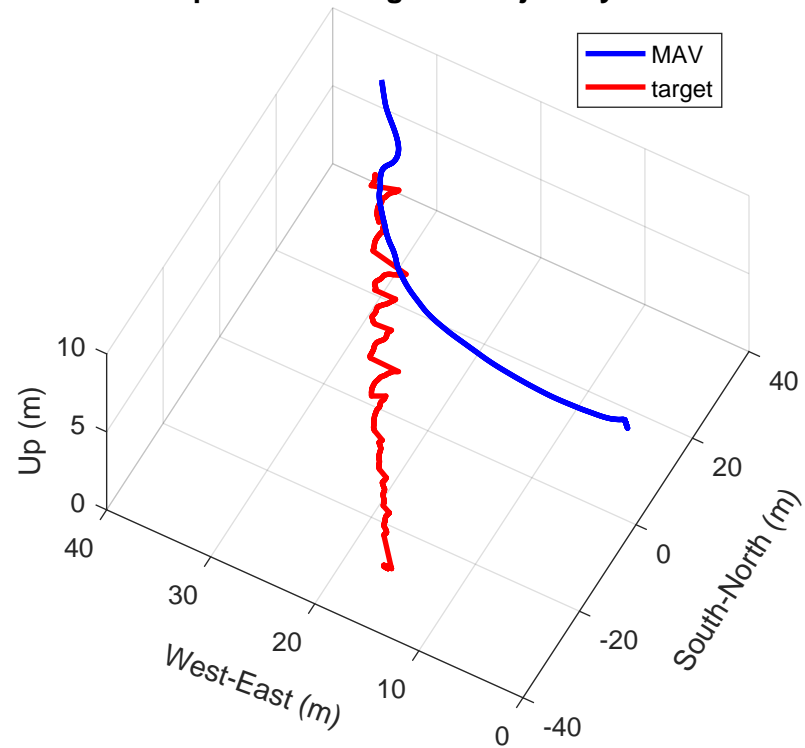
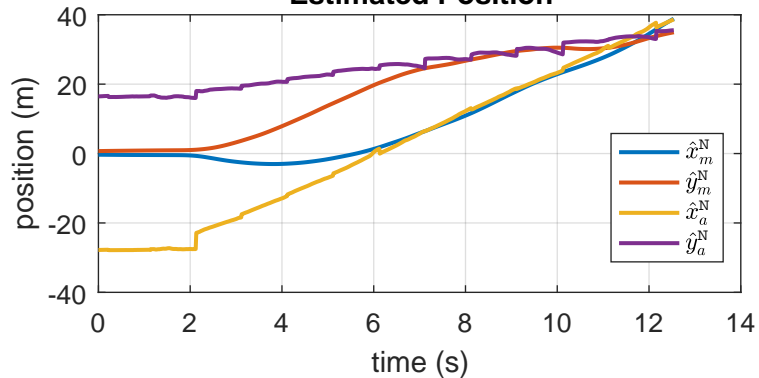


### Proportional navigation trajectory in ENU



### Estimated Position



### Estimated Speed

