

Meeting #5

Solutions to Homogeneous Equations

Example what's the general solution

$$y'' + 5y' + 6y = 0$$

Assume $y = e^{rt}$ r must be a root of the characteristic equation

$$r^2 + 5r + 6 = (r+2)(r+3) = 0$$

$$r_1 = -2 \quad r_2 = -3$$

form of the general solution

$$y = c_1 e^{-2t} + c_2 e^{-3t}$$

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Example

$$y'' + 5y' + 6y = 0$$

$$y(0) = 2$$

$$y'(0) = 3$$

$$y = c_1 e^{-2t} + c_2 e^{-3t}$$

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$$y(0) = c_1 e^0 + c_2 e^0 = 2, \quad c_1 + c_2 = 2$$

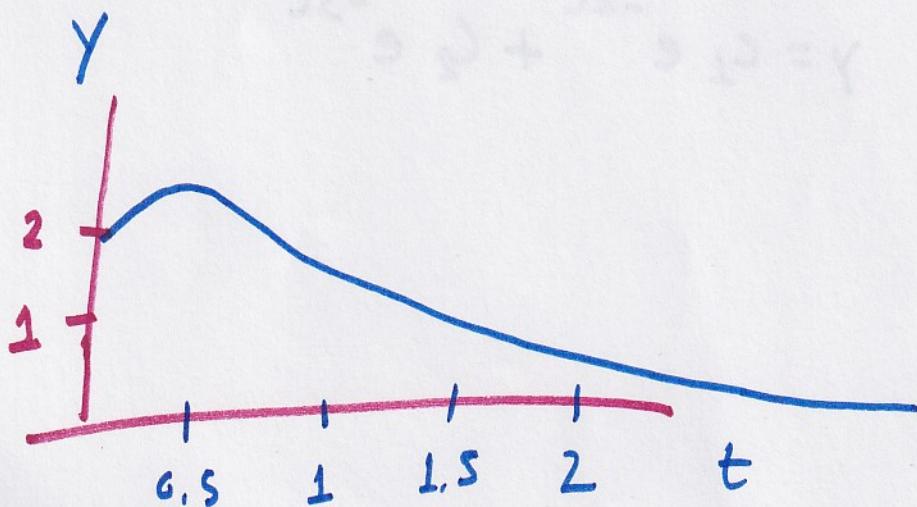
$$y' = c_1 (-2) e^{-2t} + c_2 (-3) e^{-3t}$$

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$$y'(0) = -2c_1 + -3c_2 = 3$$

$$\rightarrow c_1 = 9 \quad c_2 = -7$$

$$y = 9e^{-2t} - 7e^{-3t}$$



Example

$$4y'' - 8y' + 3y = 0 \quad y(0) = 2$$

$$y'(0) = \frac{1}{2}$$

characteristic equation

$$4r^2 - 8r + 3 = 0$$

$$r = \frac{3}{2} \quad r = \frac{1}{2} \quad \rightarrow y = C_1 e^{\frac{3}{2}t} + C_2 e^{\frac{1}{2}t}$$

Apply Initial Conditions

$$\underline{C_1 + C_2 = 2} \quad \underline{\frac{3}{2}C_1 + \frac{1}{2}C_2 = \frac{1}{2}}$$

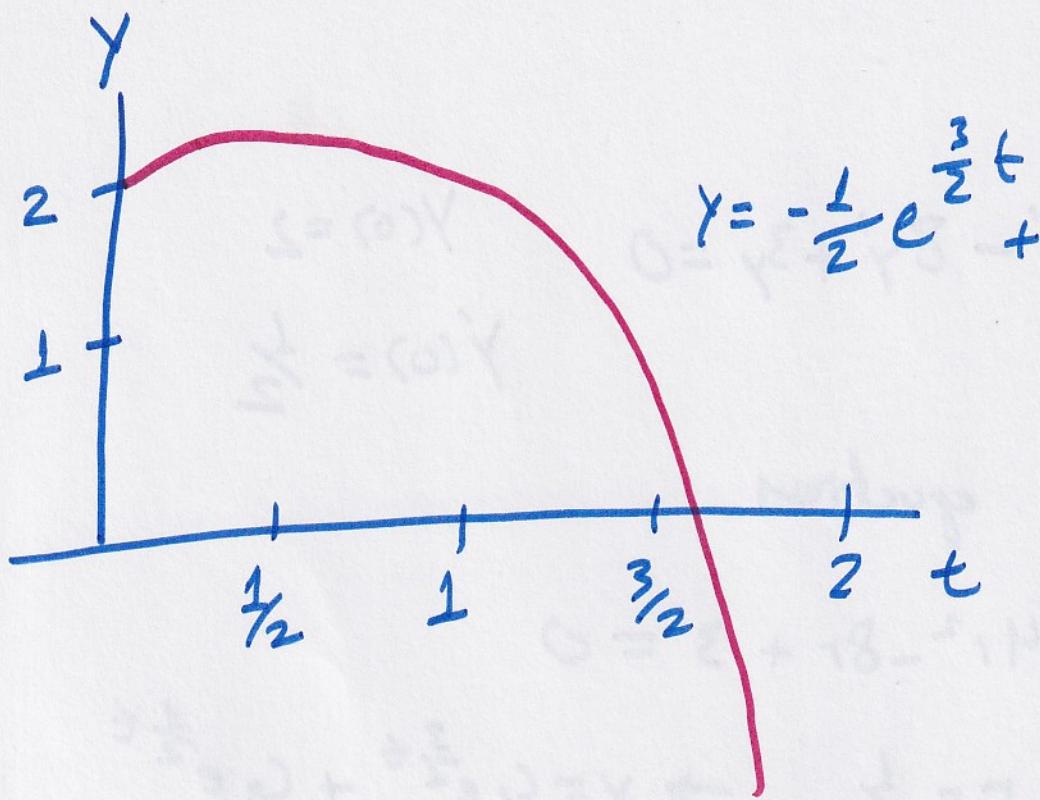
$$\text{From } y(0) = 2 \quad \text{From } y'(0) = \frac{1}{2}$$

$$C_1 = -\frac{1}{2} \quad C_2 = \frac{5}{2}$$

$$\rightarrow y = -\frac{1}{2} e^{\frac{3}{2}t} + \frac{5}{2} e^{\frac{1}{2}t}$$

This term grows faster

$\text{Expt } \frac{3}{2} > \frac{1}{2}$ for exponent/0



$$y = -\frac{1}{2}e^{\frac{3}{2}t} + \frac{5}{2}e^{\frac{1}{2}t}$$

To find the maximum of $y = 9e^{-2t} + 7e^{-3t}$

$$y' = -18e^{-2t} + 21e^{-3t}$$

$$\text{Set } y' = 0 \rightarrow t_m = \ln\left(\frac{7}{6}\right) \approx 0.15415$$

$$\text{So to get } y_m = y(t_m) = \frac{108}{49} \approx 2.204$$

Part 2 the Wronskian

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$$ay'' + by' + cy = 0$$

a, b, c are constants

To see another way, Let's Introduce an Operator.

Let P, g be continuous ~~on~~ on an open interval C^2 on I

$$I \rightarrow \alpha < t < \beta$$

for any function ϕ that is twice differentiable on I, we define the operator

$$\underbrace{L[\phi]}_{\phi} = \phi'' + p\phi' + g\phi$$

is a function on I the value of $L[\phi]$ at point t is

$$L[\phi](t) = \phi''(t) + p(t)\phi'(t) + g(t)\phi(t)$$

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$$\text{Let } p(t) = t^2, g(t) = 1+t,$$

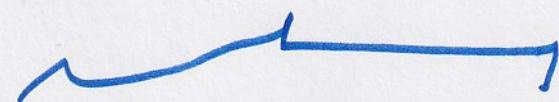
$$\phi(t) = \sin 3t$$

$$\begin{aligned} L[\phi](t) &= (\sin 3t)'' + t^2 \cdot (\sin 3t)' + (1+t) \sin 3t \\ &= -9\sin 3t + 3t^2 \cos 3t + (1+t) \sin 3t \end{aligned}$$

The operator L is often written as

$L = D^2 + pD + q$, where D is the
Derivative operator

We'll study $L[\phi](t) = 0$



2nd order linear homogeneous equation

$$\text{Let } y = \phi(t)$$

$$\rightarrow L[y] = y'' + p(t)y' + g(t)y = 0$$

We have Initial Conditions

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$$y(t_0) = y_0 \quad y'(t_0) = y'_0$$

$$t_0 \in I \quad y_0, y'_0 \in \mathbb{R}$$

Theorem 3.2.1 Existence and Uniqueness Theorem

Consider the Initial value problem

$$y'' + p(t)y' + q(t)y = f(t)$$

$$y(t_0) = y_0 \quad y'(t_0) = y'_0$$

where p, q , and f are continuous on an open interval I ($t_0 \in I$)

Then there is exactly one solution $y = \phi(t)$ of this problem. That solution exist throughout I (for $t_0 \in I$)

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- 1) The IVP has a solution
- a solution exists
- 2) The IVP has only 1 solution
- The solution is unique
- 3) solution ϕ is defined throughout
the Interval I where p, g, f
are C^2 on I

Example

$$y'' - y = 0 \quad y(0) = 2 \quad y'(0) = -1$$

The solution is $y = \frac{1}{2}e^t + \frac{3}{2}e^{-t}$

- 1.) a solution exists
- 2.) The solution is twice differentiable on I
 - because p, g, f are continuous on I
 $\rightarrow C^2$ as well, $\rightarrow y = \frac{1}{2}e^t + \frac{3}{2}e^{-t}$ is the only solution

$$y' = f(t, y) \quad f'(t, y) = \underline{\hspace{2cm}}$$

→ proving uniqueness is hard, but
3.2.1 says it's unique. Boom!⁵

Example 1) find the largest Interval in which
the solution ~~of~~ of the IVP

$$(t^2 - 3t)y'' + ty' - (t+3)y = 0$$

$$y(1) = 2 \quad y'(1) = 1$$

is certain to exist.

$$p(t) = \frac{t}{t^2 - 3t} \quad g(t) = \frac{-(t+3)}{t^2 - 3t}$$

$$= \frac{1}{t^2 - 3t} \quad = \frac{-(t+3)}{t(t-3)}$$

↗
 $t=0 \rightarrow g(t) \text{ undefined}$

$t=3 \rightarrow p, g \text{ undefined}$

3.2.1 says p, g, y have to be C^2 on I

at $t=0, t=3$ its not C^2

we have $y(0) = 2, \underset{\nwarrow}{y'(0)} = 4, \underset{\nearrow}{y'(1)} = 4$

Thus $t=1$, lies on $0 < t < 3$

So $I': 0 < t < 3$ (open Interval)

Example 2 Find the unique solution of the IVP

$$y'' + p(t)y' + g(t)y = 0$$

$$y(t_0) = 0, y'(t_0) = 0$$

where p, g are continuous on I containing t_0

$$y = \phi(t) = 0 \quad \forall t \in I$$

by 3.2.1 This is the only solution.

$$L[y] = y'' + p(t)y' + g(t)y = 0$$

Let us assume y_1, y_2 are two solutions

So we may write

$$\rightarrow L[y_1] = y_1'' + p y_1' + g y_1 = 0$$

same for y_2 and

$L[y_1 + y_2]$ works too!

We can generate more solutions by forming linear combinations of y_1 and y_2

Theorem 3.2.2 (Principle of Superposition)

If y_1 and y_2 are solutions of the diff eq

$$L[y] = y'' + p(t)y' + g(t)y = 0$$

Then the linear combination of $c_1 y_1 + c_2 y_2$ is also a solution for any of the values of c_1, c_2

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Proof Let $y = c_1 y_1 + c_2 y_2$

$$\begin{aligned}
 \rightarrow L[c_1 y_1 + c_2 y_2] &= [c_1 y_1 + c_2 y_2]'' + P[c_1 y_1 + c_2 y_2]' \\
 &\quad + g[c_1 y_1 + c_2 y_2] \\
 &= c_1 y_1'' + c_2 y_2'' + c_1 P y_1' + c_2 P y_2' \\
 &\quad + c_1 g y_1 + c_2 g y_2 \\
 &= c_1 [y_1'' + P y_1' + g y_1] \\
 &\quad + c_2 [y_2'' + P y_2' + g y_2] \\
 &= c_1 L[y_1] + c_2 L[y_2]
 \end{aligned}$$

$$L[c_1 y_1 + c_2 y_2] = c_1 L[y_1] + c_2 L[y_2]$$

Since $L[y_1] = 0, L[y_2] = 0$, it follows $L[c_1 y_1 + c_2 y_2] = 0$

regardless of c_1, c_2 , $y = c_1 y_1 + c_2 y_2$
satisfies the diff EQ

3.2.2 says

if we begin with only 2 solutions of
 $L[y]$

We can construct an infinite family of solutions

$$y = c_1 y_1 + c_2 y_2 + \dots + c_n y_n$$

We now ask ourselves,

do all solutions of $L[y]$ are
 included in y ?

or are they solutions of a different form

Can c_1, c_2, \dots, c_n be chosen so as to
 satisfy the initial condition?

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for c_1, c_2

$$\left. \begin{array}{l} c_1 y_1(t_0) + c_2 y_2(t_0) = y_0 \\ c_1 y'_1(t_0) + c_2 y'_2(t_0) = y'_0 \end{array} \right\} \text{System 1}$$

The determinant of the coefficients of the system

$$W = \begin{vmatrix} y_1(t_0) & y_2(t_0) \\ y'_1(t_0) & y'_2(t_0) \end{vmatrix} = y_1(t_0)y'_2(t_0) - y'_1(t_0)y_2(t_0)$$

If $W \neq 0$, then System 1 has a unique solution (c_1, c_2) regardless of the values of y_0 and y'_0

$$c_1 = \frac{y_0 y'_2(t_0) - y'_0 y_2(t_0)}{W}$$

$$c_2 = \frac{-y_0 y_1'(t_0) + y_0' y_1(t_0)}{W}$$

$$c_1 = \frac{\begin{vmatrix} y_0 & y_2(t_0) \\ y_0' & y_2'(t_0) \end{vmatrix}}{W} \quad c_2 = \frac{\begin{vmatrix} y_1(t_0) & y_0 \\ y_1'(t_0) & y_0' \end{vmatrix}}{W}$$

→ c_1, c_2 will satisfy ICS and
the diff eq ($L[y]$)