

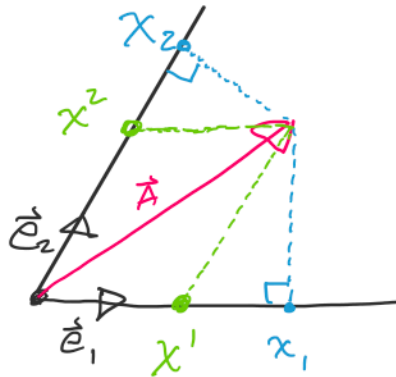
Lecture4

Wednesday, January 16, 2019

3:44 PM

Another look at contravariant vs. covariant

Consider general, non-orthogonal basis:



Covariant: perpendicular projection

Contravariant: parallel projection

$$\vec{A} \equiv A^\alpha \vec{e}_\alpha \rightarrow A^\alpha = \vec{A} \cdot \frac{1}{\vec{e}_\alpha}, \quad A_\alpha \equiv \vec{A}(\vec{e}_\alpha) = \vec{A} \cdot \vec{e}_\alpha$$

Spacetime Diagrams for Boosts

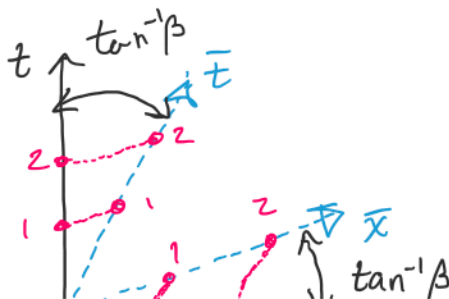
- for a pure boost in the \vec{e}_1 direction:

$$t = \gamma(\bar{t} + \beta\bar{x}), \quad x = \gamma(\bar{x} + \beta\bar{t})$$

$$\bar{t} = \gamma(t - \beta x), \quad \bar{x} = \gamma(x - \beta t)$$

where

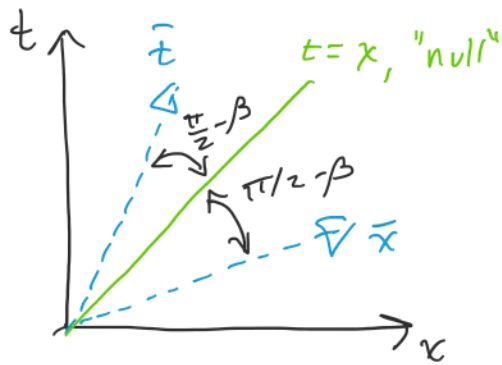
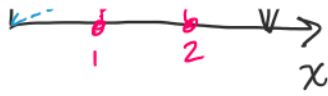
$$|\beta| < 1, \quad \gamma \equiv (1 - \beta^2)^{-1/2}$$



invariance of interval ($a=1,2$)

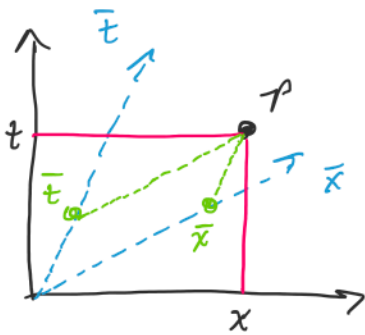
↳ event $\bar{x}=a$ on \bar{x} -axis

lies at intersection of

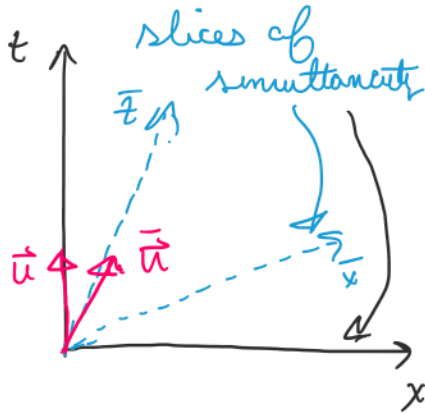


\bar{x} -axis with $x^2 - t^2 = a^2$.
and $\bar{t} = a$, where \bar{t} -axis intersects $t^2 - x^2 = a^2$

• boosted basis is orthogonal
 $\vec{e}_{\bar{t}} \cdot \vec{e}_{\bar{x}} = \frac{1}{4} [(\vec{e}_{\bar{t}} + \vec{e}_{\bar{x}})^2 - (\vec{e}_{\bar{t}} - \vec{e}_{\bar{x}})^2] = 0$



- t, x from perpendicular projection in \vec{e}_a
- \bar{t}, \bar{x} from parallel projection in $\vec{e}_{\bar{a}}$



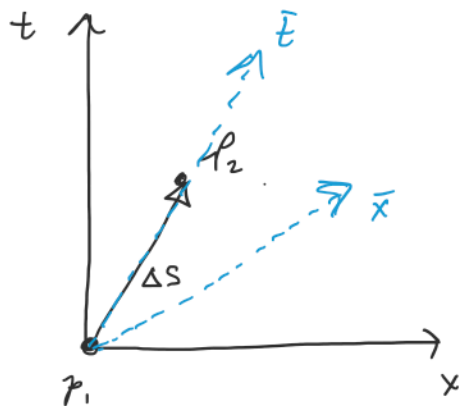
- observer at rest in unboosted frame: 4-velocity $\vec{u} = \{1, 0, 0, 0\}$
- observer at rest in boosted frame: $\vec{\bar{u}}$

Exercise 2.14 Prove the following

- Two events simultaneous in one inertial frame are not simultaneous in boosted frame.
- Two events at same spatial location in one frame are not at same location in another frame.

location in ~~rest~~ frame.

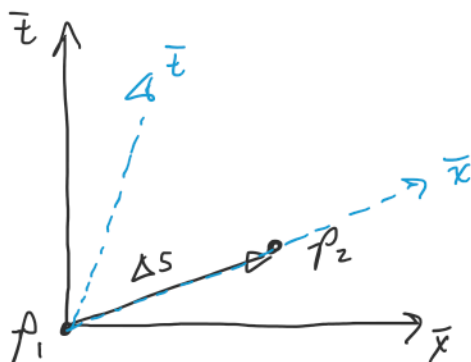
- (c) if P_1 & P_2 have a timelike separation then there is an inertial frame in which they occur at the same spatial location. In that frame the time lapse between them is $\Delta t = \Delta \tau \equiv \sqrt{-(\Delta s)^2}$.



$$(\Delta s)^2 < 0$$

- (d) P_1 & P_2 have spacelike separation, then there is a frame in which they are simultaneous. In that frame the spatial distance between them is

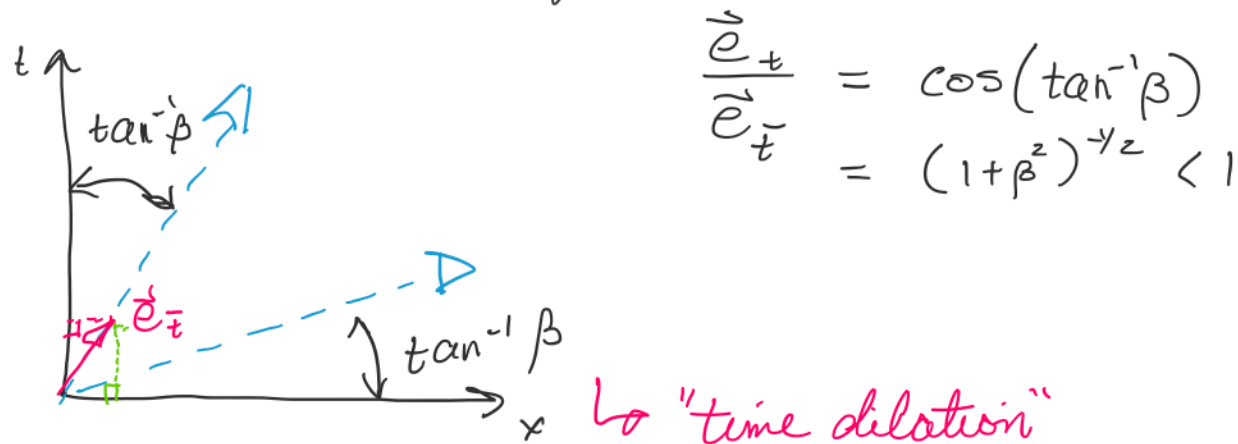
$$\sqrt{g_{ij} \Delta x^i \Delta x^j} = \Delta S = \sqrt{(\Delta s)^2}$$



$$(\Delta s)^2 > 0$$

(c) $\Delta t \neq 0$ $\Delta x = 0$ $\Delta s^2 = -(\Delta t)^2 < 0$

(e) If frame \bar{S} moves w/ speed β relative to frame S then clock at rest in \bar{S} ticks more slowly as viewed from S than \bar{S} by a factor $\gamma^{-1} = (1 - \beta^2)^{1/2}$.



(f) if frame moves w/ $\vec{v} = \beta \vec{e}_x$ relative to unbarred frame, object at rest in barred frame appears shortened by a factor $\gamma^{-1} = (1 - \beta^2)^{1/2}$.

$$\rightarrow \frac{\vec{e}_{\bar{z}} \cdot \vec{e}_x}{\vec{e}_{\bar{t}}} = \sin(\tan^{-1} \beta) = \beta (1 + \beta^2)^{-1/2}$$

Exercise 2.16 ... Maybe

Directional derivatives, gradients, Levi-Civita

- Defined in Minkowski spacetime precisely as for Euclidean space

- 'gradient': $\vec{\nabla} \hat{=}$ produces directional derivative

$$\nabla_{\vec{A}} \hat{=} = \vec{\nabla} \hat{=} (-, -, -, \vec{A})$$

can write gradient $T_{\alpha\beta\gamma;\mu}$

- in Lorentz basis, gradient is partial derivative:

$$T_{\alpha\beta\gamma;\mu} = \frac{\partial T_{\alpha\beta\gamma}}{\partial x^\mu} \equiv T_{\alpha\beta\gamma,\mu}$$

where "comma" means partial derivative

- divergence of the gradient of tensor

in Minkowski is **wave operator**:

$$\begin{aligned} T_{\alpha\beta\gamma;\mu\nu} g^{\mu\nu} &= T_{\alpha\beta\gamma,\mu\nu} g^{\mu\nu} \\ &= -\frac{\partial^2 T_{\alpha\beta\gamma}}{\partial t^2} + \frac{\partial^2 T_{\alpha\beta\gamma}}{\partial x^i \partial x^i} g^{ik} \\ &= \square T_{\alpha\beta\gamma} \end{aligned}$$

- metric tensor in 4D still connects distance
- Levi-Civita still gives volume

$$\epsilon_{\alpha\beta\gamma\delta} = +1 \quad \text{if } \alpha, \beta, \gamma, \delta \text{ even permutation}$$

$$\epsilon_{\alpha\beta\gamma\delta} = -1 \quad \text{if } \alpha, \beta, \gamma, \delta \text{ odd permutation}$$

$$\epsilon_{\alpha\beta\gamma\delta} = 0 \quad \text{if}$$

sign-flip if temporal, $\epsilon_{0123} = +1 \rightarrow \epsilon^{0123} = -1$

Maxwell's Equation

on π

to π

...

- electromagnetic 4-force on particle of charge q :

$$\frac{dp^\alpha}{d\tau} = q F^{\alpha\beta} u_\beta$$

where $F(-, -)$ is EM field tensor.

- if particle ordinary velocity is $v^i = v_j$ and 4-velocity components $u^0 = \gamma$, $u^i = \gamma v^i$, contravariant components of antisymmetric EM tensor:

$$F^{0i} = -F^{i0} = +F_{j0} = -F_{0j} = E_j$$

... Electric field

$$F^{ij} = F_{ij} = \epsilon_{ijk} B_k \quad \dots \text{Magnetic field}$$

- since $\frac{dt}{d\tau} = u^0 = \gamma$, using the above in force law:

$$\begin{aligned} \frac{dp_i}{d\tau} &= \gamma \frac{dp_i}{dt} = q (F_{j0} u^0 + F_{jk} u^k) \\ &= q \gamma (F_{j0} + F_{jk} v^k) \\ &= q \gamma (E_j + \epsilon_{ijk} v_j B_k) \end{aligned}$$

cancel

$$\frac{dp_0}{d\tau} = \gamma \frac{dp^0}{dt} = q F^{0i} u_i = q \gamma E_j v_j$$

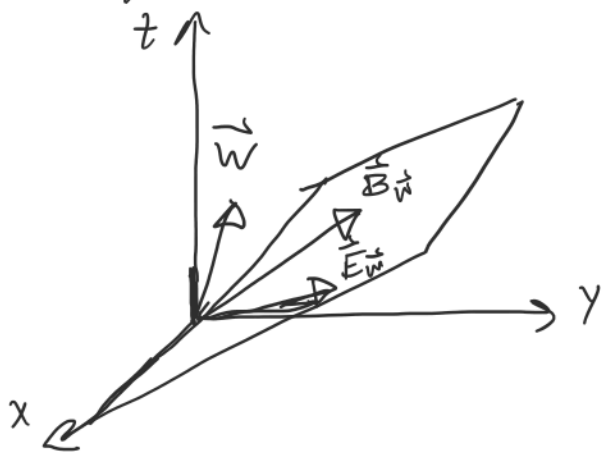
- with particle energy $E = p^0$, divided by γ :

$$\frac{d\vec{p}}{dt} = q (\vec{E} + \vec{v} \times \vec{B}); \quad \frac{dE}{dt} = q \vec{v} \cdot \vec{E}$$

... in 3-space

Note! $\vec{E} \neq \vec{B}$ tied to chosen frame!

- assume 3-vectors $\vec{E} \neq \vec{B}$ are spatial parts of 4-vectors in slice of simultaneity t



\vec{w} : 4-velocity of frame's observers.

$\vec{E}_w \neq \vec{B}_w$: 4-vectors orthogonal to \vec{w} .

- in rest frame of observer \vec{w} ($w^0=1, w^i=0$):
 $E_w^0 = 0, E_w^j = E_j = F_{j0}$

$$\therefore E_w^\alpha = F^{\alpha\beta} w_\beta, B_w^\beta = \frac{1}{2} \epsilon^{\alpha\beta\gamma\delta} F_{\gamma\delta} w_\alpha$$

- since this is true for any observer \vec{w} , these equations can be regarded as frame-independent. \therefore the Electric & magnetic fields can be found solely from an observer's 4-velocity and the EM field tensor.

$\rightarrow \vec{F}$ is geometric, $\vec{E} \neq \vec{B}$ require the choice of an observer. (inertial frame)

\rightarrow only after a 3+1 split are $\vec{E} \neq \vec{B}$ even separate entities.

... ..

- EM field tensor :

$$F^{\alpha\beta} = w^\alpha E_{\vec{w}}^\beta - E_{\vec{w}}^\alpha w^\beta + \epsilon^{\alpha\beta}_{\gamma\delta} w^\gamma B_{\vec{w}}^\delta$$

- Maxwell's Equations :

$$F^{\alpha\beta}_{;\beta} = 4\pi J^\alpha$$

$$\epsilon^{\alpha\beta\gamma\delta} F_{\delta\gamma;\beta} = 0$$

J^α is charge-current :

$J^0 = \rho_e$... charge density

$J^i = J_i$... current density

or

$$F_{\alpha\beta;\gamma} + F_{\beta\gamma;\alpha} + F_{\gamma\alpha;\beta} = 0$$

Charge Conservation in Spacetime

- for unit 3-surface $\vec{\Sigma} = \vec{e}_x$,

$\vec{J}(\vec{\Sigma}) = \vec{J}(\vec{e}_x)$ is total charge Q

that flows across $\vec{\Sigma}$ in positive sense

- Charge density ρ_e is temporal component

$$J^0 = -J_0 = \vec{J}(-\vec{e}_0) = \rho_e$$

$\hookrightarrow \vec{J}(\vec{\Sigma}) = \vec{J}(-\vec{e}_0)$ is total charge Q

that flows through $\vec{\Sigma} = -\vec{e}_0$ in positive sense

$\hookrightarrow \vec{J}(\vec{\Sigma}) \equiv J^\alpha \Sigma_\alpha$ for any small 3-surface

- Law of charge conservation :

all charge that enters 4-volume V

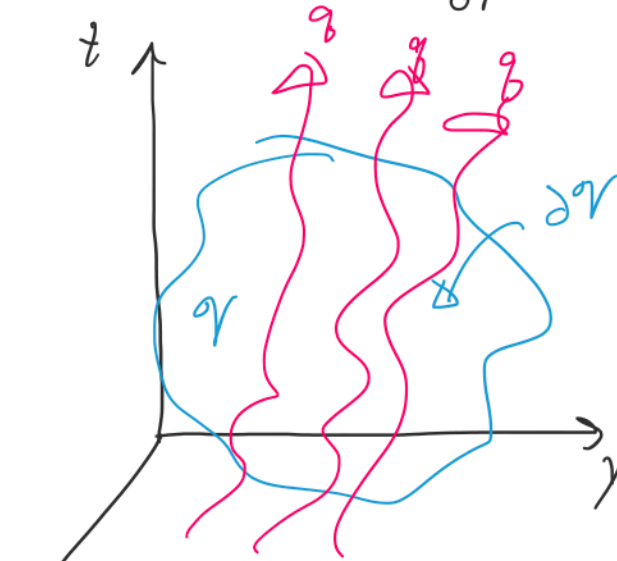
through the past part of bounding

surface ∂V must exit through

the future part of ∂V .

• globally,

$$\int_{\partial V} T^a d\Sigma_a = 0$$



• 4D Gauss theorem:

$$\int_V (\vec{\nabla} \cdot \vec{A}) dV = \int_{\partial V} \vec{A} \cdot d\vec{\Sigma}$$

$$\text{or } \int_{\partial V} T^a d\Sigma_a = \int_V T^a_{;a} dV$$

• As in 3-space, this requires that the integrand must vanish

$$\rightarrow T^a_{;a} = 0 \quad (\text{or } \vec{\nabla} \cdot \vec{T} = 0)$$

• similar conservation laws can be derived for other conserved scalars

Stress-Energy Tensor & 4-Momentum Conservation

• in a medium flowing through spacetime, net 4-momentum $\vec{T}(-, \vec{\Sigma})$ is transported from negative to positive:

$$\vec{T}(-, \vec{\Sigma}) \equiv (\text{total 4-momentum } \vec{P} \text{ flowing thru } \vec{\Sigma})$$

$$\text{or } \bar{T}^{\alpha\beta} \Sigma_{\beta} = \bar{p}^{\alpha}$$

where $\bar{T}(-, -)$ is the **stress-energy tensor**

- components of stress-energy:

T^{00} = (energy density in chosen Lorentz frame)

T^{j0} = (density of j -component of momentum in frame)

$T_{\alpha 1} \equiv T_{\alpha x} \equiv \bar{T}(\vec{e}_{\alpha}, \vec{e}_x) = (\alpha\text{-component of 4-momentum that crosses area } \Delta y \Delta z = 1$

lying in surface of constant x during time Δt , crossing from $-x$ to $+x$)

= (α component of flux of 4-momentum across surface perpendicular to \vec{e}_x)

$$\Rightarrow T^{00} = (\text{energy density})$$

$$T^{j0} = (\text{momentum density})$$

$$T^{0i} = (\text{energy flux})$$

$$T^{jk} = (\text{stress})$$

- stress-energy is symmetric: $T^{\alpha\beta} = T^{\beta\alpha}$

$$\bar{T}(\vec{A}, \vec{B}) = \bar{T}(\vec{B}, \vec{A})$$

- Conservation of 4-momentum:

$$\int_{\partial V} T^{\alpha\beta} d\Sigma_{\beta}^0 = 0$$

$$\text{Gauss's law} \rightarrow \int_V T^{\alpha\beta}_{;\beta} d\Sigma = \int_{\partial V} T^{\alpha\beta} d\Sigma_{\beta} = 0$$

$$\hookrightarrow T^{\alpha\beta}_{;\beta} = 0 \quad (\text{or } \vec{\nabla} \cdot \vec{T} = 0)$$

• Consider a perfect fluid in its local rest frame ($T^{i0} = T^{0j} = 0$):

$$T^{00} = \rho, \quad T^{ik} = P \delta^{ik}$$

where P is isotropic pressure & ρ is energy density
these assumptions lead to

$$T^{\alpha\beta} = (\rho + P) u^{\alpha} u^{\beta} + P g^{\alpha\beta}$$

$$\text{or } \vec{T} = (\rho + P) \vec{u} \otimes \vec{u} + P \vec{g}$$