

## **DATASHEET**

# DDRASDRAMDATASK Low Power DRAM (LPDDR4 FBGA)

# D0811PM2FDGUK-U (512Mx16bitsx1channel) D0811PM2FDGUKW-U (512Mx16bitsx1channel) B1621PM2FDGUK-U (512Mx16bitsx2channels) B1621PM2FDGUKW-U (512Mx16bitsx2channels)

## **Specifications**

- Die Density: 8Gbits
- Organization
  - x 16 bits: 64M words x 16 bits x 8 banks
  - 2 pieces of 8Gb (x16) in one package (For 16Gb)
  - Row Address: R0 ~ R15
  - Column Address: C0 ~ C9
- Package
  - 200-ball FBGA
- Power supply
  - VDD1 = 1.8V (1.70V to 1.95V)
  - VDD2, VDDCA and VDDQ = 1.1V (1.06V to (1.17V)
- Data rate:
  - 3733Mbps max. Backward compatible
- Eight internal banks per channel for concurrent operation
- Burst lengths (BL): 16, 32 and on-the-fly
  - On the fly mode is enabled by MRS
- Programmable RL (Read Latency) and WL (Write Latency)
- Precharge: auto precharge option for each burst
- Programmable driver strength
- Refresh: auto-refresh, self-refresh
- Refresh cycles: 8192 cycles/32ms
  - Average refresh period: 3.9µs
- Operating temperature range
  - $TC = -25^{\circ}C$  to  $+85^{\circ}C$  (Standard)
  - TC = -40°C to +95°C (Industrial Temperature)

#### **Features**

- Low power consumption
- Per Bank Refresh
- Partial Array Self-Refresh (PASR)
  - Bank Masking
  - Segment Masking
- Auto Temperature Compensated Self-Refresh
  - (ATCSR) by built-in temperature sensor
- All bank auto refresh and directed per bank auto refresh supported
- Double-data-rate architecture; two data transfers per one clock cycle
- Differential clock inputs (CK\_t and CK\_c)
- Bi-directional differential data strobe (DQS tandDQS c)
- Commands entered on both rising and falling CK\_t edge; data and data mask referenced to both edges
- DMI pin support for write data masking and DBIdc functionality

Lower Clock Frequency Limit		WRITE	Latency	READ Latency			
(MHz)			DBI Enabled				
1600	1866	1866 16 30 32		36			



**Device Addressing** 

		Device Addressing				
Device	density	8Gb (512M x 16 I/O x 1 channel)	16Gb (512M x 16 I/O x 2 channels)			
Numbe	r of die per device	1	20			
Device	density (per rank)	8Gb	16Gb			
Die den	sity	8Gb	8Gb			
Device	configuration	64Mb x 1 rank(s) x 8 banks x 16 DQ x 1 channel	64Mb x 1 rank(s) x 8 banks x 16 DQ x 2 channels			
Number	of channels	1	2			
Number	r of ranks	1	1			
Number	of banks (per channel)	8	8			
Number	r of rows (per channel)	65,536	65,536			
Bank ac	ddress	BA0-BA2	BA0-BA2			
x16	Row addresses	R0-R15	R0-R15			
710	Column addresses	C0-C9	C0-C9			
Burst st	arting address boundary	64-bit	64-bit			

Notes: 1. The lower two column addresses (C0–C1) are assumed to be zero and are not transmitted on the CA bus.

2. Row and column address values on the CA bus that are not used for a particular density are "Don't Care."



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		DO8	311PM2FDGU	K(W)-U / B1	621PM2FDGUK(W)-U
Revi	sion H	istory		OFM	ORI
Revis	sion No.	History	Release date	Editor	Approved by
F	00/	Initial release	August 2023	Annie Hsu	Sander Huang / CK Wang
E	300	Add industrial temperature & remove "preliminary" mark	October 2023	Jona Lee	Sander Huang / CK Wang

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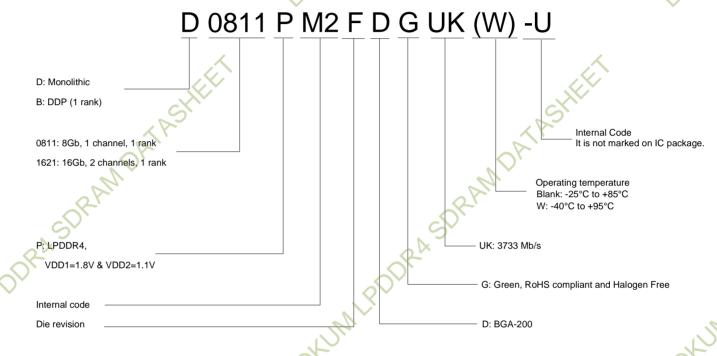
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## Ordering Information

	Part number	Die revision	Organization	Internal banks	JEDEC speed	Package
	Q.A.		(words x bits x channels)	Q.A.		
	D0811PM2FDGUK-U	F Die	512M x 16bits x 1 channel	8 banks	3733 Mb/s	200 ball FBGA
	D0811PM2FDGUKW-U	F Die	512M x 16bits x 1 channel	8 banks	3733 Mb/s	200 ball FBGA
\	B1621PM2FDGUK-U	F Die	512M x 16bits x 2 channels	8 banks	3733 Mb/s	200 ball FBGA
	B1621PM2FDGUKW-U	F Die	512M x 16bits x 2 channels	8 banks	3733 Mb/s	200 ball FBGA

#### **Part Number**





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## 1. LPDDR4 Interface

## 1.1 Pin Function and Descriptions

Table — Pin Function and Descriptions

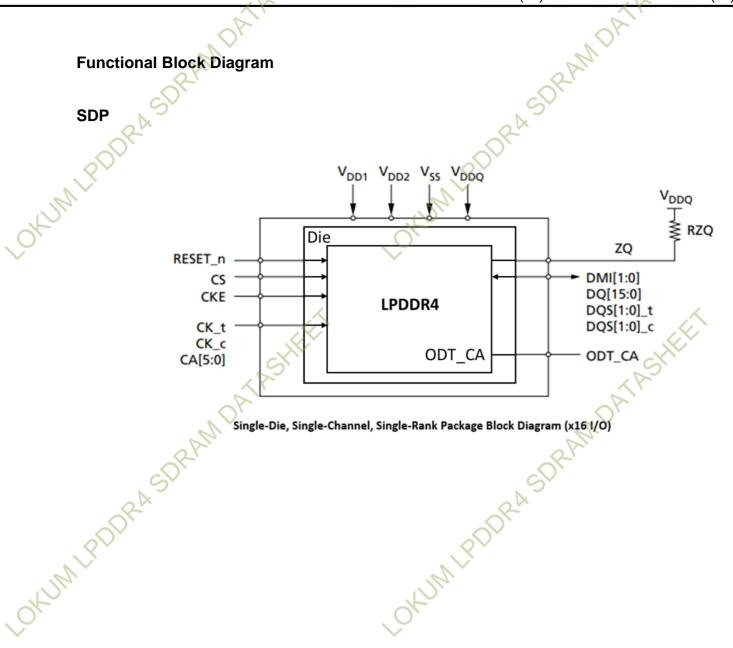
		Table — Fill Function and Descriptions
Name	Type	Description
CK_t_A, CK_c_A CK_t_B, CK_c_B	Input	<b>Clock:</b> CK_t and CK_c are differential clock inputs. All address, command, and control input signals are sampled on the crossing of the positive edge of CK_t and the negative edge of CK_c. AC timings for CA parameters are referenced to CK. Each channel (A & B) has its own clock pair.
CKE0_A CKE0_B	Input	Clock Enable: CKE HIGH activates and CKE LOW deactivates the internal clock circuits, input buffers, and output drivers. Power-saving modes are entered and exited via CKE transitions.  CKE is part of the command code. Each channel (A & B) has its own CKE signal.
CS0_A CS0_B	Input	Chip Select: CS is part of the command code. Each channel (A & B) has its own CS signal.
CA[5:0]_A CA[5:0]_B	Input	Command/Address Inputs: CA signals provide the Command and Address inputs according to the Command Truth Table. Each channel (A&B) has its own CA signals.
ODT_CA_A ODT_CA_B	Input	<b>CA ODT Control:</b> The ODT_CA pin is used in conjunction with the Mode Register to turn on/off the On-Die-Termination for CA pins.
DQ[15:0]_A, DQ[15:0]_B	I/O	Data Input/Output: Bi-direction data bus.
DQS[1:0]_t_A, DQS[1:0]_c_A, DQS[1:0]_t_B, DQS[1:0]_c_B	VO RM	<b>Data Strobe:</b> DQS_t and DQS_c are bi-directional differential output clock signals used to strobe data during a READ or WRITE. The Data Strobe is generated by the DRAM for a READ and is edge-aligned with Data. The Data Strobe is generated by the Memory Controller for a WRITE and must arrive prior to Data. Each byte of data has a Data Strobe signal pair. Each channel (A & B) has its own DQS strobes.
DMI[1:0]_A, DMI[1:0]_B	I/O	<b>Data Mask Inversion:</b> DMI is a bi-directional signal which is driven HIGH when the data on the data bus is inverted, or driven LOW when the data is in its normal state. Data Inversion can be disabled via a mode register setting. Each byte of data has a DMI signal. Each channel (A & B) has its own DMI signals. This signal is also used along with the DQ signals to provide write data masking information to the DRAM. The DMI pin function - Data Inversion or Data mask - depends on Mode Register setting.
ZQ		<b>Calibration Reference:</b> Used to calibrate the output drive strength and the termination resistance. There is one ZQ pin per die. The ZQ pin shall be connected to VDDQ through a $240\Omega \pm 1\%$ resistor.
VDDQ, VDD1, VDD2	Supply	Power Supplies: Isolated on the die for improved noise immunity.
VSS, VSSQ	GND	Ground Reference: Power supply ground reference
RESET_n	Input	<b>RESET:</b> When asserted LOW, the RESET_n signal resets all channels of the die. There is one RESET_n pad per die.

NOTE 1 "\_A" and "\_B" indicate DRAM channel "\_A" pads are present in all devices. "\_B" pads are present in dual channel SDRAM devices only.



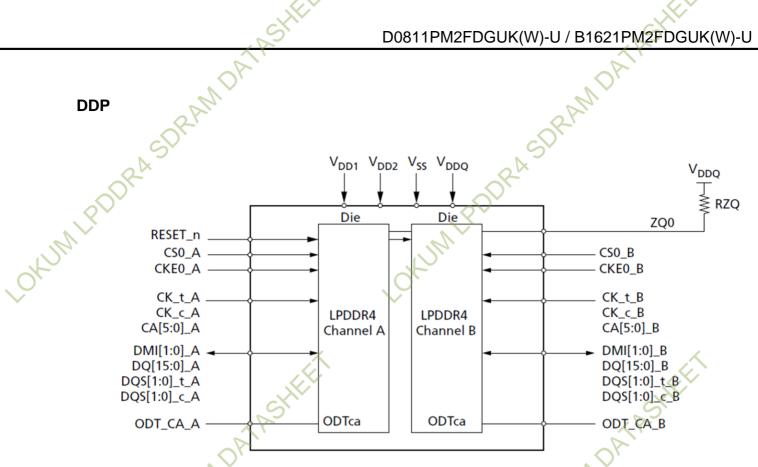
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# Functional Block Diagram









Dual-Die, Dual-Channel, Single-Rank Package Block Diagram (x16 l/O)



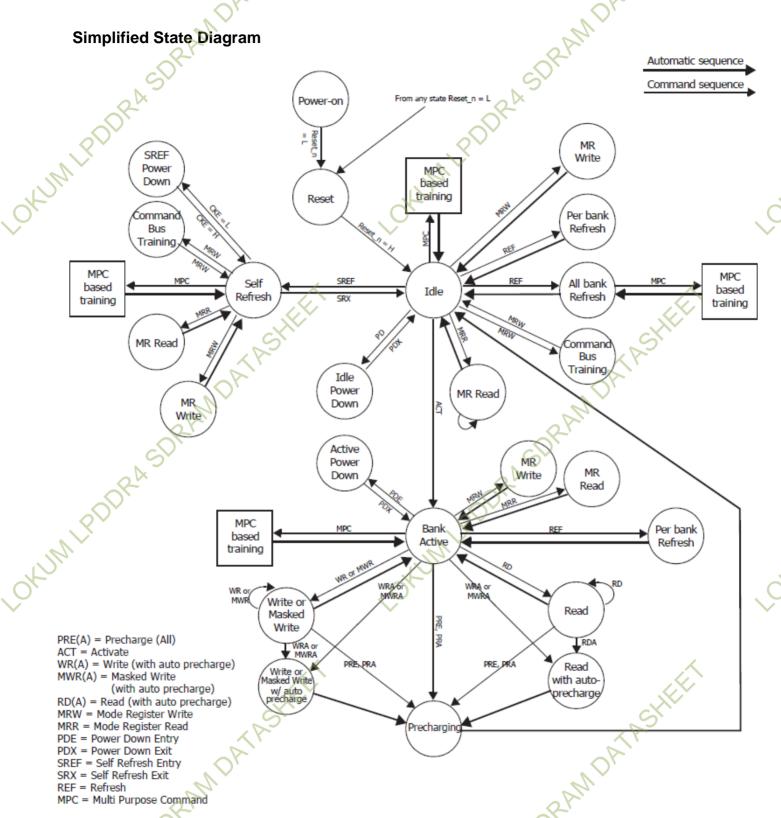


Figure — Simplified Bus Interface State Diagram

Note 1: For DDR4 Mobile RAM in the Idle state, all banks are precharged.



## 1.2 Electrical Conditions

All voltages are referenced to VSS (GND)

- Execute power-up and Initialization sequence before proper device operation is achieved.
- Operation or timing that is not specified is illegal, and after such an event, in order to guarantee proper operation, the DDR4 Mobile RAM Device must be powered down and then restarted through the specialized initialization sequence before normal operation can continue.

## 1.2.1 Absolute maximum Ratings

Table — Absolute maximum Ratings

Parameter	Symbol	min.	max.	Unit	Note
VDD1 supply voltage relative to VSS	VDD1	-0.4	2.1	V	2
VDD2 supply voltage relative to VSS	VDD2	-0.4	1.5	V	2
VDDQ supply voltage relative to VSSQ	VDDQ	-0.4	1.5	V	2
Voltage on any ball relative to VSS	VIN, VOUT	-0.4	1.5	V	
Storage Temperature	TSTG	-55	125	°C	<b>3</b>

#### Notes:

- 1. Stresses greater than those listed under "Absolute maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
- 2. See Power-Ramp section "Power-up, initialization and Power-Off" on section1.4 for relationship between power supplies
- **3.** Storage Temperature is the case surface temperature on the center/top side of the DDR3 Mobile RAM Device. For the measurement conditions, please refer to JESD51-2 standard.

#### Caution

Exposing the device to stress above those listed in Absolute maximum Ratings could cause permanent damage. The device is not meant to be operated under conditions outside the limits described in the operational section of this specification. Exposure to Absolute maximum Rating conditions for extended periods may affect device reliability.

## 1.2.2 Recommended DC Operating Conditions

Table — Recommended DC Operating Conditions

		3 U				
Parameter	Symbol	min.	Тур	max.	Unit	Note
Core Power1	VDD1	1.70	1.80	1.95	V	1,2
Core Power2, Input buffer power	VDD2	1.06	1.10	1.17	V	1,2,3
I/O Buffer Power	VDDQ	1.06	1.10	1.17	V	2,3

- 1. VDD1 uses significantly less current than VDD2.
- 2. The voltage range is for DC voltage only. DC is defined as the voltage supplied at the DRAM and is inclusive of all noise up to 20MHz at the DRAM package ball.
- 3. The voltage noise tolerance from DC to 20MHz exceeding a pk-pk tolerance of 45mV at the DRAM ball is not included in the TdIVW.



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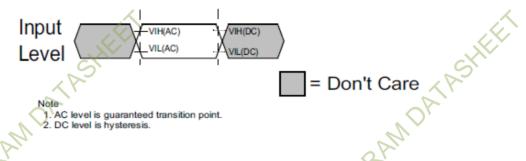
## 1.2.3 AC and DC Input Measurement Levels

## 1.2.3.1 V High speed LVCMOS (HS\_LLVCMOS)

Table — LPDDR4 Input level for CKE

Parameter	Symbol	min.	max.	Unit	Note
AC input logic high	VIH(AC)	0.75*VDD2	VDD2+0.2	V	1
AC input logic low	VIL(AC)	-0.2	0.25*VDD2	V	1
DC input logic high	VIH(DC)	0.65*VDD2	VDD2+0.2	V	
DC input logic low	VIL(DC)	-0.2	0.35*VDD2	V	

Note: 1. See "Overshoot and Undershoot Specifications" on section 1.2.4.

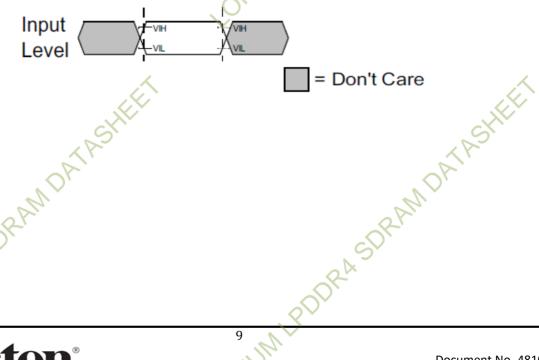


## 1.2.3.2 LPDDR4 Input Level for Reset\_n and ODT\_CA

Table — LPDDR4 Input level for Reset\_n and ODT\_CA

0	Parameter	Symbol	min.	max.	Unit	Note
8	Input high level	VIH	0.8*VDD2	VDD2+0.2	V	1
	Input low level	VIL	-0.2	0.20*VDD2	V	1

Note: 1. See "Overshoot and Undershoot Specifications" on section 1.2.4.





#### **AC Overshoot and Undershoot Specifications** 1.2.4

Table — LPDDR4 Overshoot/Undershoot Specification

Parameter	C	Specification	Unit
maximum peak amplitude allowed for overshoot area.	Max.	0.3	V
maximum peak amplitude allowed for undershoot area.	Max.	0.3	V
maximum overshoot area above VDD/VDDQ	Max.	0.8	V-ns
maximum undershoot area below VSS/VSSQ	Max.	0.8	V-ns

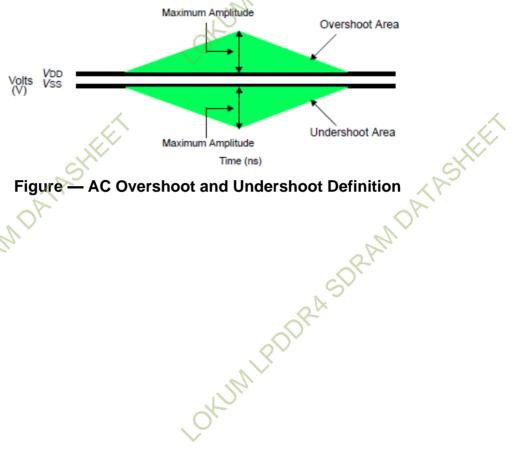


Fig. OKUMI PODRA SORAM DA AC Overshoot and Undershoot Definition



## 1.2.5 Differential Input Voltage 1.2.5.1 Differential Input Voltage for CK

The minimum input voltage need to satisfy both Vindiff CK and Vindiff CK /2 specification at input receiver and their measurement period is 1tCK. Vindiff CK is the peak to peak voltage centered on 0 volts differential and Vindiff CK /2 is max and min peak voltage from 0V.

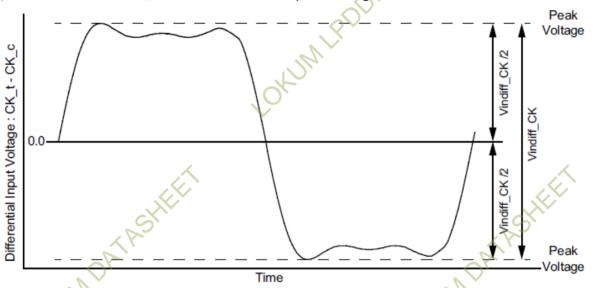


Figure — CK Differential input voltage

Table — CK Differential input voltage

				Data	Rate				
Parameter Symbol		1600/1867		2133/2400/3200		0/3200 3733/4267		Unit	Notes
QV		Min	Max	Min	Max	Min	Max		
CK differential input voltage	Vindiff_CK	420	-	380	-	360	-	mV	1

Notes:

1. The peak voltage of Differential CK signals is calculated in a following equation.

Vindiff CK = (Max Peak Voltage) - (Min Peak Voltage)

Max Peak Voltage = Max(f(t))

Min Peak Voltage = Min(f(t))

 $f(t) = VCK_t - VCK_c$ RASDRAMDATASHEET



## 1.2.5.2 Differential Input Voltage for DQS

The minimum input voltage need to satisfy both Vindiff\_DQS and Vindiff\_DQS /2 specification at input receiver and their measurement period is 1UI(tCK/2). Vindiff\_DQS is the peak to peak voltage centered on 0 volts differential and Vindiff\_DQS /2 is max and min peak voltage from 0V

Figure - DQS Differential Input Voltage

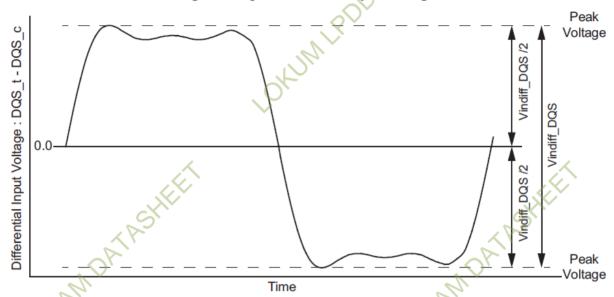


Table — Differential AC and DC Input Levels

2				Data	Rate				
Parameter	Symbol	1600/	/1867	2133/24	00/3200	3733	/4267	Unit	Notes
		Min	Max	Min	Max	Min	Max		
DQS differential input	Vindiff_DQS	360	-	360	-	340	-	mV	1

#### Notes:

1. The peak voltage of Differential CK signals is calculated in a following equation.

Vindiff\_DQS = (Max Peak Voltage) - (Min Peak Voltage)

Max Peak Voltage = Max(f(t))

Min Peak Voltage = Min(f(t))

f(t) = VDQS\_t - VDQS\_c



## 1.2.6 Differential Input Cross Point Voltage

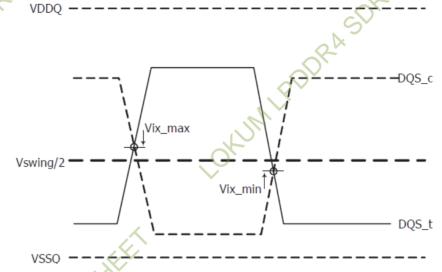


Figure — DQS input cross-point voltage (V)VIX Definition

Table — DQS input voltage cross-point (Vix) ratio

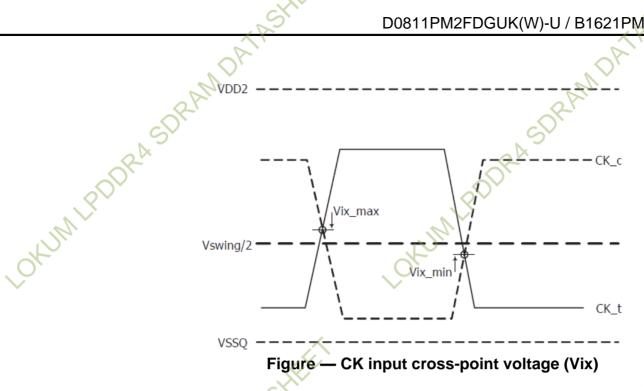
			Tollago oloca		1610		
Parameter W	Cymbol	Min /		Data rate		Unit	Note
Parameter	Symbol	Max	1600/1867	2133/2400/3200	3733/4267	Offic	note
DQS Differential input cross-	Vix DQS ratio	May	20	20	20	%	12
point voltage ratio	VIX_DQS_IAIIO	iviax	20	200	20	/0	1,2

#### Notes:

- 1. The Vix voltage is referenced to Vswing/2(avg)= 0.5(VDQS\_t + VDQS\_c) where the average is over tbd UI.
- 2. The ratio of the Vix pk voltage divided by Vdiff\_DQS: Vix\_DQS\_Ratio = 100\* (Vix\_DQS/Vdiff DQS pk-pk) where VdiffDQS pk-pk = 2\*|VDQS\_t VDQS\_c|.



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Parameter	Symbol	Min /		Data rate		Unit	Note
Parameter	Symbol	Max	1600/1867	2133/2400/3200	133/2400/3200 3733/4267		
CK Differential input cross- point voltage ratio	Vix_CK_ratio	Max	25	25	M 25	%	1,2

#### Notes:

- 1. The Vix voltage is referenced to Vswing/2(avg)= 0.5(VCK\_t + VCK\_c) where the average is over tbd UI.
- 2. The ratio of the Vix pk voltage divided by Vdiff\_CK: Vix\_CK\_Ratio = 100\* (Vix\_CK/Vdiff CK pk-pk) where VdiffCK pk-pk  $= 2*|VCK_t - VCK_c|$



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## 1.2.6.1 Single Ended Output Slew Rate

With the reference load for timing measurements, output slew rate for falling and rising edges is defined and measured between VOL(AC) and VOH(AC) for single ended signals as shown in Table 14 and Figure 8.

Table — Single-ended Output Slew Rate Definition

Description	Mea	sured	Defined by
Description	from	to	Defined by
Single-ended output slew rate for rising edge	VOL(AC)	VOH(AC)	[VOH(AC) - VOL(AC)] / DeltaTRse
Single-ended output slew rate for falling edge	VOH(AC)	VOL(AC)	[VOH(AC) – VOL(AC)] / DeltaTFse

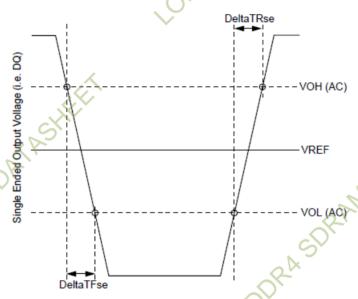


Figure — Single Ended Output Slew Rate Definition

Table — Output Slew Rate (single-ended)

Parameter	Symbol	min.	max.	Unit
Single-ended Output Slew Rate (VOH = VDDQ/3)	SRQse	3.0	9	V/ns
Output slew-rate matching Ratio (Rise to Fall)		0.8	1.2	

Remark: SR: Slew Rate, Q: Query Output (like in DQ, which stands for Data-in, Query-Output), se: Single-ended Signals

#### Notes:

- 1. Measured with output reference load.
- 2. The ratio of pull-up to pull-down slew rate is specified for the same temperature and voltage, over the entire temperature and voltage range. For a given output, it represents the maximum difference between pull-up and pulldown drivers due to process variation.
- 3. The output slew rate for falling and rising edges is defined and measured between VOL(AC) and VOH(AC).
- 4. Slew rates are measured under normal SSO conditions, with 1/2 of DQ signals per data byte driving logic high and 1/2 of DQ signals per data byte driving logic low.



## 1.2.7 Differential Output Slew Rate

With the reference load for timing measurements, output slew rate for falling and rising edges is defined and measured between VOLdiff(AC) and VOHdiff(AC) for differential signals as shown in Table 16 and Figure 9.

Table — Differential Output Slew Rate Definition

Description	Meas	ured	Defined by
Description	from	to	Defined by
Differential output slew rate for rising edge	VOLdiff(AC)	VOHdiff(AC)	[VOHdiff(AC) – VOLdiff(AC)] / DeltaTRdiff
Differential output slew rate for falling edge	VOHdiff(AC)	VOLdiff(AC)	[VOHdiff(AC) – VOLdiff(AC)] / DeltaTFdiff

Note: 1. Output slew rate is verified by design and characterization, and may not be subject to production test.

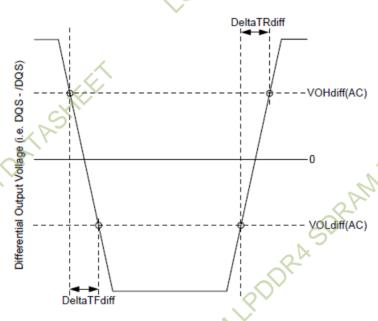


Figure — Differential Output Slew Rate Definition

Table — Differential Output Slew Rate

Parameter	Symbol	min.	max.	Unit
Differential Output Slew Rate (VOH=VDDQ x 0.5)	SRQdiff	6	18	V/ns

Remark: SR: Slew Rate, Q: Query Output (like in DQ, which stands for Data-in, Query-Output),

diff: Differential Signals

Notes:

- 1. Measured with output reference load.
- 2. The output slew rate for falling and rising edges is defined and measured between VOL(AC) and VOH(AC).
- 3. Slew rates are measured under normal SSO conditions, with 1/2 of DQ signals per data byte driving logic high and 1/2 of DQ signals per data byte driving logic low.



## 1.3 Electrical Specifications

#### 1.3.1 IDD Measurement Conditions

The following definitions are used within the IDD measurement tables:

LOW: VIN ≤ VIL(DC) max. HIGH: VIN ≥ VIH(DC) min.

STABLE: Inputs are stable at a HIGH or LOW level

Table — Definition of Switching for CA Input Signals

2	Switching for CA										
CK_t edge	R1	R2	R3	R4	R5	R6	R7	R8			
CKE	HIGH	HIGH	HIGH	HIGH	HIGH	HIGH	HIGH	HIGH			
CS	LOW	LOW	LOW	LOW	LOW	LOW	LOW	LOW			
CA0	HIGH	LOW	LOW	LOW	LOW	HIGH	HIGH	HIGH			
CA1	HIGH	HIGH	HIGH	LOW	LOW	LOW	LOW	HIGH			
CA2	HIGH	LOW	LOW	LOW	LOW	HIGH	HIGH	/ HIGH			
CA3	HIGH	HIGH	HIGH	LOW	LOW	LOW	LOW	HIGH			
CA4	HIGH	LOW	LOW	LOW	LOW	HIGH	HIGH	HIGH			
CA5	HIGH	HIGH	HIGH	LOW	LOW	LOW	LOW	HIGH			

#### Notes:

- 1. CS must always be driven LOW.
- 2. 50% of CA bus is changing between HIGH and LOW once per clock for the CA bus.
- 3. The above pattern is used continuously during IDD measurement for IDD values that require switching on the CA bus.

Table — CA pattern for IDD4R for BL = 16

Clock Cycle Number	CKE	CS	Command	CA0	CA1	CA2	CA3	CA4	CA5
N2 IX	HIGH	HIGH	Read-1	L	Н	LR IX	L	L	L
N+1	HIGH	LOW	Reau-1	L	Н	ODY	L	L	L
N+2	HIGH	HIGH	CAS-2	L	H		L	Н	L
N+3	HIGH	LOW		L		L	L	L	L
N+4	HIGH	LOW	Deselect	L		L	L	L	L
N+5	HIGH		Deselect	L		L	L	L	L
N+6	HIGH	LOW	Deselect	L	L	L	L	L	L
N+7	HIGH	LOW	Deselect	L	L	L	L	L	L
N+8	HIGH	HIGH	Read-1	L	Н	L	L	L	L
N+9	HIGH	LOW	Reau-I	L	I	Г	L	Н	L
N+10	HIGH	HIGH	CAS-2	L	Н	L	L	H	Н
N+11	HIGH	LOW	, CA3-2	Н	I	I	Н	T	Н
N+12	HIGH	LOW	Deselect	L	L	L	L	L	L
N+13	HIGH	LOW	Deselect	L	L	L	4	L	L
N+14	HIGH	LOW	Deselect	L	L	L	P	L	L
N+15	HIGH	LOW	Deselect	L	L	L	AFL .	L	L

#### Notes

- 1. BA[2:0] = 010, CA[9:4] = 000000 or 111111, Burst Order CA[3:2] = 00 or 11 (Same as LPDDR3 IDD4R Spec)
- 2. Difference from LPDDR3 Spec: CA pins are kept low with DES CMD to reduce ODT current.



Table — CA pattern for IDD4W for BL = 16

		- I GOIC			-				
Clock Cycle Number	CKE	cs	Command	CA0	CA1	CA2	CA3	CA4	CA5
N A	HIGH	HIGH	Write-1	L	L	H	L	L	L
N+1	HIGH	LOW	vviile- i	L	Н	L	L	L	L
N+2	HIGH	HIGH	CAS-2	L	H	L	L	Н	L
N+3	HIGH	LOW		L	<i>1</i> // L	L	L	L	L
N+4	HIGH	LOW	Deselect	L, I	L	L	L	L	L
N+5	HIGH	LOW	Deselect		L	L	L	L	L
N+6	HIGH	LOW	Deselect		L	L	L	L	L
N+7	HIGH	LOW	Deselect	Ľ	L	L	L	L	L
N+8	HIGH	HIGH	Write-1	L	L	Н	L	L	L
N+9	HIGH	LOW	Wille-1	L	Н	L	L	H	L
N+10	HIGH	HIGH	CAS-2	L	Н	L	L	H	Н
N+11	HIGH	LOW	UA3-2	L	L	Н	H	Н	Н
N+12	HIGH	LOW	Deselect	L	L	L	TD.	L	L
N+13	HIGH	LOW	Deselect	L	L	L	, Φ,	L	L
N+14	HIGH	LOW	Deselect	L	L	L	M, r	L	L
N+15	HIGH	LOW	Deselect	Ĺ	L	L	L L	Ĺ	Ĺ

#### Notes:

- 1. BA[2:0] = 010, CA[9:4] = 000000 or 111111 (Same as LPDDR3 IDD4W Spec.)
- 2. Difference from LPDDR3 Spec:
  - 1-No burst ordering
  - 2-CA pins are kept low with DES CMD to reduce ODT current.

Table — Data pattern for IDD4W (DBI off) for BL = 16

100				DBI OF	F case					No. of 1's
	DQ[7]	DQ[6]	DQ[5]	DQ[4]	DQ[3]	DQ[2]	DQ[1]	DQ[0]	DBI	NO. 01 1 S
BL0	1	1	1	1		1	1	1	0	8
BL1	1	1	1	1	0	0	0	0	0	4
BL2	0	0	0	0	0	0	0	0	0	0
BL3	0	0	0	0	1	1	1	1	0	4
BL4	0	0	0	0	0	0	1	1	0	2
BL5	0	0	0	0	1	1	1	1	0 🔨	4
BL6	1	1	1 / <	1	1	1	0	0	0	6
BL7	1	1	1	1	0	0	0	0	0	4
BL8	1	1	CA	1	1	1	1	1	0	8
BL9	1	1		1	0	0	0	0	0	4
BL10	0	0	0	0	0	0	0	0	0	0
BL11	0	0	0	0	1	1	1	(1) <sup>1</sup>	0	4
BL12	0	0	0	0	0	0	1	ΛĬ	0	2
BL13	0	0	0	0	1	1	1 5	1	0	4
BL14	1	1	1	1	1	1	0	0	0	6
BL15	1	1	1	1	0	0	0	0	0	4
BL16	1	1	1	1	1	1	0	0	0	6
BL17	2-1	1	1	1	0	0 🔾	0	0	0	4
BL18	0	0	0	0	0	0	1	1	0	2
BL19	0	0	0	0	1	O1)	1	1	0	4



BL20	0	0	0	0	0	0	0	0	0	0
BL21	0	0	0	0	1	1	10	1	0	4
BL22	10	1	1	1	1	1		1	0	8
BL23	(1)	1	1	1	0	0	0	0	0	4
BL24	0	0	0	0	0	0 0	× 1	1	0	2
BL25 <	0	0	0	0	1	10	1	1	0	4
BL26	1	1	1	1	1		0	0	0	6
BL27	1	1	1	1	0	0	0	0	0	4
BL28	1	1	1	1	1 ,	1	1	1	0	8
BL29	1	1	1	1	0	0	0	0	0	4
BL30	0	0	0	0	0	0	0	0	0	0
BL31	0	0	0	0	(1)	1	1	1	0	4
No. of 1's	16	16	16	16	16	16	16	16		

#### Notes:

- 1. Simplified pattern compared with last showing.
- 2. Same data pattern was applied to DQ[4], DQ[5], DQ[6], DQ[7] for reducing complexity for IDD4W/R pattern programming.

Table — Data pattern for IDD4R (DBI off) for BL =16

			D	DBI OFF case					>	No of 4's
	DQ[7]	DQ[6]	DQ[5]	DQ[4]	DQ[3]	DQ[2]	DQ[1]	DQ[0]	DBI	No. of 1's
BL0	1	1	1	1	1	1	1	(1)	0	8
BL1	1	N	1	1	0	0	0	0	0	4
BL2	0	0	0	0	0	0	7 0	0	0	0
BL3	0	0	0	0	1	1	1.0-	1	0	4
BL4	0	0	0	0	0	0	<u>(1)</u>	1	0	2
BL5	0	0	0	0	1	1	3	1	0	4
BL6	2	1	1	1	1	1 0	0	0	0	6
BL7	1	1	1	1	0	0	0	0	0	4
BL8	1	1	1	1	1		1	1	0	8
BL9	1	1	1	1	0	0	0	0	0	4
BL10	0	0	0	0	0	0	0	0	0	0
BL11	0	0	0	0	1	1	1	1	0	4
BL12	0	0	0	0	0	0	1	1	0	2
BL13	0	0	0	0	, Oi	1	1	1	0	4
BL14	1	1	1	1	<b>1</b>	1	0	0	0	6
BL15	1	1	1	1	0	0	0	0	0	4
BL16	1	1	1	1	1	1	1	1	0	8
BL17	1	1	1	_ 1	0	0	0	0	0	4
BL18	0	0	0	0	0	0	0	0	0	0
BL19	0	0	0	0	1	1	1	1	0	4
BL20	1	1	1	1	1	1	0	0	0	6
BL21	1	1	Ś	1	0	0	0	0	0	4
BL22	0	0 🗸	0	0	0	0	1	1 🗸	0	2
BL23	0	0	0	0	1	1	1	10	0	4
BL24	0	0	0	0	0	0	0	0	0	0
BL25	0	0	0	0	1	1	1	<b>(</b> ) 1	0	4
BL26	1 (	1	1	1	1	1	1.0	1	0	8
BL27	10	1	1	1	0	0	0	0	0	4
BL28	0	0	0	0	0	0	3	1	0	2
BL29	0	0	0	0	1	1	<u> </u>	1	0	4
BL30	1	1	1	1	1	1	0	0	0	6
BL31	1	1	1	1	0	0	0	0	0	4
No. of 1's	16	16	16	16	16	16	16	16		



#### Notes:

 Same data pattern was applied to DQ[4], DQ[5], DQ[6], DQ[7] for reducing complexity for IDD4W/R pattern programming.

Table — Data pattern for IDD4W (DBI on) for BL = 16

	) ·	Table	Julu	DBI ON	l case	. (33(6)	.,			
$\bigcirc$	DQ[7]	DQ[6]	DQ[5]	DQ[4]	DQ[3]	DQ[2]	DQ[1]	DQ[0]	DBI	No. of 1's
BL0	0	0	0	0	0	0	0	0	1	1
BL1	1	1	1	1	0.	0	0	0	0	4
BL2	0	0	0	0	0	0	0	0	0	0
BL3	0	0	0	0		1	1	1	0	4
BL4	0	0	0	0	0	0	1	1	0	2
BL5	0	0	0	0	1	1	1	1	0	4
BL6	0	0	0	0	0	0	1	1	1	3
BL7	1	1	1	, 1	0	0	0	0	0	4
BL8	0	0	0	0	0	0	0	0	1 🔨	. 1
BL9	1	1	1	/ 1	0	0	0	0	0	4
BL10	0	0	0	0	0	0	0	0	0	0
BL11	0	0	0	0	1	1	1	1	0	4
BL12	0	0 🔏	0	0	0	0	1	1 🔏	0	2
BL13	0	0	0	0	1	1	1	10	0	4
BL14	0	0	0	0	0	0	1	(1)	1	3
BL15	1		1	1	0	0	0	0	0	4
BL16	0	0	0	0	0	0	1	1	1	3
BL17	1	1	1	1	0	0	0	0	0	4
BL18	0	0	0	0	0	0	C	1	0	2
BL19	0	0	0	0	1	1	N 1	1	0	4
BL20	0	0	0	0	0	0	0	0	0	0
BL21	0	0	0	0	1	1	1	1	0	4
BL22	0	0	0	0	0	0	0	0	1	1
BL23	1	1	1	11	0	0	0	0	0	4
BL24	0	0	0	0	0	0	1	1	0	2
BL25	0	0	0	0	10	1	1	1	0	4
BL26	0	0	0	0	0	0	1	1	1	3
BL27	1	1	1	1	0	0	0	0	0	4
BL28	0	0	0	0	0	0	0	0	1	1
BL29	1	1	1	11	0	0	0	0	0	4
BL30	0	0	0	0	0	0	0	0	0	0
BL31	0	0	0	0	1	1	1	1	0	4
No. of 1's	8	8	8	8	8	8	16	16	8	

#### Notes:

1. Green colored cells are DBI enabled burst.



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Table — Data pattern for IDD4R (DBI on) for BL = 16

	DBI ON case									
	DQ[7]	DQ[6]	DQ[5]	DQ[4]	DQ[3]	DQ[2]	DQ[1]	DQ[0]	DBI	No. of 1's
BL0	0	0	0	0	0	0	0	0	1	1
BL1	21	1	1	1	0	0 0	0	0	0	4
BL2	0	0	0	0	0	0	0	0	0	0
BL3	0	0	0	0	1	<u> </u>	1	1	0	4
BL4	0	0	0	0	0	0	1	1	0	2
BL5	0	0	0	0	1	<b>1</b>	1	1	0	4
BL6	0	0	0	0	0	0	1	1	1	3
BL7	1	1	1	1	0	0	0	0	0	4
BL8	0	0	0	0	0	0	0	0	1	1
BL9	1	1	1	1	<b>V</b> 0	0	0	0	0	4
BL10	0	0	0	0	0	0	0	0	0	0
BL11	0	0	0	0	1	1	1	1	0	4
BL12	0	0	0	0	0	0	1	1	0	2
BL13	0	0	0	0	1	1	1	1	0	4
BL14	0	0	0	0	0	0	1	1	1/	3
BL15	1	1	1	1	0	0	0	0	0	4
BL16	0	0	0	0	0	0	0	0	<b>5</b> 1	1
BL17	1	1 1	1	1	0	0	0	0	0	4
BL18	0	0	0	0	0	0	0	0	0	0
BL19	0	0	0	0	1	1	1	1)	0	4
BL20	0	0	0	0	0	0	1	<b>U</b> 1	1	3
BL21	1 0	1	1	1	0	0	0	0	0	4
BL22	0	0	0	0	0	0	10	1	0	2
BL23	0	0	0	0	1	1	<u>G</u>	1	0	4
BL24	0	0	0	0	0	0	<b>X</b> 0	0	0	0
BL25	0	0	0	0	1	1	1	1	0	4
BL26	0	0	0	0	0	0	0	0	1	1
BL27	1	1	1	1	0	0	0	0	0	4
BL28	0	0	0	0	0	0	1	1	0	2
BL29	0	0	0	0	1 (	1	1	1	0	4
BL30	0	0	0	0	0	0	1	1	1	3
BL31	1	1	1	1	0	0	0	0	0	4
No. of 1's	8	8	8	8	8	8	16	16	8	

## Notes:

1. Green colored cells are DBI enabled burst.



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## 1.3.2 IDD Specifications

IDD values are for the entire operating voltage range, and all of them are for the entire standard range, with the exception of IDD6ET which is for the entire extended temperature range.

Table — IDD Specification Parameters and Operating Conditions-Single Die

Parameter/Condition	Symbol			R4-3733	Units	Notes
Parameter/condition	Symbol	rower Supply	85 °C	95 °C	Units	Notes
Operating one bank active-precharge	IDD01	VDD1	4.00	5.56	mA	
current: tCK = tCKmin; tRC = tRCmin;	IDD02	VDD2	29.00	39.06	mA	
CKE is HIGH;	•					
CS is LOW between valid commands;						
CA bus inputs are switching;	IDD0Q	VDDQ	0.75	0.82	mA	3
Data bus inputs are stable;						
ODT disabled						
Idle power-down standby current:	IDD2P1	VDD1	1.10	1.13	mA	
tCK = tCKmin;	IDD2P2	VDD2	1.80	2.97	mA	
CKE is LOW;				"O <sub>1</sub>		
CS is LOW;				in.		
All banks are idle;	IDD2PQ	VDDQ	0.70	0.00	mA	3
CA bus inputs are switching;	IDDZFQ	VDDQ	0.75	0.82	IIIA	3
Data bus inputs are stable;			RIV			
ODT disabled			5			
Idle power-down standby current with clock stop:	IDD2PS1	VDD1	1.10	1.13	mA	
CK_t =LOW, CK_c =HIGH;	IDD2PS2	VDD2	1.80	2.97	mA	
CKE is LOW;		O.F.				
CS is LOW;	•	~				
All banks are idle;	IDD2PSQ	VDDQ	0.75	0.82	mA	3
CA bus inputs are stable;						
Data bus inputs are stable						
ODT is disabled.					( ·	
Idle non power-down standby current:	IDD2N1	VDD1	1.20	1.24	mA	
tCK = tCKmin; CKE is HIGH; CS is LOW;	IDD2N2	VDD2	16.00	23.19	mA	
CKE is HIGH;				<sup>7</sup> O,		
			O.P.	H.		
All banks are idle;	IDD2NQ	VDDQ	0.75	0.82	mA	3
CA bus inputs are switching;			0.75	3.02		
Data bus inputs are stable			R			
ODT is disabled.			N .			



				A		
Parameter/Condition	Symbol	Power Supply	LPDD	R4-3733	Units	Notes
	<b>,</b>	The same of the sa	85 °C	95 °C		
Idle non power-down standby current with clock stopped:	IDD2NS1	VDD1	1.20	1.24	mA	
CK_t=LOW; CK_c=HIGH;	IDD2NS2	VDD2	10.00	15.70	mA	
CKE is HIGH;		P	)			
CS is LOW;		. NV.				
All banks are idle;	IDD2NSQ	VDDQ	0.75	0.82	A	3
CA bus inputs are stable;	IDDZINGQ	OVDDQ	0.70	0.02	mA	3
Data bus inputs are stable		~				
ODT disabled						
Active power-down standby current:	IDD3P1	VDD1	1.10	1.13	mA	
tCK = tCKmin;	IDD3P2	VDD2	4.80	7.42	mA	
CKE is LOW;				· S		
CS is LOW;				1 A		
One bank is active;	IDD3Po	VDDQ	0.75	0000	mA	3
CA bus inputs are switching;	IDD3FQ	VDDQ	0.75	0.82	IIIA	3
Data bus inputs are stable			RI			
ODT disabled			60,			
Active power-down standby current with clock stop:	IDD3PS1	VDD1	1.10	1.13	mA	
CK_t=LOW, CK_c=HIGH;	IDD3PS2	VDD2	4.80	7.51	mA	
CKE is LOW;		(8)				
CS is LOW;		M,				
One bank is active;	IDD3PSq	VDDQ	0.75	2.00	m A	4
CA bus inputs are stable;	IDDSFSQ	VDDQ	0.75	0.82	mA	4
Data bus inputs are stable		_				•
ODT disabled						
Active non-power-down standby current:	IDD3N1	VDD1	1.50	1.55	mA	
tCK = tCKmin;	IDD3N2	VDD2	21.00	30.00	mA	
CKE is HIGH;				S	Ť	
tCK = tCKmin; CKE is HIGH; CS is LOW;				XX		
One bank is active;	IDD3NQ	VDDQ	^ <b>7</b> 5	, Or	m ^	4
CA bus inputs are switching:	אונטטווע	VDDQ	0.75	0.82	mA	4
Data bus inputs are stable			SPY			
ODT disabled			5			



	•					
Parameter/Condition	Symbol	Power Supply	LPDD	R4-3733	Units	Notes
r al ameter/condition	Symbol	rower Supply	85 °C	95 °C	Units	NOICS
Active non-power-down standby current with clock stopped:	IDD3NS1	VDD1	1.50	1.55	mA	
CK_t=LOW, CK_c=HIGH;	IDD3NS2	VDD2	15.00	22.87	mA	
CKE is HIGH;						
CS is LOW;		NB.				
One bank is active;	IDD3NSQ	VDDQ	0.75	0.82		4
CA bus inputs are stable;	IDDSNSQ	VDDQ	0.75	0.62	mA	4
Data bus inputs are stable						
ODT disabled					<b>X</b>	
Operating burst READ current:	IDD4R1	VDD1	2.50	3.13	mA	
tCK = tCKmin;	IDD4R2	VDD2	263.00	288.95	mA	
CS is LOW between valid commands;				- XP		
One bank is active;				OR'		
BL = 16 or 32; RL = RL(MIN);	IDD4RQ	VDDQ	04.57	<b>1</b>	mA	5
CA bus inputs are switching;	IDD4KQ	VDDQ	61.57	81.07	IIIA	5
50% data change each burst transfer			co,			
ODT disabled.						
Operating burst WRITE current:	IDD4W1	VDD1	1.50	1.73	mA	
tCK = tCKmin;	IDD4W2	VDD2	195.00	222.68	mA	
CS is LOW between valid commands;						
One bank is active;		Mr.				
BL = 16 or 32; WL = WLmin;	IDD4WQ	VDDQ	0.75	0.00	mA	1
CA bus inputs are switching;	IDD4WQ	VDDQ	0.75	0.82	IIIA	7
50% data change each burst transfer						
ODT disabled						
All-bank REFRESH Burst current:	IDD51	VDD1	9.00	11.59	mΑ	
tCK = tCKmin;	IDD52	VDD2	90.00	110.08	mA	
CKE is HIGH between valid commands;				(6)		
tRC = tRFCabmin;				N.		
Burst refresh;	IDD5Q	VDDQ	0.75	0.82	mA	4
CA bus inputs are switching;	.2304	,,,,,	0.75	0.02	,	
Data bus inputs are stable;			OR'			
ODT disabled			.5			



						,
Parameter/Condition	Symbol	Power Supply	LPDDI	R4-3733	Units	Notes
T drameter/oblidition	Cymbol	1 ower ouppry	85 ℃	95 °C	Oiiits	Notes
All-bank REFRESH Average current:	IDD5AB1	VDD1	1.70	1.85	mA	
tCK = tCKmin;	IDD5AB2	VDD2	22.00	30.21	mA	
CKE is HIGH between valid commands;			<u> </u>			
tRC = tREFI;		(8)				
CA bus inputs are switching;	IDD5ABQ	VDDQ	0.75	0.82	mA	4
Data bus inputs are stable;		TO.				
ODT disabled		O,				
Per-bank REFRESH Average current:	IDD5PB1	VDD1	1.70	1.85	mA	
tCK = tCKmin;	IDD5PB2	VDD2	22.00	30.21	mA	
CKE is HIGH between valid commands;						
tRC = tREFI/8;					<b>\\</b>	
CA bus inputs are switching;	IDD5PBQ	VDDQ	0.75	0.82	mA	4
Data bus inputs are stable;				1/kg		
ODT disabled				OK		
Self refresh current (85 °C / 95 °C):	IDD61	VDD1	1.50	1.55	mA	6,7,9
CK_t=LOW, CK_c=HIGH;	IDD62	VDD2	6.00	14.42	mA	6,7,9
CKE is LOW;			S			
CA bus inputs are stable;	IDD6Q	VDDQ	0.75	0.82	mA	4,6,7,9
Data bus inputs are stable;	.5504		0.73	0.02		1,0,1,0
ODT disabled			,			
Self refresh current (25 °C):	IDD61	VDD1	0.19	0.19	mA	6,7,9
CK_t=LOW, CK_c=HIGH;	IDD62	VDD2	0.46	0.46	mA	6,7,9
CKE is LOW;		Of				
CA bus inputs are stable;	IDD6Q	VDDQ	0.64	0.04	m. Λ	4670
Data bus inputs are stable;	אסחחו	VDDQ	0.01	0.01	mA	4,6,7,9
ODT disabled						
		l				

#### Notes:

- 1. Published IDD values are the maximum of the distribution of the arithmetic mean.
- 2. ODT disabled: MR11[2:0] = 000B.
- 3. IDD current specifications are tested after the device is properly initialized.
- 4. Measured currents are the summation of VDDQ and VDD2.
- 5. Guaranteed by design with output load = 5pF and RON = 40 ohm.
- 6. This is the general definition that applies to full array Self Refresh.
- 7. Supplier datasheets may contain additional Self Refresh IDD values for temperature subranges within the Standard or elevated Temperature Ranges.
- 8. For all IDD measurements, VIHCKE = 0.8 x VDD2, VILCKE = 0.2 x VDD2.
- 9. IDD6 95°C is guaranteed, IDD6 25/105°C is typical of the distribution of the arithmetic mean.
- 10. IDD6ET is a typical value, is sampled only, and is not tested.



## 1.3.3 AC Timing Parameters

#### **Table — Core Parameters**

Parameter	Symbol	min/ max	Data Rate 533 1066 1600 2133 2667 3200 3733 426	Unit	Note
ACTIVE to ACTIVE command period	tRC	min	tRAS + tRPab (with all-bank precharge) tRAS + tRPpb (with per-bank precharge)	ns	
Minimum Self-Refresh Time (Entry to Exit)	tSR	min	max(15ns, 3nCK)	ns	
Self Refresh exit to next valid command delay	$1 \text{ fXSR} \text{ I min } \text{I} \text{ may} \text{ fRFCah} \pm 7 \text{ 5nc } 2\text{n}$		max(tRFCab + 7.5ns, 2nCK)	ns	(
Exit power down to next valid command delay	tXP	min	max(7.5ns, 5nCK)	ns	
CAS to CAS delay	tCCD	min	8	tCK(avg	
S to CAS delay (Masked Write w/ECC) tCCDMW		min	32	tCK(avg	
Internal Read to Precharge command delay			max(7.5ns, 8nCK)	ns	
RAS to CAS Delay	tRCD	min	max(18ns, 4nCK)	ns	
Row Precharge Time (single bank)	tRPpb	min	max(18ns, 3nCK)	ns	
Row Precharge Time (all banks) - 8-bank	tRPab	min	max(21ns, 3nCK)	ns	
Day Active Time	4D A C	min	max(42ns, 3nCK)	ns	
Row Active Time	tRAS	max	min(9 * tREFI * Refresh Rate, 70.2)	us	
Write Recovery Time	tWR	min	max(18ns, 4nCK)	ns	
Write to Read Command Delay	tWTR	min	max(10ns, 8nCK)	ns	
Active bank A to Active bank B	tRRD	min	max(10ns, 4ncK)  max(10ns, 4ncK)  max 7.5i s,4i CK	ns ns	1
Precharge to Precharge Delay	tPPD	min	4	tCK	2
Four Bank Activate Window tFAW min		40 30	ns	1	
Delay from SRE command to CKE input LOW	tESCKE	min	max(1.75ns, 3nCK)		3
Notos:					

#### Notes:

- 1. 4267 Mbps timing value is supported at lower data rates if the device is supporting 4266 Mbps speed grade.
- 2. Precharge to precharge timing restriction does not apply to Auto-Precharge commands.
- 3. Delay time has to satisfy both analog time (ns) and clock count (nCK). It means that tESCKE will not expire until CK has toggled through at least three full cycle (3 tCK) and 1.75ns has transpired. The case which 3nCK is applied to is shown below.



## Table — Clock timings

SHE	Г	00811PI	M2FDGL	JK(W)-U	/ B1621	PM2FD0	GUK(W)	-U
ORAM DATA			timings		AND P		<i>3</i>	
Parameter	Symbol	min/max	LPDDR4 1600	LPDDR4 3200	LPDDR4 3733	LPDDR4 4267	Unit	Note
Average Clock Period	tCK(avg)	min	1.25	0.625	0.535	0.468	ns	
Average Glock Feriod	tort(avg)	max	100	100	100	100	113	
Average high pulse width	tCH(avg)	tCH(avg) min 0.46					tCK(avg	
The sage many part of the sage many	1011(4119)	max		0.	54		)	
Average low pulse width	tCL(avg)	min		0.	46		tCK(avg	
The state of the s	(3.19)	max		0.	54		)	
Absolute Clock Period	tCK(abs)	min	tCK	(avg)min	+ tJIT(per)	min	ps	
Absolute clock HIGH pulse width	tCH(abs)	min		0.	43		tCK(avg	
Absolute clock File Figure Width	tori(abs)	max		0.	57		)	
Absolute clock LOW pulse width	tCL(abs)	min		0.	43	S	tCK(avg	
Absolute clock LOW pulse width	iCL(abs)	max		0.	57		)	
Clock Period Jitter	tJIT(per)	min	-70	-40	-34	-30	nc	
Clock Fellod Sitter	ion (per)	max	70	40	34	30	ps	
Maximum Clock Jitter between two	tJIT(cc)	min		A S			ne	
consecutive clock cycles	(CC)	max	140	80	68	60	ps	

## Table — ZQ Calibration timings

Parameter	Symbol	min/max		. 1	LI	PDDR4	Data F	Rate			Unit	Note
Na.	Symbol	IIIIII/IIIax	533   1066   1600   2133   2667   3200   3733   4267							Offic	NOIG	
ZQ Calibration Time	tZQCAL	min	1								us	
ZQ Calibration Latch Quiet Time	tZQLAT	min			r	nax(30	ns, 8nC	CK)			ns	
Calibration Reset Time	tZQRESET	min			r	nax(50	ns, 3nC	CK)			ns	
PODRASDRAMOR	KASHER				S	JOR <sup>C</sup>	s OP	AM	DATP	SKE		
Kingston	*		Document No.								48109	83B-01B



## Table —DQ Tx Voltage and Timings (Read Timing parameters)

	1			522/ 2200/					
Parameter	Symbol	min/ max	533/ 1066/ 1600	2133/ 2667	3200/ 3733/ 4267	Unit	Note		
Data Timing		0	)						
DQS_t,DQS_c to DQ Skew	tDQSQ	max		0.18		UI	6		
DQ output hold time total from DQS_t, DQS_c (DBI-Disabled)	tQH	min	min	(tQSH, tC	QSL)	ps	6		
DQ output window time total, per pin (DBI- Disabled)	tQW_total	total min 0.75 0.73 0.70		UI	6,11				
DQS_t, DQS_c to DQ Skew total, per group, per access (DBI-Enabled)	tDQSQ_DBI	max		0.18		UI	6		
DQ output hold time total from DQS_t, DQS_c (DBlenabled)	tQH_DBI	min	min(tQS	H_DBI, tC	QSL_DBI)	ps	6		
DQ output window time total, per pin (DBI-enabled)	tQW_total_DBI	min	0.75	0.73	0.70	UI	6,11		
Read preamble	tRPRE	min		1.8	1/R	tCK(avg)			
Read postamble	tRPST	min		0.4	P	tCK(avg)			
Extended Read postamble	tRPSTE	min		1.4					
DQS Low-impedance time from CK_t, CK_c	tLZ(DQS)	min	(RL x tCK) + tDQSCK(Min) - (tPRE(Max) x tCK) - 200ps		ps				
DQS High-impedance time from CK_t, CK_c	tHZ(DQS)	max	+ (BL/2 x		SCK(Max) K) -	ps			
DQ Low-impedance time from CK_t, CK_c	tLZ(DQ)	min	(RL x tC	K) + tDQ3 - 200ps	SCK(Min)	ps			
DQ High-impedance time from CK_t, CK_c	tHZ(DQ)	max	+ tDQS	K) + tDQS GQ(Max)+ CK) - 100		ps			
Data Strobe Timing									
DOS output access time from CV/CV#	+DOSCK	min		1.5		60	1		
DQS output access time from CK/CK#	tDQSCK	max		3.5		ns	1		
DQSCK Temperature Drift	tDQSCK_temp	max		4		ps/°C	3		
DQSCK Volgate Drift	tDQSCK_volt	max		7	1 DO	ps/mV	2		
CK to DQS Rank to Rank variation	tDQSCK_rank2rank	max		1	D.	ns	4,5		
DQS Output Low Pulse Width (DBI Disabled)	tQSL	min	tC	L(abs)-0.	05	tCK(avg)	9,11		
DQS Output High Pulse Width (DBI Disabled)	tQSH	min	tCH(abs)-0.05		tCK(avg)	10.,11			
DQS Output Low Pulse Width (DBI Enabled)	tQSL_DBI	min	tC	2		tCK(avg)	9,11		
DQS Output High Pulse Width (DBI Enabled)	tQSH_DBI	min	tCI	H(abs)-0.0	045	tCK(avg)	10,11		
134	1		1.34				i .		



#### Notes:

- 1. Includes DRAM process, voltage and temperature variation. It includes the AC noise impact for frequencies > 20 MHz and max voltage of 45 mV pk-pk from DC-20 MHz at a fixed temperature on the package. The voltage supply noise must comply to the component Min-Max DC Operating conditions.
- 2. tDQSCK\_volt max delay variation as a function of DC voltage variation for VDDQ and VDD2. tDQSCK\_volt should be used to calculate timing variation due to VDDQ and VDD2 noise < 20 MHz. Host controller do not need to account for any variation due to VDDQ and VDD2 noise > 20 MHz. The voltage supply noise must comply to the component Min-Max DC Operating conditions. The voltage variation is defined as the Max[abs{tDQSCKmin@V1-tDQSCKmax@V2}, abs{tDQSCKmax@V1-tDQSCKmin@V2}] / abs{V1-V2}. For tester measurement VDDQ = VDD2 is assumed.
- 3. tDQSCK\_temp max delay variation as a function of Temperature.
- 4. The same voltage and temperature are applied to tDQS2CK\_rank2rank.
- tDQSCK\_rank2rank parameter is applied to multi-ranks per byte lane within a package consisting of the same design dies
- 6. DQ to DQS differential jitter where the total includes the sum of deterministic and random timing terms for a specified BER.
- 7. The deterministic component of the total timing.
- 8. This parameter will be characterized and guaranteed by design.

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- 9. tQSL describes the instantaneous differential output low pulse width on DQS\_t DQS\_c, as measured from on falling edge to the next consecutive rising edge.
- 10. tQSH describes the instantaneous differential output high pulse width on DQS\_t DQS\_c, as measured from on falling edge to thenext consecutive rising edge.
- 11. This parameter is function of input clock jitter. These values assume the min tCH(abs) and tCL(abs). When the input clock jitter min tCH(abs) and tCL(abs) is 0.44 or greater than tCK(avg), the min value of tQSL will be tCL(abs)-0.04 and tQSH will be tCH(abs)-0.04.
- 12. UI=tCK(avg)min/2\_

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## Table — DQ Tx Voltage and Timings (Write Timing parameters)

Parameter	Symbol	min/max		2133/ 2400		4267	Unit	Note
Rx Mask voltage p-p total	VdIVW_total	max	140	140	140	120	mV	1,2,3,5
Rx Mask voltage - deterministic	VdIVW_dV	max	TBD	TBD	TBD	TBD	mV	1,5
Rx timing window total (At VdIVW voltage levels)	TdIVW_total	max	0.22	0.22	0.25	0.25	UI	1,2,4,5
Rx deterministic timing	TdIVW_dj	max	TBD	TBD	TBD	TBD	UI	1,5
Rx timing window 1bit toggle (At VdIVW voltage levels)	TdIVW_1bit	max	TBD	TBD	TBD	TBD	UI	1,2,4,5,14
DQ AC input pulse amplitude p-p	VIHIL_AC	min	180	180	180	170	mV	7,15
DQ input pulse width (At Vcent_DQ)	TdIPW	min	0.45	0.45	0.45	0.45	UI	10
DO to DOS offeet	TDOS2DO	min	200	200	200	200		0
DQ to DQS offset	TDQS2DQ	max	800	800	800	800	ps	9
DQ to DQ offset	TDQDQ	max	30	30	30	30	ps	10
DQ to DQS offset temperature variation	TDQS2DQ_temp	max	0.6	0.6	0.6	0.6	ps/°C	11
DQ to DQS offset voltage variation	TDQS2DQ_volt	max	33	33	33	33	ps/50mV	12
DQ to DQS offset rank to rank	TDQS2DQ_rank2rank	max	200	200	200	200	ps	17,18
Write command to 1st DQS latching	tDQSS	min	C	0.	75		tCK(avg)	
transition	เปิดจิจ	max	N N	1.	25		ick(avg)	
DQS input high-level width	tDQSH	min		0	.4		tCK(avg)	
DQS input low-level width	tDQSL	min		0	.4		tCK(avg)	
DQS falling edge to CK setup time	tDSS	min		0	.2		tCK(avg)	
DQS falling edge hold time from CK	tDSH	min		0	.2		tCK(avg)	
Write preamble	tWPRE	min		1	.8		tCK(avg)	
0.5 tCK Write postamble	tWPST	min		0	.4		tCK(avg)	
1.5 tCK Write postamble	tWPSTE	min		1	.4		tCK(avg)	
Input slew rate over VdIVW_total	✓ SRIN_dIVW	min	1	1	1	1	V/ns.	13
p. 1. c.c	S. a. t_a. v v v	max	7	7	7	7	7,110	

#### Notes:

- 1. Data Rx mask voltage and timing parameters are applied per pin and includes the DRAM DQ to DQS voltage AC noise impact for frequencies >250KHz at a fixed temperature on the package. The voltage supply noise must comply to the component Min-Max DC operating conditions.
- 2. The design specification is a BER <tbd. The BER will be characterized and extrapolated if necessary using a dual dirac method.
- 3. Rx mask voltage VdIVW total(max) must be centered around Vcent\_DQ(pin\_mid).
- 4. Rx differential DQ to DQS jitter total timing window at the VdIVW voltage levels.
- 5. Defined over the DQ internal Vref range. The Rx mask at the pin must be within the internal Vref DQ range irrespective of the input signal common mode.
- 6. Deterministic component of the total Rx mask voltage or timing. Parameter will be characterized and guaranteed by design. Measurement method TBD



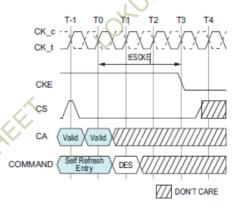
- 7. DQ only input pulse amplitude into the receiver must meet or exceed VIHL AC at any point over the total UI. No timing requirement above level. VIHL AC is the peak to peak voltage centered around Vcent\_DQ(pin\_mid) such that IHL\_AC/2 min must be met both above and below Vcent\_DQ.
- 8. DQ only minimum input pulse width defined at the Vcent\_DQ(pin\_mid).
- 9. DQ to DQS offset is within byte from DRAM pin to DRAM internal latch. Includes all DRAM process, voltage and temperature variation.
- 10. DQ to DQ offset defined within byte from DRAM pin to DRAM internal latch for a given component.
- 11. TDQS2DQ max delay variation as a function of temperature.
- 12. TDQS2DQ max delay variation as a function of the DC voltage variation for VDDQ and VDD2.
- 13. Input slew rate over VdIVW Mask centered at Vcent\_DQ(pin\_mid).
- 14. Rx mask defined for a one pin toggling with other DQ signals in a steady state.
- 15. VIHL\_AC does not have to be met when no transitions are occurring.
- 16. UI=tCK(avg)min/2
- 17. The same voltage and temperature are applied to tDQS2DQ\_rank2rank
- 18. tDQS2DQ\_rank2rank parameter is applied to multi-ranks per byte lane within a package consisting of the same design dies.
- A. The following Rx voltage and timing requirements apply for all DQ operating frequencies at or below 1600 for all speed bins. The timing parameters in UI can be converted to absolute time values where tck(avg)min/2= 625ps for DQ=1600. For example the TdIVW\_total(ps) =0.22\*625ps= 137.5ps.

## Table — Self-Refresh Timing Parameters

Parameter	O was la a l		Data Rate	Linit	Nista
	Symbol	min/max	533 1066 1600 2133 2667 3200 3733 4267	Unit	Note
Delay from Self Refresh Entry to CKE Input Low	tESCKE	min	max(1.75ns,3tCK)	nCK	1
Minimum Self-Refresh Time (Entry to Exit)	tSR	min	max(15ns, 3nCK)	ns	1
Self refresh exit to next valid command delay	tXSR	min	max(tRFCab + 7.5ns, 2nCK)	ns	1,2

#### Note

1. Delay time has to satisfy both analog time(ns) and clock count(tCK). It means that tESCKE will not expire until CK has toggled through at least 3 full cycles (3 \*tCK) and 1.75ns has transpired. The case which 3tCK is applied to is shown below.



2. MRR-1, CAS-2, SRX, MPC, MRW-1, and MRW-2 commands (except PASR bank/segment setting) are only allowed during this period.



## Table — Command Address Input Parameters

Parameter	Symbol	min/ max	DQ-1333 <sup>A)</sup>	DQ-1600/ 1867	DQ-3200	DQ-4266	Unit	Note
Rx Mask voltage p-p	VcIVW	max	175	175	155	145	mV	1,2,4
Rx timing window	tcIVW	max	0.3	0.3	0.3	0.3	UI	1,2,3,4
CA AC input pulse amplitude pk-pk	VIHL_AC	min	210	210	190	180	mV	5,8
CA input pulse width	TcIPW	min	0.55	0.55	0.6	0.6	UI	6
Input clow rate ever VolV/M	SRIN cIVW	min		1	1	1	V/ns	7
Input slew rate over VcIVW	SKIIN_CIVW	max	7	7	7	7	V/HS	,

#### Notes:

- 1. CA Rx mask voltage and timing parameters at the pin including voltage and temperature drift.
- 2. Rx mask voltage VcIVW total(max) must be centered around Vcent\_CA(pin mid).
- 3. Rx differential CA to CK jitter total timing window at the VcIVW voltage levels.
- 4. Defined over the CA internal Vref range. The Rx mask at the pin must be within the internal Vref CA range irrespective of the input signal common mode.
- 5. CA only input pulse signal amplitude into the receiver must meet or exceed VIHL AC at any point over the total UI. No timing requirement above level. VIHL AC is the peak to peak voltage centered around Vcent\_CA(pin mid) such that VIHL AC/2 min must be met both above and below Vcent CA.
- 6. CA only minimum input pulse width defined at the Vcent\_CA(pin mid).
- 7. Input slew rate over VcIVW Mask centered at Vcent\_CA(pin mid).
- 8. VIHL\_AC does not have to be met when no transitions are occurring.
- 9. UI=tCK(avg)min
- A. The following Rx voltage and timing requirements apply for DQ operating frequencies at or below 1333 for all speed bins. The timing parameters in UI can be converted to absolute time values where tck(avg)min= 1.5ns for DQ=1333. For example the TcIVW(ps) = 0.3\*1.5ns=450ps.

#### Table — Boot Parameters

Parameter	Symbol	min/ Data Rate							Linit	Note		
3	Symbol	max	533	1066	1600	2133	2667	3200	3733	4267	O I II	Note
Clock Cycle Time	tCKb	min	5			1	8				20	
Clock Cycle Time	ICND	max				10	00				ns	
DQS Output Data Access Time from	tDQSCKb	min				,	1				ns	
CK/CK#	IDQSCRD	max				1	0			>	110	
Data Strobe Edge to Output Data Edge tDQSQb	tDQSQb	max				1.	.2				ns	



	SHEV		D0811PM2FDGUK(W)-U / B1621PM2FDGU	K(W)	)-U
- AMDAT,	Table –	le Register Parameters			
Parameter	Symbol	min/ max	Data Rate           533         1066         1600         2133         2667         3200         3733         4267	Unit	Note
Additional time after tXP has expired until the MRR command may be issued	tMRRI	min	tRCD + 3nCK	ns	
MODE REGISTER Write command period	tMRW	min	max(10ns, 10nCK)	ns	
MODE REGISTER Read command period	tMRR	min	8	nCK	
Mode Register Write Set Command Delay	tMRD	min	max(14ns, 10nCK)	ns	

## Table — VRCG Enable/Disable Timing

Parameter	Symbol	min/				Data	Rate		Ċ	H	Unit	Noto
	Symbol	max	533	1066	1600	2133	2667	3200	3733	4267	Offic	Note
VREF high current mode enable time	tVRCG_Enable					20	0	.0	>,		ns	
VREF high current mode disable time	tVRCG_Disabl e	max				10	0	W.			ns	
JM LPDDPASD.				141	PO	RA						



## Table — Command Bus Training Parameters

Parameter	Symbol	min/ max	Data Rate 533   1066   1600   2133   2667   3200   3733   4267	Unit	Note
Valid Clock Requirement after CKE Input Low	tCKELCK	min	max(5ns, 5nCK)	-	
Data Setup for Vref Training Mode	tDStrain	min	2	ns	
Data Hold for Vref Training Mode	tDHtrain	min	2	ns	
Asynchronous Data Read	tADR	max	<i>[11</i> 20	ns	
CA Bus Training Command to CA Bus Training command Delay	tCACD	min	RU(tADR/tCK)	tCK	2
Valid Strobe Requirement before CKE Low	tDQSCKE	min	10	ns	1
First CA Bus Training Command Following CKE Low	tCAENT	min	250	ns	
Vref Step Time – multiple steps	tVref_long	max	250	ns	
Vref Step Time – one step	tVref_short	max	80	ns	
Valid Clock Requirement before CS High	tCKPRECS	min	2*tCK + tXP	1	
Valid Clock Requirement after CS High	tCKPSTCS	min	max(7.5ns, 5nCK)		
Minimum delay from CS to DQS toggle in command bus training	tCS_Vref	min	211	tCK	
Minimum delay from CKE High to Strobe High Impedance	tCKEHDQ S	min	5010	ns	
Valid Clock Requirement before CKE Input High	tCKCKEH	min	max(1.75ns, 3nCK)	-	
CA Bus Training CKE High to DQ Tri-state	tMRZ	min	1.5	ns	
ODT turn-on latency from CKE	tCKELODT on	min	20	ns	
ODT turn-off latency from CKE	tCKELODT off	min	20	ns	

#### Notes:

- 1. DQS\_t has to retain a low level during tDQSCKE period, as well as DQS\_c has to retain a high level.
- 2. If tCACD is violated, the data for samples which violate tCACD will not be available, except for the last sample (where tCACD after this sample is met). Valid data for the last sample will be available after tADR.



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## Table — Write Leveling Parameters

Cymbol	min/			Data	Rate			Linit	Note
Symbol	max	1600	2133	2400	3200	3733	4267	Offic	Note
tWLDQSEN	min		$\sim$	OP 2	0			tCK	
tWLWPRE	min			2	0			tCK	
tWLMRD	min	OK.	714	4	0			tCK	
t\\\/ \	min			(	)			nc	
TVVLO	max			2	0			113	
tCKPRDQS	min			max(7.5n	ns, 4nCK)		į	<	
tCKPSTDQS	min			max(7.5n	ns, 4nCK)				
tWLH	min	150	100	100	75	62.5	50	ps	1,2
tWLS	min	150	100	100	75	62.5	50	ps	1,2
tWLIVW_Total	min	240	160	160	120	105	90	ps	1,2
	tWLWPRE tWLMRD tWLO tCKPRDQS tCKPSTDQS tWLH tWLS	tWLDQSEN min  tWLWPRE min  tWLMRD min  tWLO min  tWLO min  tCKPRDQS min  tCKPSTDQS min  tWLH min  tWLS min	tWLDQSEN min  tWLWPRE min  tWLMRD min  tWLO min  tCKPRDQS min  tCKPSTDQS min  tWLH min 150  tWLS min 1600	Symbol         max         1600         2133           tWLDQSEN         min            tWLWPRE         min            tWLMRD         min            tWLO         min            tCKPRDQS         min            tCKPSTDQS         min            tWLH         min         150         100           tWLS         min         150         100	Symbol         max         1600         2133         2400           tWLDQSEN         min         2           tWLWPRE         min         4           tWLMRD         min         0           tWLO         min         0           tCKPRDQS         min         max(7.5r           tCKPSTDQS         min         max(7.5r           tWLH         min         150         100         100           tWLS         min         150         100         100	Symbol         max         1600         2133         2400         3200           tWLDQSEN         min         20           tWLWPRE         min         40           tWLMRD         min         0           tWLO         min         0           tCKPRDQS         min         max(7.5ns, 4nCK)           tCKPSTDQS         min         max(7.5ns, 4nCK)           tWLH         min         150         100         100         75           tWLS         min         150         100         100         75	Symbol         max         1600         2133         2400         3200         3733           tWLDQSEN         min         20           tWLWPRE         min         40           tWLO         min         0           tCKPRDQS         min         max(7.5ns, 4nCK)           tCKPSTDQS         min         max(7.5ns, 4nCK)           tWLH         min         150         100         100         75         62.5           tWLS         min         150         100         100         75         62.5	Symbol         max         1600         2133         2400         3200         3733         4267           tWLDQSEN         min         20           tWLWPRE         min         40           tWLO         min         0           tWLO         max         20           tCKPRDQS         min         max(7.5ns, 4nCK)           tCKPSTDQS         min         max(7.5ns, 4nCK)           tWLH         min         150         100         100         75         62.5         50           tWLS         min         150         100         100         75         62.5         50	Symbol         max         1600         2133         2400         3200         3733         4267         Unit           tWLDQSEN         min         20         tCK           tWLWPRE         min         20         tCK           tWLMRD         min         0         ns           tWLO         min         0         ns           tCKPRDQS         min         max(7.5ns, 4nCK)         max(7.5ns, 4nCK)           tCKPSTDQS         min         min         150         100         100         75         62.5         50         ps           tWLS         min         150         100         100         75         62.5         50         ps

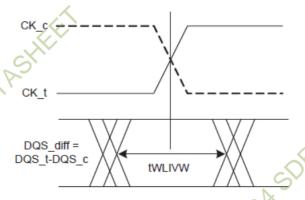
#### Notes:

- 1. In addition to the traditional setup and hold time specifications above, there is value in a invalid window based specification for write-leveling training. As the training is based on each device, worst case process skews for setup and hold do not make sense to close timing between CK and DQS.
- 2. tWLIVW\_Total is defined in a similar manner to tdIVW\_Total, except that here it is a DQS invalid window with respect to CK. This would need to account for all VT (voltage and temperature) drift terms between CK and DQS within the DRAM that affect the write-leveling invalid window.

The DQS input mask for timing with respect to CK is shown in the following figure. The "total" mask (TdiVW\_total) defines the time the input signal must not encroach in order for the DQS input to be successfully captured by CK with a BER of lower than tbd. The mask is a receiver property and it is not the valid data-eye.

Figure — DQS\_t/DQS\_c and CK\_t/CK\_c at DRAM Latch

Internal Composite DQS Eye Center aligned to CK





## Table — Read Preamble Training Timings

Parameter	Cumbal	min/				Data	Rate				Lloit	Note
, didiesor	Symbol	max	533	1066	1600	2133	2667	3200	3733	4267	Unit	note
Delay from MRW command to DQS Driven out	tSDO	max			ma	ax(12n0	CK, 20n	s)			ns	1

## Table — MPC [Write FIFO] AC Timing

Parameter	Symbol	min/		42	*	Data	Rate				Lloit	Note
r diameter	Symbol	max	533	1066	1600	2133	2667	3200	3733	4267	Unit	note
Additional time after tXP has expired until MPC [Write FIFO] command may be issued	tMPCWR	min				tRCD +	· 3nCK					

## Table - DQS Interval Oscillator AC Timing

Parameter	Symbol	min/max	Value	S	Unit	Note
Delay time from OSC stop to Mode Register Readout	tOSCO	min	max(40ns,8nCK)	A	ns	

## Table — Frequency Set Point Timing

Parameter	Symbol	min/ max	Data Rate  533   1066   1600   2133   2667   3200   3733   4267	Unit	Not e
R	tFC_Short	min	200	ns	1
Frequency Set Point Switching Time	tFC_Middle	min	200	ns	1
	tFC_Long	min	250	ns	1
Valid Clock Requirement after entering FSP change	tCKFSPE	min	max(7.5ns, 4nCK)		
Valid Clock Requirement before 1st valid ommand after FSP change	tCKFSPX	min	max(7.5ns, 4nCK)		

#### Notes:

Additionally change of Frequency Set Point may affect Vref(dq) setting. Setting time of Vref(dq) level is same as Vref(ca) level.



<sup>1.</sup> Frequency Set Point Switching Time depends on value of Vref(ca) setting: MR12 OP[5:0] and Vref(ca) Range: MR12 OP[6] of FSPOP

<sup>0</sup> and 1. The details are shown in Table "tFC value maping".

## Table — CA ODT setting timing

Parameter	Symbol	min/max	LPDDR4-1600/1866/2133/2400/3200/4267	Unit	Note
ODT CA Value Update Time	tODTUP	min	RU(20ns/tCK,avg)		

## Table — Power Down timing

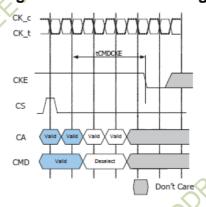
Parameter	Symbol	min/	Data Rate Unit	Not
2.	Cymbol	max	533   1066   1600   2133   2667   3200   3733   4267	е
CKE minimum pulse width (HIGH and LOW pulse width)	tCKE	min	Max(7.5ns,4nCK) -	
Delay from valid command to CKE input LOW	tCMDCKE	min	Max(1.75ns,3nCK) ns	1
Valid Clock Requirement after CKE Input low	tCKELCK	min	Max(5ns,5nCK) ns	1
Valid CS Requirement before CKE Input Low	(CSCKE	min	1.75 ns	
Valid CS Requirement after CKE Input low	tCKELCS	min	Max(5ns, 5nCK) ns	
Valid Clock Requirement before CKE Input High	tCKCKEH	min	Max(1.75ns, 3nCK) ns	1
Exit power- down to next valid command delay	tXP	min	Max(7.5ns, 5nCK) ns	1
Valid CS Requirement before CKE Input High	tCSCKEH	min	1,75 ns	
Valid CS Requirement after CKE Input High	tCKEHCS	min	Max(7.5ns, 5nCK) ns	1
Valid Clock and CS Requirement after CKE Input low after MRW Command	tMRWCKEL	min	Max(14ns, 10nCK) ns	1
Valid Clock and CS Requirement after CKE Input low after ZQ Calibration Start Command	tZQCKE	min	Max(1.75ns, 3nCK) ns	1
Motoo		*		

#### Notes:

1. Delay time has to satisfy both analog time(ns) and clock count(nCK).

For example, tCMDCKE will not expire until CK has toggled through at least 3 full cycles (3 \*tCK) and 3.75ns has transpired. The case which 3nCK is applied to is shown below.

## Figure — tCMDCKE Timing





## Table — PPR Timing Parameters

SHE	D0811PM2F	DGUK(W)-	U / B162 <sup>-</sup>	1PM2FDGUI	((W)-U
Table — PP	R Timing Para	ameters	RAMO	<b>\( \)</b>	
Parameter	Symbol	LPDI Min	DR4 Max	Unit	Note
PPR Programming Time	tPGM	1000	-	ms	
PPR Exit Time	tPGM_Exit	15	-	ns	
New Address Setting Time	tPGMPST	50	-	us	

## Table — Temperature Derating for AC timing

Parameter	Symbol	min/ max	Unit	Note	
DQS Output access time from CK_t/CK_c (derated)	tDQSCKd	max	3600	ps	1
RAS-to-CAS delay (derated)	tRCDd	min	tRCD + 1.875	ns	1
Activate-to-Activate command period (derated)	tRCd	min	tRC + 3.75	ns	1
Row active time (derated)	tRASd	min	tRAS + 1.875	ns	1
Row precharge time (derated)	tRPd	min	tRP + 1.875	ns	1
Active bank A to Active bank B (derated)	tRRDd	min	tRRD + 1.875	ns	1
Notes:  1. Timing derating applies for operation at	85°C to 95°		OKUM LPDDRA ST		

#### Notes:

DRA SDRAW DATASHEET



<sup>1.</sup> Timing derating applies for operation at 85°C to 95°C

## 1.3.4 Truth Tables

Operation or timing that is not specified is illegal, and after such an event, in order to guarantee proper operation, the LPDDR4 device must be powered down and then restarted through the specified initialization sequence before normal operation can continue.

**Table — Command Truth Table** 

10 X	able — Command	Huu	Iab	IC					
Command	SDR Command Pins	DDR CA Pins (10)						CK_ted	Nietes
Sommand	CS_n	CA0	CA1	CA2	САЗ	CA4	CA5	ge	Notes
Deselect (DES)	LO			`	<			R1	1,2
	Н	L	L	L	L	L	OP6	R1	4.00
Multi Purpose Command (MPC)	L	OP0	OP1	OP2	OP3	OP4	OP5	R2	1,2,9
Drack and (Dea Beats All Beats)	∠ H	L	L	L	L	Н	AB	R1	4004
Precharge (Per Bank, All Bank)	L	BA0	BA1	BA2	V	V	V	R2	1,2,3,4
Defrach (Der Denk, All Denk)	Н	L	L	L	Н	L	AB	R1	1224
Refresh (Per Bank, All Bank)	L	BA0	BA1	BA2	V	V	V	R2	1,2,3,4
Solf Defrach Entry	Н	L	L	L	Н	Н	V	R1	4.0
Self Refresh Entry	L			\	/			R2	1,2
Write-1	Н	L	L	Н	4	L	BL	R1	1,2,3,6,7,
write-1	L	BA0	BA1	BA2	V	C9	AP	R2	9
Self Refresh Exit	Н	L	L	Ħ	L	Н	V	R1	1.0
Sell Reflesh Exit	L		R	,	/			R2	1,2
Mask Write-1	Н	L	Z	Н	Ι	L	L	R1	1,2,3,5,6,
IvidSk Wille-1	L	BA0	BA1	BA2	V	C9	AP	R2	9
RFU	Н	L	L	Н	Η	Н	V	R1	1,2
	L	V			R2	1,∠			
Read-1	Н	L	Н	L	L	L	BL	R1	1,2,3,6,7,
iveau- i	L	BA0	BA1	BA2	V	C9	AP	R2	9
CAS-2 (Write-2 or Mask Write-2 or Read-2	Н	L	Н	L	L	Н	C8	R1	1,8,9
or MRR-2)	/ L	C2	C3	C4	C5	C6	C7	R2	1,0,9
RFU	Н	L	Н	L	Н	L	V	R1	1,2
	L			١	/		C	R2	1,2
RFU	Н	L	Н	L	Н	Н	V	R1	1,2
	L		V				>	R2	1,2
MRW-1	Н	L	Н	Н	Ls	VL.	OP7	R1	1,2,11
21	L	MA0	MA1	MA2	MA3	MA4	MA5	R2	.,_,
MRW-2	Н	L	Н	H	) L	Н	OP6	R1	1,2,11
	L	OP0	OP1	OP2	OP3	OP4	OP5	R2	1,4,11
MRR-1	Н	L	H	Н	Н	L	V	R1	1,2,12
	L	MA0	MA1	MA2	MA3	MA4	MA5	R2	1,2,12



DEII ON	Н	L	Н	Н	Н	Н	V	R1	4.0
RFU	L							R2	1,2
Activate-1	Н	Н	L	R12	R13	R14	R15	R1	1 2 2 10
Activate-1	L	BA0	BA1	BA2	V	R10	R11	R2	1,2,3,10
Activote 3	Н	Н	Н	R6	R7	R8	R9	R1	1 10
Activate-2	L	R0	R1	R2	R3	R4	R5	R2	1,10

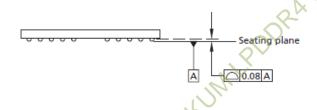
#### Notes

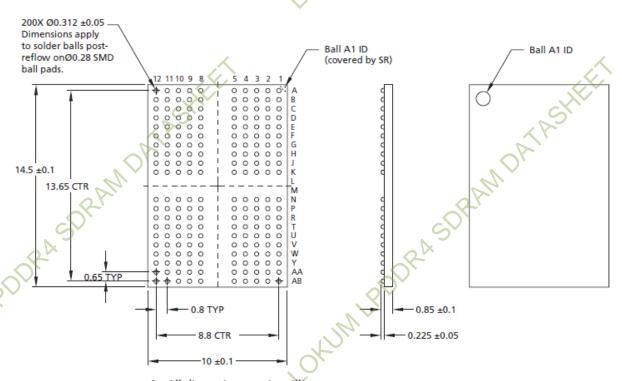
- All LPDDR4 commands except for Deselect are 2 clock cycle long and defined by states of CS and CA[5:0] at the first rising edge of clock. Deselect command is 1 clock cycle long.
- 2. "V" means "H" or "L" (a defined logic level). "X" means don't care in which case CS, CK\_t, CK\_c and CA[5:0] can be floated.
- 3. Bank addresses BA[2:0] determine which bank is to be operated upon.
- 4. AB "HIGH" during Precharge or Refresh command indicates that command must be applied to all banks and bank address is a don't care.
- 5. Mask Write-1 command supports only BL 16. For Mark Write-1 comamnd, CA5 must be driven LOW on first rising clock cycle (R1).
- 6. AP "HIGH" during Write-1, Mask Write-1 or Read-1 commands indicates that an auto-precharge will occur to the bank associated with the Write, Mask Write or Read command.
- 7. If Burst Length on-the-fly is enabled, BL "HIGH" during Write-1 or Read-1 command indicates that Burst Length should be set on-the-Fly to BL=32. BL "LOW" during Write-1 or Read-1 command indicates that Burst Length should be set on-the-fly to BL=16. If Burst Length on-the-fly is disabled, then BL must be driven to defined logic level "H" or "L".
- 8. For CAS-2 commands (Write-2 or Mask Write-2 or Read-2 or MRR-2 or MPC (Only Write FIFO, Read FIFO & Read DQ Calibration), C[1:0] are not transmitted on the CA[5:0] bus and are assumed to be zero. Note that for CAS-2 Write-2 or CAS-2 Mask Write-2 command, C[3:2] must be driven LOW.
- 9. Write-1 or Mask Write-1 or Read-1 or Mode Register Read-1 or MPC (Only Write FIFO, Read FIFO & Read DQ Calibration) command must be immediately followed by CAS-2 command consecutively without any other command in between. Write-1 or Mask Write-1 or Read-1 or Mode Register Read-1 or MPC (Only Write FIFO, Read FIFO & Read DQ Calibration) command must be issued first before issuing CAS-2 command. MPC (Only Start & Stop DQS Oscillator, Start & Latch ZQ Calibration) commands do not require CAS-2 command; they require two additional DES or NOP commands consecutively before issuing any other commands.
- 10. Activate-1 command must be immediately followed by Activate-2 command consecutively without any other command in between. Activate-1 command must be issued first before issuing Activate-2 command. Once Activate-1 command is issued, Activate-2 command must be issued before issuing another Activate-1 command.
- 11. MRW-1 command must be immediately followed by MRW-2 command consecutively without any other command in between. MRW-1 command must be issued first before issuing MRW-2 command.
- 12. MRR-1 command must be immediately followed by CAS-2 command consecutively without any other command in between. MRR-1 command must be issued first before issuing CAS-2 command.



#### **Package Mechanical** 2.

## 2.1. 200 ball FBGA (10 x 14.5 x 1.0mm max)





3RA SDRAM DATASHEET

- 1. All dimensions are in millimeters.
- 2. Solder ball composition: SAC302 with NiAu pads (Sn3Ag0.2Cu).



AT JIM LEDDRA SDRAWIDATASHIFIFT

# 3. Ball Assignment

## 3.1. 200 balls assignment

		)				0.80 m	m Pitch		C	<b>)</b>		
2	× .	1	2	3	4	5	6 7	8	0 3	10	11	12
-00°	Α	DNU	DNU	VSS	VDD2	ZQ0		ZQ1	VDD2	vss	DNU	DNU
	В	DNU	DQ0_A	VDDQ	DQ7_A	VDDQ		VDDQ	DQ15_A	VDDQ	DQ8_A	DNU
	С	vss	DQ1_A	DMI0_A	DQ6_A	vss	JUN - JUN	VSS	DQ14_A	DMI1_A	DQ9_A	vss
LOKUMIRDDR	D	VDDQ	VSS	DQS0_t_A	vss	VDDQ	OF	VDDQ	vss	DQS1_t_A	vss	VDDQ
	E	vss	DQ2_A	DQS0_c_A	DQ5_A	vss		vss	DQ13_A	DQS1_c_A	DQ10_A	vss
	F	VDD1	DQ3_A	VDDQ	DQ4_A	VDD2		VDD2	DQ12_A	VDDQ	DQ11_A	VDD1
	G	vss	ODT(ca)_A	vss	VDD1	vss		vss	VDD1	vss	ZQ2	vss
	н	VDD2	CAO_A	CS1_A	CSO_A	VDD2		VDD2	CA2_A	CA3_A	CA4_A	VDD2
	J	vss	CA1_A	vss	CKEO_A	CKE1_A		CK_t_A	CK_c_A	vss	CA5_A	VSS
	ĸ	VDD2	vss	VDD2	vss	CS2_A		CKE2_A	vss	VDD2	vss	VDD2
			100								100	
	M	A	1/1							A	1/1	
feb	м	VDD2	vss	VDD2	vss	CS2_B		CKE2_B	vss	VDD2	vss	VDD2
omm Pitch	м	VDD2 VSS	VSS CA1_B	VDD2 VSS	VSS CKE0_B	CS2_B CKE1_B		CKE2_B	VSS CK_c_B	VDD2 VSS	VSS CA5_B	VDD2 VSS
0.65 mm Pitch	м					_		_	-0			
0.65 mm Pitch	м	vss	CA1_B	VSS CS1_B	CKEO_B	CKE1_B		CK_t_B	CK_c_B	VSS	CA5_B	VSS
O 65 mm Pitch	M N P R	VSS VDD2	CA1_B	VSS CS1_B	CKE0_B	CKE1_B		CK_t_B	CK_c_B	VSS CA3_B	CA5_B	VSS VDD2
O.66 mm Pitch	M N P R	VSS VDD2 VSS	CA1_B CA0_B ODT(ca)_B	VSS CS1_B VSS	CKE0_B CS0_B VDD1 DQ4_B	CKE1_B VDD2 VSS	04V1	CK_t_B VDD2 VSS	CK_c_B CA2_B VDD1	VSS CA3_B VSS	CA5_B CA4_B RESET_n DQ11_B	VSS VDD2 VSS
OKINI I WILL OK THE PICH	M N P R T	VSS VDD2 VSS VDD1	CA1_B CA0_B ODT(ca)_B DQ3_B	VSS CS1_B VSS VDDQ	CKE0_B CS0_B VDD1 DQ4_B	CKE1_B  VDD2  VSS  VDD2	OKJIN	CK_t_B  VDD2  VSS  VDD2	CK_c_B CA2_B VDD1 DQ12_B	VSS CA3_B VSS VDDQ	CA5_B CA4_B RESET_n DQ11_B	VSS VDD2 VSS VDD1
OKANA OKANA OKANA OKANA DICH	M N P R T U	VSS VDD2 VSS VDD1 VSS	CA1_B CA0_B ODT(ca)_B DQ3_B DQ2_B	VSS CS1_B VSS VDDQ DQS0_c_B	CKE0_B CS0_B VDD1 DQ4_B DQ5_B	CKE1_B  VDD2  VSS  VDD2  VSS	OKUM	CK_t_B  VDD2  VSS  VDD2  VSS	CK_c_B CA2_B VDD1 DQ12_B DQ13_B	VSS CA3_B VSS VDDQ DQS1_c_B	CA5_B CA4_B RESET_n DQ11_B DQ10_B	VSS VDD2 VSS VDD1 VSS
OKJANIJA OKO OKO OKO OKO OKO OKO OKO OKO OKO OK	M N P R T U V	VSS VDD2 VSS VDD1 VSS VDDQ	CA1_B CA0_B ODT(ca)_B DQ3_B DQ2_B VSS	VSS CS1_B VSS VDDQ DQS0_c_B DQS0_t_B	CKE0_B  CS0_B  VDD1  DQ4_B  DQ5_B	CKE1_B  VDD2  VSS  VDD2  VSS  VDD2	OKIN	VDD2 VSS VDD2 VSS VDD2	CK_c_B CA2_B VDD1 DQ12_B DQ13_B VSS	VSS  CA3_B  VSS  VDDQ  DQS1_c_B  DQS1_t_B	CA5_B CA4_B RESET_n DQ11_B DQ10_B V\$\$	VSS VDD2 VSS VDD1 VSS VDDQ

NOTE 1 0.8 mm pitch (X-axis), 0.65 mm pitch (Y-axis), 22 rows.

NOTE 2 Top View, A1 in top left corner.

NOTE 3 ODT(ca)\_[x] balls are wired to ODT(ca)\_[x] pads of Rank 0 DRAM die. ODT(ca)\_[x] pads for other ranks (if present) are disabled in the package.

NOTE 4 ZQ2, CKE2\_A, CKE2\_B, CS2\_A, and CS2\_B balls are reserved for 3-rank package. For 1-rank and 2-rank package those balls are NC.

NOTE 5 Die pad VSS and VSSQ signals are combined to VSS package balls.

NOTE 6 Package requires dual channel die or functional equivalent of single channel die-stack.



#### NOTES FOR CMOS DEVICES

#### 1 PRECAUTION AGAINST ESD FOR MOS DEVICES

Exposing the MOS devices to a strong electric field can cause destruction of the gate oxide and ultimately degrade the MOS devices operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it, when once it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. MOS devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. MOS devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor MOS devices on it.

## 2 HANDLING OF UNUSED INPUT PINS FOR CMOS DEVICES

No connection for CMOS devices input pins can be a cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. The unused pins must be handled in accordance with the related specifications.

## **③** ∕ STATUS BEFORE INITIALIZATION OF MOS DEVICES

Power-on does not necessarily define initial status of MOS devices. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the MOS devices with reset function have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. MOS devices are not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for MOS devices having reset function.



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- Usage involving exposure to significant amounts of corrosive gas, including sea air, CL2, H2S, NH3, SO2, and NOx.
  Usage in environments with static electricity, or strong electromagnetic waves or radiation.
- Usage in places where dew forms.
- Usage in environments with mechanical vibration, impact, or stress.
- Usage near heating elements, igniters, or flammable items.

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