



Roadmap

- Motivation
- Matrix tools
- Tensor tools
- Case studies

- Tensor Basics
- Tucker
 - Tucker 1
 - Tucker 2
 - Tucker 3
- PARAFAC
- Incrementalization



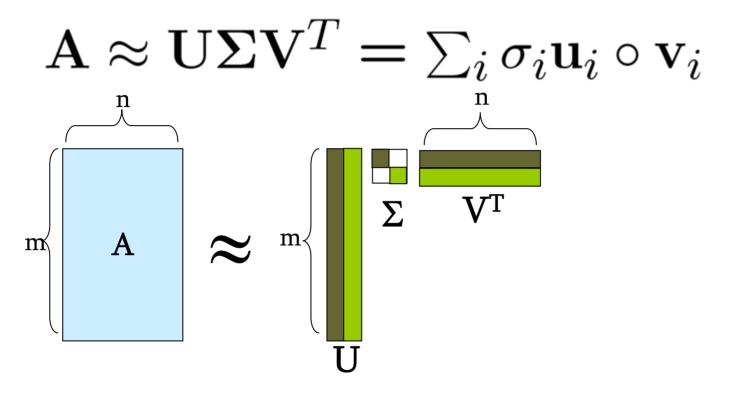


Tensor Basics





Reminder: SVD

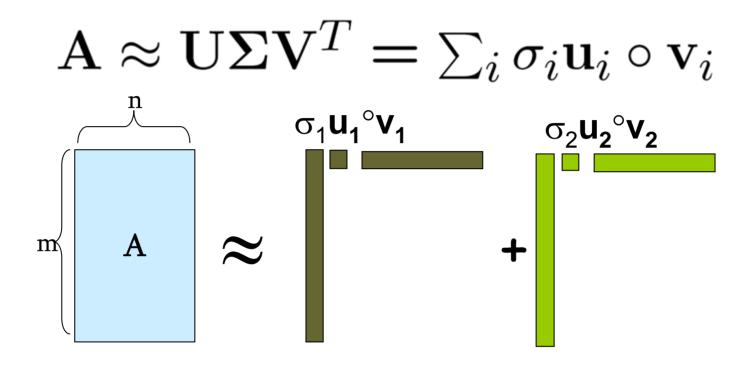


Best rank-k approximation in L2





Reminder: SVD

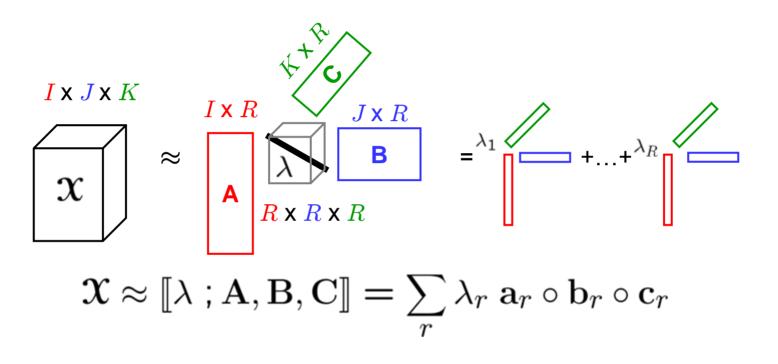


Best rank-k approximation in L2





Goal: extension to >=3 modes







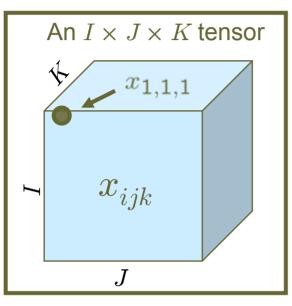
Main points:

- 2 major types of tensor decompositions: PARAFAC and Tucker
- both can be solved with ``alternating least squares'' (ALS)
- Details follow we start with terminology:



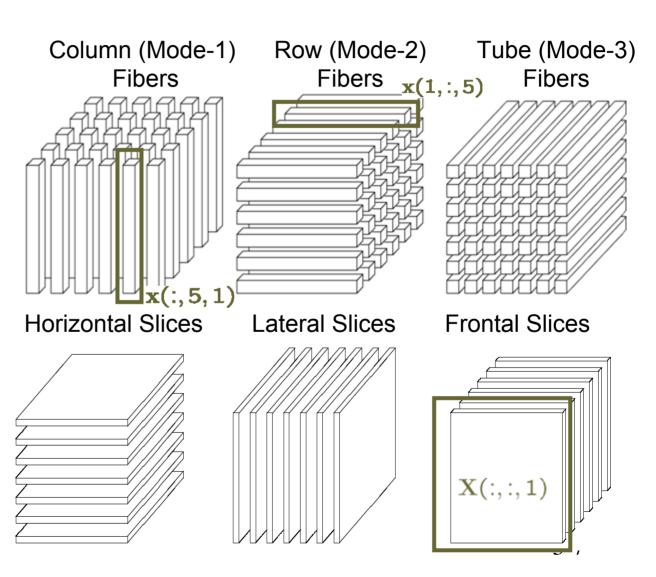


A tensor is a multidimensional array



 $3^{\rm rd}$ order tensor mode 1 has dimension I mode 2 has dimension J mode 3 has dimension K

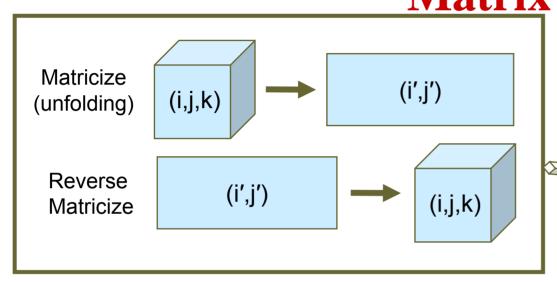
Note: Tutorial focus is on 3rd order, but everything can be extended to higher orders.



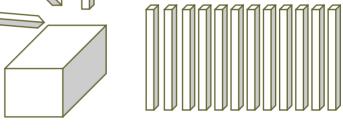




Matrization: Converting a Tensor to a **Matrix**



 $X_{(n)}$: The mode-**n** fibers are rearran ed to be the columns ্ৰ ma rix



$$x = \begin{bmatrix} 1 & 5 & 7 \\ 2 & 6 & 8 \\ 2 & 4 & 8 \end{bmatrix}$$

$$\mathbf{X_{(1)}} = \begin{bmatrix} 1 & 3 & 5 & 7 \\ 2 & 4 & 6 & 8 \end{bmatrix}$$

$$\mathbf{X}_{(2)} = \begin{vmatrix} 1 & 2 & 5 & 6 \\ 3 & 4 & 7 & 8 \end{vmatrix}$$

$$\mathbf{X}_{(2)} = \begin{bmatrix} 1 & 2 & 5 & 6 \\ 3 & 4 & 7 & 8 \end{bmatrix}$$
$$\mathbf{X}_{(3)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{bmatrix}$$

$$\mathbf{x}$$
 $\mathbf{x}_{(3)}$

$$VectoriZation$$

$$Vec(x) = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \end{bmatrix}$$

$$3-8$$





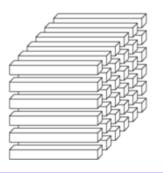
Tensor Mode-n Multiplication

$$\mathbf{X} \in \mathbb{R}^{I \times J \times K}, \ \mathbf{B} \in \mathbb{R}^{M \times J}, \ \mathbf{a} \in \mathbb{R}^{I}$$

Tensor Times Matrix

$$\mathbf{\mathcal{Y}} = \mathbf{\mathcal{X}} \times_{\mathbf{2}} \mathbf{B} \in \mathbb{R}^{I \times M \times K}$$
$$y_{imk} = \sum_{j} x_{ijk} b_{mj}$$
$$\mathbf{Y}_{(2)} \stackrel{j}{=} \mathbf{B} \mathbf{X}_{(2)}$$

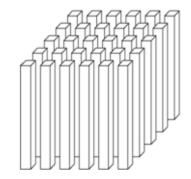
Multiply each row (mode-2) fiber by **B**



Tensor Times Vector

$$\mathbf{Y} = \mathbf{X} \,\bar{\mathbf{x}}_{\mathbf{1}} \,\mathbf{a} \in \mathbb{R}^{J \times K}$$
$$y_{jk} = \sum_{\mathbf{i}} x_{\mathbf{i}jk} \,a_{\mathbf{i}}$$

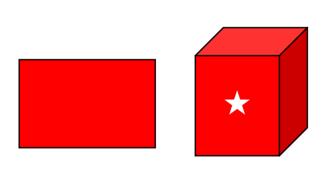
Compute the dot product of a and each column (mode-1) fiber







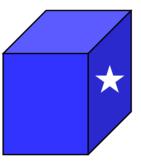
Pictorial View of Mode-n Matrix Multiplication

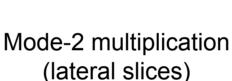


Mode-1 multiplication (frontal slices)

$$\mathbf{\mathcal{Y}} = \mathbf{\mathcal{X}} \times_1 \mathbf{A}$$

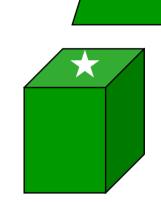
 $\mathbf{Y}_{::k} = \mathbf{X}_{::k} \mathbf{A}^\mathsf{T}$





$$\mathbf{\mathcal{Y}} = \mathbf{\mathcal{X}} \times_2 \mathbf{B}$$

 $\mathbf{Y}_{:j:} = \mathbf{X}_{:j:} \mathbf{B}^\mathsf{T}$



Mode-3 multiplication (horizontal slices)

$$\mathbf{\mathcal{Y}} = \mathbf{\mathcal{X}} \times_{3} \mathbf{C}$$

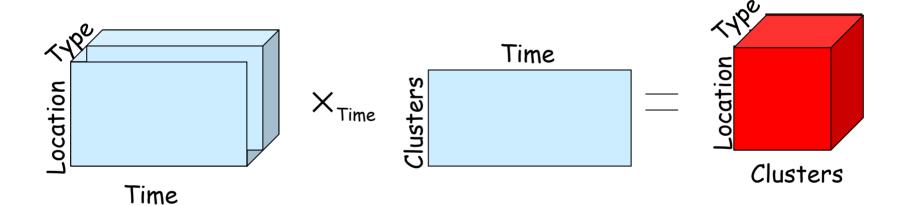
 $\mathbf{Y}_{i::} = \mathbf{X}_{i::} \mathbf{C}^{\mathsf{T}}$





Mode-n product Example

• Tensor times a matrix

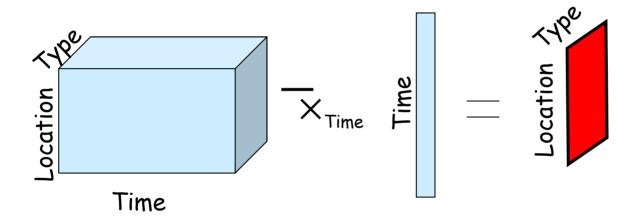






Mode-n product Example

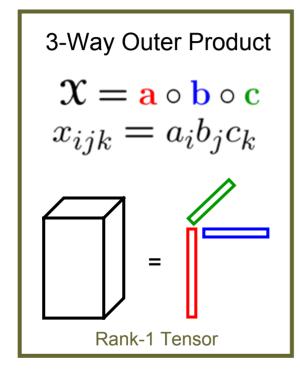
Tensor times a vector







Outer, Kronecker, & Khatri-Rao Products



Review: Matrix Kronecker Product
$$\mathbf{A} \otimes \mathbf{B} = \begin{bmatrix} a_{11}\mathbf{B} & a_{12}\mathbf{B} & \cdots & a_{1N}\mathbf{B} \\ a_{21}\mathbf{B} & a_{22}\mathbf{B} & \cdots & a_{2N}\mathbf{B} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1}\mathbf{B} & a_{M2}\mathbf{B} & \cdots & a_{MN}\mathbf{B} \end{bmatrix}$$
$$= \begin{bmatrix} \mathbf{a}_1 \otimes \mathbf{b}_1 & \mathbf{a}_1 \otimes \mathbf{b}_2 & \cdots & \mathbf{a}_N \otimes \mathbf{b}_Q \end{bmatrix}$$

Matrix Khatri-Rao Product

$$\mathbf{A} \odot \mathbf{B} = \begin{bmatrix} \mathbf{a}_1 \otimes \mathbf{b}_1 & \mathbf{a}_2 \otimes \mathbf{b}_2 & \cdots & \mathbf{a}_R \otimes \mathbf{b}_R \end{bmatrix}$$

<u>Observe</u>: For two vectors **a** and **b**, $\mathbf{a} \circ \mathbf{b}$ and $\mathbf{a} \otimes \mathbf{b}$ have the same elements, but one is shaped into a matrix and the other into a vector.



Specially Structured Tensors





Specially Structured Tensors

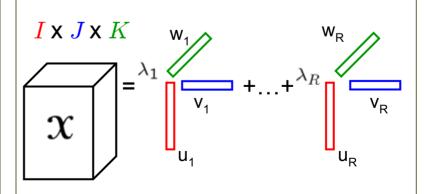
• Tucker Tensor

$$\mathfrak{X} = \mathfrak{S} \times_{1} \mathbf{U} \times_{2} \mathbf{V} \times_{3} \mathbf{W} \\
= \sum_{r} \sum_{s} \sum_{t} g_{rst} \mathbf{u}_{r} \circ \mathbf{v}_{s} \circ \mathbf{w}_{t} \\
\equiv \llbracket \mathfrak{G} ; \mathbf{U}, \mathbf{V}, \mathbf{W} \rrbracket \right] \xrightarrow{\text{Our}} \underset{\text{Notation}}{\text{Our}} \\
\stackrel{\text{"core"}}{\text{V}} = \boxed{\mathbf{U}} \xrightarrow{\mathbf{R} \times \mathbf{S} \times T}$$

Kruskal Tensor

$$\mathbf{\mathcal{X}} = \sum_{r} \lambda_r \ \mathbf{u}_r \circ \mathbf{v}_r \circ \mathbf{w}_r$$

$$\equiv [\![\lambda \ ; \mathbf{U}, \mathbf{V}, \mathbf{W}]\!]$$
Our Notation







Specially Structured Tensors

• Tucker Tensor

$$\mathfrak{X} = \mathfrak{G} \times_{1} \mathbf{U} \times_{2} \mathbf{V} \times_{3} \mathbf{W}
= \sum_{r} \sum_{s} \sum_{t} g_{rst} \mathbf{u}_{r} \circ \mathbf{v}_{s} \circ \mathbf{w}_{t}
\equiv \llbracket \mathfrak{G} ; \mathbf{U}, \mathbf{V}, \mathbf{W} \rrbracket$$

In matrix form:

$$\mathbf{X}_{(1)} = \mathbf{U}\mathbf{G}_{(1)}(\mathbf{W} \otimes \mathbf{V})^{\mathsf{T}}$$
$$\mathbf{X}_{(2)} = \mathbf{V}\mathbf{G}_{(2)}(\mathbf{W} \otimes \mathbf{U})^{\mathsf{T}}$$
$$\mathbf{X}_{(3)} = \mathbf{W}\mathbf{G}_{(3)}(\mathbf{V} \otimes \mathbf{U})^{\mathsf{T}}$$

$$\mathsf{vec}(\mathfrak{X}) = (\mathbf{W} \otimes \mathbf{V} \otimes \mathbf{U}) \mathsf{vec}(\mathfrak{G})$$

Kruskal Tensor

$$\mathbf{X} = \sum_{r} \lambda_r \ \mathbf{u}_r \circ \mathbf{v}_r \circ \mathbf{w}_r$$
$$\equiv [\![\lambda \ ; \mathbf{U}, \mathbf{V}, \mathbf{W}]\!]$$

In matrix form:

$$\begin{aligned} &\text{Let } \boldsymbol{\Lambda} = \text{diag}(\boldsymbol{\lambda}) \\ \boldsymbol{X}_{(1)} &= \boldsymbol{U} \boldsymbol{\Lambda} \left(\boldsymbol{W} \odot \boldsymbol{V} \right)^\mathsf{T} \\ \boldsymbol{X}_{(2)} &= \boldsymbol{V} \boldsymbol{\Lambda} \left(\boldsymbol{W} \odot \boldsymbol{U} \right)^\mathsf{T} \\ \boldsymbol{X}_{(3)} &= \boldsymbol{W} \boldsymbol{\Lambda} \left(\boldsymbol{V} \odot \boldsymbol{U} \right)^\mathsf{T} \end{aligned}$$

$$\text{vec}(\mathfrak{X}) = (\mathbf{W} \odot \mathbf{V} \odot \mathbf{U}) \lambda$$





What is the HO Analogue of the Matrix SVD?

Matrix SVD:

$$\mathbf{X} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^{\mathsf{T}} = \begin{bmatrix} \mathbf{v}_{1} & \mathbf{v}_{2} & \mathbf{v}_{3} \\ \mathbf{v}_{1} & \mathbf{v}_{2} & \mathbf{v}_{4} \\ \mathbf{v}_{2} & \mathbf{v}_{3} & \mathbf{v}_{4} \end{bmatrix}$$

Tucker Tensor (finding bases for each subspace):

$$\mathbf{X} = \mathbf{\Sigma} \times_1 \mathbf{U} \times_2 \mathbf{V} = \llbracket \mathbf{\Sigma} ; \mathbf{U}, \mathbf{V}
V$$

Kruskal Tensor (sum of rank-1 components):

$$\mathbf{X} = \sum_{r=1}^{n} \sigma_r \ \mathbf{u}_r \circ \mathbf{v}_r = \llbracket \sigma \ ; \mathbf{U}, \mathbf{V} \rrbracket$$

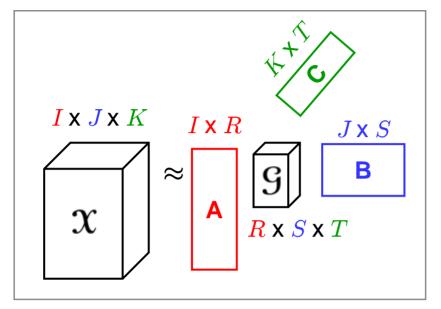


Tensor Decompositions





Tucker Decomposition - intuition



- author x keyword x conference
- A: author x author-group
- B: keyword x keyword-group
- C: conf. x conf-group
- 9: how groups relate to each other





Reminder

term group x doc. group

med. terms

cs terms

common terms

$$\begin{bmatrix} .36 & .36 & .28 & 0 & 0 & 0 \\ 0 & 0 & 0 & .28 & .36 & .36 \end{bmatrix} =$$

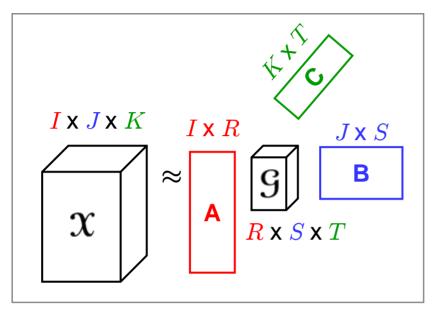
doc x doc group

term x term-group





Tucker Decomposition



$$\mathfrak{X} \approx \llbracket \mathfrak{G} ; \mathbf{A}, \mathbf{B}, \mathbf{C}
bracket$$

Given A, B, C, the optimal core is:

$$\mathcal{G} = [\![\mathfrak{X} ; \mathbf{A}^\dagger, \mathbf{B}^\dagger, \mathbf{C}^\dagger]\!]$$

- Proposed by Tucker (1966)
- AKA: Three-mode factor analysis, three-mode PCA, orthogonal array decomposition
- **A**, **B**, and **C** generally assumed to be orthonormal (generally assume they have full column rank)
- **9** is <u>not</u> diagonal
- Not unique

Recall the equations for converting a tensor to a matrix

$$\begin{aligned} \mathbf{X}_{(1)} &= \mathbf{A}\mathbf{G}_{(1)}(\mathbf{C} \otimes \mathbf{B})^\mathsf{T} \\ \mathbf{X}_{(2)} &= \mathbf{B}\mathbf{G}_{(2)}(\mathbf{C} \otimes \mathbf{A})^\mathsf{T} \\ \mathbf{X}_{(3)} &= \mathbf{C}\mathbf{G}_{(3)}(\mathbf{B} \otimes \mathbf{A})^\mathsf{T} \\ \mathsf{vec}(\mathfrak{X}) &= (\mathbf{C} \otimes \mathbf{B} \otimes \mathbf{A}) \mathsf{vec}(\mathfrak{G}) \end{aligned}$$

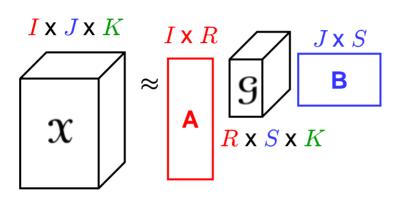




Tucker Variations

See Kroonenberg & De Leeuw, Psychometrika, 1980 for discussion.

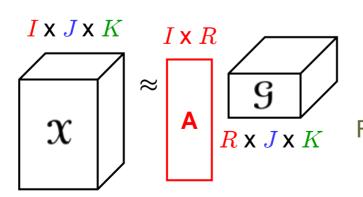
• Tucker2



Identity Matrix

$$\mathbf{X} \approx \llbracket \mathbf{G} ; \mathbf{A}, \mathbf{B}, \mathbf{I}
bracket$$
 $\mathbf{X}_{(3)} \approx \mathbf{G}_{(3)} (\mathbf{B} \otimes \mathbf{A})^\mathsf{T}$

Tucker1



$$\mathbf{X} pprox \llbracket \mathbf{G} \; ; \mathbf{A}, \mathbf{I}, \mathbf{I}
bracket \ \mathbf{X}_{(1)} pprox \mathbf{A} \mathbf{G}_{(1)}$$

Finding principal components in only mode 1 can be solved via rank-R matrix SVD



Solving for Tucker

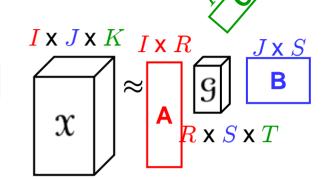
$$\mathfrak{X} \approx \llbracket \mathfrak{G} ; \mathbf{A}, \mathbf{B}, \mathbf{C}
rbracket$$

Given A, B, C orthonormal, the optimal core is:

$$\mathcal{G} = [\![\mathcal{X}; \mathbf{A}^\mathsf{T}, \mathbf{B}^\mathsf{T}, \mathbf{C}^\mathsf{T}]\!]$$

Tensor norm is the square root of the sum of all the elements squared

Eliminate the core to get:



$$\|\mathbf{x} - [\mathbf{G}; \mathbf{A}, \mathbf{B}, \mathbf{C}]\|^2 = \|\mathbf{x}\|^2 - 2\langle \mathbf{x}, [\mathbf{G}; \mathbf{A}, \mathbf{B}, \mathbf{C}] \rangle + \|\mathbf{G}\|^2$$

$$= \|\mathbf{x}\|^2 - \|[\mathbf{x}; \mathbf{A}^\mathsf{T}, \mathbf{B}^\mathsf{T}, \mathbf{C}^\mathsf{T}]\|^2$$
s.t. **A,B,C** orthonormal fixed maximize this

If B & C are fixed, then we can solve for A as follows:

$$\left\| \left[\mathbf{X} ; \mathbf{A}^\mathsf{T}, \mathbf{B}^\mathsf{T}, \mathbf{C}^\mathsf{T} \right] \right\| = \left\| \mathbf{A}^\mathsf{T} \mathbf{X}_{(1)} (\mathbf{C} \otimes \mathbf{B}) \right\|$$

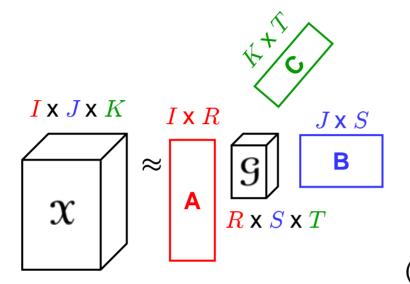
Optimal **A** is R left leading singular vectors for X_{ℓ}







Higher Order SVD (HO-SVD)



Not optimal, but often used to initialize Tucker-ALS algorithm.

(Observe connection to Tucker1)

 $\mathbf{A} = \text{leading } \mathbf{R} \text{ left singular vectors of } \mathbf{X}_{(1)}$

 ${f B}=$ leading ${f S}$ left singular vectors of ${f X}_{(2)}$

 $C = leading T left singular vectors of <math>X_{(3)}$

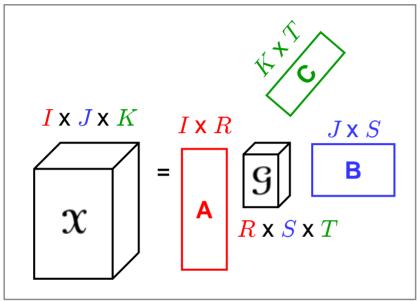
$$g = [\![\mathbf{X}; \mathbf{A}^\mathsf{T}, \mathbf{B}^\mathsf{T}, \mathbf{C}^\mathsf{T}]\!]$$





Tucker-Alternating Least Squares (ALS)

Successively solve for each component (A,B,C).



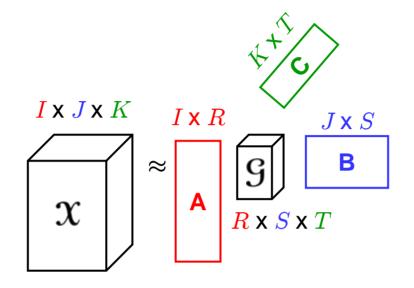
- Initialize
 - Choose R, S, T
 - Calculate A, B, C via HO-SVD
- Until converged do…
 - $\mathbf{A} = \mathbf{R}$ leading left singular vectors of $\mathbf{X}_{(1)}(\mathbf{C} \otimes \mathbf{B})$
 - $\mathbf{B} = \mathbf{S}$ leading left singular vectors of $\mathbf{X}_{(2)}(\mathbf{C} \otimes \mathbf{A})$
 - $\mathbf{C} = \mathbf{T}$ leading left singular vectors of $\mathbf{X}_{(3)}(\mathbf{B} \otimes \mathbf{A})$
- Solve for core:

$$\mathbf{G} = [\![\mathbf{X}; \mathbf{A}^\mathsf{T}, \mathbf{B}^\mathsf{T}, \mathbf{C}^\mathsf{T}]\!]$$





Tucker in Not Unique



Tucker decomposition is <u>not</u> unique. Let Y be an RxR orthogonal matrix. Then...

$$\mathbf{X} \approx \mathbf{G} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{C} = \left(\mathbf{G} \times_1 \mathbf{Y}^\mathsf{T}\right) \times_1 (\mathbf{A} \mathbf{Y}) \times_2 \mathbf{B} \times_3 \mathbf{C}$$
$$\mathbf{X}_{(1)} \approx \mathbf{A} \mathbf{G}_{(1)} (\mathbf{C} \otimes \mathbf{B})^\mathsf{T} = \mathbf{A} \mathbf{Y} \mathbf{Y}^\mathsf{T} \mathbf{G}_{(1)} (\mathbf{C} \otimes \mathbf{B})^\mathsf{T}$$





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- Case studies

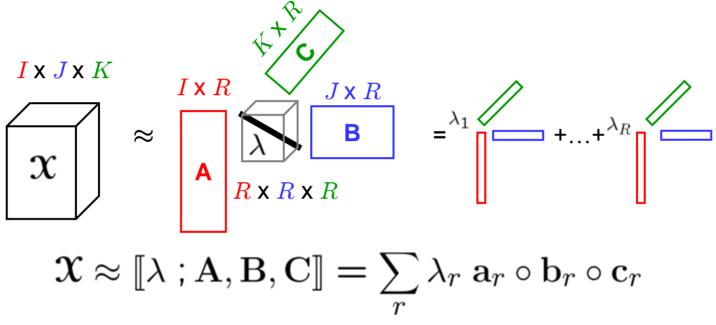
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 - Tucker 3
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- Incrementalization







CANDECOMP/PARAFAC Decomposition



- CANDECOMP = Canonical Decomposition (Carroll & Chang, 1970)
- PARAFAC = Parallel Factors (Harshman, 1970)
- Core is <u>diagonal</u> (specified by the vector λ)
- Columns of A, B, and C are <u>not</u> orthonormal
- If R is *minimal*, then R is called the **rank** of the tensor (Kruskal 1977)
- Can have rank(X) > min{I,J,K}

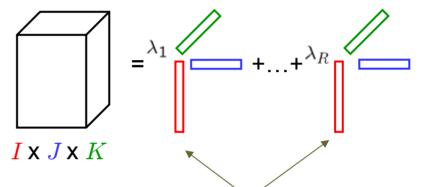




PARAFAC-Alternating Least Squares (ALS)

Successively solve for each component (A,B,C).

$$egin{aligned} \mathbf{\mathfrak{X}} &pprox \left[\!\!\left[\lambda\right.; \mathbf{A}, \mathbf{B}, \mathbf{C}
ight]\!\!\right] \ &\mathbf{X_{(1)}} &pprox & \mathbf{A} \mathbf{\Lambda} (\mathbf{C} \odot \mathbf{B})^\mathsf{T} \end{aligned}$$



Find all the vectors in one mode at a time

KHATRI-RAO PRODUCT

(column-wise Kronecker product)

$$\mathbf{C} \odot \mathbf{B} \equiv \begin{bmatrix} \mathbf{c}_1 \otimes \mathbf{b}_1 & \mathbf{c}_2 \otimes \mathbf{b}_2 & \cdots & \mathbf{c}_R \otimes \mathbf{b}_R \end{bmatrix}$$

$$(\mathbf{C}\odot\mathbf{B})^{\dagger} \equiv (\mathbf{C}^{\mathsf{T}}\mathbf{C} * \mathbf{B}^{\mathsf{T}}\mathbf{B})^{\dagger} (\mathbf{C}\odot\mathbf{B})^{\mathsf{T}}$$

If C, B, and Λ are fixed, the optimal A is given by:

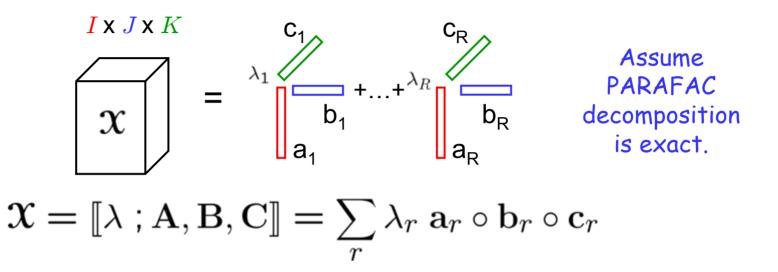
$$\mathbf{A} = \mathbf{X}_{(1)}(\mathbf{C} \odot \mathbf{B})(\mathbf{C}^{\mathsf{T}}\mathbf{C} * \mathbf{B}^{\mathsf{T}}\mathbf{B})^{\dagger} \mathbf{\Lambda}^{-1}$$
Repeat for **B**,**C**, etc.

3-29





PARAFAC is often unique



Sufficient condition for uniqueness (Kruskal, 1977):

$$2R + 2 \le k_{\mathbf{A}} + k_{\mathbf{B}} + k_{\mathbf{C}}$$

 k_A = k-rank of A = max number k such that every set of k columns of A is linearly independent





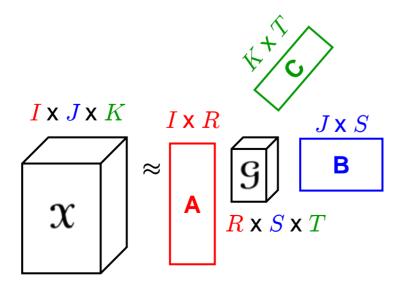
Tucker vs. PARAFAC Decompositions

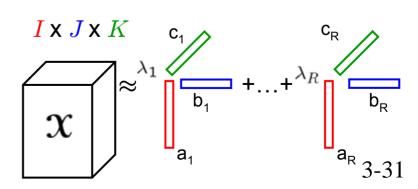
Tucker

- Variable transformation in each mode
- Core G may be dense
- A, B, C generally orthonormal
- Not unique

PARAFAC

- Sum of rank-1 components
- No core, i.e., superdiagonal core
- A, B, C may have linearly dependent columns
- Generally unique









Tensor tools - summary

- Two main tools
 - PARAFAC
 - Tucker
- Both find row-, column-, tube-groups
 - but in PARAFAC the three groups are identical
- To solve: Alternating Least Squares

Toolbox: from Tamara Kolda:

http://csmr.ca.sandia.gov/~tgkolda/TensorToolbox/