## **Geometry of Surfaces**

5CCM223A/6CCM223B

Video 32 Theorema Egregium

Jürgen Berndt King's College London Recall: The Gaussian curvature K of a surface satisfies

$$K = \kappa_1 \kappa_2 = \frac{LN - M^2}{EG - F^2}$$

 $\kappa_1, \kappa_2$  principal curvatures

 $Ldu^2 + 2Mdudv + Ndv^2$  second fundamental form

These are extrinsic invariants and it appears that K depends on the extrinsic geometry of the surface. Carl Friedrich Gauss proved

**Theorema egregium.** The Gaussian curvature K of a surface depends only on the first fundamental form of the surface

Conclusion: The Gaussian curvature is an intrinsic invariant!

To prove the <code>Theorema</code> egregium, we use the <code>Method</code> of <code>Moving frames</code>. Choose locally an orthonormal frame field  $\mathbf{e}', \mathbf{e}'', \mathbf{N} = \mathbf{e}' \times \mathbf{e}''$ . At each point the vectors  $\mathbf{e}', \mathbf{e}''$  are tangent to the surface and orthonormal. The partial derivatives  $\mathbf{e}'_u, \mathbf{e}'_v, \mathbf{e}''_u, \mathbf{e}''_v$  satisfy

$$\mathbf{e}_u' = \alpha \mathbf{e}'' + \lambda' \mathbf{N}, \ \mathbf{e}_v' = \beta \mathbf{e}'' + \mu' \mathbf{N}, \ \mathbf{e}_u'' = -\alpha \mathbf{e}' + \lambda'' \mathbf{N}, \ \mathbf{e}_v'' = -\beta \mathbf{e}' + \mu'' \mathbf{N}$$

Lemma. We have

$$\mathbf{e}'_{u} \cdot \mathbf{e}''_{v} - \mathbf{e}''_{u} \cdot \mathbf{e}'_{v} = \lambda' \mu'' - \lambda'' \mu' = \alpha_{v} - \beta_{u} = \frac{LN - M^{2}}{\sqrt{EG - F^{2}}} = K\sqrt{EG - F^{2}}$$

Proof. Straightforward computations, see lecture notes for details

The Lemma implies  $K = \frac{\alpha_V - \beta_U}{\sqrt{EG - F^2}}$ . It therefore suffices to prove that  $\alpha, \beta$  depend only on E, F, G for a suitable choice of  $\mathbf{e}', \mathbf{e}''$ . Apply GRAM-SCHMIDT PROCESS to  $\sigma_U, \sigma_V$ :

$$\mathbf{e}' = \epsilon \sigma_u, \ \epsilon = \frac{1}{\|\sigma_u\|} = \frac{1}{\sqrt{E}}$$

Write  $\mathbf{e''} = \gamma \sigma_u + \delta \sigma_v$ . From  $\mathbf{e'} \cdot \mathbf{e''} = 0$  and  $\mathbf{e''} \cdot \mathbf{e''} = 1$  we get

$$\mathbf{e}'' = \gamma \sigma_u + \delta \sigma_v, \ \gamma = -\frac{F}{\sqrt{E}\sqrt{EG - F^2}}, \ \delta = \frac{\sqrt{E}}{\sqrt{EG - F^2}}$$

Thus  $\epsilon, \gamma, \delta$  depend on E, F, G only

$$\alpha = \mathbf{e}'_{u} \cdot \mathbf{e}'' = (\epsilon \sigma_{u})_{u} \cdot (\gamma \sigma_{u} + \delta \sigma_{v})$$

$$= (\epsilon_{u} \sigma_{u} + \epsilon \sigma_{uu}) \cdot (\gamma \sigma_{u} + \delta \sigma_{v})$$

$$= \cdots = \frac{1}{2} \epsilon \gamma E_{u} + \epsilon \delta (F_{u} - \frac{1}{2} E_{v})$$

$$\beta = \mathbf{e}'_{v} \cdot \mathbf{e}'' = (\epsilon \sigma_{u})_{v} \cdot (\gamma \sigma_{u} + \delta \sigma_{v})$$

$$= (\epsilon_{v} \sigma_{u} + \epsilon \sigma_{uv}) \cdot (\gamma \sigma_{u} + \delta \sigma_{v})$$

$$= \cdots = \frac{1}{2} \epsilon \gamma E_{v} + \frac{1}{2} \epsilon \delta G_{u}$$

Thus  $\alpha, \beta$  depend on E, F, G only. This finishes the proof of the THEOREMA EGREGIUM

We see from the proof of the THEOREMA EGREGIUM that there exists an explicit expression for the Gaussian curvature K in terms of E, F, G and their derivatives. This involves tedious calculations and the formula is not practical in general. Special cases:

If F = 0, then

$$K = -\frac{1}{2\sqrt{EG}} \left( \frac{\partial}{\partial u} \left( \frac{G_u}{\sqrt{EG}} \right) + \frac{\partial}{\partial v} \left( \frac{E_v}{\sqrt{EG}} \right) \right)$$

If E = 1 and F = 0, then

$$K = -\frac{1}{\sqrt{G}} \frac{\partial^2 \sqrt{G}}{\partial u^2}$$

Apply this to surface of revolution

Application of THEOREMA EGREGIUM to cartography:

**Proposition.** Any planar map of any region of the earth's surface must distort distances.

*Proof.* A sphere of radius r has constant Gaussian curvature  $\frac{1}{r^2}$  and a plane has constant Gaussian curvature 0. A planar map of any region of the earth's surface not distorting distances is an isometry (up to rescaling by a constant factor) and hence preserves the first fundamental forms of sphere and plane. Such an isometry cannot exist by Theorema Egregium.

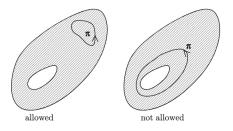
## **Geometry of Surfaces**

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Video 33 Gauss-Bonnet Theorem (local version)

> Jürgen Berndt King's College London

Let  $\sigma: U \to \mathbb{R}^3$  be a regular surface patch and  $\pi(s) = (u(s), v(s))$  be a simple closed curve in  $\mathbb{R}^2$  whose interior  $\inf(\pi)$  is contained in U.



Define  $\gamma(s)=\sigma(\pi(s))=\sigma(u(s),v(s))$  and assume  $\|\dot{\gamma}\|=1$ . We say that  $\gamma$  is positively oriented if  $\pi$  is positively oriented, that is, if the oriented unit normal  $\mathbf{n}_s$  of  $\pi$  points into  $\mathrm{int}(\pi)$  everywhere.

**Gauss-Bonnet Theorem (local version).** Let  $\sigma: U \to \mathbb{R}^3$  be a regular surface patch and  $\pi(s) = (u(s), v(s))$  be a simple closed curve in  $\mathbb{R}^2$  with  $\operatorname{int}(\pi) \subset U$ . Let  $\gamma(s) = \sigma(\pi(s))$  and assume that  $\gamma$  is positively oriented and  $\|\dot{\gamma}\| = 1$ . Then

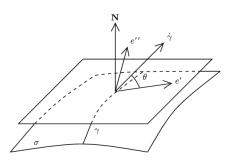
$$\int_{\gamma} \kappa_{g} ds = 2\pi - \iint_{\operatorname{int}(\pi)} K d\mathcal{A}_{\sigma}$$

where  $\kappa_g$  is the geodesic curvature of  $\gamma$ , K is the Gaussian curvature of  $\sigma$ ,  $d\mathcal{A}_{\sigma}=\sqrt{\mathsf{EG}-\mathsf{F}^2}\mathrm{d}u\mathrm{d}v$  is the area element on  $\sigma$ .

Choose moving frame  $\mathbf{e}', \mathbf{e}'', \mathbf{N} = \mathbf{e}' \times \mathbf{e}''$ . Then

$$\begin{split} \int_{\gamma} \mathbf{e}' \cdot \dot{\mathbf{e}}'' ds &= \int_{\gamma} \mathbf{e}' \cdot (\mathbf{e}''_u \dot{u} + \mathbf{e}''_v \dot{v}) ds = \int_{\pi} \left( (\mathbf{e}' \cdot \mathbf{e}''_u) du + (\mathbf{e}' \cdot \mathbf{e}''_v) dv \right) \\ &= \iint_{\mathrm{int}(\pi)} \left( (\mathbf{e}' \cdot \mathbf{e}''_v)_u - (\mathbf{e}' \cdot \mathbf{e}''_u)_v \right) du dv \quad \text{(Green's Thm)} \\ &= \iint_{\mathrm{int}(\pi)} \left( (\mathbf{e}'_u \cdot \mathbf{e}''_v) - (\mathbf{e}'_v \cdot \mathbf{e}''_u) \right) du dv \\ &= \iint_{\mathrm{int}(\pi)} \frac{LN - M^2}{\sqrt{EG - F^2}} du dv \quad \text{(Lemma on moving frames)} \\ &= \iint_{\mathrm{int}(\pi)} \frac{LN - M^2}{EG - F^2} \sqrt{EG - F^2} du dv = \iint_{\mathrm{int}(\pi)} K d\mathcal{A}_{\sigma} \end{split}$$

Put 
$$\theta(s) = \angle(\mathbf{e}'(\gamma(s)), \dot{\gamma}(s))$$



Then 
$$\dot{\gamma} = \cos(\theta)\mathbf{e}' + \sin(\theta)\mathbf{e}''$$
 and

$$\begin{aligned} \mathbf{N} \times \dot{\gamma} &= (\mathbf{e}' \times \mathbf{e}'') \times (\cos(\theta)\mathbf{e}' + \sin(\theta)\mathbf{e}'') = -\sin(\theta)\mathbf{e}' + \cos(\theta)\mathbf{e}'' \\ \ddot{\gamma} &= \cos(\theta)\dot{\mathbf{e}}' + \sin(\theta)\dot{\mathbf{e}}'' + \dot{\theta}(-\sin(\theta)\mathbf{e}' + \cos(\theta)\mathbf{e}'') \end{aligned}$$

$$\mathbf{N} \times \dot{\gamma} = (\mathbf{e}' \times \mathbf{e}'') \times (\cos(\theta)\mathbf{e}' + \sin(\theta)\mathbf{e}'') = -\sin(\theta)\mathbf{e}' + \cos(\theta)\mathbf{e}''$$
$$\ddot{\gamma} = \cos(\theta)\dot{\mathbf{e}}' + \sin(\theta)\dot{\mathbf{e}}'' + \dot{\theta}(-\sin(\theta)\mathbf{e}' + \cos(\theta)\mathbf{e}'')$$

Then

$$\kappa_{\mathbf{g}} = (\mathbf{N} \times \dot{\gamma}) \cdot \ddot{\gamma} = \dots = \dot{\theta} - \mathbf{e}' \cdot \dot{\mathbf{e}}''$$

Altogether

$$\iint_{\operatorname{int}(\pi)} K \, d\mathcal{A}_{\sigma} = \int_{\gamma} \mathbf{e}' \cdot \dot{\mathbf{e}}'' ds = \int_{\gamma} (\dot{\theta} - \kappa_{g}) ds$$

It remains to prove that  $\int_{\gamma}\dot{\theta}ds=2\pi$ . This is the so-called HOPF UMLAUFSATZ (Hopf rotation angle theorem) and requires topological arguments for its proof (see notes for heuristic argument)

## **Geometry of Surfaces**

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Video 34 Gauss-Bonnet Theorem for curvilinear polygons

Jürgen Berndt King's College London A curvilinear polygon is a simple closed curve  $\gamma$  for which there exist real numbers

$$0 = s_0 < s_1 < \cdots < s_{n-1} < s_n = \ell = L(\gamma)$$

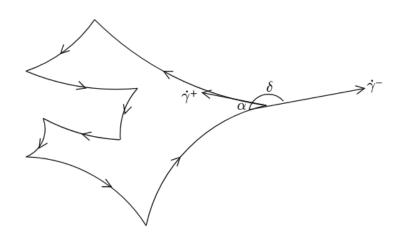
so that  $\gamma(0) = \gamma(\ell)$ ,  $\gamma$  is smooth on the intervals  $(s_{i-1}, s_i)$  and the two one-sided derivatives at the corners  $s_i$ ,

$$\frac{\dot{\gamma}^{-}(s_i)}{\dot{\gamma}^{-}(s_i)} = \lim_{s \uparrow s_i} \frac{\gamma(s) - \gamma(s_i)}{s - s_i}, \quad \frac{\dot{\gamma}^{+}(s_i)}{\dot{\gamma}^{+}(s_i)} = \lim_{s \downarrow s_i} \frac{\gamma(s) - \gamma(s_i)}{s - s_i},$$

exist, are non-zero and non-parallel. The angle

$$\delta_i = \angle (\dot{\gamma}^-(s_i), \dot{\gamma}^+(s_i)) \in (-\pi, \pi)$$

is called the external angle of  $\gamma$  at  $s_i$  and  $\alpha_i = \pi - \delta_i \in (0, 2\pi)$  is called the internal angle of  $\gamma$  at  $s_i$ 



## Gauss-Bonnet Theorem for curvilinear polygons. Let

 $\sigma: U \to \mathbb{R}^3$  be a regular surface patch and  $\gamma(s) = \sigma(u(s), v(s))$  be a curvilinear polygon on  $\sigma$  for which the interior  $\operatorname{int}(\gamma)$  of the curve (u(s), v(s)) is contained in U. Assume that  $\gamma$  is positively oriented and parametrized by arc length. Then

$$\int_{\gamma} \kappa_{g} ds = \sum_{i=1}^{n} \alpha_{i} - (n-2)\pi - \iint_{\operatorname{int}(\gamma)} K dA_{\sigma}$$

where  $\kappa_{\rm g}$  is the geodesic curvature of  $\gamma$ , K is the Gaussian curvature of  $\sigma$ ,  $d\mathcal{A}_{\sigma}=\sqrt{{\it EG}-{\it F}^2}{\it dudv}$  is the area element on  $\sigma$ . *Proof.* The same arguments as in the proof for the local version of the Gauss-Bonnet Theorem give

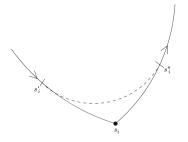
$$\iint\limits_{\mathrm{int}(\gamma)} \mathsf{K}\, d\mathcal{A}_{\sigma} = \int_{\gamma} \dot{ heta} \mathsf{d} s - \int_{\gamma} \kappa_{\mathsf{g}} \mathsf{d} s$$

with  $\theta(s) = \angle(\mathbf{e}'(\gamma(s)), \dot{\gamma}(s))$ . Need to compute  $\int_{\gamma} \dot{\theta} ds$ .

We first smoothen each vertex of the polygon to get a smooth curve  $\tilde{\gamma}$ 



HOPF'S UMLAUFSATZ gives  $\int_{\tilde{\gamma}} \tilde{\theta} ds = 2\pi$  with  $\tilde{\theta}(s) = \angle(\mathbf{e}'(\tilde{\gamma}(s)), \dot{\tilde{\gamma}}(s))$ . Choose points  $s_i', s_i''$  as illustrated here



Then

$$\int_{\tilde{\gamma}} \dot{\tilde{\theta}} ds - \int_{\gamma} \dot{\theta} ds = \sum_{i=1}^{n} \left( \int_{s_{i}'}^{s_{i}''} \dot{\tilde{\theta}} ds - \int_{s_{i}'}^{s_{i}} \dot{\theta} ds - \int_{s_{i}}^{s_{i}''} \dot{\theta} ds \right)$$

Since  $\gamma$  is smooth on  $(s'_i, s_i)$  and  $(s_i, s''_i)$ , we have

$$\lim_{s'_i \to s_i} \int_{s'_i}^{s_i} \dot{\theta} ds = 0 , \lim_{s''_i \to s_i} \int_{s_i}^{s''_i} \dot{\theta} ds = 0$$

Furthermore,

$$\int_{s_i'}^{s_i''} \dot{\tilde{\theta}} ds = \angle (\dot{\tilde{\gamma}}(s_i''), \dot{\tilde{\gamma}}(s_i')) \xrightarrow[s_i', s_i'' \to s_i]{} \angle (\dot{\gamma}^-(s_i), \dot{\gamma}^+(s_i)) = \delta_i$$

Altogether,

$$\int_{\tilde{\gamma}} \dot{\tilde{\theta}} ds - \int_{\gamma} \dot{\theta} ds = \sum_{i=1}^{n} \left( \int_{s_i'}^{s_i''} \dot{\tilde{\theta}} ds - \int_{s_i'}^{s_i} \dot{\theta} ds - \int_{s_i}^{s_i''} \dot{\theta} ds \right) = \sum_{i=1}^{n} \delta_i$$

Thus,

$$\int_{\gamma} \dot{\theta} ds = \int_{\tilde{\gamma}} \dot{\tilde{\theta}} ds - \sum_{i=1}^{n} \delta_{i} = 2\pi - \sum_{i=1}^{n} \delta_{i} = 2\pi - \sum_{i=1}^{n} (\pi - \alpha_{i})$$
$$= 2\pi - n\pi + \sum_{i=1}^{n} \alpha_{i}$$

Altogether,

$$\int_{\gamma} \kappa_{g} ds = \int_{\gamma} \dot{\theta} ds - \iint_{\text{int}(\gamma)} K dA_{\sigma} = \sum_{i=1}^{n} \alpha_{i} - (n-2)\pi - \iint_{\text{int}(\gamma)} K dA_{\sigma}$$

**Corollary.** If  $\gamma$  is a curvilinear polygon with n edges each of which is a geodesic, then

$$\sum_{i=1}^{n} \alpha_i = (n-2)\pi + \iint_{\text{int}(\gamma)} K \, d\mathcal{A}_{\sigma}$$

Question: What does this tell us about polygons in the plane (K=0) and about triangles in the unit sphere (K=1) and in the pseudosphere (K=-1)?