

Yocto Project and OpenEmbedded development training

On-line seminar, 4 sessions of 4 hours

Latest update: November 02, 2023

Title	Yocto Project and OpenEmbedded development training
Training objectives	 Be able to understand the role and principle of an embedded Linux build system, and compare Yocto Project/OpenEmbedded to other tools offering similar functionality. Be able to configure and build basic embedded Linux system with Yocto, and install the result on an embedded platform. Be able to write and extend recipes, for your own packages or customizations. Be able to use existing layers of recipes, and create your own new layers. Be able to integrate support for your own embedded board into a BSP layer. Be able to create custom images. Be able to use the Yocto Project SDK to develop applications. Be able to use devtool to generate and modify recipes.
Duration	Four half days - 16 hours (4 hours per half day)
Pedagogics	 Lectures delivered by the trainer, over video-conference. Participants can ask questions at any time. Practical demonstrations done by the trainer, based on practical labs, over video-conference. Participants can ask questions at any time. Optionally, participants who have access to the hardware accessories can reproduce the practical labs by themselves. Instant messaging for questions between sessions (replies under 24h, outside of week-ends and bank holidays). Electronic copies of presentations, lab instructions and data files. They are freely available at https://bootlin.com/doc/training/yocto.
Trainer	One of the engineers listed on: https://bootlin.com/training/trainers/
Language	Oral lectures: English, French, Italian. Materials: English.





Audience	Companies and engineers interested in using the Yocto Project to build their embedded Linux system.
Prerequisites	 Knowledge and practice of UNIX or GNU/Linux commands: participants must be familiar with the Linux command line. Participants lacking experience on this topic should get trained by themselves, for example with our freely available on-line slides at bootlin.com/blog/command-line/. Minimal experience in embedded Linux development: participants should have a minimal understanding of the architecture of embedded Linux systems: role of the Linux kernel vs. user-space, development of Linux user-space applications in C. Following Bootlin's Embedded Linux course at bootlin.com/training/embedded-linux/ allows to fulfill this pre-requisite. Minimal English language level: B1, according to the Common European Framework of References for Languages, for our sessions in English. See bootlin.com/pub/training/cefr-grid.pdf for self-evaluation.
Required equipment	 Computer with the operating system of your choice, with the Google Chrome or Chromium browser for videoconferencing. Webcam and microphone (preferably from an audio headset) High speed access to the Internet
Certificate	Only the participants who have attended all training sessions, and who have scored over 50% of correct answers at the final evaluation will receive a training certificate from Bootlin.
Disabilities	Participants with disabilities who have special needs are invited to contact us at <i>training@bootlin.com</i> to discuss adaptations to the training course.



Hardware, first option

BeagleBone Black board

- An ARM AM335x processor from Texas Instruments (Cortex-A8 based), 3D acceleration, etc.
- 512 MB of RAM
- 2 GB of on-board eMMC storage (4 GB in Rev C)
- USB host and device
- HDMI output
- 2 x 46 pins headers, to access UARTs, SPI buses, I2C buses and more.



Hardware, second option

One of these Discovery Kits from STMicroelectronics: STM32MP157A-DK1, STM32MP157D-DK1, STM32MP157C-DK2 or STM32MP157F-DK2

- STM32MP157 (dual Cortex-A7) CPU from STMicroelectronics
- · USB powered
- 512 MB DDR3L RAM
- Gigabit Ethernet port
- 4 USB 2.0 host ports
- 1 USB-C OTG port
- 1 Micro SD slot
- On-board ST-LINK/V2-1 debugger
- Arduino Uno v3-compatible headers
- · Audio codec
- Misc: buttons, LEDs
- LCD touchscreen (DK2 kits only)





Half day 1

Lecture - Introduction to embedded Linux build systems

- Overview of an embedded Linux system architecture
- Methods to build a root filesystem image
- · Usefulness of build systems

Lecture - Yocto Project and Poky reference system overview

- Introduction to the Yocto / OpenEmbedded build system and its lexicon
- Overview of the Poky reference system

Lecture - Using Yocto Project - basics

- Setting up the build directory and environment
- Configuring the build system
- Building a root filesystem image

Demo 1 - First Yocto Project build

- Downloading the Poky reference build system
- Configuring the build system
- · Building a system image

Lecture - Using Yocto Project - basics

• Organization of the build output

Demo 1 - Flashing and booting

• Flashing and booting the image on the board



Half day 2

Lecture - Using Yocto Project - advanced usage

- Variable assignment, operators and overrides
- · Package variants and package selection
- bitbake command line options

Demo 2 - Using NFS and configuring the build

- Configuring the board to boot over NFS
- Add a package to the root filesystem
- Learn how to use the PREFERRED_ PROVIDER mechanism
- Get familiar with the bitbake command line options

Lecture - Writing recipes - basics

- Recipes: overview
- Recipe file organization
- Applying patches
- · Recipe examples

Demo 3 - Adding an application to the build

- Writing a recipe for *nInvaders*
- Troubleshooting the recipe
- Troubleshooting cross-compilation issues
- Adding *ninvaders* to the final image

Lecture - Writing recipes - advanced features

- · Extending and overriding recipes
- Virtual packages
- Learn about classes
- BitBake file inclusions
- · Debugging recipes
- · Configuring BitBake network usage



Half day 3

Lecture - Layers

- · What layers are
- Where to find layers
- · Creating a layer

Demo 4 - Writing a layer

- Learn how to write a layer
- Add the layer to the build
- Move *ninvaders* to the new layer

Demo 5 - Extend a recipe

- Extend the kernel recipe to add patches
- Configure the kernel to compile the nunchuk driver
- Edit the ninvaders recipe to add patches
- Play nInvaders

Lecture - Writing a BSP

- Introduction to BSP layers
- · Adding a new machine
- Bootloader configuration
- Linux: the kernel bbclass and the linuxyocto recipe

Demo 6 - Create a custom machine configura- tion

- Create a new machine configuration
- Build an image for the new machine

Lecture - Distro layers

- Distro configuration
- Distro layers



Lecture - Images

- · Writing an image recipe
- Image types
- Writing and using package groups recipes

Demo 7 - Create a custom image

- Add a basic image recipe
- Select the image capabilities and packages
- Add a custom package group
- · Add an image variant for debugging

Half day 4

Lecture - Writing recipes - going further

- The per-recipe sysroot
- Using Python code in metadata
- Variable flags
- · Packages features and PACKAGECONFIG
- · Conditional features
- Package splitting
- Dependencies in detail

Lecture - Licensing

• Managing open source licenses

Lecture - The Yocto Project SDK

- Goals of the SDK
- · Building and customizing an SDK
- Using the Yocto Project SDK

Demo 8 - Develop your application in the Poky SDK

- · Building an SDK
 - Using the Yocto Project SDK

Lecture - Devtool

- · About devtool
- Devtool use cases

Demo 9 - Using devtool

- Generate a new recipe
- Modify a recipe to add a new patch
- Upgrade a recipe to a newer version



Lecture - Automating layer management

• Automating layer management

Lecture - Runtime Package Management

- Introduction to runtime package management
- Build configuration
- Package server configuration
- Target configuration

Questions and Answers

- Questions and answers with the audience about the course topics
- Extra presentations if time is left, according what most participants are interested in.

Possible extra time

Extra time (up to 4 hours) may be proposed if the agenda didn't fit in 4 half days, according to the time spent answering questions from participants.