1) Implement Bellman-Ford algorithm. Output should contain the shortest path, path cost, and the table containing the costs and parent of each node after each iteration.

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```
#include <bits/stdc++.h>
using namespace std;
struct Edge
  int u, v, w;
};
vector<Edge> E;
int cost[1000];
int parent[1000];
int n;
void printPath(int node)
  if (parent[node] == -1)
    cout << node;
    return;
  printPath(parent[node]);
  cout << " -> " << node;
}
void printTable()
  cout<<"DestinationNode\t\tParentNode\tcost\n"<<endl;</pre>
  for (int j = 1; j \le n; j++)
    cout << j << "\t\t" << parent[j] << "\t\t" << cost[j] << "\n";
  }
}
void BellmanFord(int s)
  int cnt = 0;
  for (int i = 1; i <= n; i++)
    cost[i] = 100000000;
    parent[i] = -1;
  cost[s] = 0;
  cout << "\nAll Iterations: \n"<<endl;</pre>
  for (int i = 1; i < n; i++)
  {
    for (Edge e : E)
```

```
{
       if (cost[e.v] > cost[e.u] + e.w)
         cost[e.v] = cost[e.u] + e.w;
         parent[e.v] = e.u;
         cout << "on Iteration " << cnt << ":\n";
         printTable();
         cnt++;
       }
    }
  }
}
int main()
  int node, edges;
  cout << "Enter the number of vetices: ";</pre>
  cin >> node;
  n = node;
  cout << "Enter the number of edges: ";
  cin >> edges;
  cout << "Enter the edges (source, destination, weight):\n";</pre>
  while (edges--)
    Edge edge;
    cin >> edge.u >> edge.v >> edge.w;
    E.push_back(edge);
  }
  int source;
  cout << "Enter the source vertex: "<<endl;;</pre>
  cin >> source;
  BellmanFord(source);
  cout << "\nAll Shortest paths from source " << source << ":\n\n";</pre>
  for (int i = 1; i <= node; i++)
    cout << "Path to vertex " << i << ": ";
    printPath(i);
    cout << "\nTotal Path cost: " << cost[i] << "\n\n";
  }
  return 0;
}
```