

# Iterator

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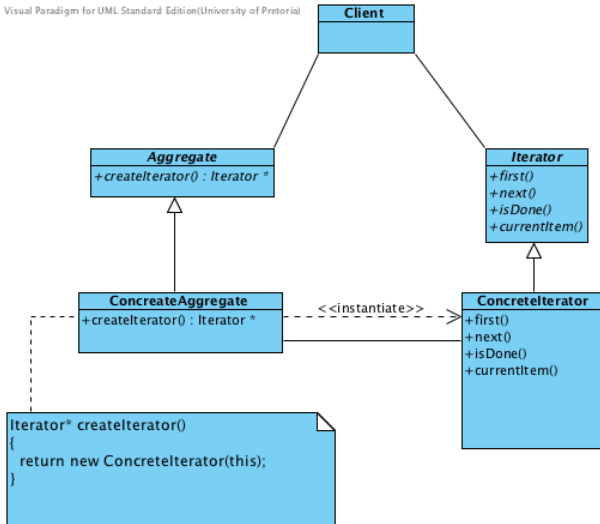
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## **Name and Classification:** Iterator (Object Behavioural)

**Intent:** “Provide a way to access the elements of an aggregate object sequentially without exposing its underlying representation” GoF(257)

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Visual Paradigm for UML Standard Edition (University of Pretoria)



## Iterator

- Defines an interface for accessing and traversing elements.

## Concrete Iterator

- Implements the Iterator interface
- Keeps track of the current position in the traversal of the aggregate

## Aggregate

- Defines an interface for creating an Iterator object

## Concrete Aggregate

- Implements the Iterator creation Interface to return an instance of the proper concrete iterator.

*Separation of concerns*: The separation of the aggregate - and how the aggregate behaves - from how the aggregate is traversed.

By moving the mechanism of iteration outside the aggregate, all aggregates can be traversed in a uniform manner.

- **Factory Method:** Both Iterator and Factory Method use a subclass to decide what object should be created. In fact `createIterator()` is an example of a factory method.
- **Memento:** The memento pattern is often used in conjunction with the iterator pattern. An iterator can use a memento to capture the state of the aggregate. This memento is stored inside the iterator to be used for traversing the aggregate.
- **Adapter:** Both patterns provides an interface through which operations are performed. They differ in the reason for providing this interface.
- **Composite:** Recursive structures such as composites usually need iterators to traverse them sequentially. Although recursive traversal might be very easy to implement without extending the composite pattern, its is strongly advised to create a composite iterator.



The C++ Containers library – referred to as the Standard Template Library (STL) prior to C++11 – provides efficient implementations for many data structures (for example: array, vector, deque, forward\_list, list set, map, stack etc.)

In C++ STL  
A Queue iterator  
Covariant return type

### Member function table

- functions present in C++03
- functions present since C++11
- functions present since C++17
- functions present since C++20

[illegible]

<http://en.cppreference.com/w/cpp/container>

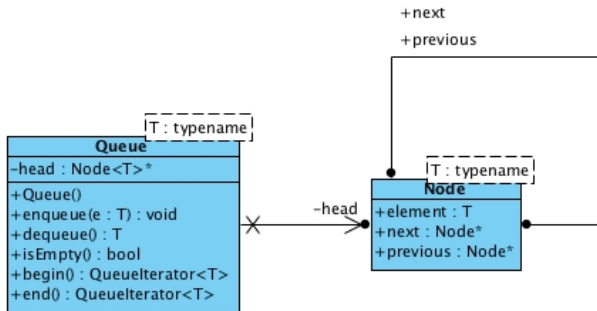
From the Observer example:

```
...  
// Create the container  
vector<PitCrew*> pitcrew;  
...  
// Insert elements into the container  
pitcrew.push_back(person);  
...  
// Create an iterator  
vector<PitCrew*>::iterator it = pitcrew.begin();  
// Iterate through the container  
while ((it != pitcrew.end()) && (! found)) {  
    if (*it == person) {  
        found = true;  
        pitcrew.erase(it);  
    }  
    ++it;  
}  
// OR  
vector<PitCrew*>::iterator it = pitcrew.begin();  
for (it = pitcrew.begin(); it != pitcrew.end(); ++it){  
    (*it)->update();  
}
```

Using templates in programs to enable the “structure” to cater for different types of objects as long as they adhere to certain traits.

Examples of traits are: Assignable,  
Constructible...

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```
#ifndef _NODE_H
#define _NODE_H
    template <typename T>
    class Node {
    public:
        T element;
        Node *next;
        Node *previous;
    };

#endif
```

```
#ifndef _QUEUE_H
#define _QUEUE_H

#include "Node.h"
#include "QueueIterator.h"

template <typename T>
class Queue{
    friend class QueueIterator<T>;
public:
    Queue();
    void enqueue(T e);
    T dequeue();
    bool isEmpty();
    QueueIterator<T> begin();
    QueueIterator<T> end();
private:
    Node<T>* head;
};

#include "Queue.cpp" // Necessary - working with templates

#endif
```

```
#ifndef _QUEUE_C
#define _QUEUE_C

#include "Node.h"
#include "Queue.h"
#include "QueueIterator.h"

template <typename T>
Queue<T>::Queue(){
    head = 0;
}
...
```



```
...
template <typename T>
void Queue<T>::enqueue(T e){
    Node<T>* n = new Node<T>();
    n->element = e;
    if (isEmpty()) {
        n->next = n;
        n->previous = n;
    } else {
        n->next = head;
        n->previous = head->previous;
        head->previous->next = n;
        head->previous = n;
    }
    head = n;
}
...
```

```
...
template <typename T>
T Queue<T>::dequeue(){
    if (isEmpty())
        return 0;
    else if (head->previous == head) {
        Node<T> *tmp= head;
        head = 0;
        return tmp->element;
    } else {
        Node<T> *tmp = head->previous;
        head->previous = head->previous->previous;
        head->previous->next = head;
        return tmp->element;
    }
}
...
```

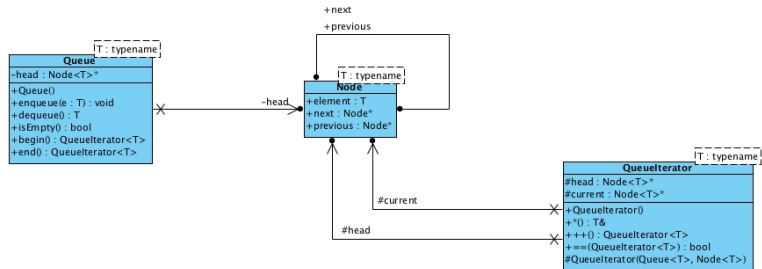
```
...
template <typename T>
bool Queue<T>::isEmpty(){
    return head == 0;
}

template <typename T>
QueueIterator<T> Queue<T>::begin(){
    return QueueIterator<T> (*this, head);
}

template <typename T>
QueueIterator<T> Queue<T>::end(){
    return QueueIterator<T> (*this, head->previous);
}

#endif
```

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Note, this code has collapsed both the aggregate (Queue is both the Aggregate and ConcreteAggregate participants) and iterator ( QueueIterator represents both the Iterator and ConcreteIterator participants) hierarchies. Refer to Figure 2 in the notes for an example with two complete aggregate and iterator hierarchies.

```
#ifndef _QUEUEITERATOR_H
#define _QUEUEITERATOR_H

template <typename T>
class Queue;
template <typename T>
class Node;

template <typename T>
class QueueIterator {
    friend class Queue<T>;
public:
    QueueIterator();
    T& operator*();
    QueueIterator<T> operator++();
    bool operator==(const QueueIterator<T>&) const;
protected:
    QueueIterator(const Queue<T>&, Node<T>*);
    Node<T>* head;
    Node<T>* current;
};
#include "QueueIterator.cpp"
#endif
```

```
#ifndef _QUEUEITERATOR_C
#define _QUEUEITERATOR_C

#include <iostream>
using namespace std;
#include "QueueIterator.h"
#include "Queue.h"
#include "Node.h"

template <typename T>
QueueIterator<T>::QueueIterator() : head(0), current(0) {}

template <typename T>
QueueIterator<T>::QueueIterator(const Queue<T>& source,
                                Node<T>* p) : head(source.head), current(p) {}

template <typename T>
T& QueueIterator<T>::operator*(){
    return current->element;
}

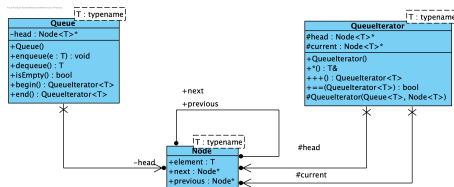
...
```

```
...
template<typename T>
QueueIterator<T> QueueIterator<T>::operator++(){
    if (this != nullptr)
        this->current = this->current->next;
    return *this;
}

template <typename T>
bool QueueIterator<T>::operator==(const QueueIterator<T>& rhs)
                                   const{
    return current == rhs.current;
}

#endif
```

Now having seen a user-defined queue and its corresponding iterator, how would you abstract the design to include other data structures?





Concept - **covariant return types**. Replace the return type with a more specialised type in a derived class.

```
class A {  
public:  
    A someFunction() {  
        return new A;  
    }  
};  
  
class B : public A {  
public:  
    B someFunction() {  
        return new B;  
    }  
};
```