

# Heap

## Pattern: Heap / Priority Queue (Min-Heap / Max-Heap)

### How to Recognize

- You're asked to find **top K elements**, **kth smallest/largest**, or **median**.
- There's a need to maintain a **running order** or **priority** among elements.
- The problem involves **frequent insertions and deletions** of extremes (min/max).
- Often paired with **sorting**, **frequency counting**, or **streaming data**.

### Step-by-Step Thinking Process (Template)

1. **Identify what you want to track:** e.g., k largest, k closest, top frequent.
2. **Choose the right heap type:**
  - Min-heap: keep smallest k elements → pop when size > k
  - Max-heap: keep largest k elements → use negative values in Python (min-heap trick)
3. **Use a heap of size K** to maintain only relevant candidates.
4. **Pop or push based on comparison logic.**
5. **Extract result** after processing all inputs (e.g., return root or sort remaining).

### Common Pitfalls & Edge Cases

- Forgetting that Python `heapq` is a **min-heap only** → use negative values for max-heap.
- Not limiting heap size → leads to  $O(n \log n)$  instead of  $O(k \log n)$ .
- Incorrectly handling ties (e.g., in “Top K Frequent Words”, tie-breaking by lexicographic order).
- Empty input → handle early return.

## 1. K Closest Points to Origin

### Problem Summary

Given an array of points in 2D space, return the k closest points to the origin (0, 0) based on Euclidean distance.

### Pattern

- **Heap / Priority Queue** (max-heap of size k)
- Alternative: **Sorting** (but less efficient for large datasets)

### Solution with Inline Comments

```
import heapq
from typing import List, Tuple

def kClosest(points: List[List[int]], k: int) -> List[List[int]]:
    # Use a max-heap to store the k closest points
    # We store (-distance, point) so that the farthest
    # (largest distance) is at top
    # Negative distance ensures we simulate max-heap behavior using min-heap
    heap = []

    for x, y in points:
        # Calculate squared distance (avoid sqrt for speed & precision)
        dist = x*x + y*y

        # If heap has fewer than k elements, add current point
        if len(heap) < k:
            heapq.heappush(heap, (-dist, [x, y]))
        # Else, if current point is closer than the farthest in heap, replace it
        elif dist < -heap[0][0]: # -heap[0][0] is the max distance in heap
            heapq.heappop(heap)
            heapq.heappush(heap, (-dist, [x, y]))

    # Extract points from heap (they are in no particular order)
    return [point for _, point in heap]
```

```
# ---- Official LeetCode Example ----
if __name__ == "__main__":
    # Example Input: points = [[1,3],[-2,2]], k = 1
    points = [[1, 3], [-2, 2]]
    k = 1

    # Call function
    result = kClosest(points, k)

    # Expected Output: [[-2,2]]
    # Because distance of (1,3): 1+9=10; (-2,2): 4+4=8 → (-2,2) is closer
    print("Output:", result) # Output: [[-2, 2]]
```

### Example Walkthrough

- Input: `points = [[1,3],[-2,2]]`, `k = 1`
- Process (1,3):  $\text{dist} = 1^2 + 3^2 = 10 \rightarrow \text{heap} = [(-10, [1,3])]$
- Process (-2,2):  $\text{dist} = 4 + 4 = 8 \rightarrow 8 < 10 \rightarrow \text{pop } (-10, \dots), \text{push } (-8, [-2,2])$
- Final heap:  $[(-8, [-2,2])] \rightarrow \text{return } [[-2, 2]]$

### Complexity

- **Time:**  $O(n \log k)$  — each insertion/removal takes  $O(\log k)$ , done  $n$  times
  - **Space:**  $O(k)$  — heap stores at most  $k$  elements
- 

## 2. Find Median from Data Stream

### Problem Summary

Design a data structure that supports adding integers and finding the median of all added numbers dynamically.

### Pattern

- **Two Heaps:** Max-heap for left half, Min-heap for right half
- Balance sizes: difference  $\leq 1$
- Median = top of larger heap or average of both

## Solution with Inline Comments

```
import heapq

class MedianFinder:
    def __init__(self):
        # Max-heap for smaller half (store negative values)
        self.small = [] # represents left half (max-heap via negatives)
        # Min-heap for larger half
        self.large = [] # represents right half (min-heap)

    def addNum(self, num: int) -> None:
        # Push to small (max-heap) first
        heapq.heappush(self.small, -num)

        # Ensure every number in small <= every number in large
        # If top of small > top of large, swap
        if self.small and self.large and (-self.small[0]) > self.large[0]:
            val = -heapq.heappop(self.small)
            heapq.heappush(self.large, val)

        # Balance the heaps: difference should be at most 1
        if len(self.small) > len(self.large) + 1:
            val = -heapq.heappop(self.small)
            heapq.heappush(self.large, val)
        elif len(self.large) > len(self.small) + 1:
            val = heapq.heappop(self.large)
            heapq.heappush(self.small, -val)

    def findMedian(self) -> float:
        # If heaps are same size, median is average
        if len(self.small) == len(self.large):
            return (-self.small[0] + self.large[0]) / 2.0
        # Else, median is top of larger heap
        elif len(self.small) > len(self.large):
            return -self.small[0]
        else:
            return self.large[0]

# ---- Official LeetCode Example ----
if __name__ == "__main__":
```

```
# Example Usage:
mf = MedianFinder()
mf.addNum(1)
mf.addNum(2)
print("Median after [1,2]:", mf.findMedian()) # Output: 1.5

mf.addNum(3)
print("Median after [1,2,3]:", mf.findMedian()) # Output: 2.0
```

## Example Walkthrough

We'll go through this sequence:

```
mf = MedianFinder()
mf.addNum(1)
mf.addNum(2)
print(mf.findMedian()) # 1.5
mf.addNum(3)
print(mf.findMedian()) # 2.0
```

### Step 1: addNum(1)

- Push -1 into `small` → `small = [-1]`, `large = []`
- No need to compare since `large` is empty.
- Size check:
  - `len(small) = 1`, `len(large) = 0` → difference is 1 → acceptable.

Final state: - `small = [-1]` (i.e., contains 1) - `large = []`

---

### Step 2: addNum(2)

- Push -2 into `small` → `small = [-2, -1]` (min-heap of negatives → top is -2 → actual value is 2)
- Now check: is `top(small) > top(large)`?
  - But `large` is still empty → skip comparison.
- Balance sizes:

- `len(small) = 2, len(large) = 0` → difference is 2 ( $>1$ ), so move one element.
- Pop from small: `val = -heapq.heappop(self.small)` → pop -2, so `val = 2`
- Push 2 into large: `large = [2]`
- Now `small = [-1], large = [2]`

Final state: - `small = [-1] → {1}` - `large = [2] → {2}`

Now both heaps differ in size by only 1 → good.

---

### Step 3: `findMedian()` → after adding [1,2]

- `len(small) == 1, len(large) == 1` → equal sizes
- `Median = (-self.small[0] + self.large[0]) / 2.0`
  - `-self.small[0] = -(-1) = 1`
  - `self.large[0] = 2`
  - `Median = (1 + 2) / 2 = 1.5`

Output: 1.5 → Correct

---

### Step 4: `addNum(3)`

- Push -3 into small → `small = [-3, -1]` → top is -3 → value is 3
- Check: is `top(small) > top(large)`?
  - `-self.small[0] = 3, self.large[0] = 2`
  - Is `3 > 2`? Yes → need to fix!
- So:
  - Pop from small: `val = -heapq.heappop(self.small)` → pop -3 `val = 3`
  - Push 3 into large: now `large = [2, 3]` → min-heap: `[2, 3]`
  - Now `small = [-1], large = [2, 3]`
- Recheck size balance:
  - `len(small) = 1, len(large) = 2` → difference is 1 → acceptable

Final state: - `small = [-1] → {1}` - `large = [2, 3] → {2, 3}`

### Step 5: findMedian() → after [1,2,3]

- `len(small) = 1, len(large) = 2` → not equal
- Since `large` has more elements → median is `large[0] = 2`

Output: 2.0 → Correct

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### Summary of States

Operation	small (max-heap)	large (min-heap)	Median
<code>addNum(1)</code>	<code>[-1]</code>	<code>[]</code>	—
<code>addNum(2)</code>	<code>[-1]</code>	<code>[2]</code>	—
<code>findMedian()</code>	<code>[-1]</code>	<code>[2]</code>	1.5
<code>addNum(3)</code>	<code>[-1]</code>	<code>[2, 3]</code>	—
<code>findMedian()</code>	<code>[-1]</code>	<code>[2, 3]</code>	2.0

---

### Complexity

- **addNum:**  $O(\log n)$  — heap operations
- **findMedian:**  $O(1)$
- **Space:**  $O(n)$

---

## 3. Merge k Sorted Lists

### Problem Statement

You are given an array of `k` linked lists, each of which is sorted in ascending order.

Merge all the lists into one sorted linked list and return it.

**Constraints:** - `k == lists.length - 0 <= k <= 104 - 0 <= lists[i].length <= 500 - -104 <= lists[i][j] <= 104` - All lists are sorted in non-decreasing order.

### Example:

```
Input: lists = [[1,4,5],[1,3,4],[2,6]]  
Output: [1,1,2,3,4,4,5,6]
```

---

### Solution: Min-Heap Approach (Optimal)

```
import heapq  
from typing import List, Optional  
  
# Definition for singly-linked list.  
class ListNode:  
    def __init__(self, val=0, next=None):  
        self.val = val  
        self.next = next  
  
class Solution:  
    def mergeKLists(self, lists: List[Optional[ListNode]]):  
        # Step 1: Create a min-heap to store (value, index, node)  
        heap = []  
  
        # Step 2: Push the head of each non-empty list into the heap  
        for i, lst in enumerate(lists):  
            if lst: # Skip empty lists  
                heapq.heappush(heap, (lst.val, i, lst))  
  
        # Step 3: Dummy node to simplify result construction  
        dummy = ListNode(0)  
        current = dummy  
  
        # Step 4: While heap is not empty, extract smallest and add to result  
        while heap:  
            # Pop the smallest element: (val, index, node)  
            val, idx, node = heapq.heappop(heap)  
  
            # Add this node to the result list  
            current.next = node
```



```

        current = current.next

        # If the node has a next, push it back into the heap
        if node.next:
            heapq.heappush(heap, (node.next.val, idx, node.next))

    # Step 5: Return the merged list (skip dummy head)
    return dummy.next

```

---

## Code Walkthrough with Example

**Input:**

```

lists = [
    [1 → 4 → 5], # list 0
    [1 → 3 → 4], # list 1
    [2 → 6]      # list 2
]

```

We'll simulate every step.

### Initial Setup

- `heap = []`
- `dummy = ListNode(0)`
- `current = dummy`

---

### Step 1: Push Heads into Heap

Loop over lists:

i	lst	lst.val	Pushed?	Tuple
0	nodeA (1)	1	Yes	(1, 0, nodeA)

i	lst	lst.val	Pushed?	Tuple
1	nodeD (1)	1	Yes	(1, 1, nodeD)
2	nodeG (2)	2	Yes	(2, 2, nodeG)

Now:

```
heap = [(1, 0, nodeA), (1, 1, nodeD), (2, 2, nodeG)]
```

Heap maintains min-heap property: smallest value first. Ties broken by index.

---

#### Iteration 1: Pop (1, 0, nodeA)

- val = 1, idx = 0, node = nodeA
- current.next = nodeA → result: [1]
- current = nodeA
- nodeA.next = nodeB → push (4, 0, nodeB)

Heap now:

```
[(1, 1, nodeD), (2, 2, nodeG), (4, 0, nodeB)]
```

---

#### Iteration 2: Pop (1, 1, nodeD)

- Add nodeD → result: [1, 1]
- Push nodeE (value 3) → (3, 1, nodeE)

Heap:

```
[(2, 2, nodeG), (3, 1, nodeE), (4, 0, nodeB)]
```

### Iteration 3: Pop (2, 2, nodeG)

- Add nodeG  $\rightarrow$  result: [1, 1, 2]
- Push nodeH (value 6)  $\rightarrow$  (6, 2, nodeH)

Heap:

```
[(3, 1, nodeE), (4, 0, nodeB), (6, 2, nodeH)]
```

---

### Iteration 4: Pop (3, 1, nodeE)

- Add nodeE  $\rightarrow$  result: [1, 1, 2, 3]
- Push nodeF (value 4)  $\rightarrow$  (4, 1, nodeF)

Heap:

```
[(4, 0, nodeB), (4, 1, nodeF), (6, 2, nodeH)]
```

Two 4s  $\rightarrow$  pick (4, 0, nodeB) because  $0 < 1$

---

### Iteration 5: Pop (4, 0, nodeB)

- Add nodeB  $\rightarrow$  result: [1, 1, 2, 3, 4]
- Push nodeC (value 5)  $\rightarrow$  (5, 0, nodeC)

Heap:

```
[(4, 1, nodeF), (5, 0, nodeC), (6, 2, nodeH)]
```

---

**Iteration 6: Pop (4, 1, nodeF)**

- Add nodeF → result: [1, 1, 2, 3, 4, 4]
- No next → don't push

Heap:

```
[(5, 0, nodeC), (6, 2, nodeH)]
```

---

**Iteration 7: Pop (5, 0, nodeC)**

- Add nodeC → result: [1, 1, 2, 3, 4, 4, 5]
- No next → stop

Heap:

```
[(6, 2, nodeH)]
```

---

**Iteration 8: Pop (6, 2, nodeH)**

- Add nodeH → result: [1, 1, 2, 3, 4, 4, 5, 6]
  - Done!
- 

**Final Result**

Return `dummy.next` → the full merged list:

1 → 1 → 2 → 3 → 4 → 4 → 5 → 6

Output: [1,1,2,3,4,4,5,6]

---

## Time & Space Complexity

Metric	Complexity	Explanation
<b>Time</b>	$O(n \log k)$	- $n$ = total number of nodes- Each node is pushed and popped once $\rightarrow$ $n$ operations- Each heap op takes $O(\log k)$ - Total: $O(n \log k)$
<b>Space</b>	$O(k)$	- Heap stores at most $k$ elements (one per list)- dummy and pointers: $O(1)$ - Output list not counted

Efficient even for large  $k$  (e.g., 1000 lists)

## Key Takeaways (Revision Notes)

Concept	Why It Matters
<b>Min-Heap</b>	Always gives smallest current head in $O(\log k)$
<b>Tuple (val, idx, node)</b>	Prevents errors when values are equal; tiebreaker via <code>idx</code>
<b>Dummy Node</b>	Avoids edge cases when building result list
<b>One Pass Per Node</b>	Each node inserted and removed exactly once
<b>Heap Size <math>k</math></b>	Memory efficient — only keeps front nodes

## Pro Tips for Interviews

1. **Always use (val, idx, node)** — never compare `ListNode` directly!
2. **Handle empty lists** (if `lst`) — avoid `None` errors.
3. **Use `heapq`** — Python's built-in min-heap is perfect.
4. **Draw the heap evolution** on paper during interviews.
5. **Explain the logic clearly**: “We always pick the smallest available head.”

## 4. Task Scheduler

### Problem Statement

You are given a characters array `tasks` representing tasks labeled from 'A' to 'Z'. Each task takes **one unit of time** to complete. You are also given an integer `n`, which represents the **cooldown period** between two identical tasks.

You can only perform one task at a time. After performing a task, you must wait **exactly n units** before performing the same task again.

Return the **minimum number of time units** needed to complete all tasks.

**Constraints:** -  $1 \leq \text{tasks.length} \leq 10$  - `tasks[i]` is an uppercase English letter. -  $0 \leq n \leq 100$

---

### Sample Input & Output

```
Input: tasks = ["A","A","A","B","B","B"], n = 2
```

```
Output: 8
```

```
Explanation:
```

```
One valid schedule is:
```

```
Time:  0  1  2  3  4  5  6  7  
       [A, B, _, A, B, _, A, B]
```

All As are separated by 2 units → valid

All Bs are separated by 2 units → valid

Total time = 8 units

---

### Solution Code

```

from collections import Counter
from typing import List

class Solution:
    def leastInterval(self, tasks: List[str], n: int) -> int:
        """
        Find the minimum time to schedule all tasks with cooldown n.

        :param tasks: List of task labels (e.g., ['A','A','B','B'])
        :param n: Cooldown period between identical tasks
        :return: Minimum time units required

        Intuition:
        - The most frequent task(s) determine the minimum time.
        - We need to place max_freq tasks with
        - at least n other tasks/idle in between.
        - If there are enough other tasks to fill gaps → no idle time needed.
        """

        # Step 1: Count frequency of each task
        task_count = Counter(tasks)

        # Step 2: Find the maximum frequency
        max_freq = max(task_count.values())

        # Step 3: Count how many tasks have the maximum frequency
        count_max_freq = sum(
            1 for freq in task_count.values() if freq == max_freq
        )

        # Step 4: Calculate minimum time using formula
        # (max_freq - 1) full cycles of length (n + 1) each
        # Plus the final instances of the most frequent tasks
        min_time = (max_freq - 1) * (n + 1) + count_max_freq

        # Step 5: Return the maximum between min_time and total tasks
        # Why? If there are enough other tasks to fill all slots,
        # we don't need idle time → answer is just len(tasks)
        return max(min_time, len(tasks))

```

## Step-by-Step Walkthrough (Example)

Input:

```
tasks = ["A", "A", "A", "B", "B", "B"]  
n = 2
```

### Step 1: Count Frequencies

```
task_count = {'A': 3, 'B': 3}
```

### Step 2: Max Frequency

```
max_freq = 3
```

### Step 3: Count Tasks with Max Frequency

```
count_max_freq = 2 # Both A and B appear 3 times
```

### Step 4: Apply Formula

```
min_time = (3 - 1) * (2 + 1) + 2  
           = 2 * 3 + 2  
           = 6 + 2  
           = 8
```

### Step 5: Compare with Total Tasks

```
len(tasks) = 6  
return max(8, 6) = 8
```

Answer: 8

---



## Valid Schedule Visualization

Time	Task
0	A
1	B
2	—
3	A
4	B
5	—
6	A
7	B

Final output: 8 time units

Check cooldowns: - A at 0 → next at 3 → gap = 3 → valid - B at 1 → next at 4 → gap = 3 → valid - A at 3 → next at 6 → gap = 3 → valid - B at 4 → next at 7 → gap = 3 → valid

All constraints satisfied!

---

## Time Complexity

- $O(m)$  where  $m = \text{len(tasks)}$ 
  - One pass to build **Counter**:  $O(m)$
  - Finding **max()** and counting frequencies:  $O(26)$   $O(1)$
- So overall:  $O(m)$

---

## Space Complexity

- $O(1)$  because:
  - The **Counter** stores at most 26 keys (letters A–Z)
  - No additional data structures grow with input size
- Thus, space used is constant regardless of input size

## Key Takeaways

- The bottleneck is the **most frequent task**.
  - Use the formula:  $(\text{max\_freq} - 1) * (n + 1) + \text{count\_max\_freq}$
  - Only add idle time if needed — otherwise, use `len(tasks)`
- 

## 5. Top K Frequent Words

### Problem :

We want to find the `k` most frequent words in a list, with ties broken by **lexicographical (dictionary) order**.

```
words = ["the","day","is","sunny","the","the","the","sunny","is","is"]
k = 4
print(topKFrequent(words, k))
# Output: ["the", "is", "sunny", "day"]
```

### Solution (Python):

```
import heapq
from collections import Counter

def topKFrequent(words, k):
    # Step 1: Count frequency of each word
    count = Counter(words)

    # Step 2: Create a min-heap (or use negative frequency for max behavior)
    heap = [(-freq, word) for word, freq in count.items()]
    heapq.heapify(heap)

    # Step 3: Pop the top k elements
    return [heapq.heappop(heap)[1] for _ in range(k)]

# ---- Official LeetCode Example ----
if __name__ == "__main__":
```

```
# Example Input: words = ["i","love","leetcode","i","love","coding"],k = 2
words = ["i", "love", "leetcode", "i", "love", "coding"]
k = 2

# Call function
result = topKFrequent(words, k)

# Expected Output: ["i","love"]
# i:2, love:2, coding:1 → top 2 → i and
# love (tie broken by lex order: i < love)
print("Output:", result) # Output: ['i', 'love']
```

## Step-by-Step Breakdown

### Step 1: Count Frequencies

```
count = Counter(words)
```

- Counter is a subclass of dict that counts occurrences.
- Example:

```
words = ["i","love","leetcode","i","love","coding"]
count = Counter(words)
# count = {'i': 2, 'love': 2, 'leetcode': 1, 'coding': 1}
```

---

### Step 2: Build a List for the Heap

```
heap = [(-freq, word) for word, freq in count.items()]
```

- We create a list of tuples: (-frequency, word)
- We use **negative frequency** because:
  - Python's **heapq** is a **min-heap** by default.
  - To simulate a **max-heap** for frequency, we negate the frequency.
  - So higher actual frequency becomes more negative → smaller in min-heap → comes out first.

### Example:

From our `count`, this gives:

```
[(-2, 'i'), (-2, 'love'), (-1, 'leetcode'), (-1, 'coding')]
```

Now, when we heapify, the **smallest tuple** (by first element, then second) will be at the top.

But here's the **key insight**:

When two frequencies are the same (e.g., -2), Python compares the **second element**, which is the word.

So: - (-2, 'i') vs (-2, 'love') → 'i' < 'love' lexicographically → (-2, 'i') is smaller.

- But we want **higher frequency first**, and **lexicographically smaller word first** in the result.

Wait — doesn't that mean 'i' should come before 'love'? Yes.

But in the heap, since (-2, 'i') is smaller than (-2, 'love'), it will be **popped first** — which is exactly what we want.

So the tuple (-freq, word) naturally gives us: - Higher frequency first (because of -freq)  
- Lexicographically smaller word first in case of tie

This is why the tuple ordering works perfectly.

---

### Step 3: Heapify the List

```
heapq.heapify(heap)
```

- Converts the list into a **min-heap** in-place.
- The smallest element (i.e., highest frequency, then lexicographically smallest) is at the top.

After heapify, the internal structure maintains heap property: - `heap[0]` is always the smallest (i.e., the “best” candidate).

But note: The entire list is **not sorted** — just heap-ordered.

---

#### Step 4: Extract Top k Elements

```
return [heapq.heappop(heap)[1] for _ in range(k)]
```

- We pop  $k$  times.
- Each `heappop()` removes and returns the smallest (i.e., most frequent, or lexicographically smaller) element.
- We take `[1]`  $\rightarrow$  the **word** part of the tuple `(-freq, word)`.

Each pop takes  $O(\log n)$  time, so  $k$  pops  $\rightarrow O(k \log n)$ .

---

#### Example Walkthrough

Let's run through:

```
words = ["i","love","leetcode","i","love","coding"]  
k = 2
```

#### Step 1: Count

```
count = {'i': 2, 'love': 2, 'leetcode': 1, 'coding': 1}
```

#### Step 2: Build heap list

```
heap = [(-2, 'i'), (-2, 'love'), (-1, 'leetcode'), (-1, 'coding')]
```

#### Step 3: heapify

After `heapify`, the heap is reordered so that: `(-2, 'i')` is at the top (smallest), because `'i' < 'love'` lexicographically.

So the heap order ensures: 1. `(-2, 'i')` 2. `(-2, 'love')` 3. `(-1, ...)` etc.

#### Step 4: Pop k=2 times

- 1st pop:  $(-2, 'i') \rightarrow$  append 'i'
- 2nd pop:  $(-2, 'love') \rightarrow$  append 'love'

Result: ["i", "love"]

#### Why Doesn't Lex Order Mess It Up?

Suppose we had:

```
words = ["love", "i", "i", "love"] # same frequencies
```

Then:  $-(-2, 'i')$  and  $(-2, 'love')$  - 'i' < 'love'  $\rightarrow$  so  $(-2, 'i')$  is smaller  $\rightarrow$  popped first  $\rightarrow$  correct.

So the natural tuple comparison handles the tie-break correctly.

---

#### Time & Space Complexity

Aspect	Complexity
<b>Time</b>	$O(n + k \log n)$ - $O(n)$ for counting - $O(n)$ for heapify - $O(k \log n)$ for popping k times
<b>Space</b>	$O(n)$ for counter and heap

---

#### Final Notes

- The **tuple**  $(-freq, word)$  is the magic key.
- Python's **lexicographic comparison of strings in tuples** makes tie-breaking automatic.
- **heapq** only supports min-heap, so we **negate frequency** to simulate max behavior.

---

Let me know if you'd like to see the **bucket sort** version ( $O(n)$  time) too!

## 6. Find K Closest Elements

### Problem Statement

Given a **sorted** integer array `arr`, two integers `k` and `x`, return the `k` closest integers to `x` in the array. The result should be **sorted in ascending order**.

- “Closest” means smallest absolute difference:  $|\text{num} - x|$
  - If there’s a tie in distance, **choose the smaller number**
- 

### Sample Input / Output

```
Input: arr = [1, 2, 3, 4, 5], k = 4, x = 3
Output: [1, 2, 3, 4]
```

```
Explanation:
|1-3|=2, |2-3|=1, |3-3|=0, |4-3|=1, |5-3|=2
Closest 4: [1, 2, 3, 4] → distances [2,1,0,1]
```

Another example:

```
Input: arr = [1, 3, 5, 7], k = 2, x = 4
Output: [3, 5]
```

```
Explanation:
|1-4|=3, |3-4|=1, |5-4|=1, |7-4|=3
Closest: 3 and 5 → [3,5] (both distance 1, but 3 < 5 so both included)
```

---

### Solution Code

```

class Solution:
    def findClosestElements(self, arr: List[int], k: int, x: int) -> List[int]:
        left = 0
        right = len(arr) - k # last valid start index for window of size k

        while left < right:
            mid = (left + right) // 2
            if x - arr[mid] > arr[mid + k] - x:
                left = mid + 1
            else:
                right = mid

        return arr[left : left + k]

```

---

## Step-by-Step Explanation

### Key Insight:

In a **sorted array**, the  $k$  closest elements to  $x$  will always form a **contiguous subarray**.

So instead of computing all distances and sorting (which would be  $O(n \log n)$ ), we can: - Use **binary search** to find the best **starting index** of this window. - Return the slice of  $k$  elements starting from that index.

---

### How Binary Search Works

We are **not** searching for  $x$ , but for the **best starting position** of a window of size  $k$ .

Let: -  $mid$  = current candidate start index - Window:  $arr[mid]$  to  $arr[mid + k - 1]$  - The next possible element (if we shift right):  $arr[mid + k]$

Now compare: - Distance from  $x$  to **left end**:  $x - arr[mid]$  - Distance from  $x$  to **next right element**:  $arr[mid + k] - x$



### Decision Rule:

```
if x - arr[mid] > arr[mid + k] - x:
    # Left end is farther → move window to the right
    left = mid + 1
else:
    # Right end is not closer, or tie → prefer smaller numbers (stay left)
    right = mid
```

This handles ties naturally: when distances are equal, we keep the left window  
→ includes smaller numbers.

---

### Example Walkthrough

```
arr = [1, 3, 5, 7], k = 2, x = 4
```

Possible windows of size 2: - Start 0 → [1,3] - Start 1 → [3,5] - Start 2 → [5,7]

We binary search between `left = 0`, `right = 4 - 2 = 2`

#### Iteration 1:

- $\text{mid} = (0 + 2) // 2 = 1$
- $x - \text{arr}[1] = 4 - 3 = 1$
- $\text{arr}[1+2] - x = \text{arr}[3] - 4 = 7 - 4 = 3$
- Is  $1 > 3$ ? →  $\text{right} = \text{mid} = 1$

#### Iteration 2:

- $\text{left} = 0, \text{right} = 1$
- $\text{mid} = (0 + 1) // 2 = 0$
- $x - \text{arr}[0] = 4 - 1 = 3$
- $\text{arr}[0+2] - x = 5 - 4 = 1$
- Is  $3 > 1$ ? →  $\text{left} = \text{mid} + 1 = 1$

Now  $\text{left} == \text{right} == 1 \rightarrow$  exit loop

Return  $\text{arr}[1:1+2] = \text{arr}[1:3] = [3, 5]$

---

## Complexity Analysis

Metric	Value	Reason
Time Complexity	$O(\log n + k)$	$O(\log n)$ for binary search, $O(k)$ for slicing the result
Space Complexity	$O(1)$	Only using constant extra space (no additional data structures)

Note: Output array of size  $k$  is not counted in space complexity unless specified.

---

## 7. Kth Largest Element in an Array

### Problem

Given an array `nums` and integer `k`, find the **kth largest element**.

Example:

`nums = [3,2,1,5,6,4]`, `k = 2` → return 5 (since 5 is the 2nd largest)

---

### Why Use a Min-Heap?

We want the **kth largest**, so we only need to keep track of the **top k largest elements**.

### Code

```
import heapq

class Solution:
    def findKthLargest(self, nums: list[int], k: int) -> int:
        # Min-heap to store the k largest elements
        heap = []

        for num in nums:
            if len(heap) < k:
```

```

        # If we have space, add the number
        heapq.heappush(heap, num)
    elif num > heap[0]:
        # If current number is bigger than the smallest in heap,
        # replace the smallest with this one
        heapq.heapreplace(heap, num)

# The root of the min-heap is the kth largest
return heap[0]

```

---

### Step-by-Step Walkthrough with `nums = [3,2,1,5,6,4]`, `k = 2`

```
heap = [] # min-heap
```

#### 1. `num = 3`

- `len(heap) = 0 < 2` → push 3
- `heap = [3]`

#### 2. `num = 2`

- `len(heap) = 1 < 2` → push 2
- `heap = [2, 3]` (heap property: min at front)

#### 3. `num = 1`

- `len(heap) = 2` → not less than k
- Is `1 > heap[0]`? → `1 > 2`? No → skip

#### 4. `num = 5`

- `len(heap) = 2` → check if `5 > 2` → Yes
- Replace: `heapreplace(heap, 5)` → removes 2, adds 5
- `heap = [3, 5]` → now min is 3

#### 5. `num = 6`

- `6 > 3` → Yes
- `heapreplace(heap, 6)` → removes 3, adds 6
- `heap = [5, 6]` → min is 5

#### 6. `num = 4`

- $4 > 5$ ? No  $\rightarrow$  skip

Final heap:  $[5, 6] \rightarrow \text{heap}[0] = 5 \rightarrow \text{return } 5$

---

### Time & Space Complexity

Metric	Complexity	Explanation
<b>Time</b>	$O(n \log k)$	For each of $n$ elements: heap operation takes $O(\log k)$
<b>Space</b>	$O(k)$	Heap stores at most $k$ elements

Efficient when  **$k$  is small** compared to  $n$  (e.g.,  $k = 10$ ,  $n = 10000$ )

---

### Pro Tips

- Use `heapq.heapreplace()` instead of `heappop()` + `heappush()` for efficiency.
- Always compare `num > heap[0]` — not `>=`, because duplicates are allowed.
- This method works even if there are duplicate values.

Example: `nums = [1,1,1,2,2]`,  $k = 3 \rightarrow$  3rd largest is 1  $\rightarrow$  correct.

---

## 8. Smallest Range Covering Elements from K Lists

### Problem Statement:

You are given  $k$  sorted integer arrays. You need to find the **smallest range** that includes **at least one number from each array**.

The range is defined as  $[\text{start}, \text{end}]$ , and its **size** is  $\text{end} - \text{start}$ .

Return the **smallest such range**. If multiple ranges have the same size, return any one of them.

### Example:

```
Input: nums = [[4,10,15,24,26], [0,9,12,20], [5,18,22,30]]
Output: [20,24]
```

Explanation: The range [20,24] covers: - 20 from the second list, - 24 from the first list, - 22 from the third list.

All lists are covered, and it's the smallest possible range.

### Key Insight:

We want to minimize the difference (**end - start**) while ensuring that **each of the k lists contributes at least one element** in the range.

A greedy + heap approach works well here.

### Python Implementation:

```
import heapq
from typing import List

class Solution:
    def smallestRange(self, nums: List[List[int]]) -> List[int]:
        # Min-heap to store (value, list_index, index_in_list)
        heap = []
        max_val = float('-inf')

        # Initialize: add the first element from each list
        for i in range(len(nums)):
            heapq.heappush(heap, (nums[i][0], i, 0))
            max_val = max(max_val, nums[i][0])

        # Initialize result range
        best_start, best_end = float('-inf'), float('inf')

        while heap:
            min_val, list_idx, idx_in_list = heapq.heappop(heap)

            # Update the best range if current range is smaller
```

```

        if max_val - min_val < best_end - best_start:
            best_start, best_end = min_val, max_val

        # Move to next element in the same list
        if idx_in_list + 1 < len(nums[list_idx]):
            next_val = nums[list_idx][idx_in_list + 1]
            heapq.heappush(heap, (next_val, list_idx, idx_in_list + 1))
            max_val = max(max_val, next_val)
        else:
            # One list is exhausted; we can't form a valid range anymore
            break

    return [best_start, best_end]

```

### Complexity Analysis:

- **Time Complexity:**

$O(N \log k)$ , where  $N$  is the total number of elements across all lists, and  $k$  is the number of lists.

Each element is pushed and popped once from the heap ( $\log k$  per operation).

- **Space Complexity:**

$O(k)$  for the heap (stores one element per list at a time).

### Why This Works:

- We always maintain one element from each list (initially), then replace the smallest one with the next in its list.
- By doing this, we ensure we never skip a potentially better range.
- The heap ensures we always process the smallest current element, which helps shrink the range.

### Example walkthrough

We'll use this example:

```

nums = [
    [4, 10, 15, 24, 26], # List 0
    [0, 9, 12, 20],      # List 1
    [5, 18, 22, 30]      # List 2
]

```

## Line-by-Line Walkthrough (With Visuals & Tracing)

Let's now go **step-by-step**, updating variables at every stage.

### Step 1: Initialize heap and max\_val

```
heap = []  
max_val = float('-inf') # -∞
```

Now loop over each list ( $i = 0, 1, 2$ ):

**$i = 0$ : List 0  $\rightarrow$  element = 4**

- Push (4, 0, 0) into heap
- $\text{max\_val} = \max(-\infty, 4) = 4$

Heap: [(4, 0, 0)]

**$i = 1$ : List 1  $\rightarrow$  element = 0**

- Push (0, 1, 0) into heap
- $\text{max\_val} = \max(4, 0) = 4$

Heap: [(0, 1, 0), (4, 0, 0)]  $\rightarrow$  min-heap sorted: [0, 4]

**$i = 2$ : List 2  $\rightarrow$  element = 5**

- Push (5, 2, 0) into heap
- $\text{max\_val} = \max(4, 5) = 5$

Heap: [(0, 1, 0), (4, 0, 0), (5, 2, 0)]  $\rightarrow$  sorted by value

**After initialization:** - heap = [(0, 1, 0), (4, 0, 0), (5, 2, 0)] -  $\text{max\_val} = 5$  -  
 $\text{best\_start} = -\infty, \text{best\_end} = \infty$

This window: {0 (list1), 4 (list0), 5 (list2)}  $\rightarrow$  covers all lists!

---

### Step 2: Set best\_start, best\_end

```
best_start, best_end = float('-inf'), float('inf')
```

So far, no valid range  $\rightarrow$  we'll update it when we find a better one.

---

### Step 3: Start the while heap: Loop

We process the heap until it's empty or a list runs out.

Let's trace each iteration.

---

#### Iteration 1: Pop (0, 1, 0)

```
min_val, list_idx, idx_in_list = heapq.heappop(heap)
#  $\rightarrow$  min_val = 0, list_idx = 1, idx_in_list = 0
```

Now check:

```
if max_val - min_val < best_end - best_start:
    #  $5 - 0 = 5 < \infty - (-\infty) \rightarrow \text{True}$ 
    best_start, best_end = 0, 5
```

Update best range: [0, 5] (size = 5)

Now try to advance list 1:

```
if idx_in_list + 1 < len(nums[1]): #  $0+1=1 < 4 \rightarrow \text{True}$ 
    next_val = nums[1][1] = 9
    heapq.heappush(heap, (9, 1, 1))
    max_val = max(5, 9) = 9
```

New heap: [(4, 0, 0), (5, 2, 0), (9, 1, 1)]  
 $\rightarrow$  Sorted: [4, 5, 9]

Now window: {4, 5, 9}  $\rightarrow$  min=4, max=9  $\rightarrow$  range=5

---



### Iteration 2: Pop (4, 0, 0)

```
min_val = 4, list_idx = 0, idx_in_list = 0
```

Check:

```
if 9 - 4 = 5 < 5 - 0 = 5? → No (5 < 5 is False)
```

No update.

Advance list 0:

```
if 0+1=1 < 5 → True  
next_val = nums[0][1] = 10  
push (10, 0, 1)  
max_val = max(9, 10) = 10
```

Heap: [(5, 2, 0), (9, 1, 1), (10, 0, 1)] → sorted: [5, 9, 10]

Window: {5, 9, 10} → range = 5

---

### Iteration 3: Pop (5, 2, 0)

```
min_val = 5, list_idx = 2, idx_in_list = 0
```

Check:

```
10 - 5 = 5 < 5 → False → no update
```

Advance list 2:

```
1 < 4 → True  
next_val = nums[2][1] = 18  
push (18, 2, 1)  
max_val = max(10, 18) = 18
```

Heap: [(9, 1, 1), (10, 0, 1), (18, 2, 1)] → [9, 10, 18]

Window: {9, 10, 18} → range = 9

---

#### Iteration 4: Pop (9, 1, 1)

```
min_val = 9, list_idx = 1, idx_in_list = 1
```

Check:

```
18 - 9 = 9 < 5? → No → skip
```

Advance list 1:

```
1+1=2 < 4 → True  
next_val = nums[1][2] = 12  
push (12, 1, 2)  
max_val = max(18, 12) = 18
```

Heap: [(10, 0, 1), (12, 1, 2), (18, 2, 1)] → [10, 12, 18]

Window: {10, 12, 18} → range = 8

---

#### Iteration 5: Pop (10, 0, 1)

```
min_val = 10, list_idx = 0, idx_in_list = 1
```

Check:

```
18 - 10 = 8 < 5? → No
```

Advance list 0:

```
1+1=2 < 5 → True  
next_val = nums[0][2] = 15  
push (15, 0, 2)  
max_val = max(18, 15) = 18
```

Heap: [(12, 1, 2), (15, 0, 2), (18, 2, 1)] → [12, 15, 18]

Window: {12, 15, 18} → range = 6

---

### Iteration 6: Pop (12, 1, 2)

```
min_val = 12, list_idx = 1, idx_in_list = 2
```

Check:

```
18 - 12 = 6 < 5? → No
```

Advance list 1:

```
2+1=3 < 4 → True  
next_val = nums[1][3] = 20  
push (20, 1, 3)  
max_val = max(18, 20) = 20
```

Heap: [(15, 0, 2), (18, 2, 1), (20, 1, 3)] → [15, 18, 20]

Window: {15, 18, 20} → range = 5 → same as before → no update

---

### Iteration 7: Pop (15, 0, 2)

```
min_val = 15, list_idx = 0, idx_in_list = 2
```

Check:

```
20 - 15 = 5 < 5? → No
```

Advance list 0:

```
2+1=3 < 5 → True  
next_val = nums[0][3] = 24  
push (24, 0, 3)  
max_val = max(20, 24) = 24
```

Heap: [(18, 2, 1), (20, 1, 3), (24, 0, 3)] → [18, 20, 24]

Window: {18, 20, 24} → range = 6

---

### Iteration 8: Pop (18, 2, 1)

```
min_val = 18, list_idx = 2, idx_in_list = 1
```

Check:

```
24 - 18 = 6 < 5? → No
```

Advance list 2:

```
1+1=2 < 4 → True  
next_val = nums[2][2] = 22  
push(22, 2, 2)  
max_val = max(24, 22) = 24
```

Heap: [(20, 1, 3), (22, 2, 2), (24, 0, 3)] → [20, 22, 24]

Now check:

```
24 - 20 = 4 < 5? → YES!
```

Update best range: best\_start = 20, best\_end = 24

We found a better range: [20, 24] (size = 4)

---

### Iteration 9: Pop (20, 1, 3)

```
min_val = 20, list_idx = 1, idx_in_list = 3
```

Check:

```
24 - 20 = 4 < 4? → No (4 == 4)
```

Now try to advance list 1:

```
3+1=4 < 4? → False → list 1 is exhausted!  
break
```

Loop ends.

---

Final Output

```
return [best_start, best_end] # → [20, 24]
```

Summary Table: Key Variables Over Time

Iteration	Popped From	New Max	Current Window	Range	Best Range
1	List 1 (0)	9	{4,5,9}	5	[0,5]
2	List 0 (4)	10	{5,9,10}	5	[0,5]
3	List 2 (5)	18	{9,10,18}	9	[0,5]
4	List 1 (9)	18	{10,12,18}	8	[0,5]
5	List 0 (10)	18	{12,15,18}	6	[0,5]
6	List 1 (12)	20	{15,18,20}	5	[0,5]
7	List 0 (15)	24	{18,20,24}	6	[0,5]
8	List 2 (18)	24	{20,22,24}	4	[20,24]
9	List 1 (20)	24	List 1 done → break		

Why This Works: Algorithm Logic

Concept	Explanation
Min-Heap	Always picks the smallest current element → helps shrink the left side of the range.
Track max_val	Ensures we know how wide the current window is.
Replace with next in same list	Keeps one element per list, explores new combinations.
Break when list exhausted	Can't form a full window anymore → stop.
Greedy but optimal	Because arrays are sorted, advancing the smallest guarantees we don't miss the global minimum.

## Final Answer

[20, 24]

## Pro Tips for Understanding

- Think of the heap as a “**priority queue**” of “front runners” — always the smallest.
- The `max_val` is like the **tallest person in the group** — we care about the span between shortest and tallest.
- Every time we move the shortest forward, we’re trying to **tighten the group**.