Glossary

OS provides the environment within which programs are executed

Provides services for programs

• Provides interfaces for users

• Collection of components and their interconnections

Parallelism > 1 task being performed simultaneously

(one process may be waiting on another)

Concurrency multiple tasks making progress at one time

(nobody is waiting)

Throughput number of processes completed in a unit of time

Turnaround from time of submission to completion,

INCLUDING wait time

Wait Time time spent in waiting/ready queue, NOT including I/O queue / time

Response Time time from submission to time when 'first' usable data/output

TLB Translation Lookaside Buffer

MMU Memory Management Unit

RMS Rate Monotonic Scheduling

EDF Earliest Deadline First

PTBR Page Table Base Register (pointer to page table in memory) Context Switch When a process is forced out of CPU (quantum or pre-emption)

Thrashing When a process spends more time swapping than executing

Track The 'ring' that is 1 bit wide that passes under a stationary HD head

Cylinder The set of tracks among all platers for a single seek position

Sector A segment in a track

RAID Redudant Array of Independent Disks

DMA Direct Memory Access

FAT File Allocation Table

Parameter Passing

1. Pass paramater via registers

2. Save parameters in block/table (memory), pass via registers the address of the block

3. Placed onto the stack

Working Set Model

Main Idea Consider pages a process needed in the past, and use as indicator of pages needed in the future

Locality A set of pages actively used together

Spatial Locality Page references close in time are located near to each other in space

Temporal Locality A page is referenced repeatedly in some unit of time

Essentially a sliding window of time $t = \Delta$ that moves over the page requests a process makes.

In modern systems, Δ is in the 5000 15000 range.

If the WS size of process i is WSS_i ...

$$D = \sum_{i=0}^{n} WSS_i$$

If total demand D is greater than count of available frames, thrashing will occur.

The OS monitors WSS for each process, and allocates for each enough frames to its working set size. If there are 'free' frames, initates another process. If too few, a process is suspended.

Process



Process Control Block		
State		
Program Counter		
CPU Registers		
CPU Scheduling Info		
Mem Mgmt Info		
Accounting Info		
I/O Status		

Two processes are independent if the write set of each is disjoint from both the read and write sets of the other.

Threads

Many-to-one

All user threads map to a single kernel thread If a user thread makes a block system call, the entire process (made up of multiple user threads) will block Because only 1 thread can access the kernel at any one time, multiple threads are unable to run concurrently on a multicore computer

One-to-one

Each user thread is mapped to a unique kernel thread

The creation of a user thread requires (considerable) overhead to create a kernel thread. If a user thread is idle (perhaps waiting on another thread to finish), then the kernel thread with which the user thread 1s associated is needlessly consuming kernel space resources When one thread is blocked (user or kernel thread), the other threads can continue. Concurrency is enabled

Many-to-many

Many user threads are mapped to a \leq # kernel threads At the user level, multiple threads are created, and it is up to the OS to schedule/orchestrate/map each of them to a kernel thread

With m threads, n instructions each:

 $\frac{(mn)!}{(n!)^m}$ possible histories

Critical Section Problem

Mutual Exclusion If a process is executing its critical section, no others can be executing theirs

Progress If no process is executing its critical section, AND some process wants to enter its, only those processes NOT executing can decide who

Bounded Waiting There must be a limit on the number of times another process is allowed to enter its critical section after a process has made a request to enter its critical section (i.e., no starvation).

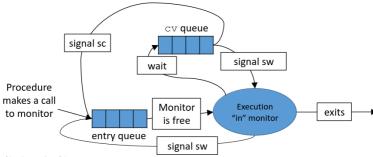
Semaphores

- Must be careful NOT to omit an inc/dec in code.
- Global, thus must know how entire program works to use them
- Can't infer which waiting process will run next

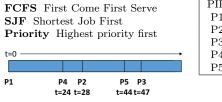
Monitors

SC The signaler continues, and the signaled executes at some later time SW The signaler waits until some later time and the signaled executes im-

A monitor follows one, but not both.



Scheduling



PID	ms	Priority
P1	24	1
P2	16	3
P3	2	5
P4	4	2
P5	3	4

Hard Drive

Priority

May encounter issues like starvation / aging (hence Round Robin).

FCFS First Come First Serve SSTF Shortest Seek Time First

SCAN Full back and forth, reading during both swings

C-SCAN Full back and forth, reading during only one swing (C = Circular) ${\bf LOOK}\:$ Back and forth from lowest requested address to highest requested

C-LOOK Back and forth from lowest requested address to highest requested address, reading during only one swing

An I/O request will be for a specific block, in a specific sector, for a certain track, on one of many cylinders. File Systems



Real-time scheduling

Periodic occuring at a constant interval / period (p) **Process time** time needed to burst (t)

Deadline time the process must be completed by (d)

If a requesting process does not 'satisfy' $0 \le t \le d \le p$, the scheduler should reject the process.

Suppose two processes: Process 1 p:50ms, t:20ms, d:1/period Process 2 p:100ms, t:35ms, d:1/period

Can the CPU process Utilization (t/p)both? P1:20/50= 0.4P2:35/100= 0.35 Assuming no other process runs, we should be able to service both.

RMS Upon entering, a process is assigned a priority inversely proportional to its period. (i.e., the shorter the period, the higher the priority). P2 would be broken up into two chunks (30 / 5) at t=50.

EDF Upon entering, a process is assigned a priority inversely proportional to its deadline. (i.e., the sooner the deadline, the higher the priority).

By design, real-time CPU scheduling does not permit a process that has already met its period deadline to start a second time in the same period.

Storage Hierarchy

LRU - Second Chance



- 1. Assign a reference bit to each page
- 2. When a page is referenced, set the reference bit to 1

0.75

- 3. When evicting, start at the location where last eviction occurred
- 4. If reference bit is 1, set to 0 and move to next page
- 5. Repeat until a page with reference bit 0 is found

$$\begin{array}{ccc} & \text{(referenced, modified)} \\ (0,\,0) & (1,\,0) & (0,\,1) & (1,\,1) \\ \text{Evict first 'best choice'} & \text{Evict last 'worst choice'} \end{array}$$

Memory Allocation

Best Fit Fit into a hole such that resulting left-over hole is size minimized

First Fit Fit into first hole (most often reading from bottom addresses to higher) that can accomodate the process

Worst Fit Fit into largest hole, resulting in left-over hole whose size is maximized

Segmentation

Logical Address -> < segment num, offset>

$$\text{Logical Address-} > \begin{cases} \text{Segment Number, offset} \\ S, D \end{cases}$$

S is the index into the table which iden-Segment Table tifies a row containing limit and base limit base value. In the example table, <3, 200>, 1400 2500 3500 <3, 60000> would result in address errors 2600 17000 1800

Allocation

tual memory... m, dole out for process i:

$$S = \sum_{i=0}^{n} s_i$$

$$a_i = (s_i/S) \times m$$

The *minimum* frames per process is defined by the architecture The maximum frames per process is upper bounded by frames available

Fragmentation

External occurs when unused space is non-contiguous Internal refers to the unused space within a frame / page

Paging

A page size must be a power of 2, usually between 512 bytes and 1 GB.

The m-n highest order bits are needed to address into the page table.

Logical Address Space
$$= 2^m = 2^4 = 16$$

Page Size $= 2^n = 2^2 = 4$ bytes



Thus, the logical address gives us some (p,d). We use p to index into the page table to find the correct frame (f), with the offset of d (which is from the n lower bits of the address). Thus our physical address is (f, d).

A single datum in logical address space still requires reserving the entire frame for that datum. Internal fragmentation refers to the unused space within a frame/page.

Downsides

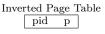
- Every mapping MUST go through page table
- A page table can be implemented via registers, but this limits their size
- One solution is putting it in main memory, and having the PTBR point to where it is

Inverted Page Table

1 byte

A SINGLE page table regardless of how many processes. CPU generates a pid, page number, and offset.

Search the entire page table for $\langle pid, p \rangle$. The index of that entry is the frame number.



Virtual Memory

Page Replacement

FIFO First In First Out LRU Least Recently Used Could be implemented concretely (timestamp), or use a reference bit LFU Least Frequently Used

 \mathbf{RNG} Random

Belady's Anomaly

The phenomenon in which increasing the number of page frames results in an increase in the number of page faults for certain memory access pat-

Effective Access Time

$$EAT = (1 - p) \times ma + p(fault)$$

Copy-on-Write

If two processes rely on the same pages in physical memory, the OS can allocate a single page to both processes. If one process writes to the page, the OS will allocate a new page to the process that wrote to it, and 'copy' the contents of the original page to the new page.

Miscellaneous

- T/F: If segmentation is used, and the total free (unallocated) main memory is 128MB, then the OS can place into main memory a segment of size 64MB. False - Holes might be tiny
- If process p_i needs s_i amount of vir- If total amount of available frames is \bullet RMS is neither optimal nor guaranteed to work even if CPU util is < 1
 - Given n invocations of fork, there will be $2^n 1$ child processes
 - An I/O request would induce a process changing from running -> waiting.
 - For a logical address space of 16 bytes, among which there are 8 pages, and assuming the use of a page table:
 - For the corresponding physical memory, each frame is 2 bytes
 - The last byte of frame 1 has a corresponding logical memory address whose offset is 1
 - The 3 highest bit of the logical address are used to index into the page table.

$$2^4 \Rightarrow m = 4$$

 $2^3 \Rightarrow n = 3$ bits for page table index

16 bytes/8 pages = 2 bytes per page and frame

$$m-n=4-3=1$$
 bit for the offset

Last byte of first frame $= \underbrace{000}_{\text{page index}} 1$

• As the number of frames allocated to each process decreases, overall page fault rate goes up