ACTIVITY: MODELLING A CUBE (from CMU lecture 01)

Suppose a cube is:
- centered at origin
- has dimensions 2 × 2 × 2
- edges aligned with x/y/z axis

coordinates:

A: (1, 1, 1) D: (-1, -1, 1)

B: (-1, 1, 1) E: (1, 1, -1)

C: (+1, -1, 1) F: (-1, 1, -1)

G: (1, -1, -1)

H: (-1, -1, -1)

We now have to find the edges:

AB, CD, EF, GH, AC, BD, EG, FH, AE, CG, BF, DH.

This is called the modelling stage, where we find out what to place where and how.

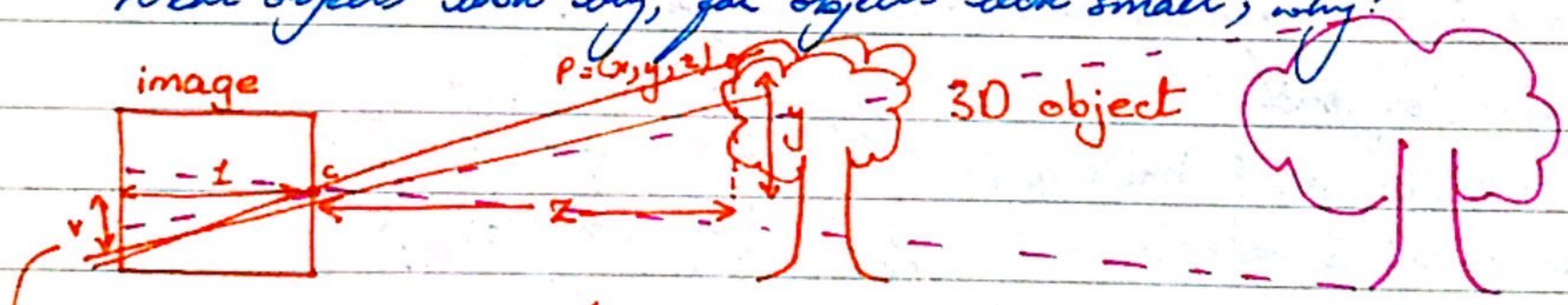
How do we draw this 3D shape as a 2D flat image?

This process is called rendering.

3D coordinates —map (how?)→ 2D coordinates

1. Perspective Projection

- Near objects look big, far objects look small, why?



$\frac{v}{1} = \frac{y}{x}$ horizontal coordinate

$v = y/x$ $u = x/z$

This means that to go from 3D to 2D, all you have to do is divide by z.

Let's try it

- Assume camera c is at (2, 3, 5)
- Convert (x, Y, Z) to (u, v)
  1. Subtract c from (X, Y, Z) to get (x, y, z) (3D location of points relative to the camera).
  2. divide (x, y) by z to get (u, v)
- Draw a line between (u1, v1) and (u2, v2)

Let's try some of them

A (1, 1, 1) - (2, 3, 5)
= (-1, -2, -4)
(-1, -2) ÷ -4 = (1/4, 1/2)

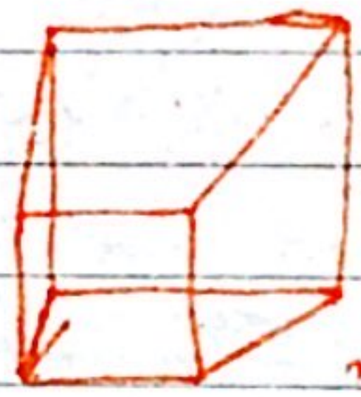
B. (-1, 1, 1) - (2, 3, 5)
(-3, -2, -4)
(-3, -2) ÷ -4 = (3/4, 1/2)

C. (1, -1, 1) - (2, 3, 5)
(-1, -4, -4)
(-1, -4) ÷ -4 = (1/4, 1)

D. (-1, -1, 1) - (2, 3, 5)
(-3, -4, -4)
(-3, -4) ÷ -4 = (3/4, 1)

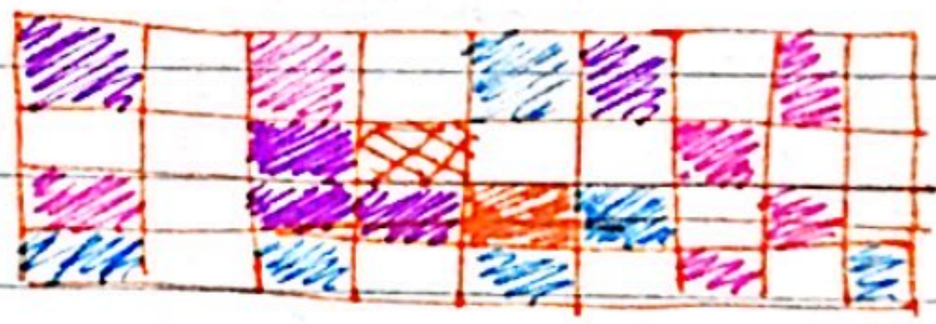
and so on.

E: (1/6, 1/3)
F: (1/2, 1/3)
G: (1/6, 2/3)
H: (1/2, 2/3)

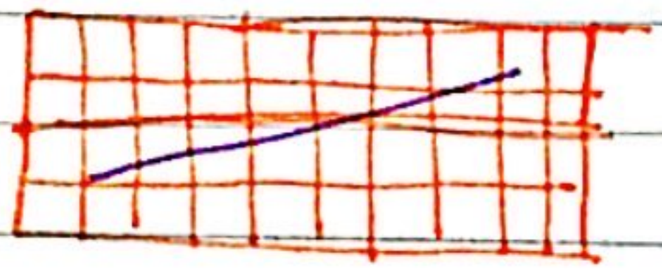


you come up with something like this by implementing the algorithm

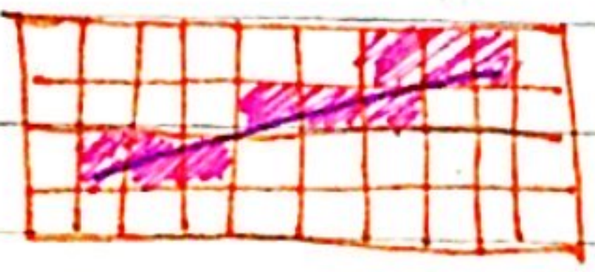
How to draw lines on a computer?
↳ how are images represented on a computer? are "rasterise"
- colours on a grid.
- each box, i.e. pixel, holds a numerical value.



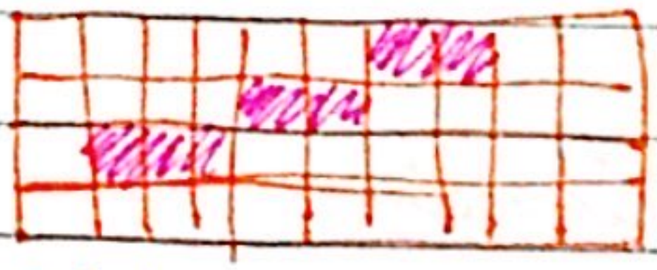
RASTERIZATION



criteria: every pixel line touches:



criteria: diamond rule.



↳ used by modern GPUs.

Incremental Line Rasterization Algorithm

```
v = v1
for (u = u1, u < u2, u++){
    v += s
    draw (u, round(v))
}
```

integer closest to current v value