TXL18S-1 B

Rukhsora Nazarova

Mikhail Stefantsev

Mariia Saveleva

# Robot projects

## Abstract

* 1. /\* General summary of the whole project \*/

## Introduction

* 1. /\* The goal and scope of the project \*/

The goal of this project is to design and build a Zumo robot software that will allow it to pass all the challenges in the final assignment.

## Methods and materials

* 1. /\* What methods and materials are we using. Zumo, sensors, language, creator, libs \*/

## Theoretical background

* 1. /\* Some theory about how sensor, robot works, how some algorithms work \*/

The robot consists of three main part: Arduino, Zumo Shield and Zumo chassis.

## Implementation

* 1. Batteries

First challenge we faced was related to the batteries in the robot. Since Zumo uses conventional nickel metal hydride batteries that should never be discharged below the certain threshold in order to stay functioning we had to implement the function which constantly checks the voltage of the batteries and notifies the user in case of need to charge the batteries. When battery voltage gets too low, the robot starts blinking the onboard LED in full power that can’t be discarded in any way. It is also planned to implement the feature that locks the motors in case of low battery charge in order to prevent them from further discharging and subsequently damaging them. This required us to calculate the real voltage from the readings of the battery ADC.

The ADC connection diagram:



As seen from the diagram, the ADC input is connected to the output of the divider to lower the voltage as it may exceed the maximum allowed voltage of the ADC itself. That is why it is required to not only convert ADC output to volts, but also get the source voltage.

To convert the ADC output to the volts, the following conversion coefficient was used: , where is the reference voltage of the ADC (*5V as specified in the documentation)* and is number of bits used by ADC (*in our case, =12*).

To get the source voltage the voltage conversion coefficient is needed. It is calculated like:

where is the equivalent resistance of and .

So, the source voltage equals to:

where is the output level of ADC (*an integer number between and* ).

* 1. Sensors
     1. Ultrasonic sensor
     2. Reflectance array
     3. Accelerometer

## Results

* 1. /\* won or not, how was the challenges \*/

## Discussion

* 1. /\* What was challenging? Did we have problems? How did we solve them? Why did robot fail, for example? \*/

## Conclusion

## References

<https://www.pololu.com/product/2508>

30/11/18

Installed bitBucked, Trello, got

01/11/18

Today is the second day with our robots. We are applying several commands to it. Such as giving values to motors (0 or 1). Make our robot to move forward and backward.