



## ST solutions for robotics

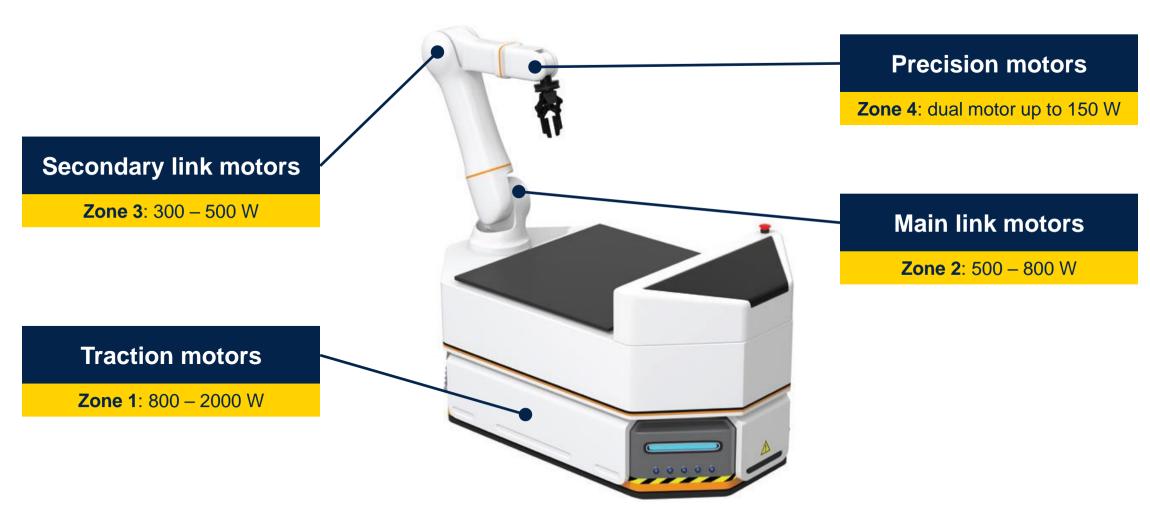
**Autonomous Ground Vehicle Autonomous Mobile Robots** 

### Introduction

- The advantages of Autonomous Ground Vehicles (AGVs) and Autonomous Mobile Robots (AMRs) are their flexibility and their customization to suit the specific application
- There are three basic form factors in the AGV & AMR sector: mouse, forklift and tugger. In the present document we mixed these form factors to show the ST solution for them.



### Robot motor & sensor zones

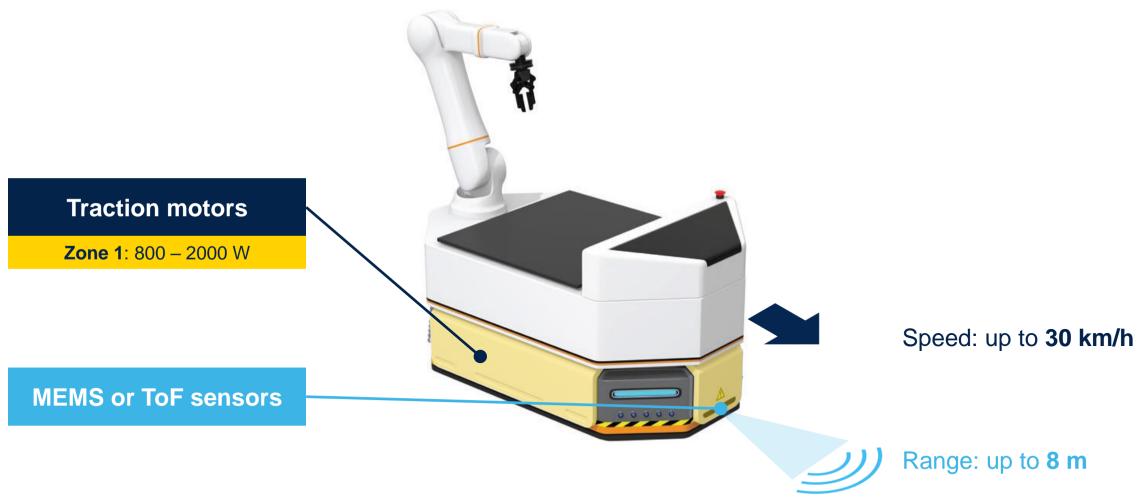




## Solution for zone 1



# Solutions for zone 1 Motion & orientation

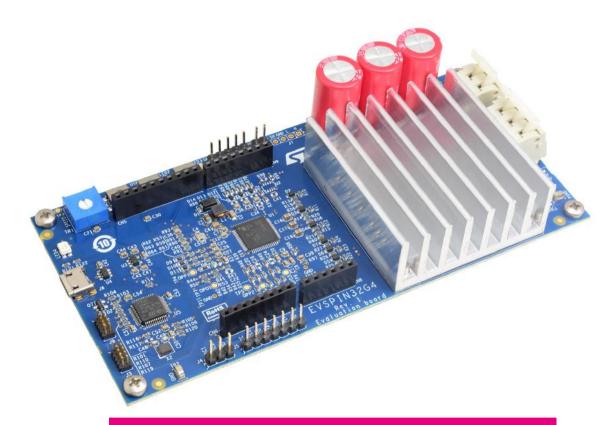






### EVSPIN32G4

### Solution for three-phase brushless motors for e-vehicles



#### Main design challenges

- Motor control 10 75 V design with high scale integration
- Max power dissipation up to 1 kW

#### **Key products**

- STSPIN32G4: high performance three-phase motor controller with embedded STM32G431 Arm Cortex-M4 MCU+FPU)
- STL110N10F7: N-channel 80 V, 1.7 mOhm typ., 180 A STripFET F7 Power MOSFET

- CORDIC mathematical hardware accelerator for trigonometric functions
- 75 V rated gate drivers with 1 A sink / source current and embedded bootstrap diodes
- F7 power MOSFETs
- Three-shunt or single-shunt configurable current sensing
- V<sub>CC</sub> buck converter up to 200 mA, with programmable output and embedded MOSFET
- 3.3 V LDO linear regulator up to 150 mA
- Full set of interfaces: I2C, SPI, UART and CAN
- Digital Hall sensor and quadrature encored input
- Arduino UNO connector. Predisposition for CAN bus





## STEVAL-CTM009V1 5 kW low voltage high current inverter



#### Main design challenges

- Motor control 48 V design with high scale integration
- Max current up to 100 A

#### Key products

#### Composed of 4 boards:

- Power board STEVAL-CTM004V1
- Bulk capacitor board STEVAL-CTM005V1
- Driver board STEVAL-CTM006V1
- Current sensing board STEVAL-CTM008V1 (can be replaced by STDES-AKI003V1)

- Power board:
  - Hosts 36 STH31xN10F7 power MOSFETs
  - 3-shunt resistors ground referred for current sensing (optional)
- Control board:
  - Based on 3x L6491 gate driver with current capability up to 4 A sink/source
  - Over-current/temperature/voltage protection





### STDES-AKI003V1

### Sigma delta ADC solution for industrial drive



#### Main design challenges

Create a motor control solution for achieving the FOC of a PMSM using an external Sigma Delta insulated analog to digital converter

#### **Key products**

ISOSD61: 16-bit isolated Sigma-Delta modulator, single-ended and LVDS interfaces

- · Solution Tailored for High End Servo drive
- Accurate current sensing for high end industrial motor control applications
- · 6 kV Galvanic isolation
- Up to 25 MHz Σ-Δ clock
- Fast dynamic and response to load variations
- · Field oriented control of PMSM motors
- Triple simultaneous current sampling via shunt resistor placed inline with the motor phases
- Fully compatible with DFSDM peripheral (STM32 F4/F7/H7)





### ST Morpho connector\* Arduino UNO R3 connector DIL 24-pin Magnetometer MEMS microphone 6-axis IMU Accelerometer **IIS2MDC IMP34DT05** ISM330DHCX **IIS2DLPC**

\*\* Connector for the STM32 Nucleo Board

# X-NUCLEO-IKS02A1 Industrial sensors extension

#### **Key products**

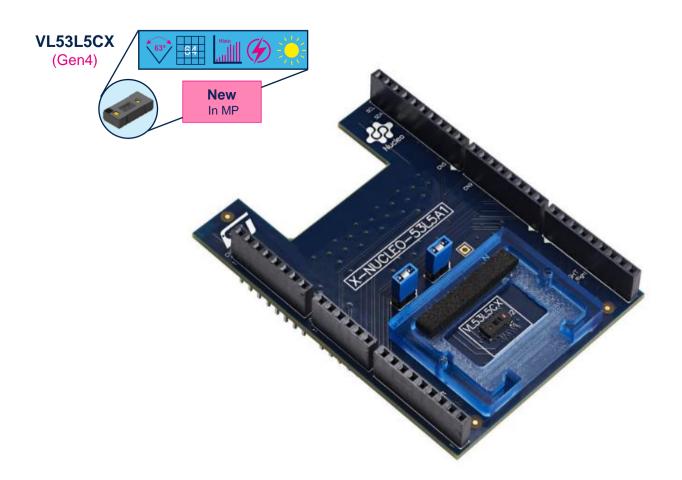
- ISM330DHCX: 6-axis IMU (accelerometer + gyroscope) to detect movement and rotation of the object
- **IIS2DLPC**: 3D accelerometer for low power wake-up from movement
- IIS2MDC: 3D magnetometer for absolute orientation of the object
- IMP34DT05: MEMS microphone for environment monitoring

- Motion MEMS and environmental sensor expansion board for STM32
   Nucleo for Industrial
- DIL 24-pin socket available for additional MEMS adapters and other sensors
- I<sup>2</sup>C, SPI support
- Available I<sup>2</sup>C sensor hub features on ISM330DHCX
- · Equipped with Arduino UNO R3 connector
- Free comprehensive development firmware library and samples for all sensors compatible with STM32Cube firmware





# X-NUCLEO-53L5A1 Multi-zones ToF up to 4 m range for obstacle detection



#### **Key products**

- VL53L5CX: Up to 4 m ToF with wide 63 deg FOV, 64 Region Of Interest, histogram information for multi-targets detection
- Nucleo-F401RE recommended motherboard with STM32F401 MCU, P-NUCLEO-53L5A1/ includes both

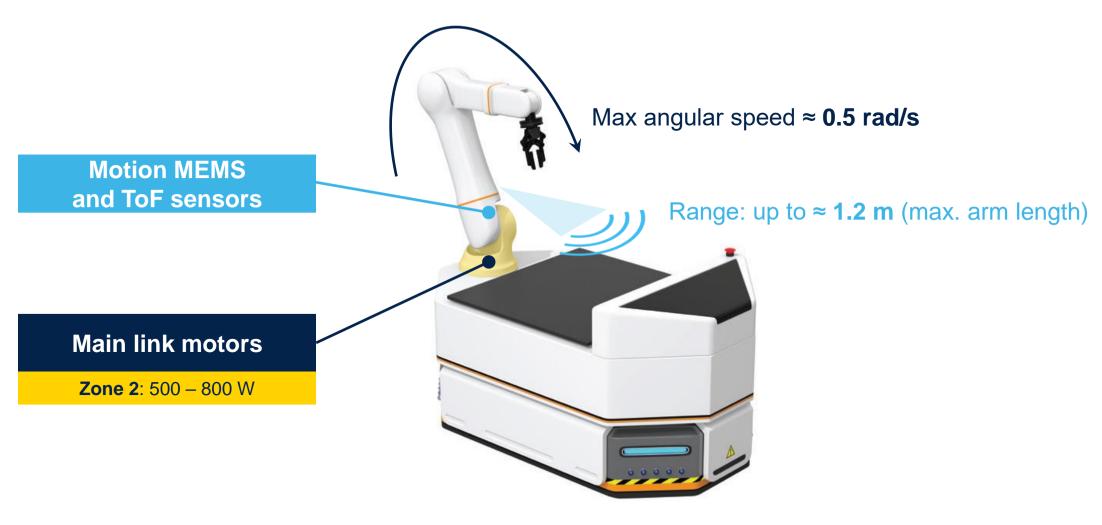
- Parallel multizone ranging output:4x4 or 8x8 zones separate regions of interest
- Wide FoV: 45° x 45° (63° diagonal) with possibility to use multiple units to extend the area (ease of integration)
- Up to 400 cm ranging: Long range to detect obstacles for robot
- Multi-target detection and distance measurement in each zone
- 60 Hz (4x4 zones) frame rate capability
- Immunity to cover glass cross-talk beyond 60 cm
- · Detection thresholds mode available
- Robust to smudge, excellent under dirty cover glass
- · Performance already proven for challenging industrial designs
- Full set of product documentation & SW tools available on st.com



## Solution for zone 2



## Solutions for zone 2 Main link movement







### STEVAL-ETH001V1

### Servo drive solution for multiaxial position control



Ensured compatibility with Master Ethercat (implemented using Twincat software tool by Bechkoff instead of hardware solution)

#### Main design challenges

- Motor control 48 V design with high scale integration
- Max power dissipation up to 700 W

#### **Key products**

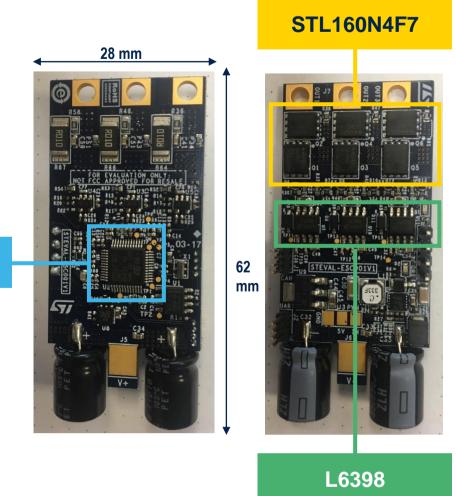
- STM32F767: High-performance, Arm Cortex- M7 MCU with DSP & FPU
- STDRIVE101: Triple half-bridge gate driver
- IPS160H: Single channel IPS
- CLT03-2Q3: Dual channel digital input interface
- ST3485: RS485 / RS422 transceiver
- TSV991ILT: Wide-bandwidth rail to rail 5V CMOS Op-Amp
- STH270N8F7-2: N-channel 80 V, 1.7 mOhm typ., 180 A STripFET F7 Power MOSFET
- L7987L (61 V 2 A asynchronous step-down switching regulator)

- Real-Time Ethernet based on Ethercat protocol (NETX90 processor)
- Motor control driving powered by STDRIVE StripFET F7
- · Digital Actuation for industrial load
- Driving power circuit with brake energy discharge circuit, to drive the rotor position and manage the energy discharge
- · Power management circuit to generates all the reference voltage
- Quadrature encoder feedback signal input based on digital protocol like EnDat, BiSS and Ssi
- RS485 interface for digital sensors or other use





# STEVAL-ESC001V1 The professional UAV ESC with CAN interface



#### **Key products**

- STM32F303: Arm Cortex- M4 MCU
- L6398: High-voltage gate drivers
- STL160N4F7: Low-voltage STripFET F7 series

#### **Key features**

- · Implementing a sensorless FOC algorithm
- Designed for 6S pack of LiPo batteries (22.2V)
- · Ready for communication with any standard FCU: PWM or CAN
- Temperature overheating protection
- BEC 5 V / 0.5 A for external receiver or FCU
- Complete pre-configured firmware package available (STSW-ESC001V1)
- Maximum rate 20 A, 400 W



STM32F303



### ST Morpho connector\* Arduino UNO R3 connector DIL 24-pin Magnetometer MEMS microphone 6-axis IMU Accelerometer **IIS2MDC IMP34DT05** ISM330DHCX **IIS2DLPC**

\*\* Connector for the STM32 Nucleo Board

# X-NUCLEO-IKS02A1 Industrial sensors extension

#### **Key products**

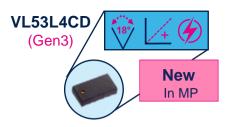
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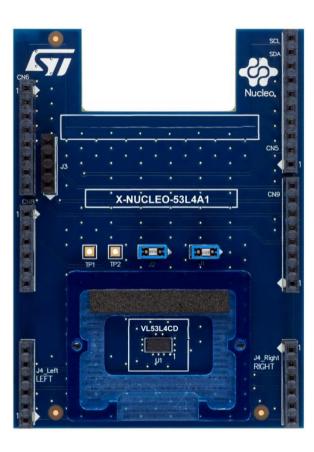
- Motion MEMS and environmental sensor expansion board for STM32 Nucleo for Industrial
- DIL 24-pin socket available for additional MEMS adapters and other sensors
- I<sup>2</sup>C, SPI support
- Available I<sup>2</sup>C sensor hub features on ISM330DHCX
- Equipped with Arduino UNO R3 connector
- Free comprehensive development firmware library and samples for all sensors compatible with STM32Cube firmware





# X-NUCLEO-53L4A1 ToF up to 1.2 m range for obstacle detection





#### **Key products**

- VL53L4CD: Up to 1.3m TOF with 18 deg FOV and excellent short distance linearity (>0.1cm)
- Nucleo-F401RE recommended motherboard with STM32F401 MCU, P-NUCL FO-53I 4A1- includes both

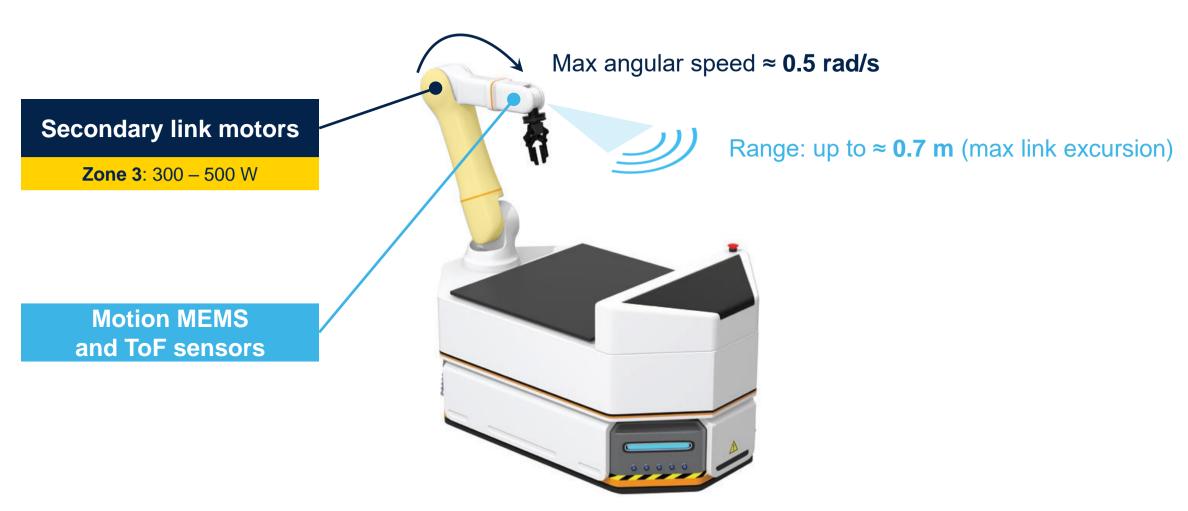
- Full FoV ranging: 130 cm+ (white target, no IR)
- **Very high-performance proximity** sensor, for accurate obstacles detection in close proximity.
- Excellent short distance linearity (>0.1cm)
- Low power autonomous mode with interrupts thresholds for user / object detection
- Fast ranging frequency (up to 100Hz)
- Same pinout of VL53L0CX, VL53L1CX/CB, VL53L3CX and VL53L4CX
- · Crosstalk compensation
- · Low power mode available
- Full set of product documentation & SW tools available on st.com



## **Solution for zone 3**



## Solutions for zone 3: Secondary link movement



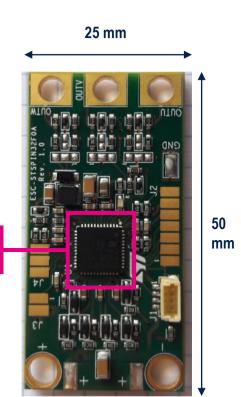




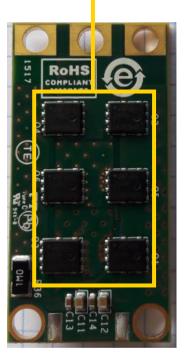
## STEVAL-ESC002V1

### Super compact turn-key solution for robots & drones





**STL140N6F7** 



#### **Key products**

- STSPIN32F0A: Arm Cortex-M0 MCU + 3-phase gate driver
- STL140N4F7: 40 V 120 A STripFET F7 series

#### **Key features**

- Implementing a 6-step voltage mode algorithm
- · Designed for 2S-6S pack of LiPo batteries
- Maximum Rate 45 V, 20 A
- Available soon: Support of BLHeli\_32 FW adapted to STSPIN32F0A
- Complete pre-configured firmware package available (STSW-ESC002V1)

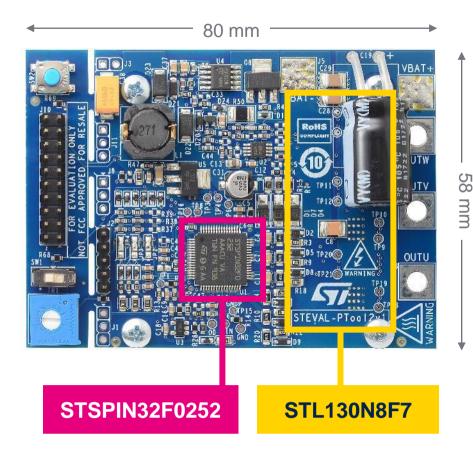


STSPIN32F0A



# STEVAL-PTOOL2V1 High voltage solution for power tools





#### **Key products**

- STSPIN32F0252: Arm Cortex-M0 MCU + 3-phase gate driver. 250 V
- STL130N8F7: 80 V 120 A STripFET F7 series

- Implementing a 6-step voltage mode algorithm. 6-step single shunt with Hall sensors inputs
- · Designed for 8S-15S pack of LiPo batteries
- Max operating ratings: 80 V, 15 A<sub>RMS</sub>
- Very low stand-by power consumption
- · Trigger, direction and speed inputs available
- · Speed control potentiometer available
- Over current protection
- · Mounting options for:
  - Field Oriented Control, sensorless / sensored
  - · BEMF detection circuitry
- · Ready to use dedicated 6-step firmware package
- Heatsink (54 x 54 x 20 mm)





### ST Morpho connector\* Arduino UNO R3 connector DIL 24-pin Magnetometer MEMS microphone 6-axis IMU Accelerometer **IIS2MDC IMP34DT05** ISM330DHCX **IIS2DLPC**

\*\* Connector for the STM32 Nucleo Board

# X-NUCLEO-IKS02A1 Industrial sensors extension

#### **Key products**

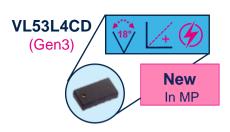
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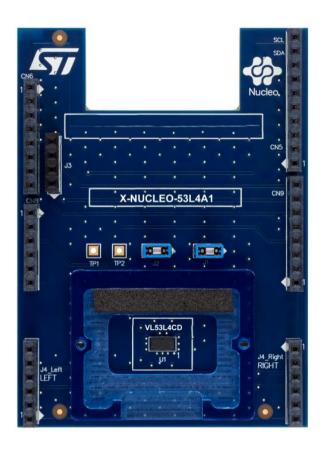
- Motion MEMS and environmental sensor expansion board for STM32
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- Available I<sup>2</sup>C sensor hub features on ISM330DHCX
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# X-NUCLEO-53L4A1 ToF up to 1.2 m range for obstacle detection





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- Nucleo-F401RE recommended motherboard with STM32F401 MCU, P-NUCL FO-53I 4A1- includes both

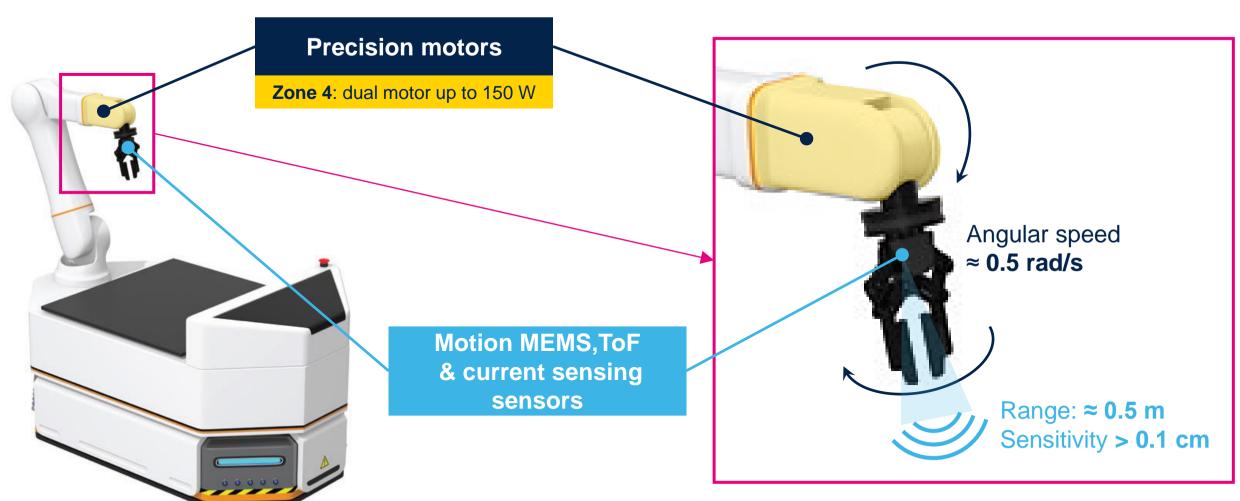
- Full FoV ranging: 130 cm+ (white target, no IR)
- **Very high-performance proximity** sensor, for accurate obstacles detection in close proximity.
- Excellent short distance linearity (>0.1cm)
- Low power autonomous mode with interrupts thresholds for user / object detection
- Fast ranging frequency (up to 100Hz)
- Same pinout of VL53L0CX, VL53L1CX/CB, VL53L3CX and VL53L4CX
- · Crosstalk compensation
- · Low power mode available
- Full set of product documentation & SW tools available on st.com



## Solution for zone 4



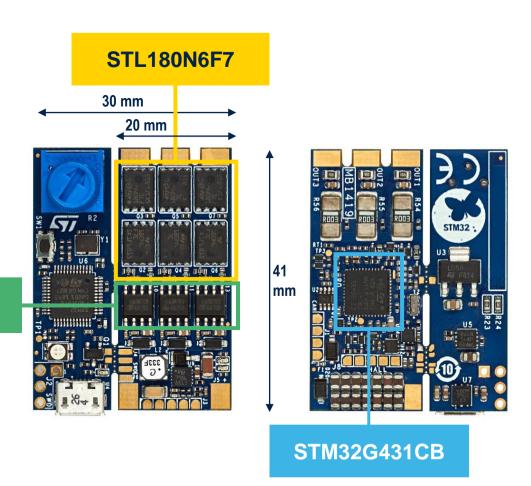
# Solutions for Zone 4 Manipulator







# Turn-key solution with sensorless FOC and 6-step control



#### **Key products**

- STM32G431CB: ARM Cortex- M4 MCU
- L6398: High-voltage gate drivers
- STL180N6F7: N-Channel 60 V, 120A STripFET F7 series

#### **Key features**

- Full reference design capable of both sensorless FOC and 6-step algorithm
- Ultra-compact solution
- Up to 6S LiPo battery pack or equivalent 11-24V DC supply
- On-board ST-LINK/V2-1 debugger/programmer detachable from the main board

B-G431B-ESC1

- · BEC available through the daughterboard
- · Output peak motor current: 40 A
- Support for motor sensors (Hall or encoder)



L6398



### **EVALKIT-ROBOT-1**

### Compact reference design kit for robotics and automation

#### **Key products**

- STSPIN32F0A: ARM Cortex-M0 MCU + 3-phase gate driver
- STL7DN6LF3: 60 V, 35 mΩ dual N-Channel MOSFETs



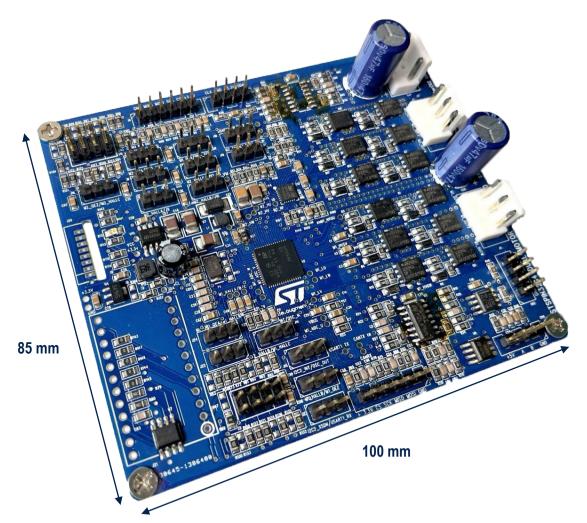
- 36 V/6 Apeak power stage
- Hall sensors
- · Position control loop based on Field Oriented Control
- Extremely compact footprint (40 mm x 40 mm)
- MODBUS communication protocol through RS-485
- maxon EC-i 40 100 W 3-phase brushless DC motor
- maxon ENX 16 EASY 1024-pulse incremental encoder







# STSPIN32G4 dual motor board Dual motor PMSM FOC



#### **Key products**

- STSPIN32G4: 3-phase motor controller with embedded STM32G4 MCU
- STDRIVE101: Triple half-bridge gate driver
- **STL110N6F7**: 40V 108 A STripFET F7 series
- TSV914: Op-Amp
- ST1S40IDIR: Buck regulator
- VL53CX: Time of Flight sensor, optional
- ISM330DHCX: 3D Gyroscope, optional

- 5 75 V, 200 W
- FW & HW support for Dual Motor FOC sensorless / sensored
- Magnetic Encoder /QEI
- Hall sensors (Timer or No-Timer support)
- IMU & ToF data acquisition
- CAN, RS485 protocols
- If customized, size can be reduced up to 50%







# EVSPIN32G4-DUAL Dual motor PMSM FOC

#### **Key products**

- STSPIN32G4: 3-phase motor controller with embedded STM32G4 MCU
- STDRIVE101: Triple half-bridge gate driver
- STL110N6F7: 40V 108 A STripFET F7 series
- **TSV914**: Op-Amp
- ST1S40IDIR: Buck regulator
- VL53CX: Time of Flight sensor, optional
- ISM330DHCX: 3D Gyroscope, optional

- 5 75 V, 200 W
- FW & HW support for Dual Motor FOC sensorless / sensored
- Magnetic Encoder /QEI
- Hall sensors (Timer or No-Timer support)
- IMU & ToF data acquisition
- CAN, RS485 protocols (available on demand)





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\*\* Connector for the STM32 Nucleo Board

# X-NUCLEO-IKS02A1 Industrial sensors extension

#### **Key products**

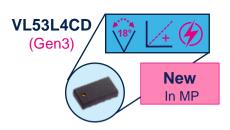
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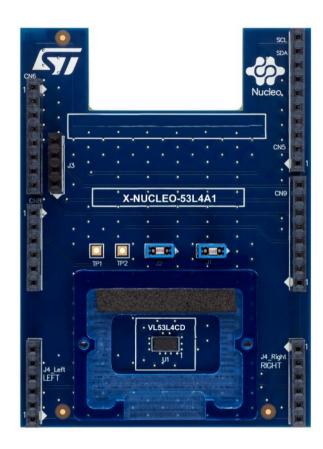
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- Nucleo-F401RE recommended motherboard with STM32F401 MCU, P-NUCL FO-53I 4A1- includes both

- Full FoV ranging: 130 cm+ (white target, no IR)
- **Very high-performance proximity** sensor, for accurate obstacles detection in close proximity.
- Excellent short distance linearity (>0.1cm)
- Low power autonomous mode with interrupts thresholds for user / object detection
- Fast ranging frequency (up to 100Hz)
- Same pinout of VL53L0CX, VL53L1CX/CB, VL53L3CX and VL53L4CX
- · Crosstalk compensation
- · Low power mode available
- Full set of product documentation & SW tools available on st.com





# STEVAL-AETKT1V2 Bidirectional current sensing TSC201x evaluation kit



STEVAL-AETKT1V2 – includes all gain configurations daughter boards

#### **Key products**

- TSC2010, TSC2011, TSC2012: High voltage, precision, bidirectional current sense amplifier
- · Different gain available

TSC2010: 20 V/VTSC2011: 60 V/V

TSC2012: 100 V/V

- · Can host different types of shunts
- · Both SMD and THT
- Allows simple setting of V<sub>REE</sub> and standby pin by jumpers
- Embeds RC filter. External wire connection
- TSC2010-2011-2012 on daughterboard
  - Wide input common mode voltage: 20 to 70 V
  - Offset voltage: ± 200 μV max
  - 2.7 to 5.5 V supply voltage
  - Gain error: 0.3% max
  - Offset drift: 5 µV/°C max





# STEVAL-AETKT2V1 Bidirectional current sensing TSC21x evaluation kit



Table 1. - Example of current ranges with 3mOhm shunt over different gain, Vcc and Vref

Device	Vcc (V)	Vref (V)	Range I₁ (A)	Range I <sub>2</sub> (A)
TSC213	3,3	2,5	4,33	16
	5	2,5	15,66	16
TSC210	3,3	2,5	1,08	4
	5	2,5	3,91	4
TSC212	3,3	2,5	0,21	0,8
	5	2,5	0,78	0,8

#### **Key products**

- TSC210, TSC211, TSC212, TSC213, TSC214, TSC215: series of zerodrift current sense amplifiers
- Different gain available: TSC210 (200 V/V), TSC211 (500 V/V), TSC212 (1000 V/V), TSC213 (50 V/V), TSC214 (100 V/V), TSC215 (75 V/V)

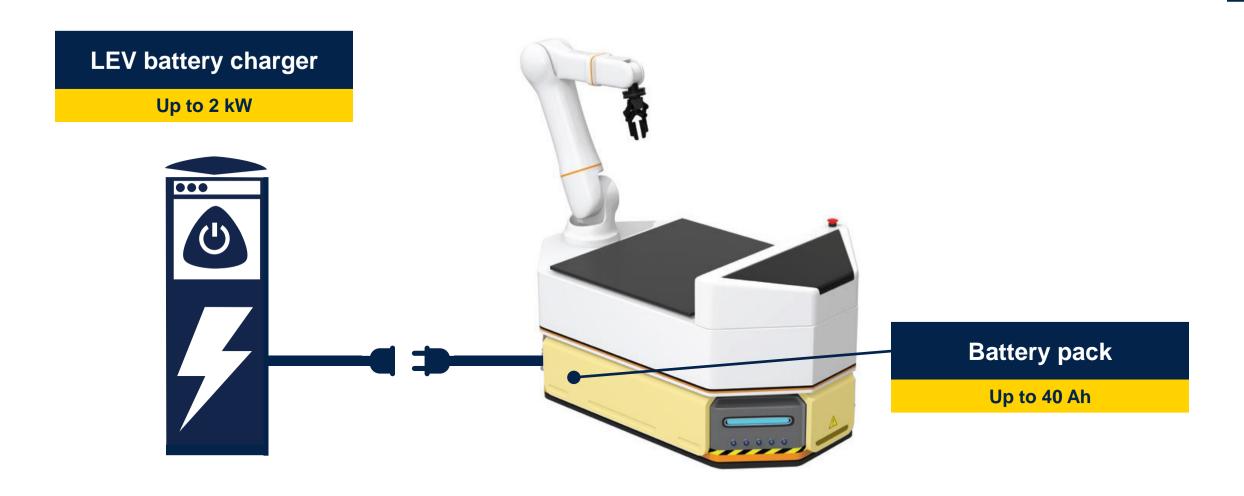
#### **Key features**

- Test with on-board 2512 size shunt area or with connector to external shunt
- Allows simple set of VREF from internal precision op-amp, voltage reference or external source
- TSC21x on daughter board
  - Input common mode voltage: 26V
  - Offset voltage: 35 μV (100 μV max)
  - 2.7 to 26V supply voltage
  - Offset drift: 0.1 μV/°C max
  - Quiescent current: 100 µA max



STEVAL-AETKT2V1 – includes TSC210 and TSC213 daughter boards

## Power supply / Battery charger







#### Main design challenges

- High-efficiency
- Thermal management

## 2.5 kW LEV charger

#### **Key products**

- L4984D: CCM PFC controller
- · L6699D: LLC controller
- **STW57N65M5**: HV MOSFET TO247
- STO67N60DM6: HV MOSFET TO-LL pack
- STPSC20H065CW: SiC Diode
- STM32G072CBT6: MCU-ARM Cortex- M0+
- L6491: Half bridge gate driver
- Vlper16LN: Off-line converter

- Input voltage range: 90 V AC to 265 V AC
- Multi battery chemistry charger design: lead-acid and Li-ion with a nominal voltage of 48 V (40 V DC to 60 V DC)
- PFC Efficiency: > 97.5 %
- LLC Efficiency: > 96%
- Power Factor (PF): > 0.9 from 10 % rated load
- THD: < 10% from 20 % of the load at high-line
- CAN Communication
- Battery chemistry selection: by switch and CAN/RS485
- Battery size: by MENU switch combination and CAN/RS485



# Our technology starts with You



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