NN Models:

-) There one different available NN Models.

1) McCulloch-Pitts Namon (earliest) LIM-P Neuron (1943)

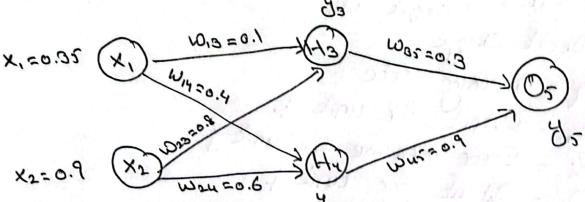
2) Perception MN

18lock (1962), Minsly-Papert (1969)

3) Adaptive Linear MM

a) Multiple Adoptive Linear MN

Giradient Decenti-



Activation Function (AF) = Signoid AF

Actual Output Learning Rate

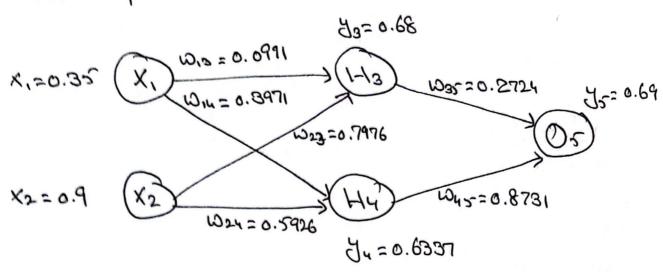
Forward Pass (propagation):

Compute you y & ys

J; = F(ai) = 1+ 0-0; aij = 5, (wij * xi)

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a, = (w10 + x1) + (w20 + x2)
                                                     12)
    = (0.1 x 0.35) + (0.8 x 0.9) = 0.755
3= f(a) = 1/(1+ e.755) = 0.68
a2 = (w, x x,) + (w24 x x2)
    = (0.4 × 0.35) + (0.6 × 0.9) = 0.68
Un = 8(az) = 1/(1+ e-0.68) = 0.6937
a3 = (w35 * c42) + (w45 x 244)
    = (0.3 x0.68) + (0.9 x0.6337) = 0.801
ys = f(a3) = 1/(1+e-0.801) = [0.69] (Network Output)
  So
        Error = 9 target - 7 = 0.5 - 0.69 = 70.19
Now Weight Change
      U = Jeaning eate
      ti = Output for unit i.
      8: = Escor measure for unit i
      O; = Output for unit j.
          DW: = N 8; 0;
                                       : if it's Output unit
          8; = 0; (1-0;)(E; -0)
                                     ! if i is hidden unit
          8; = 0; (1-0;) & 8, WK
Backwark Pass (propagation):
           Compute 83,84 & 85
 For output unit
              85 = 45 (1-75) (AFORTER - 75)
                = 0.69 (1-0.69) (0.5-0.69)
                 = -0.0406
```

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For hidden unit:
          80 = 93 (1-73) (035 ×85)
            = 0.68 (1-0.68) ( == 0.3 x -0.0406)
            = -0.00265
    84 = 44 (1-74) (Bus x85)
       = 0.6637 x (1-0.6337) (0.9 x -0.0406)
       2800.0- =
Comput New Weights
       DW; = 78:0;
Dwg= 78544
     = 1 x (-0.0406) x 0.6687 = -0.0269
Was(New) = Dwas + was(OId) = -0.0269 + (0.9)
                        = 0.8731
Wm = 78 x x1
   = 1 x (-0.0082) x0.35 = -0.00287
Awm (New) = Dwm + wm (01d)
          = -0.00287 +0.4 = 0.3971
Similarly
                    8; Xi N Updated Wij
               \omega_{ii}
              0.1 -0.00265 0.35 1 0.6991
              0.8 -0.00265 0.9 1 0.7976
   2
             0.4 -0.0082 0.35 1
                                         0.3971
         4
   1
                                        0.5926
       4
               0.6 -0.0082 0.9 1
    2
               0.3 -0.0406 0.68 1 0.2724
   3
         5
               0.9 _0.0406 0.6337 1 0.8731
   4
```



$$a_1 = (\omega_{19} * sx_1) + (\omega_{29} * sx_2)$$

= $(0.0991 \times 0.35) + (0.7976 \times 0.9) = 0.7525$
 $3 = f(a_1) = 1 / (1 + e^{-0.7525}) = 0.6797$

$$a_2 = (\omega_{,n} * x_1) + (\omega_{2n} * x_2)$$

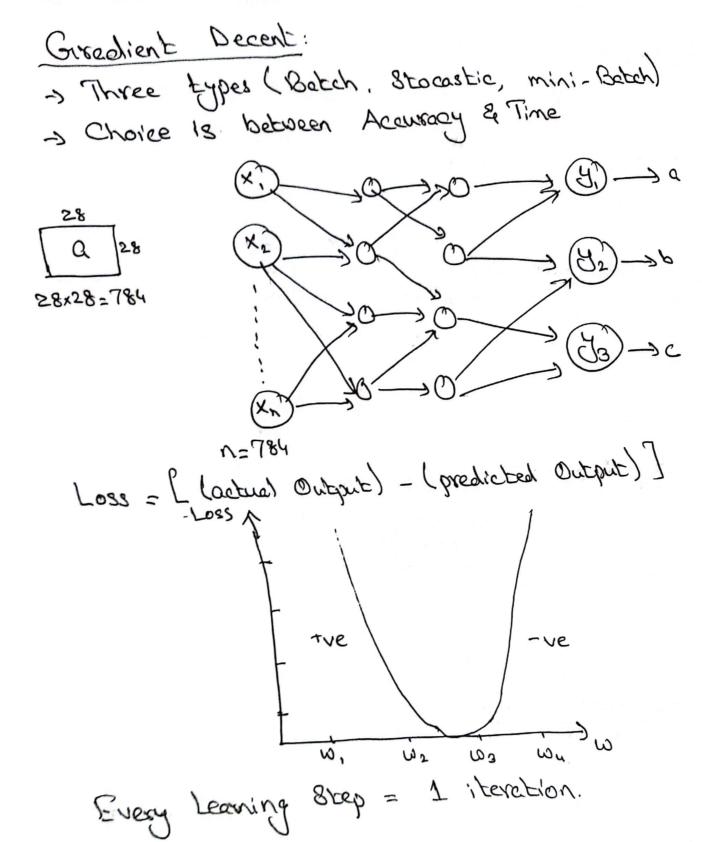
= $(0.3971 \times 0.35) + (0.5926 \times 0.9) = 0.6723$
 $y_n = f(a_2) = 1/(1 + e^{-0.6723}) = 0.6620$

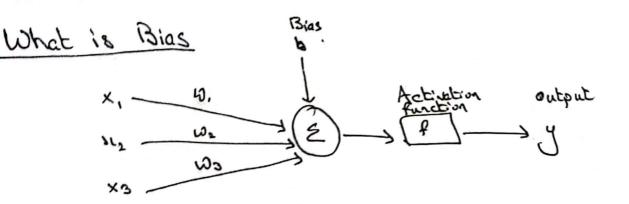
$$a_3 = (\omega_{35} \times J_3) + (\omega_{45} \times J_4)$$

$$= (0.2724 \times 0.6797) + (0.8731 \times 0.6620)$$

$$= 0.7631$$

$$= (0.6820) (Network Output)$$





-> Bias can shift the AF. y= mx + c -> Used to control AF (triggering, delay, steepness). -> Used to control AF (triggering, delay, steepness).

> y = m x + C weight Bias

