**TXL18S-1 B**

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Robot projects

1. Abstract

/\* General summary of the whole project \*/

1. Introduction

/\* The goal and scope of the project \*/

1. Methods and materials

/\* What methods and materials are we using. Zumo, sensors, language, creator, libs \*/

1. Theoretical background

/\* Some theory about how sensor, robot works, how some algorithms work \*/

The robot consists of three main part: Arduino, Zumo Shield and Zumo chassis.

1. Implementation

/\* Блок-схема, расчет ADC voltage (формула) \*/

1. Results

/\* won or not, how was the challenges \*/

1. Discussion

/\* What was challenging? Did we have a problems? How did we solved it? Why did robot fail, for example? \*/

1. Conclusion
2. References

<https://www.pololu.com/product/2508>

30/11/18

Installed bitBucked, Trello, got

01/11/18

Today is the second day with our robots. We are applying several commands to it. Such as giving values to motors (0 or 1). Make our robot to move forward and backward.