# Linear Algebra and Geometry 1

Systems of equations, matrices, vectors, and geometry

#### Linear transformations

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An introduction to linear operations

Linear operations preserve linear combinations

## Differentiation is a linear operation

$$(f+g)' = f' + g'$$

$$(\alpha f)' = \alpha f'$$

$$(\alpha f + \beta g)' = \alpha f' + \beta g'$$

### Integration is linear

$$\int_{a}^{b} (f(x) + g(x))dx = \int_{a}^{b} f(x)dx + \int_{a}^{b} g(x)dx$$

$$\int_{a}^{b} \alpha f(x) dx = \alpha \int_{a}^{b} f(x) dx$$

$$\int_{a}^{b} (\alpha f(x) + \beta g(x))dx = \alpha \int_{a}^{b} f(x)dx + \beta \int_{a}^{b} g(x)dx$$

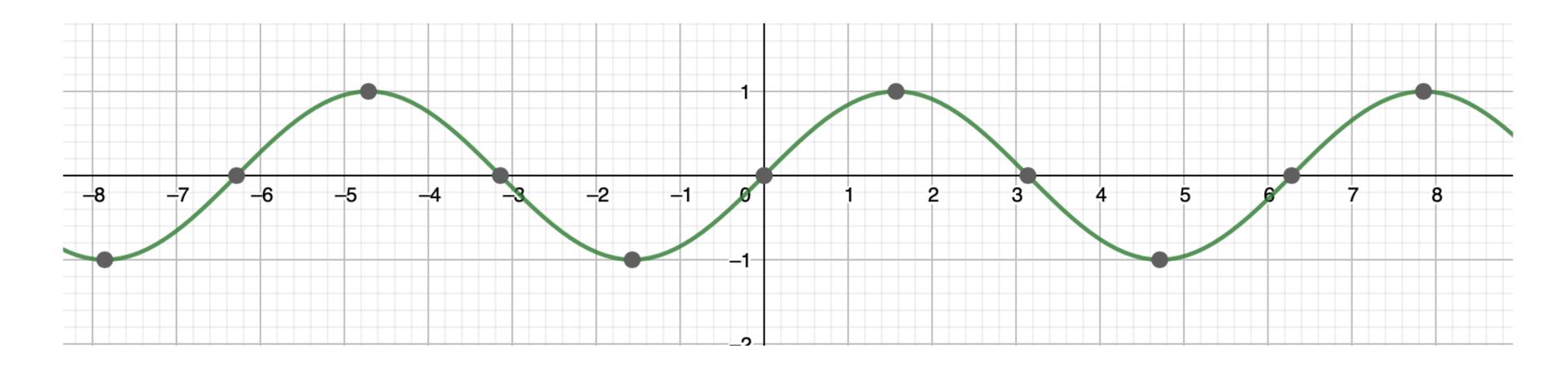
#### Sine is not a linear function

$$\sin(x+y) \neq \sin x + \sin y$$

$$\sin(x+y) = \sin x \cos y + \sin y \cos x$$

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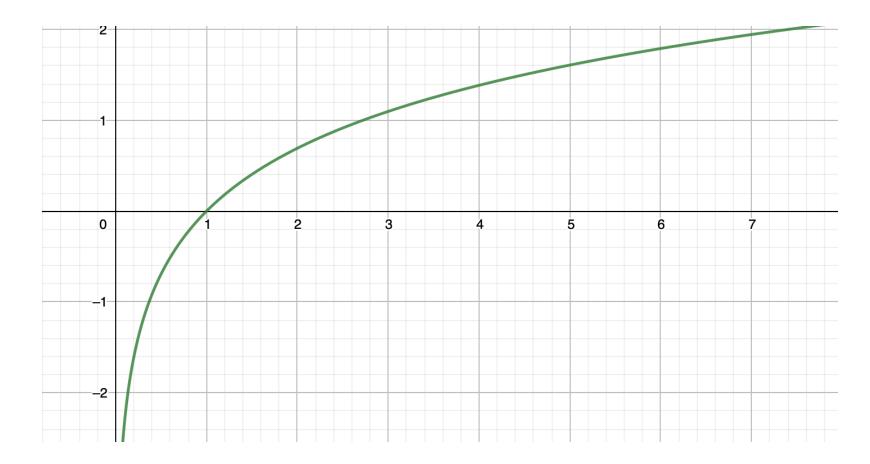
## Logarithm is not a linear function

$$\ln(x+y) \neq \ln x + \ln y$$

$$\ln(xy) = \ln x + \ln y$$

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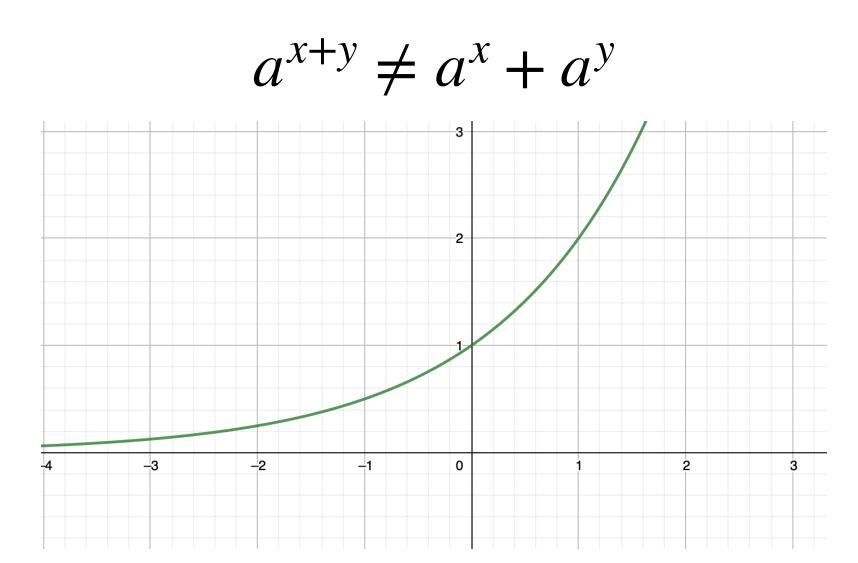
$$\ln(xy) = \ln x + \ln y$$

# Exponential function is not linear

$$a^{x+y} \neq a^x + a^y$$

$$a^{x+y} = a^x \cdot a^y$$

## Exponential function is not linear



$$a^{x+y} = a^x \cdot a^y$$

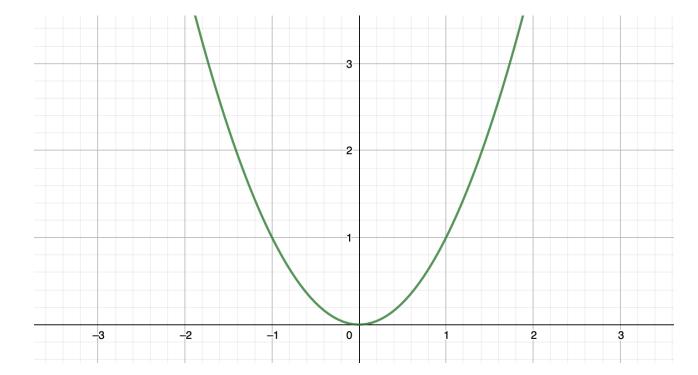
#### Power functions are not linear

$$(x+y)^2 \neq x^2 + y^2$$

$$(x+y)^2 = x^2 + 2xy + y^2$$

### Power functions are not linear

$$(x+y)^2 \neq x^2 + y^2$$



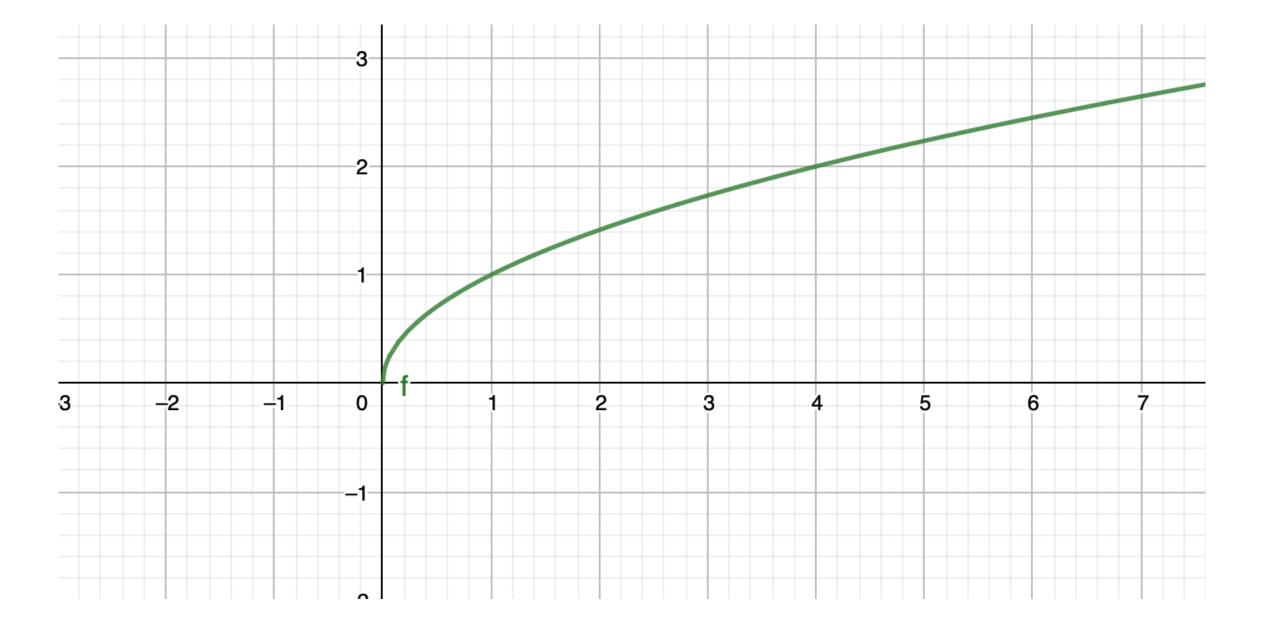
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## Square root is not a linear function

$$\sqrt{x+y} \neq \sqrt{x} + \sqrt{y}$$

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Functions, generally

#### Domain, codomain, range

$$f: X \to Y$$

$$D_f \subset X$$
 all the possible arguments

Y

$$V_f \subset Y$$
  $V_f = \{ y; y = f(x) \text{ for some } x \in D_f \}$ 

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$$f\colon \mathbb{R} \to \mathbb{R}, \quad f(x) = \frac{1}{x}$$

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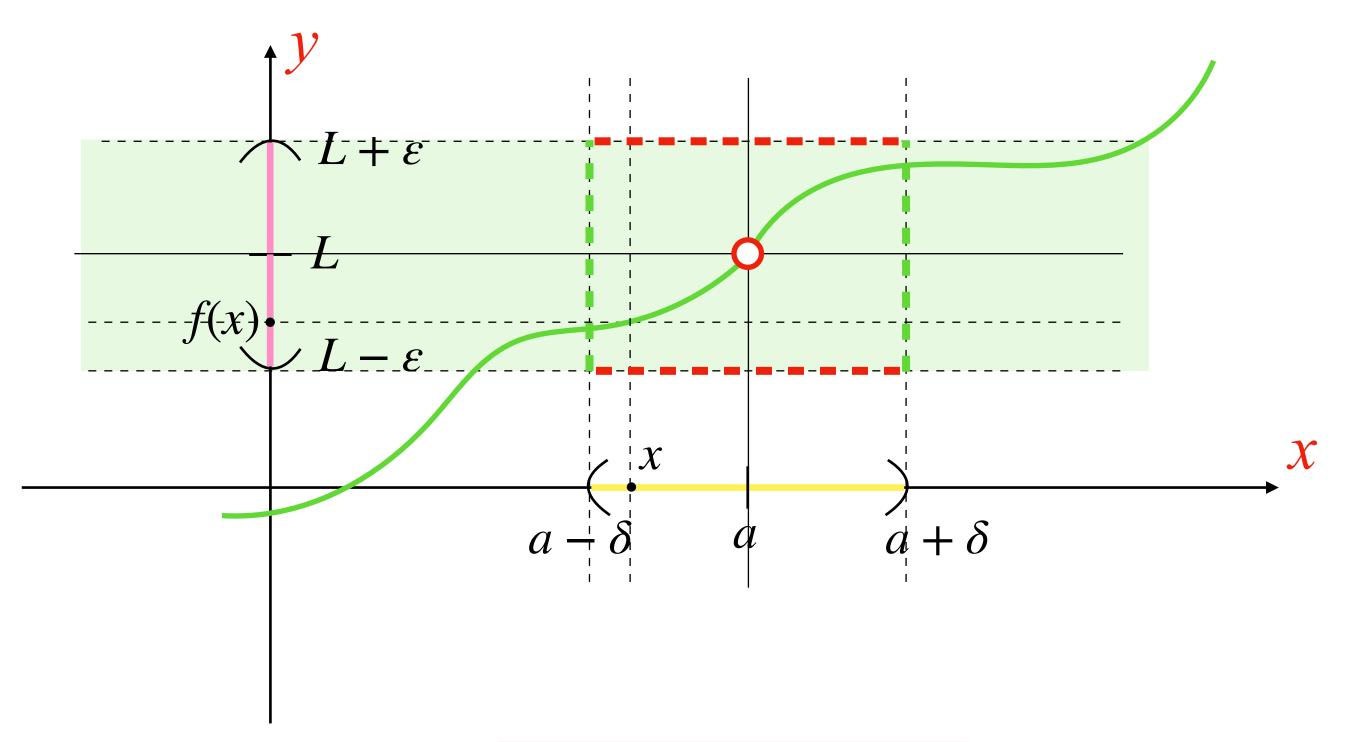
$$D_f = \mathbb{R} \setminus \{0\} = V_f$$

Functions in Calculus 1

Continuous functions

$$\lim_{x \to a} f(x) = L$$

$$\forall \varepsilon > 0 \quad \exists \delta > 0 \quad \forall x \in D_f \quad 0 < |x - a| < \delta \quad \Rightarrow \quad |f(x) - L| < \varepsilon$$

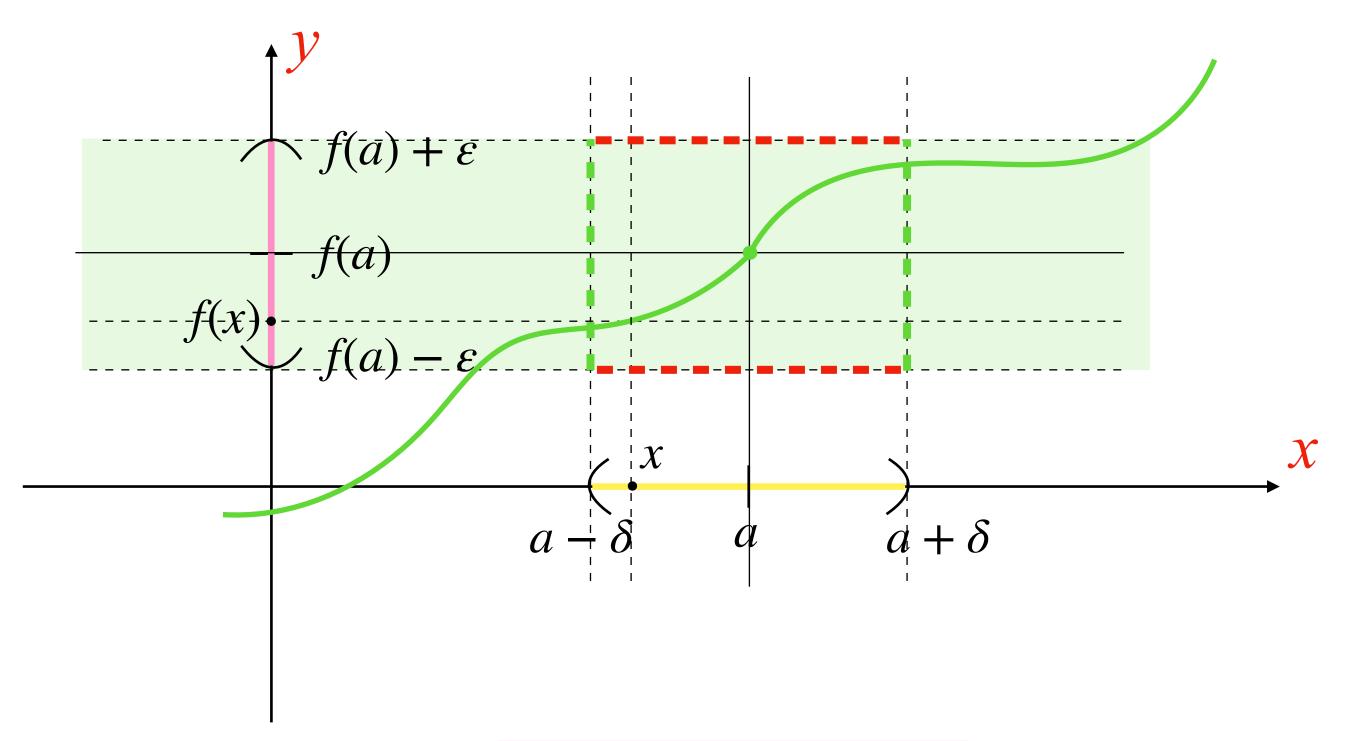


The values f(x) can get arbitrarily close ( $\varepsilon$ -close) to L if only the arguments x are close enough ( $\delta$ -close) the point a

$$x \to a \Rightarrow |f(x) - L| \to 0$$

$$\lim_{x \to a} f(x) = f(a)$$

$$\forall \varepsilon > 0 \quad \exists \delta > 0 \quad \forall x \in D_f \quad |x - a| < \delta \quad \Rightarrow \quad |f(x) - f(a)| < \varepsilon$$



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Functions in Linear Algebra

Linear transformations

 $T: \mathbb{R}^n \to \mathbb{R}^m$ 

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$$T(\mathbf{x} + \mathbf{y}) = T(\mathbf{x}) + T(\mathbf{y})$$

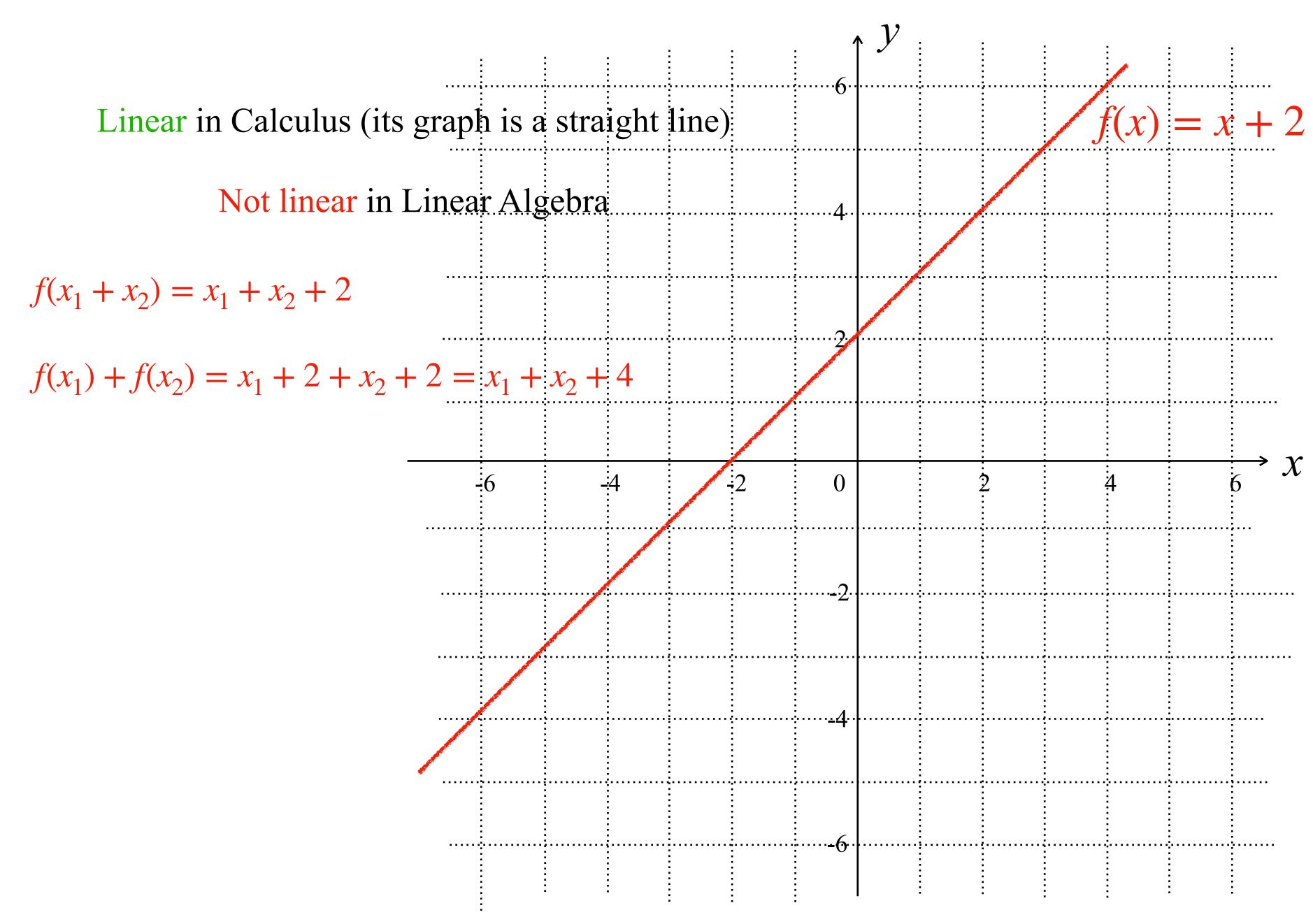
$$T(\alpha \mathbf{x}) = \alpha T(\mathbf{x})$$

$$T:\mathbb{R}^n\to\mathbb{R}^m$$

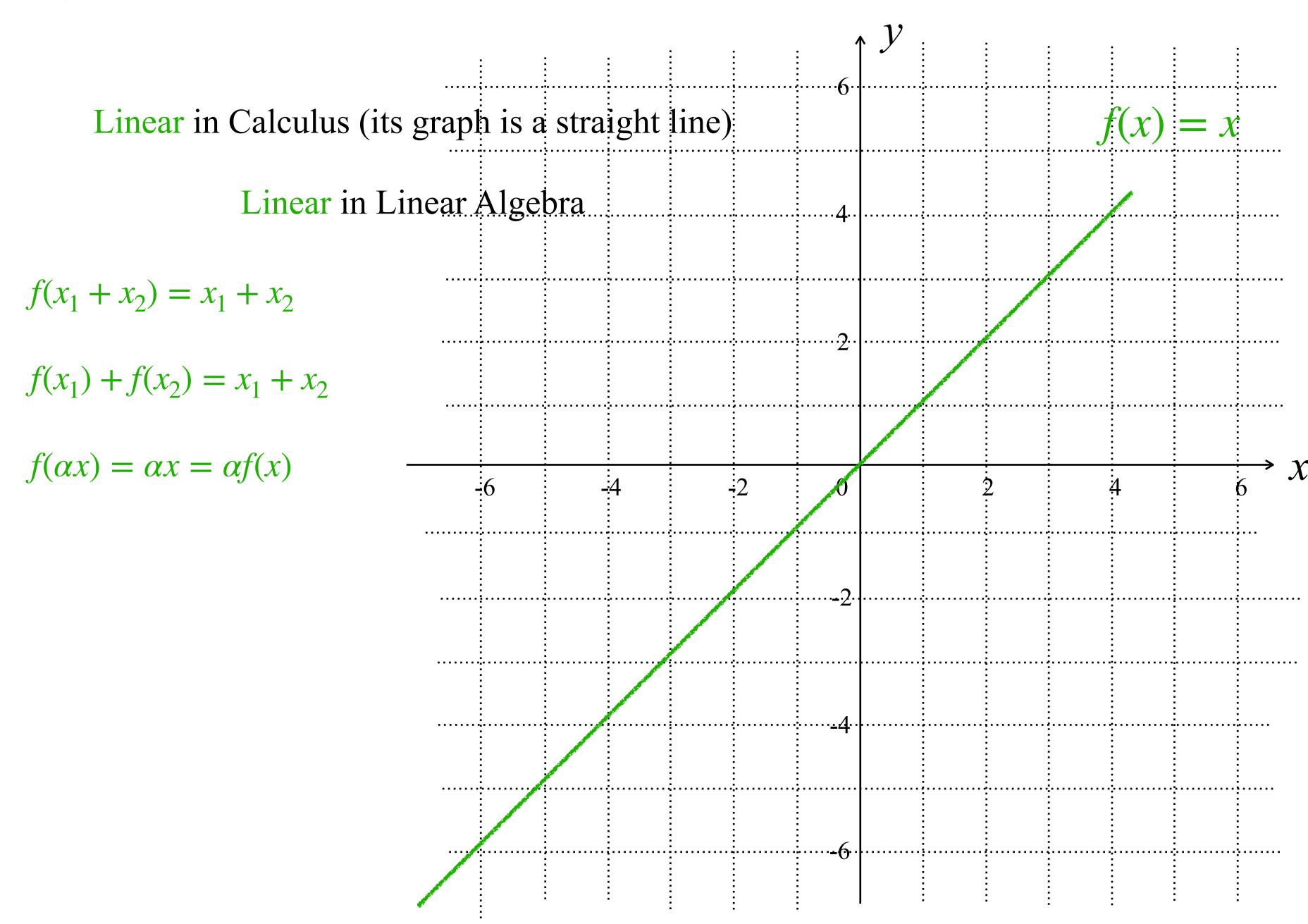
$$T(\mathbf{x} + \mathbf{y}) = T(\mathbf{x}) + T(\mathbf{y})$$
  
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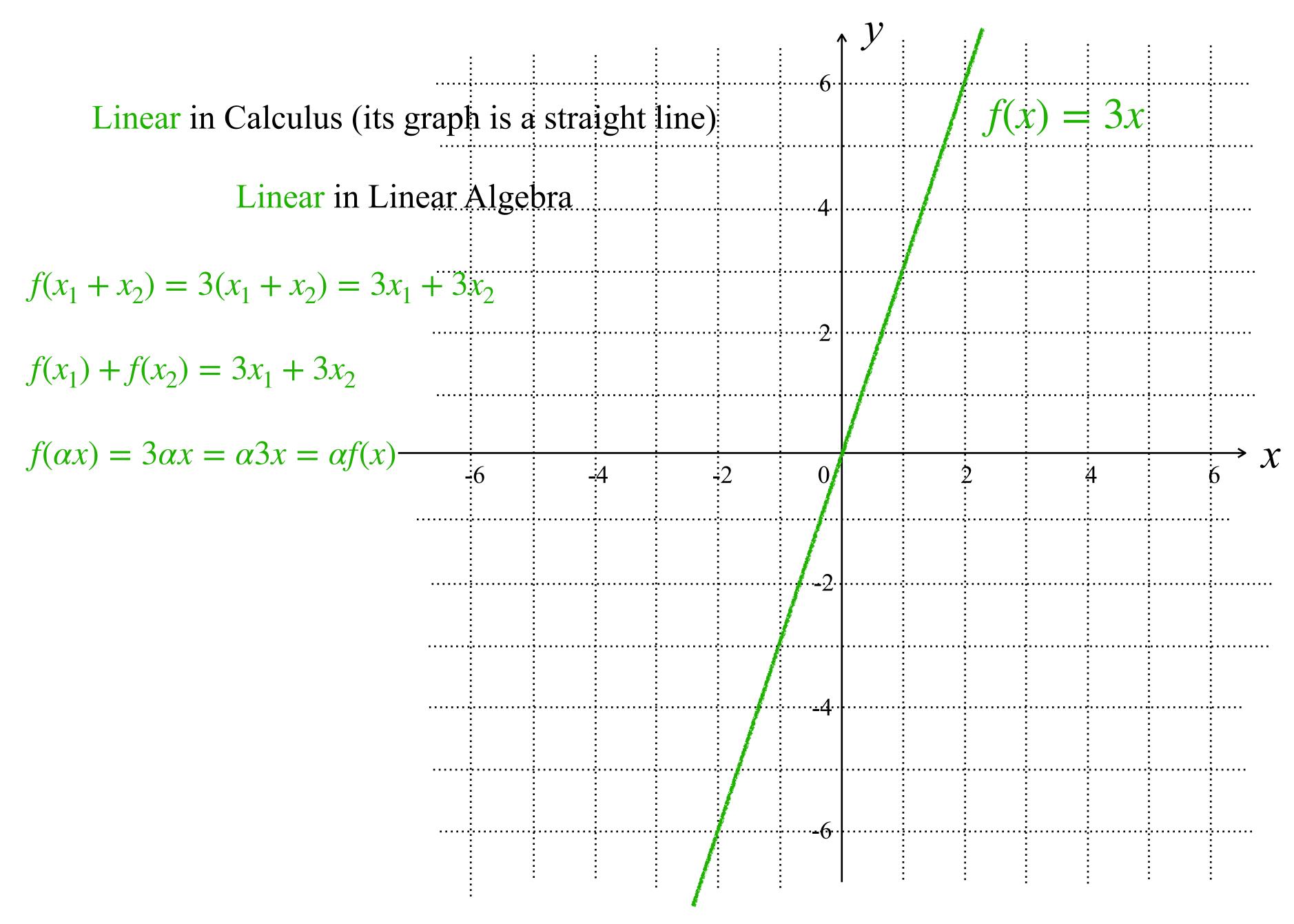
The image of a linear combination of two vectors is the same linear combination of the images of the vectors.



#### $T:\mathbb{R} \to \mathbb{R}$



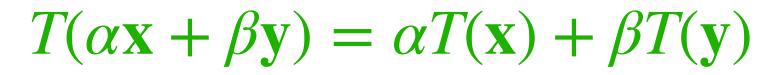
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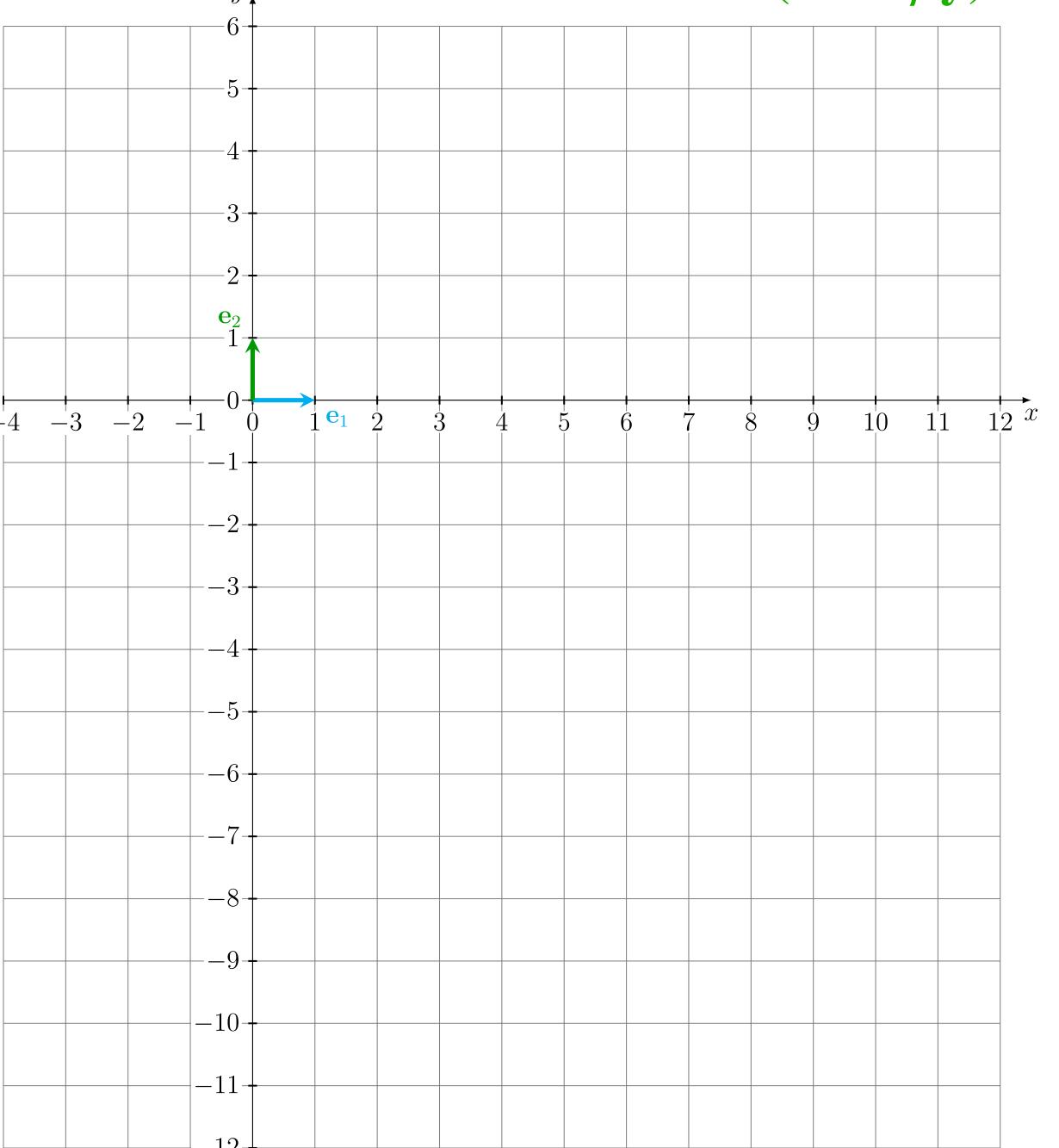


$$T: \mathbb{R}^2 \to \mathbb{R}^2$$

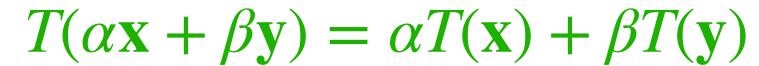
$$T(\alpha \mathbf{x} + \beta \mathbf{y}) = \alpha T(\mathbf{x}) + \beta T(\mathbf{y})$$

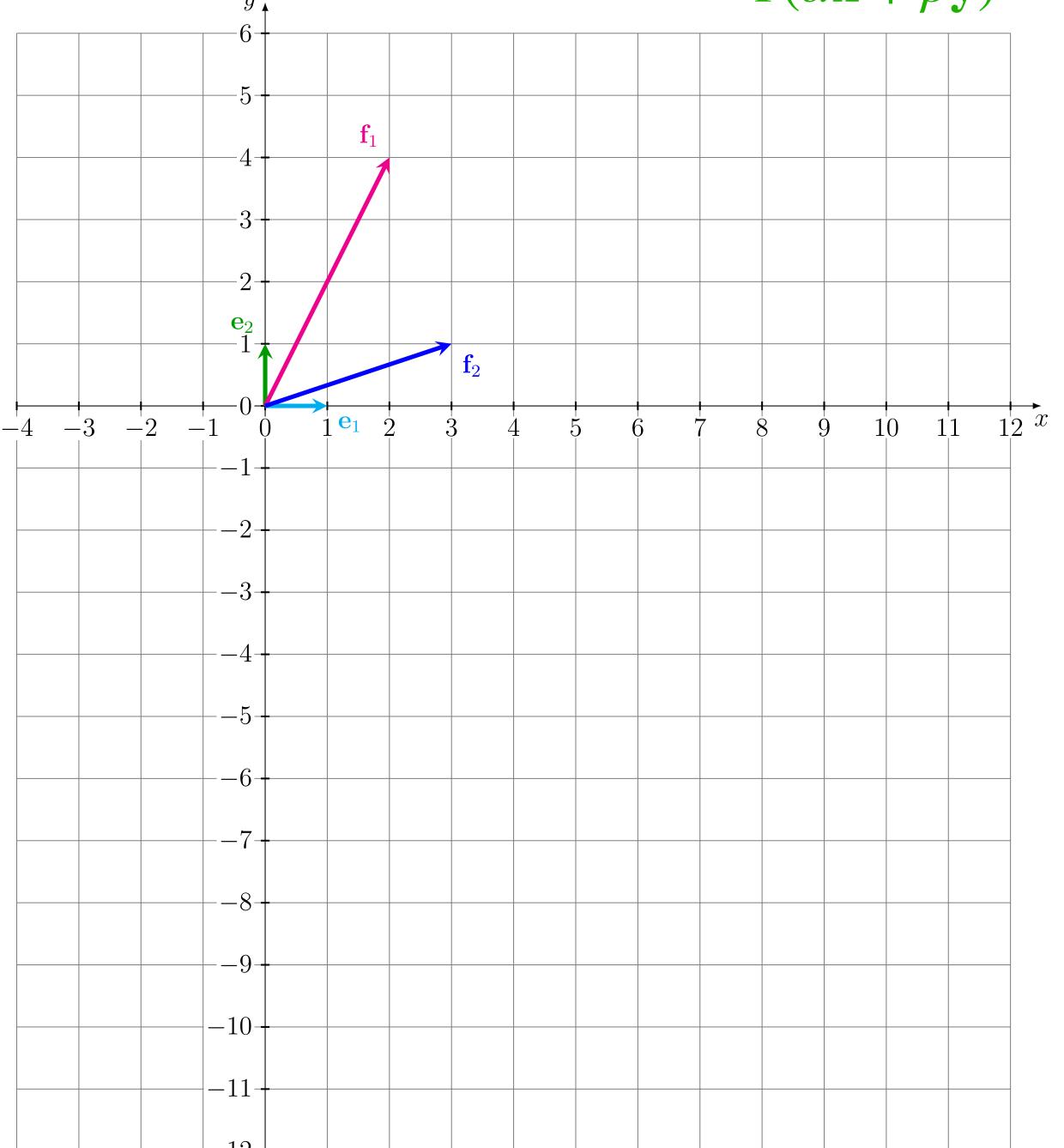
$$T(\mathbf{e}_1) = \begin{bmatrix} 2 \\ 4 \end{bmatrix} = \mathbf{f}_1, \quad T(\mathbf{e}_2) = \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \mathbf{f}_2$$





$$T(\mathbf{e}_1) = \begin{bmatrix} 2\\4 \end{bmatrix} = \mathbf{f}_1, \quad T(\mathbf{e}_2) = \begin{bmatrix} 3\\1 \end{bmatrix} = \mathbf{f}_2$$

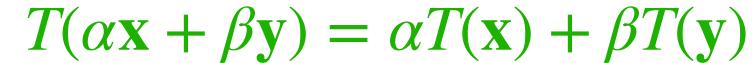


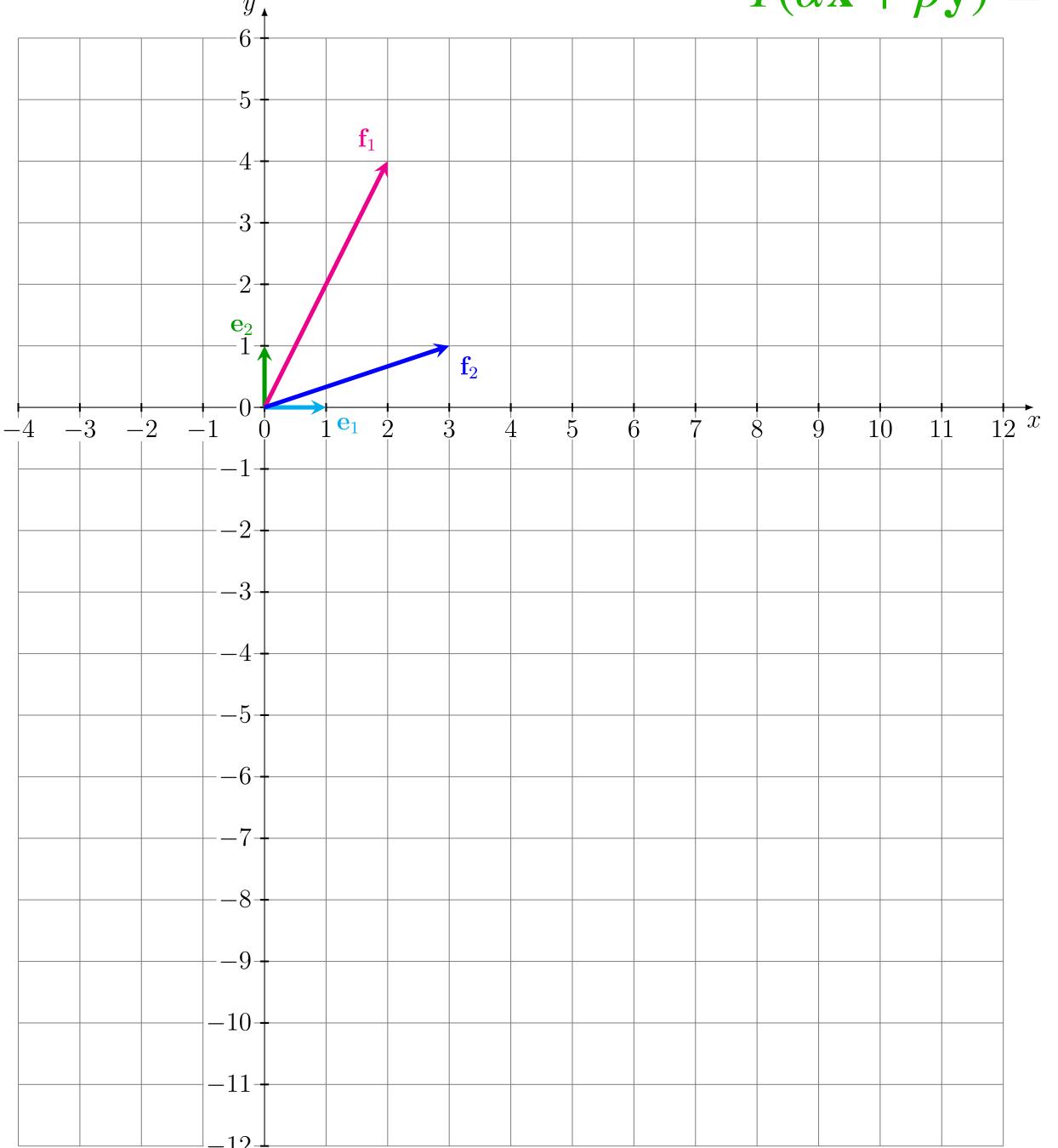


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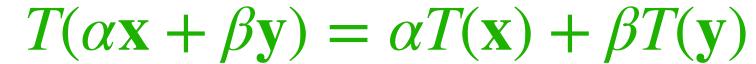


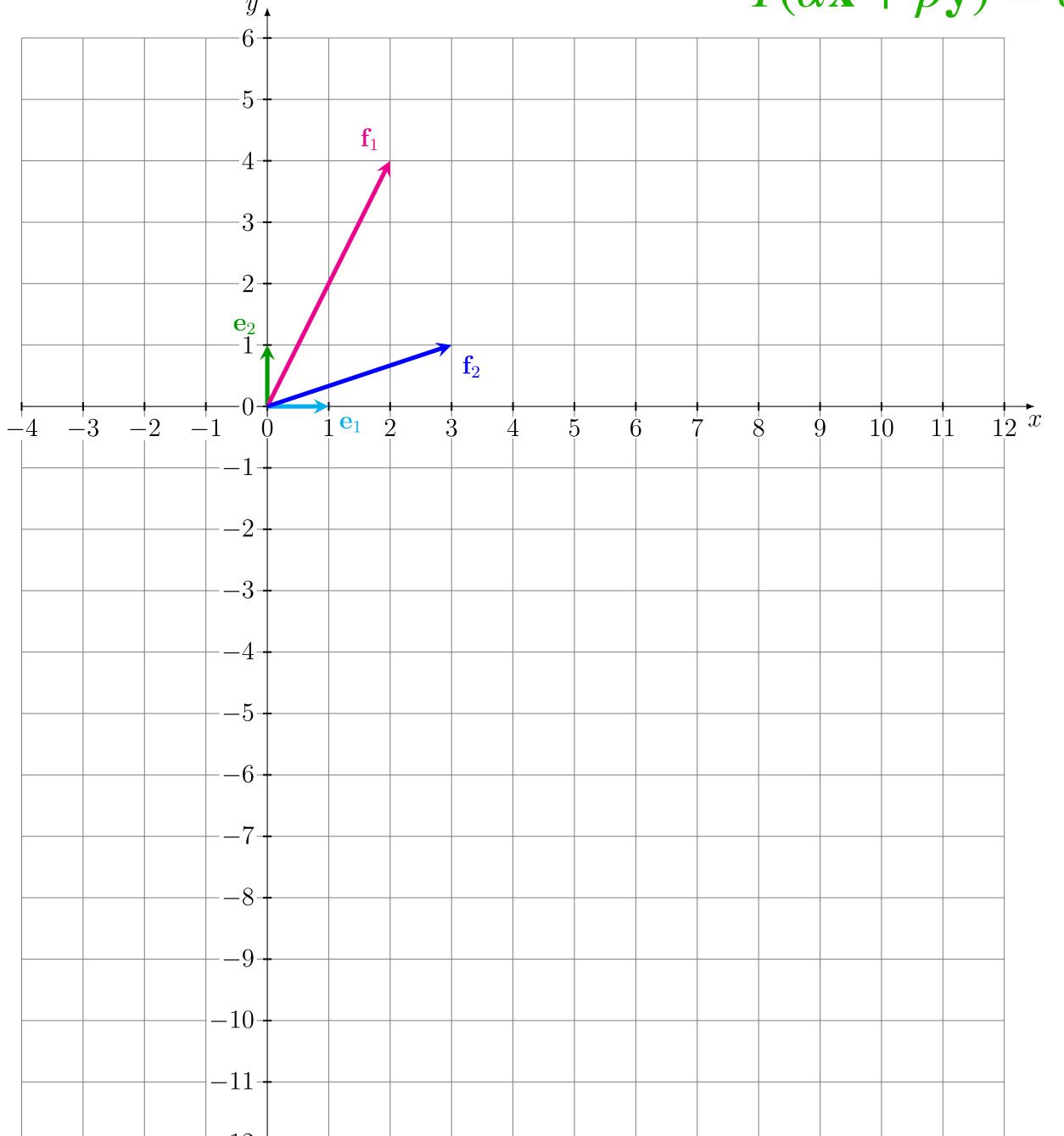
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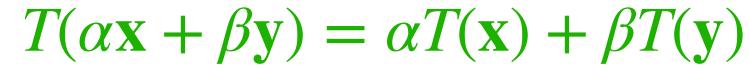


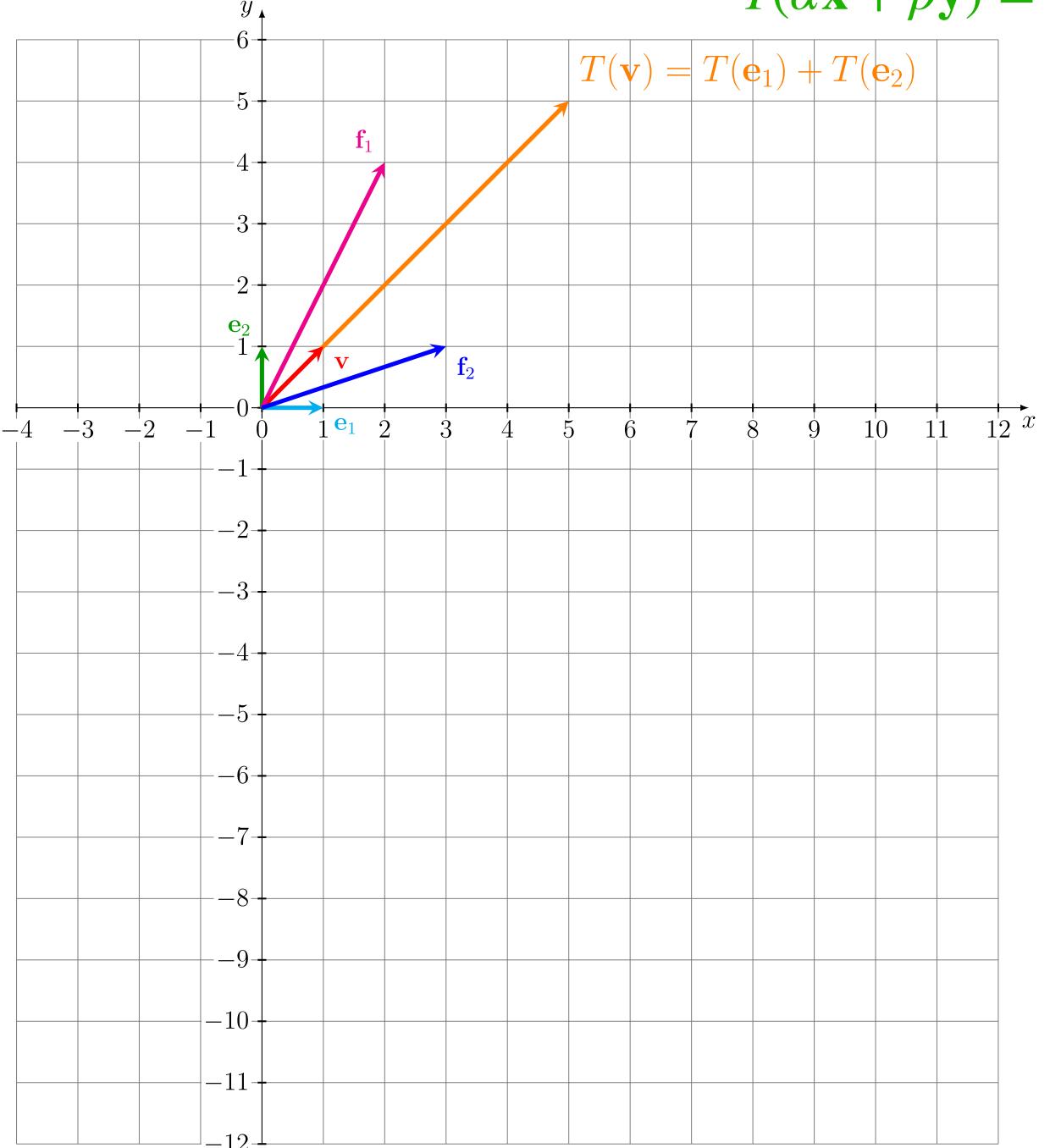
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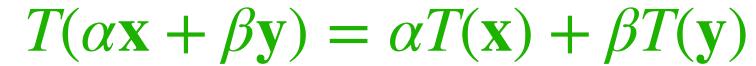


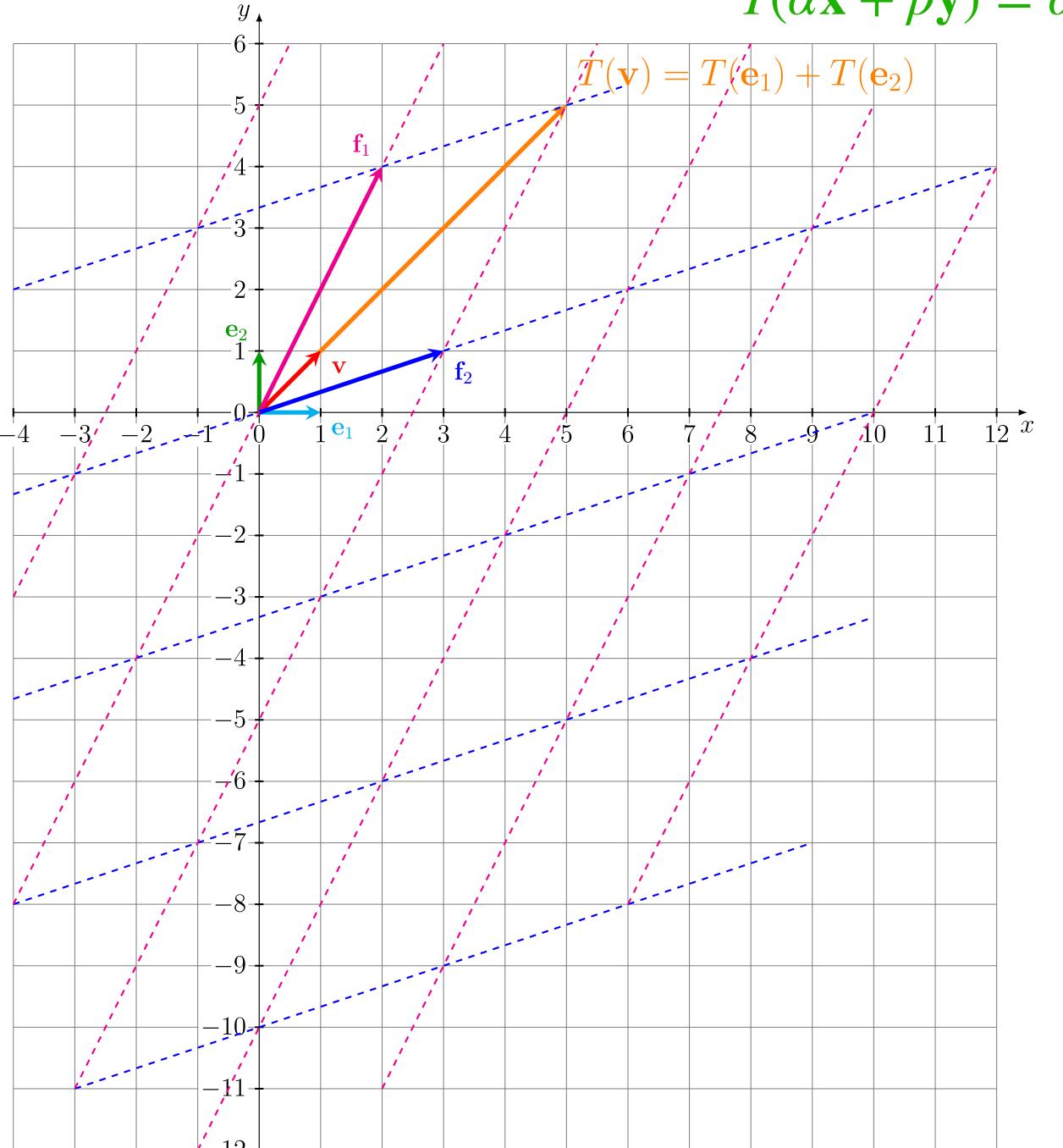
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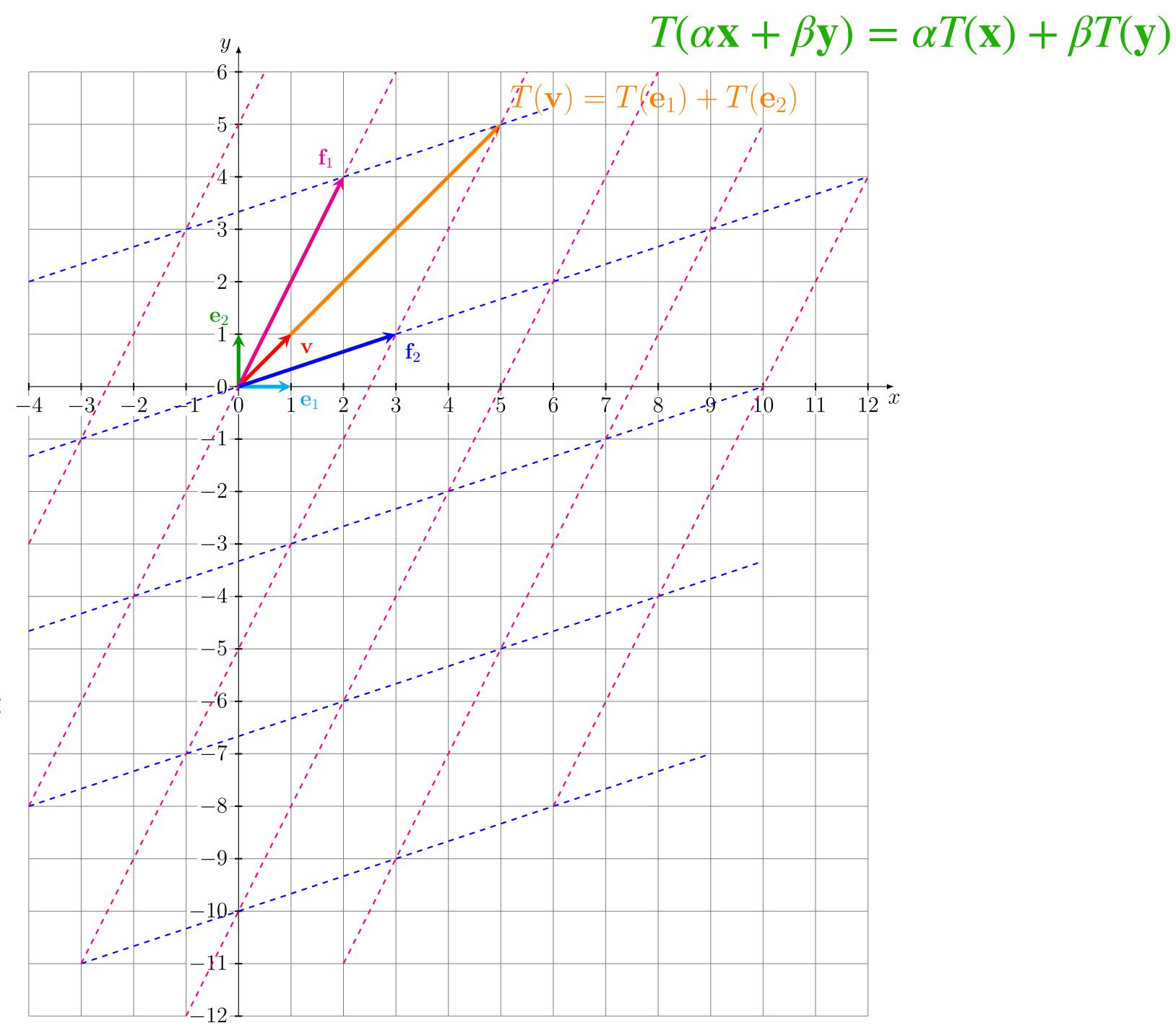


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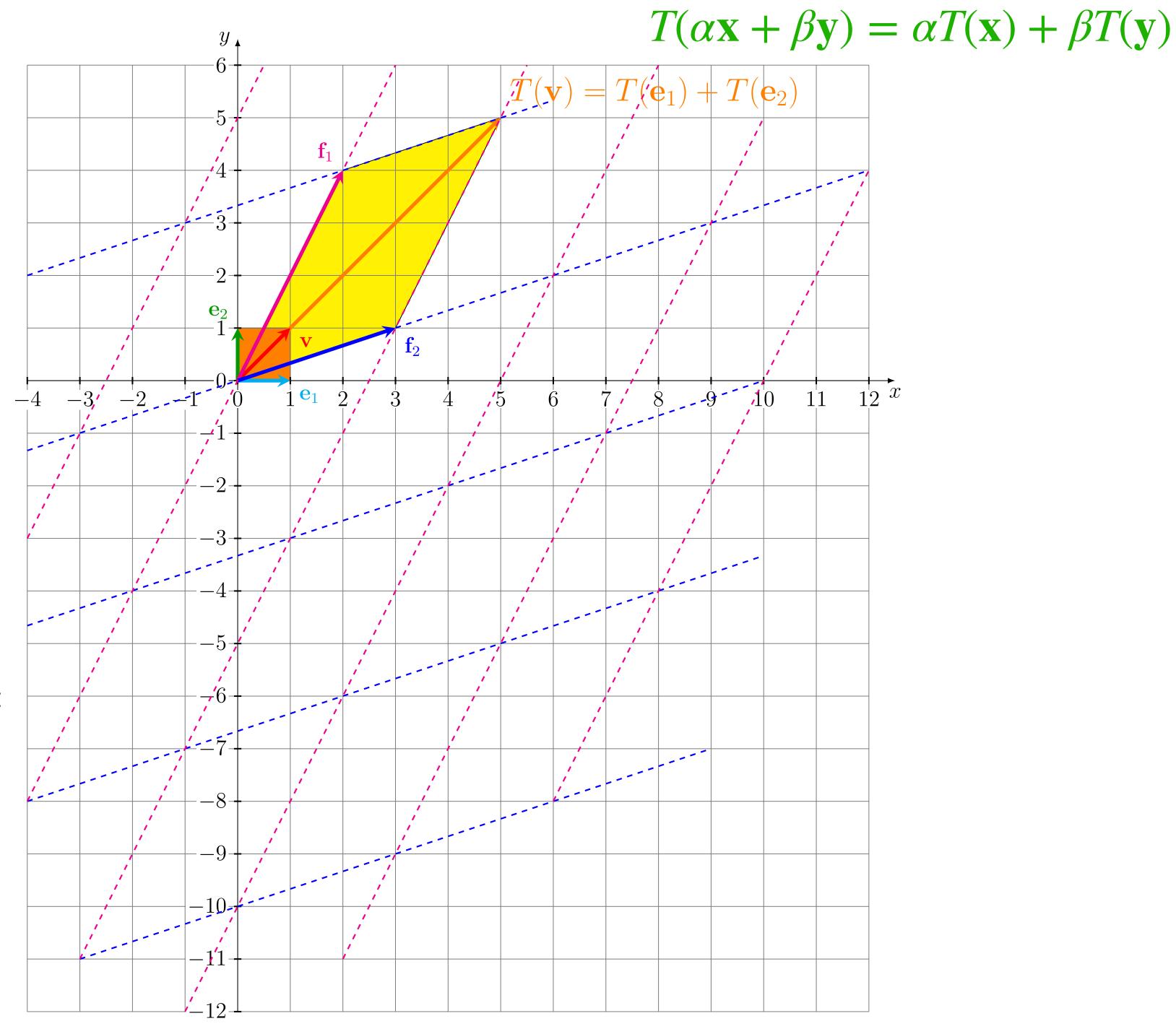


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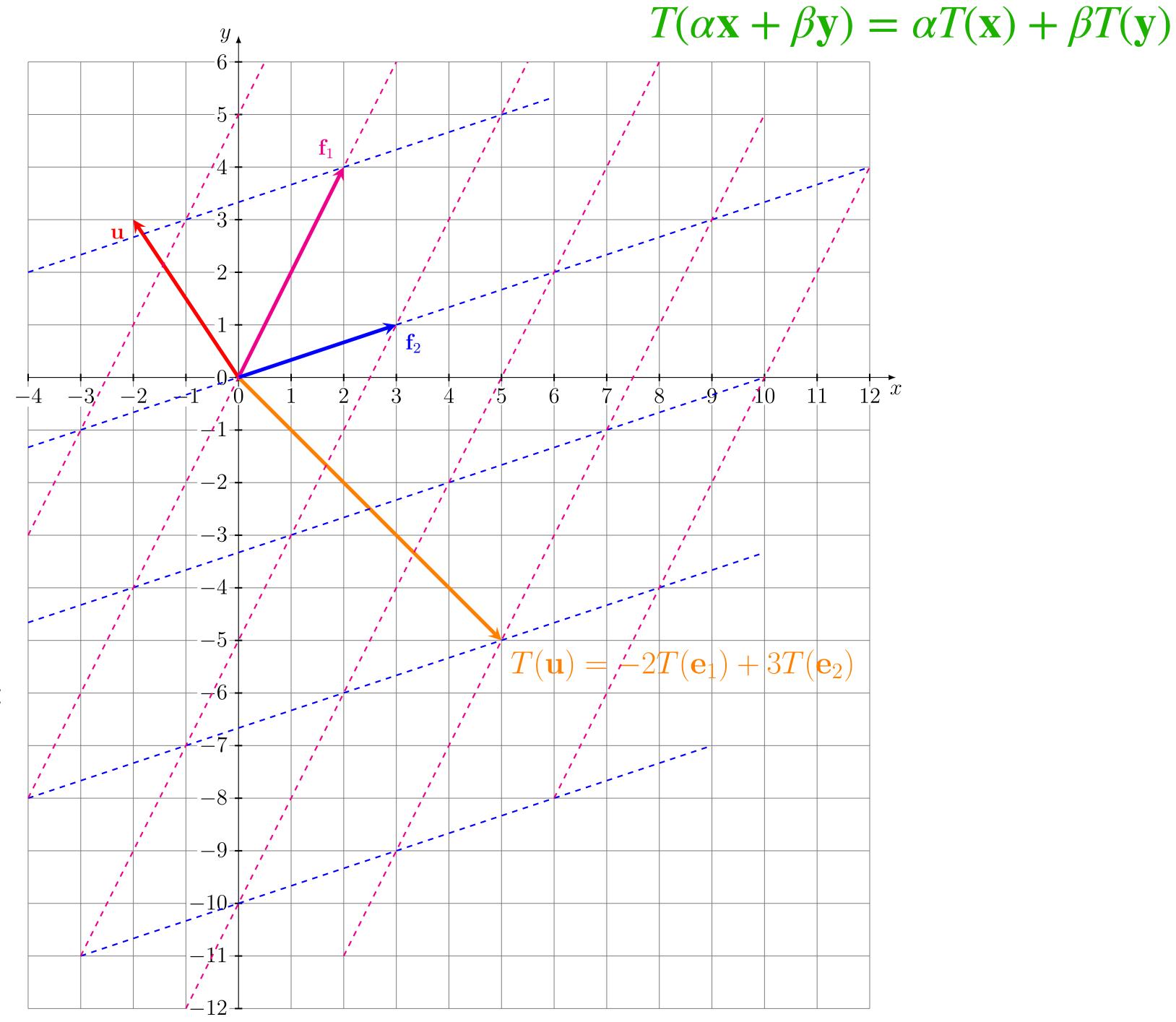


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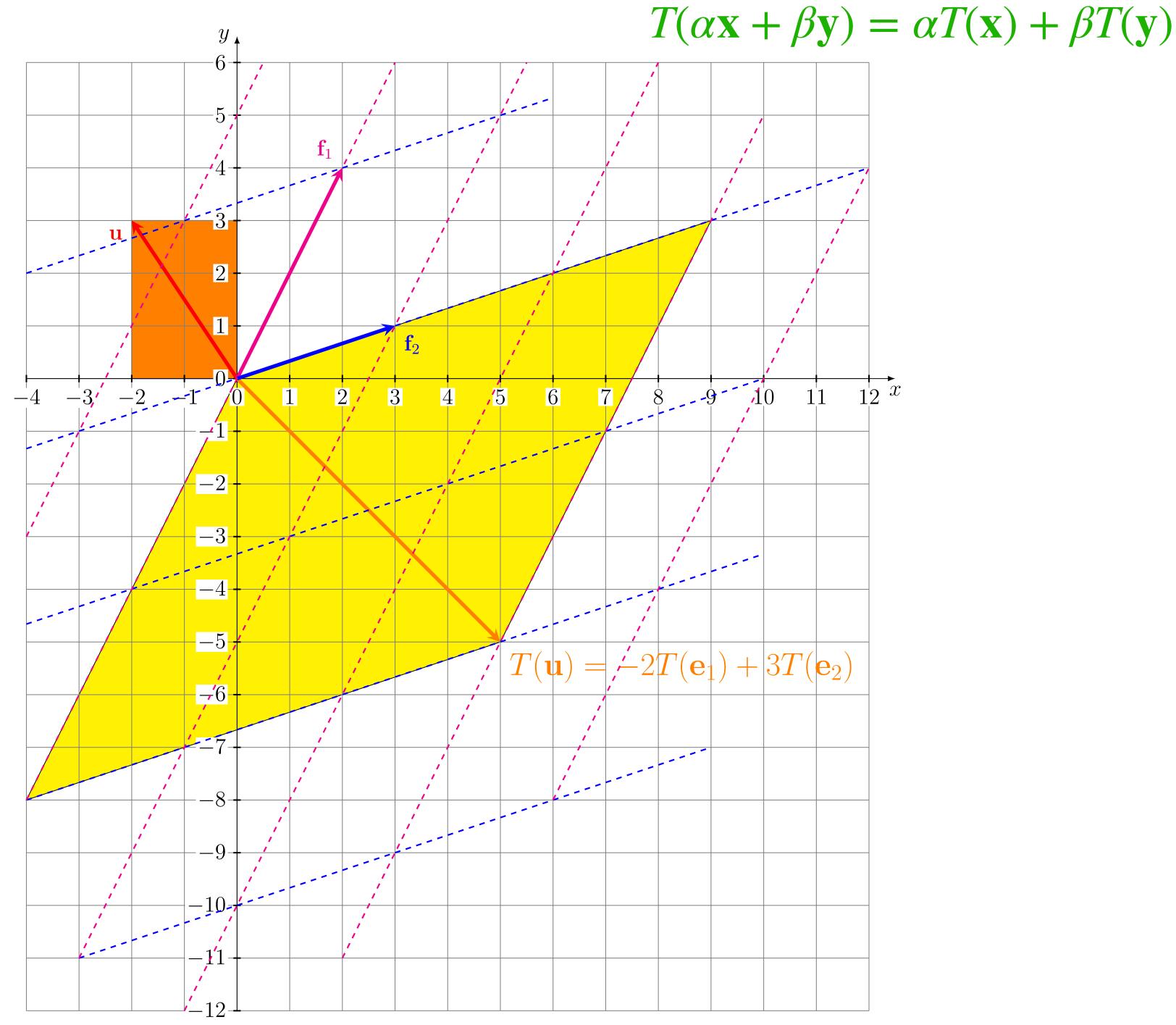


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