### **NON-NEGATIVE MATRIX FACTORIZATION**

AP

## REVIEW OF SPECTRAL ANALYSIS/SVD

Decompose the data matrix and interpret its 'first' eigenvalues as concepts/topics for user and activity classification:

$$M = U\Sigma V^T$$

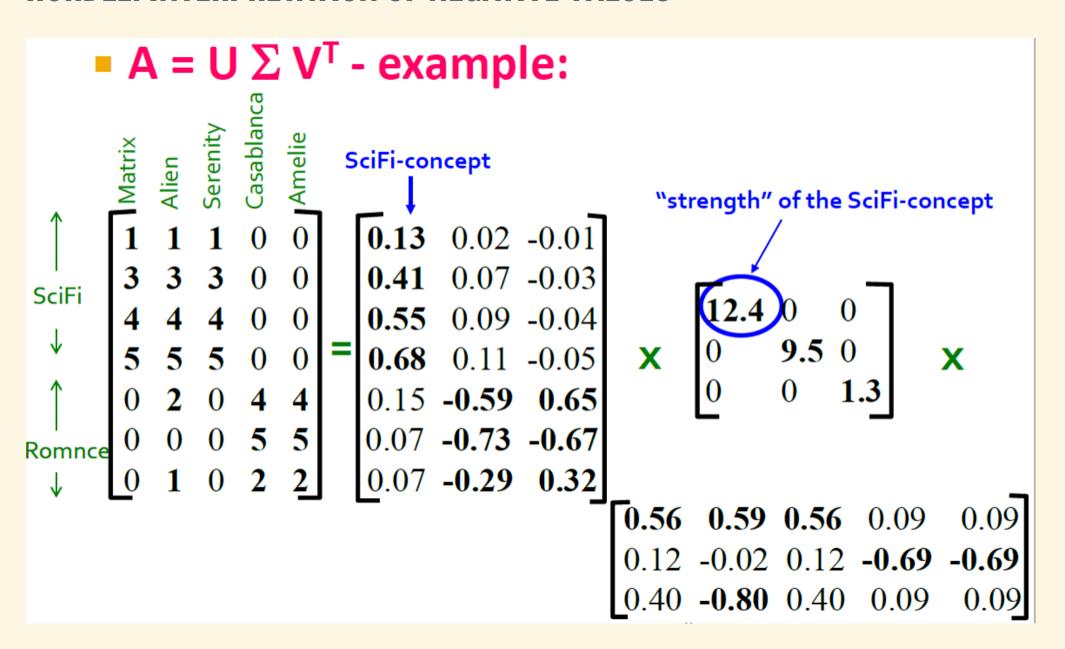
 $U_{(m imes r)}$  is column-orthonormal:  $u_i\cdot u_j^T=0$ 

 $V_{(r imes n)}^T$  is row-orthonormal:  $v_i^T \cdot v_j = 0$ 

 $\Sigma_{(r imes r)}$  (or  $D_{(r imes r)}$ ) is diagonal,  $\sigma_{ij}$  are the singular values

dimension  $r \leq \min\{m,n\}$  also depends on the no. of singular values found; it can be further reduced by dropping 0 and very low  $\sigma$ s

## **HURDLE: INTERPRETATION OF NEGATIVE VALUES**



With negative values from SVD we cannot distinguish between

- i. lack of information,
- ii. lack of interest or
- ii. outright repulsion.

## **AN IDEAL VIEW**

A non-negative decomposition of the activity matrix would be interpretable:

$$A_{(m imes n)} = P_{(m imes r)} \cdot Q_{(r imes n)}$$

- A: activity
- P: user participation to a topic
- Q: quantity of the topic in product

user/product profiling and reccommender sys. would be half-done already!

P and Q are of independent interest

## NON-NEGATIVE DECOMPOSITION

## CONTEXT

Lee and Seung sought a new approach to the problem of learning images (how to recognise them) via visual patters:

reduce a specific image to the combination of known patters: face  $\approx$  eyes, eyebrows, nose, chin etc.

Could each face be decomposed into basic, repeated visual patterns?

In the neural network model of brain activity, firing rates of neurons cannot be negative: patterns are either activated or ignored

Sparsity: only few patterns should be needed to re-create an image

Example dataset: faces (not Olivetti)

2429 mugshots, each having 19 imes 19 = 361 pixels, rescaled to [0,1]:  $V_{361 imes 2429}$ 

Lee-Seung fix r=49 and compute  $V_{361 imes2429}=W_{361 imes49} imes H_{49 imes2429}$ 

For comparison, they also try PCA (diagonalisation of  $VV^T$ ) and VQ

## THE NUMERICAL PROBLEM

Istance: a non-negative matrix V

Solution: non-negative matrix factors W and H s.t.

$$V pprox W \cdot H$$

with  $w_{ij}, h_{rs} \geq 0$ 

## **EXAMPLE**

$$V_{3 imes 3} = egin{pmatrix} 4 & 0 & 2 \ 0 & 3 & 1 \ 2 & 1 & 3 \end{pmatrix}$$

choose r=2

$$V_{3 imes 3}pprox W_{3 imes 2} imes H_{2 imes 3}=egin{pmatrix} 2&0\0&1.5\1&1 \end{pmatrix} imes egin{pmatrix} 2&0&1\0&2&1 \end{pmatrix} \ egin{pmatrix} 4&0&2\0&3&1\2&1&3 \end{pmatrix}pprox egin{pmatrix} 4&0&2\0&3&1.5\2&2&2&2 \end{pmatrix}$$

## **NOTATION**

$$A = B \cdot C$$

Let  $\mathbf{a}_i$  be the i-th column of A. It can be expressed as

$$\mathbf{a}_i = B \cdot \mathbf{c}_i$$

each col. of the result is seen as a linear combination of the cols. of B, with  $c_i$  supplying the weights:

$$\mathbf{a}_i = B \cdot \mathbf{c}_i = c_{1,i} \mathbf{b}_1 + c_{2,i} \mathbf{b}_2 + \cdots + c_{n,i} \mathbf{b}_n$$

### **EXAMPLE**

$$egin{pmatrix} 4 & 0 & 2 \ 0 & 3 & 1 \ 2 & 1 & 3 \end{pmatrix} pprox egin{pmatrix} 2 & 0 \ 0 & 1.5 \ 1 & 1 \end{pmatrix} imes egin{pmatrix} 2 & 0 & 1 \ 0 & 2 & 1 \end{pmatrix} \ egin{pmatrix} 4 \ 0 \ 2 \end{pmatrix} pprox egin{pmatrix} 2 & 0 \ 0 & 1.5 \ 1 & 1 \end{pmatrix} imes egin{pmatrix} 2 \ 0 \ 1.5 \ 1 \end{pmatrix} imes 0 \ 1.5 \ 1 \end{pmatrix} \cdot 0$$

## INTERPRETABILITY OF NMF

## **HOW WE READ NMF**

Let  $\mathbf{v}_i$  be the i-th column of V.

If V is an activity m.,  $\mathbf{v}_i$  represent the consumption of i

$$v_i pprox W \cdot h_i$$

Consumption of i is given by a linear combination of the cols. of W, with  $h_i$  supplying the weights.

Each  $\mathbf{w}_i$  is interpretable as a pattern (or mask)

[Lee & Seung, Nature, 1999]: "Learning the parts of objects by non-negative matrix factorization."

$$\mathbf{v}_i pprox \mathbf{w}_1 \cdot h_{1,i} + \ldots \mathbf{w}_r \cdot h_{1,r}$$

W can be regarded as containing a basis that is optimized for the linear approximation of the data in V.

Since relatively few basis vectors are used to represent many data vectors, good approximation can only be achieved if the basis vectors discover structure that is latent in the data.

## **NORM NOTATION**

Frobenius' element-wise norm:

$$||A_{m imes n}||_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n a_{ij}^2} = \sqrt{\sum_{i,j} a_{ij}^2}$$

Notation for error:

$$||X-Y||_F^2 = ||X-Y||^2 = \sum_{i,j} (x_{ij}-y_{ij})^2$$

## NMF AS ERROR-MINIMIZATION

## **COMPUTATIONAL PROBLEM**

Input:  $V_{n imes m}$ Minimize  $||V - WH||^2$ subject to  $W, H \geq 0$ .

- choose the new dimension r s.t. (n+m)r < nm;
- ullet calculate  $W_{n imes r}$  and  $H_{r imes m}$ .

## **ASIDE: INFORMATION-THEORETIC VIEW**

If the input matrix can be (somehow) normalised then we see the search for the perfect non-negative decomposition in terms of minimizing *divergence*:

$$D_I(X||Y) = \Sigma_{i,j}(x_{ij} \cdot \log(rac{x_{ij}}{y_{ij}}) - x_{ij} + y_{ij}))$$

Minimize  $D_I(V||WH)$ 

subject to  $W, H \geq 0$ .

Recommended version for sparse counting data.

The Kullback-Leibler divergence,  $D_{KL}$ , may also be used.

## **GRADIENT DESCENT MAY NOT FIND THE MINIMAL-ERROR SOLUTION**

Although [error func.] are convex in W only or H only, they are not convex in both variables together.

Therefore it is unrealistic to expect an algorithm to solve [the problem] in the sense of finding global minima.

However, there are many techniques from numerical optimization for finding local minima.

Gradient descent is perhaps the simplest technique to implement, but convergence can be slow.

## LEE-SEUNG'S METHOD

## **ITERATED ERROR BALANCING**

1. initialise W and H at random

#### repeat:

- 2. compute the error
- 3. update W and H with the multiplicative update rule
- 4. normalise W: each column sums to 1

#### until error is tamed

$$\begin{aligned} W_{ia} \leftarrow W_{ia} \sum_{\mu} \frac{V_{i\mu}}{(WH)_{i\mu}} H_{a\mu} \\ W_{ia} \leftarrow \frac{W_{ia}}{\sum_{j} W_{ja}} \end{aligned}$$

$$H_{a\mu} \leftarrow H_{a\mu} \sum_{i} W_{ia} \frac{V_{i\mu}}{(WH)_{i\mu}}$$

## **MULTIPLICATIVE UPDATE**

Classical Gradient descent: we move around by adding/subtracting some quantity

NMF: we move around by multiplying by a local error measure  $\frac{v_{i\mu}}{(wh)_{i\mu}}$ 

$$\begin{aligned} W_{ia} \leftarrow W_{ia} \sum_{\mu} \frac{V_{i\mu}}{(WH)_{i\mu}} H_{a\mu} \\ W_{ia} \leftarrow \frac{W_{ia}}{\sum_{j} W_{ja}} \end{aligned} \end{bmatrix} H_{a\mu} \leftarrow H_{a\mu} \sum_{i} W_{ia} \frac{V_{i\mu}}{(WH)_{i\mu}}$$

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$$H_{a\mu} \leftarrow H_{a\mu} \sum_{i} W_{ia} \frac{V_{i\mu}}{(WH)_{i\mu}}$$

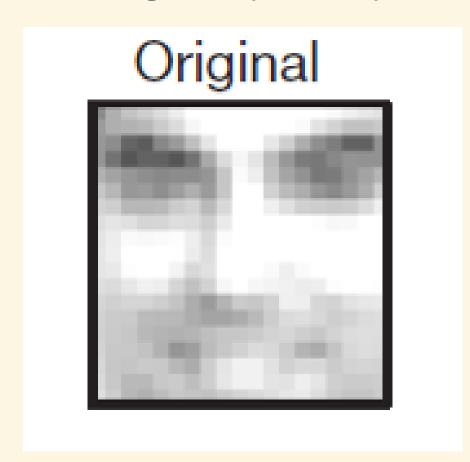
- through iteration, the  $\frac{v_{i\mu}}{(wh)_{i\mu}}$  factors vanish and we stop.
- the update rules maintain non-negativity and force the  $\mathbf{w}_i$  columns to sum to 1.

## INTERPRETABILITY OF NMF

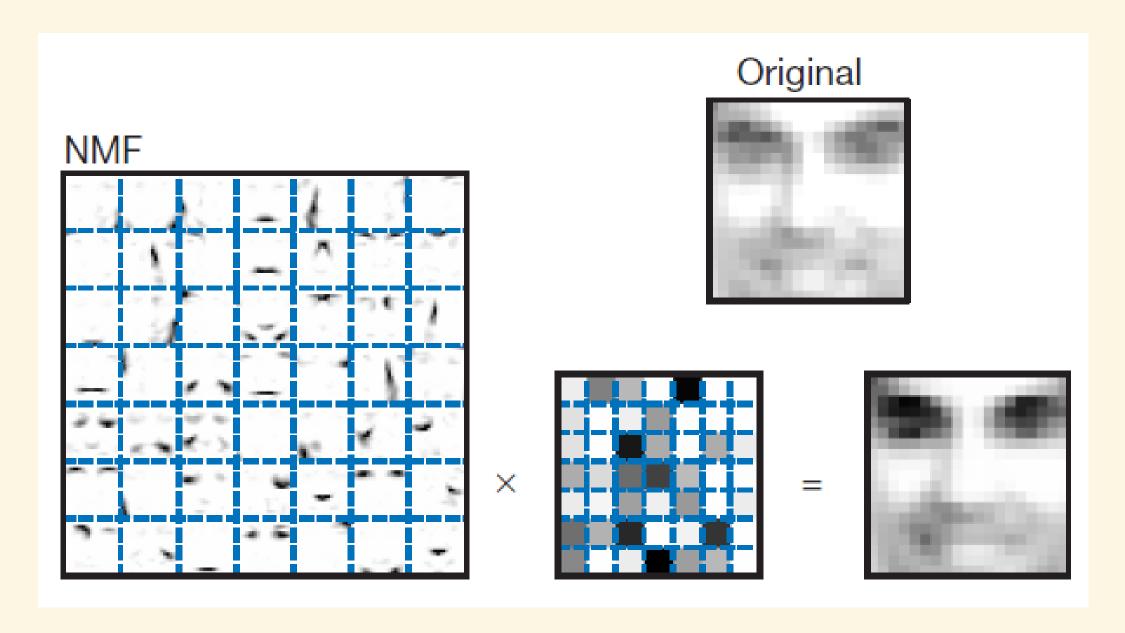
## **EXTRACTING COMMON PARTS: FACIAL FEATURES**

Each column  $V_i$  represent a 19x19 mugshots

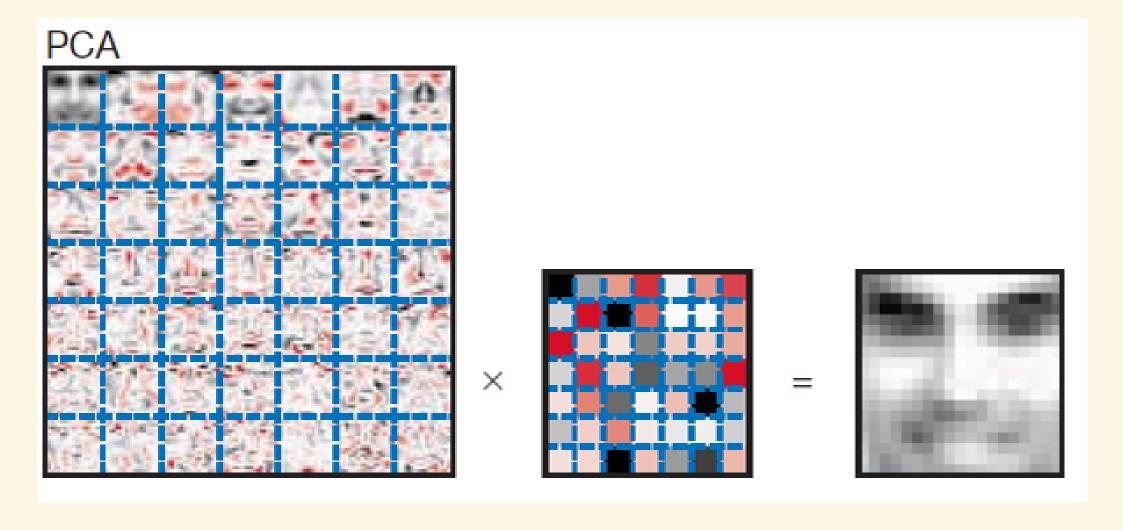
Lee-Seung render it as a linear combination of 49 common facial features, each weighted by an entry in the H matrix.



## W AND H IN A 7X7 MONTAGE



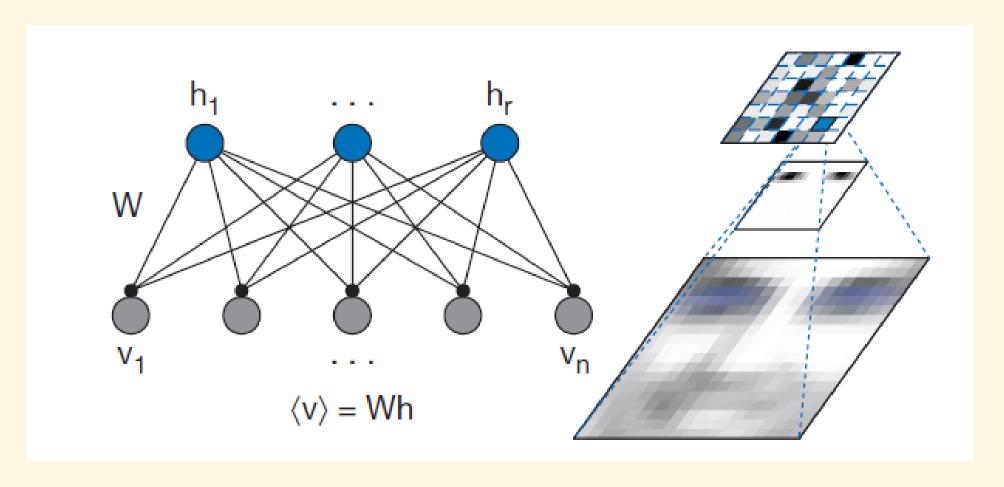
### The eigenfaces might have negative values



### A PROBABILISTIC HIDDEN-VARIABLES MODEL:

The columns. of W are bases that are combined to form the reconstruction

As in neural networks, the influence of  ${f h}_a$  on  ${f v}_i$  is represented by a connection of strength  $w_{ia}$ 



## NMF IN SCIKIT-LEARN

## THE OLIVETTI FACES

Today Lee-Seung method is implemented in Scikit-learn via the mu (multiplicative update) method

try sklearn.decomposition.NMF

```
1 faces = fetch_olivetti_faces()
2
3 nmf_estimator = decomposition.NMF(solver='mu')
4
5 nmf_estimator.fit(faces)
```

For reference: a visual comparison of the decomposition methods available in Scikit-learn

## CODA: SIMPLE NMF EXAMPLE

### **DECOMPOSING THE NETFLIX EXAMPLE**

Another look at the running example with film ratings

W: users' committment to a topic.

H: films' pertinence to a specific topic (binary, why?)

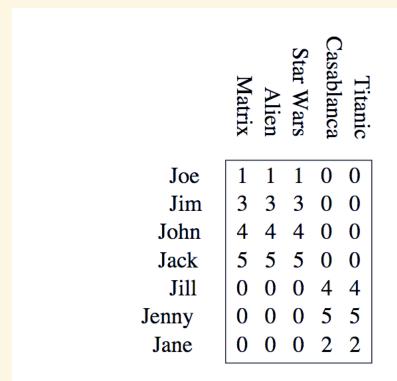


Figure 11.6: Ratings of movies by users

# Let R be the film ratings matrix and compute R=PQ M=7, N=5 and we fix K=2 to run NMF:

```
1 @INPUT:
2 R: input matrix to be factorized, dim. M x N
3 P: an initial m. of dim. M x K
4 Q: an initial m. of dim. K x N
5 K: the no. of latent features
6 steps: the max no. of steps to perform the optimisation
7 alpha: the learning rate
8 beta: the regularization parameter
9
10 @OUTPUT:
11 the final matrices P and Q
```

## DIRECT IMPLEMENTATION (1 RUN)

```
1 nP=
2 [[ 0.33104196  0.39332058]
3  [ 1.08079793  1.08397306]
4  [ 1.59267325  1.27929568]
5  [ 1.87852789  1.72209575]
6  [ 0.67146598  1.76523621]
7  [ 1.04872774  2.10824903]
8  [ 0.94419145  0.59698619]]

1 nQ.T=
2 [[ 1.27381876  1.3870236  1.67315614  0.9855609  0.81578369]
3  [ 1.50953822  1.38352352  1.06501557  1.87281749  1.96189735]]
```

## ANALYSIS OF THE ERROR, I

```
np.dot(nP, nQ.T) = [
      [ 3.01303945  2.99879446  2.96279189  3.09527589  3.0083412 ]
         [ 3.95992279  3.97901104  4.02726085  3.9655638  3.80912366]
4
5
         [ 4.99247343  4.98812249  4.97712927  5.07657468  4.91104751]
6
         [ 3.52001748  3.37358497  3.00347147  3.96773585  4.01098322]
         [ 4.51837154  4.37142223  4.00000329  4.98195069  4.99170315]
         [ 2.10390225  2.13556026  2.21557931  2.04860435  1.94148161]
8
9
  ratings = [[1, 1, 1, 0, 0],
             [3, 3, 3, 0, 0],
             [4, 4, 4, 0, 0],
4
             [5, 5, 5, 0, 0],
             [0, 0, 0, 4, 4],
6
             [0, 0, 0, 5, 5],
             [0, 0, 0, 2, 2]
8
```

## ANALYSIS OF THE ERROR, II

```
np.rint(np.dot(nP, nQ.T))= [
       [ 1. 1. 1. 1. 1.]
             [3. 3. 3. 3.]
             [4.4.4.4.4.]
             [5. 5. 5. 5. 5.]
             [4.4.4.4.4.]
6
             [5. 5. 5. 5. 5.]
             [ 2. 2. 2. 2. 2.]
9
  ratings = [[1, 1, 1, 0, 0],
            [3, 3, 3, 0, 0],
            [4, 4, 4, 0, 0],
            [5, 5, 5, 0, 0],
            [0, 0, 0, 4, 4],
            [0, 0, 0, 5, 5],
6
            [0, 0, 0, 2, 2]]
```

### **ANALYSIS OF THE RESULT**

W: users' committment to a topic.

H: films' pertinence to a specific topic (binary, why?)