

# Shanghai MXCHIP Information Technology Co., Ltd.

**IoT Solution Provider** 

Version	Author	Date	Note
V0.9	NEO	2019.09.20	Initial version
V0.91	NEO	2019.10.27	Update Tool chain

# **Step 1. Install Mxos-cube**

- 1. Install Python2.7.13 & Git
- --Python Software:https://www.python.org/downloads/release/python-2713/
- --Git: https://git-scm.com/
- 2. Configure python and git to your system path
- --Python27: https://superuser.com/questions/143119/how-do-i-add-python-to-the-windows-path

Python Pip: same as above, add path(example): C:\Python27\Scripts

Git: https://stackoverflow.com/questions/26620312/installing-git-in-path-with-github-client-for-windows

- 3. Install mxos-cube
- --Use command: *pip install mxos-cube* in cmd.exe

## **Step 2. Global Configure Micoder**

- 1. Copy Micoder file to your defined path
- --Software: http://firmware.mxchip.com/MiCoder\_v1.3\_Win32:64.zip



#### 2. Configure Micoder

--You can set the MiCoder Tools location via the cmd.exe:

\$\(\frac{\mathrice}{mxos} \cdots \overline{\mathrice}{mxos} \overline{\mathrice}{mxos} \overline{\mathrice}{\mathrice}{\mathrice}{\mathrice}{mxos} \overline{\mathrice}{\mathrice}{\mathrice}{\mathrice}{\mathrice}{mxos} \overline{\mathrice}

Microsoft Windows [Version 10.0.18362.356]
(c) 2019 Microsoft Corporation. All rights reserved.

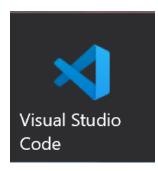
C:\Users\neofr>mxos config --global MICODER C:\Users\neofr\Documents\MiCoder [mxos] C:\Users\neofr\Documents\MiCoder now set as global MICODER

C:\Users\neofr>mxos config --list [mxos] Global config:
MICODER=C:\Users\neofr\Documents\MiCoder

# **Step 3. Install Visual Studio Code**

Download and Install Visual Studio Code

--Software: https://code.visualstudio.com/

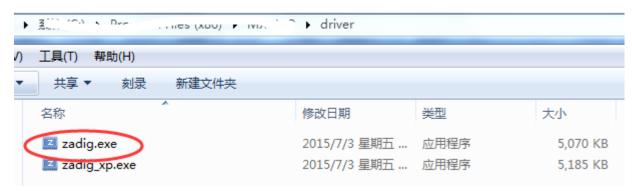


# **Step 4. Install Driver**

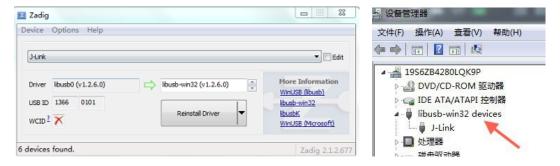
- 1. Install Driver
- --Software: \MXCHIP Install for Windows\Driver Install



2. "CP210x\_Universal\_Windows\_Driver" is for UART driver, "Setup\_JLink\_V600i.exe" is for Jlink driver, "jlink\_driver\_for\_mico" is for MX1290 series when download by Jlink Run: zadig.exe or zadig\_xp.exe (for Windows XP) in "jlink\_driver\_for\_mico"



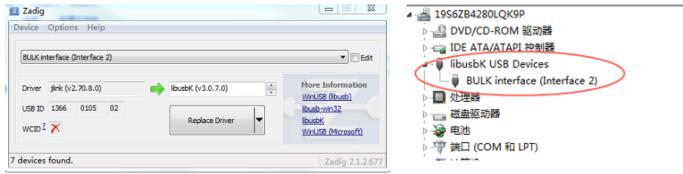
3. Select the menu: Options->List All Devices, select J-Link from the drop-down list, select "libusb-win32(v1.2.6.0)" for the driver, click "Replace Driver", and return to "successful" to close. "libusb-win32 devices will appear in the device manager. If you are using JLinkV8, the update process is as follows:



If you are using JLinkV9, the update process is as follows:

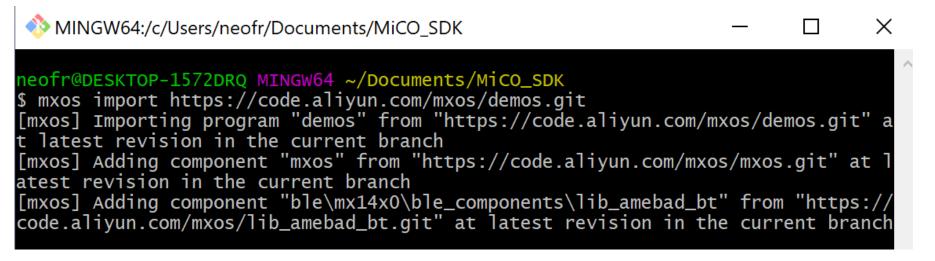


Due to different JLink firmware versions from different manufacturers, some JLink drivers may not work properly after replacing them with libusb-win32 (v1.2.6.0). In this case, try using "libusbK (v3.0.7.0)".



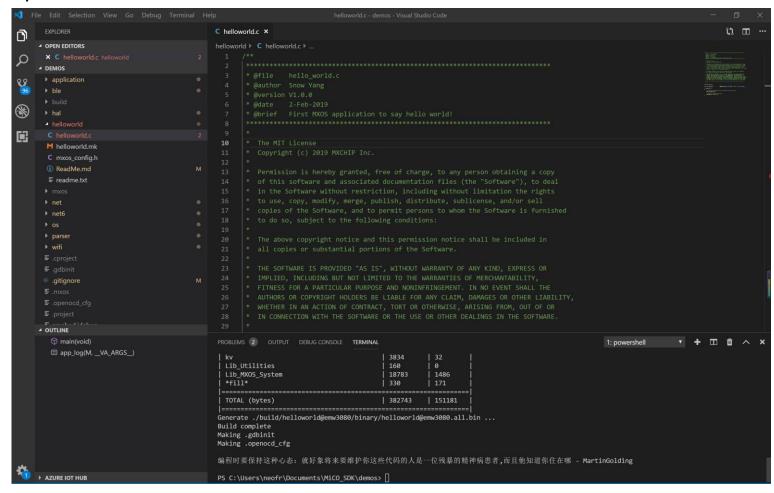
## **Step 5. Download SDK**

- 1. SDK
- --Https: https://code.aliyun.com/mxos/demos.git
- 2. Use Git Bash to download SDK with command: mxos import https://code.aliyun.com/mxos/demos.git



## Step 6. Use SDK with VS Code

1. Open demos folder in VS code



2. Compile with command in TERMINAL: mxos make helloworld@emw3080

```
OUTPUT DEBUG CONSOLE TERMINAL
PS C:\Users\neofr\Documents\MiCO SDK\demos> mxos make helloworld@emw3080
Making config file for first time
processing components: helloworld emw3080 MXOS
Making build/helloworld@emw3080/libraries/EMW3080.a
Making build/helloworld@emw3080/libraries/Lib_MXOS_Kernel.a
Making build/helloworld@emw3080/libraries/Lib MXOS Security SRP 6a.a
Making build/helloworld@emw3080/libraries/Lib_MXOS_Security_Sodium.a
Making build/helloworld@emw3080/libraries/aws.a
Making build/helloworld@emw3080/libraries/Lib wolfSSL.a
Compiling App Helloworld
Compiling MXOS
Compiling Lib MXOS Security
Compiling Lib_MXOS_System
Compiling Lib Utilities
Compiling platform mx1290
```