Michael Painter

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EDUCATION

Tel (UK): (+44) 789-551-0611

University of Oxford, Oxford Robotics Institute, Pembroke College Oct 2018 – Apr 2024

- DPhil Engineering Science (Robotics/Machine Learning) • Research focuses: Reinforcement Learning, Monte Carlo Tree Search and sequential decision making
 - Teaching: masters project supervision and teaching assistant for robotics/software engineering courses
 - Presenting (my own/others) research, and reviewing for conferences such as IJCAI, ICRA and AAAI

Stanford University

Sep 2016 - Jun 2018

MS Computer Science

- Main courses: AI, Machine Learning, Reinforcement Learning, Robotics, Computer Vision, NLP with Deep Learning, Randomised Algorithms, Optimisation and Algorithmic Paradigms, Data Mining
- Course staff (CA) for Probability, Principles of Computer Systems and Reinforcement Learning

University of Cambridge, Churchill College

Oct 2013 - Jun 2016

BA (Hons) Computer Science

• Algorithms, Concurrent/Distributed Systems, Networks, Software Engineering, Databases, Security

EMPLOYMENT

Software Engineer Intern — Google, Display Ads Predictions

Jul 2019 - Oct 2019

- Worked on estimating parameters in Generalised Linear Mixed Models with billions of data points
- Used variational inference to optimise the model, outperforming the baseline with less training time
- Documented how to distribute the algorithm across multiple machines to exploit model sparsity
- Technologies used: Python, TensorFlow, Borg (including BCL)

Applied Scientist Intern — Microsoft, DNN Frameworks Team

Jul 2018 - Sep 2018

- Used Generative Adversarial Networks to produce 3D human pose estimates given a single RGB image
- Improved robustness to "in the wild" images using data augmentation and semi-supervised techniques
- Incorporated depth estimation networks to produce global 3D pose predictions, for Kinect for Azure
- Technologies used: Python, PyTorch, NumPy, SciPy, ONNX

SELECTED Projects Code for most projects found at: github.com/MWPainter

THTS++

Oct 2022 - Ongoing

• Open source parallelised implementation of Trial Based Heuristic Tree Search in C++

MCTS with Boltzmann Exploration (NeurIPS2023)

Jan 2022 – May 2023

- Developed two Monte Carlo Tree Search (MCTS) algorithms using Boltzmann search policies
- Proved exponential convergence bounds for the performance of both algorithms using simple regret
- Used the Alias Method for faster sampling and improving the asymptotic complexity of the algorithms
- Technologies used: C++, KataGo

Convex Hull Monte-Carlo Tree Search (ICAPS2020)

Apr 2019 - Jan 2020

- Adapted Monte Carlo Tree Search for multi-objective planning using convex hull backups
- Novel analysis of sample based multi-objective planning algorithms using contextual regret
- Improved scalability over prior works, demonstrated with Generalised Deep Sea Treasure environments
- Technologies used: Python, NumPy, SciPy

Sequential Variational Autoencoders — SAIL/Ermon Group

Jan 2018 - Jun 2018

- Work on applying Variational Autoencoders (VAEs) sequentially to generate "sharper" images
- Developed novel objective functions and used multiple VAE architectures to improve image quality
- Technologies used: Python, TensorFlow, NumPy

CNNs for Visual Recognition — Efficient Architecture Search

Apr 2018– Jun 2018

- Implemented novel network preserving transformations for Convolutional Neural Networks.
- Demonstrated training speed up on simple classification tasks, by utilising the transformations.
- Used the transformations with neuroevolution and parameter sharing in an efficient architecture search.
- Technologies used: Python, PyTorch, NumPy.

LANGUAGES

Python, C++, C, Cython, Java, Javascript, Matlab, PHP, MySQL, HTML.

PACKAGES

PyTorch, TensorFlow, NumPy, SciPy, GTest, Git, SKLearn, ONNX, Microsoft Azure, AWS.

ACTIVITIES AND Interests

Trying not to burn my food; Keen hiker; Ex-competitive track and field athlete; Picking up skills, such as juggling, slacklining and cocktail making; Getting lost in a novel; Struggling to find shoes that fit

LIST OF PUBLICATIONS	2023	Painter, M.; Baioumy, M; Hawes, N; and Lacerda, B. Monte Carlo Tree Search With Boltzmann Exploration. Advances in Neural Information Processing Systems (NeurIPS)
	2020	Painter, M.; Lacerda, B.; and Hawes, N. 2020. Convex Hull Monte Carlo Tree Search. Int. Conf on Automated Planning and Scheduling (ICAPS)
	In Progress	Multi-Objective Maximum Entropy Tree Search (Sep 2022 - Ongoing)
		Using Tree Search To Integrate Skills From Multiple Agents (Jun 2022 - Ongoing)