

Lab 7 : Program 16

Date : 04/11/20

Experiment : Smart Irrigation

Aim: To design a smart irrigation system

Hardware:

- Servo Motor
- Soil moisture sensor(Potentiometer)
- Arduino Uno

Source Code:

```
#include <Servo.h>
```

```
int servom = 3 ;
```

```
Servo motor;
```

```
int sensor = A0 ;
```

```
void setup()
```

```
{
```

```
  Serial.begin(9600);
```

```
  pinMode(servom, OUTPUT);
```

```
  motor.attach(servom);
```

```
}
```

```
void loop()
```

```
{
```

```
  int analog = analogRead(sensor);
```

```
  int pos = map(analog,0,1023,0,255);
```

```
  motor.write(pos);
```

```
  delay(50);
```

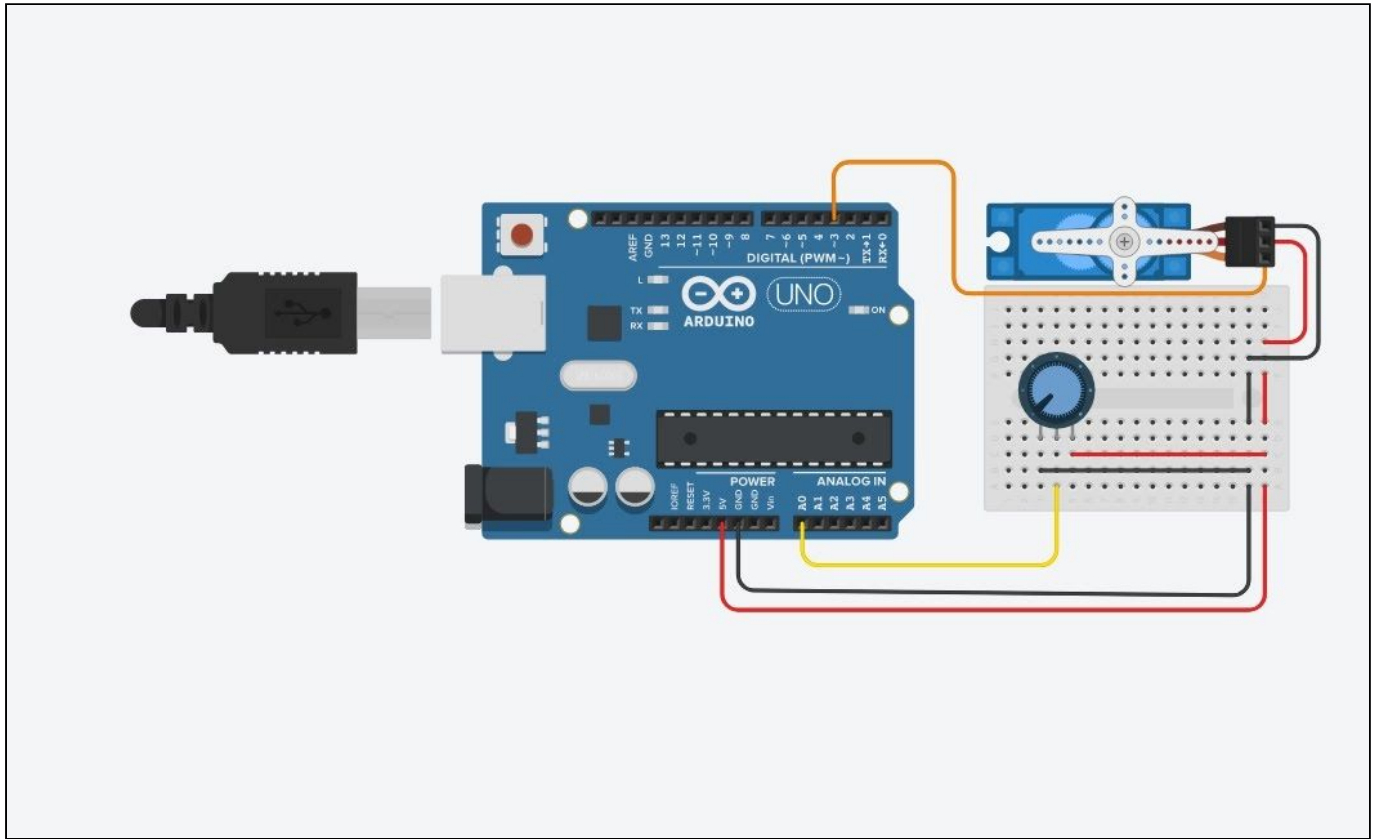
```
  Serial.println((String)"Sensor: "+analog+ "Moisture : " +pos);
```

```
  delay(500);
```

```
}
```

Observation: The motor rotates on change in moisture level (analog voltage).

Circuit :



Write Up:

Source Code

```
#include <Servo.h>
```

```
int servom = 3;
```

```
Servo smotor;
```

```
int sensor = A0;
```

```
void setup()
```

```
{  
  Serial.begin(9600);  
  pinMode(smotor, OUTPUT);  
  motor.attach(smotor);  
}
```

```
void loop()
```

```
{  
  int analog = analogRead(sensor);  
  int pos = map(analog, 0, 1023, 0, 180);  
  motor.write(pos);  
  delay(50);  
  Serial.println((String)"Sensor:" + analog +  
                  "Position:" + pos);  
  delay(500);  
}
```