# My basic AI notebook (tips that I think matter)

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September 21, 2020

#### 1 Math

A vector is a  $x \times 1$  matrix.

Vector  $\vec{x}$  has a Weight property which indicates its travel distance (Euclidean). Weight of  $\vec{x}$  is indicated by  $||\vec{x}||$ .

Euclidean or Normal distance is calculated like below where Ds is the number of dimensions:

$$d(p,q) = d(q,p) = \sqrt{\sum_{i=1}^{Ds} (q_i - p_i)^2}$$
 (1)

## 2 Not-Math

## 2.1 Hypothesis

 $h_{\Theta}(x)$  is the example function for  $\Theta$  parameters as in  $h_{\Theta}(x) = \Theta^T x$ . A good h gives a correct answer y for any given x.

#### 2.2 Cost function

J(x) is the difference between a guessed answer  $(h_{\Theta})$  and the correct one. In the simplest form:

$$J(x) = h_{\Theta}(x) - y \tag{2}$$

Linear-Regression J for a set like  $x = \{(x_1, y_1), (x_2, y_2), \dots, (x_m, y_m)\}$ :

$$J(x) = \frac{\sum_{i=1}^{m} (h_{\Theta}(x_i) - y_i)^2}{2m}$$
 (3)

The power 2 prevents negative values from cancelling out the positive ones. Absolute function (|x|) can be used as well. The reason that the power 2 function is more used is that it penalizes outlier values exponentially.

### 2.3 Logistic/Sigmoid function

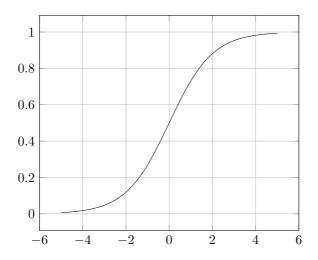
$$g(x) = \frac{L}{1 + e^{-k(x - x_0)}} \tag{4}$$

Where

 $x_0$  = the x value of the sigmoid's midpoint (default=0),

L = the curve's maximum value (default=1),

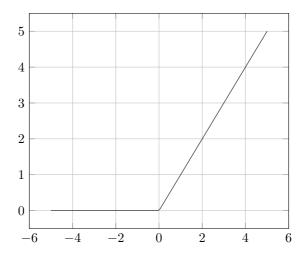
k = the logistic growth rate or steepness of the curve (default=1).



# 2.4 ReLU

**Rectified Linear Unit** 

$$\sigma(x) = R(x) = \max(0, x) \tag{5}$$



# 3 Normalization

Normalization aims to reduce processing required or simplifying values.

$$s = \max(x) - \min(x) \quad \mathsf{OR} \quad s = \underbrace{\sigma(x)}_{\mathsf{std}} \tag{6}$$

## 3.1 Feature Scaling

By dividing a constant, s, to x in order to make the change range closer to  $-1 \le x \le 1$ , we scale the features.

$$x' = \frac{x}{s} \tag{7}$$

To rescale a range between an arbitrary set of values [a,b], the formula becomes:

$$x' = \frac{(x - \min(x))(b - a)}{s} \tag{8}$$

## 3.2 Mean Noramlization

$$x' = \frac{x - \overbrace{\mu}^{\bar{x}}}{s} \tag{9}$$

## 3.3 Making decision based on decision boundary

For any given decision boundary  $\vec{d}$ , there is a perpendicular vector,  $\vec{w}$ , to it from the origin ((0,0)).

To determine if unknown vector  $\vec{u}$  if over  $\vec{d}$  or not we check if  $\vec{u} \cdot \vec{w} + bias > 0$  or not.

If  $\vec{u} \cdot \vec{w} + bias > 0$ ,  $\vec{u}$  is over  $\vec{d}$ . else If  $\vec{u} \cdot \vec{w} + bias < 0$ ,  $\vec{u}$  is not over  $\vec{d}$ . else If  $\vec{u} \cdot \vec{w} + bias = 0$ ,  $\vec{u}$  is on the decision boundary  $\vec{d}$ .