



**KNU**

School of Computer Science and Engineering

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# Optimized node clustering by using genetic algorithm

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# Overview

- ❖ Introduction
- ❖ System model
- ❖ Simulation result
- ❖ Conclusion

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# Introduction

## ❖ Trajectory planning for UAV assisted data collection

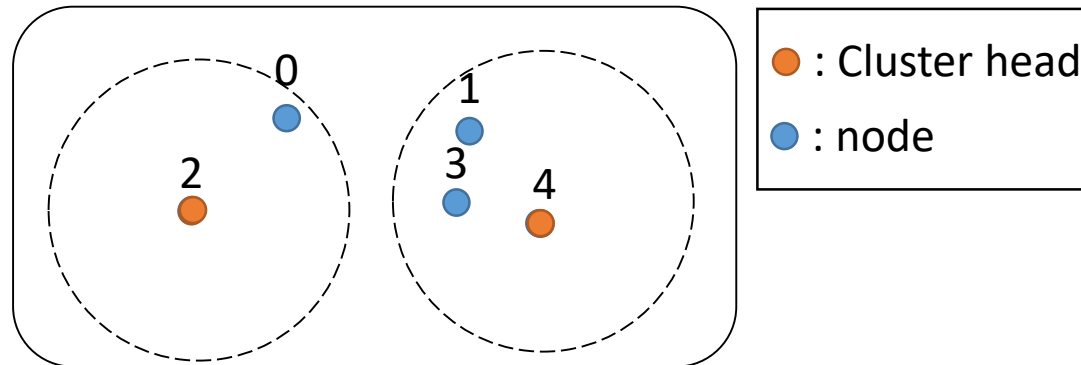
### □ Two general steps

#### ➤ Cluster head election based node clustering

- Cluster head (CH) identification ➔ Group the nodes within the region of a CH as a cluster
- Cluster heads should collect data from nodes with their own region and deliver them to the UAV.

#### ➤ Path planning

- Shortest tour that passes through all cluster heads. (TSP)



# Introduction

## ❖ Trajectory planning for UAV assisted data collection

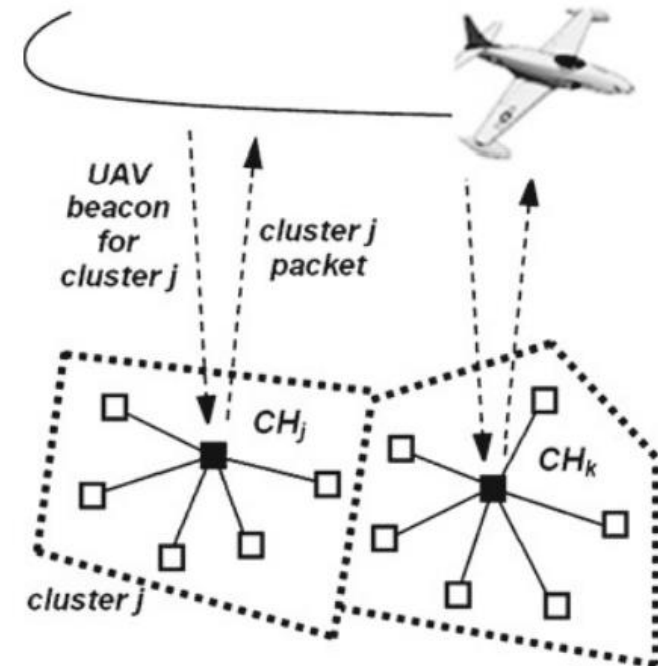
### □ Two general steps

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**Fig. 2** Basic scheme for cluster-based UAS data collection

# Introduction

## ❖ Problem definition

□ Given a set  $\mathbf{D} = \{d_1, \dots, d_K\}$  of  $K$  nodes

➤ Group them into  $N$  clusters with  $N < M$ , where  $M$  is a given integer.

□ Basic assumption

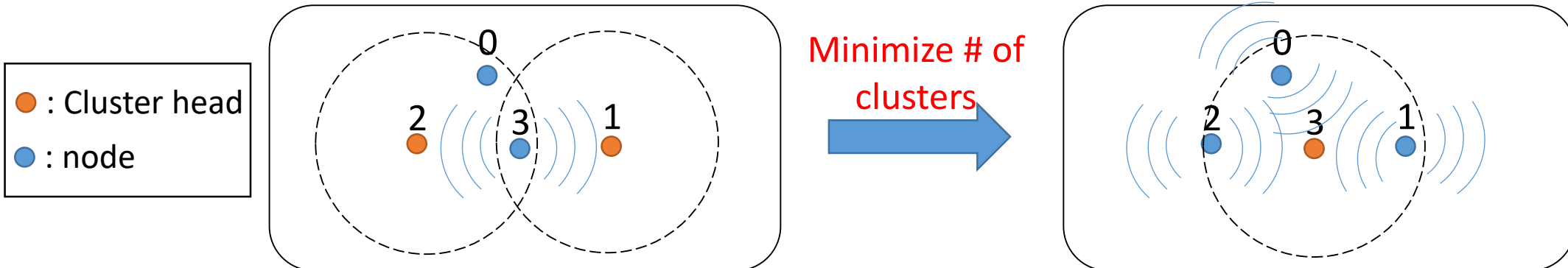
➤ It is allowed that a node is covered by multiple cluster heads.

- The UAV would receive **redundant data**, since the node transmit data to adjacent CHs by **broadcasting**.

- The region defined by the CH = The communication range.

➤ It is desirable to have **as few clusters as possible**.

- This could **alleviate the degree of overlap**



# Introduction

## ❖ Node clustering

### □ Set cover problem with additional goal

➤ Given a set  $I = \{1, \dots, K\}$  of integers and a collection  $\mathcal{S} = \{\{1\}, \dots, \{1, 3, \dots, K\}\}$  of sets whose union is  $I$

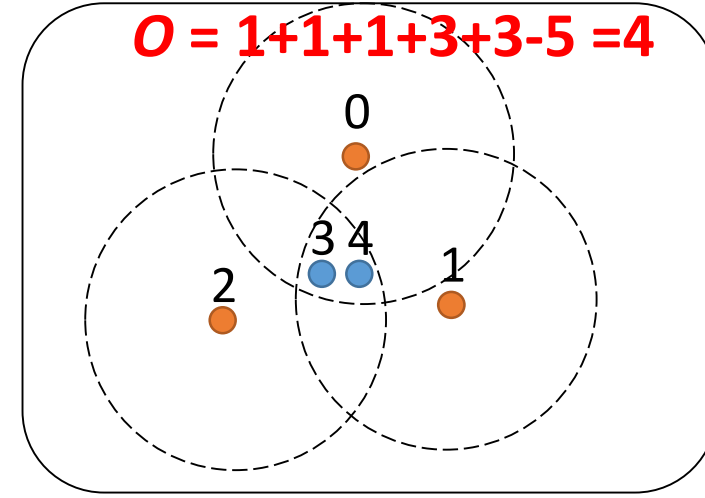
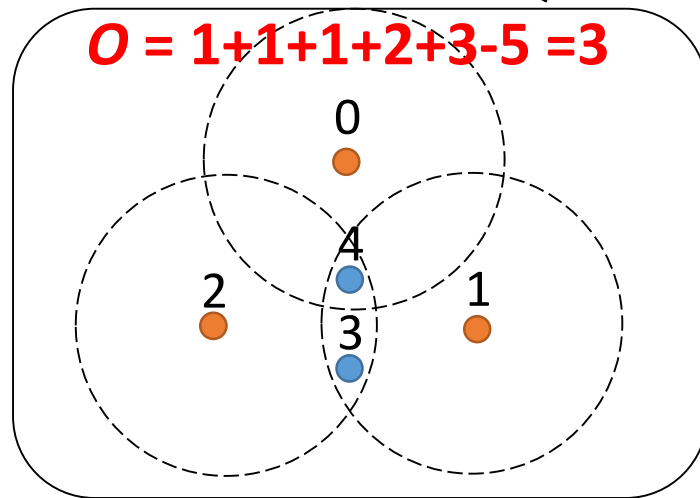
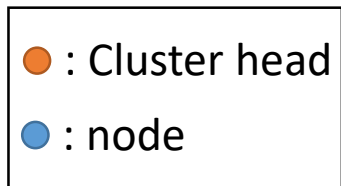
- $I = D$ ,  $\mathcal{S} =$  **potential cluster configurations.**

➤ Goal: identify a **smallest sub-collection** of  $\mathcal{S}$  whose union is  $I$

- Minimizing the # of clusters which can cover all nodes.

➤ **Extra goal:** if **multiple feasible** solutions  $\Rightarrow$  chose the one with **minimal overlap degree.**

- Overlap degree,  $O = \sum_{i=1}^K (\sum_{s \in \mathcal{S}} 1\{i \in s\}) - K$ : **The amount of redundant data.**



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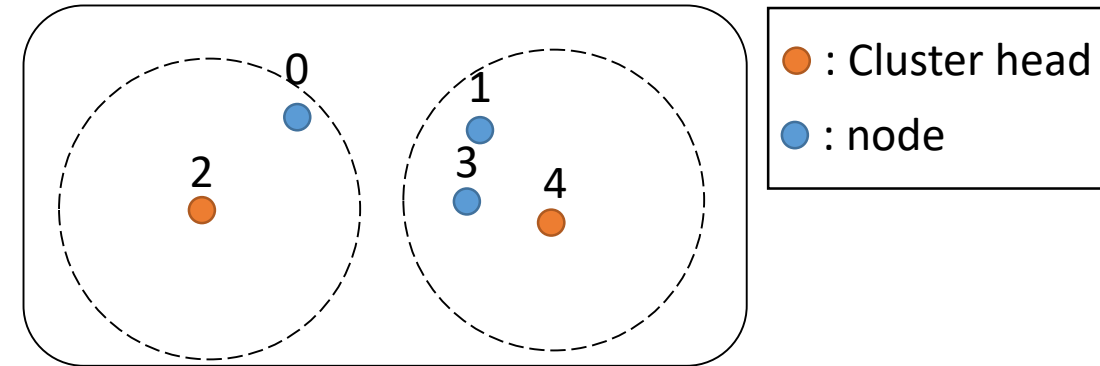
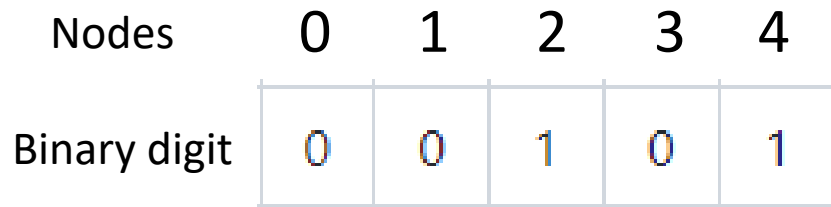
# System model

## ❖ Model description

### □ Representation ( $K$ nodes)

➤  $K$  bit binary digit.

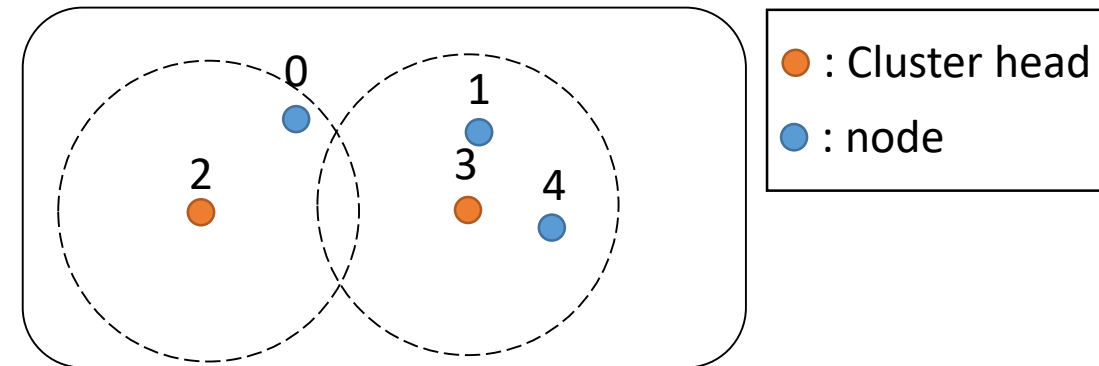
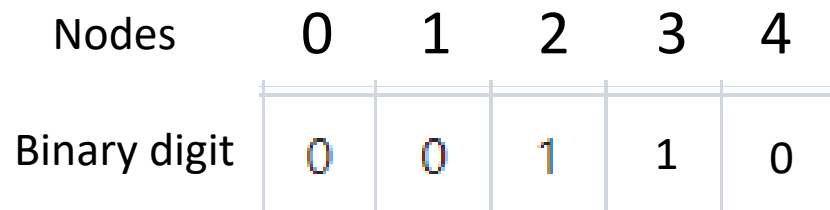
✓  $i$ -th bit: the binary value implies whether the corresponding node is the cluster header



### □ Operators

➤ Change the binary values in the digit.

➤ Group the nodes according to the result.

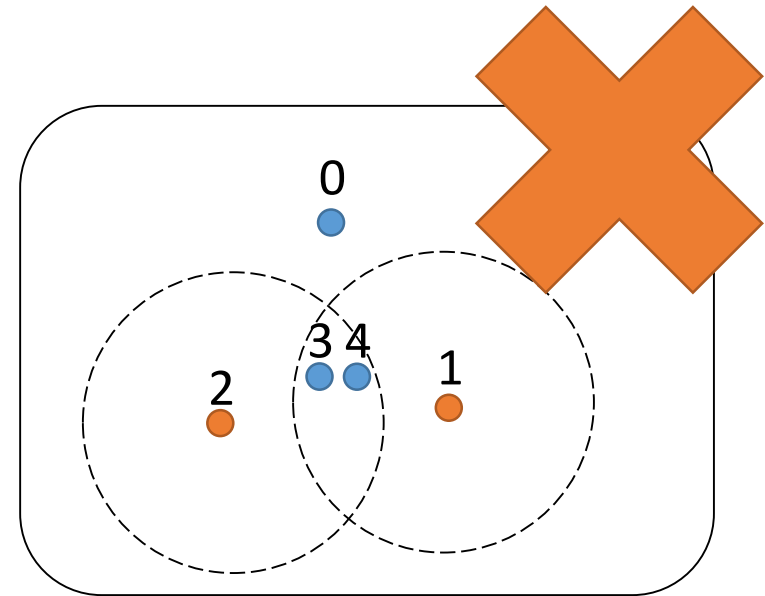


# System model

## ❖ Model description

### ❑ Fitness function

- The priority for this problem.
  - P1: Ensure that all *K* nodes are grouped



# System model

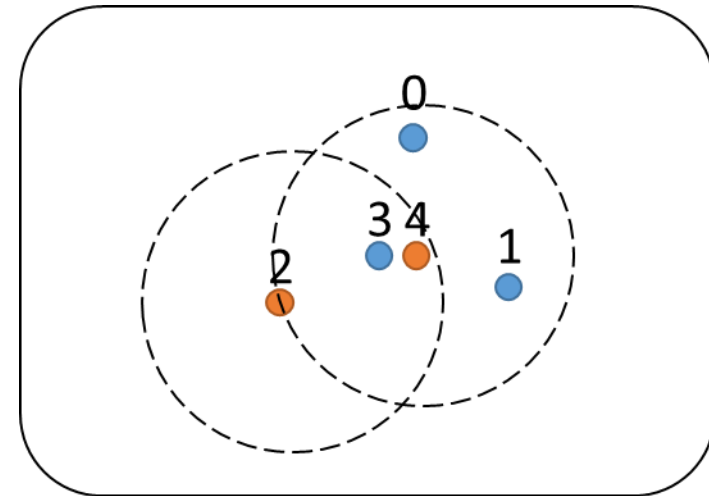
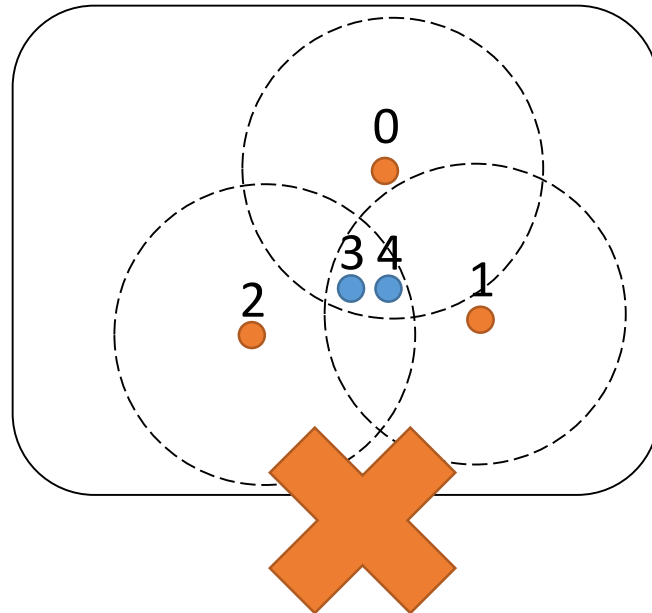
## ❖ Model description

### ❑ Fitness function

➤ The priority for this problem.

- P1: Ensure that all  $K$  nodes are grouped
- P2: Ensure that number of the generated clusters,  $N$ , is less than or equals to  $M$

When  $M = 2$



Okay !

# System model

## ❖ Model description

### □ Fitness function

➤ The priority for this problem.

- P1: Ensure that all  $K$  nodes are grouped
- P2: Ensure that number of the generated clusters,  $N$ , is less than  $M$
- P3: Minimize the number of clusters
- P4: Minimize the degree of overlap

} Constraints

# of ungrouped nodes

The set of clusters

$$fitness = \begin{cases} -error * K^3, & \text{if } error > 0 \\ -(|C| - M) * K^2, & \text{if } error == 0, |C| \geq M \\ -(|C| * K + O), & \text{if } error == 0, |C| < M \end{cases}$$

P1

P2

P3 & P4

The degree of overlap

```
# calculates the fitness
def calculateFitness(self, M):
    if self.error > 0:
        self.fitness = 0 - self.error * (K ** 3)
    elif self.num_cluster > M:
        self.fitness = (M - self.num_cluster) * (K ** 2)
    else:
        cluster_fit = self.num_cluster * K
        self.fitness = 0 - (cluster_fit + self.overlap)
```

# System model

## ❖ Problem formulation

$$\max_{C^*} \text{fitness} :$$

$$\text{fitness} = \begin{cases} -\text{error} * K^3, & \text{if error} > 0 & \text{P1} \\ -(|C| - M) * K^2, & \text{if error} == 0, |C| \geq M & \text{P2} \\ -(|C| * K + O), & \text{if error} == 0, |C| < M & \text{P3 \& P4} \end{cases}$$

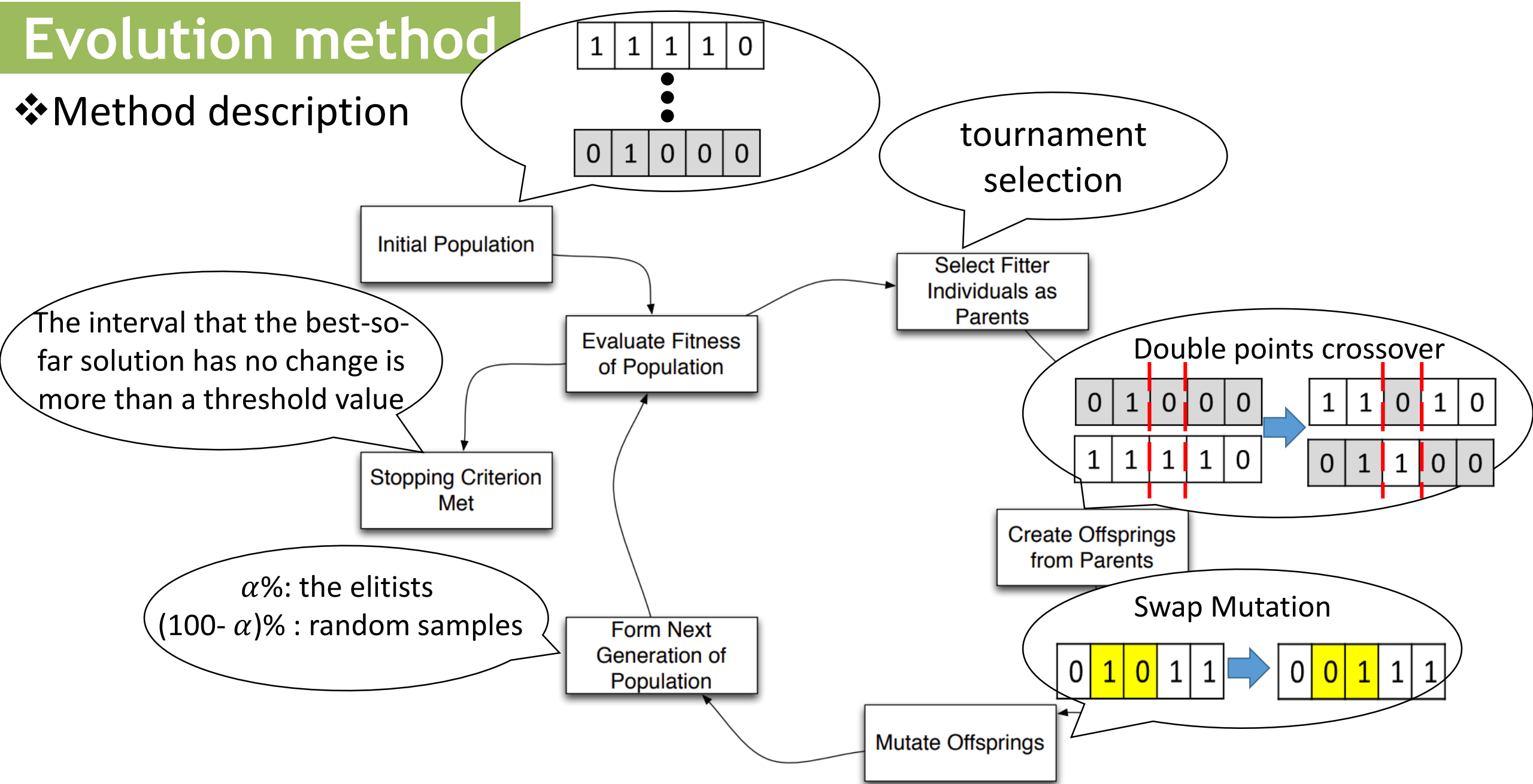
$$O = \sum_{n_j \in D} \sum_{c_i \in C} 1\{\|n_j - c_i\| \leq r\} - |\mathbf{D}| \quad \text{The degree of overlaps}$$

$$\text{error} = \sum_{n_j \in \text{Node}} 1 \left\{ \sum_{c_i \in C} 1\{\|n_j - c_i\| \leq r\} == 0 \right\} \quad \text{\# of ungrouped nodes}$$

The radius of the region defined by CH

# Evolution method

## ❖ Method description



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# Simulation result

## ❖ Parameter configuration

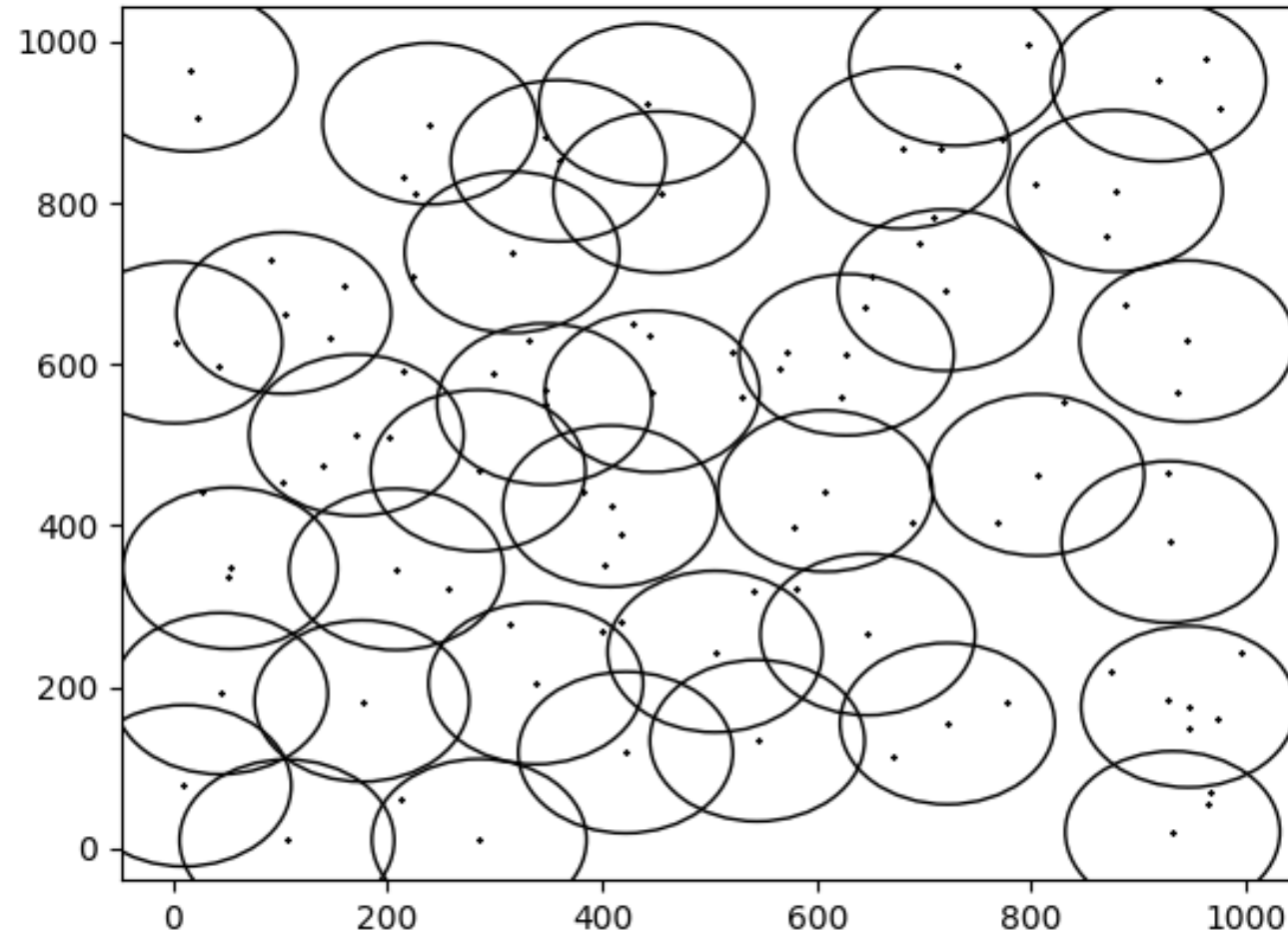
```
K = 100 # The number of nodes, cannot be change
M = 50 # The required number of cluster
a = 0.5 # alpha: the ratio of the elitist to the next generat
pro_mutation = 0.2 # The probability of executing mutation
size_pop = 1000 # The size of population for each generation
round_crossover = int(size_pop/4) # The rounds of crossover
r = 100 # The radius of cluster region
max_interval = 500 # The maximum interval between old and new
```

Parameters	Values	Notice or Range
The number of nodes	100	Should be fixed
The required number of clusters	50	1 ~ 100
-alpha	0.5	0 ~ 1
The probability of mutation	0.2	0 ~ 0.5
The size of population	1000	1000 ~
The rounds of crossover	250	250 ~ 1000
The radius of the region defined by each CH	100	Fixed
The threshold on the interval that best-so-far solution has no change	500	<b>200</b> ~ 1000 (empirical test)



# Simulation result

## ❖ Example of clustering result



# Simulation result

- ❖ To see the impact of probability of mutation (max\_interval = 200)
  - ❑ The mutation could more or less speed up the convergence process
  - ❑ No significant change in the fitness.

Probability of mutation	Result (running 20 times for the same initial pop)		
	average # of generation	average opt fitness	average time cost (second)
0 (Only crossover)	521.7	-3779.05	174.925
0.1	531.1	<b>-3776.6</b>	174.29375
0.2	512.1	-3794.35	157.1421875
0.3	509	-3794.05	152.21953125
0.4	548.7	-3783.8	162.134375
0.5	<b>503.75</b>	-3779.15	<b>134.6125</b>

# Simulation result

❖ To see the impact of alpha (max\_interval = 200)

❑ Elitists selection has a positive effect on finding a better fitness.

❑ Speed up the convergence process

alpha (The ratio of the elitists to the next generation of population)	Result (running 20 times for the same initial pop)		
	average # of generation	average opt fitness	average time cost (second)
0 (random selection)	779.25	-4197.65	421.65
0.2	579.05	-3794.75	197.26
0.4	554.4	-3789.2	168.8671875
0.6	<b>534.75</b>	-3794.15	155.59
0.8	537.35	-3798.8	<b>152.44</b>
1 (elitists selection)	540.35	<b>-3783.95</b>	152.58

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# Conclusion

## ❖ Combinatorial problem?

□ To check it

➤ Definition: Search an optimal solution from a finite solution space.

➤ Characteristic:

- In most cases, exhaustive search is not tractable.
  - ✓ The size of solution space:  $2^K$  (The # of possible  $K$ -bit binary digits)
- The domain of the problems is the discrete set of feasible solutions or can be reduced to discrete.
  - ✓ The size of feasible solution set is countable:  $\leq 2^K$
- The goal is to find the best solution
  - ✓ To minimize the number of clusters and the degree of overlap

# Conclusion

## ❖ Limitations of the design on the genetic algorithm

- ❑ The search space of cluster centers is based on cluster head election
  - Not continuous.
  - There is little possibility that the result is the global optima.

## ❖ Future work

- ❑ Develop the grid-based clustering method using genetic algorithm.
  - The search space could be larger.

*Thank  
you*

