Mechatronics 3700 Death Star Tracker: Technical Manual

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Abstract

This document describes how each of the modules (including both software and hardware) work, and how to use them.

Part I Technical Documentation

Introduction

- 1.1 Document Identification
- 1.2 System Overview
- 1.3 Document Overview
- 1.4 Reference Documents
- 1.4.1 Acronyms and Abbreviations

System Description

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- 2.2 Operational Scenarios
- 2.3 System Requirements
- 2.4 Module Design
- 2.5 Module Requirements: Module X
- 2.5.1 Functional Requirements

Inputs

Processes

Outputs

Timing

Failure Modes

2.5.2 Non-Functional (Quality of Service) Requirements

Performance

Interfaces

Design Constraints

- 2.6 Conceptual Design: Module X
- 2.6.1 Assumptions Made
- 2.6.2 Constraints on Module X Performance

User Interface Design

- 3.1 Classes of User
- 3.2 Interface Design: User Class Y
- 3.2.1 User Inputs and Outputs
- 3.2.2 Input Validation and Error Trapping

Hardware Design

- 4.1 Scope of X System Hardware
- 4.2 Hardware Design
- 4.2.1 Power Supply
- 4.2.2 Computer Design
- 4.2.3 Sensor Hardware
- 4.2.4 Actuator Hardware
- 4.2.5 Operator Input Hardware
- 4.2.6 Operator Output Hardware
- 4.2.7 Hardware Quality Assurance
- 4.3 Hardware Validation
- 4.4 Hardware Calibration Procedures
- 4.5 Hardware Maintenance and Adjustment

Software Design

- 5.1 Software Design Process
- 5.1.1 Software Development Environment
- 5.1.2 Software Implementation Stages and Test Plans
- 5.2 Software Quality Assurance
- 5.3 Software Design Description
- 5.3.1 Architecture
- 5.3.2 Software Interface
- **5.3.3** Software Components
- 5.4 Preconditions for Software
- 5.4.1 Preconditions for System Startup
- 5.4.2 Preconditions for System Shutdown

System Performance

- 6.1 Performance Testing
- 6.2 State of the System as Delivered
- 6.3 Future Improvements

Safety Implications

Conclusions

Part II Appendicies

Supporting Calculations

DOxygen Documentation

Code Listing