

Lecture 13

Wednesday, February 27, 2019

2:44 PM

Constructing Initial Data

- To solve evolution eqns., must first specify $\gamma_{ij} + K_{ij}$ (and T^a_b if there is matter) on Σ . Must satisfy constraints:
$$R + K^2 - K_{ij} K^{ij} = 16\pi \rho$$
$$\Delta_j (K^{ij} - \gamma^{ij} K) = 8\pi S^i$$
- $\gamma_{ij} + K_{ij}$ have 12 independent components
 - constraints give 4, coordinate choice gives 4
 - remaining 4 related to 2 polarizations of GWs (these are dynamical \rightarrow can't get them from constraints)

Conformal Transformations

- rewrite spatial metric: $\gamma_{ij} = \psi^4 \bar{\gamma}_{ij}$
where ψ is the **conformal factor**
 $\bar{\gamma}_{ij}$ is the **conformally-related metric**
- usual choice: $\bar{\gamma}_{ij} = \gamma^{-1/3} \gamma_{ij}$
 $\hookrightarrow \gamma = \psi^{12}$ conformal factor characterizes

the metric scale

- connection coefficients:

$$\Gamma^i_{jk} = \bar{\Gamma}^i_{jk} + 2(\delta^i_j \bar{\Delta}_k \ln \psi + \delta^i_k \bar{\Delta}_j \ln \psi - \bar{\gamma}_{jk} \bar{\gamma}^{il} \bar{\Delta}_l \ln \psi)$$

where $\gamma^{ij} = \psi^{-4} \bar{\gamma}^{ij}$

$$\rightarrow \bar{\Delta}_i \bar{\gamma}_{jk} = 0$$

- Ricci tensor:

$$R_{ij} = \bar{R}_{ij} - 2(\bar{\Delta}_i \bar{\Delta}_j \ln \psi + \bar{\gamma}_{ij} \bar{\gamma}^{lm} \bar{\Delta}_l \bar{\Delta}_m \ln \psi) + 4\left[(\bar{\Delta}_i \ln \psi)(\bar{\Delta}_j \ln \psi) - \bar{\gamma}_{ij} \bar{\gamma}^{lm} (\bar{\Delta}_l \ln \psi)(\bar{\Delta}_m \ln \psi)\right]$$

- Curvature scalar:

$$R = \psi^{-4} \bar{R} - 8 \psi^{-5} \bar{\Delta}^2 \psi$$

where $\bar{\Delta}^2 = \bar{\gamma}^{ij} \bar{\Delta}_i \bar{\Delta}_j$ is covariant Laplacian

\rightarrow Hamiltonian constraint:

$$8 \bar{\Delta}^2 \psi - \psi \bar{R} - \psi^5 K^2 + \psi^5 K_{ij} K^{ij} = -16 \pi \psi^5 \rho$$

Conformal transform of extrinsic curvature

- split K_{ij} into trace K & traceless part A_{ij} :

$$K_{ij} = A_{ij} + \frac{1}{3} \gamma_{ij} K$$

- conformal transform separately
 - significant freedom in how to do this
- Consider, \therefore

$$A^{ij} = \psi^\alpha \bar{A}^{ij}, \quad K = \psi^\beta \bar{K}$$

where α, β are undetermined exponents

- now, any symmetric, traceless tensor A^{ij} satisfies, $\Delta_j A^{ij} = \psi^{-10} \bar{\Delta}_j (\psi^{10+\alpha} \bar{A}^{ij})$

→ adopt $\alpha = -10$

$$\hookrightarrow A^{ij} = \psi^{-10} \bar{A}^{ij}; \quad A_{ij} = \psi^{-2} \bar{A}_{ij}$$

$$\therefore \Delta_j A^{ij} = 0 \quad \text{if} \quad \bar{\Delta}_j \bar{A}^{ij} = 0$$

- apply this decomposition to momentum constraint,

$$\psi^{-10} \bar{\Delta}_j \bar{A}^{ij} - \frac{2}{3} \psi^{\beta-4} \gamma^{ij} \bar{\Delta}_j \bar{K} - \frac{2}{3} \beta \psi^{\beta-5} \bar{K} \bar{\Delta}_j \psi = 8\pi S^i$$

- if we take $\beta=0$, $K = \bar{K}$ "conformally invariant"

$$\hookrightarrow 8 \bar{\Delta}^2 \psi - \psi \bar{R} - \frac{2}{3} \psi^5 K^2 + \psi^{-7} \bar{A}_{ij} \bar{A}^{ij} = -16\pi \psi^5 \rho$$

.... Hamiltonian constraint

$$\text{and} \quad \bar{\Delta}_j \bar{A}^{ij} - \frac{2}{3} \psi^6 \bar{\gamma}^{ij} \bar{\Delta}_j \bar{K} = 8\pi \psi^{10} S^i$$

.... momentum constraint

Conformal transverse-traceless

- for any traceless, symmetric tensor:

$$\bar{A}^{ij} = \bar{A}_{\text{TT}}^{ij} + \bar{A}_L^{ij}$$

where "transverse traceless" part,

$$\bar{\Delta}_j \bar{A}_{\text{TT}}^{ij} = 0$$

... "longitudinal" part ...

and the longitudinal part,

$$\bar{A}_L^{ij} = \bar{\Delta}^i W^j + \bar{\Delta}^j W^i - \frac{2}{3} \bar{\gamma}^{ij} \bar{\Delta}_k W^k \equiv (\bar{L} W)^{ij}$$

W^i is a vector potential

longitudinal operator \bar{L} produces a symmetric, traceless tensor,

• now,

$$\begin{aligned} \bar{\Delta}_j A^{ij} &= \bar{\Delta}_j \bar{A}_L^{ij} = \bar{\Delta}_j (\bar{L} W)^{ij} \\ &= \bar{\Delta}^2 W^i + \frac{1}{3} \bar{\Delta}^i (\bar{\Delta}_j W^j) + \bar{R}^i_j W^j \\ &\equiv (\bar{\Delta}_L W)^i \end{aligned}$$

where $\bar{\Delta}_L$ is *vector Laplacian*

• using this decomposition in momentum constraint,

$$(\bar{\Delta}_L W)^i - \frac{2}{3} \psi^6 \bar{\gamma}^{ij} \bar{\Delta}_j K = 8\pi \psi^{10} S^i$$

• CTT decomposition summary:

1. $\bar{\gamma}_{ij}$, K , $\bar{A}_{\tau\tau}^{ij}$ are freely specifiable
2. solve above momentum constraint for W^i
3. Hamiltonian constraint,

$$8 \bar{\Delta}^2 \psi - \psi \bar{R} - \frac{2}{3} \psi^5 K^2 + \psi^{-7} \bar{A}_{ij} \bar{A}^{ij} = -16\pi \psi^5 \rho$$

where $\bar{A}^{ij} = \bar{A}_{\tau\tau}^{ij} + \bar{A}_L^{ij} = \bar{A}_{\tau\tau}^{ij} + (\bar{L} W)^{ij}$

is solved for ψ

4. physical (ie. not "conformal") spatial metric,

$$\gamma_{ij} = \psi^4 \bar{\gamma}_{ij}$$

... ..

physical extrinsic curvature,

$$K_{ij} = A_{ij} + \frac{1}{3} \gamma_{ij} K = \psi^{-2} \bar{A}_{ij} + \frac{1}{3} \gamma_{ij} K$$

- choice of **background data** ($\bar{\gamma}_{ij}$, K , \bar{A}_{ij}^{ij} , and matter sources) must be made carefully for the physical system of interest

- common choice: $\bar{A}_{ij}^{ij} = 0$ [minimizes GW content of background]

- **maximal slicing**: $K = 0$, maximizes volume of Σ in M

- assuming $\rho = 0 = S^i$ (no matter),
Hamiltonian constraint,

$$(\bar{\Delta}_L W)^i = 0 \quad \dots \text{ can be solved w/o}$$

first specifying background

- assume conformal flatness: $\bar{\gamma}_{ij} = \eta_{ij}$

↳ vector Laplacian in Cartesian:

$$\partial^j \partial_j W^i + \frac{1}{3} \partial^i \partial_j W^j = 0$$

\Rightarrow **Bianchi-York solutions**

- CTT can be prone to initial transients since derivative info cannot be specified

Conformal thin-sandwich (CTS)

- define *densitized lapse* . $\alpha = \gamma \bar{\alpha}$

$$\hookrightarrow \bar{A}^{ij} = \frac{1}{2\bar{\alpha}} \left((\bar{L}\beta)^{ij} - \bar{u}^{ij} \right)$$

... relates \bar{A}^{ij} to shift β^i

- insert this into momentum constraint to solve for shift,

$$(\bar{L}_L \beta)^i - (\bar{L}\beta)^{ij} \bar{D}_j \ln(\bar{\alpha}) = \bar{\alpha} \bar{D}_j (\bar{\alpha}^{-1} u^{ij}) + \frac{4}{3} \bar{\alpha} \psi^6 \bar{D}^i K + 16\pi \bar{\alpha} \psi^{10} S^i$$

- Summary of CTS:

1. specify $\bar{\gamma}_{ij}$, \bar{u}_{ij} , K , & $\bar{\alpha}$
2. input into reduced momentum constraint & solve for β^i

3. solve for ψ from Hamiltonian constraint:

$$\bar{D}^2 \psi - \frac{1}{8} \psi \bar{R} - \frac{1}{12} \psi^5 K^2 + \frac{1}{8} \psi^{-7} \bar{A}_{ij} \bar{A}^{ij} = -2\pi \psi^5 \rho$$

where $\bar{A}^{ij} = \frac{1}{2\bar{\alpha}} \left((\bar{L}\beta)^{ij} - \bar{u}^{ij} \right)$

4. Construct physical solution:

$$\gamma_{ij} = \psi^4 \bar{\gamma}_{ij}$$

$$K_{ij} = A_{ij} + \frac{1}{3} \gamma_{ij} K = \psi^{-2} \bar{A}_{ij} + \frac{1}{3} \gamma_{ij} K$$

$$\alpha = \psi^6 \bar{\alpha}$$

- CTS has 16 unknowns vs. 12 for CTT.

- for extra are α & β^i which account for inclusion of time derivatives, &c. info

extrinsic to Σ_i .

- instead of specifying lapse $\bar{\alpha}$ can instead specify $\partial_t K$ & solve:

$$\Delta^2 \alpha = - \partial_t K + \alpha (K_{ij} K^{ij} + 4\pi (\rho + S)) + \beta^i \Delta_i K$$

for α .

→ "extended" CTS

Mass, momentum, angular momentum

- continuity eqn. for conservation of rest-mass:

$$\nabla_a (\rho_0 u^a) = 0$$

where ρ_0 is rest-mass density.

- M_0 will be total conserved rest-mass or "baryon" mass.
- integrating continuity eqn. over $\mathcal{V} \cap \Sigma$:

$$\int_{\Sigma} d^3x \sqrt{\gamma} \nabla_a (\rho_0 u^a) = 0$$

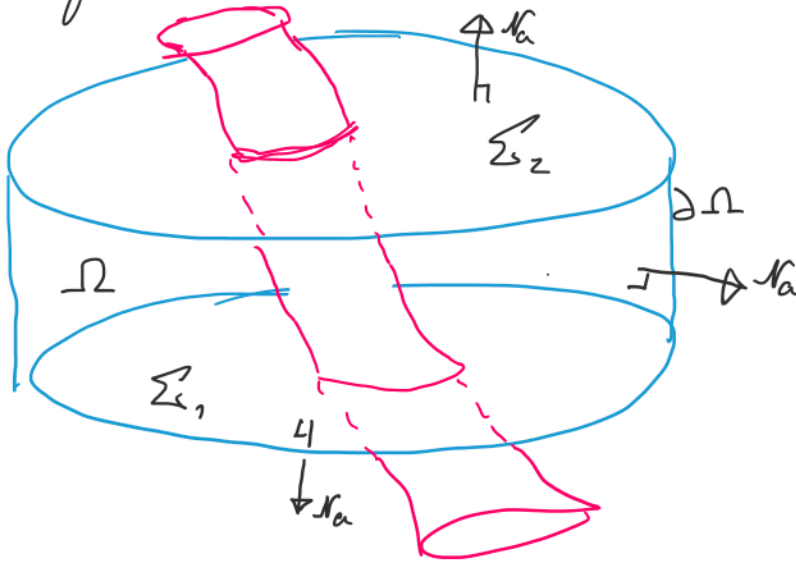
- Gauss' theorem →

$$\int_{\Sigma} d^3x \sqrt{\gamma} \nabla_a (\rho_0 u^a) = \int_{\partial \Sigma} d^3\Sigma_a \rho_0 u^a$$

where $d^3\Sigma_a = \epsilon_{N_a} \sqrt{\gamma} d^3x$

N_a : outward-pointing unit normal on $\partial\Omega$.

- for spacelike $\partial\Omega$, $\epsilon = -1$
- for timelike $\partial\Omega$, $\epsilon = +1$



• normal vector: $N_a u^a = n_a u^a = -\alpha u^t$
 on Σ_2

• on Σ_1 , $N^a = -n^a$

$$\hookrightarrow \int_{\Sigma_1} d^3x \sqrt{\gamma} \alpha u^t \rho_0 - \int_{\Sigma_2} d^3x \sqrt{\gamma} \alpha u^t \rho_0 = 0$$

$$\therefore \text{rest mass } M_0 = \int_{\Sigma} d^3x \sqrt{\gamma} \alpha u^t \rho_0$$

is conserved

• Defining total mass-energy of a system in GR is tricky since it is non-local.

→ define "ADM" mass as total mass-energy of isolated system at an instant of time measured in a spatial surface cut to infinity:

$$M_{ADM} = \frac{1}{16\pi} \int_{\partial\Sigma_\infty} \sqrt{\gamma} \gamma^{jn} \gamma^{im} (\partial_j \gamma_{mn} - \partial_m \gamma_{jn}) dS_i$$

where $dS_i = \sigma_i \sqrt{\gamma} d\Sigma_\infty d^2z$

is outward-oriented surface element,

z^i are coords on $\partial\Sigma_\infty$, $\gamma_{ij}^{\partial\Sigma_\infty}$ is the induced metric on $\partial\Sigma_\infty$, & σ^i

is the unit normal ($\sigma^i \sigma_i = 1$) to $\partial\Sigma_\infty$

- formally, integral carried out to infinity but in practice must at least be taken to asymptotically flat space:

$$g_{ab} - \eta_{ab} = \mathcal{O}(r^{-1})$$

- ADM angular momentum:

$$J_i^{ADM} = \frac{1}{8\pi} \int_{\partial\Sigma_\infty} dS_m (K^m_n - \delta^m_n K) \xi^{(i)}_n$$

where $\xi^{(i)}_n$ is some global Killing vector field

- adopting $\xi^{(\phi)} = \xi_\phi^{(i)} = \epsilon_{xml} e^m_{(i)} x^l$

in Cartesian, where $e^m_{(i)} = \delta_i^m$ is basis vector along x^i

$$\hookrightarrow J_i^{ADM} = \frac{1}{8\pi} \epsilon_{ijn} \int_{\partial\Sigma_\infty} dS_m x^j (K^{mn} - \delta^{mn} K)$$

- can obtain linear ADM momentum by adopting a translational Killing vector along x^i : $\xi^n_{(i)} = e^n_{(i)}$

$$\hookrightarrow P_i^{ADM} = \frac{1}{8\pi} \int_{\partial\Sigma_\infty} dS_m (K^m_i - \delta^m_i K)$$

- M^{ADM} , J_i^{ADM} , P_i^{ADM} are globally conserved and this should be monitored during numerical simulations.