



①

all θ 's are variables

#	θ	d	a	α
0-1	$\theta_{1,var}$	d_1	a_1	-90°
1-2	$\theta_{2,var}$	0	a_2	0°
2-3	$\theta_{3,var}$	0	0	-90°
3-4	$\theta_{4,var}$	d_4	0	90°
4-5	$\theta_{5,var}$	0	0	-90°
5-6	$\theta_{6,var}$	d_6	0	0°

$${}^0A_{n+1} = \text{Rot}(Z, \theta_{n+1}) \text{Trans}(0, 0, d_{n+1}) \text{Trans}(a_{n+1}, 0, 0) \text{Rot}(X, \alpha_{n+1})$$

$${}^0A_1 = \begin{bmatrix} c_1 & -s_1 & 0 & 0 \\ s_1 & c_1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & d_1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & a_1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & C(-90^\circ) & -S(-90^\circ) & 0 \\ 0 & S(-90^\circ) & C(-90^\circ) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0A_1 = \begin{bmatrix} c_1 & -s_1 & 0 & 0 \\ s_1 & c_1 & 0 & 0 \\ 0 & 0 & 1 & d_1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & a_1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & C(-90^\circ) & -S(-90^\circ) & 0 \\ 0 & S(-90^\circ) & C(-90^\circ) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0A_1 = \begin{bmatrix} c_1 & -s_1 & 0 & a_1 c_1 \\ s_1 & c_1 & 0 & a_1 s_1 \\ 0 & 0 & 1 & d_1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0A_1 = \begin{bmatrix} c_1 & 0 & -s_1 & a_1 c_1 \\ s_1 & 0 & c_1 & a_1 s_1 \\ 0 & -1 & 0 & d_1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^1A_2 = \begin{bmatrix} C_2 & -S_2 & 0 & 0 \\ S_2 & C_2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & a_2 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & a_2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & C(0) & -S(0) & 0 \\ 0 & S(0) & C(0) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad (4)$$

$${}^1A_2 = \begin{bmatrix} C_2 & -S_2 & 0 & a_2 \\ S_2 & C_2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & (1) & (0) & 0 \\ 0 & (0) & (1) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^1A_2 = \begin{bmatrix} C_2 & -S_2 & 0 & a_2 \\ S_2 & C_2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^2A_3 = \begin{bmatrix} C_3 & -S_3 & 0 & 0 \\ S_3 & C_3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & C(-90) & -S(-90) & 0 \\ 0 & S(-90) & C(-90) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^2A_3 = \begin{bmatrix} C_3 & -S_3 & 0 & 0 \\ S_3 & C_3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^2A_3 = \begin{bmatrix} C_3 & 0 & -S_3 & 0 \\ S_3 & 0 & C_3 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^3A_4 = \begin{bmatrix} C_4 & -S_4 & 0 & 0 \\ S_4 & C_4 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & d_4 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & C(90) & -S(90) & 0 \\ 0 & S(90) & C(90) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^3A_4 = \begin{bmatrix} C_4 & -S_4 & 0 & 0 \\ S_4 & C_4 & 0 & 0 \\ 0 & 0 & 1 & d_4 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^3A_4 = \begin{bmatrix} C_4 & 0 & S_4 & 0 \\ S_4 & 0 & -C_4 & 0 \\ 0 & 1 & 0 & d_4 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^4A_5 = \begin{bmatrix} C_5 & -S_5 & 0 & 0 \\ S_5 & C_5 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & C(-90) & -S(-90) & 0 \\ 0 & S(-90) & C(-90) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^4A_5 = \begin{bmatrix} C_5 & -S_5 & 0 & 0 \\ S_5 & C_5 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^4A_5 = \begin{bmatrix} C_5 & 0 & -S_5 & 0 \\ S_5 & 0 & C_5 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^5A_6 = \begin{bmatrix} C_6 & -S_6 & 0 & 0 \\ S_6 & C_6 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & d_6 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & C(\theta) & -S(\theta) \\ 0 & S(\theta) & C(\theta) \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^5A_6 = \begin{bmatrix} C_6 & -S_6 & 0 & 0 \\ S_6 & C_6 & 0 & 0 \\ 0 & 0 & 1 & d_6 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & (1) & (0) & 0 \\ 0 & (0) & (1) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^5A_6 = \begin{bmatrix} C_6 & -S_6 & 0 & 0 \\ S_6 & C_6 & 0 & 0 \\ 0 & 0 & 1 & d_6 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0A_6 = {}^0A_1 {}^1A_2 {}^2A_3 {}^3A_4 {}^4A_5 {}^5A_6$$

$${}^0A_1A_2 = \begin{bmatrix} c_1 & 0 & -s_1 & a_1c_1 \\ s_1 & 0 & c_1 & a_1s_1 \\ 0 & -1 & 0 & d_1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c_2 & -s_2 & 0 & a_2 \\ s_2 & c_2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0A_1A_2 = \begin{bmatrix} c_1c_2 & -c_1s_2 & -s_1 & a_2c_1 + a_1c_1 \\ s_1c_2 & -s_1s_2 & c_1 & a_2s_1 + a_1s_1 \\ -s_2 & -c_2 & 0 & d_1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0A_1A_2A_3 = \begin{bmatrix} c_1c_2 & -c_1s_2 & -s_1 & c_1(a_1+a_2) \\ s_1c_2 & -s_1s_2 & c_1 & s_1(a_1+a_2) \\ -s_2 & -c_2 & 0 & d_1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c_3 & 0 & -s_3 & 0 \\ s_3 & 0 & c_3 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} c_1c_2c_3 - c_1s_2s_3 & s_1 & -c_1c_2s_3 - c_1s_2c_3 & c_1(a_1+a_2) \\ s_1c_2c_3 - s_1s_2s_3 & -c_1 & -s_1c_2s_3 - s_1s_2c_3 & s_1(a_1+a_2) \\ -s_2c_3 - c_2s_3 & 0 & s_2s_3 - c_2c_3 & d_1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^0A_1A_2A_3 = \begin{bmatrix} c_1c_2c_3 - c_1s_2s_3 & s_1 & -c_1c_2s_3 - c_1s_2c_3 & c_1(a_1+a_2) \\ s_1c_2c_3 - s_1s_2s_3 & -c_1 & -s_1c_2s_3 - s_1s_2c_3 & s_1(a_1+a_2) \\ -s_2c_3 - c_2s_3 & 0 & s_2s_3 - c_2c_3 & d_1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$${}^3A_4 {}^4A_5 = \begin{bmatrix} C_4 & 0 & S_4 & 0 \\ S_4 & 0 & -C_4 & 0 \\ 0 & 1 & 0 & d_4 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} C_5 & 0 & -S_5 & 0 \\ S_5 & 0 & C_5 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

⑥

$${}^3A_4 {}^4A_5 = \begin{bmatrix} C_4 C_5 & -S_4 & -C_4 S_5 & 0 \\ S_4 C_5 & C_4 & -S_4 S_5 & 0 \\ S_5 & 0 & C_5 & d_4 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^3A_4 {}^4A_5 {}^5A_6 = \begin{bmatrix} C_4 C_5 & -S_4 & -C_4 S_5 & 0 \\ S_4 C_5 & C_4 & -S_4 S_5 & 0 \\ S_5 & 0 & C_5 & d_4 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} C_6 & -S_6 & 0 & 0 \\ S_6 & C_6 & 0 & 0 \\ 0 & 0 & 1 & d_6 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}^3A_4 {}^4A_5 {}^5A_6 = \begin{bmatrix} C_4 C_5 C_6 - S_4 S_6 & -C_4 C_5 S_6 - S_4 C_6 & -C_4 S_5 & -d_6 C_4 S_5 + 0 \\ S_4 C_5 C_6 + C_4 S_6 & -S_4 C_5 S_6 + C_4 C_6 & -S_4 S_5 & -d_6 S_4 S_5 + 0 \\ S_5 C_6 & -S_5 S_6 & C_5 & d_6 C_5 + d_4 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

⑦

$$\begin{aligned}
 (b1) \quad c_1 c_2 c_3 - c_1 s_2 s_3 &\Rightarrow c_1 (c_2 c_3 - s_2 s_3) = c_1 \left[\frac{1}{2} [c(\theta_2 - \theta_3) + c(\theta_2 + \theta_3)] \right. \\
 &\quad \left. - \frac{1}{2} [c(\theta_2 - \theta_3) - c(\theta_2 + \theta_3)] \right] \\
 &= c_1 (c_{23})
 \end{aligned}$$

$$\begin{aligned}
 (1,3) \quad -c_1 (c_2 s_3 + s_2 c_3) &\Rightarrow -c_1 \left[\frac{1}{2} [s(\theta_2 + \theta_3) - s(\theta_2 - \theta_3)] + \frac{1}{2} [s(\theta_2 + \theta_3) + s(\theta_2 - \theta_3)] \right] \\
 &= -c_1 [s_{23}] \Rightarrow -c_1 s_{23}
 \end{aligned}$$

$$\begin{aligned}
 (3,1) \quad -(s_2 c_3 + c_2 s_3) &\Rightarrow - \left[\frac{1}{2} [s(\theta_2 + \theta_3) + s(\theta_2 - \theta_3)] + \frac{1}{2} [s(\theta_2 + \theta_3) - s(\theta_2 - \theta_3)] \right] \\
 &= -(s_{23})
 \end{aligned}$$

$$\begin{aligned}
 (3,3) \quad (s_2 s_3 - c_2 c_3) &\Rightarrow \frac{1}{2} [c(\theta_2 - \theta_3) - c(\theta_2 + \theta_3)] - \frac{1}{2} [c(\theta_2 - \theta_3) + c(\theta_2 + \theta_3)] \\
 &\Rightarrow -c_{23}
 \end{aligned}$$

(8)

$${}^0A_3 = \begin{bmatrix} C_1(C_2C_3 - S_2S_3) & S_1 & -C_1(C_2S_3 + S_2C_3) & C_1(a_1 + a_2) \\ S_1(C_2C_3 - S_2S_3) & -C_1 & -S_1(C_2S_3 + S_2C_3) & S_1(a_1 + a_2) \\ -(S_2C_3 + C_2S_3) & 0 & S_2S_3 - C_2C_3 & d_1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$${}^0A_3 = \begin{bmatrix} C_1C_{23} & S_1 & -C_1S_{23} & C_1(a_1 + a_2) \\ S_1C_{23} & -C_1 & -S_1S_{23} & S_1(a_1 + a_2) \\ -S_{23} & 0 & -C_{23} & d_1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

${}^0A_3 {}^3A_6$ position column "P"

$$\left\{ \begin{array}{l} C_1C_{23} \{-d_6C_4S_4\} + S_1 \{-d_6S_4S_5\} - C_1S_{23} \{d_6C_5 + d_4\} + C_1(a_1 + a_2) \\ S_1C_{23} \{-d_6C_4S_4\} - C_1 \{-d_6S_4S_5\} - S_1S_{23} \{d_6C_5 + d_4\} + S_1(a_1 + a_2) \\ -S_{23} \{-d_6C_4S_4\} + 0 - C_{23} \{d_6C_5 + d_4\} + d_1 \\ 0 + 0 + 0 + 0 + 1 \end{array} \right\}$$

position "P" of ${}^0A_3 {}^3A_6$

$$\begin{bmatrix} -d_6C_1C_{23}C_4S_4 - d_6S_1S_4S_5 - d_6C_1C_{23}C_5 - d_4C_1S_{23} + C_1(a_1 + a_2) \\ -d_6S_1C_{23}C_4S_4 - d_6C_1S_4S_5 - d_6S_1S_{23}C_5 - d_4S_1S_{23} + S_1(a_1 + a_2) \\ -d_6S_{23}C_4S_4 - d_6C_{23}C_5 - d_4C_{23} + d_1 \\ 1 \end{bmatrix}$$