

SMART WEARABLE LEARNING DEVICE

FOR VISUALLY DISABLED PERSONS

INTERNAL GUIDE

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OBJECTIVE:-

- ❖ The designed Smart wearable device can identify objects in the outside environment and give output as an audio format.
- ❖ The designed Smart wearable device provides Voice Command Assistance
- ❖ This help visually disabled person aid them in the primary learning task of identifying objects without the supervision of the third party.



BASE PAPER:-

- ❖ Smart Hat: Design and Implementation of a Wearable Learning Device for Kids using AI and IoTs Techniques by Hsiung Chang, Chih-Yung Chang, Bhargavi Dande.



COMPARISON

Previous Project

- Captures Only Image.
- Complex Hardware(Arduino, raspberryPI,wifi,Bluetooth module).
- More Power Consumption.
- Issue with Arduino and raspberry communication.
- Contains single functionality button.
- Hardware system is costly.

Present Project

- Captures image, voice command and voice assistance
- Simple Hardware (RaspberryPI)
- Less Power Consumption.
- No, need of communication.
- Consists 3 different buttons for 3 different functionalities.
- Hardware system is economic.



Requirements:-

❖ Hardware:-

- I. Raspberry pi 3
- II. Speaker
- III. Microphone
- IV. PI camera
- V. Breadboard with Switches

❖ Software:-

- I. Python 3
- II. Tensor Flow
- III. Anaconda Navigator



PHASE'S:-

1. IOT PHASE

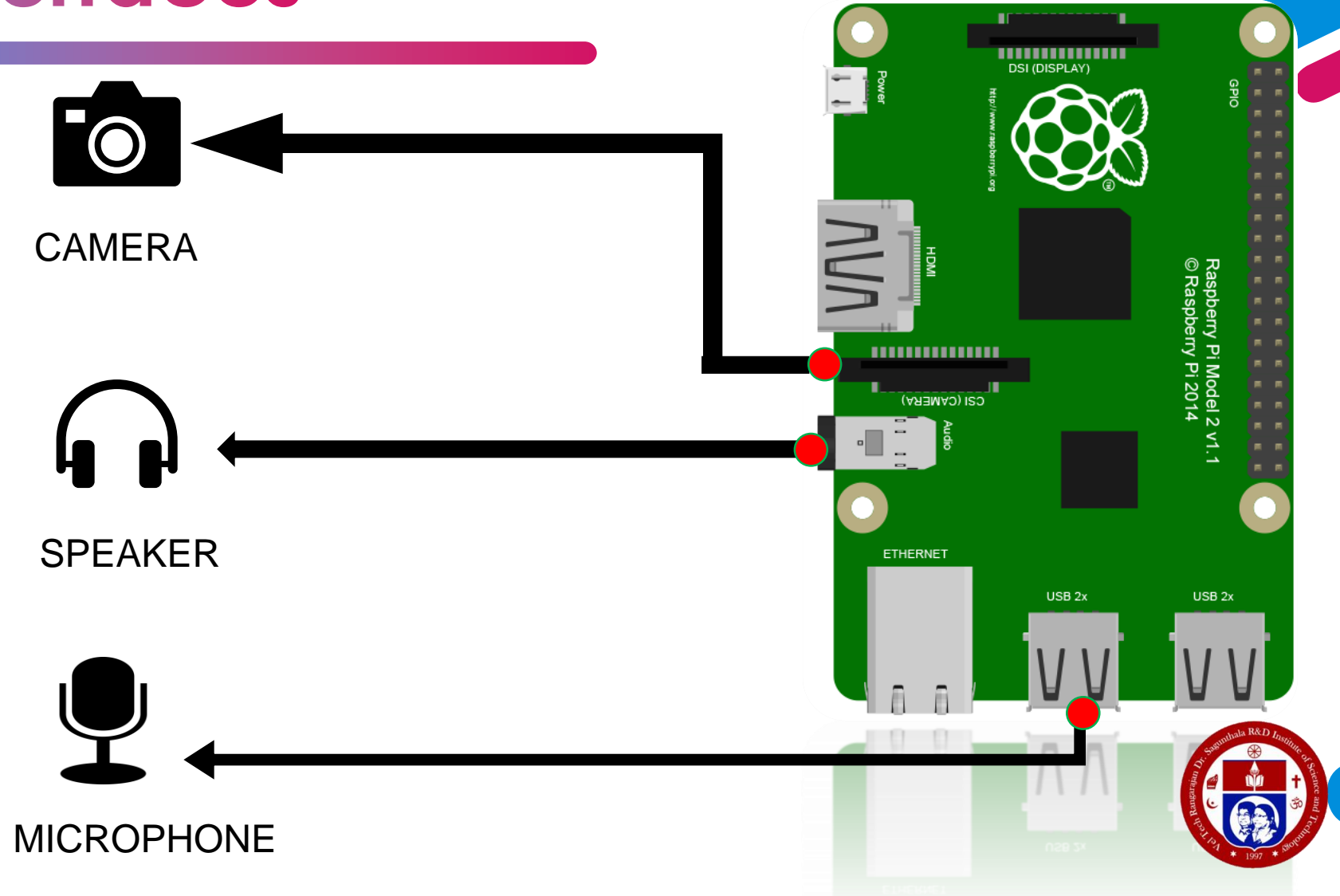
- a) Interfacing Peripherals.
- b) Capturing Image.
- c) Speech Recording.
- d) Audio Output.

2. AI PHASE

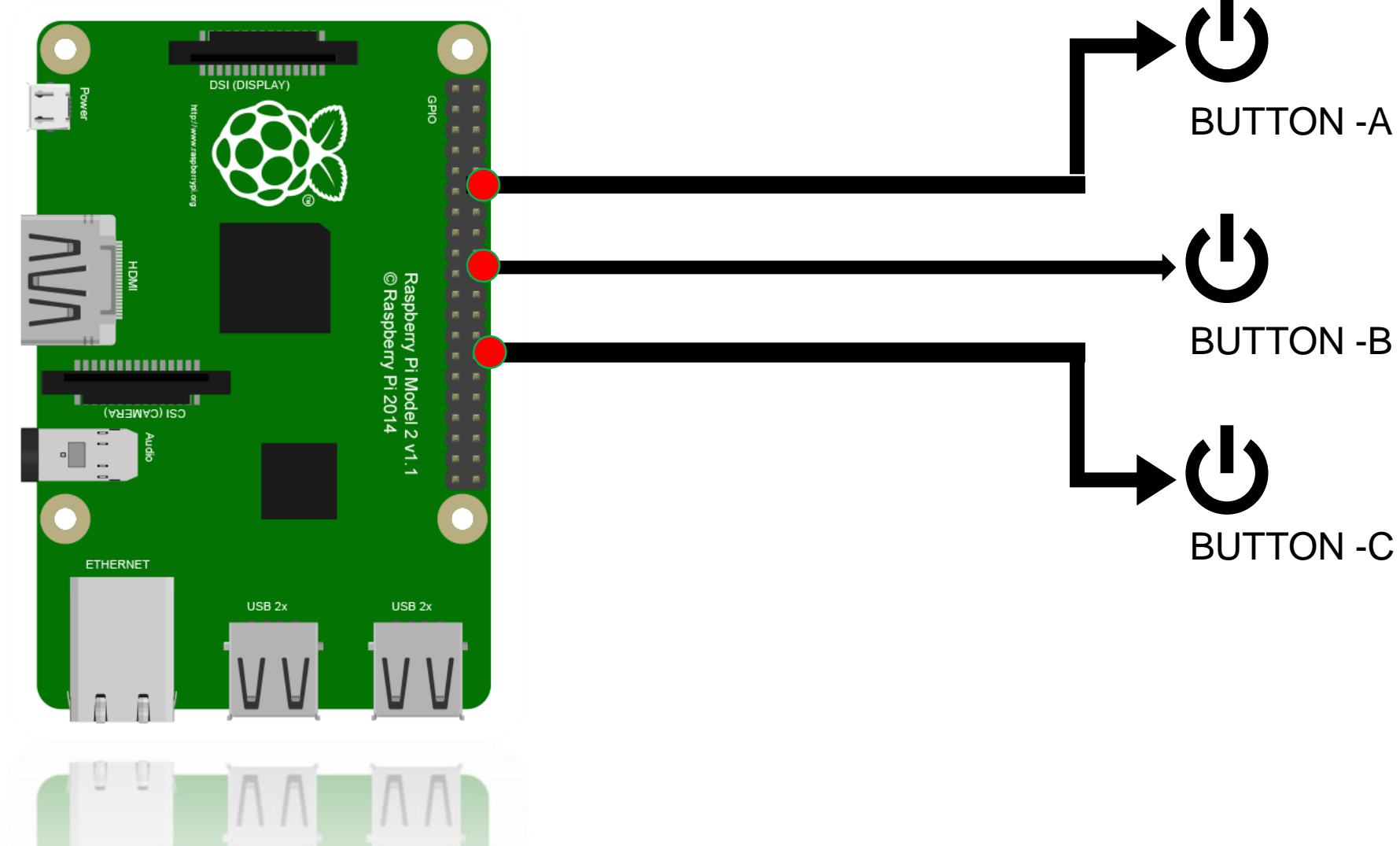
- a) Image Recognition.
- b) Command Assistance.



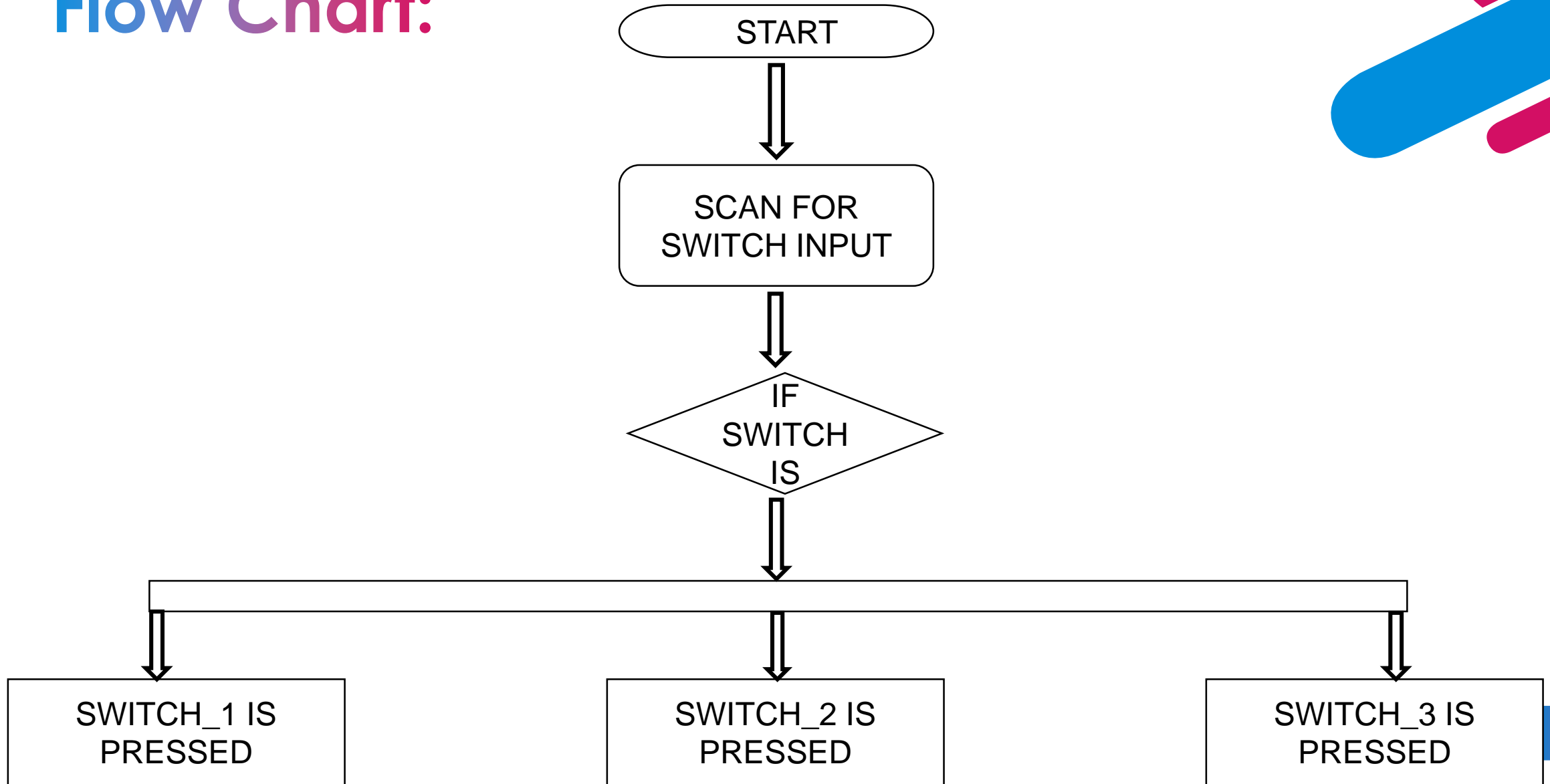
Out Put interfaces



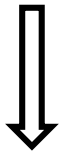
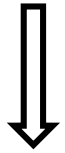
Input Interfaces



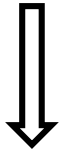
Flow Chart:



CAMERA == TRUE

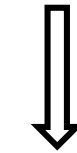
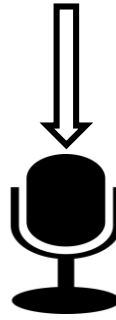


DELAY (500 ms)

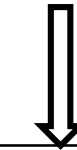


CAMERA == FALSE

MICROPHONE == TRUE

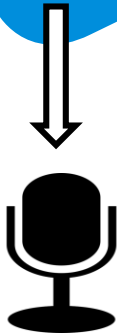


RECORDS 8
SECONDS



MICROPHONE == FALSE

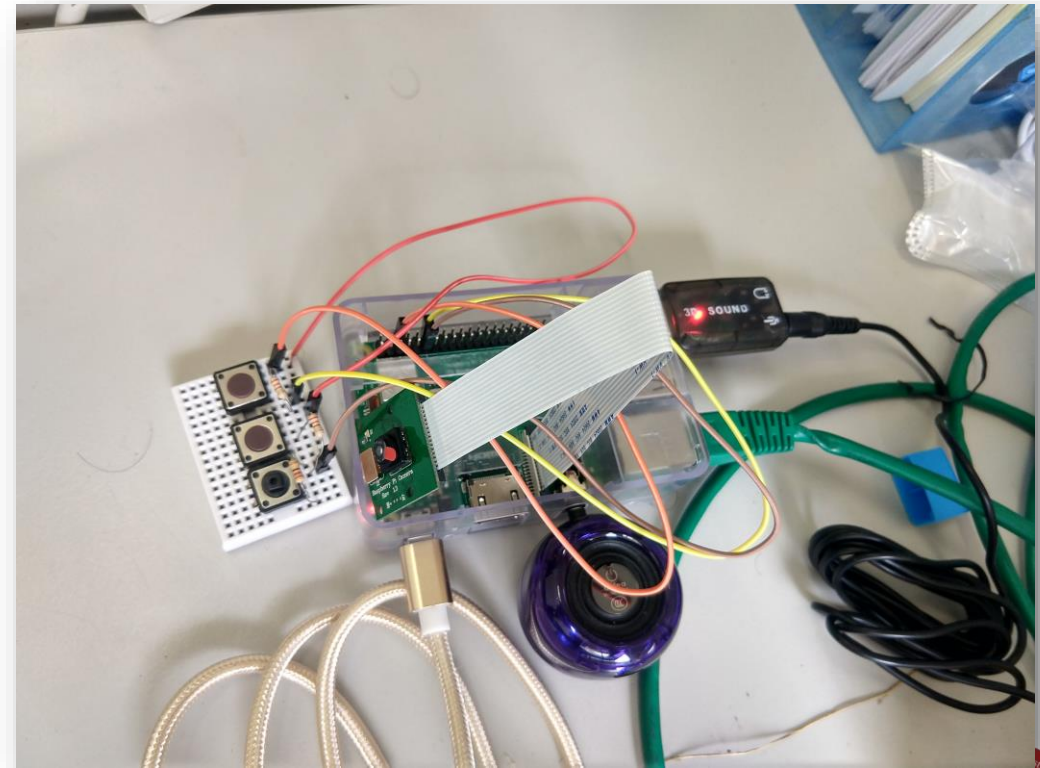
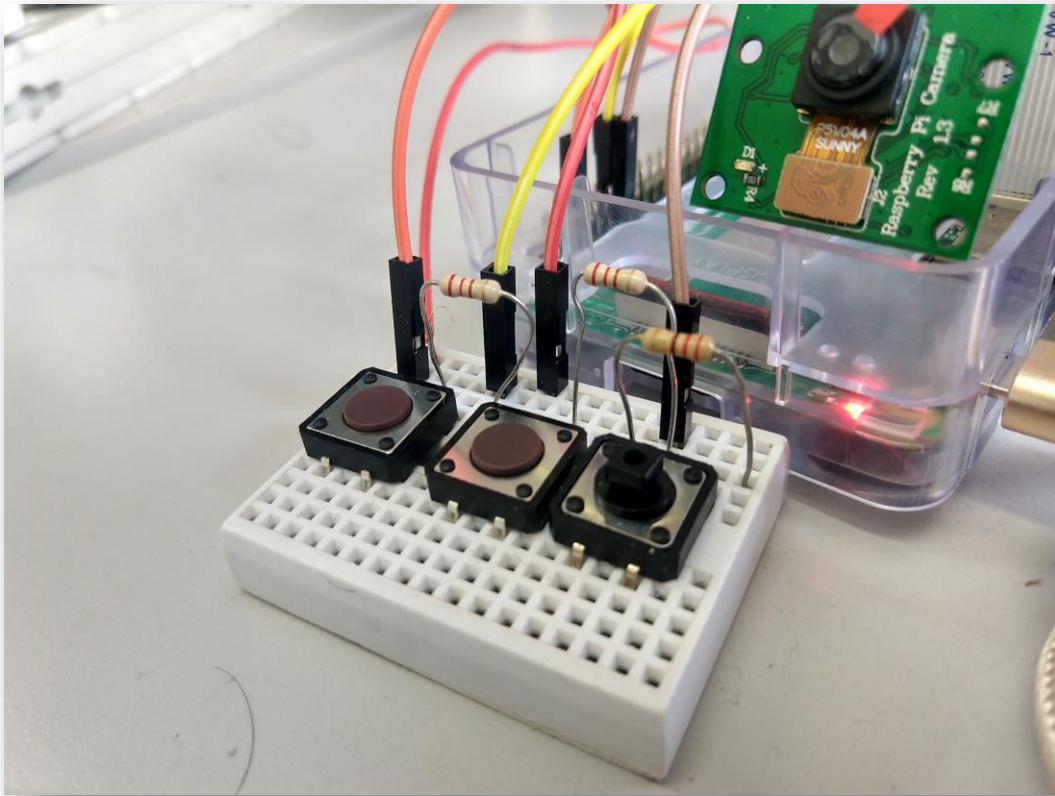
GOOGLE API == TRUE



SPEAKER == ENABLE



Hardware Setup



WORKING MODEL

The screenshot displays two overlapping Python IDE windows. The left window, titled "Rootcode.py - /home/pi/Rootcode.py (3.5.3)", contains Python code defining functions for a camera and a microphone. The right window, titled "*Python 3.5.3 Shell*", shows the output of the program, which consists of repeated prompts for switching between camera and microphone recording. Red circles highlight specific parts of both windows: one circle highlights the prompt "switch status:= your choice" in the shell output, and another circle highlights the corresponding logic in the code files. The system tray at the bottom indicates the date as 08-04-2019 and time as 11:26 AM.

The image shows two side-by-side windows from a Python IDE.

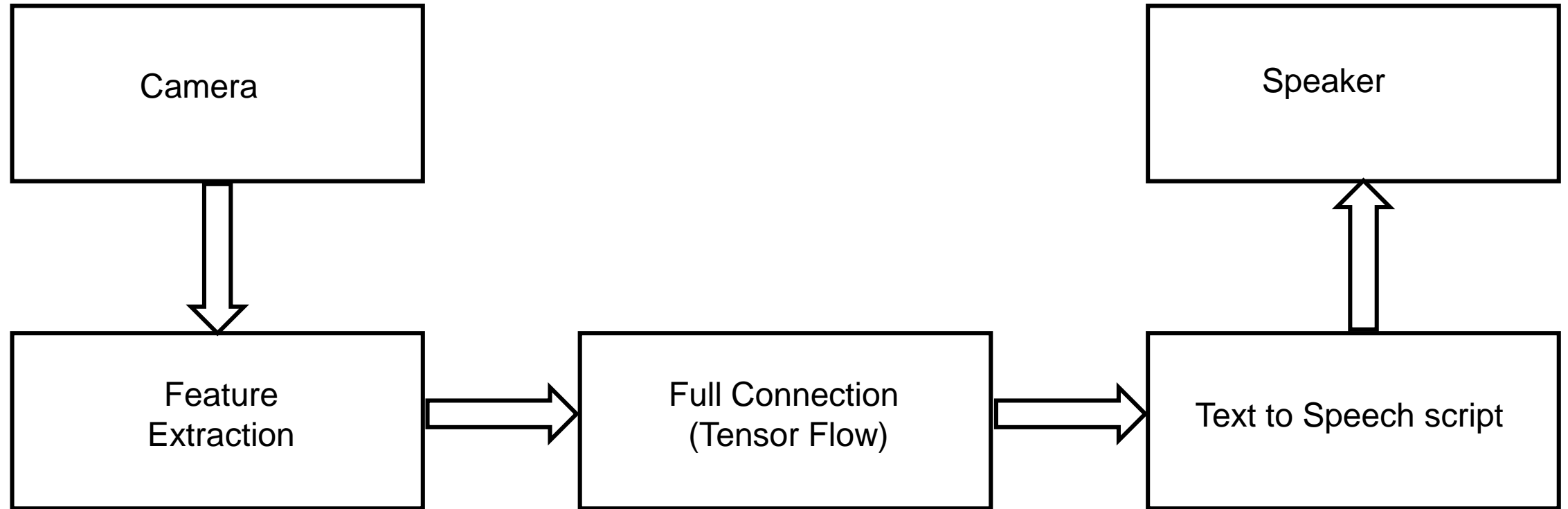
The left window, titled "Rootcode.py - /home/pi/Rootcode.py (3.5.3)", contains the following Python code:

```
def camera():  
    print("Camera is taking picture")  
    camera = picamera.PiCamera()  
    camera.resolution = (800, 600)  
    camera.start_preview()  
    camera.capture("/home/pi/newimage.jpg", resize=(1920, 1080))  
    camera.stop_preview()  
    print("Picture is captured")  
  
def microphone():  
    import pyaudio  
    import wave  
  
    form_1 = pyaudio.paInt16  
    chans = 1  
    samp_rate = 44100  
    chunk = 4096  
    record_secs = 8  
    dev_index = 2  
    wav_output_filename = 'test1.wav'  
  
    audio = pyaudio.PyAudio()  
  
    stream = audio.open(format = form_1, rate = samp_rate, channels = chans,  
                        input_device_index = dev_index, input = True, \  
                        frames_per_buffer=chunk)  
    print("recording")  
    frames = []  
  
    for ii in range(0,int((samp_rate/chunk)*record_secs)):  
        data = stream.read(chunk)  
        frames.append(data)  
  
    print("finished recording")  
  
    # stop the stream, close it, and terminate the pyaudio instantiation  
    stream.stop_stream()  
    stream.close()
```

The right window, titled "*Python 3.5.3 Shell*", shows the output of the program. It displays a series of prompts where the user can switch between camera and microphone recording. Two red circles are drawn around the text "switch status:= your choice" in the output, highlighting the interactive part of the program.



Image Recognition



Building The CNN

Building the CNN consists of three parts –

- Convolution

- Polling

- Flattening



Convolution:-




❖ Consider a 5 x 5 image whose pixel values are only 0 and 1.

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

❖ consider tensor flow filter 3 x 3 matrix as shown below:

1	0	1
0	1	0
1	0	1



1 <small>x1</small>	1 <small>x0</small>	1 <small>x1</small>	0	0
0 <small>x0</small>	1 <small>x1</small>	1 <small>x0</small>	1	0
0 <small>x1</small>	0 <small>x0</small>	1 <small>x1</small>	1	1
0	0	1	1	0
0	1	1	0	0

Image with Filter

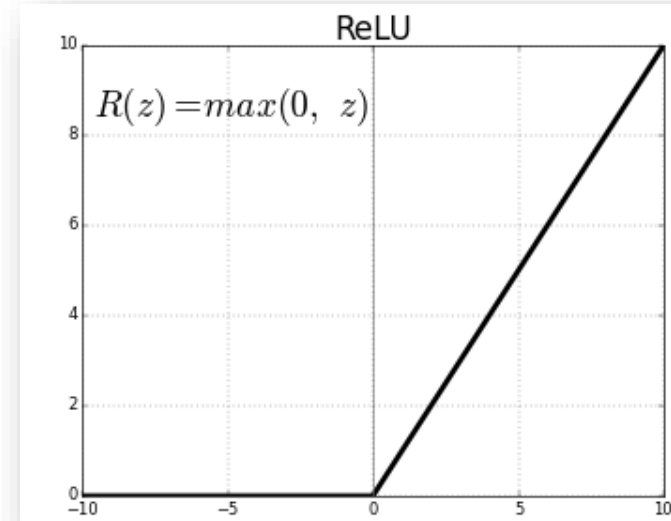
4		

Convolved
feature map

Activation Function:-

- ❖ Activation function of a node defines the output of that node, or "neuron," given an input or set of inputs
- ❖ ReLU (Rectified Linear Unit) activation Function has been used in the CNN.

- ❖ If input > 0:
 return input
else:
 return 0



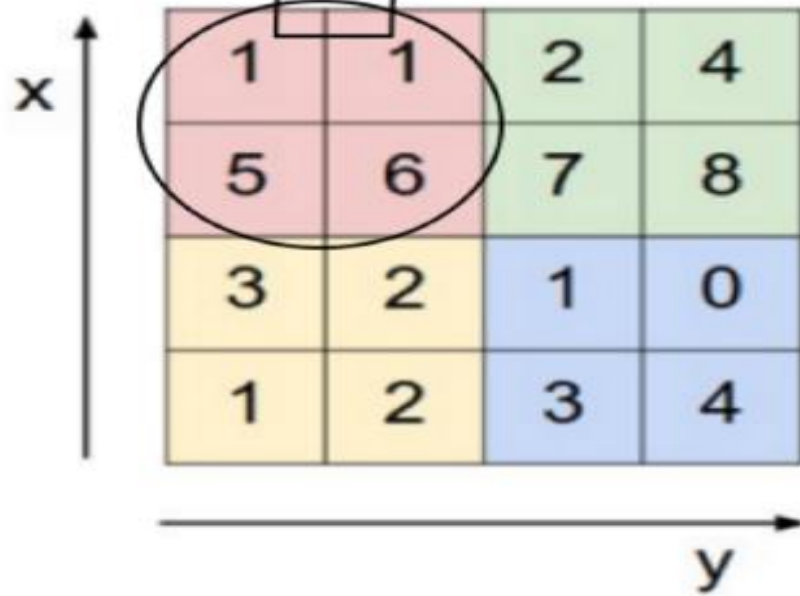
Pooling:-



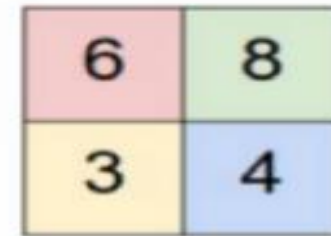
- ❖ Pooling reduces the dimensionality of each feature map but retains the most important information.
- ❖ But in this project we have been used Max Pooling Technique.
- ❖ Tensor flow graph having better results with max pooling technique.



$$\text{Max}(1, 1, 5, 6) = 6$$



max pool with 2x2 filters
and stride 2



Rectified Feature Map

Flattening:-

- ❖ Here the matrix is converted into a linear array
- ❖ so that to input it into the nodes of our neural network.

1	1	0
4	2	1
0	2	1

Pooled Feature Map

Flattening

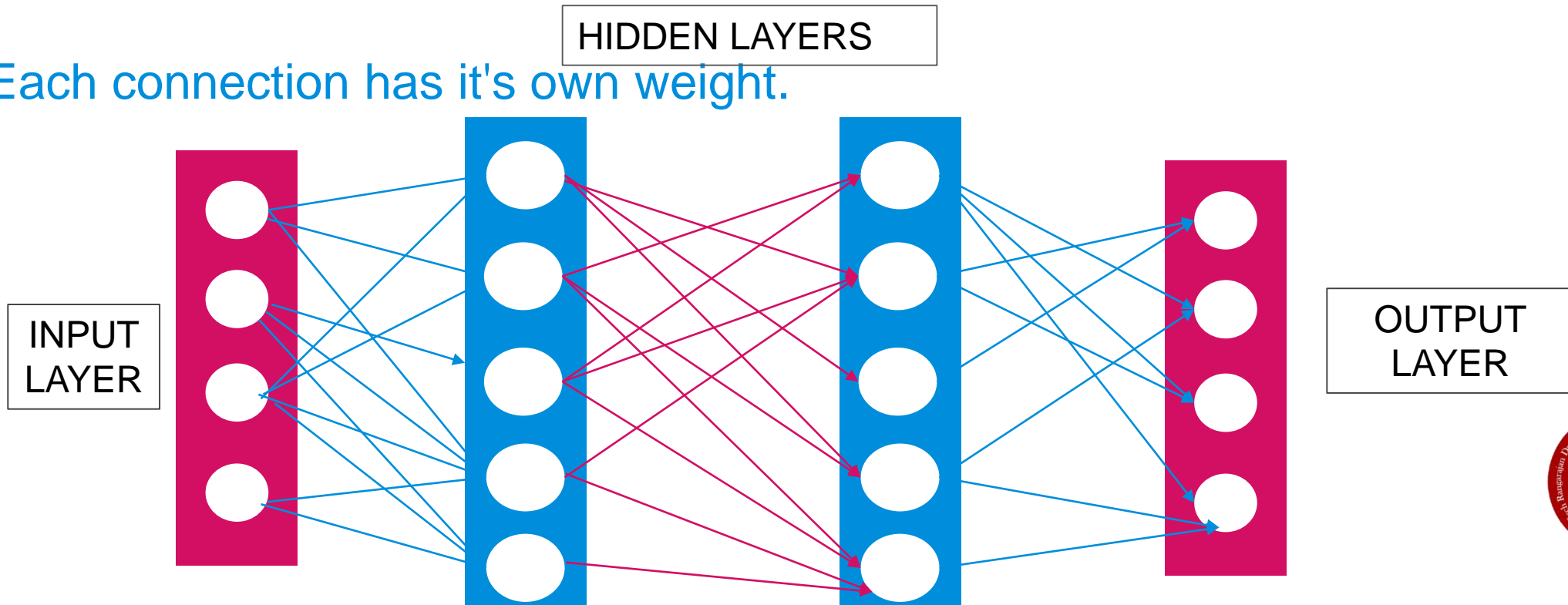
1
1
0
4
2
1
0
2
1



Fully Connected:-

- ❖ Fully connected layers are those where each nodes is connected to every previous and every next node.

- ❖ Each connection has it's own weight.



Softmax Function:-

- ❖ The weight calculation is carried out by softmax function.
- ❖ It normalizes it into a probability distribution consisting of K probabilities

$$S(y_i) = \frac{e^{y_i}}{\sum_j e^{y_j}}$$



CNN Algorithm:-

```
model = Sequential()

model.add(Conv2D(32, (3, 3), activation='relu', input_shape=(100, 100, 3)))

model.add(Conv2D(32, (3, 3), activation='relu'))

model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Conv2D(64, (3, 3), activation='relu'))

model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Conv2D(64, (3, 3), activation='relu'))

model.add(Conv2D(128, (3, 3), activation='relu'))

model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Dropout(0.25))
```



IMAGE RECOGNITION

```
print( Picture is captured )

def microphone():
    import pyaudio
    import wave

    form_1 = pyaudio.paInt16
    chans = 1
    samp_rate = 44100
    chunk = 4096
    record_secs = 8
    dev_index = 2
    wav_output_filename = 'test1.wav'

    audio = pyaudio.PyAudio()

    stream = audio.open(format = form_1, rate = samp_rate, channels = chans, \
        input_device_index = dev_index, input = True, \
        frames_per_buffer=chunk)
    print("recording")
    frames = []

    for ii in range(0, int((samp_rate/chunk)*record_secs)):
        data = stream.read(chunk)
        frames.append(data)

    print("finished recording")

    # stop the stream, close it, and terminate the pyaudio instantiation
    stream.stop_stream()
    stream.close()
    audio.terminate()

    # save the audio frames as .wav file
    wavefile = wave.open(wav_output_filename, 'wb')
    wavefile.setnchannels(chans)
    wavefile.setsampwidth(audio.get_sample_size(form_1))
    wavefile.setframerate(samp_rate)
```

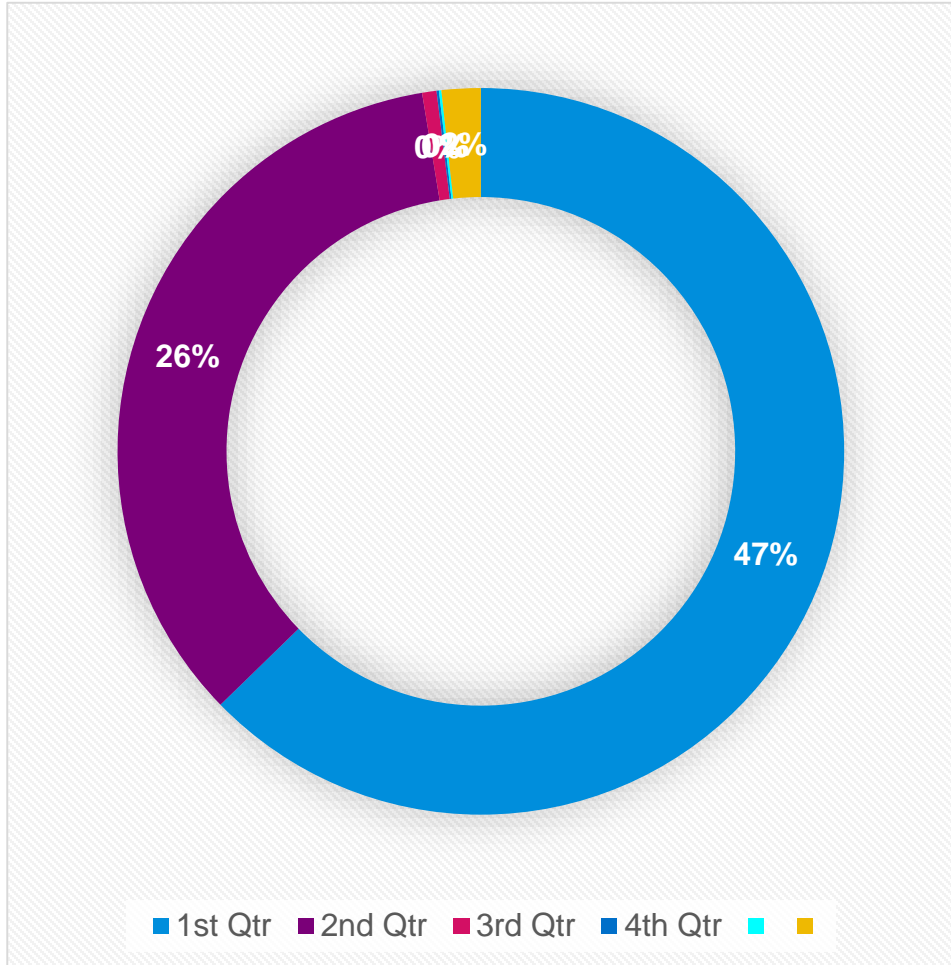
```
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Button Pressed
Camera is taking picture
Picture is captured
WARNING:tensorflow:From /home/pi/Rootcode.py:196: FastGFile.__init__ (from tensorflow.python.platform.gfile) is deprecated and will be removed in a future version.
Instructions for updating:
Use tf.gfile.GFile.
water jug
water jug (score = 0.47978)
water bottle (score = 0.26398)
pill bottle (score = 0.04873)
soap dispenser (score = 0.00872)
nipple (score = 0.00871)
```



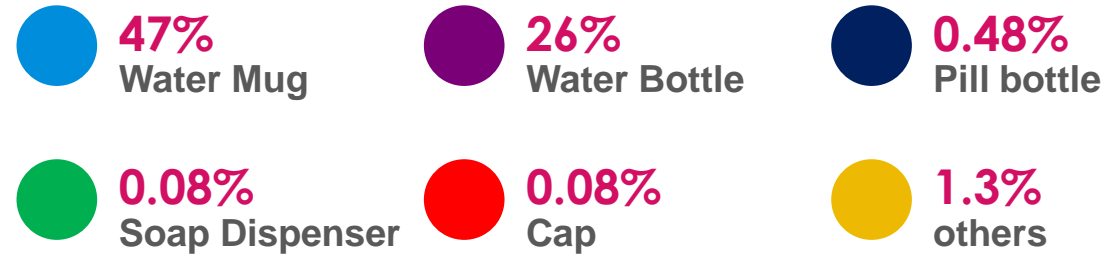
PREDICTIONS

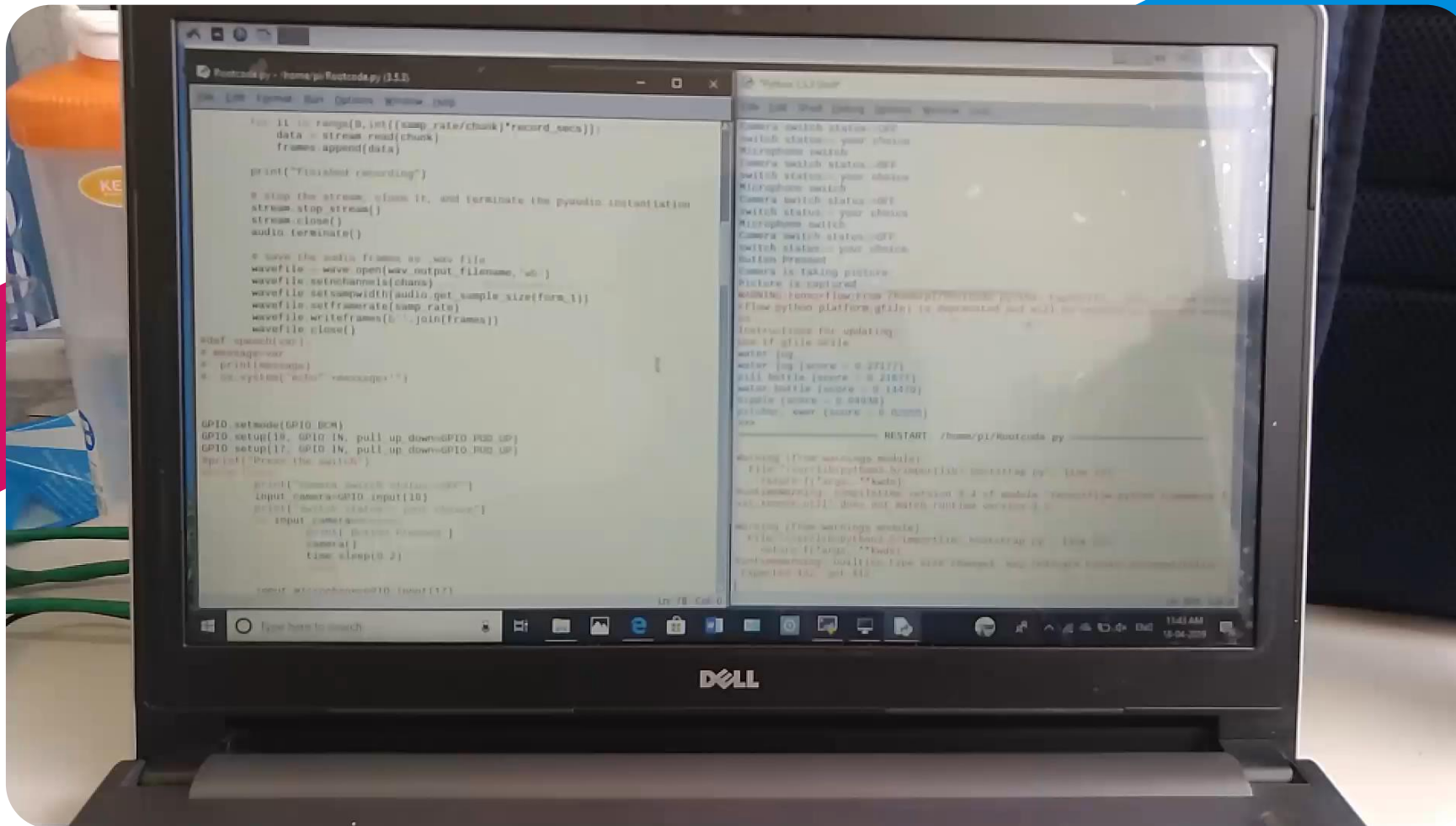
```
Camera switch status:=OFF
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Microphone switch
Camera switch status:=OFF
switch status:= your choice
Button Pressed
Camera is taking picture
Picture is captured
WARNING:tensorflow:From /home/pi/Rootcode.py:19:
rfLOW.python.platform.gfile) is deprecated and
on.
Instructions for updating:
Use tf.gfile.GFile.
water jug
water jug (score = 0.47978)
water bottle (score = 0.26398)
pill bottle (score = 0.04873)
soap dispenser (score = 0.00872)
nipple (score = 0.00871)
>>>
```





Prediction

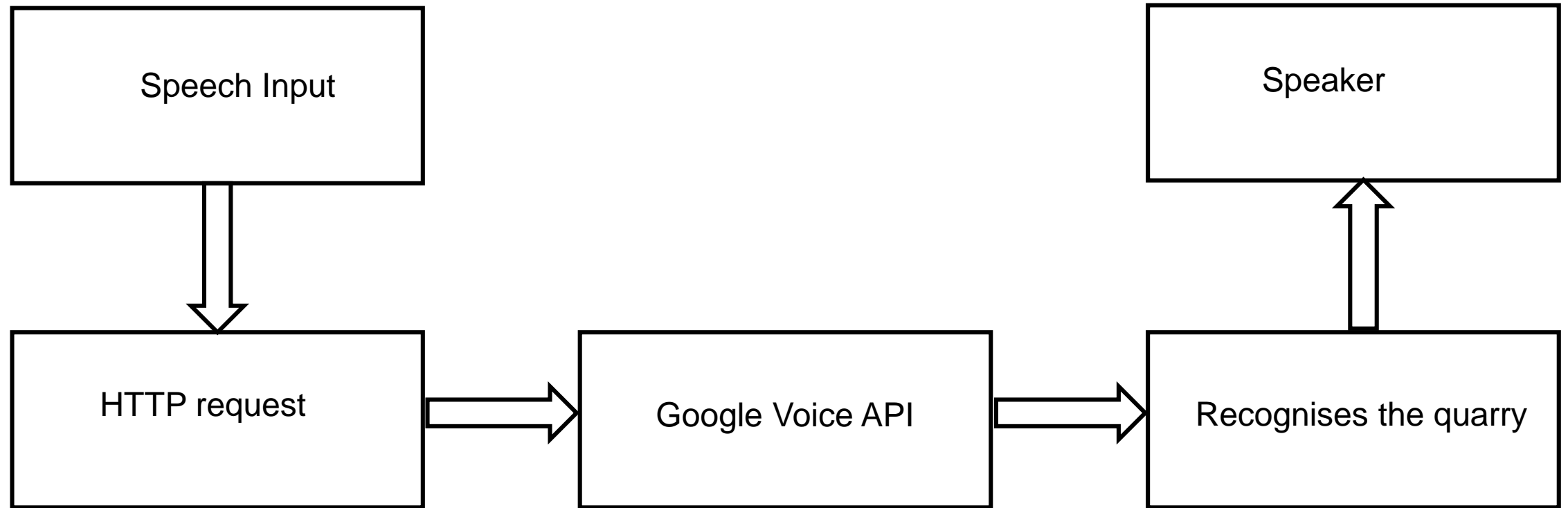




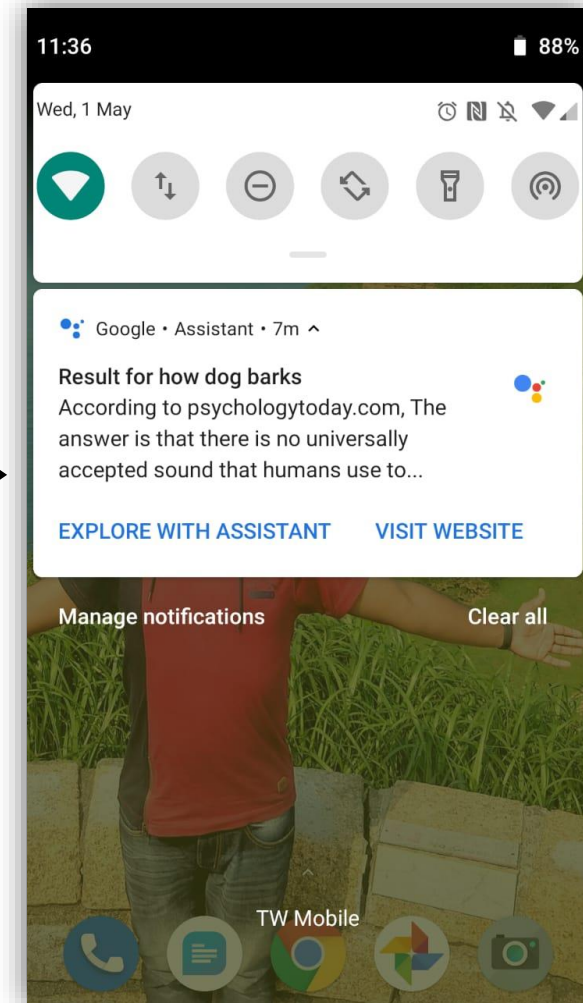
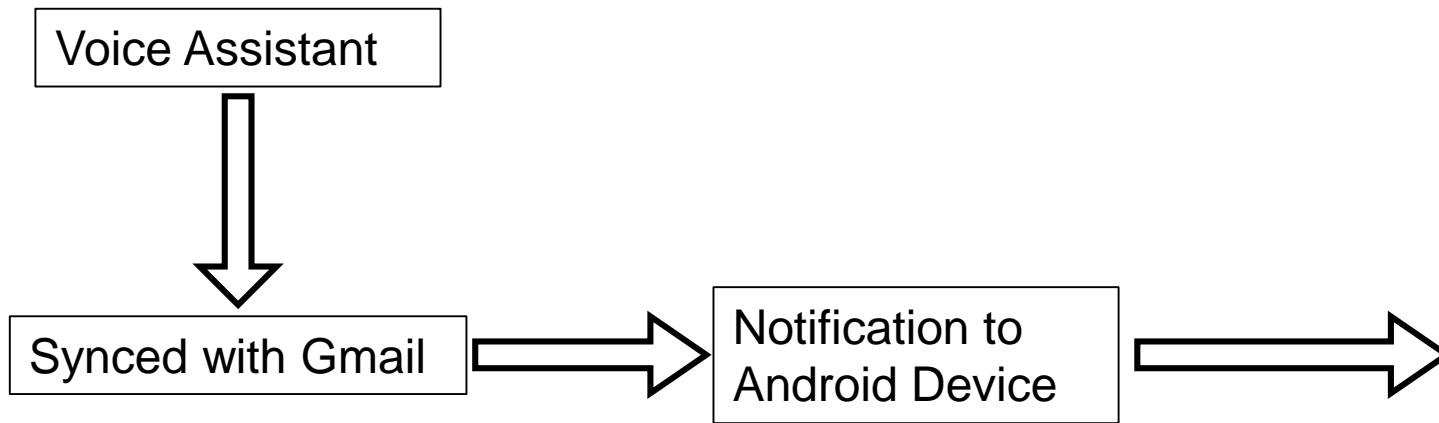
Demonstration

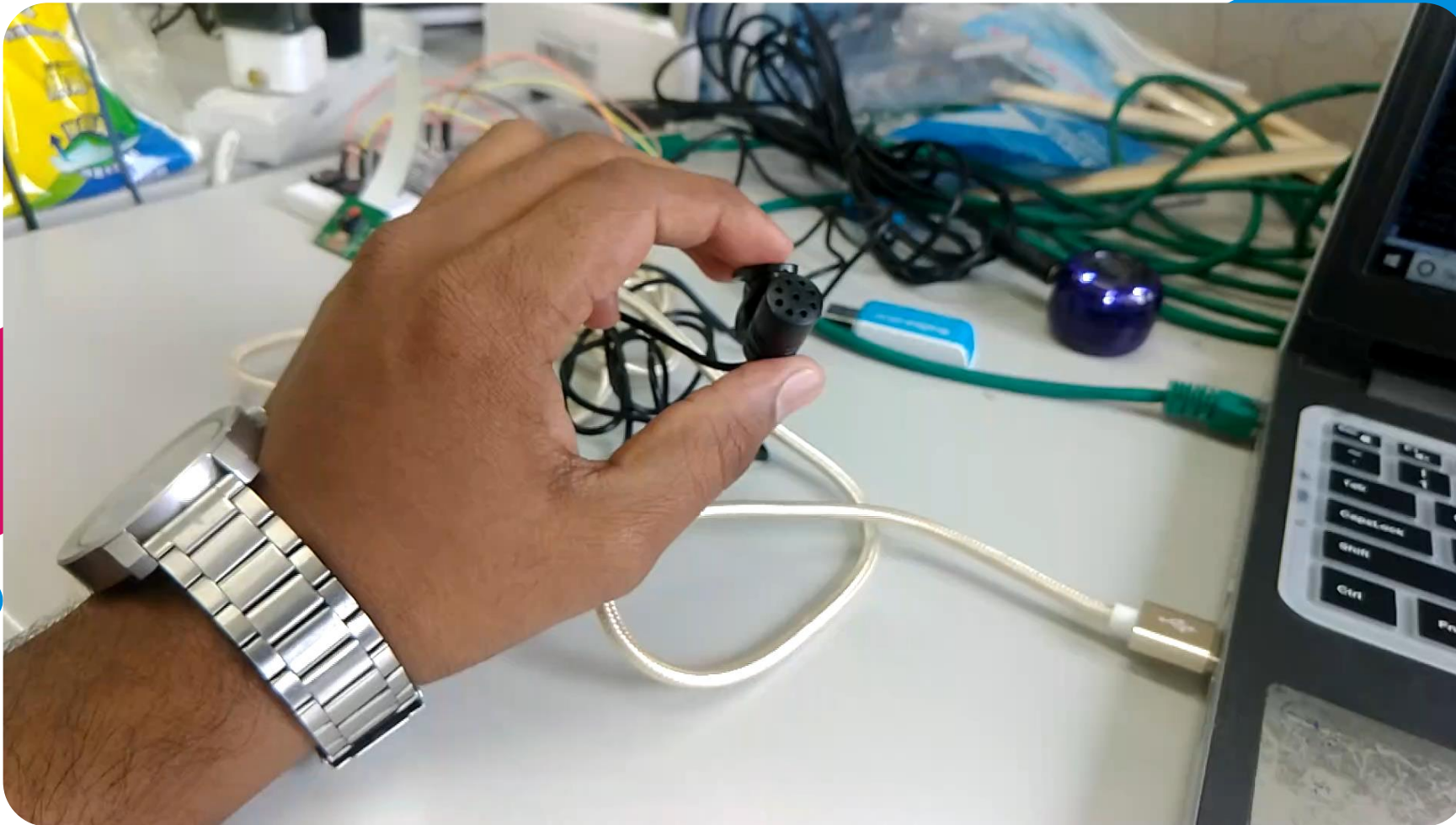


Voice Assistance



Notifications





ADD A FOOTER

Voice Assistant Demonstration



THANK YOU!

MUKESH BADIGINENI

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