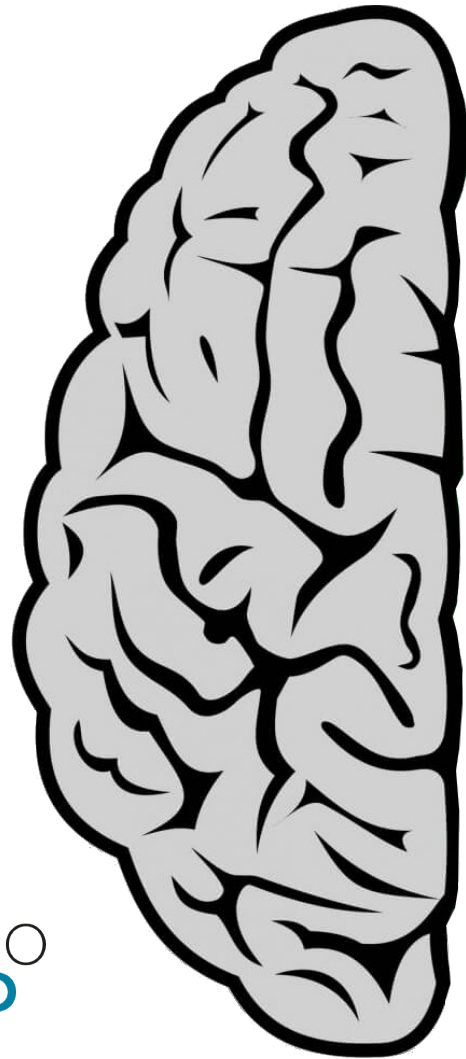


Toward everyday BCI: Augmented Covariance Method in a reduced dataset setting

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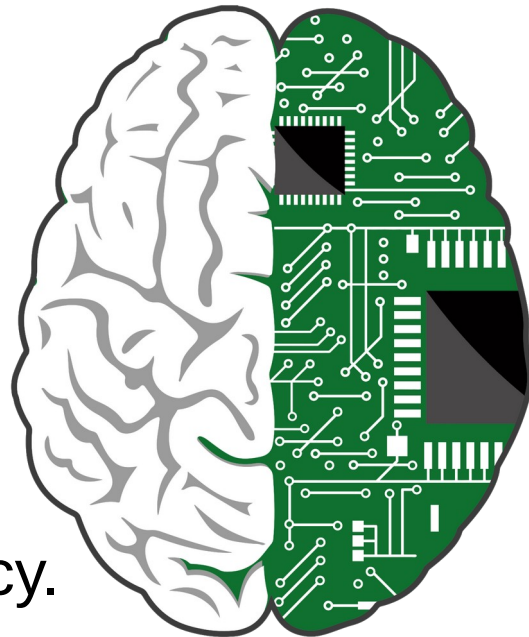
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Goals

Improve BCI effectiveness:

- Cost of equipment, setup or comfort
 - Use less electrodes.
- Efficiency / Usability
 - Reduce the training time...
 - ... while keeping a reasonable accuracy.



Study how the augmented covariance approach can help.

- Within-session.
- Cross-session.

Tests done with MOABB on motor imagery benchmarks.

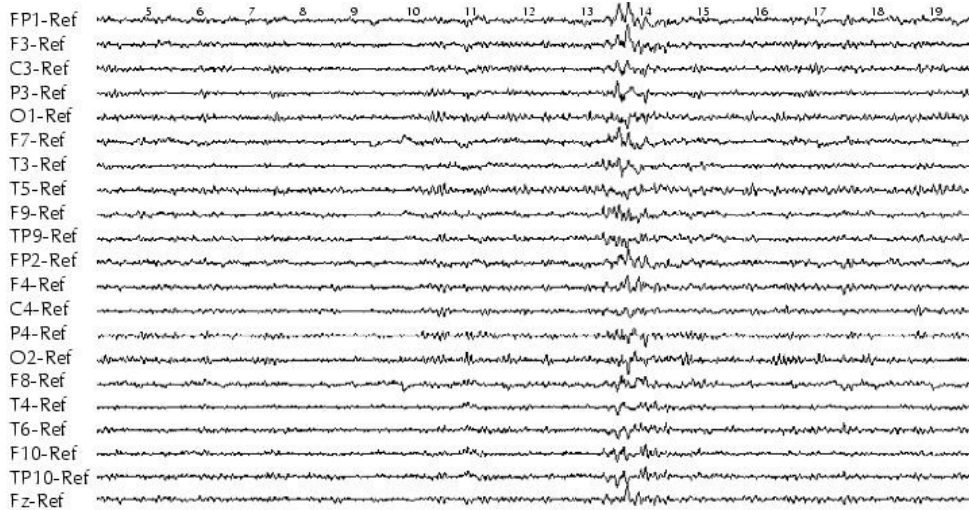
Augmented Covariance (ACM)

Autoregressive model formulation

$$\mathbf{X}_t = \sum_{i=1}^p \mathbf{A}_i \mathbf{X}_{t-i\tau} + \varepsilon_t$$

Compute the Yule-Walker equations

$$\left\{ \begin{array}{l} \Gamma(0) = \sum_{k=1}^p \mathbf{A}_k \Gamma(-k) + \mathbf{U} \text{ for } i = 0 \\ \Gamma(i) = \sum_{k=1}^p \mathbf{A}_k \Gamma(i - k) \text{ for } i \neq 0 \end{array} \right.$$



With:

- $\Gamma(i) = E(\mathbf{X}_t, \mathbf{X}_{t-i\tau}^T)$ is autocovariance matrix of lag i .
- \mathbf{U} is the covariance matrix of the noise.
- 2 new parameters p and τ .

Autoregressive model formulation

$$\mathbf{X}_t = \sum_{i=1}^p \mathbf{A}_i \mathbf{X}_{t-i\tau} + \varepsilon_t$$

Compute the Yule-Walker equation

$$\begin{cases} \Gamma(0) = \sum_{k=1}^p \mathbf{A}_k \Gamma(-k) + \mathbf{U} & \text{for } i = 0 \\ \Gamma(i) = \sum_{k=1}^p \mathbf{A}_k \Gamma(i-k) & \text{for } i \neq 0 \end{cases}$$

SPD matrix

$$\begin{bmatrix} \Gamma_0 & \Gamma_{-1} & \Gamma_{-2} & \cdots \\ \Gamma_1 & \Gamma_0 & \Gamma_{-1} & \cdots \\ \Gamma_2 & \Gamma_1 & \Gamma_0 & \cdots \\ \vdots & \vdots & \vdots & \ddots \\ \Gamma_{p-1} & \Gamma_{p-2} & \Gamma_{p-3} & \cdots \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ \vdots \\ A_p \end{bmatrix} = \begin{bmatrix} \Gamma_1 \\ \Gamma_2 \\ \Gamma_3 \\ \vdots \\ \Gamma_p \end{bmatrix}$$

Two strategies:

- Compute $(\mathbf{A}_i)_{i=1\dots p}$ and classify.
- **Classify the ACM directly.**

Augmented Covariance Matrix (ACM)

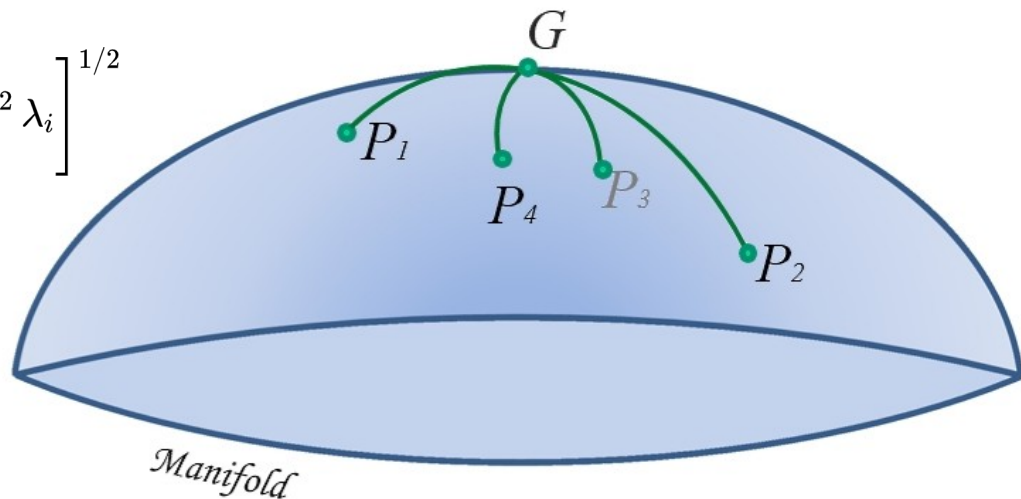
Riemann distance based classification

Affine Invariant metrics

$$\delta_R(\mathbf{P}_1, \mathbf{P}_2) = \left\| \log \left(\mathbf{P}_1^{-\frac{1}{2}} \mathbf{P}_2 \mathbf{P}_1^{-\frac{1}{2}} \right) \right\|_F = \left[\sum_{i=1}^n \log^2 \lambda_i \right]^{1/2}$$

Fréchet mean

$$\mathfrak{G}(\mathbf{P}_1, \dots, \mathbf{P}_m) = \operatorname{argmin}_{G \in P(n)} \sum_{i=1}^m \delta_R^2(\mathbf{G}, \mathbf{P}_i)$$



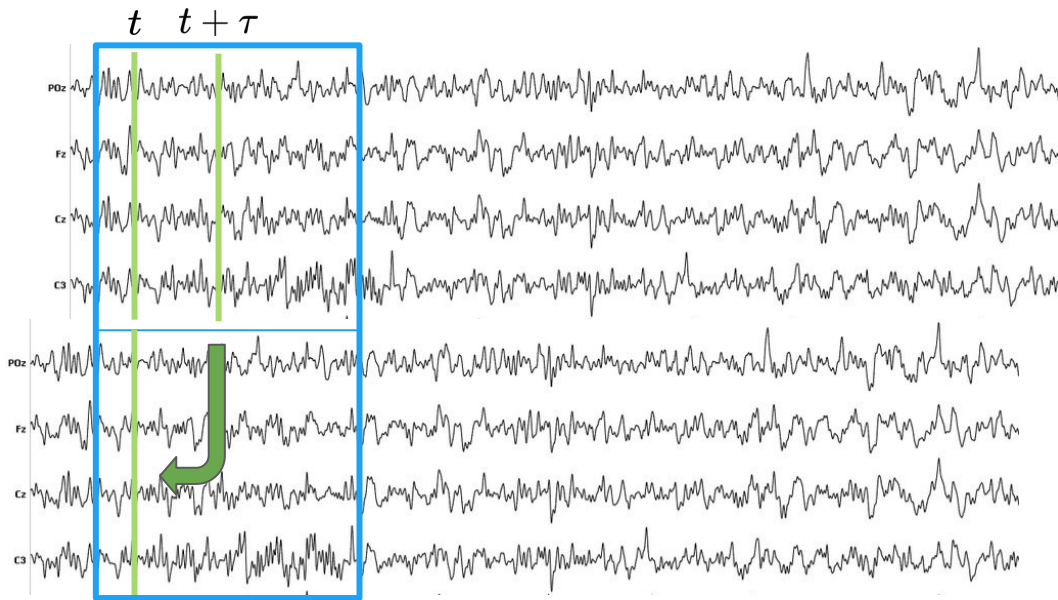
SPD matrix considered

$$\operatorname{Cov}(X) = \frac{1}{\operatorname{Time} - 1} \sum_{i=1}^{\operatorname{Time}} X_i X_i^T$$

Alexandre Barachant et al. "Riemannian geometry applied to BCI classification". In: *International conference on latent variable analysis and signal separation*. Springer. 2010, pp. 629–636.

Maher Moakher. "A differential geometric approach to the geometric mean of symmetric positive-definite matrices". In: *SIAM Journal on Matrix Analysis and Applications* 26.3 (2005), pp. 735–747.

Alternative formulation



Taken's Theorem

$$\Gamma_{aug} = \begin{bmatrix} \Gamma_0 & \Gamma_{-1} & \Gamma_{-2} & \cdots \\ \Gamma_1 & \Gamma_0 & \Gamma_{-1} & \cdots \\ \Gamma_2 & \Gamma_1 & \Gamma_0 & \cdots \\ \vdots & \vdots & \vdots & \ddots \\ \Gamma_{p-1} & \Gamma_{p-2} & \Gamma_{p-3} & \cdots \end{bmatrix}$$

Sample Covariance

$$Cov(X) = \frac{1}{Time - 1} \sum_{i=1}^{Time} X_i X_i^T$$

Introducing block-Toeplitz covariance matrices to remaster linear discriminant analysis for event-related potential brain-computer interfaces.

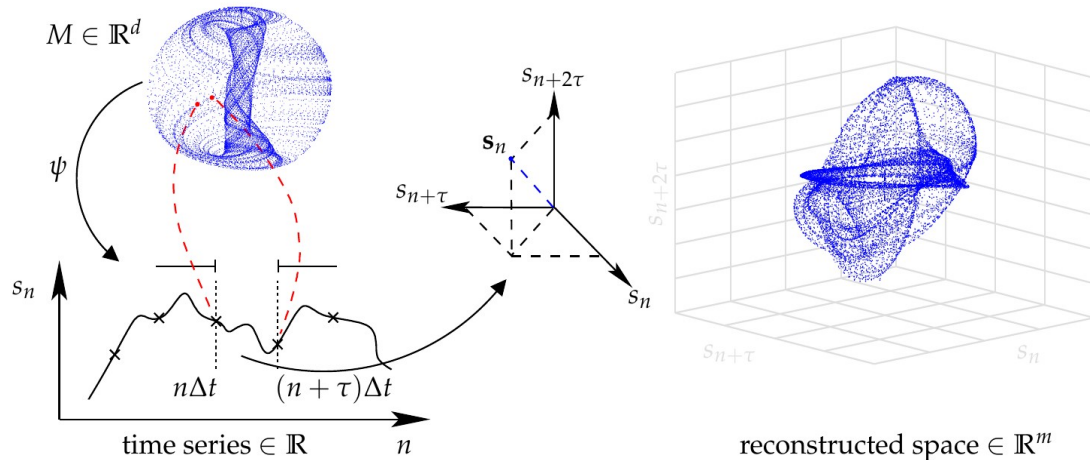
Jan Sosulski and Michael Tangermann. JNE, 2022.

Takens Theorem

Let M to be a compact manifold of dimension m . For pairs (Φ, Y) , $\Phi : M \rightarrow M$ a smooth diffeomorphism and $Y : M \rightarrow \mathbb{R}$ a smooth function, it is a generic property that the map $\varphi_{(\Phi, Y)} : M \rightarrow \mathbb{R}^{2m+1}$, defined by

$$\varphi_{(\Phi, Y)}(x) = (Y(x), Y(\Phi(x)), \dots, Y(\Phi^{2m}(x)))$$

is an embedding; by "smooth" we mean at least \mathbb{C}^2 . We refer to the function Y as measurement function. By embedding we mean that the reconstructed system and the original system have the same dynamic invariants.



$s(n)$



$$s_{R(n)} = [s(n), s(n - \tau), \dots, s(n - (D - 1)\tau)]^T$$

Experiments

ID	subjects	channels	sampling rate	sessions	tasks	trials/class	Epoch (s)
Zhou2016	3	14	250 Hz	3	3	160	[0, 5]
BNCI2014001	9	22	250 Hz	2	4	144	[2, 6]
BNCI2015001	12	13	512 Hz	1	2	200	[0, 5]
BNCI2014002	14	15	512 Hz	5	2	80	[3, 8]
BNCI2014004	9	3	250 Hz	1	2	360	[3, 7.5]

Bandpass [8, 35]Hz

Classification of different task

- Right hand vs Left hand.
- Right hand vs Feet.
- Right Hand vs Left Hand vs Feet.

Different evaluation

- Within-session (5 folds Cross Validation).
- Cross-session (LOOCV),

Classification Algorithm

- On Riemann Surface (MDM).
- On Tangent Space (using SVM),

Hyper-parameters

- Grid search.

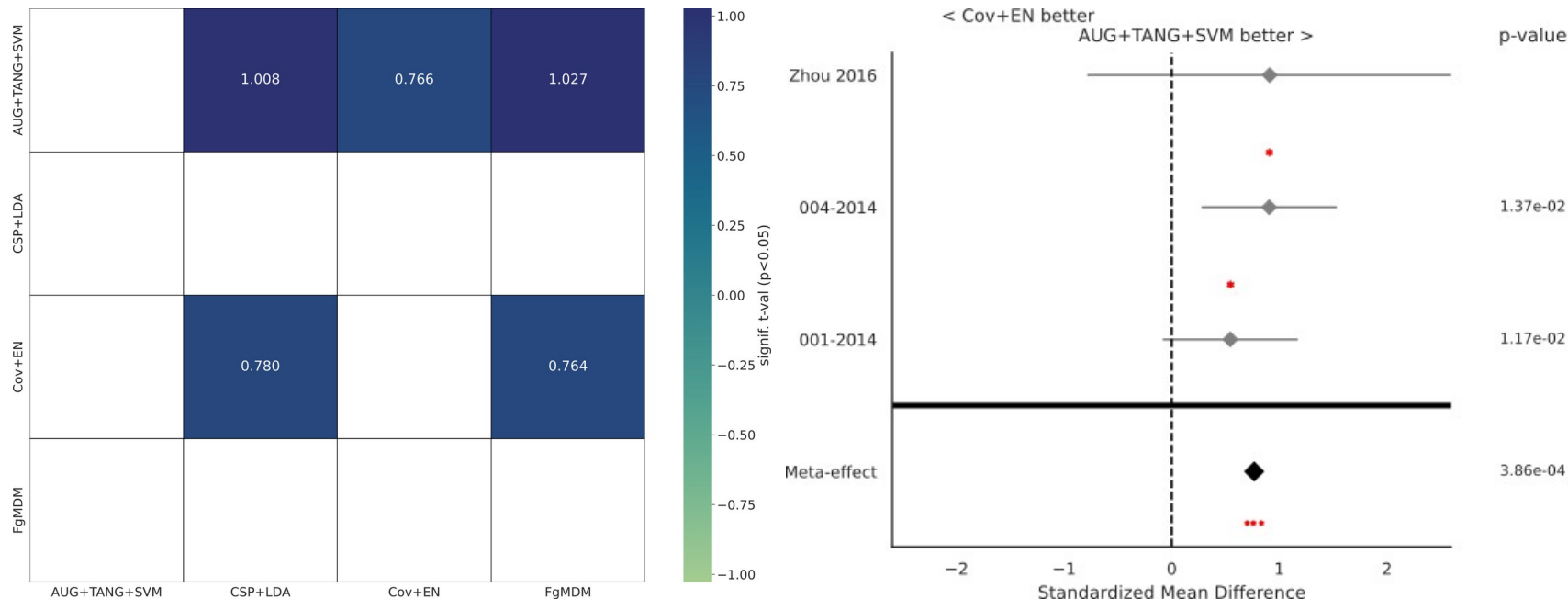
Carrara, I., & Papadopoulos, T. (2023).
Classification of BCI-EEG based on augmented
covariance matrix.
arXiv preprint arXiv:2302.04508.



Vinay Jayaram and Alexandre Barachant. "MOABB: trustworthy algorithm benchmarking for BCIs". In: *Journal of neural engineering* 15.6 (2018), p. 066011.

Classification results on **Right Hand vs Left Hand** task w.r.t the **state of the art** using a **within-session** evaluation procedure.

Dataset	CSP+LDA	AUG+TANG+SVM (Grid Search)	COV+EN	FgMDM
BNCI2014001	0.85 ± 0.14	0.93 ± 0.09	0.88 ± 0.11	0.88 ± 0.11
BNCI2014004	0.80 ± 0.15	0.83 ± 0.15	0.80 ± 0.15	0.79 ± 0.15
Zhou2016	0.91 ± 0.09	0.95 ± 0.06	0.93 ± 0.07	0.91 ± 0.08



Classification results on **Right Hand vs Left Hand** task w.r.t the **state of the art** using a **within-session** evaluation procedure.

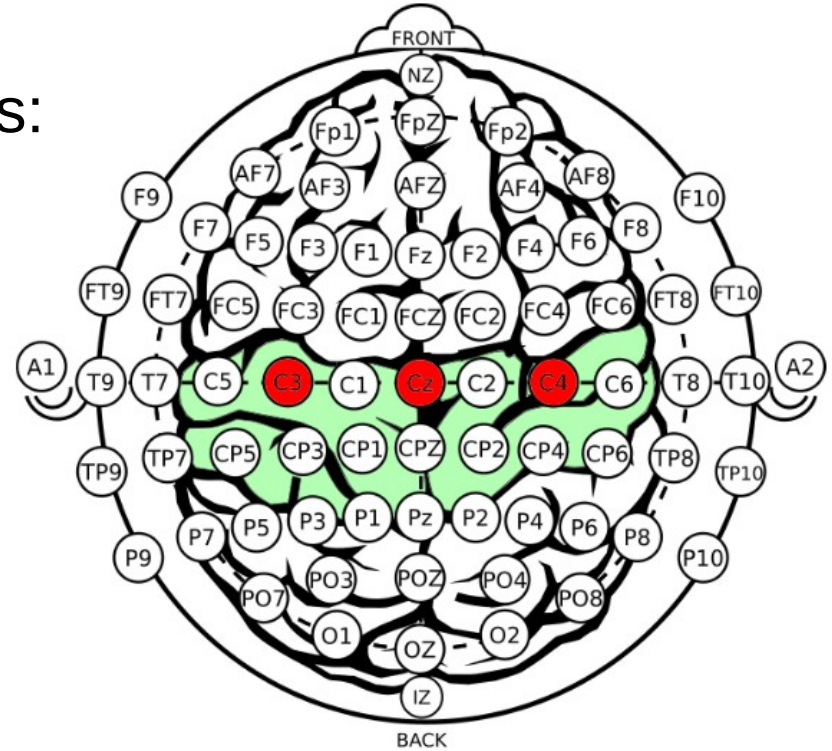
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Zhou2016	0.91 ± 0.09	0.95 ± 0.06	0.93 ± 0.07	0.91 ± 0.08

- 2% to 5% over the second best method !!!
- Easily obtained.

Reduced Dataset setting

1. Reduced Number of Electrodes

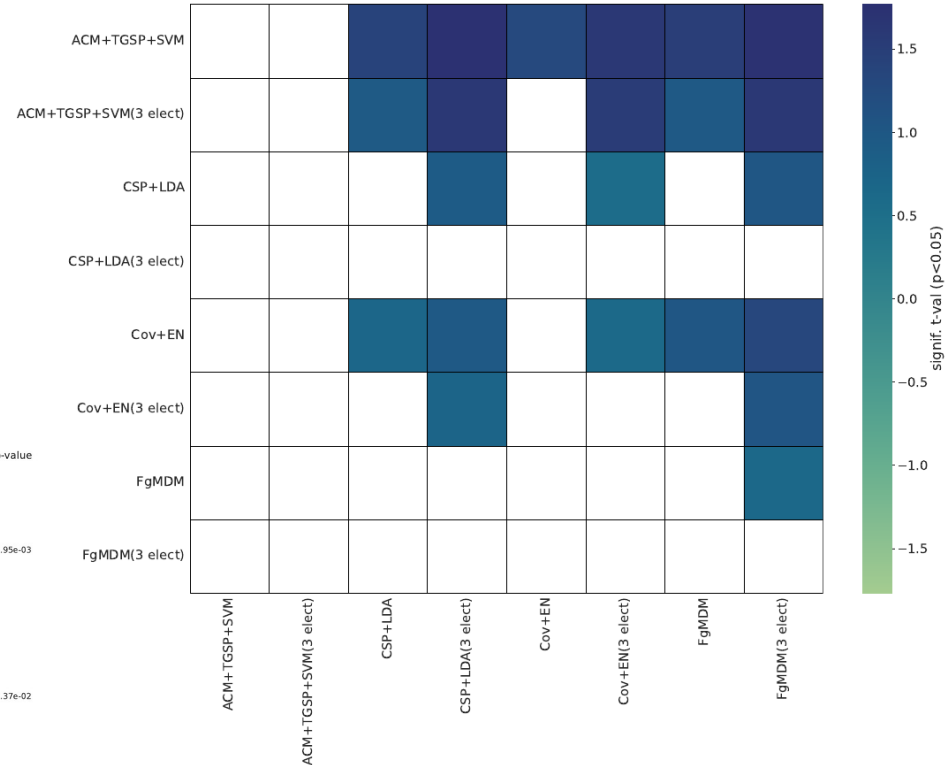
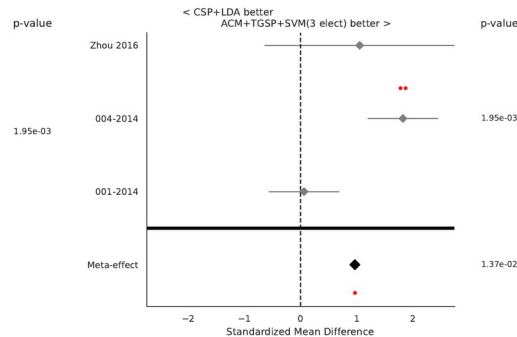
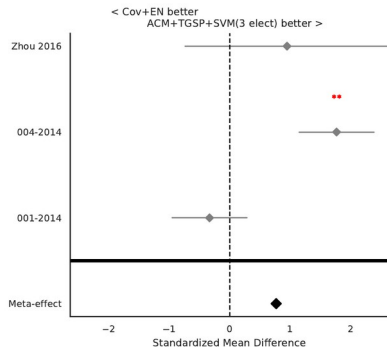
Only use the “motor” electrodes:
C3, Cz, C4



1. Reduced Number of Electrodes (c3, c4, cz)

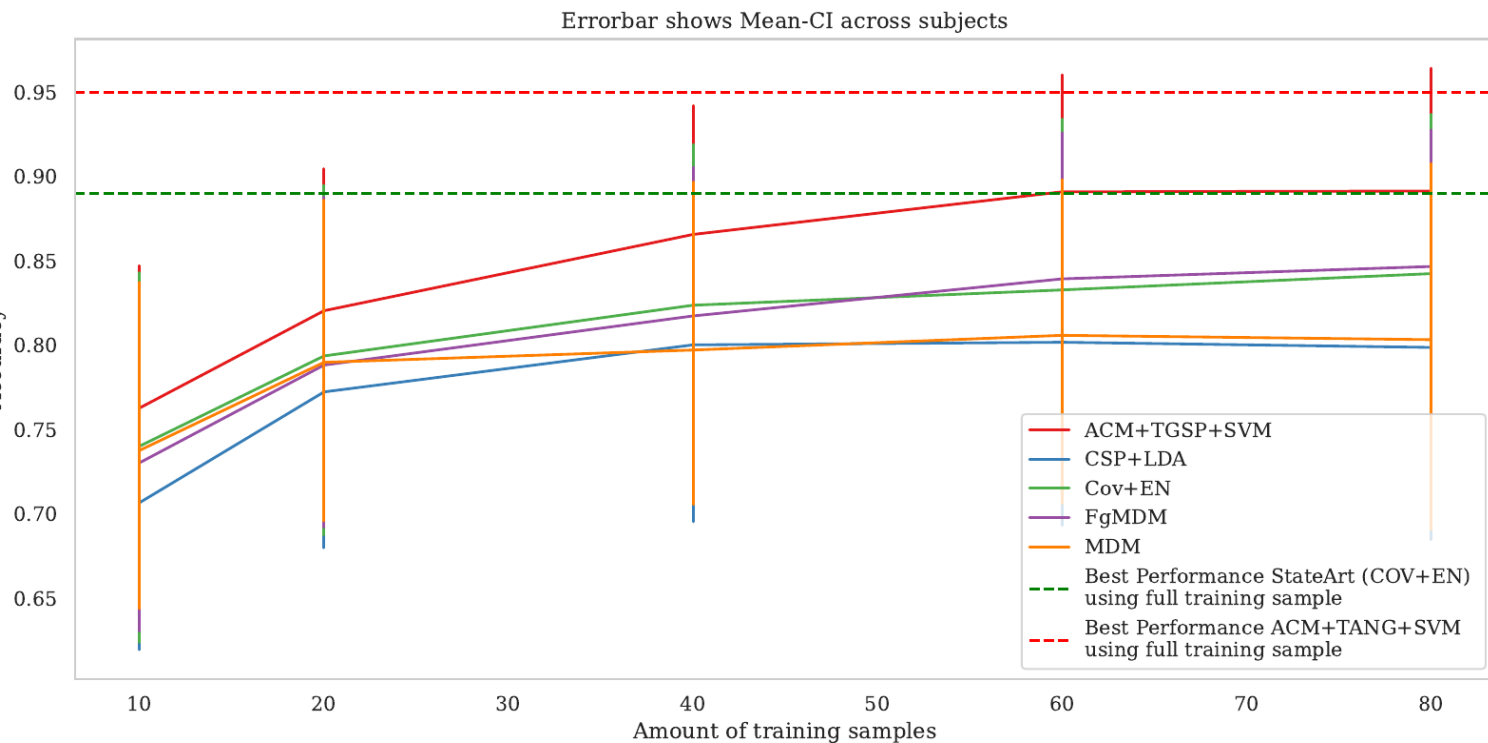
Different datasets, different tasks and evaluation procedures.

Pipeline	Eval	BNCI2014001	BNCI2014004	Zhou2016
MDM	WS	0.76 ± 0.15	0.78 ± 0.16	0.90 ± 0.05
COV+EN	WS	0.78 ± 0.15	0.80 ± 0.15	0.93 ± 0.05
FgMDM	WS	0.77 ± 0.15	0.79 ± 0.15	0.91 ± 0.05
ACM + TANG + SVM	WS	0.86 ± 0.10	0.89 ± 0.11	0.98 ± 0.03
CSP + LDA	WS	0.77 ± 0.16	0.80 ± 0.15	0.91 ± 0.06
ACM + CSP + LDA	WS	0.83 ± 0.12	0.85 ± 0.13	0.97 ± 0.02
VECTORIZE + LDA	WS	0.73 ± 0.15	0.80 ± 0.16	0.86 ± 0.08
ACM + VECTORIZE + LDA	WS	0.79 ± 0.13	0.83 ± 0.15	0.92 ± 0.04
MDM	CS	0.75 ± 0.16	0.79 ± 0.15	0.90 ± 0.04
COV+EN	CS	0.78 ± 0.14	0.81 ± 0.14	0.92 ± 0.06
FgMDM	CS	0.78 ± 0.13	0.80 ± 0.14	0.91 ± 0.06
ACM + TANG + SVM	CS	0.84 ± 0.11	0.86 ± 0.14	0.97 ± 0.02
CSP + LDA	CS	0.77 ± 0.15	0.81 ± 0.14	0.92 ± 0.05
ACM + CSP + LDA	CS	0.81 ± 0.13	0.84 ± 0.14	0.97 ± 0.02
VECTORIZE + LDA	CS	0.74 ± 0.14	0.79 ± 0.15	0.85 ± 0.11
ACM + VECTORIZE + LDA	CS	0.80 ± 0.12	0.84 ± 0.14	0.93 ± 0.03



2. Reduced Training Set

Different datasets, tasks in the Within-Session evaluation framework.



Conclusion

- Augmented Covariance Method is an “easy” way to improve BCI MI classification.
- Introduces only 2 hyper-parameters.
- Classification improvements can be used to reduce the number of channels or the number of training sample, while maintaining an accuracy comparable to the non-ACM state of the art.
→ More classification improvements.

Future Directions

- Explore different distances.
- Investigate what makes the Riemannian distance so effective.
- Find better ways than Grid Search to estimate hyper-parameters.
- Use the tools of AR models or dynamical system theory.

Thanks for the Attention

*To know more, see Igor demo at the end of the session...
And also poster 1-F-51*



We are looking for 1 (2) postdocs and 1 engineer → Contact me for details.