

$$\text{OPENING } A \circ B = (A \ominus B) \oplus B$$

Erode then dilate.

Break narrow bridges, eliminate THIN STRUCTURES

but in some cases it won't work

$$\text{Closing } A \bullet B = (A \oplus B) \ominus B$$

Dilate, then Erode

fixes narrow breaks, eliminates small Holes

MatLab → Look back at circuit diagram

```
im=imread('bwcirc.tif')
```

```
b=strel('disk',1);
```

0	1	0
1	1	1
0	1	0

```
out1=imerode(im,b);
```

try

```
b=strel('disk',3);
```

out2=imopen(im,b); erosion by b, then dilation by b

it's better to use two steps → (1) eroion (2) dilation

too slow in some cases that's why
use first step instead of two -

(12)

$$B \oplus (B \ominus A) = B \ominus A$$

~~minima~~

$$b = \text{strel}('square', 2)$$

$$\text{out} = \text{imclose}(im, b);$$

~~13 dilation then erosion~~

→ Area is same but the Gaps are fixed

$$B \ominus (B \oplus A) = B \cdot A$$

~~Convol~~

44:30

binary finger print scan ~~minima~~ matt, static

~~left hand~~ ~~extremes~~ ~~ridges~~ ~~worm exrt~~

$$\text{imshow}(im)$$

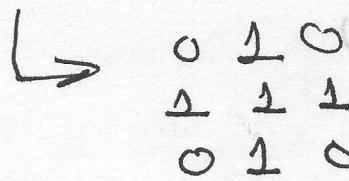
→ Picked White Snow

— between ridges

→ False Negative inside
actual print

→ erode then dilate → open image

$$b = \text{strel}('diamond', 1)$$

→ 

$$\text{out1} = \text{imclose}(im, b)$$

figure

$$\text{imshow}(\text{out1}) \rightarrow \text{outside noise is gone}$$

→ We are left with gaps in object
— want to bridge that Gap

~~(13)~~
b2 = strel('square', 3)

$$\begin{matrix} L & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{matrix}$$

$\{(2,2)\} \text{ tot } = 9$

$\{(9)\} \text{ center}$

Take result of previous guy then close that with strel b2.

out2 = imclose(out1, b2);

figure

imshow(out2) \rightarrow Lines are more connected

There are many combinations of erosion and dilation - e.g.,

Boundary Extraction: Take shape, code by pixel, subtract thinner shape from original

$$\partial A = A - A \ominus B$$

del shape
"Boundary"

im = imread('lowprofile.tif')

out = imclose(im, strel('disk', 1))

~~(X)~~ white pixels in original but not in erosion

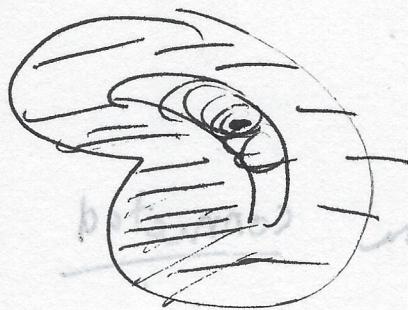
total \rightarrow no white pixels

(14)



$P = \text{xor } (\text{in}, \text{out})$
instead of p ;

filled fill / Hole fill



$$((Sd) \text{ ero}) \cup (Sd) = Sd$$



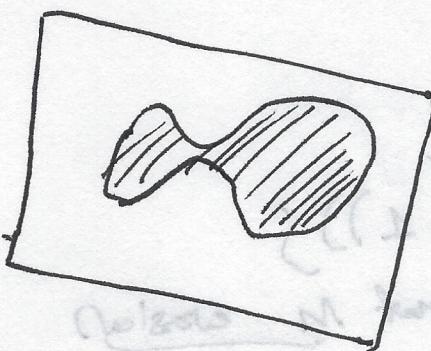
$$((Sd) \text{ dil}) \cup (Sd) = Sd$$

dilate the pixel as long
as you stay with the
region

do morphological \rightarrow list of binary operations

→ process b/w images
→ version applied to
gray scale images

One Application: Water shed Segmentation



Human sees Sd

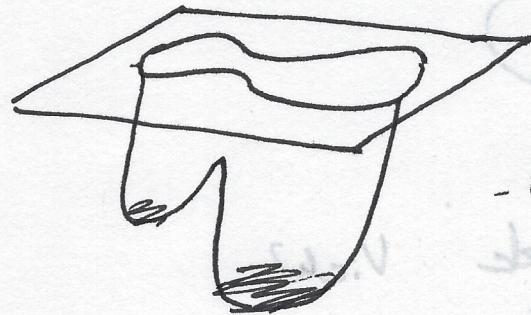
GrayScale Image

Darker spots on a bright
background

So: height map

(15)

Plot surface at pixel value

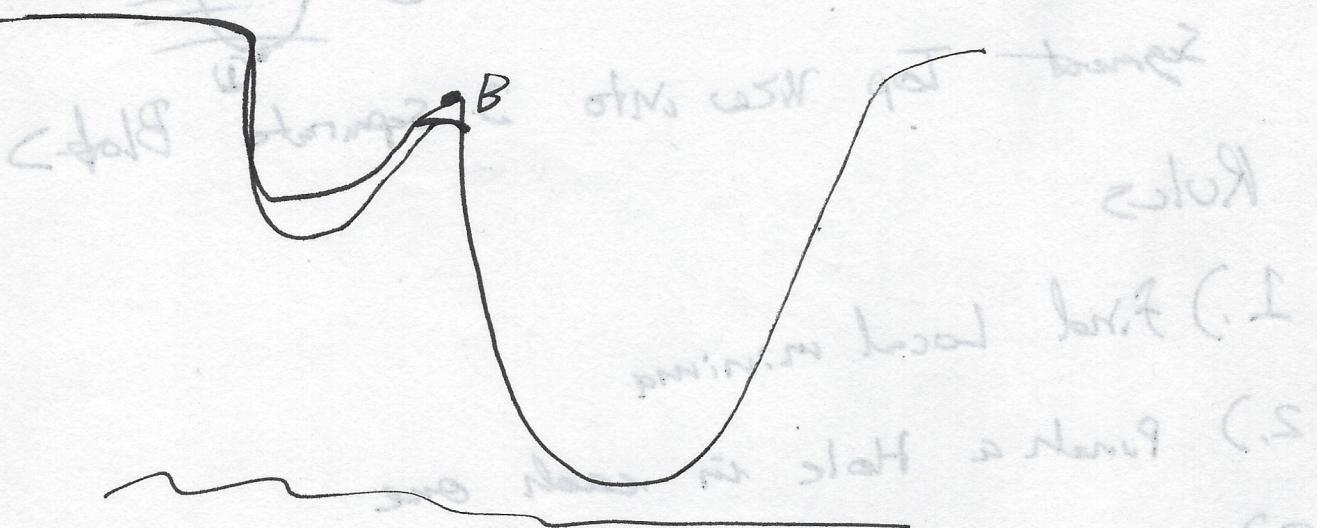


Think of this as a Height map.
Watershed \rightarrow how water might
flow around this 3D surface



2 Basins

where water would collect



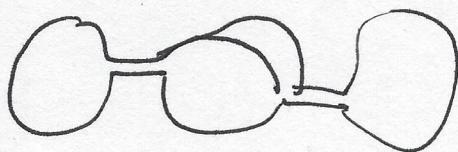
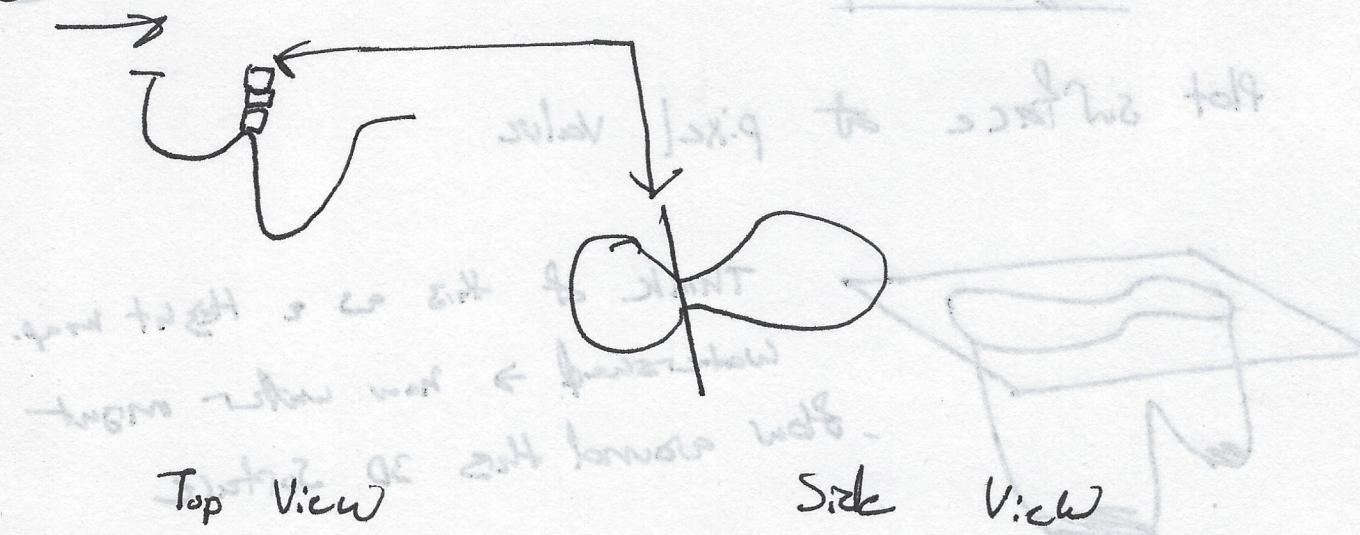
→ hits lower ~~Basin~~ first then eventually hits
2nd Basin then reaches a point where water
could go into either way.

→ Build a dam at that point to keep those
two things separate \rightarrow called water shed

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water shed

geom topog : S



Segment Top View into 3 separate Blobs

Rules

- 1.) find Local minima
- 2.) Punch a Hole in each one
- 3.) Start rising the water level from the bottom ~~one unit at a time.~~
- 4.) Keep track of which points are associated with each minima.

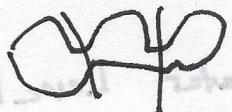
~~start out of holes first to make a block~~
~~keep holes holes ← storage capacity not~~

5.) At the moment two basins are about to merge, Build a single-Pixel-wide "DAM" to keep them separate.

We see, (2) and (1) will be separate after the first dam but not (3) and (2)

Yet

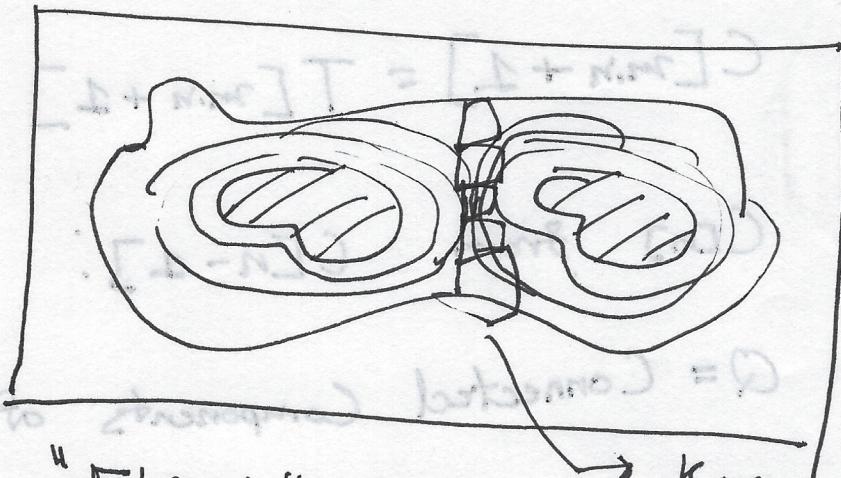
Top View



6.) After water has completely filled, dams produce desired segmentation.

2D IMPLEMENTATION

1:05:30



"FLOOD" AT Time n $I(x,y) \leftarrow n$

Keep building DAM To Keep These Separate.

Adding water is like Dilating a binary image of the basin locations

(18)

Algorithm:

LET M_1, \dots, M_R BE THE Coordinates
 at the Local minima of some Image $g(x,y)$
 m,n, \max BE $\min(g)$
 $\max(g)$

$$\text{LET } T[n] = \{ (x,y) \mid g(x,y) < n \}$$

The points below water Level n .

$C_n(M_i)$ = SET of Points in catchment
 Basin of M_i AT Time n .

$$C[n] = \bigcup_{i=1}^R C_n(M_i)$$

Initialize

$$C[m,n+1] = T[m,n+1]$$

$C[n]$ from $C[n-1]$:

To Compute

Q = Connected Components of $T[n]$

1) LET

2) For Each $q \in Q$, There are 3
 possibilities

~~The~~ possibilities

~~19~~ (19)

a) $q \cap [n-1] = \emptyset$

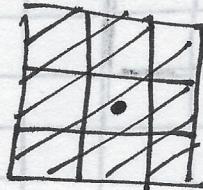
START A NEW Basin (New minima)

b) $q \cap [n-1]$ contains one connected component of $[n-1]$ (Add to Basin)

c) $q \cap [n-1]$ contains more than one element of $[n-1]$ (Build a DAM)

DAM-Building : Based on Morphological Operations (Dilate)

e.g Let $B = \text{Struct}$



SUCCESSIVELY Dilate Each $[n-1](M_i)$

By B , only consider points in q

if Dilation would cause merging,

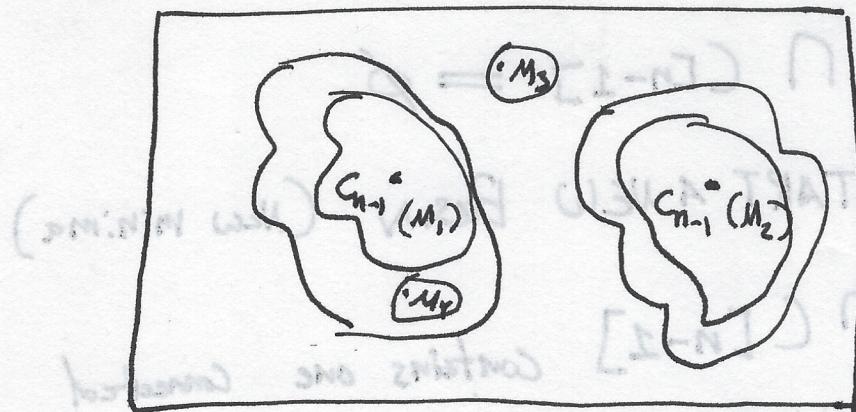
Build a DAM AT That Pixel

(20)

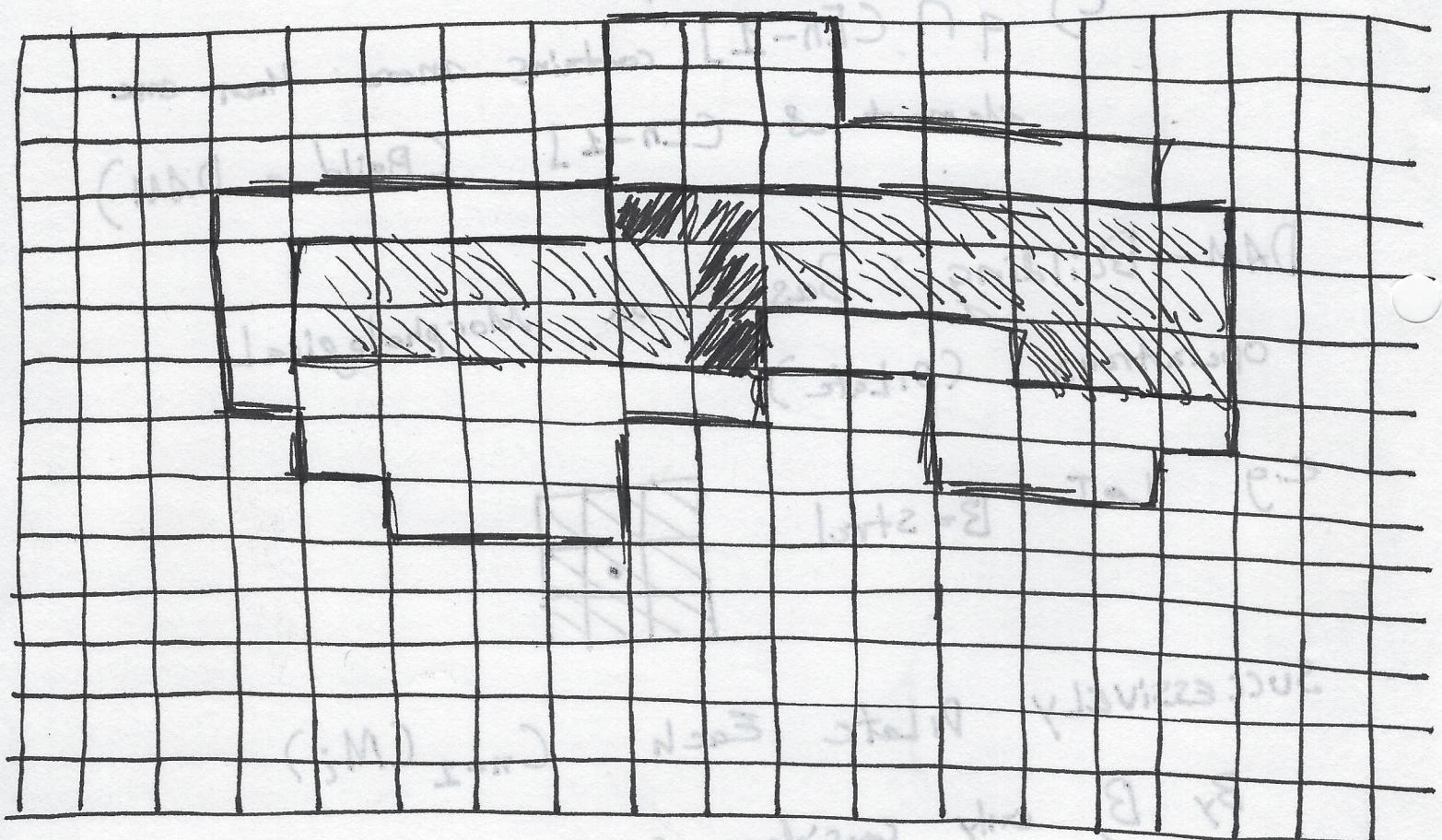
$C_{[n-1]}$

~~sufficiently SH~~

(P1)



(view of M_1) $[2-n]$ To triangulate



For some reason, it

is difficult to make a

good test to make a