## **Geometry of Surfaces**

5CCM223A/6CCM223B

Video 15 Length of curves on surfaces

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Let  $\sigma: U \to \mathbb{R}^3$  be a regular surface patch and

$$\gamma: (\alpha, \beta) \to \mathbb{R}^3 , t \mapsto \sigma(u(t), v(t))$$

be a curve on the surface  $S = \sigma(U)$ . The CHAIN RULE implies

$$\dot{\gamma}(t) = \sigma_u(u(t), v(t))\dot{u}(t) + \sigma_v(u(t), v(t))\dot{v}(t)$$
  $\dot{z} = \frac{d}{dt}$ 

or briefly

$$\dot{\gamma} = \sigma_u \dot{u} + \sigma_v \dot{v}$$

Then

$$\|\dot{\gamma}\|^2 = (\sigma_u \cdot \sigma_u)\dot{u}^2 + 2(\sigma_u \cdot \sigma_v)\dot{u}\dot{v} + (\sigma_v \cdot \sigma_v)\dot{v}^2 = E\dot{u}^2 + 2F\dot{u}\dot{v} + G\dot{v}^2$$

with

$$E = \sigma_u \cdot \sigma_u$$
,  $F = \sigma_u \cdot \sigma_v$ ,  $G = \sigma_v \cdot \sigma_v$ 



Let  $t_0 \in (\alpha, \beta)$  and consider the arc length function

$$s(t) = \int_{t_0}^{t} \left\| \frac{d\gamma}{dx} \right\| dx = \int_{t_0}^{t} \left( E \frac{du^2}{dx^2} + 2F \frac{du}{dx} \frac{dv}{dx} + G \frac{dv^2}{dx^2} \right)^{\frac{1}{2}} dx$$
$$= \int_{t_0}^{t} \left( E du^2 + 2F du dv + G dv^2 \right)^{\frac{1}{2}}$$

The expression

$$Edu^2 + 2Fdudv + Gdv^2$$

is called the first fundamental form of  $\sigma$ . Since  $s(t) = \int_{t_0}^t \left(ds^2\right)^{\frac{1}{2}}$ , we also write

$$ds^2 = Edu^2 + 2Fdudv + Gdv^2$$

The first fundamental form depends on the parametrization but not on the curve  $\gamma$ 

#### First fundamental form of plane

$$\sigma(u,v)=a+up+vq$$

with  $a, p, q \in \mathbb{R}^3$  and p, q linearly independent. Then  $\sigma_u = p$  and  $\sigma_v = q$ . Thus

$$E = \sigma_u \cdot \sigma_u = \|p\|^2$$
,  $F = \sigma_u \cdot \sigma_v = p \cdot q$ ,  $G = \sigma_v \cdot \sigma_v = \|q\|^2$ 

We can always choose  $p, q \in \mathbb{R}^3$  with ||p|| = 1 = ||q|| and  $p \cdot q = 0$ . Then the first fundamental form of the plane is of the form

$$ds^2 = du^2 + dv^2$$

#### First fundamental form of sphere

$$\begin{split} &\sigma(\theta,\varphi) = (\cos(\theta)\cos(\varphi),\cos(\theta)\sin(\varphi),\sin(\theta))\\ &\sigma_{\theta}(\theta,\varphi) = (-\sin(\theta)\cos(\varphi),-\sin(\theta)\sin(\varphi),\cos(\theta))\\ &\sigma_{\varphi}(\theta,\varphi) = (-\cos(\theta)\sin(\varphi),\cos(\theta)\cos(\varphi),0) \end{split}$$

The coefficients of the first fundamental form are

$$E = \sigma_{\theta} \cdot \sigma_{\theta} = 1$$
,  $F = \sigma_{\theta} \cdot \sigma_{\varphi} = 0$ ,  $G = \sigma_{\varphi} \cdot \sigma_{\varphi} = \cos(\theta)^2$ 

The first fundamental form of the sphere is

$$ds^2 = d\theta^2 + \cos(\theta)^2 d\varphi^2$$

#### First fundamental form of generalized cylinder

$$\sigma(u, v) = (f(u), g(u), v)$$
  

$$\sigma_u(u, v) = (\dot{f}(u), \dot{g}(u), 0)$$
  

$$\sigma_v(u, v) = (0, 0, 1)$$

The coefficients of the first fundamental form are

$$E = \sigma_u \cdot \sigma_u = \dot{f}^2 + \dot{g}^2$$
,  $F = \sigma_u \cdot \sigma_v = 0$ ,  $G = \sigma_v \cdot \sigma_v = 1$ 

Since  $\sigma$  is regular, also  $\gamma$  is regular. If we parametrize  $\gamma$  by arc length, then E=1 and the first fundamental form is

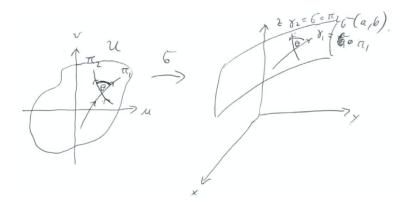
$$ds^2 = du^2 + dv^2$$

This is the same expression as for the plane!

Reparametrizations change E, F, G but not  $ds^2$  (Exercise!) Every surface has a conformal parametrization, that is, a parametrization for which E = G and F = 0.

**Proposition.** A surface parametrization  $\sigma: U \to \mathbb{R}^3$  is conformal if and only if for any two curves  $\pi_1 = (u_1, v_1)$ ,  $\pi_2 = (u_2, v_2)$  in U with  $\pi_1(t_0) = (a, b) = \pi_2(t_0)$  the angle of intersection of  $\pi_1$  and  $\pi_2$  at (a, b) is equal to the angle of intersection of  $\gamma_1 = \sigma \circ \pi_1$  and  $\gamma_2 = \sigma \circ \pi_2$  at  $\sigma(a, b)$ 

Briefly: Conformal parametrizations are angle-preserving parametrizations



*Proof.* Assume  $\sigma$  is conformal. Let  $\theta$  be the angle between  $\dot{\gamma}_1(t_0)$  and  $\dot{\gamma}_2(t_0)$ . We have  $\dot{\gamma}_i = \sigma_u \dot{u}_i + \sigma_v \dot{v}_i$  and

$$\cos(\theta) = \frac{\dot{\gamma}_{1} \cdot \dot{\gamma}_{2}}{\|\dot{\gamma}_{1}\| \|\dot{\gamma}_{2}\|}(t_{0}) 
= \frac{E\dot{u}_{1}\dot{u}_{2} + F(\dot{u}_{1}\dot{v}_{2} + \dot{v}_{1}\dot{u}_{2}) + G\dot{v}_{1}\dot{v}_{2}}{(E\dot{u}_{1}^{2} + 2F\dot{u}_{1}\dot{v}_{1} + G\dot{v}_{1}^{2})^{\frac{1}{2}}(E\dot{u}_{2}^{2} + 2F\dot{u}_{2}\dot{v}_{2} + G\dot{v}_{2}^{2})^{\frac{1}{2}}}(t_{0}) \quad (*)$$

Since  $\sigma$  is conformal, we have E = G and F = 0 and thus

$$\cos(\theta) = \frac{\dot{u}_1 \dot{u}_2 + \dot{v}_1 \dot{v}_2}{(\dot{u}_1^2 + \dot{v}_1^2)^{\frac{1}{2}} (\dot{u}_2^2 + \dot{v}_2^2)^{\frac{1}{2}}} \tag{**}$$

which is the angle between  $\dot{\pi}_1(t_0)$  and  $\dot{\pi}_2(t_0)$ . Thus  $\sigma$  is angle-preserving

Conversely, assume  $\sigma$  is angle-preserving, which means (\*) = (\*\*) for all curves  $\pi_1, \pi_2$  with  $\pi_1(t_0) = (a, b) = \pi_2(t_0)$ . Take

$$\pi_1(t) = (a+t,b) , \ \pi_2(t) = (a,b+t) , \ t_0 = 0$$

Then (\*) = (\*\*) gives 0 = F. Take

$$\pi_1(t) = (a+t,b+t)$$
,  $\pi_2(t) = (a+t,b-t)$ ,  $t_0 = 0$ 

Then (\*) = (\*\*) gives 0 = E - G.

## **Geometry of Surfaces**

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Video 16 Isometries of surfaces

Jürgen Berndt King's College London Plane and round cylinder have same first fundamental form.

plane ∼ round cylinder

Length of curve remains unchanged when deforming plane to round cylinder

expect different first fundamental form



 $\sigma_1: U_1 \to \mathbb{R}^3$ ,  $\sigma_2: U_2 \to \mathbb{R}^3$  regular surface patches,  $S_1 = \sigma_1(U_1)$ ,  $S_2 = \sigma_2(U_2)$ 

A map  $f: \mathcal{S}_1 \to \mathcal{S}_2$  is smooth if there exists a smooth map  $F: \mathcal{U}_1 \to \mathcal{U}_2$  with  $f \circ \sigma_1 = \sigma_2 \circ F$ 



A map  $f: \mathcal{S}_1 \to \mathcal{S}_2$  is a diffeomorphism if f is bijective and  $f, f^{-1}$  are smooth maps ( $\iff F: U_1 \to U_2$  bijective and  $F, F^{-1}$  smooth) Note: If  $\mathcal{S}_1 = \mathcal{S}_2 = \mathcal{S}$ ,  $f = \mathrm{id}_{\mathcal{S}_1}$ , then F is a reparametrization map A diffeomorphism  $f: \mathcal{S}_1 \to \mathcal{S}_2$  preserving the length of curves is called an isometry

 $\mathcal{S}_1$  and  $\mathcal{S}_2$  are isometric (or  $\sigma_1$  and  $\sigma_2$  are isometric) if there exists an isometry  $f: \mathcal{S}_1 \to \mathcal{S}_2$ . We write  $\mathcal{S}_1 \cong \mathcal{S}_2$  if  $\mathcal{S}_1$  and  $\mathcal{S}_2$  are isometric

The concept of isometric surfaces is independent of reparametrizations

**Theorem.** Two surfaces are isometric if and only if they have reparametrizations  $\sigma_1: U_1 \to \mathbb{R}^3$  and  $\sigma_2: U_2 \to \mathbb{R}^3$  with the same first fundamental form

*Proof.* Let  $\tilde{\sigma}_1: U_1 \to \mathbb{R}^3$ ,  $\tilde{\sigma}_2: U_2 \to \mathbb{R}^3$  be regular surface patches,  $\mathcal{S}_1 = \tilde{\sigma}_1(U_1)$ ,  $\mathcal{S}_2 = \tilde{\sigma}_2(U_2)$ . Let  $f: \mathcal{S}_1 \to \mathcal{S}_2$  be an isometry. There exists a bijective smooth map  $F: U_1 \to U_2$  so that

$$\begin{array}{c|c} U_1 \stackrel{F}{\longrightarrow} U_2 & U = U_1 \stackrel{F}{\longrightarrow} U_2 \\ \tilde{\sigma}_1 \bigg| & \int \tilde{\sigma}_2 & \sigma_1 = \tilde{\sigma}_1 \bigg| & \tilde{\sigma}_2 & \tilde{\sigma}_2 \\ S_1 \stackrel{F}{\longrightarrow} S_2 & S_1 \stackrel{F}{\longrightarrow} S_2 \end{array}$$

Define  $U = U_1$ ,  $\sigma_1 = \tilde{\sigma}_1 : U \to \mathcal{S}_1$ ,  $\sigma_2 = \tilde{\sigma}_2 \circ F : U \to \mathcal{S}_2$ .  $\sigma_2$  is a reparametrization of  $\tilde{\sigma}_2$ . Consider curves

$$\gamma_1(t) = \sigma_1(u(t), v(t)), \ \gamma_2(t) = \sigma_2(u(t), v(t)) = (f \circ \sigma_1)(u(t), v(t))$$

Since f is an isometry,  $\gamma_1, \gamma_2$  have the same length

$$\int_{t_0}^{t_1} \left( E_1 \dot{u}^2 + 2F_1 \dot{u}\dot{v} + G_1 \dot{v}^2 \right)^{\frac{1}{2}} dt = \int_{t_0}^{t_1} \left( E_2 \dot{u}^2 + 2F_2 \dot{u}\dot{v} + G_2 \dot{v}^2 \right)^{\frac{1}{2}} dt$$
Put  $u_0 = u(t_0)$ ,  $v_0 = v(t_0)$ 

$$(u(t), v(t)) = (u_0 + t - t_0, v_0) \Longrightarrow E_1 = E_2$$

$$(u(t), v(t)) = (u_0, v_0 + t - t_0) \Longrightarrow G_1 = G_2$$

$$(u(t), v(t)) = (u_0 + t - t_0, v_0 + t - t_0) \Longrightarrow F_1 = F_2$$

Thus  $\sigma_1$  and  $\sigma_2$  have the same first fundamental form

Conversely, assume that  $\sigma_1$  and  $\sigma_2$  have the same first fundamental form. Define  $f: \mathcal{S}_1 \to \mathcal{S}_2$  by  $f(\sigma_1(u,v)) = \sigma_2(u,v)$ . Let

$$\gamma_1(t) = \sigma_1(u(t), v(t)), \ \gamma_2(t) = \sigma_2(u(t), v(t)) = (f \circ \sigma_1)(u(t), v(t))$$

Length of  $\gamma_1,\gamma_2$  is obtained by integrating  $\left(E_2\dot{u}^2+2F_2\dot{u}\dot{v}+G_2\dot{v}^2\right)^{\frac{1}{2}}$ , which is the same for both surfaces by assumption. It follows that f preserves the length of curves and hence is an isometry.

plane  $\cong$  generalized cylinder  $\cong$  generalized cone

A tangent developable is the union of tangent lines to a regular curve  $\gamma$  in  $\mathbb{R}^3$  (can assume  $\|\dot{\gamma}\|=1$ ):

$$\sigma(u, v) = \gamma(u) + v\dot{\gamma}(u)$$

$$\sigma_{u}(u, v) = \dot{\gamma}(u) + v\ddot{\gamma}(u)$$

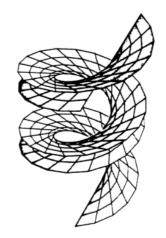
$$\sigma_{v}(u, v) = \dot{\gamma}(u)$$

$$(\sigma_{u} \times \sigma_{v})(u, v) = v\ddot{\gamma}(u) \times \dot{\gamma}(u) = v(\dot{\mathbf{t}} \times \mathbf{t})(u)$$

$$= v\kappa(u)(\mathbf{n} \times \mathbf{t})(u) = -v\kappa(u)\mathbf{b}(u)$$

Thus  $\sigma$  regular if and only if  $\kappa > 0$  and  $\nu \neq 0$ 

### The tangent developable of a circular helix



**Theorem.** Any tangent developable is isometric to (part of) a plane.

Proof. 
$$\sigma(u,v) = \gamma(u) + v\dot{\gamma}(u)$$
 
$$\sigma_u(u,v) = \dot{\gamma}(u) + v\ddot{\gamma}(u)$$
 
$$\sigma_v(u,v) = \dot{\gamma}(u)$$
 
$$E = (\sigma_u \cdot \sigma_u)(u,v) = \|\dot{\gamma}(u) + v\ddot{\gamma}(u)\|^2 = 1 + v^2\kappa(u)^2$$
 
$$F = (\sigma_u \cdot \sigma_v)(u,v) = (\dot{\gamma}(u) + v\ddot{\gamma}(u)) \cdot \dot{\gamma}(u) = 1$$
 
$$G = (\sigma_v \cdot \sigma_v)(u,v) = \|\dot{\gamma}(u)\|^2 = 1$$
 
$$ds^2 = (1 + v^2\kappa(u)^2)du^2 + 2dudv + dv^2$$

Tangent developable of a plane curve  $\tilde{\gamma}$  with curvature  $\kappa$  has the same first fundamental form (tangents fill out parts of a plane). Thus both surfaces are isometric

One can prove that a surface that is isometric to (part of) a plane is (part of)

- plane
- generalized cylinder
- generalized cone
- tangent developable

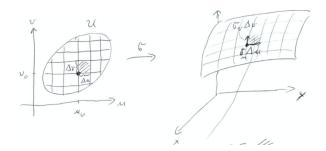
# **Geometry of Surfaces**

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Video 17 Surface area

Jürgen Berndt King's College London Let  $\sigma: U \to \mathbb{R}^3$  be a regular surface patch. Let R be a rectangle in U with side lengths  $\Delta u$  and  $\Delta v$ . Then, for small  $\Delta u$  and  $\Delta v$ , the area of  $\sigma(R)$  is approximately the area of the parallelogram with sides  $\sigma_u \Delta u$  and  $\sigma_v \Delta v$ :

$$\|\sigma_u \Delta u \times \sigma_v \Delta v\| = \|\sigma_u \times \sigma_v\| \Delta u \Delta v$$



Let  $\sigma:U\to\mathbb{R}^3$  be a regular surface patch and  $R\subseteq U$ . The area of  $\sigma(R)$  is

$$\mathcal{A}_{\sigma}(R) = \iint\limits_{R} \|\sigma_{u} \times \sigma_{v}\| dudv$$

Let  $\theta$  be the angle between  $\sigma_u$  and  $\sigma_v$ . Then

$$\begin{split} \|\sigma_{u} \times \sigma_{v}\|^{2} &= \|\sigma_{u}\|^{2} \|\sigma_{v}\|^{2} \underbrace{\sin(\theta)^{2}}_{1-\cos(\theta)^{2}} \\ &= \|\sigma_{u}\|^{2} \|\sigma_{v}\|^{2} - \underbrace{\|\sigma_{u}\|^{2} \|\sigma_{v}\|^{2} \cos(\theta)^{2}}_{(\sigma_{u}, \sigma_{v})^{2}} = EG - F^{2} \end{split}$$

Therefore

$$\mathcal{A}_{\sigma}(R) = \iint\limits_{R} \left(EG - F^2\right)^{\frac{1}{2}} du dv$$

**Proposition.** Area is unchanged by reparametrizations.

*Proof.* Let  $\sigma: U \to \mathbb{R}^3$  be a regular surface patch and  $\tilde{\sigma}: \tilde{U} \to \mathbb{R}^3$  be a reparametrization of  $\sigma$  with reparametrization map  $\phi: U \to \tilde{U}$ :

$$\tilde{\sigma}(\tilde{u}, \tilde{v}) = \tilde{\sigma}(\phi(u, v)) = \sigma(u, v)$$

The CHAIN RULE gives

$$\begin{split} \sigma_{u} &= \tilde{\sigma}_{\tilde{u}} \frac{\partial \tilde{u}}{\partial u} + \tilde{\sigma}_{\tilde{v}} \frac{\partial \tilde{v}}{\partial u} \;, \; \sigma_{v} = \tilde{\sigma}_{\tilde{u}} \frac{\partial \tilde{u}}{\partial v} + \tilde{\sigma}_{\tilde{v}} \frac{\partial \tilde{v}}{\partial v} \\ \sigma_{u} \times \sigma_{v} &= \underbrace{\left(\frac{\partial \tilde{u}}{\partial u} \frac{\partial \tilde{v}}{\partial v} - \frac{\partial \tilde{u}}{\partial v} \frac{\partial \tilde{v}}{\partial u}\right)}_{\det(J\phi)} \tilde{\sigma}_{\tilde{u}} \times \tilde{\sigma}_{\tilde{v}} \end{split}$$

Thus

$$\sigma_{\it u} \times \sigma_{\it v} = \det(J\phi)\tilde{\sigma}_{\tilde{\it u}} \times \tilde{\sigma}_{\tilde{\it v}}$$

Altogether,

$$\mathcal{A}_{\sigma}(R) = \iint\limits_{R} \|\sigma_{u} \times \sigma_{v}\| du dv$$

$$= \iint\limits_{R} |\det(J\phi)| \|\tilde{\sigma}_{\tilde{u}} \times \tilde{\sigma}_{\tilde{v}}\| du dv$$

$$= \iint\limits_{R} \|\tilde{\sigma}_{\tilde{u}} \times \tilde{\sigma}_{\tilde{v}}\| d\tilde{u} d\tilde{v} = \mathcal{A}_{\tilde{\sigma}}(R)$$

by Change of Variables Formula