

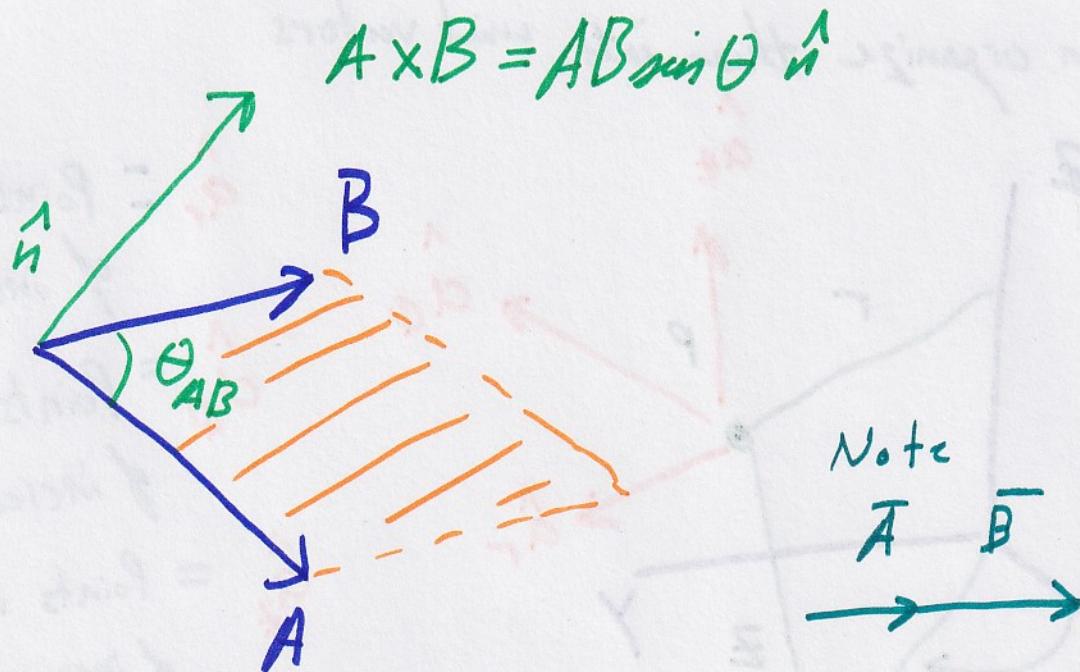
1

Fields and Waves I L9 part II

Vectors Curl Divergence

Cartesian coordinates Cross product

$$\bar{A} \times \bar{B} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$



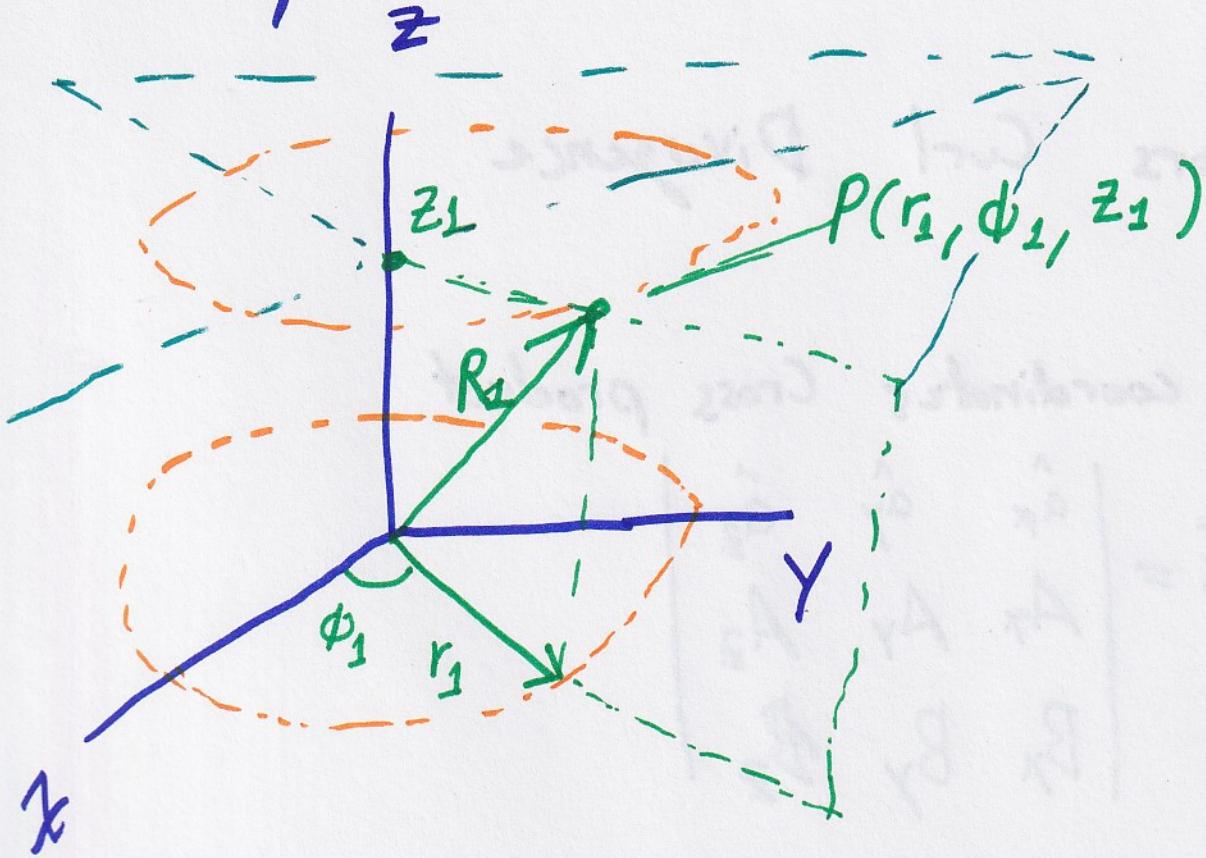
Note
 \bar{A} \bar{B}

$$A \times B = 0$$

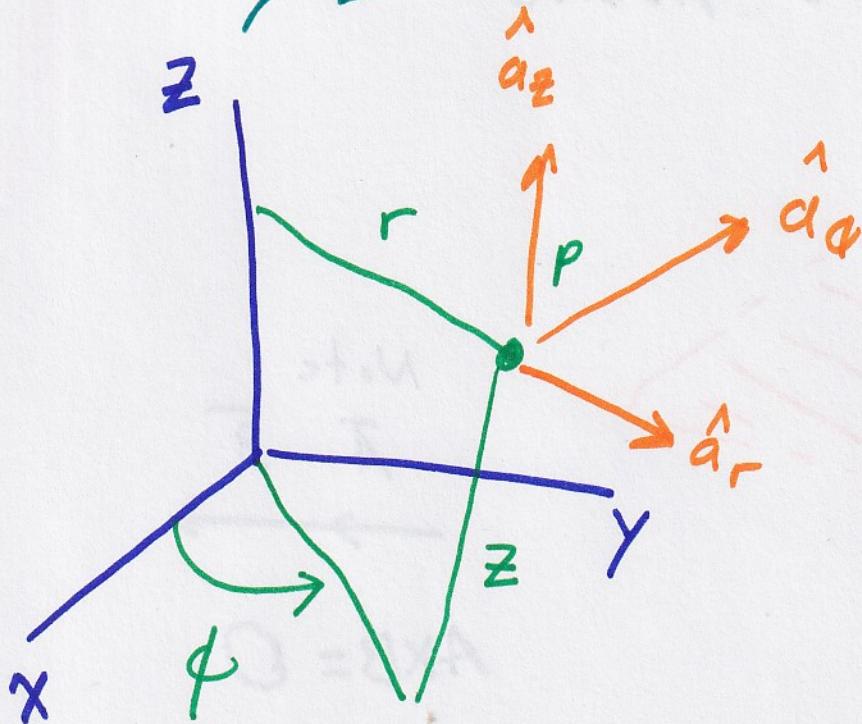
(cuz of the $\sin 0$)

2

Recall from part I, Cylindrical coordinates



we can organize these into unit vectors



\hat{a}_r = Points in direction of increasing r
 \hat{a}_ϕ = Points in direction of increasing ϕ
 \hat{a}_z = Points in direction of increasing z

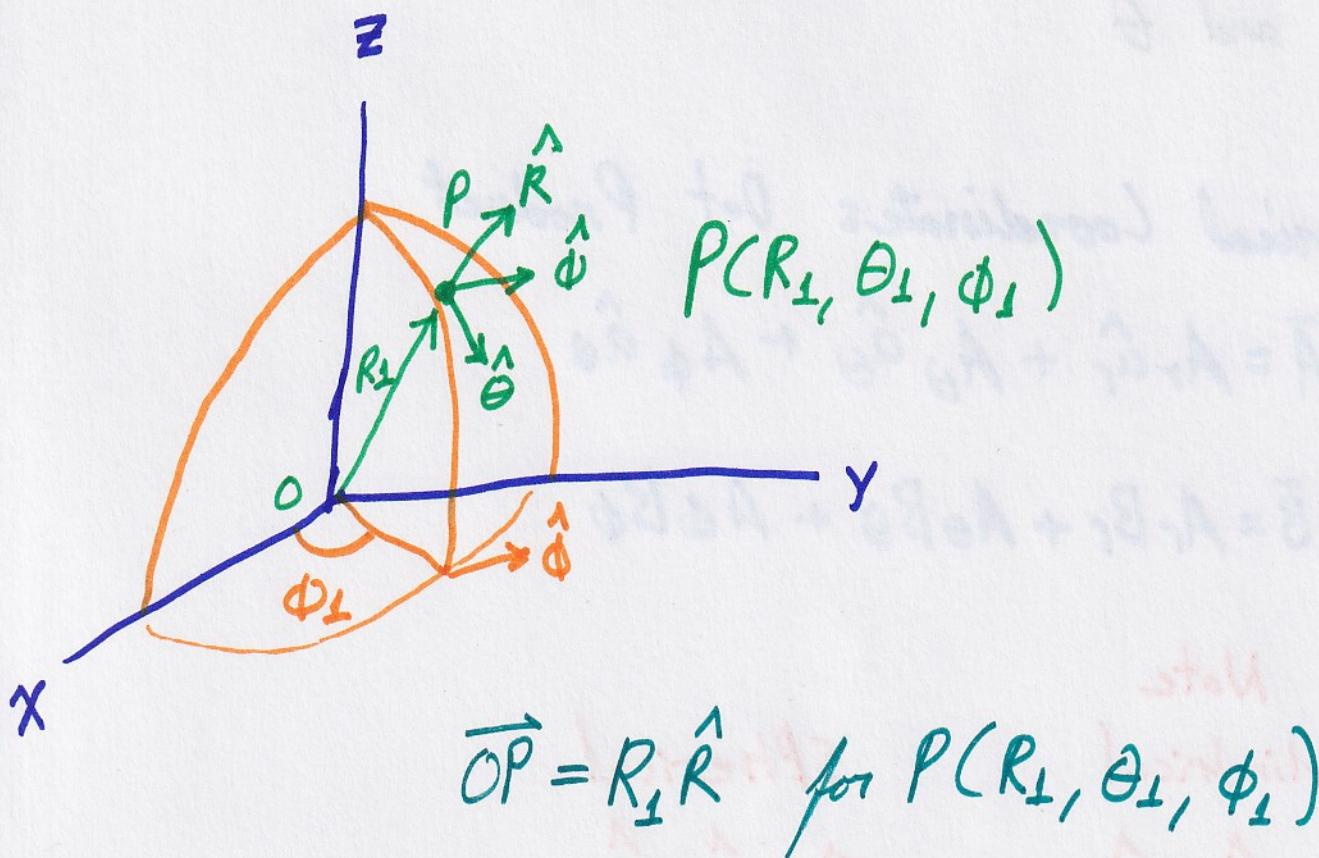
In cylindrical coordinates, both \hat{a}_r and \hat{a}_ϕ are functions of ϕ

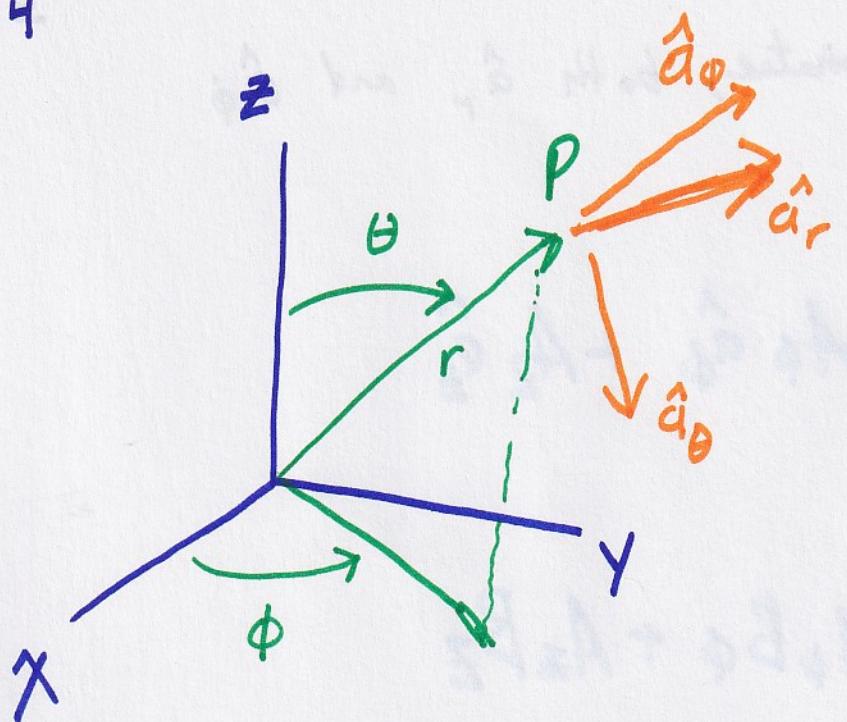
And for $\bar{A} = A_r \hat{a}_r + A_\phi \hat{a}_\phi + A_z \hat{a}_z$

we can see that

$$\bar{A} \cdot \bar{B} = A_r B_r + A_\phi B_\phi + A_z B_z$$

Look at Spherical coordinates





\hat{a}_r = Points in the direction of increasing r

\hat{a}_θ = Points in the direction of increasing θ

\hat{a}_ϕ = Points in the direction of increasing ϕ

In spherical coordinates, \hat{a}_r , \hat{a}_θ , and \hat{a}_ϕ are functions of ϕ and θ

Spherical Coordinates Dot Product

$$\bar{A} = A_r \hat{a}_r + A_\theta \hat{a}_\theta + A_\phi \hat{a}_\phi$$

$$\bar{A} \cdot \bar{B} = A_r B_r + A_\theta B_\theta + A_\phi B_\phi$$

Note

Cylindrical

$\hat{a}_r \hat{a}_\theta \hat{a}_z$

Spherical

$\hat{a}_r \hat{a}_\theta \hat{a}_\phi$

Example spherical coordinate systems

$$\bar{A} = r^3 \hat{a}_r + 4 \sin \theta \hat{a}_\phi$$

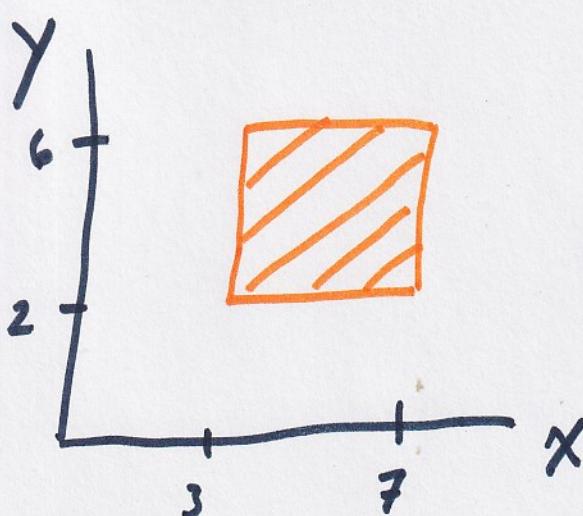
$$\bar{B} = 3 \hat{a}_r + 2 \hat{a}_\theta + \frac{12 \sin \theta}{r^3} \hat{a}_\phi$$

$$\bar{A} \cdot \bar{B} = r^3(3) + 0 \cdot 2 + \frac{(4)(12) \sin^2 \theta}{r^3}$$

$$\bar{A} \times \bar{B} = \begin{vmatrix} \hat{a}_r & \hat{a}_\theta & \hat{a}_\phi \\ r^3 & 0 & 4 \sin \theta \\ 3 & 2 & \frac{12 \sin \theta}{r^3} \end{vmatrix} = -8 \sin \theta \hat{a}_r - \left[12 \sin \theta - r^3 \frac{12 \sin \theta}{r^3} \right] (\hat{a}_\theta)$$

Differential calculus

Example



Length $\int_3^7 dx = x \Big|_3^7 = 7 - 3 = 4$

Area $\int_3^7 \int_2^6 dy dx = \int_3^7 4 dx = 4x \Big|_3^7 = 4(7 - 3) = 16$

6

This is integration over 2 'delta' distances

$$\rightarrow \frac{\square \Delta y}{\Delta x} \text{ or } \frac{\square dy}{dx}$$

Differential lengths

1.) Rectangular Coordinates

when you move a small amount in x -direction,
the distance is dx (Units in 'metres')

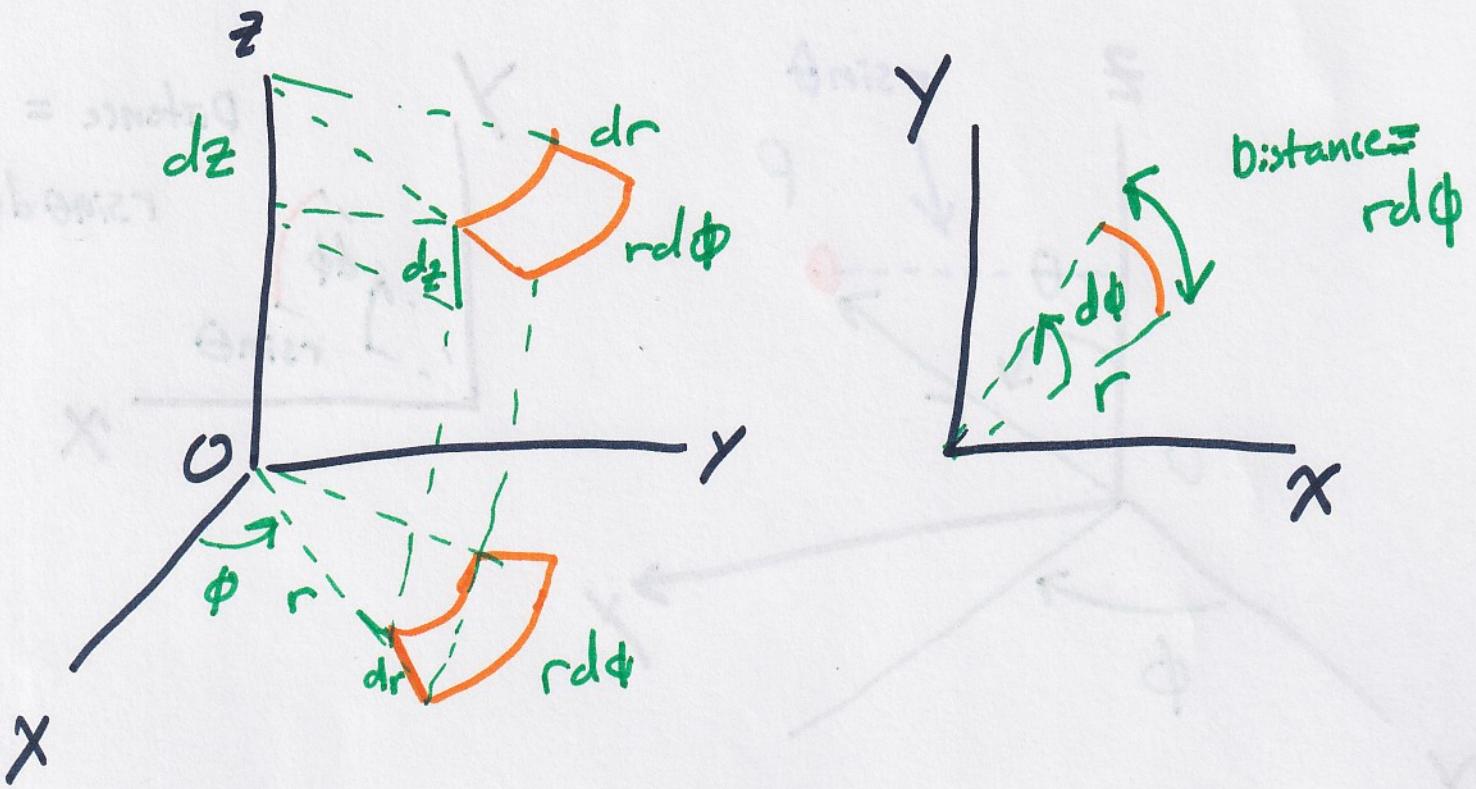
In a similar fashion we see that we can generate dy and dx

Differential Distances

(dx, dy, dz)

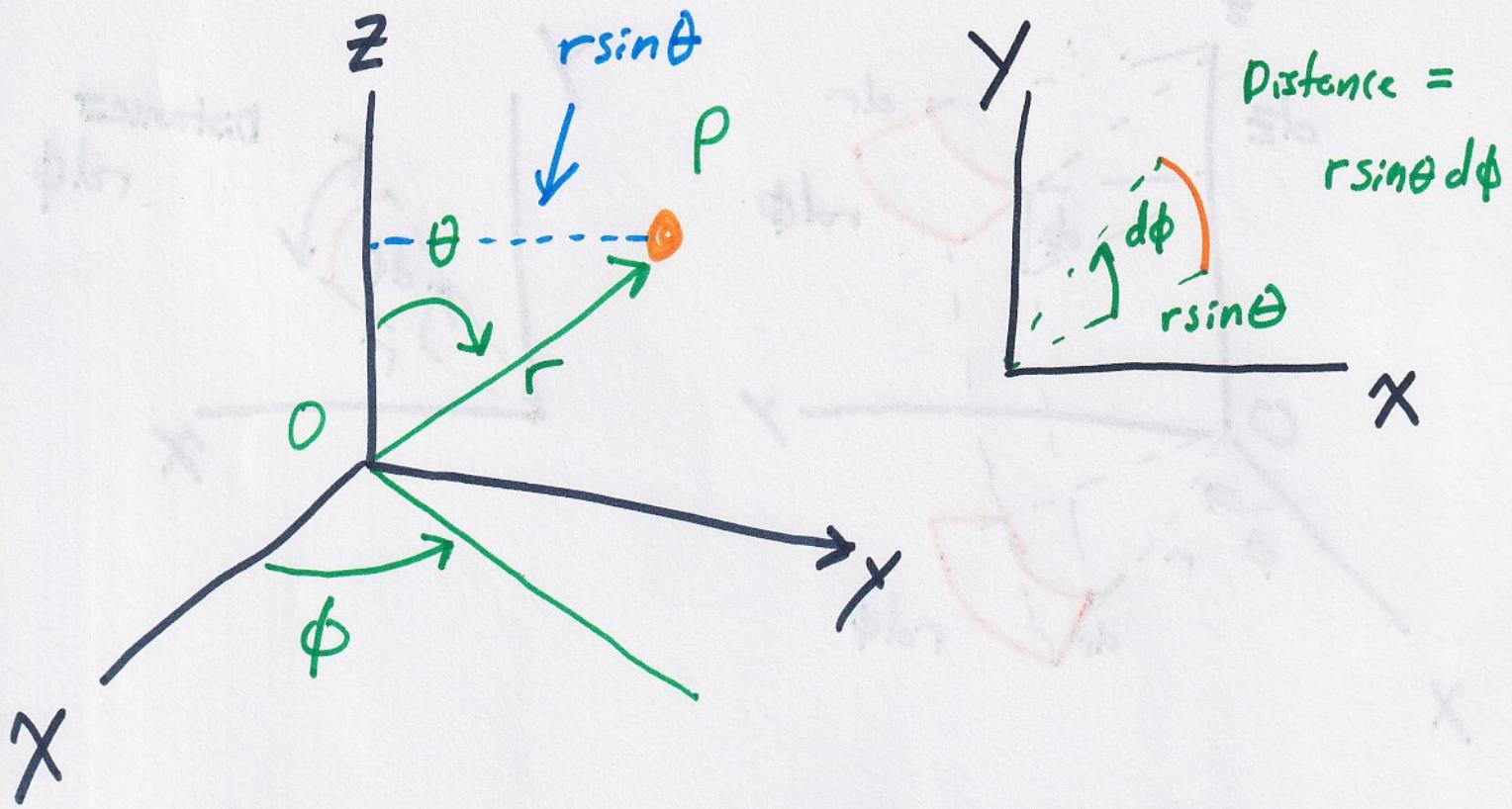


2. Cylindrical Coordinates



Differential distances
 $(dr, r d\phi, dz)$

3.) Spherical Coordinates



Differential Distances

$$(dr, r d\theta, r \sin \theta d\phi)$$

9

Representation of differential lengths ~~dL~~ in
the 3 coordinate systems $d\bar{l}$

rectangular

$$d\bar{l} = dx \cdot \hat{a}_x + dy \cdot \hat{a}_y + dz \cdot \hat{a}_z$$

cylindrical

$$d\bar{l} = dr \cdot \hat{a}_r + r \cdot d\phi \cdot \hat{a}_\phi + dz \cdot \hat{a}_z$$

spherical

$$d\bar{l} = dr \cdot \hat{a}_r + r \cdot d\theta \cdot \hat{a}_\theta + r \cdot \sin\theta \cdot d\phi \cdot \hat{a}_\phi$$

Differential surfaces and volumes

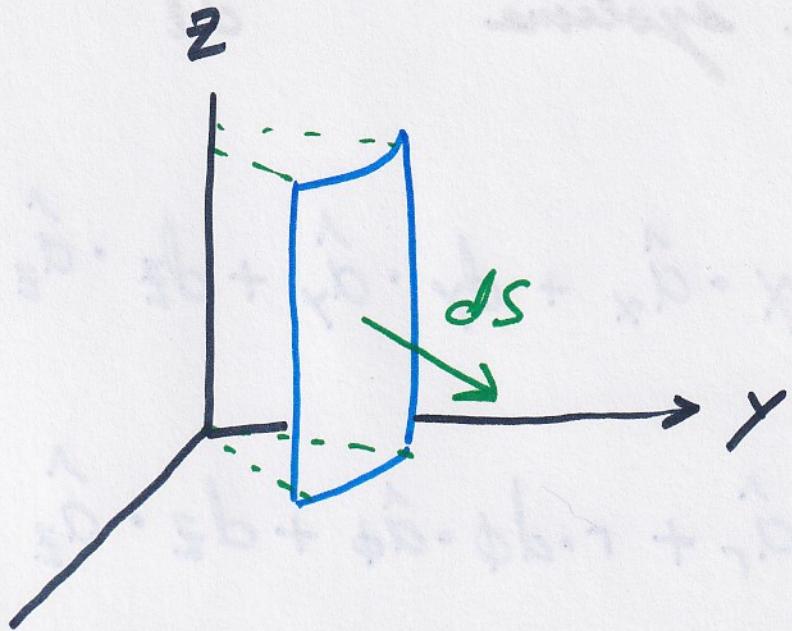
Example of surface differentials

$$ds = dx dy \hat{a}_z \quad \sigma \quad ds = rd\phi \cdot dz \hat{a}_r$$

So how do we set this up?

10

Representation of differential surface element

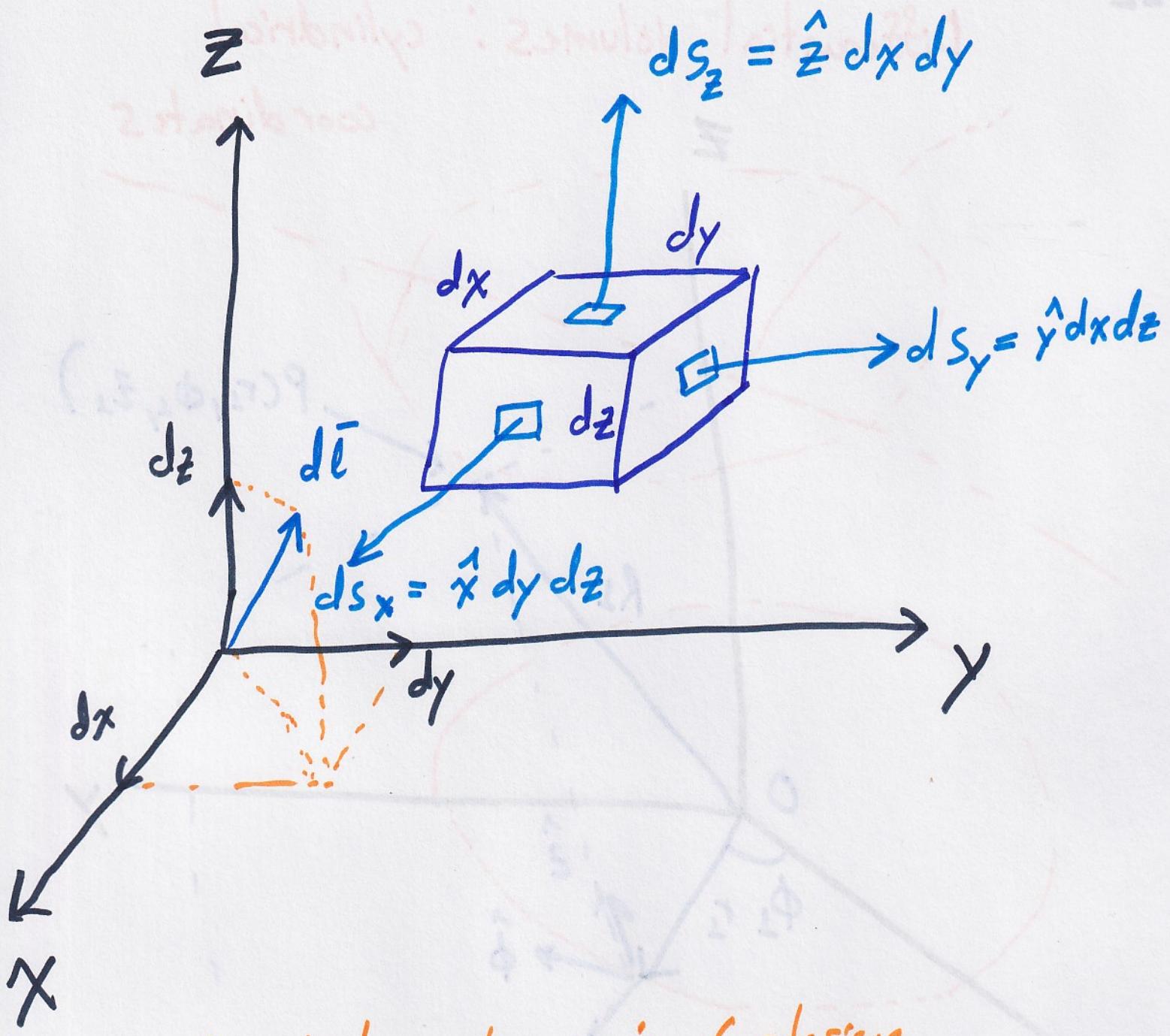


Vector is Normal to surface

$$ds = dx dy \hat{a}_z$$

Differential Volume (a scalar)

$$dV = dx dy dz$$

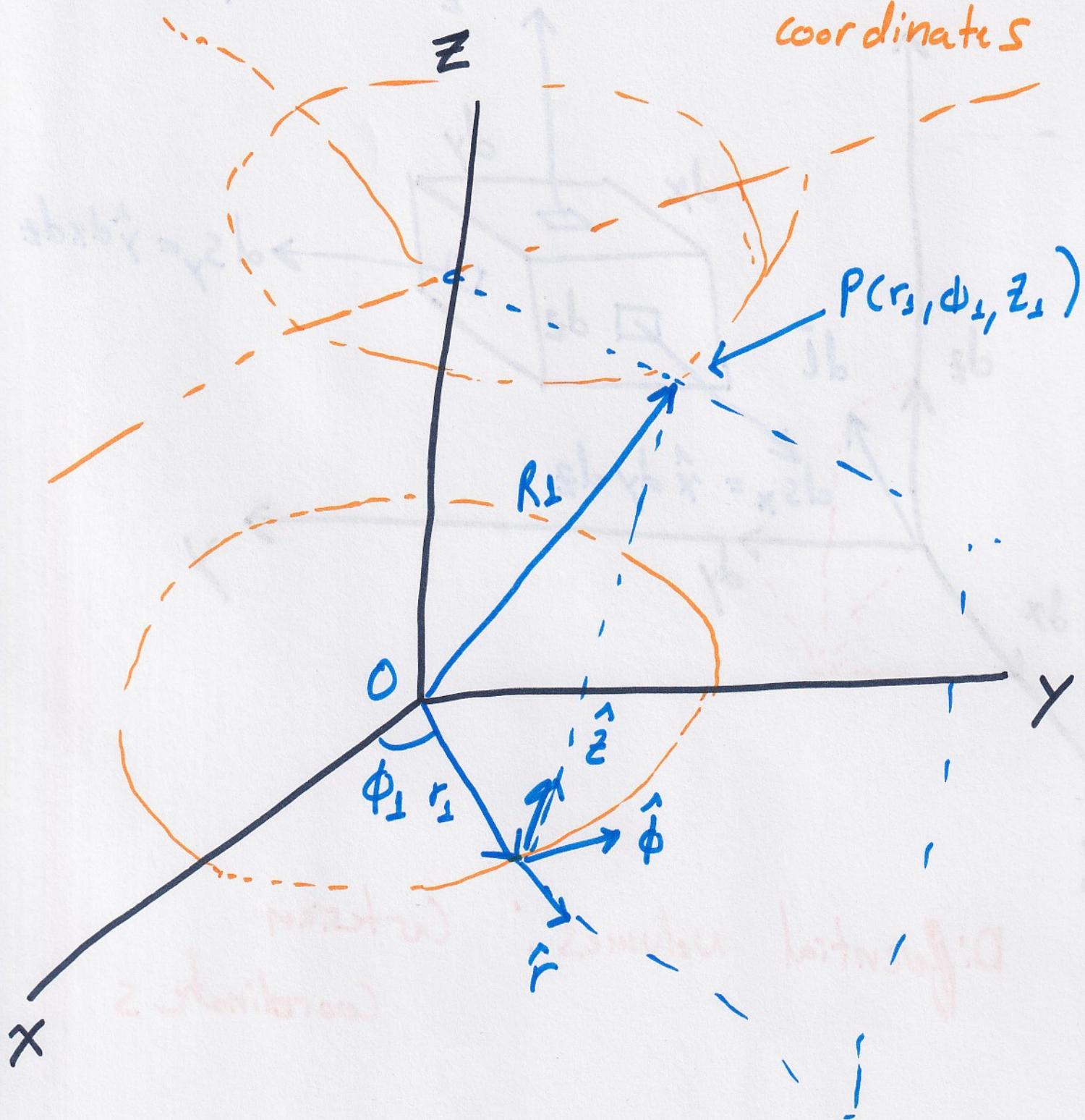


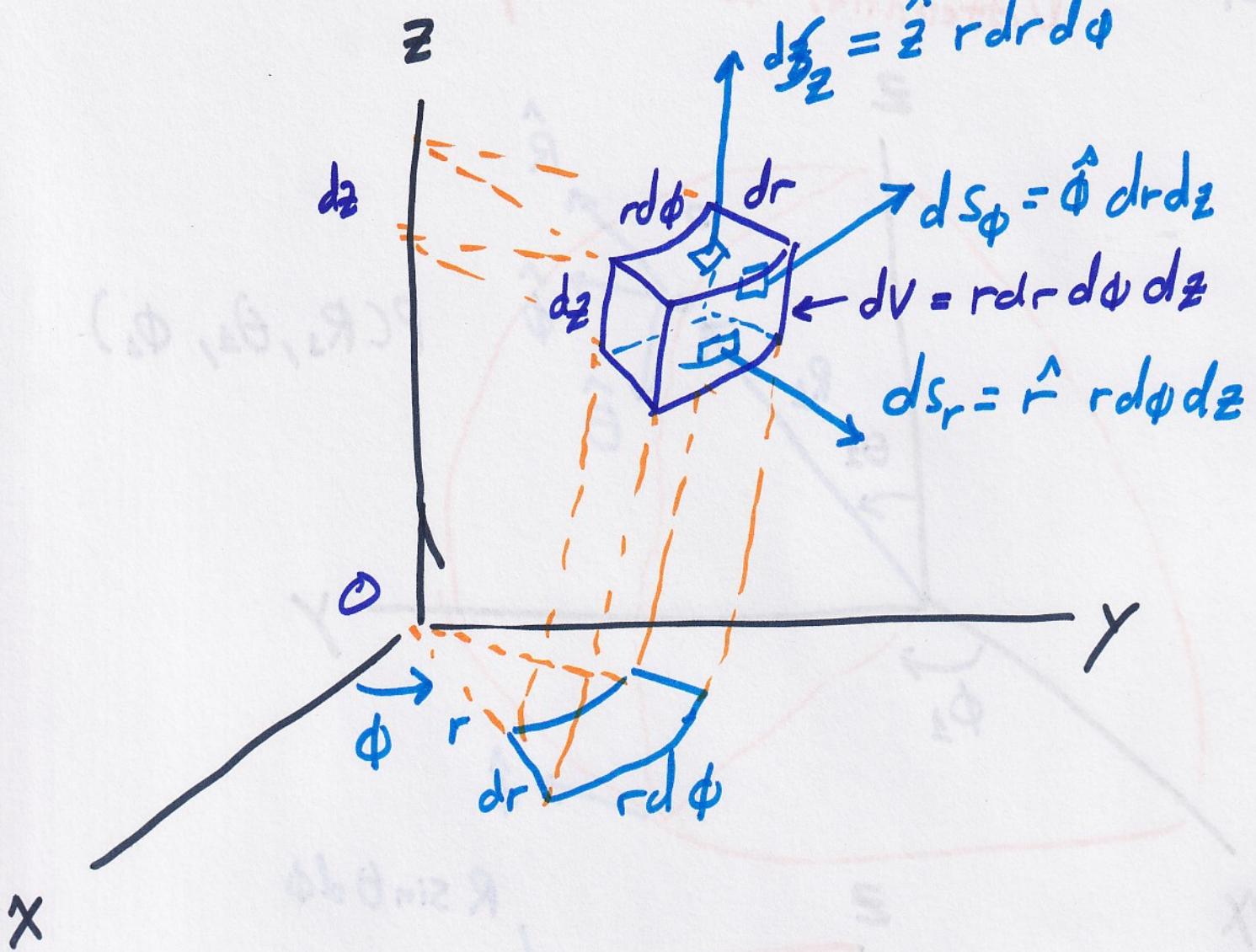
Differential volumes: Cartesian
Coordinates

12

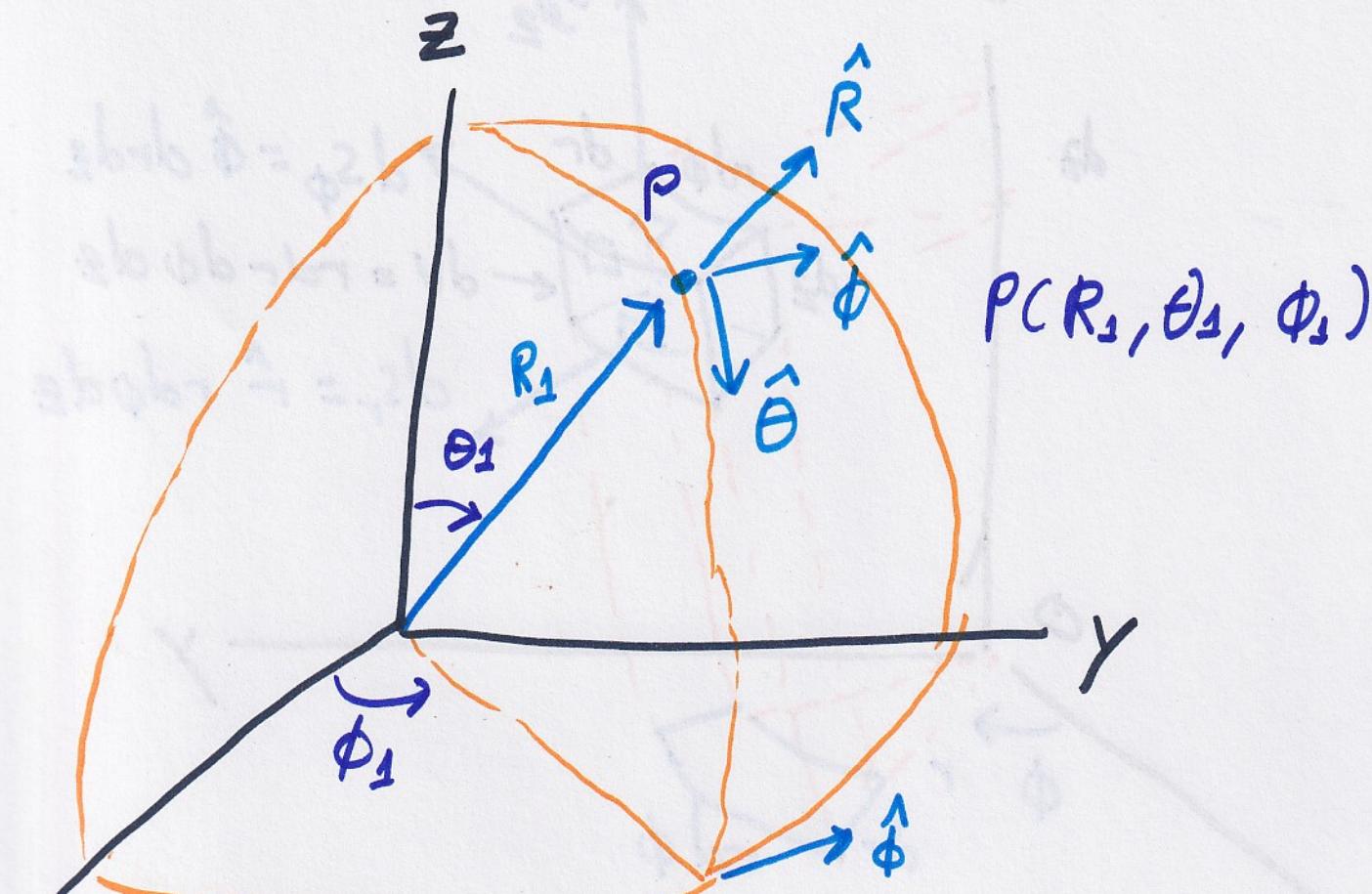
Differential volumes: cylindrical

coordinates

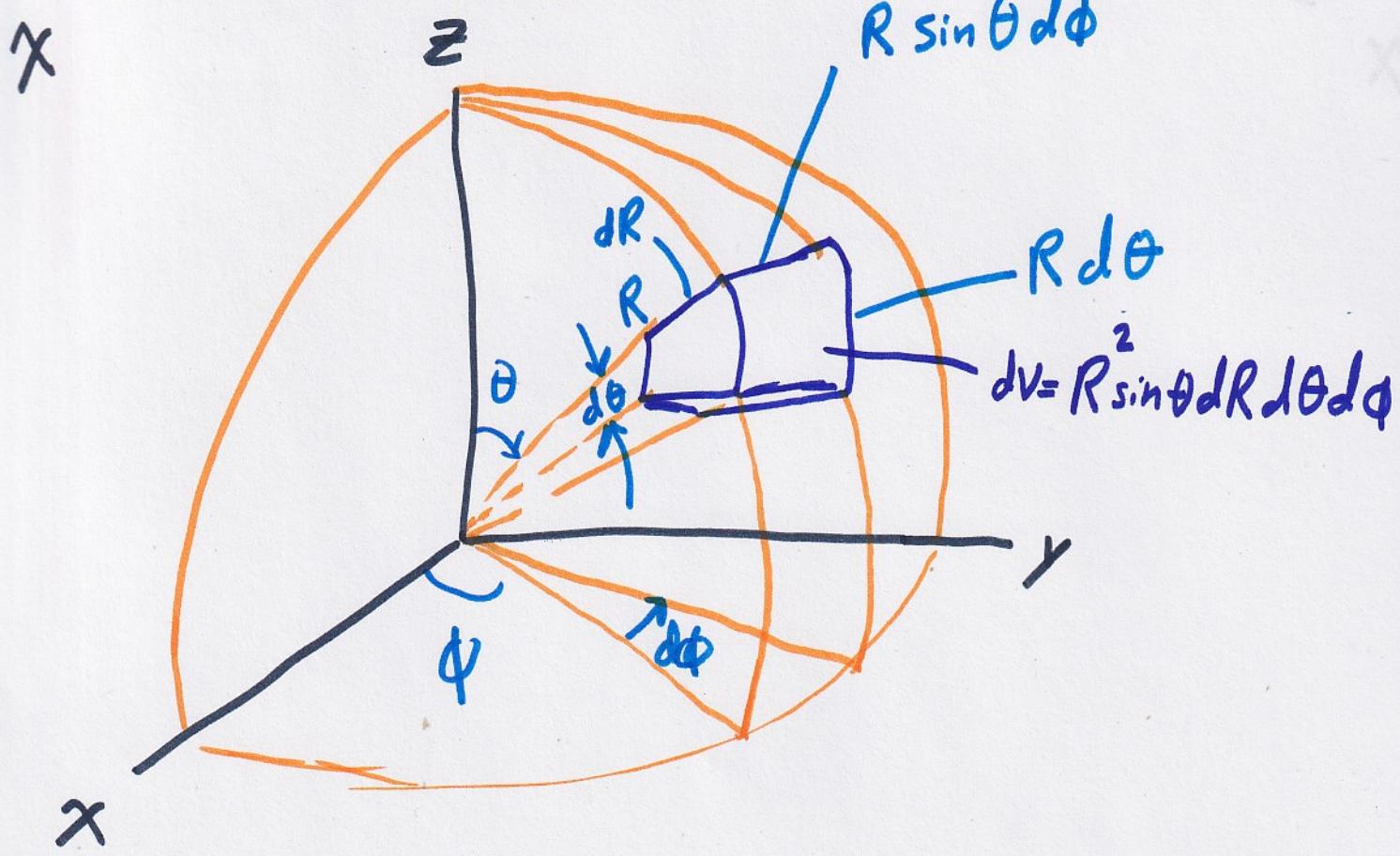




Differential volumes : spherical coordinates



$$P(R_s, \theta_s, \phi_s)$$



$$dV = R^2 \sin \theta dR d\theta d\phi$$

Integrals Calculations

15

Area calculus:

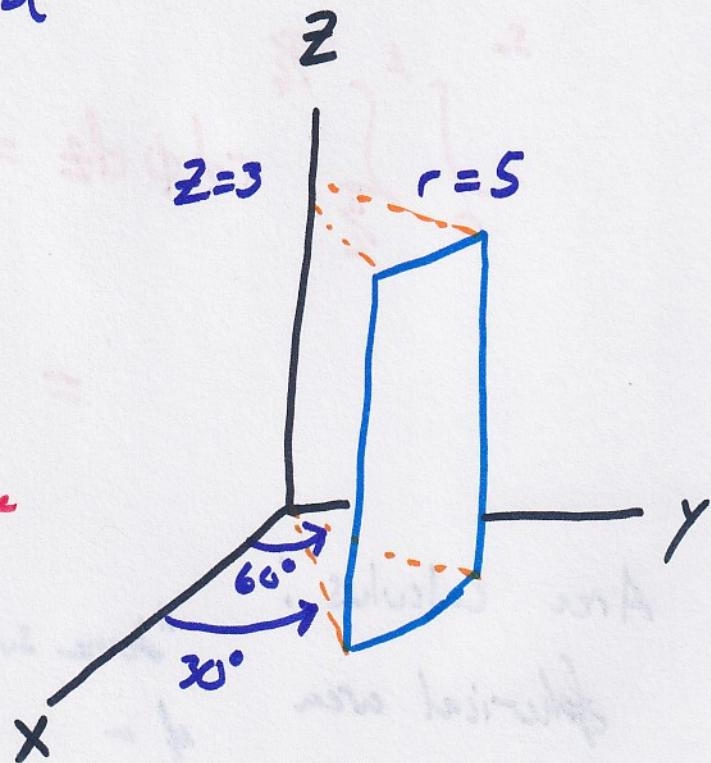
- find the following area

- Cylindrical area

$$- r=5, \quad 30^\circ \leq \phi \leq 60^\circ$$

$$0 \leq z \leq 3 \text{ cm}$$

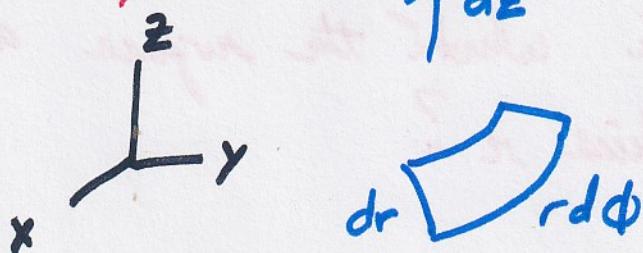
Basically, what's the surface area with radius r and length l .



So choose the normal to the surface

$$d\bar{s} = ds_r = \hat{r} r d\phi dz$$

Uc choose the normal (from the cylindrical coordinates)
because recall,



$$\begin{aligned} \text{Area} &\in L(w) \\ \text{so } &(rd\phi)(dz) \end{aligned}$$

16

so we set up the integral

$$30 \times \frac{\pi}{180} = \frac{\pi}{6}, \quad 60 \times \frac{\pi}{180} = \frac{2\pi}{6}$$

$$\int_0^r \int_{\frac{\pi}{6}}^{\frac{2\pi}{6}} r d\phi dz = r \left[\frac{2\pi}{6} - \frac{\pi}{6} \right] l = \frac{r\pi}{6} l$$

$$= \frac{(5)\pi}{6} (3) \text{ cm}^2$$

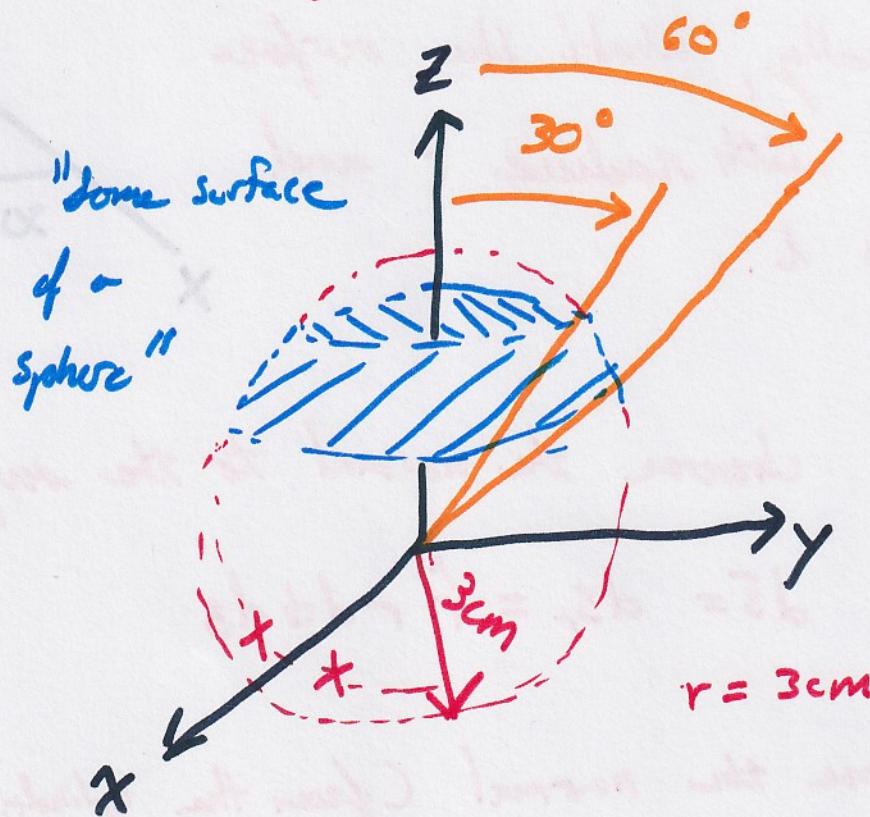
Area Calculus :

spherical area

$$30^\circ < \theta < 60^\circ$$

$$0 < \phi < 2\pi$$

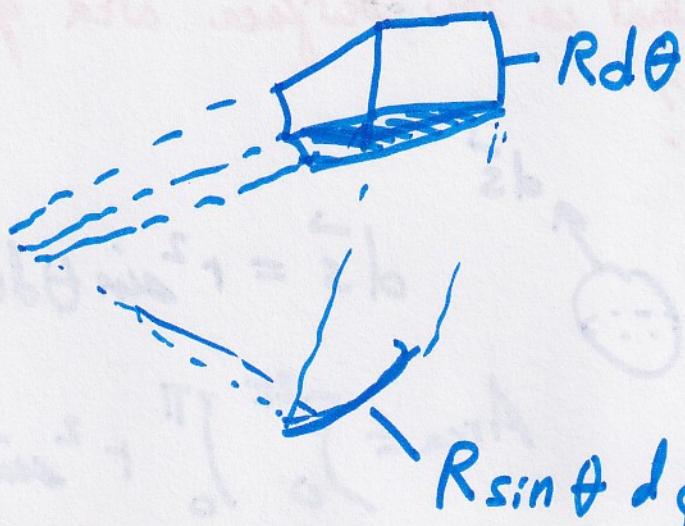
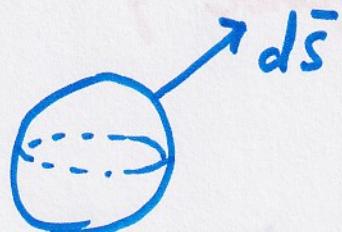
$$r = 3 \text{ cm}$$



So the question is what's the surface area of a sphere of radius r ?

The Idea

recall



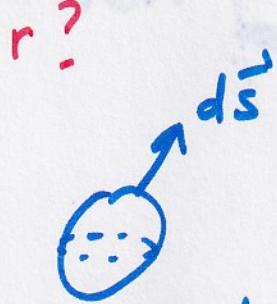
$$\text{so we can say } d\bar{s} = (R \sin \theta d\phi)(R d\theta) \hat{a}_r \\ = R^2 \sin \theta d\theta d\phi \hat{a}_r$$

↖ direction going outward

$$\begin{aligned} \text{Area} &= \int_{\phi} \int_{\theta} R^2 \sin \theta d\theta d\phi \\ &= \int_0^{2\pi} \int_{\frac{\pi}{6}}^{\frac{\pi}{3}} R^2 \sin \theta d\theta d\phi \\ &= \int_0^{2\pi} R^2 \left(-[\cos \frac{\pi}{3} - \cos \frac{\pi}{6}] \right) d\phi \\ &= R^2 (0.366) 2\pi = 9(0.366) 2\pi \text{ cm}^2 \end{aligned}$$

1F

a) What is the surface area of a sphere of radius r ?

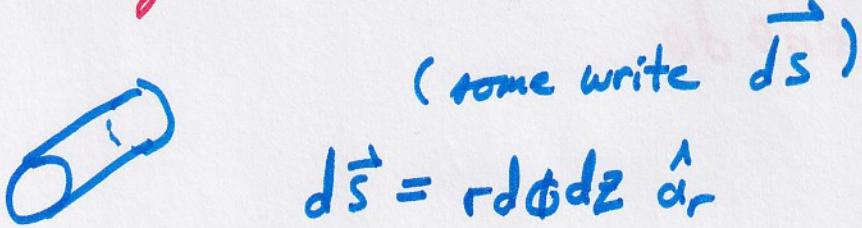


$$d\vec{s} = r^2 \sin\theta d\theta d\phi \hat{a}_r$$

$$\text{Area} = \int_0^{2\pi} \int_0^\pi r^2 \sin\theta d\theta d\phi$$

$$= r^2 \left(-\cos\theta \Big|_0^\pi \right) 2\pi = \underline{4\pi r^2}$$

b) What is the surface area of the side of a cylinder with radius r and length l ?



$$d\vec{s} = r d\phi dz \hat{a}_r$$

$$\text{Area} = \int_0^l \int_0^{2\pi} r d\phi dz = r 2\pi l$$

c) What is the volume of a sphere of radius r ?

"Think" volume:

$$(R \sin\theta d\phi)(R d\theta)(dR)$$

from surface area

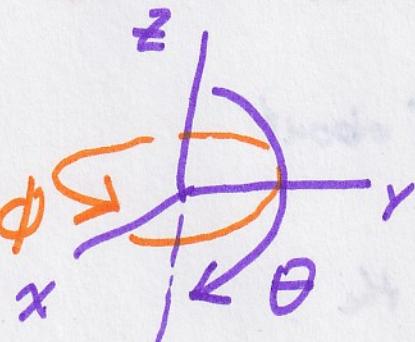
we are going outward from the origin to R (radius)

$$\text{Volume} = \int_0^{2\pi} \int_0^{\pi} \int_0^r r^2 \sin\theta dr d\theta d\phi$$

$$= \frac{r^3}{3} (-[-1-1]) 2\pi = \frac{4\pi}{3} r^3$$

1st we go out to radius

2nd we then integrate from +z axis to -z axis



3rd we integrate from x 360° to x again

20

d) What is the volume of a cylinder of radius r and length l ?

to

$$(r d\phi)(dz)(dr)$$

from surface area

we are going away from z to radius r

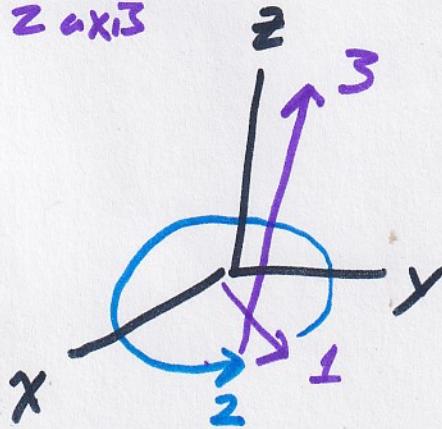
$$\text{to } dV = r dr d\phi dz$$

$$\text{Volume} = \int_0^l \int_0^{2\pi} \int_0^R r dr d\phi dz = \frac{R^2}{2} (2\pi) l = \pi R^2 l$$

1st, integrate from z axis to r

2nd Integrate 360° about the X axis

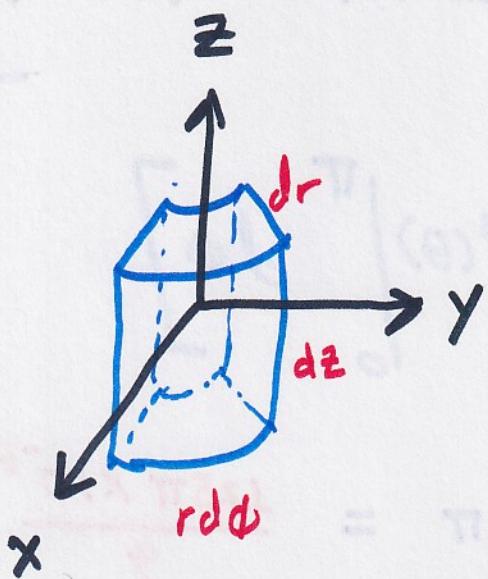
3rd Integrate along the z axis



Volume in cylindrical coordinates

What is the volume with boundaries

$$1 \leq r \leq 3, \quad 0 \leq \phi \leq \frac{\pi}{3}, \quad -2 \leq z \leq 2$$



$$\begin{aligned} \rightarrow \int dV &= \int_{-2}^2 \int_0^{\frac{\pi}{3}} \int_1^3 r dr d\phi dz \\ &= \frac{1}{2} [3^2 - 1^2] \left(\frac{\pi}{3}\right) [2 - (-2)] \\ &= \frac{16\pi}{3} \end{aligned}$$

The electric charge density inside a sphere is given by $4\cos^2(\theta)$. Find the total charge Q contained in a sphere of radius 2 cm.

$$\text{So recall } dV = r^2 \sin\theta dr d\theta d\phi$$

$$\text{recall density } \rho = \frac{m}{V} \text{ or for charge, } \rho = \frac{Q}{V}$$

But charge depends on the variable θ

\rightarrow So put $4\cos^2(\theta)$ in the integral

22

$$\int_0^{2\pi} \int_0^{\pi} \int_0^{0.02} 4(\cos^2(\theta)) r^3 \sin(\theta) dr d\theta d\phi$$

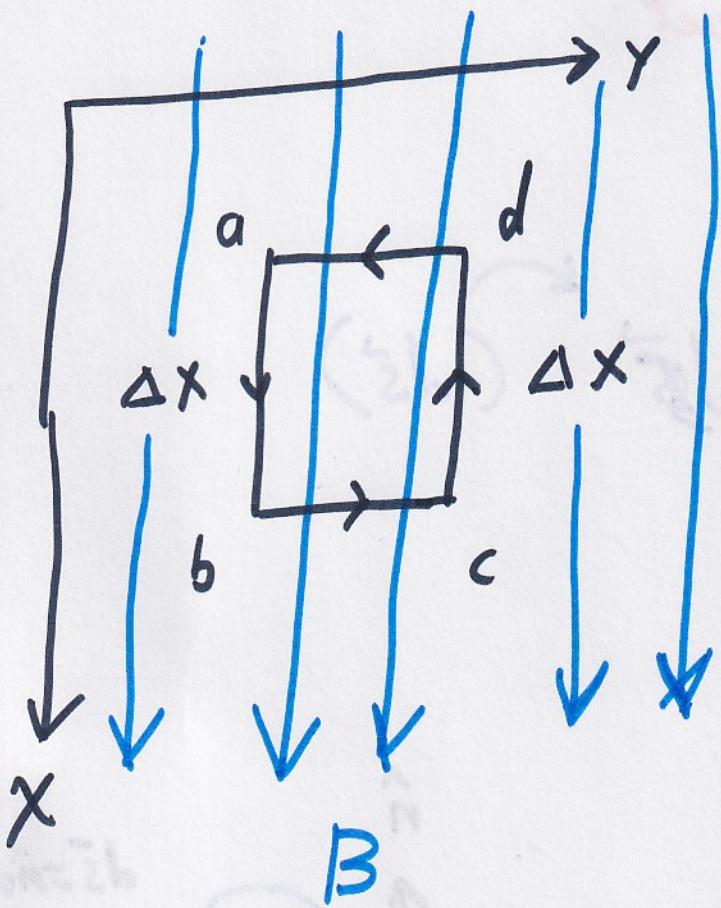
$$= 4 \frac{r^3}{3} \int_0^{0.02} \left[\int_0^{2\pi} \int_0^{\pi} \sin^2(\theta) \sin(\theta) d\theta d\phi \right]$$

$$= \frac{4}{3} [8 \times 10^{-6}] \left[\int_0^{2\pi} -\frac{\cos^3(\theta)}{3} \Big|_0^{\pi} d\phi \right]$$

$$= \frac{32 \times 10^{-6}}{3} \left[-\frac{(-1-1)}{3} \right] 2\pi = \frac{128\pi \times 10^{-6}}{9} C$$

The curl, gradient and divergence operators

Note: \oint implies a closed Loop integral



$\oint \vec{B} \cdot d\ell$ measures circulation or curl of B

Example of a uniform field B in the X direction

$$\text{Circulation} = \oint \vec{B} \cdot d\ell$$

$$\begin{aligned}
 &= \int_a^b B \hat{x} \cdot \hat{x} dx + \int_b^c B \hat{x} \cdot \hat{y} dy + \int_c^d B \hat{x} \cdot \hat{x} dx \\
 &+ \int_d^a B \hat{x} \cdot \hat{y} dy = 0
 \end{aligned}$$

The curl operator

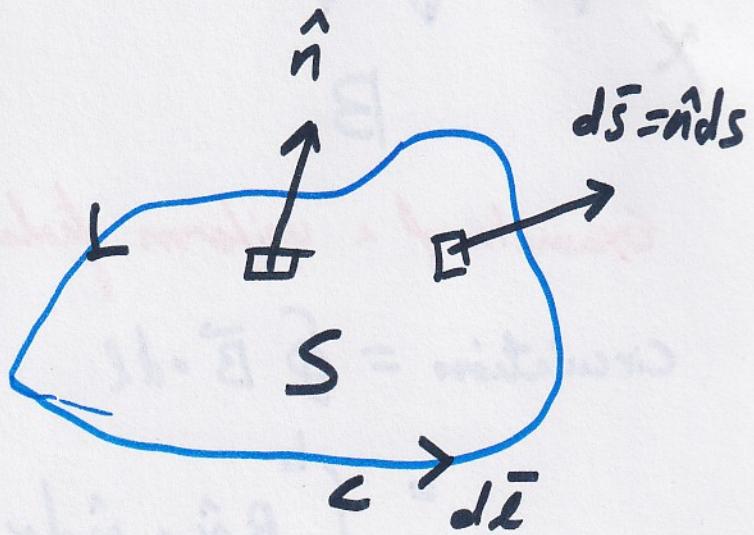
Note: $\nabla \times \vec{B}$ yields a vector

This phenomenon does not give a cross ~~product~~ product

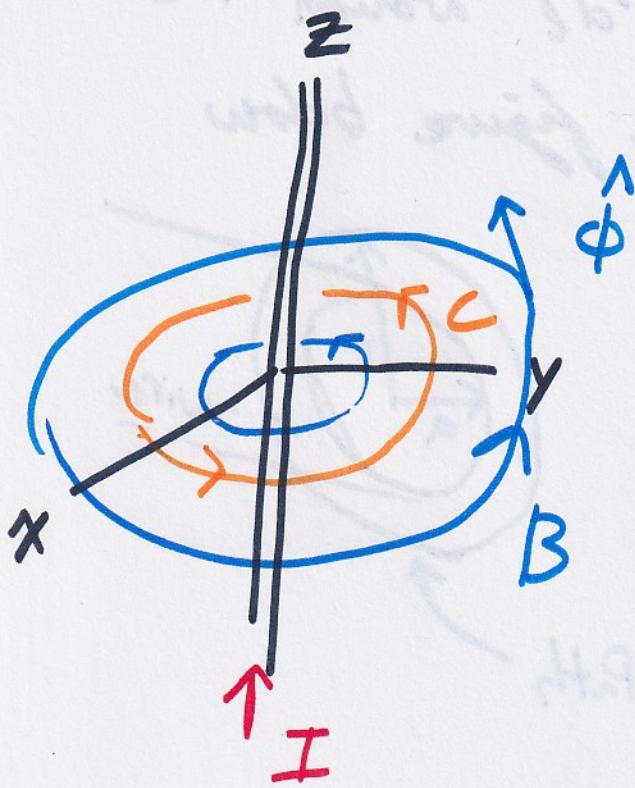
Stokes's Theorem

$$\oint \vec{B} \cdot d\vec{l} = \iint (\nabla \times \vec{B}) \cdot d\vec{S} \quad (d\vec{S})$$

This surface integral has its surface enclosed by the line on the LHS (Left hand side)



Current flow in a wire



we can write,

$$\nabla \times \vec{B} = \mu_0 J$$

(curl of \vec{B})

and

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I$$

Circulation

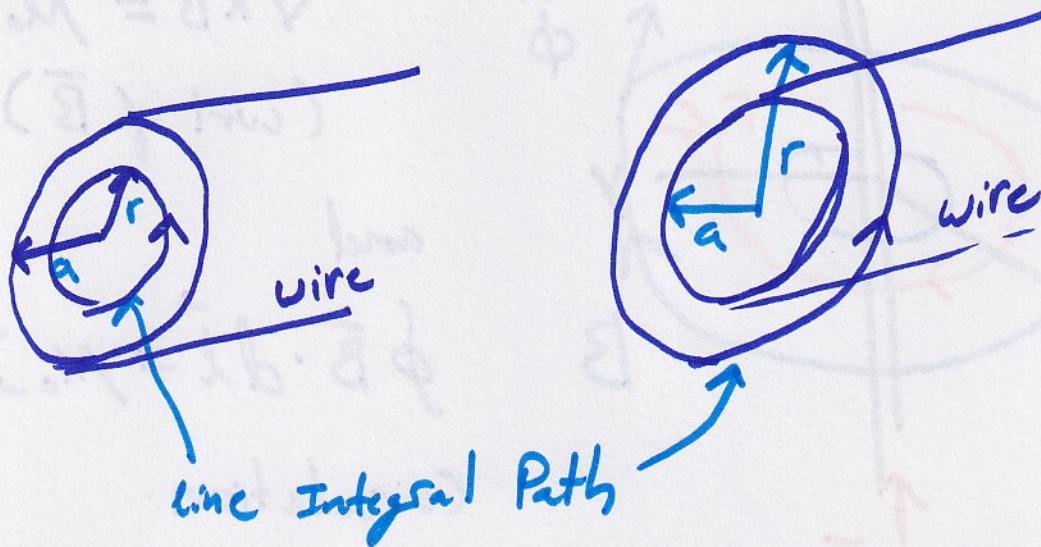
Rotation / curl operator Examples

The magnetic field of a straight wire of radius a which has a constant current density J_0 , is given by:

$$\vec{B} = \frac{\mu_0 J_0 r}{2} \hat{a}_\phi \quad r < a \quad (\text{inside the wire})$$

$$\vec{B} = \frac{\mu_0 J_0 a^2}{2r} \hat{a}_\phi \quad r > a \quad (\text{outside the wire})$$

a) Calculate $\oint \vec{B} \cdot d\vec{l}$ around the 2 paths shown in the figure below



for $r < a$

$$\begin{aligned}\oint \vec{B} \cdot d\vec{l} &= \int_0^{2\pi} B_\phi r d\phi = \int_0^{2\pi} \frac{\mu_0 J_0 r}{2} r d\phi \\ &= \frac{\mu_0 J_0 r^2}{2} 2\pi = \mu_0 J_0 \pi r^2\end{aligned}$$

for $r > a$

$$\oint \vec{B} \cdot d\vec{l} = \int_0^{2\pi} \frac{\mu_0 J_0 a^2}{2r} r d\phi = \mu_0 J_0 \pi a^2$$

b. Calculate $\nabla \times \vec{B}$ for both regions

$$\nabla \times \vec{B} = \frac{1}{r} \begin{vmatrix} \hat{a}_r & \hat{a}_\phi & \hat{a}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & rB & 0 \end{vmatrix} = \frac{1}{r} \left[\hat{a}_r \left(-\frac{\partial}{\partial z} rB \right) - \hat{a}_\phi (0) + \hat{a}_z \left(\frac{\partial}{\partial r} rB \right) \right]$$

$$= \frac{1}{r} \frac{\partial}{\partial r} r B \hat{a}_z$$

for $r < a$

$$\nabla \times \vec{B} = \frac{1}{r} \frac{\partial}{\partial r} r \frac{M_0 J_0 r}{2} \hat{a}_z$$

$$= \frac{M_0 J_0}{2r} \frac{\partial}{\partial r} r^2 \hat{a}_z = M_0 J_0 \hat{a}_z$$

for $r > a$

$$\nabla \times \vec{B} = \frac{1}{r} \frac{\partial}{\partial r} r \frac{M_0 J_0 a^2}{2r} \hat{a}_z = 0$$

28

Example

Calculate $\int \nabla \times \vec{B} \cdot d\vec{s}$ over the two shaded surfaces and compare to the previous result.

Now that we calculated $\nabla \times \vec{B}$, we can now use Stokes's Theorem to see that the result is the same as $\oint \vec{B} \cdot d\vec{L}$!

 $r < a$

$$\int \nabla \times \vec{B} \cdot d\vec{s} = \int_0^{2\pi} \int_0^R M_0 J_0 \hat{a}_z^1 \cdot r dr d\phi \hat{a}_z^1$$

$$= M_0 J_0 \frac{R^2}{2} \int_0^{2\pi} d\phi = M_0 J_0 \pi R^2$$

same as $\oint \vec{B} \cdot d\vec{s}$
for $r < a$

 $r > a$ we note that the loopencloses the surface with $r < a$ and $r > a$

so we are left with

$$\int \nabla \times \vec{B} \cdot d\vec{s} = \int_0^{2\pi} \int_0^a M_0 J_0 r dr d\phi + \int_0^{2\pi} \int_a^R 0 \cdot r dr d\phi$$

This is the $r > a$
contribution

so ultimately

$$= M_0 J_0 \pi a^2$$

we have stokes's theorem

$$\oint \vec{B} \cdot d\vec{l} = \int \nabla \times \vec{B} \cdot d\vec{s}$$

Gradient Operator

Gradient measures change in a scalar field

- result is a vector pointing in the direction of increase

Ex Cartesian System

$$\nabla f = \frac{\partial f}{\partial x} \cdot \hat{a}_x + \frac{\partial f}{\partial y} \cdot \hat{a}_y + \frac{\partial f}{\partial z} \cdot \hat{a}_z$$

Note $\nabla \times \nabla f = 0$ Always

If $F = \nabla f$, $\nabla \times F = 0$ & $\oint F \cdot d\ell = 0$
because of Stokes

30

Gradient examples

Compute the gradient of the following functions

a. $f = 8a^2 \cos\phi + 2rz$ (cylindrical)

$$\nabla f = \frac{\partial f}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial f}{\partial \phi} \hat{a}_\phi + \frac{\partial f}{\partial z} \hat{a}_z$$

$$= 2z \hat{a}_r + \frac{1}{r} (-8a^2 \sin\phi) \hat{a}_\phi + 2r \hat{a}_z$$

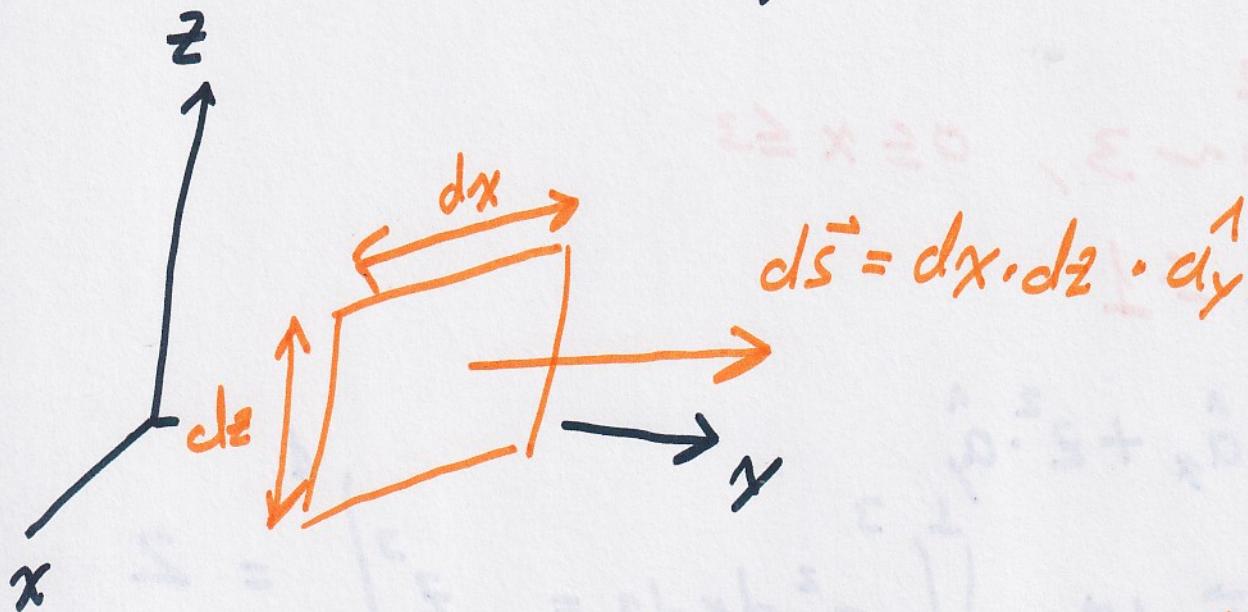
b. $f = \frac{a \cos 2\theta}{r}$ (spherical)

$$\nabla f = \frac{\partial f}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{a}_\theta + \frac{1}{r \sin\theta} \frac{\partial f}{\partial \phi} \hat{a}_\phi$$

$$= -a \cos 2\theta (r^{-2}) \hat{a}_r + \frac{1}{r} \frac{a}{r} (-2 \sin 2\theta) \hat{a}_\theta + 0$$

Surface Integrals

31



all 3 coordinates are involved

$\int \bar{A} \cdot d\bar{s}$ measures flux of A
through a surface

Example Fluid Flow

for $v \parallel d\bar{s}$, we have fluid flow
but $v \perp d\bar{s}$, no flow

Hence $v \cdot d\bar{s}$ measures flux

32

Example

$$y=2$$

$$x=0 \sim 3, 0 \leq x \leq 3$$

$$-1 \leq z \leq 1$$

$$\vec{A} = xy \cdot \hat{a}_x + z^2 \cdot \hat{a}_y$$

$$\text{to } \int \vec{A} \cdot d\vec{s} = \iint_{-1}^1 z^2 dx dz = \left. z^3 \right|_{-1}^1 = 2$$

we have the contribution from \hat{a}_y only

Understand... Divergence operator

$\int \vec{A} \cdot d\vec{s}$ measures flux thru any surface

$\oint \vec{A} \cdot d\vec{s}$ measures flux thru closed surfaces

$\nabla \cdot \vec{A}$ is a 'local' measure of flux
property

→ we will get a scalar

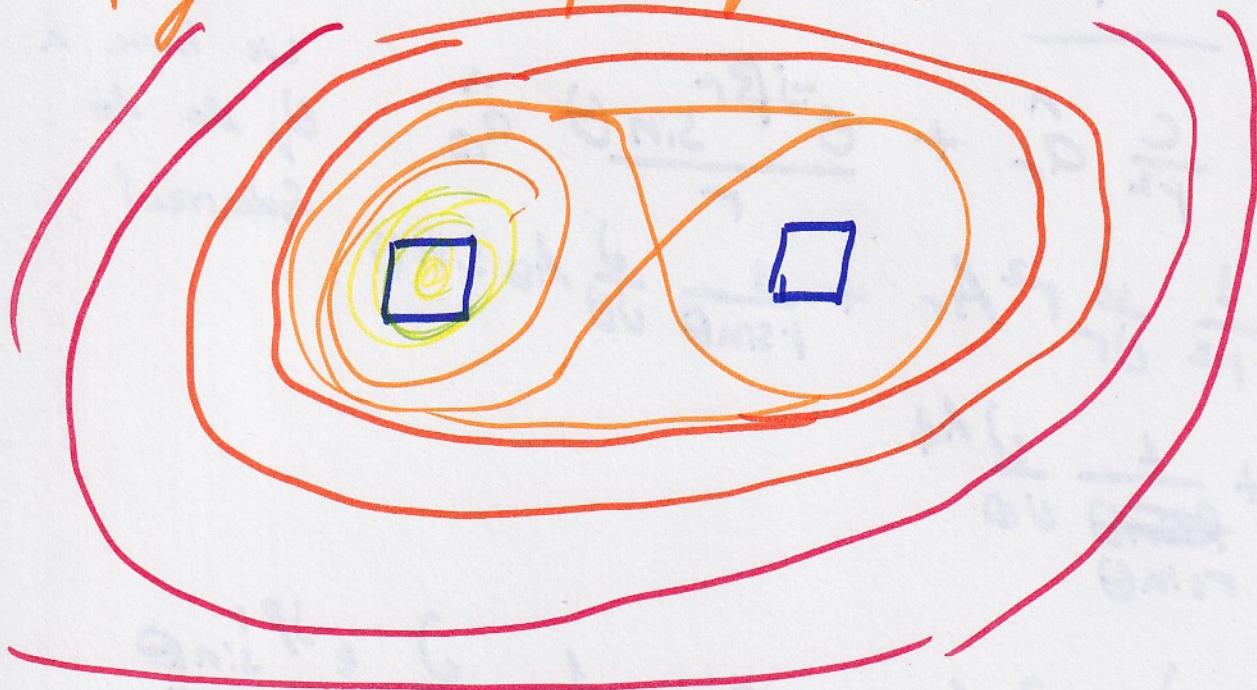
Divergence Divergence Theorem

$$\oint \vec{A} \cdot d\vec{s} = \int (\nabla \cdot \vec{A}) \cdot dV$$



Volume Integral on right (RHS)
is the volume enclosed by Surface on LHS

Physical Example of Divergence Operator



We have 2 chips, Temperatures in color

Integral heat flux through the surface of a chip

=

Amount of heat included in its Volume

calculate $\nabla \cdot \vec{A}$ for each of the vectors below

a) $\vec{A} = x^2y \hat{a}_x + c^2x \hat{a}_z$ c, β are constants

$$\nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$= \frac{\partial}{\partial x} x^2y + 0 + \frac{\partial}{\partial z} c^2x$$

$$= \underline{2xy}$$

b) $\vec{A} = \frac{c}{r^2} \hat{a}_r + \frac{e^{-j\beta r} \sin \theta}{r} \hat{a}_\theta$

We have a
 θ, ϕ to
 spherical

$$\nabla \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} r^2 A_r + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} A_\theta \sin \theta$$

$$+ \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} A_\phi$$

$$= \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{c}{r^2} + 0 + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \frac{e^{-j\beta r} \sin \theta}{r}$$

$$= 0$$

Summary

Curl $(\nabla \times \vec{B}) \rightarrow \text{Vector}$

Measures the circulation of a vector field

Gradient $\nabla f \rightarrow \text{Vector}$

Measures the change in a scalar field

Divergence $\nabla \cdot A \rightarrow \text{Scalar}$

Measures the flux of a vector field
through a surface