

# With Big Data Comes Big Compute: Scaling Machine Learning onto Public and Commercial Clouds with Kubernetes - Part 2

Introduction to Containers and Kubernetes

IEEE International Conference on Big Data



December 2023



### Part 2 - Learning Objectives

- Deploying Scikit Learn ML Jobs to Kubernetes
- Deploying GPU Jobs to Kubernetes for Training Computer Vision Models
- Scaling Computer Vision Models on Kubernetes with Job Automation





#### **MU-HPDI/Nautilus**

- Sample Dockerfiles
- Sample Kubernetes YAML File
- Wiki with detailed walkthroughs for:
  - Getting Started
  - Creating PVC
  - Creating Pods
  - Creating Jobs

► Nautilus Portal:

#### https://portal.nrp-nautilus.io

► JupyterHub Instance:

https://bigdata-2023.nrp-nautilus.io/

► Tutorial Repository of Jupyter Project Pages, Code Samples, YAML, etc.

https://github.com/MU-HPDI/bigdata-2023

► Git Clone Command:

git clone <a href="https://github.com/MU-HPDI/bigdata-2023.git">https://github.com/MU-HPDI/bigdata-2023.git</a>



Over a short break, we will ensure everyone has cloned this Repo into their JupyterLab environment



## Part 2-A National Research Platform Nautilus Research Cluster

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#### Motivation

- Shallow ML modules often require extensive hyperparameter optimization to find optimal performance
- Deep Learning models require incredible amounts of compute to effectively train
- Using single developer machines or local on-prem resources often fail to scale effectively
- Kubernetes Clusters provide an efficient and scalable solution to training ML and deep learning models at scale
- ► This workshop will address the building and deployment of ML and deep learning containers to Nautilus to train deep networks



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#### Part-2 Tutorial Outline

- Quick Containerization Review and Advanced:
  - Review of containerization
  - Building ML containers for Scikit-Learn
  - Building Optimized Containers for Deep Learning with PyTorch
  - Using Common Frameworks: Detectron2, MMDetection, and Ultralytics
- ► Kubernetes ML / Deep Learning:
  - Review of Kubernetes Architecture and Key Concepts
  - Introduction to NRP Nautilus HyperCluster
  - Migrating Data to NRP with S3
  - Deploying Scikit-Learn ML Jobs to Nautilus
  - Deploying GPU Jobs to Nautilus for Training Computer Vision Models



### Containerization

Building Optimized Containers for Deep Learning with PyTorch



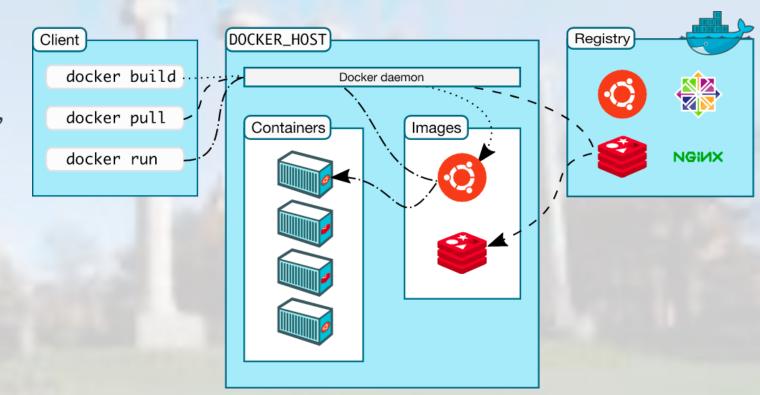
#### Containerization Docker

#### ▶ Docker

➤ You can think of Docker containers as mini-VMs that contain all the packages, both at the OS and language-specific level, necessary to run your software.

#### ► Nautilus Gitlab

- Offers the ability to create repo for your code
- Offers the ability to create easily maintained and developed custom images using CI/CD feature





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## Using Common Deep Learning Frameworks

Open MMLab, FAIR, and Ultralytics



#### Deep Learning Frameworks

- Many companies and research labs are developing open source Deep Neural Network frameworks to perform Computer Vision tasks
  - ▶ Open MMLab
  - ► Facebook Al Research
  - ▶ Ultralytics
  - ▶ Google
- ► We can build optimized Docker containers with these frameworks and use them as a baseline for research
- ► To use a given framework on Nautilus, we only need a Dockerfile → From the Dockerfile, we can build a container image that can be deployed on the cluster











# MMLab Frameworks: MMDetection, MMClassification, MMSegmentation

- Open MMLab has developed a set of extensible libraries for performing key Computer Vision tasks:
  - ► Classification: MMClassification
  - ▶ Object Detection: MMDetection
  - ► Semantic Segmentation: MMSegmentation
- ► These libraries can serve as an excellent starting point for many CV applications
- Very large model zoo with community trained models and benchmarks
- ► Highly extensible and configurable frameworks









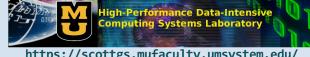
#### MMDetection Dockerfile

- Dockerfile contains all steps to create a fully functional MMDetection Python environment
- Add your code to the container or use this Dockerfile as a base in a multi-stage build

```
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```

```
FROM nvcr.io/nvidia/pytorch:22.06-py3
# arg
ARG MMDET_VERSION=2.25.0
ARG MMCV VERSION=1.5.2
ARG MMCLS_VERSION=0.23.1
ARG BUILD DIR="/build"
# env variables
ENV MPLCONFIGDIR /tmp
ENV TORCH_HOME /tmp
ENV MMCV_WITH_OPS 1
ENV FORCE_CUDA 1
ENV CUDA_HOME /usr/local/cuda
# create the build dir
RUN mkdir -p ${BUILD_DIR}
RUN apt update -y && apt install -y libpng-dev libjpeg-dev libgl-dev wget && rm -rf /var/lib/apt/lists/*
# install mm cv
# https://mmcv.readthedocs.io/en/latest/get_started/build.html#build-on-linux-or-macos
RUN wget https://github.com/open-mmlab/mmcv/archive/refs/tags/v${MMCV_VERSION}.tar.gz -0 /tmp/mmcv.tar.gz
RUN tar -xzf /tmp/mmcv.tar.gz
RUN mv ./mmcv-${MMCV_VERSION} ${BUILD_DIR}/mmcv
# install it
RUN pip install -r ${BUILD_DIR}/mmcv/requirements/optional.txt
RUN pip install -v ${BUILD_DIR}/mmcv
# install mm detection
# https://github.com/open-mmlab/mmdetection/blob/v2.25.0/docs/en/get_started.md#customize-installation
RUN wget https://github.com/open-mmlab/mmdetection/archive/refs/tags/v${MMDET_VERSION}.tar.gz -0 /tmp/mmdet.tar.gz
RUN tar -xzf /tmp/mmdet.tar.gz
RUN mv ./mmdetection-${MMDET_VERSION} ${BUILD_DIR}/mmdet
# install it
RUN pip install ${BUILD_DIR}/mmdet
```



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# ee Detectron2

- ▶ Detectron2 is an open source framework for Object Detection and Instance Segmentation developed by FAIR
- ► The original Mask R-CNN model was developed and published via this framework
- ► Highly extensible with custom components and highly configurable
- ► High quality pretrained models and dataset benchmarks









#### Detectron2 Dockerfile



- Dockerfile contains all steps to create a fully functional Detectron2 Python environment
- Add your code to the container or use this Dockerfile as a base in a multi-stage build

```
FROM nvcr.io/nvidia/pytorch:21.06-py3
      # install system reqs
       RUN apt update && apt install -y vim libgl-dev
      RUN apt-get install -- reinstall ca-certificates # for git
      # env variables
      ENV MPLCONFIGDIR /tmp
       ENV TORCH_HOME /tmp
10
       ENV FVCORE_CACHE /tmp
11
13
       ##########
14
       # Detectron 2
15
       #########
      RUN git clone -b 'v0.4' --single-branch --depth 1 --recursive https://github.com/facebookresearch/detectron2.git /workspace/detectron2
       RUN pip install -v /workspace/detectron2/
```

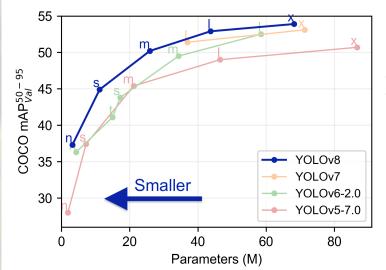






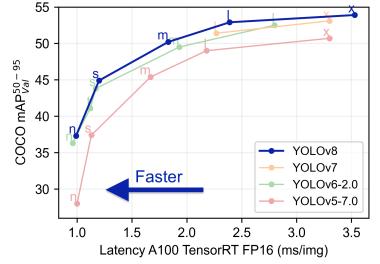
### Ultralytics

- Developer of most used Open-Source implementation of YOLOv3, YOLOv5, and more recently, YOLOv8
- ➤ You Only Look Once (YOLO) is a common real-time object detection architecture with many variations over the years
  - ► YOLO
  - ► YOLO9000 (a.k.a. YOLOv2)
  - ► YOLOv3
  - ► YOLOv5
  - ▶ YOLOv8











#### **Ultralytics** Dockerfile

Dockerfile contains all steps to create a fully functional YOLOv3, YOLOv5, or YOLOv8 Python environment

11

13

ENV OMP\_NUM\_THREADS=1

- ► Add your code to the container or use this Dockerfile as a base in a multi-stage build
- ultralytics/ultralytics

```
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```

```
# Ultralytics YOLO 🚀, AGPL-3.0 license
# Builds ultralytics/ultralytics:latest image on DockerHub https://hub.docker.com/r/ultralytics/ultralytics
# Image is CUDA-optimized for YOLOv8 single/multi-GPU training and inference
# Start FROM PyTorch image https://hub.docker.com/r/pytorch/pytorch or nvcr.io/nvidia/pytorch:23.03-py3
FROM pytorch/pytorch:2.0.0-cuda11.7-cudnn8-runtime
# Downloads to user config dir
ADD https://ultralytics.com/assets/Arial.ttf https://ultralytics.com/assets/Arial.Unicode.ttf /root/.config/Ultralytics/
# Install linux packages
# g++ required to build 'tflite_support' package
RUN apt update \
    && apt install --no-install-recommends -y gcc git zip curl htop libgl1-mesa-glx libglib2.0-0 libpython3-dev gnupg g++
# RUN alias python=python3
# Security updates
# https://security.snyk.io/vuln/SNYK-UBUNTU1804-OPENSSL-3314796
RUN apt upgrade --no-install-recommends -y openssl tar
# Create working directory
RUN mkdir -p /usr/src/ultralytics
WORKDIR /usr/src/ultralytics
# Copy contents
# COPY . /usr/src/app (issues as not a .git directory)
RUN git clone https://github.com/ultralytics/ultralytics /usr/src/ultralytics
ADD https://github.com/ultralytics/assets/releases/download/v0.0.0/yolov8n.pt /usr/src/ultralytics/
# Install pip packages
RUN python3 -m pip install --upgrade pip wheel
RUN pip install --no-cache -e . albumentations comet tensorboard thop pycocotools
# Set environment variables
```



Migrating Data to Nautilus



#### Deep Learning & Data

- Deep Learning algorithms require a vast amount of representative training data to effectively train
  - ► The more complex the network architecture, the more quality data is required
- Previous portions of this workshop have covered creating the containers to train the algorithms, but we have not yet covered how to stage data to Nautilus
  - ▶ All data for use on Nautilus will need to be moved to persistent volumes on the cluster
- ▶ Three ways to move data to a persistent volume on Nautilus:
  - ▶ Using KubeCTL
  - Using Commercial Cloud Storage
  - ► Using Nautilus S3 Storage ← Recommended



# Migrating Data to Nautilus: KubeCTL

- ► The command line Kubernetes tool, KubeCTL, has functionality to copy data to and from running pods
  - ▶ We can use this copy utility to move data to the cluster
- Advantages:
  - ► No additional installation or setup
  - ▶ No need to stage data in cloud storage
  - Requires only the KubeCTL command line tool

- ▶ Disadvantages:
  - ➤ Only small amounts (< 100 MB) of data can be moved per kubectl copy command
  - ► KubeCTL copy is *slow* at < 100 Mbps upload speeds

► How to:

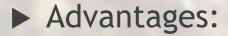
kubectl cp localpath podname:/path/on/pod





# Migrating Data to Nautilus: Using Commercial Cloud Storage

▶ We can use commercial cloud storage, such GCP Buckets or AWS S3 to move data to Nautilus



- ► Flexibility of cloud platform
- Very fast transfer speeds
- ► Capable of virtually any amount of data

#### Disadvantages

- ▶ Cost
- Setup of Cloud Storage
- ► Installation of Cloud Interface
- Staging of data in cloud

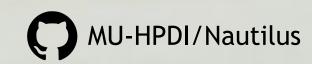
#### ► How to:

- Create cloud bucket with Commercial Cloud Vendor (i.e., GCP)
- ► Copy data to Bucket: gsutil cp localpath gs://bucketName
- Create Google Cloud Pod on Nautilus
- ► Copy data from Bucket: gsutil cp gs://bucketName /path/on/pod













# Migrating Data to Nautilus: Using Nautilus S3 Storage



- ▶ NRP provides S3 bucket storage for free to Nautilus users upon request
- ► Advantages:
  - ▶ Free
  - ► High-throughput link to Nautilus cluster
  - ► Integration with S3-compatible software
  - ► Capability to handle large amounts of data

- ▶ Disadvantages:
  - ▶ Must request access
  - Setup of cloud integration
  - Staging of data into Nautilus S3

#### ► How To:

- ► Request access to cloud storage to receive Access ID and Keys
- ▶ Install rclone or similar tool at data source and copy data from source to Nautilus S3
- ► Create rclone or similar tool pod on Nautilus cluster and copy from S3 to Persistent Volume





# High-Performance Data-Intensive Computing Systems Laboratory

Part 2-B Deploying Scikit-Learn Jobs to Nautilus for Machine Learning

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### Prerequisites

- ▶ To run jobs on Nautilus, the following prerequisites must be met:
  - ► You have access to Nautilus and have been assigned a namespace
  - You have a container published to a public registry with the necessary code to perform the ML task
  - ► You have the data for the ML task on a persistent volume in the cluster



Access

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**Data** 



### Access the MachineLearning\_K8s Notebook

Follow along activity





# Deploying GPU Jobs to Nautilus for Computer Vision Applications

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Part 2-C



nttps://scottgs.mu+aculty.umsystem.

### Prerequisites - Review + GPU differences

- ▶ To run GPU jobs on Nautilus, the following prerequisites must be met:
  - ► You have access to Nautilus and have been assigned a namespace
  - ► You have a GPU enabled container published to a public registry with the necessary code to perform the CV task
  - ► You have the data for the CV task on a persistent volume in the cluster



Access

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Data



### Access the DeepLearning\_K8s Notebook

Follow along activity





Part 2-D
Automating Jobs on Nautilus using Bash
and Python

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# Deep Learning on Nautilus: Semantic segmentation

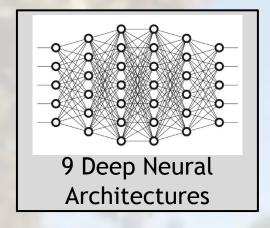


- ▶ Iterations of Training Completed: 515,550
- ▶ Number of images Processed: 7,070,400
- ► Trainable Parameters Optimized: 23 millions per model
- ► The time it took to prepare the experimental set up and to run all the training sessions in parallel is 12 hours
- ▶ The actual time it would have take to train is 21 days 12 hours 45 minutes



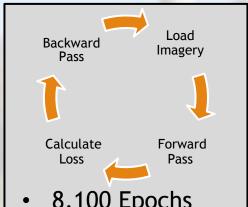
### Deep Learning on Nautilus: Transformer Research



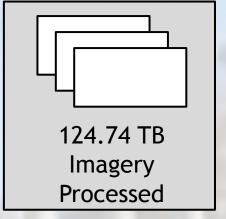








- 8,100 Epochs
- 30M iterations
- 1.7B parameters











#### MU-HPDI/Nautilus - A resource for exploration

- ▶ Sample Dockerfiles
- ► Sample Kubernetes YAML File
- Wiki with detailed walkthroughs for:
  - ▶ Getting Started
  - ► Creating PVC
  - ► Creating Pods
  - ► Creating Jobs

Check back occasionally, we are adding more content and recipes for scaling

Machine Learning and Deep Learning

