

Fairness Assumptions in the Modal μ -Calculus

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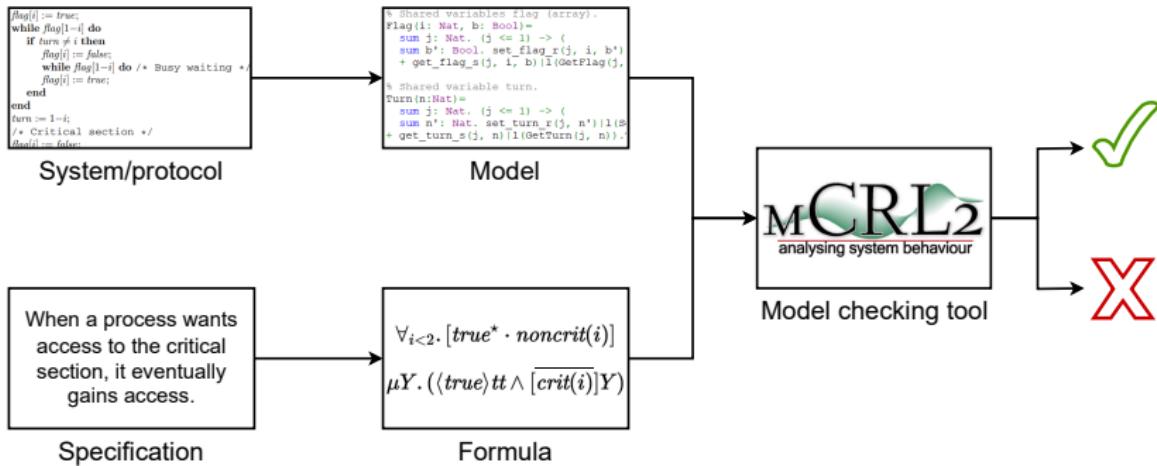
Motivation

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- Model checking

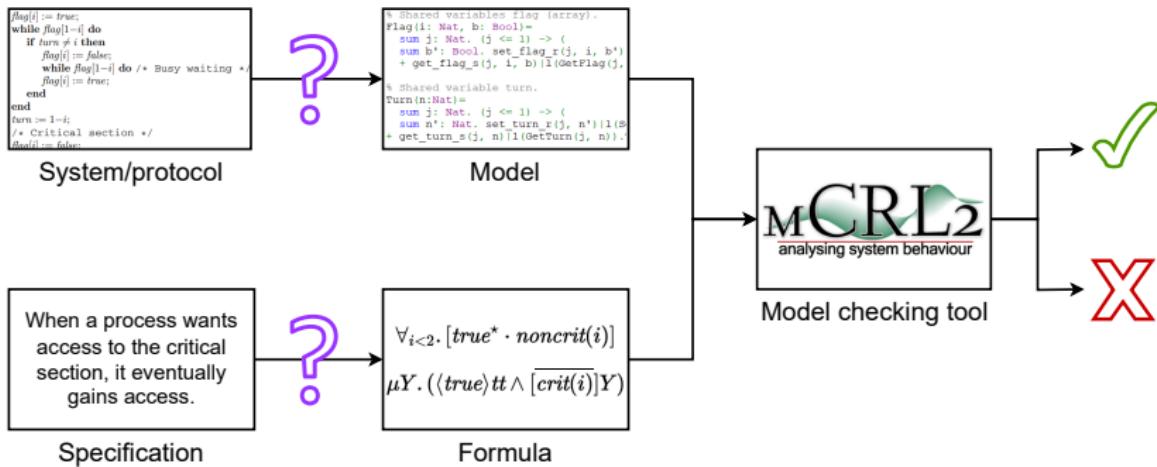
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- The modal μ -calculus:
 - Used in mCRL2
 - Highly expressive
 - Difficult to understand formulae

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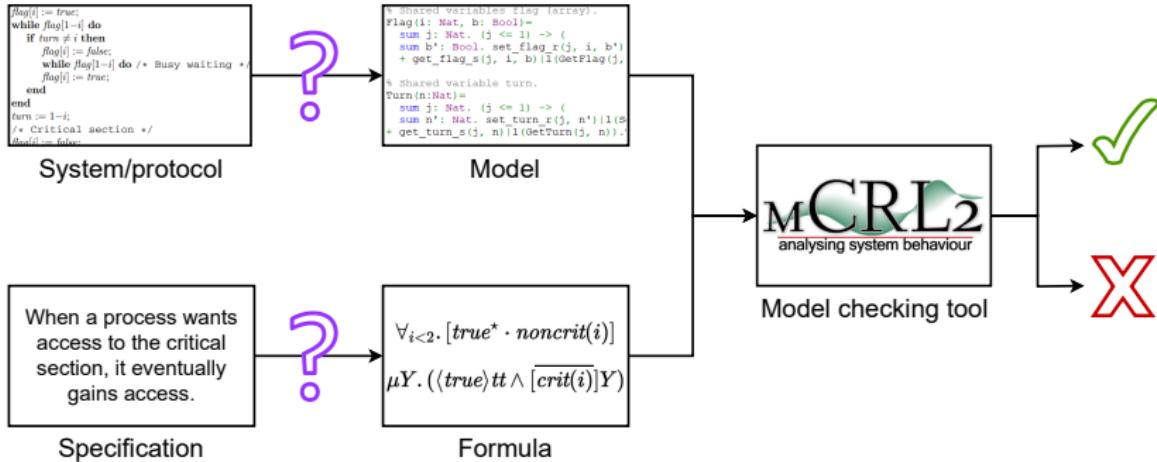
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 - Commonly required

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 - Commonly required
 - Non-trivial

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 - Properties are satisfied if all violations are unfair

Motivation: Which Formulae

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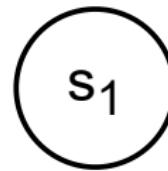
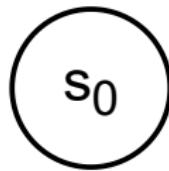
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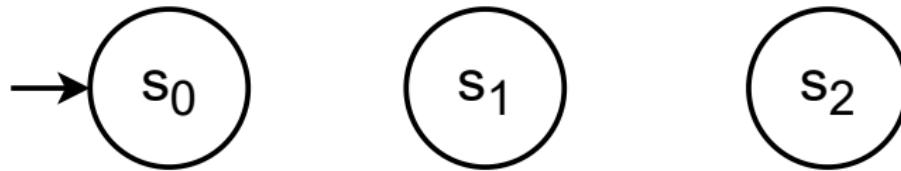
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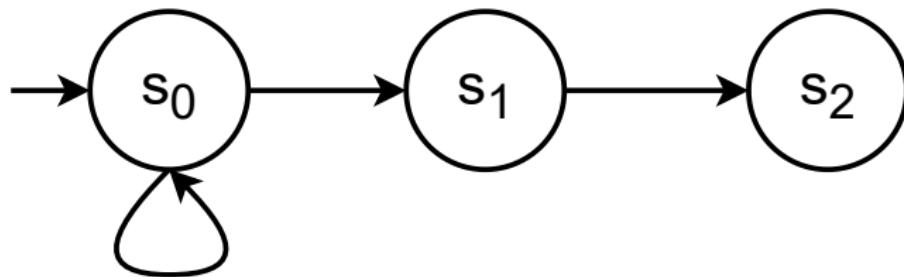
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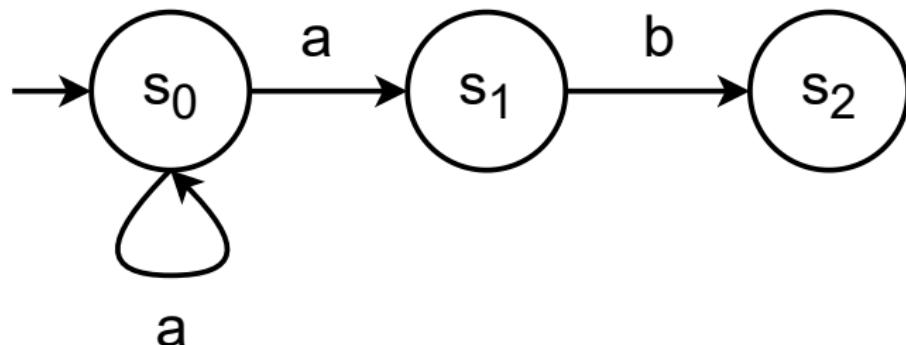
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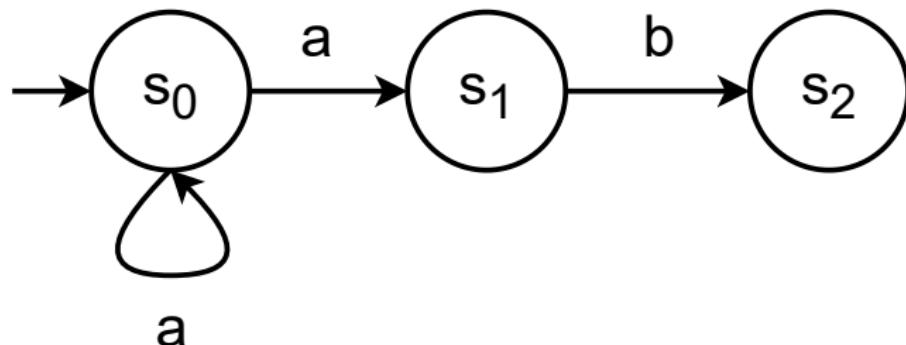
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- Finite systems

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- Combine *behaviour* with *scope*
 - Behaviour: “ r action never occurs” (absence), “every q is eventually followed by an r ” (response)
 - Scope: “throughout entire path” (global), “after first a action” (after-first)

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- Focus on three:
 - Weak fairness of actions (WFA)
 - Strong fairness of actions (SFA)
 - Fair reachability of actions (FRA)

Project

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 - 4 Practical use in mCRL2

Global Response Formulae

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- RQ2: First design formulae for global response

Interlude: μ -calculus

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$$\begin{aligned}\phi, \psi ::= & tt \mid ff \mid X \mid \neg\phi \mid \phi \wedge \psi \mid \phi \vee \psi \mid \phi \Rightarrow \psi \mid \\ & [a]\phi \mid \langle a \rangle \phi \mid \mu X.\phi \mid \nu X.\phi\end{aligned}$$

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- tt is all states, ff none
- X is a set of states, determined by environment
- \neg, \wedge, \vee and \Rightarrow as expected
- $[a]\phi$ if all a -transitions go to a state satisfying ϕ
- $\langle a \rangle \phi$ if there exists an a -transition to a state satisfying ϕ .
- $\mu X.\phi$ is the least fixpoint of ϕ , $\nu X.\phi$ the greatest
 - Rough intuition: finite and infinite recursion

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- Adding fairness

Global Response Formulae: WFA

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- Weak fairness of actions (WFA): an action that is *perpetually enabled* from some point onwards must occur infinitely often

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- If an action is perpetually enabled, it occurs infinitely often
- If an action is not perpetually enabled, it is disabled infinitely often

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- Proof in thesis
- Formula design with Bas Luttik, inspired by justness formula from Bouwman, Luttik and Willemse (2020)

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- Observation also given in *Fairness* by Francez (1986)

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$$\neg(\langle \text{true}^* \cdot q \rangle (\bigvee_{F \subseteq \text{Act}} (\mu Y. (\langle \bar{r} \rangle Y \vee \nu X. \text{inf}_{\text{SFA}}(F)))))$$

Where

$$\text{inf}_{\text{SFA}}(F) = \text{exec}_{\text{SFA}}(F, n)$$

$$\text{exec}_{\text{SFA}}(F, 0) = [\bar{F}]ff \wedge X$$

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- Due to subsets, exponential in number of actions

Other Patterns

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- These fairness assumption are not relevant for all

Other Patterns

Behaviour	Relevant	Covered	Scope	Relevant	Covered
Absence	✗	✗	Global	✓	✓
Existence	✓	✓	Before	✗	✗
Existence (Most)	✗	✗	After-First	✓	✓
Existence (Least)	✓	✗	Between-First	✗	✗
Existence (Exactly)	✓	✗	Until-First	✓	✓
Universality	✗	✗	Before-Variant	✓	✓
Precedence	✗	✗	After-Last	✓	✓
Response	✓	✓	Between-Last	✗	✗
Chain-Precedence	✗	✗	Until-Last	✓	✓
Chain-Response	✓	✗	After-Any	✓	✓
Always-Enabled	✗	✗	Between-Any	✗	✗
Precedence-Variant	✓	✗	Until-Any	✓	✓
Response-Variant	✓	✗			
Constrained-Chain	✓	✗			

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Other Patterns

- First, designed separate formulae
- Mostly identical, same fairness assumption
 - Identify impact of behaviour and scope
 - Represent with 5 variables: $\delta_1, \delta_2, \delta_3, \delta_4, \delta_5$

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- Similar for FRA and SFA

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Behaviour	Scope	δ_1	δ_2	δ_3	δ_4	δ_5
Response	Global	ε	$true^* \cdot q$	$false$	r	$false$
	Before-Var	ε	$\bar{b}^* \cdot q$	b	r	$false$
	After	$true^* \cdot a$	$true^* \cdot q$	$false$	r	$false$
		$\bar{a}^* \cdot a$	$true^* \cdot q$	$false$	r	$false$
		$true^* \cdot a$	$\bar{a}^* \cdot q$	$false$	r	a
		$true^* \cdot a$	$\bar{b}^* \cdot q$	b	r	$false$
	Until	$(\bar{a}^* \cdot a) +$	$\bar{b}^* \cdot q$	b	r	$false$
		$(true^* \cdot b \cdot \bar{a}^* \cdot a)$				
		$true^* \cdot a$	$\overline{a \cup b}^* \cdot q$	b	r	a
Existence	Global	ε	ε	$false$	r	$false$
	Before-Var	ε	ε	b	r	$false$
	After	$true^* \cdot a$	ε	$false$	r	$false$
		$\bar{a}^* \cdot a$	ε	$false$	r	$false$
		$true^* \cdot a$	ε	$false$	r	a
		$true^* \cdot a$	ε	b	r	$false$
		$(\bar{a}^* \cdot a) +$	ε	b	r	$false$
	Until	$(true^* \cdot b \cdot \bar{a}^* \cdot a)$				
		$true^* \cdot a$	ε	b	r	a

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 - Discussions of unconditional fairness of actions

Future Work

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Behaviour	Relevant	Covered	Scope	Relevant	Covered
Absence	✗	✗	Global	✓	✓
Existence	✓	✓	Before	✗	✗
Existence (Most)	✗	✗	After-First	✓	✓
Existence (Least)	✓	✗	Between-First	✗	✗
Existence (Exactly)	✓	✗	Until-First	✓	✓
Universality	✗	✗	Before-Variant	✓	✓
Precedence	✗	✗	After-Last	✓	✓
Response	✓	✓	Between-Last	✗	✗
Chain-Precedence	✗	✗	Until-Last	✓	✓
Chain-Response	✓	✗	After-Any	✓	✓
Always-Enabled	✗	✗	Between-Any	✗	✗
Precedence-Variant	✓	✗	Until-Any	✓	✓
Response-Variant	✓	✗			
Constrained-Chain	✓	✗			

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$$\begin{aligned} & \neg(\langle \text{true}^* \cdot q_0 \cdot \overline{q_1}^* \cdot q_1 \rangle \nu X. (\bigwedge_{\lambda \in \text{Act}} (\langle \lambda \rangle tt \Rightarrow (\\ & \mu Y. (([\lambda] ff \wedge X) \vee \\ & \quad \langle \lambda \setminus r_0 \rangle X \vee \langle \overline{\lambda \cup r_0} \rangle Y)))))) \\ & \wedge \neg(\langle \text{true}^* \cdot q_0 \cdot \overline{q_1}^* \cdot q_1 \cdot \overline{r_0}^* \cdot r_0 \rangle \nu X. (\bigwedge_{\lambda \in \text{Act}} (\langle \lambda \rangle tt \Rightarrow (\\ & \mu Y. (([\lambda] ff \wedge X) \vee \\ & \quad \langle \lambda \setminus r_1 \rangle X \vee \langle \overline{\lambda \cup r_1} \rangle Y)))))) \end{aligned}$$

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$$\neg(\langle \delta_1 \cdot \delta_2 \rangle \nu X. (\bigwedge_{\lambda \in (Act \setminus B)} (\langle \lambda \rangle tt \Rightarrow (\mu Y. (\langle \delta_3 \rangle tt \vee ([\lambda] ff \wedge X) \vee \langle \lambda \setminus (\delta_4 \cup \delta_5) \rangle X \vee \overline{\langle \lambda \cup \delta_4 \cup \delta_5 \rangle Y}))))))$$

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Final Thoughts

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