

Lecture 20

Tuesday, April 9, 2019

9:14 AM

Spherical spacetimes

- reduce $3+1$ to $1+1$ where everything depends only on t & r

- can't really treat, e.g., rotation

- general 3-metric:

$$dl^2 = A dr^2 + B r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

A & B : functions of t & r only

→ full 4-metric then requires gauge functions $\alpha(t, r)$ & $\beta^r(t, r)$

- **radial gauge**: set $B=1$

→ r is the areal radius:

$$r = r_s = (A/4\pi)^{1/2} = (C/2\pi)$$

A : proper area

C : circumference

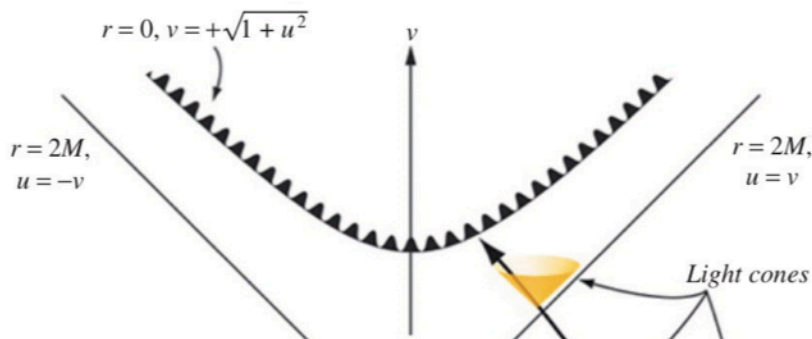
- *isotropic gauge*: $A = B \rightarrow r = \bar{r}$
- *comoving gauge*: set $\beta^r(t, r)$ such that fluid is always at rest w.r.t. coords

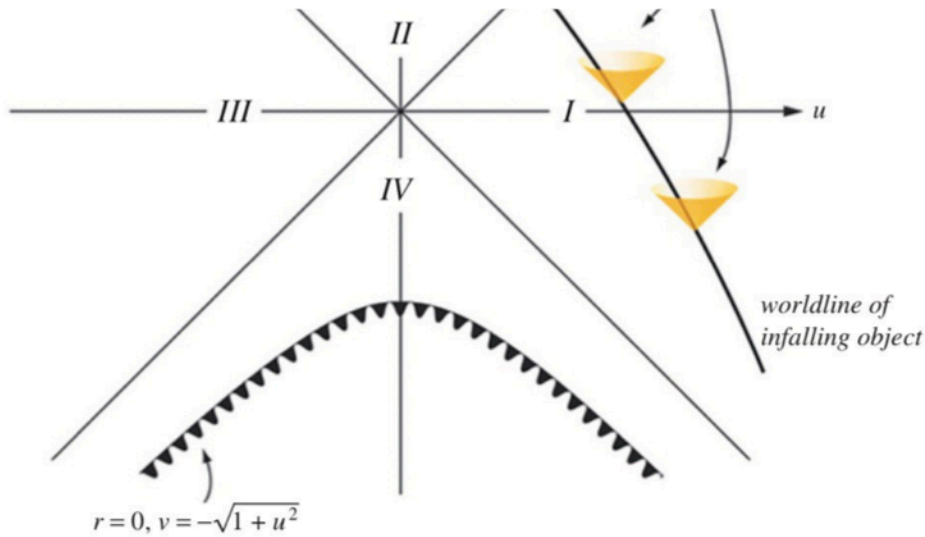
Slicing

- must then specify $\alpha(t, r)$
- *geodesic slicing*: $\alpha = 1 \rightarrow$ coord. singularities
- other choices: maximal or polar slicing

Black Holes

- start by adopting analytic $\alpha + \beta^r$ that lead to Killing lapse & shift
 \hookrightarrow metric is time independent
- take initial data as spacelike $v=0$ surface from $0 \leq u \leq \infty$ in $u-v$ plane:





Kruskal-Szekeres diagram

→ this is equivalent to $t_s = 0$.

from $2M \leq r_s \leq \infty$ in Schwarzschild coords.

• gauge choice:

$$\alpha(r_s) = (1 - 2M/r_s)^{1/2} \quad \beta'(r_s) = 0$$

$$\rightarrow A(r_s) = \frac{1}{1 - 2M/r_s}, \quad B(r_s) = 1$$

... static solution

• asymptotic limit reached at $t_s = \infty$
when $r_s = 2M$

→ no time slice ever penetrates
horizon

• coordinate transformation to isotropic \bar{r} :

$$\alpha(\bar{r}) = \frac{1 - M/2\bar{r}}{1 + M/2\bar{r}}, \quad \beta(\bar{r}) = 0$$

$$\rightarrow A(\bar{r}) = B(\bar{r}) = \left(1 + \frac{M}{2\bar{r}}\right)^4$$

- same time slicing as Schwarzs.
- still not horizon penetrating

Kerr - Schild

$$\alpha(r_s) = \left(\frac{r_s}{r_s + 2M}\right)^{1/2}, \quad \beta(r_s) = \frac{2M}{r_s + 2M}$$

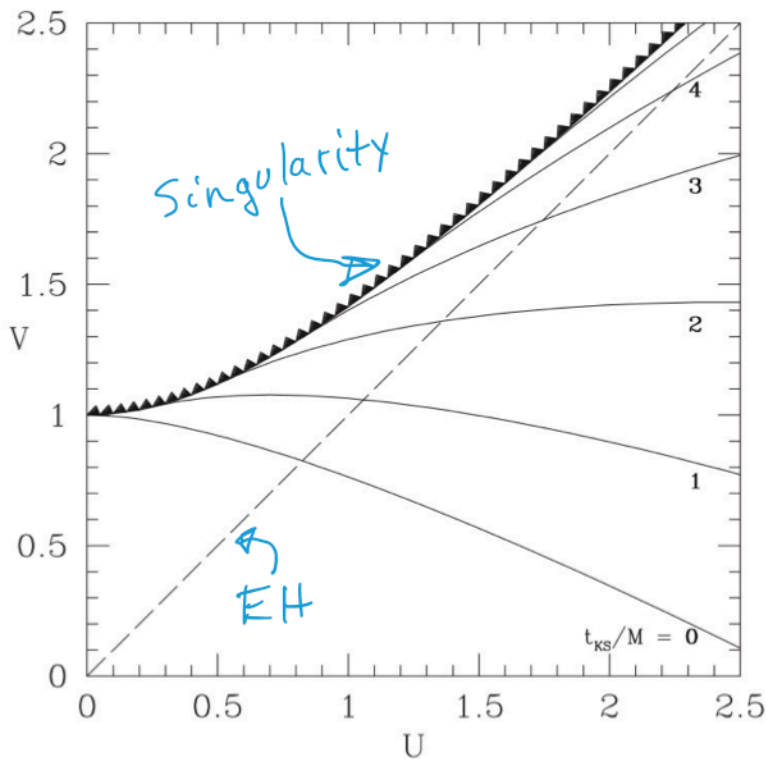
$$\rightarrow A(r_s) = 1 + \frac{2M}{r_s}, \quad B(r_s) = 1$$

- horizon penetrating, but not singularity avoiding
- must locate at $t_{KS} = \text{const.}$ slice to set initial data
- solving to u & v in terms of t_{KS} :

$$u = \frac{1}{2} \left[e^{(t_{KS} + r_s)/4M} + e^{(t_{KS} - r_s)/4M} \left(\frac{r_s}{2M} - 1 \right) \right]$$

$$v = \frac{1}{2} \left[e^{(t_{KS} + r_s)/4M} - e^{(t_{KS} - r_s)/4M} \left(\frac{r_s}{2M} - 1 \right) \right]$$

where $t_{KS} = 4M \ln(u+v) - r_s$



- all slices penetrate horizon + hit singularity

Maximal slicing

- horizon penetrating and singularity avoiding
- usually no exact solutions (but see chapter 4.2 in BS)

• • • • •

• one element:

$$ds^2 = -(\alpha^2 - \beta^2/A) d\bar{t}^2 + 2\beta d\bar{t} dr + A dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

r : Schwarzschild radial coord.

$$\beta = \beta_r = A\beta^r$$

\bar{t} : maximal time coord.

α, β, A depend on \bar{t} & r only

• for 3+1 ADM eqns., need connection coeffs:

$$\Gamma_{rr}^r = \partial_r A / (2A), \quad \Gamma_{\theta\theta}^r = -r/A, \quad \Gamma_{\phi\phi}^r = -r \sin^2 \theta / A$$

$$\Gamma_{r\theta}^\theta = \Gamma_{\theta r}^\theta = 1/r, \quad \Gamma_{\phi\phi}^\theta = -\sin \theta \cos \theta$$

$$\Gamma_{\theta\phi}^\phi = \Gamma_{\phi\theta}^\phi = \cot \theta, \quad \Gamma_{r\phi}^\phi = \Gamma_{\phi r}^\phi = 1/r$$

• Use these to evaluate Ricci tensor:

$$R_{ij} = \partial_k \Gamma_{ij}^k - \partial_j \Gamma_{ik}^k + \Gamma_{ij}^k \Gamma_{kl}^l - \Gamma_{il}^k \Gamma_{jk}^l$$

$$\hookrightarrow R_{rr} = \partial_r A / (rA)$$

$$R_{\theta\theta} = R_{\phi\phi} / \sin^2 \theta = 1 - A^{-1} + r \partial_r A / (2A^2)$$

... ..

- curvature scalar.

$$R = R^i_i = 2\partial_r A / (rA^2) + 2(1-A^{-1})/r^2$$

- find extrinsic curvature from spatial metric evolution eqn:

$$\partial_t \gamma_{ij} = -2\alpha K_{ij} + D_i \beta_j + D_j \beta_i$$

$$\rightarrow K_{rr} = -(\partial_t A + \beta \partial_r A / A - 2\partial_r \beta) / (2\alpha)$$

$$K_{\theta\theta} = K_{\phi\phi} / \sin^2 \theta = r\beta / (\alpha A)$$

- maximal slicing requires $K = K^i_i = 0$
 - combine with above to find,

$$K_{rr} = -2\beta / (\alpha r), \quad K_{ij} K^{ij} = 6(\beta / \alpha A r)^2$$

$$-\partial_t \ln A + (\beta / A) \partial_r \ln(\beta^2 r^4 / A) = 0$$

- then Hamiltonian constraint,

$$R + K^2 - K_{ij} K^{ij} = 16\pi \rho$$

is

$$R = K_{ij} K^{ij} \quad (\text{assume vacuum})$$

- insert into above,

$$3\beta^2/(\alpha^2 A) = A - 1 + r\partial_r A/A$$

this plus K_{rr} above give for the momentum constraint,

$$\Delta_j (K^{ij} - \gamma^{ij} K) = 0$$

$$\rightarrow \partial_r \ln(\beta r^2 / A \alpha) = 0$$

- max. slicing requires $\partial_{\bar{t}} K = 0$, so contraction of extrinsic curvature evolution eqn. gives

$$\Delta^2 \alpha = \alpha R$$

- using curvature scalar above,

$$\begin{aligned} \partial_r \partial_r \alpha + 2\partial_r \alpha / r - (\partial_r \ln A) \partial_r \alpha / 2 \\ = 2\alpha (A - 1 + r\partial_r \ln A) / r^2 \end{aligned}$$

... lapse eqn.

- full extrinsic curvature evolution eqn is

$$\begin{aligned} \partial_{\bar{t}} K_{ij} = \alpha (R_{ij} - 2K_{ik} K^k_j) - \Delta_i \Delta_j \alpha \\ + \beta^k \partial_k K_{ij} + K_{ik} \partial_j \beta^k + K_{kj} \partial_i \beta^k \end{aligned}$$

which for K_{rr} becomes,

$$\begin{aligned}\partial_{\bar{t}} \ln(\beta/\alpha) &= (3\beta/A + \alpha^2 A/\beta - \alpha^2/\beta)/r \\ &+ 3(\partial_r \beta)/A + (\alpha^2/\beta - 4\beta/A)(\partial_r \ln A)/2 \\ &- (\beta/A + \alpha^2/\beta) \partial_r \ln \alpha\end{aligned}$$

• integrating $\partial_r \ln(\beta r^2/A\alpha) = 0$ gives

$$\beta = \alpha A T / r^2$$

$$T = T(\bar{t}) \quad \dots \text{constant of int.}$$

• using this in

$$3\beta^2/(\alpha^2 A) = A - 1 + r \partial_r A/A$$

$$\hookrightarrow A = \frac{1}{1 - 2M/r + T^2/r^4}$$

M function of \bar{t} only

• using this to compute $\partial_t A$ & inserting into above gives

$$\partial_r (\alpha A^{1/2}) = A^{3/2} (r \partial_{\bar{t}} M/T - \partial_{\bar{t}} T/r^2)$$

- can be used to show $\partial_{\bar{t}} M = 0$

- integrating this gives

$$\alpha = (1 - 2M/r + T^2/r^4)^{1/2} \left[1 + \right.$$

$$\left. \frac{dT}{M} \int_0^{M/r} dx (1 - 2x + T^2 x^4 / M^4)^{-3/2} \right]$$

• $T = T(\bar{r})$ undetermined

choose $T=0$ → zero shift

$T=C$ → time-independent solns.
from Ch. 4.2

Stellar Collapse

- see May + White (1966, 1967)
- treating singularity formation tricky. but collapse to NS is ok.

Misner-Sharp formalism

- Lagrangian, spherical symmetry
- see MTW ex. 32.7
- diagonal line element:

$$ds^2 = - e^{2\phi(t,A)} dt^2 + e^{\lambda(t,A)} dA^2 + R^2(t,A) d\Omega^2$$

R : circumferential radius

$\rightarrow e^\phi$ is the lapse $\Phi = 0$

- each mass shell labeled by A & its worldline is $R(t, A)$

- can choose A to be enclosed rest mass

- 4-velocity:

$$u^a = (e^{-\phi}, 0, 0, 0)$$

- define the following,

$$M = 4\pi \int_0^A \rho_0 (1 + \epsilon) R^2 (\partial_A R) dA$$

.... gravitational mass enclosed

$$U = e^{-\phi} \partial_t R \quad \dots \text{coord. velocity}$$

$$\Gamma = e^{-\lambda/2} \partial_A R \quad \dots \text{radial metric function}$$

- Einstein field eqns become,

$$\partial_t U = -e^\phi \left(\frac{4\pi R^2}{h} \partial_A P + \frac{m + 4\pi R^3 P}{R^2} \right)$$

$$\partial_t m = -e^\phi 4\pi R^2 P U$$

$$\partial_A \phi = -\frac{1}{\rho_0 h} \partial_A P$$

$$\Gamma = (1 + U^2 - 2m/R)^{1/2}$$

$$\rho_0 = \frac{P}{4\pi R^2 \partial_A R}$$

- P pressure & h enthalpy of a perfect gas

- differentiating mass eqn,

$$\partial_A m = (1 + \epsilon) \Gamma$$

- using rest mass in above for Γ ,

$$e^{-\lambda/2} = 4\pi \rho_0 R^2$$

- need an EOS:

$$\partial_t \epsilon = -P \partial_t \left(\frac{1}{\rho_0} \right) \dots \text{1st law of thermo}$$

$$\phi \quad P = P(\rho, \epsilon)$$

- for γ -law EOS: $P = (\gamma - 1) \rho_0 \epsilon$

• Boundary conditions:

$$R=0, U=0, \Gamma=1, m=0 \dots \text{center}, A=0$$

$$P=0, e^\phi = 1 \dots \text{surface}, A = A_{\text{total}}$$

→ similar to Newtonian, but
crashes if a singularity forms

Eulerian 1D GR Hydro

- see O'Connor & Ott (2010)
- use "radial gauge polar slicing" RGPS
→ shift vanishes & metric is
diagonal + almost Schwarzschild

• line element:

$$ds^2 = -\alpha(r,t)^2 dt^2 + X(r,t)^2 dr^2 + r^2 d\Omega^2$$

$$\alpha(r,t) = e^{\phi(r,t)} \quad X(r,t) = \left(1 - \frac{2m(r,t)}{r}\right)^{-1/2}$$

where ϕ is metric potential &

$$M_{\text{grav}}(r, t) = m(r, t) \dots \text{enclosed grav. mass}$$

• for matter:

$$T^{\mu\nu} = \rho_0 h u^\mu u^\nu + P g^{\mu\nu} \dots \text{S-E}$$

$$J^\mu = \rho_0 u^\mu \dots \text{mass current}$$

$$h = 1 + \epsilon + \frac{P}{\rho_0} \dots \text{enthalpy}$$

$$u^\mu = [W/\alpha, W v^r, 0, 0] \dots \text{4-velocity}$$

where

$$W = (1 - v^2)^{-1/2} \dots \text{Lorentz factor}$$

$$v = \chi v^r$$

• from the Hamiltonian constraint, can derive mass eqn.

$$m(r, t) = 4\pi \int_0^r (\rho_0 h W^2 - P + \tau_m^\nu) r'^2 dr'$$

τ_m^ν due to trapped neutrinos

• metric potential $\phi(r, t)$ found from momentum constraint w/ polar slicing:

$$\text{tr } K = K_r^r$$

$$\hookrightarrow \phi(r,t) = \int_0^r X^2 \left[\frac{m(r',t)}{r'^2} + 4\pi r' (\rho_0 h w^2 v^2 + p + \tau_\phi^v) \right] dr' + \phi_0$$

- constant offset ϕ_0 determined by matching to Schwarzschild at surface ($r = R_*$):

$$\phi(R_*, t) = \ln[\alpha(R_*, t)] = \frac{1}{2} \ln \left[1 - \frac{z_m(R_*, t)}{R_*} \right]$$

Matter evolution

- as usual, obtained from:

$$\nabla_\mu T^{\mu\nu} = 0 \quad \dots \text{4-momentum conservation}$$

$$\nabla_\mu J^\mu = 0 \quad \dots \text{baryon number conservation}$$

- Valencia formulation in flux-conservative:

$$\partial_t \vec{u} + \frac{1}{r^2} \partial_r \left[\frac{\alpha r^2}{X} \vec{f} \right] = S$$

- conserved variables:

$$[D = \alpha X^T X = X P W]$$

$$\vec{u} = \left[\begin{array}{l} D y_e = \alpha X y_e J^t = X \rho_0 W y_e \\ S^r = \alpha X T^{tr} = \rho_0 h W^2 v \\ \tau = \alpha^2 T^{tt} - D = \rho_0 h W^2 - P - D \end{array} \right]$$

$$\vec{u} = \left[\begin{array}{l} D v \\ D y_e v \\ S^r v + P \\ S^r - D v \end{array} \right]$$

$$\vec{S} = \left[\begin{array}{l} 0 \\ 0 \\ (S^r v - \tau - D) \alpha X \left(8\pi r P + \frac{m}{r^2} \right) + \alpha P X \frac{m}{r^2} + \frac{2\alpha P}{X r} \\ 0 \end{array} \right]$$