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Algorithm 1 Breadth First Search (Graph)
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1: function BFS(problem) returns a solution, or failure
       node \leftarrow a node with STATE = problem.INITIAL-STATE, PATH-COST = 0
 2:
       if problem.GOAL-TEST(node.STATE) then return SOLUTION(node)
 3:
 4:
       frontier \leftarrow a FIFO queue with node as the only element
 5:
       explored \leftarrow \text{an empty set}
6:
 7:
8:
       loop do
          if frontier = \emptyset then return failure
9:
10:
          node \leftarrow POP(frontier)
11:
          add node.STATE to explored
12:
13:
          for each action in problem.ACTIONS(node.STATE) do
14:
              child \leftarrow \text{CHILD-NODE}(problem, node, action)
15:
16:
             if child.STATE \notin explored or frontier then
17:
                 if problem.GOAL-TEST(child.STATE) then return SOLUTION(child)
18:
                 fontier \leftarrow frontier.APPEND(child)
19:
```