the infinity and second norm error estimates for all three of those.

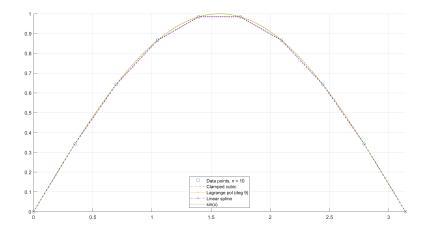


Figure 5: s_C, s_L, P_n and $f = \sin x$ on $\Omega = [0, \pi]$

n	$ f-s_C _{\infty}$	$ f-P_n _{\infty}$	$ f-s_L _{\infty}$	$ f-s_C _2$	$ f-P_n _2$	$ f-s_L _2$
4	0.004733	0.043615	0.133943	0.026204	0.385470	0.974899
6	0.000434	0.001312	0.048912	0.002878	0.008534	0.356398
8	0.000111	0.000024	0.025041	0.000712	0.000127	0.182606
10	0.000040	0.000000	0.015161	0.000255	0.000001	0.110658
12	0.000018	0.000000	0.010147	0.000113	0.000000	0.074142
14	0.000009	0.000000	0.007260	0.000057	0.000000	0.053110
16	0.000005	0.000000	0.005447	0.000032	0.000000	0.039905
18	0.000003	0.000000	0.004235	0.000020	0.000000	0.031074
20	0.000002	0.000000	0.003384	0.000012	0.000000	0.024880

Table 7: Comparing error estimates for s_C, P_n, s_L with $f = \sin x$

4 Conclusion

As observed in this analysis, the rate of convergence for both the L_{∞} and L_2 norm error is the highest when Lagrangian polynomial of degree n-1 is used to interpolate n points.

It is to be noted that the clamped cubic spline with clamped first derivative yields a better approximation that the natural cubic spline. The accuracy of the linear spline, on the other hand, is *comparable* to that of the natural cubic spline (for both being bounded by $\mathcal{O}(h^2)$). As stated earlier, the result presented showing a significant accuracy in the linear spline case was inaccurate, and was probably caused by using two different set of x-values to estimate the interpolated function (i.e. s_N and s_L).

It can be concluded that, for *significantly large value* of n, the approximation accuracy follows this order- Lagrangian polynomial, clamped cubic spline (with the first derivative being constrained), natural cubic spline, linear spline.