

Fairness Assumptions in the Modal μ -Calculus

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Motivation

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- Model checking

Motivation

■ Model checking

```
flag[i] := true;  
while flag[i-1] do  
  if turn ≠ i then  
    flag[i] := false;  
    while flag[i-1] do /* Busy waiting */  
      flag[i] := true;  
    end  
  end  
  turn := i-1;  
/* Critical section */  
flag[i] := false;
```

System/protocol

```
/* Shared variables flag (array).  
flag(i: Nat, b: Bool) =  
  sum j: Nat. {j <= 1} -> {  
    sum b': Bool. set_flag_r(j, i, b')  
    + get_flag_s(j, i, b)} | l(GetFlag(j,  
/* Shared variable turn.  
Turn(n: Nat) =  
  sum j: Nat. {j <= 1} -> {  
    sum n': Nat. set_turn_r(j, n') | l(S  
    + get_turn_s(j, n)} | l(GetTurn(j, n)).
```

Model

When a process wants
access to the critical
section, it eventually
gains access.

Specification

$$\forall i < 2. [true^* \cdot noncrit(i)]$$
$$\mu Y. ((\langle true \rangle tt \wedge \overline{crit(i)} Y)$$

Formula

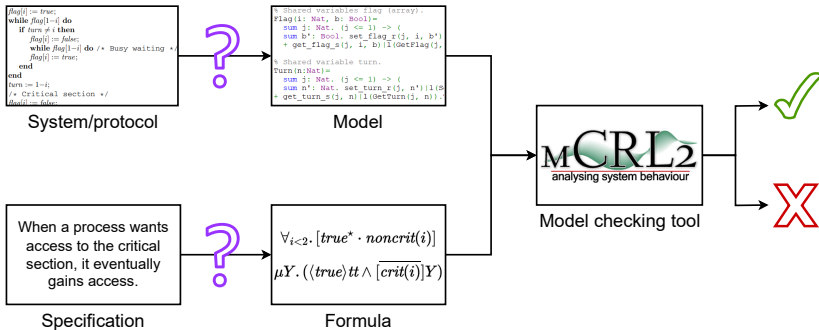


Model checking tool



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- The modal μ -calculus:
 - Used in mCRL2
 - Highly expressive
 - Difficult to understand formulae

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- Consider specific types of formulae

Motivation

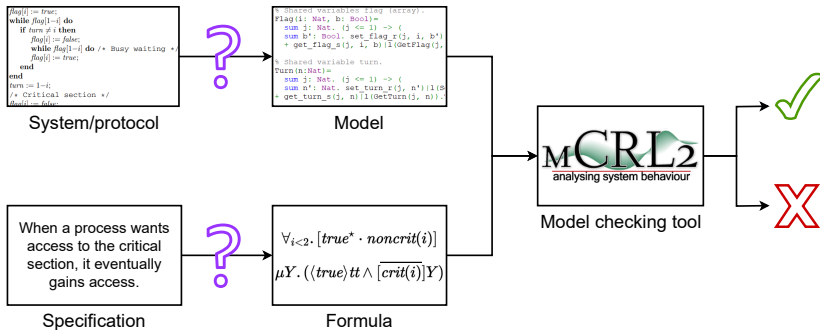
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 - Commonly required

Motivation

- Question: did I design my formula correctly?
- Consider specific types of formulae
 - Commonly required
 - Non-trivial

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 - Fair and unfair executions
 - Properties are satisfied if all violations are unfair

Motivation: Which Formulae

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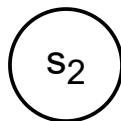
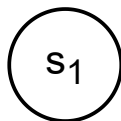
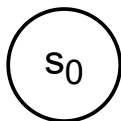
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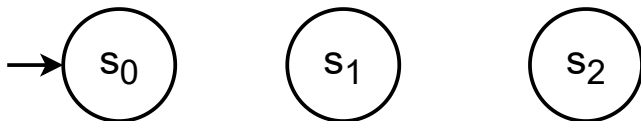
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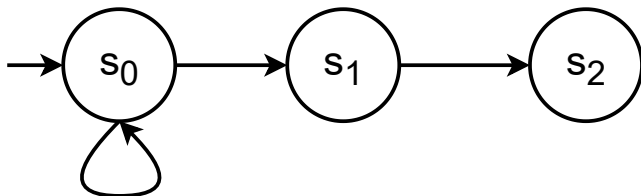
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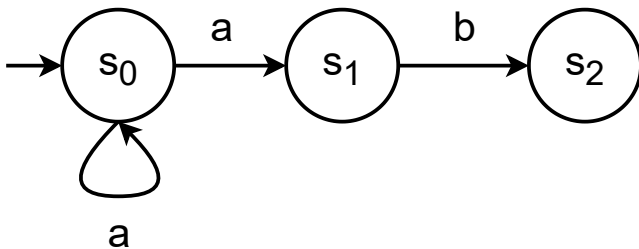
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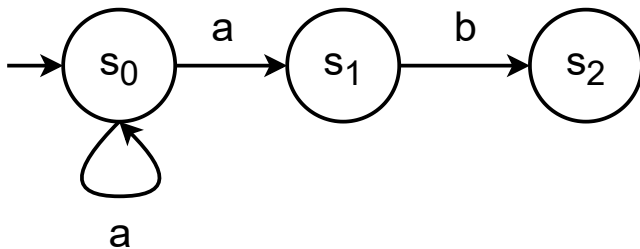
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- Finite systems

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- Combine *behaviour* with *scope*
 - Behaviour: “ r action never occurs” (absence), “every q is eventually followed by an r ” (response)
 - Scope: “throughout entire path” (global), “after first a action” (after-first)

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- Focus on three:
 - Weak fairness of actions (WFA)
 - Strong fairness of actions (SFA)
 - Fair reachability of actions (FRA)

Project

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- Research questions (paraphrased)

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- 4 Practical use in mCRL2

Global Response Formulae

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- RQ2: First design formulae for global response

Interlude: μ -calculus

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$$\phi, \psi ::= tt \mid ff \mid X \mid \neg\phi \mid \phi \wedge \psi \mid \phi \vee \psi \mid \phi \Rightarrow \psi \mid \\ [a]\phi \mid \langle a \rangle\phi \mid \mu X.\phi \mid \nu X.\phi$$

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- tt is all states, ff none
- X is a set of states, determined by environment
- \neg , \wedge , \vee and \Rightarrow as expected
- $[a]\phi$ if all a -transitions go to a state satisfying ϕ
- $\langle a \rangle\phi$ if there exists an a -transition to a state satisfying ϕ .
- $\mu X.\phi$ is the least fixpoint of ϕ , $\nu X.\phi$ the greatest
 - Rough intuition: finite and infinite recursion

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- Adding fairness

Global Response Formulae: WFA

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- Weak fairness of actions (WFA): an action that is *perpetually enabled* from some point onwards must occur infinitely often

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- If an action is perpetually enabled, it occurs infinitely often
- If an action is not perpetually enabled, it is disabled infinitely often

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- Proof in thesis
- Formula design with Bas Luttik, inspired by justness formula from Bouwman, Luttik and Willemse (2020)

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- Observation also given in *Fairness* by Francez (1986)

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Where

$$\begin{aligned} \text{inf}_{SFA}(F) &= \text{exec}_{SFA}(F, n) \\ \text{exec}_{SFA}(F, 0) &= [\bar{F}]ff \wedge X \\ \text{exec}_{SFA}(F, k+1) &= \mu W_{k+1}. ([\bar{F}]ff \wedge \\ &\quad (\langle \bar{r} \rangle W_{k+1} \vee \langle \alpha_{k+1} \setminus r \rangle \text{exec}_{SFA}(F, k))) \end{aligned}$$

With an arbitrary order on the actions in F such that α_1 is the first action, α_2 the second, etc. until α_n

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- Due to subsets, exponential in number of actions

Other Patterns

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- These fairness assumption are not relevant for all

Other Patterns

Behaviour	Relevant	Covered	Scope	Relevant	Covered
Absence	×	×	Global	✓	✓
Existence	✓	✓	Before	×	×
Existence (Most)	×	×	After-First	✓	✓
Existence (Least)	✓	×	Between-First	×	×
Existence (Exactly)	✓	×	Until-First	✓	✓
Universality	×	×	Before-Variant	✓	✓
Precedence	×	×	After-Last	✓	✓
Response	✓	✓	Between-Last	×	×
Chain-Precedence	×	×	Until-Last	✓	✓
Chain-Response	✓	×	After-Any	✓	✓
Always-Enabled	×	×	Between-Any	×	×
Precedence-Variant	✓	×	Until-Any	✓	✓
Response-Variant	✓	×			
Constrained-Chain	✓	×			

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Other Patterns

- First, designed separate formulae
- Mostly identical, same fairness assumption
 - Identify impact of behaviour and scope
 - Represent with 5 variables: $\delta_1, \delta_2, \delta_3, \delta_4, \delta_5$

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- Similar for FRA and SFA

Other Patterns

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■ Only need to know how to fill in

Behaviour	Scope	δ_1	δ_2	δ_3	δ_4	δ_5
Response	Global	ε	$true^* \cdot q$	<i>false</i>	<i>r</i>	<i>false</i>
	Before-Var	ε	$\bar{b}^* \cdot q$	<i>b</i>	<i>r</i>	<i>false</i>
	After	Any	$true^* \cdot a$	$true^* \cdot q$	<i>false</i>	<i>r</i>
		First	$\bar{a}^* \cdot a$	$true^* \cdot q$	<i>false</i>	<i>r</i>
		Last	$true^* \cdot a$	$\bar{a}^* \cdot q$	<i>false</i>	<i>r</i>
	Until	Any	$true^* \cdot a$	$\bar{b}^* \cdot q$	<i>b</i>	<i>r</i>
		First	$(\bar{a}^* \cdot a) + (true^* \cdot b \cdot \bar{a}^* \cdot a)$	$\bar{b}^* \cdot q$	<i>b</i>	<i>r</i>
		Last	$true^* \cdot a$	$\overline{a \cup b^* \cdot q}$	<i>b</i>	<i>r</i>
Existence	Global	ε	ε	<i>false</i>	<i>r</i>	<i>false</i>
	Before-Var	ε	ε	<i>b</i>	<i>r</i>	<i>false</i>
	After	Any	$true^* \cdot a$	ε	<i>false</i>	<i>r</i>
		First	$\bar{a}^* \cdot a$	ε	<i>false</i>	<i>r</i>
		Last	$true^* \cdot a$	ε	<i>false</i>	<i>r</i>
	Until	Any	$true^* \cdot a$	ε	<i>b</i>	<i>r</i>
		First	$(\bar{a}^* \cdot a) + (true^* \cdot b \cdot \bar{a}^* \cdot a)$	ε	<i>b</i>	<i>r</i>
		Last	$true^* \cdot a$	ε	<i>b</i>	<i>r</i>

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 - 1 Treat only some actions fairly

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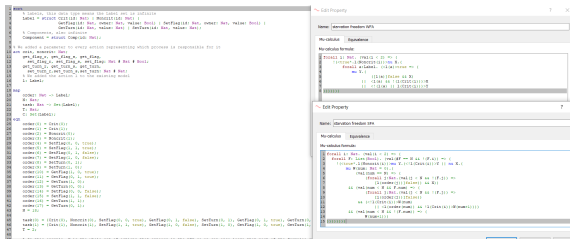
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 - Comparisons to other formulae in the literature
 - Discussions of unconditional fairness of actions

Future Work

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- Remainder of PSP

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Behaviour	Relevant	Covered	Scope	Relevant	Covered
Absence	×	×	Global	✓	✓
Existence	✓	✓	Before	×	×
Existence (Most)	×	×	After-First	✓	✓
Existence (Least)	✓	×	Between-First	×	×
Existence (Exactly)	✓	×	Until-First	✓	✓
Universality	×	×	Before-Variant	✓	✓
Precedence	×	×	After-Last	✓	✓
Response	✓	✓	Between-Last	×	×
Chain-Precedence	×	×	Until-Last	✓	✓
Chain-Response	✓	×	After-Any	✓	✓
Always-Enabled	×	×	Between-Any	×	×
Precedence-Variant	✓	×	Until-Any	✓	✓
Response-Variant	✓	×			
Constrained-Chain	✓	×			

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$$\neg(\langle true^* \cdot q_0 \cdot \overline{q_1}^* \cdot q_1 \rangle \nu X. (\bigwedge_{\lambda \in Act} (\langle \lambda \rangle tt \Rightarrow (\mu Y. ([\lambda] ff \wedge X) \vee \langle \lambda \setminus r_0 \rangle X \vee \langle \overline{\lambda \cup r_0} \rangle Y))))))$$
$$\wedge \neg(\langle true^* \cdot q_0 \cdot \overline{q_1}^* \cdot q_1 \cdot \overline{r_0}^* \cdot r_0 \rangle \nu X. (\bigwedge_{\lambda \in Act} (\langle \lambda \rangle tt \Rightarrow (\mu Y. ([\lambda] ff \wedge X) \vee \langle \lambda \setminus r_1 \rangle X \vee \langle \overline{\lambda \cup r_1} \rangle Y))))))$$

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$$\neg(\langle \delta_1 \cdot \delta_2 \rangle \nu X. (\bigwedge_{\lambda \in (Act \setminus B)} (\langle \lambda \rangle tt \Rightarrow (\mu Y. (\langle \delta_3 \rangle tt \vee ([\lambda] ff \wedge X) \vee \langle \lambda \setminus (\delta_4 \cup \delta_5) \rangle X \vee \langle \overline{\lambda \cup \delta_4 \cup \delta_5} \rangle Y))))))$$

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Final Thoughts

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