

# Detecting Exoplanets and recovering Parameters

A short recap of my work in week 3

# What did Tamanini and Danielski do?

1. Steal the important equations for the waveform of the strain  $h(t)$  from Cutler  $\rightarrow h_{I,II}(t) = \frac{\sqrt{3}}{2} A_{I,II}(t) \cos \left[ \Psi_{obs}(t) + \Phi_{I,II}^{(p)}(t) + \Phi_D(t) \right]$

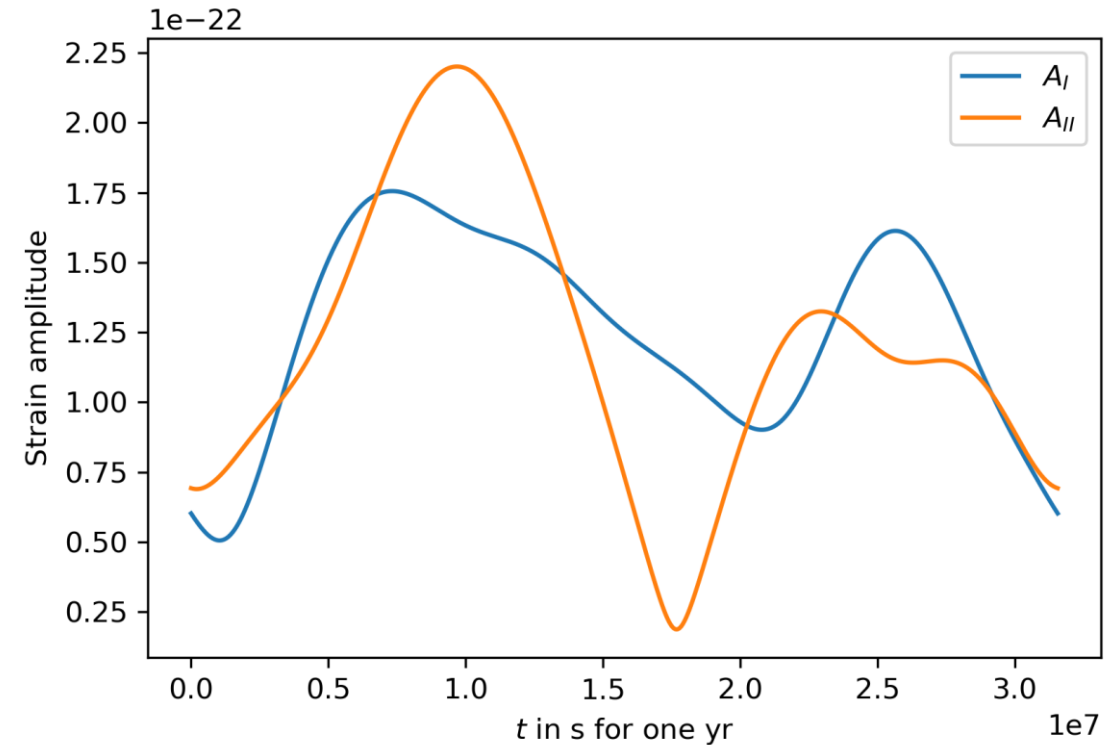
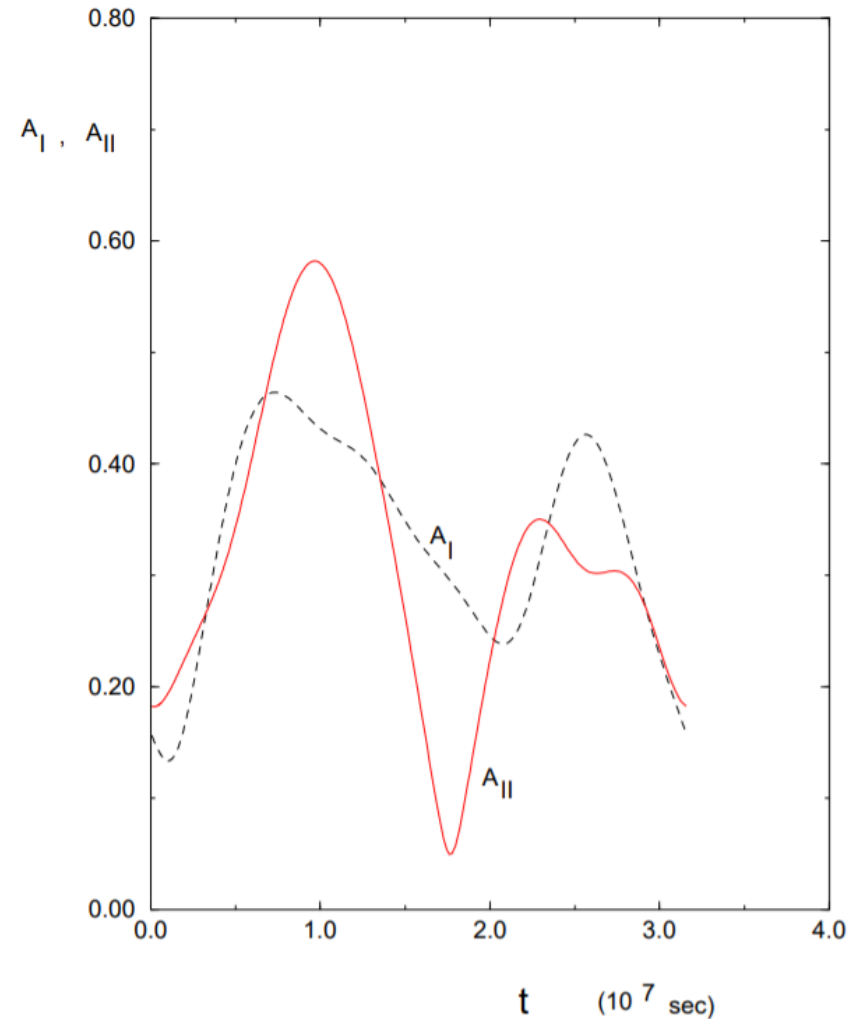
2. Look at the Doppler-signal of a circumbinary exoplanet:  
$$f_{obs}(t) = \left( 1 + \frac{v_{\parallel}(t)}{c} \right) f_{GW} = \left( 1 - \frac{K}{c} \cos \left( \frac{2\pi}{P} t + \varphi_0 \right) \right) f_{GW}$$

3. Derive  $\frac{\partial h_{I,II}}{\partial \lambda}(t)$  analytically to compute numerically the integral

$$\Gamma_{ij} = \frac{2}{S_n(f_0)} \sum_{\alpha=I,II} \int_0^{T_0} dt \frac{\partial h_{\alpha}}{\partial \lambda_i}(t) \frac{\partial h_{\alpha}}{\partial \lambda_j}(t)$$

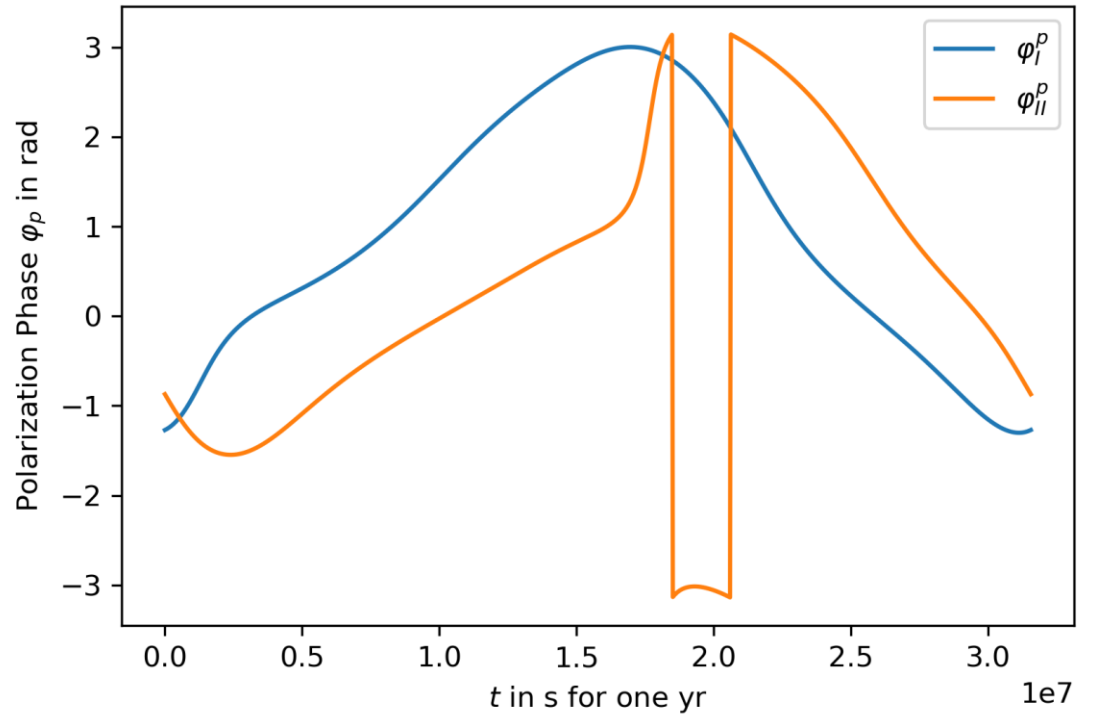
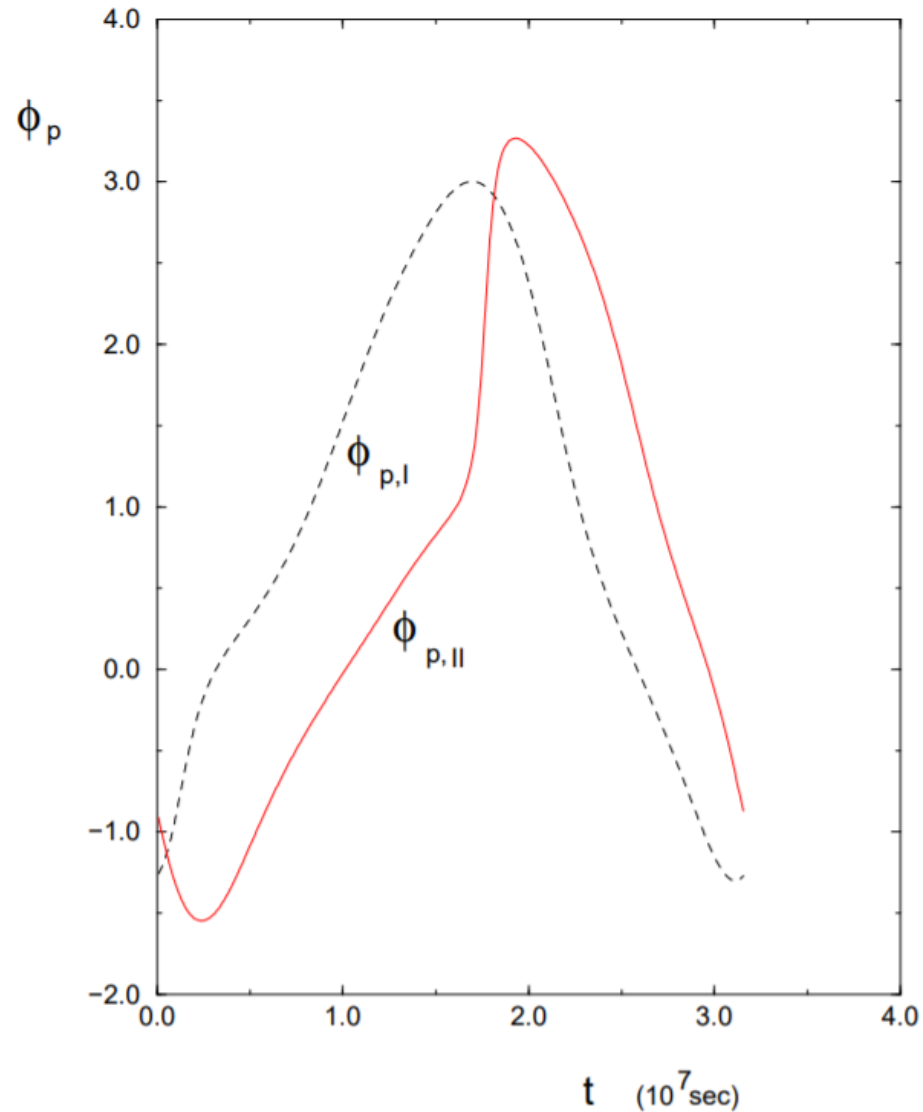
4. The inverse of the Fisher matrix is the covariance matrix  $\Sigma_{ij} = (\Gamma^{-1})_{ij}$  with  $\sigma_i^2 = \Sigma_{ii} \rightarrow$  After numerical inversion we are done ☺

# 1. Steal from Cutler: Amplitude



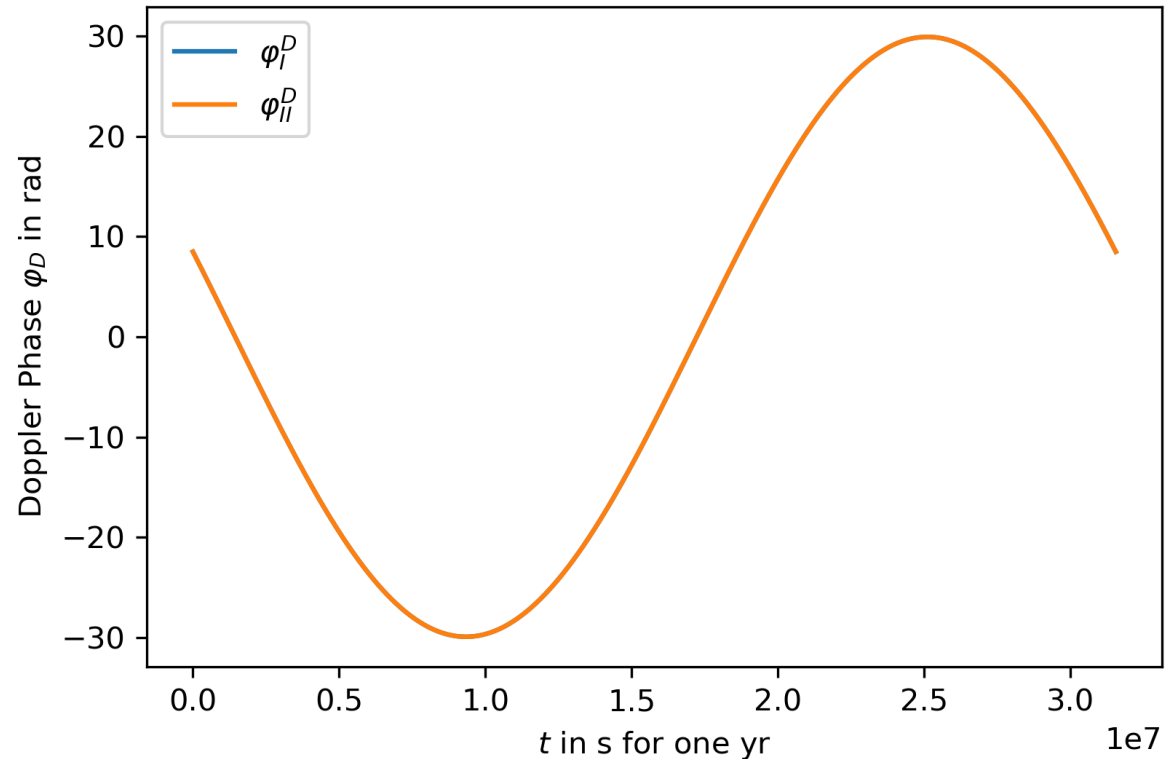
The amplitude and pattern function of course depends strongly on the ecliptic coordinates of the source – thankfully Tamanini and Danielski used the same example coordinates to place their binary as Cutler

# 1. Steal from Cutler: Polarization Phase



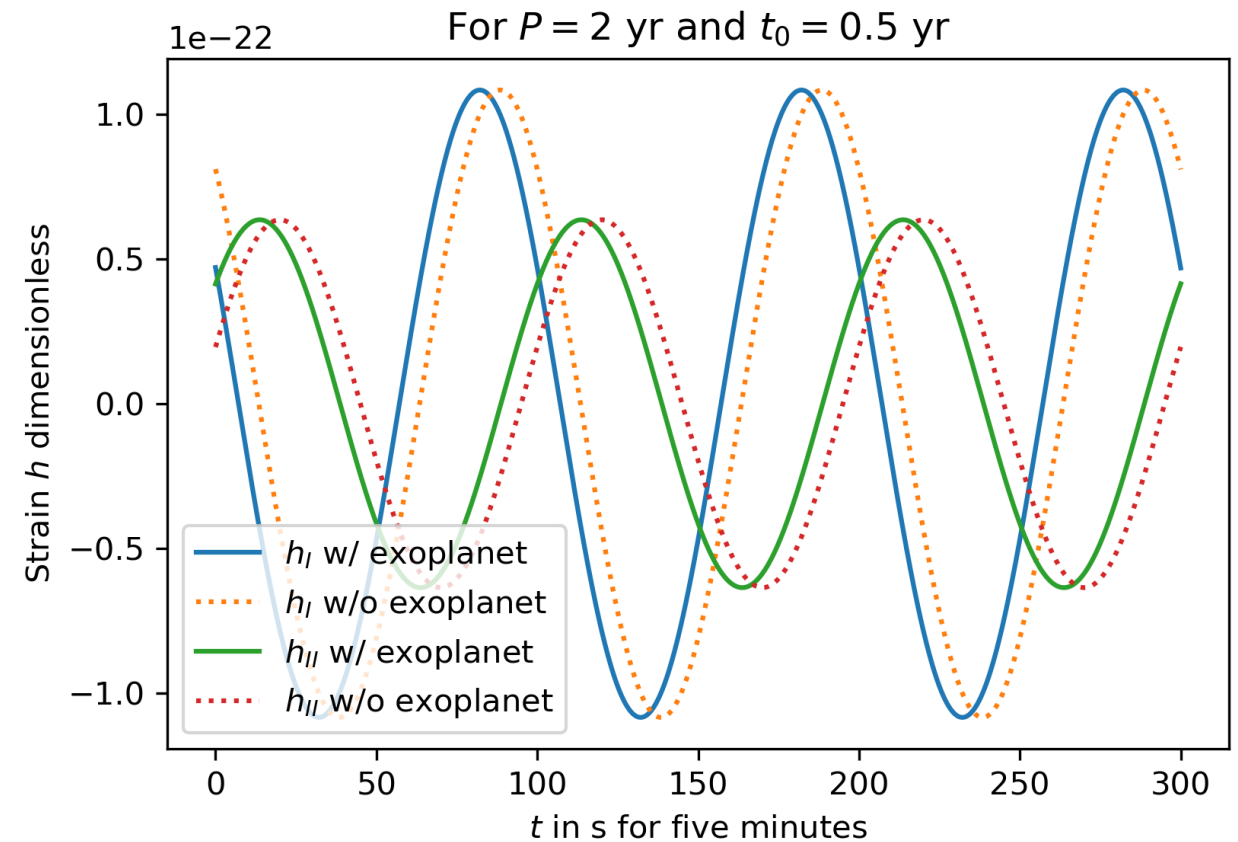
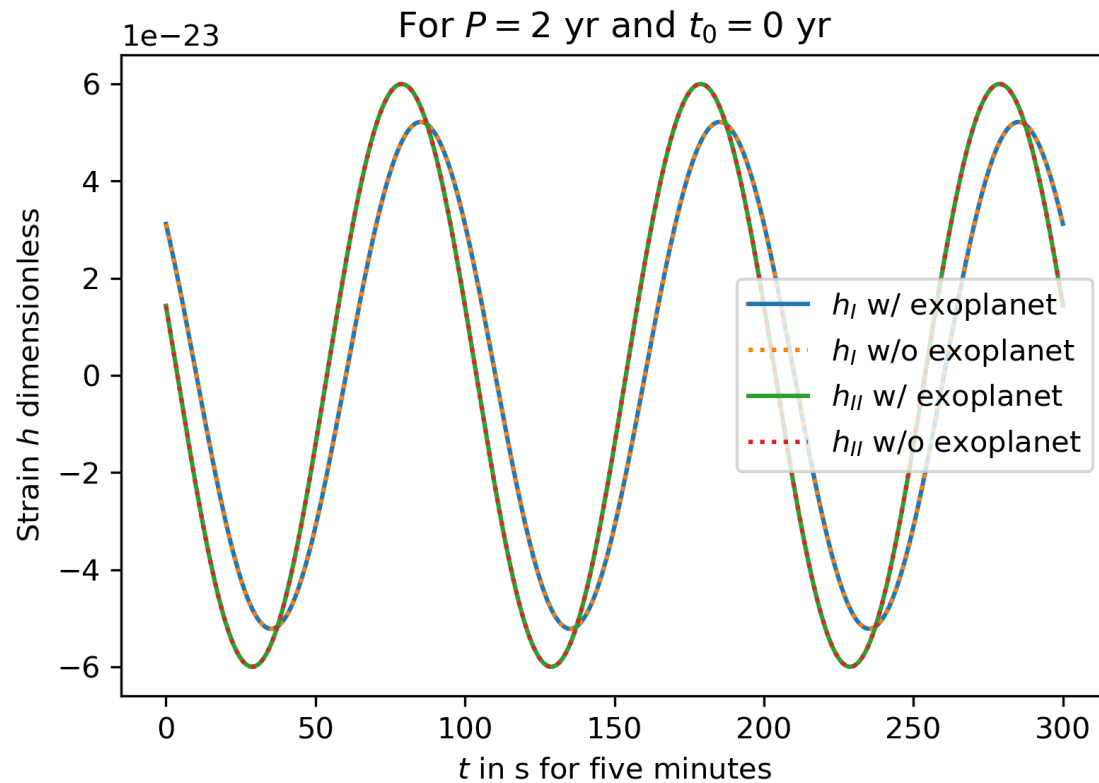
Note the incontinuity due to  $2\pi$  modulus

# 1. Steal from Cutler: Doppler Phase



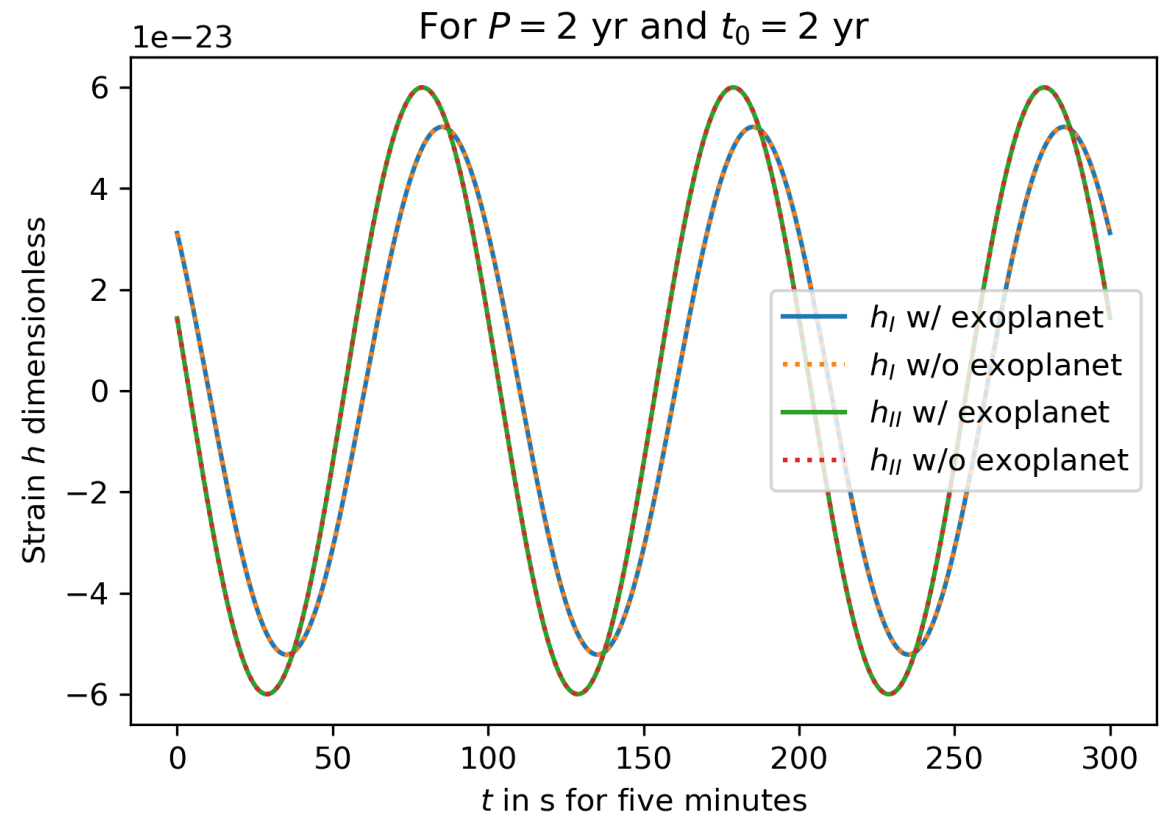
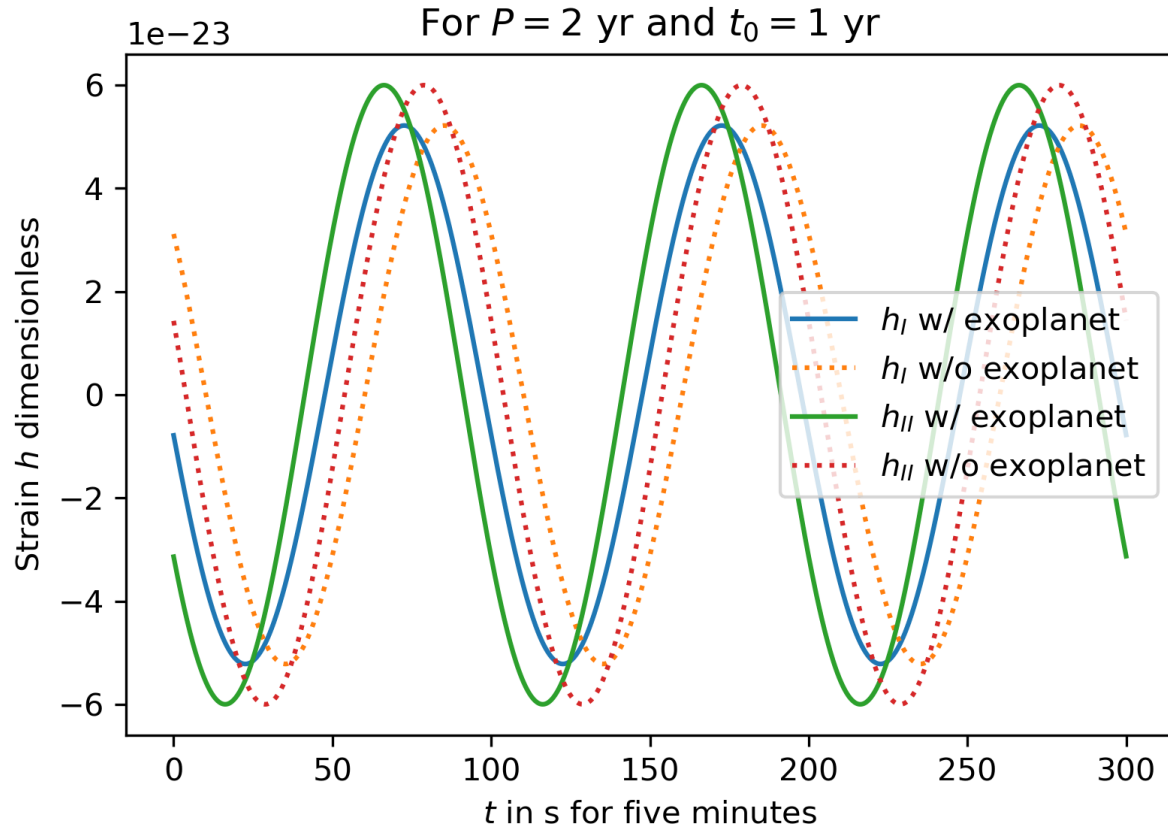
The amplitude depends on the GW frequency as it should, and it should be the same for the two arms (same barycenter)

## 2. Look at the Doppler signal of CBPs



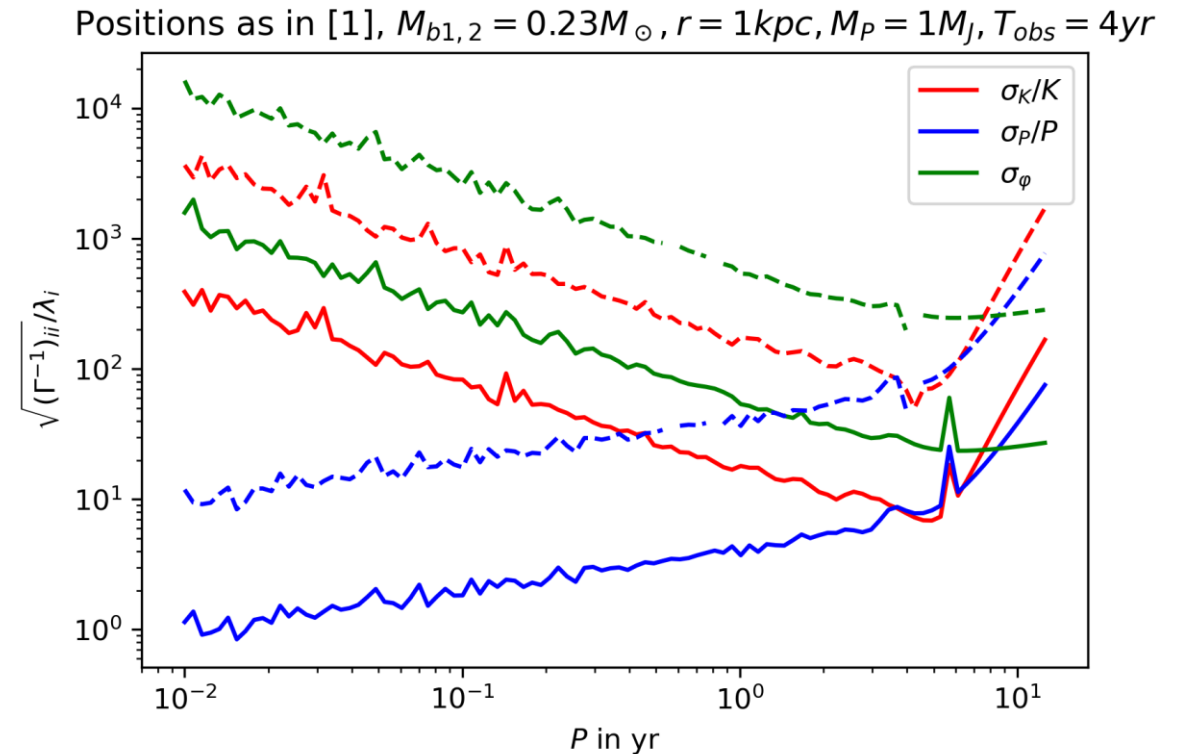
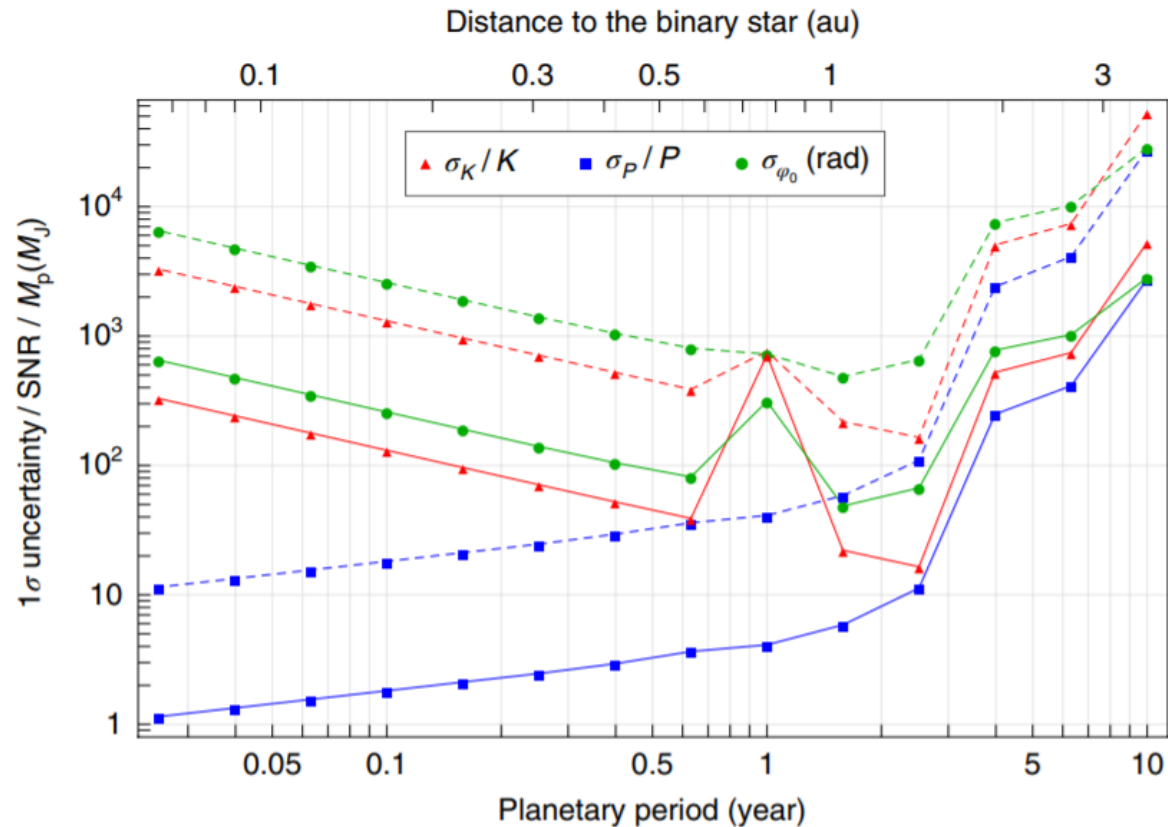
One can see the desyncing due to the presence of an exoplanet quite clearly, here a shift in the waveform due to an exoplanet of  $5 M_J$  over half a year... (different start time of the detector  $t_0$ )

## 2. Look at the Doppler signal of CBPs



...but after two years we will sync up again (as we should)

### 3. Compute the uncertainties



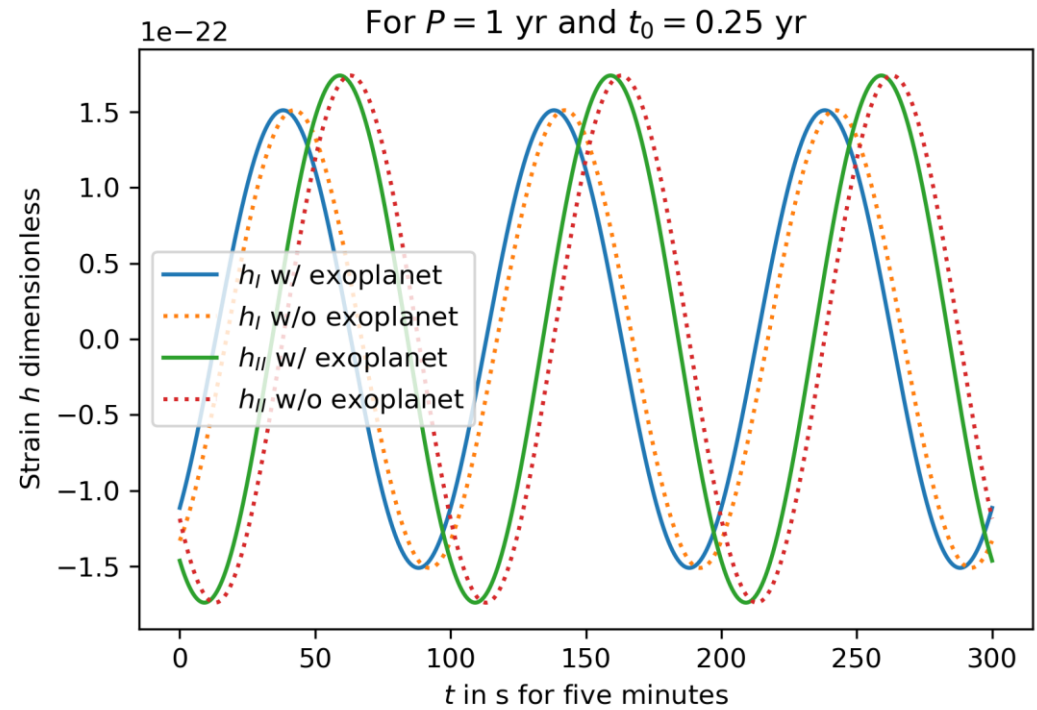
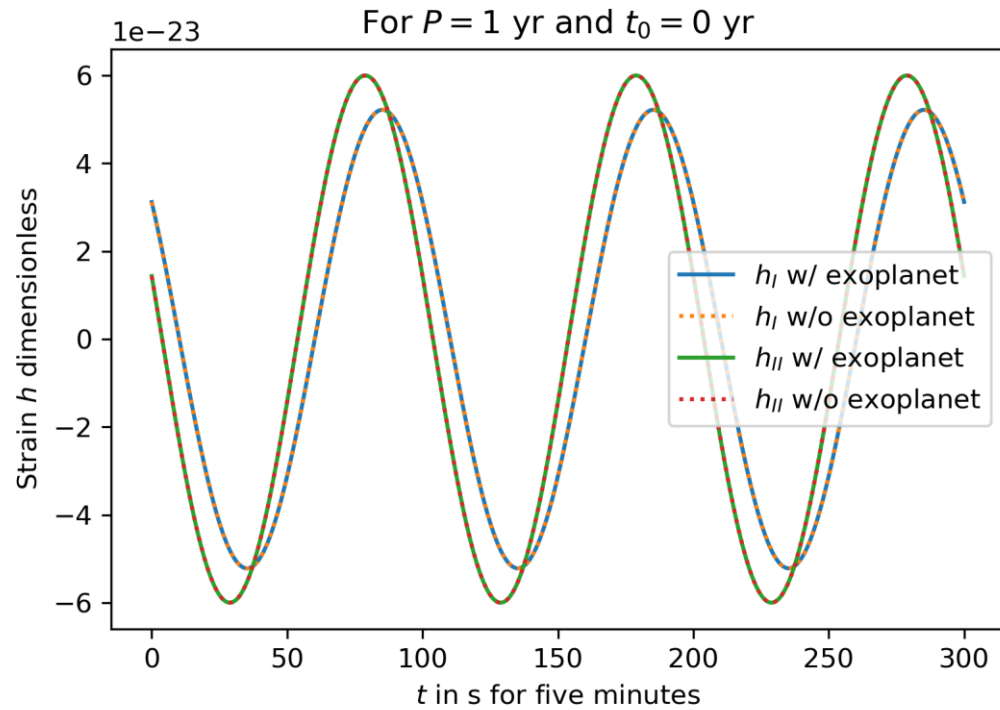
It's quite similar, but: It's not the same! Where is the degeneracy at 1 yr?

Note #1: Wigliness probably due to floating point errors in integration + matrix inversion

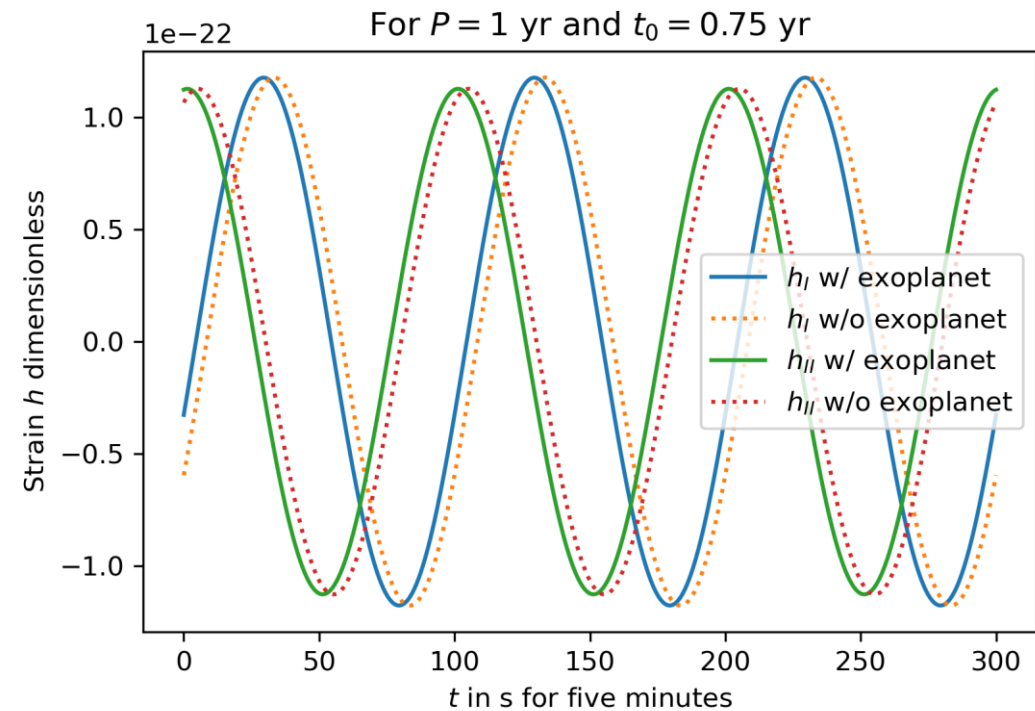
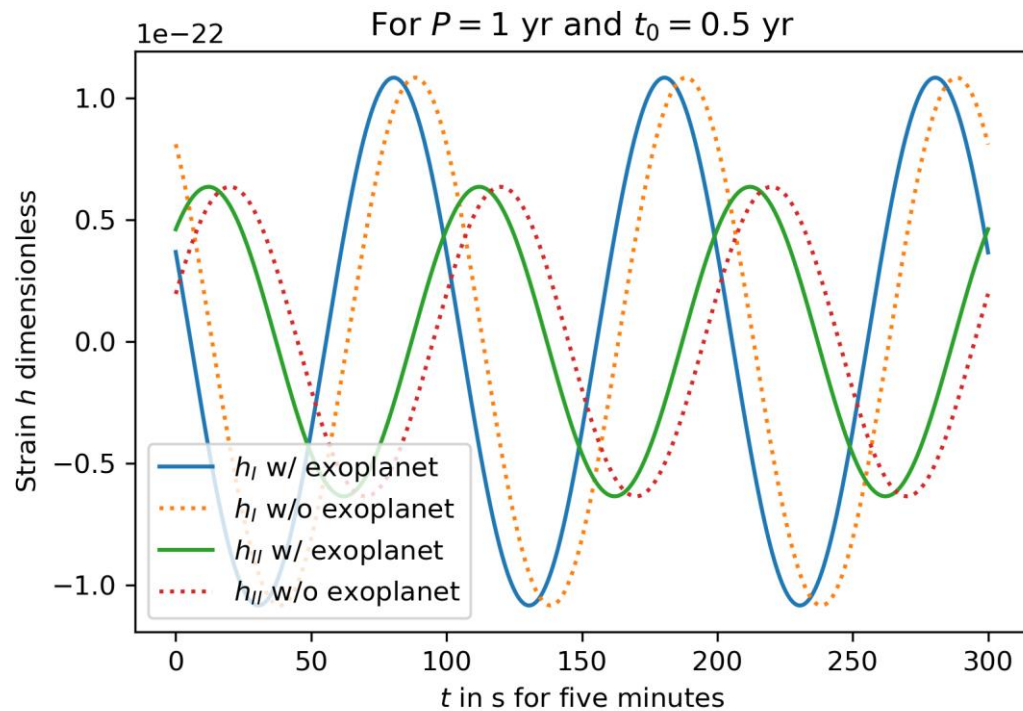
Note #2: Different amplitude probably due to me using the wrong strain sensitivity, WIP



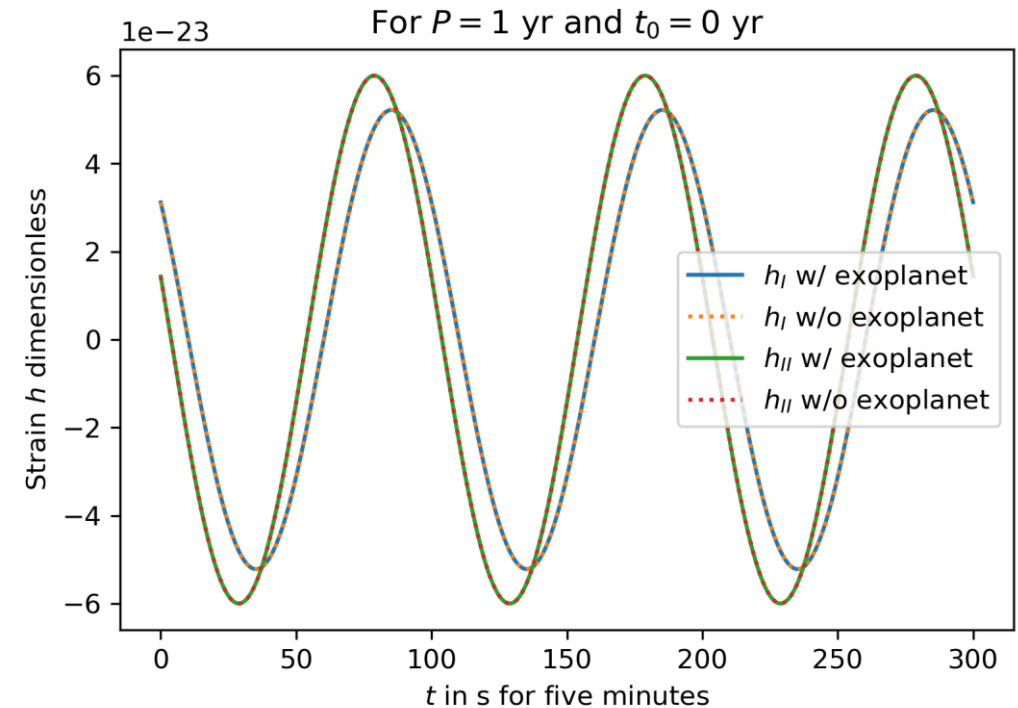
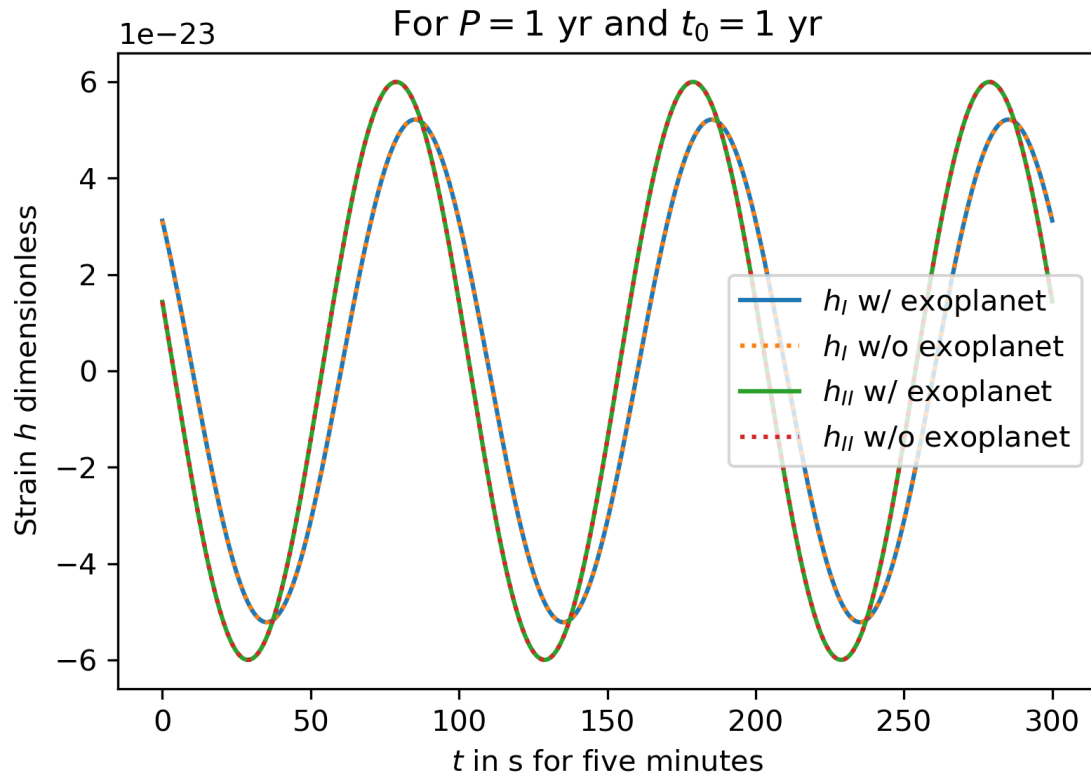
## 4. Why don't I see the degeneracy at $P=1$ yr?



## 4. Why don't I see the degeneracy at $P=1$ yr?



## 4. Why don't I see the degeneracy at $P=1$ yr?



I don't see exactly, why there should be one: The amplitude of the frequency shift is still given by  $K$  and should in principle be read out by a search algorithm independent of the  $P=1$  yr thing  
-> I'm still looking for bugs in my code though

## 5. New inputs

- The waveform is indeed quite important: To repeat the same approach with IceCube, all I'd need is a parametric line of sight between the detector and the spacecrafts for each detection period  
-> Then we could also think about combining measurements
- The uncertainties of the parameters scale  $\sigma \propto \text{SNR}$  and actually the fisher matrix estimation of the uncertainties will be the same as for example a log-likelihood parameter estimation of the real data only for  $\text{SNR} \gg 1$  (see Maggiore eq. 7.73 in Chapter 7, we have to ignore a term  $O(\text{SNR})$ ) which could become quite problematic for IceGiant
- Could we maybe meet and talk next week for lunch or coffee?