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Artificial Intelligence

ANFIS

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ANFIS objective

- To integrate the best features of Fuzzy Systems and Neural Networks:
 - From FS: Representation of prior knowledge into a set of constraints (network topology) to reduce the optimization search space
 - From NN: Adaptation of backpropagation to structured network to automate FC parametric tuning
- ANFIS application to synthesize:
 - Controllers
 - Models



What is ANFIS?

- There is a class of adaptive networks that are functionally equivalent to fuzzy inference systems
- The architecture of these networks is referred to as ANFIS, which stands for adaptive network based fuzzy inference system or semantically equivalently, adaptive neuro-fuzzy inference system.



TS Fuzzy Model

- Assume that the fuzzy inference system under consideration has two inputs x and y and one output z .
- For a first-order Sugeno fuzzy model with two if then rules

Rule 1: If x is A_1 and y is B_1 , then $f_1 = p_1x + q_1y + r_1$,

Rule 2: If x is A_2 and y is B_2 , then $f_2 = p_2x + q_2y + r_2$.



TS Fuzzy Model

- IF X is small, then $Y_1=4$
- IF X is medium, then $Y_2= -0.2X+4$
- IF is large, then $Y_3=X-1$

$$Y = \frac{\sum_{i=1}^n w_i Y_i}{\sum_{i=1}^n w_i}$$



ANFIS

- Proposed by J.-S. Roger Jang in 1992
- Creates a fuzzy rule to classify the data into one of p^n linear regression models to minimize the sum of squared errors (SSE):

$$SSE = \sum_j e_j^2$$

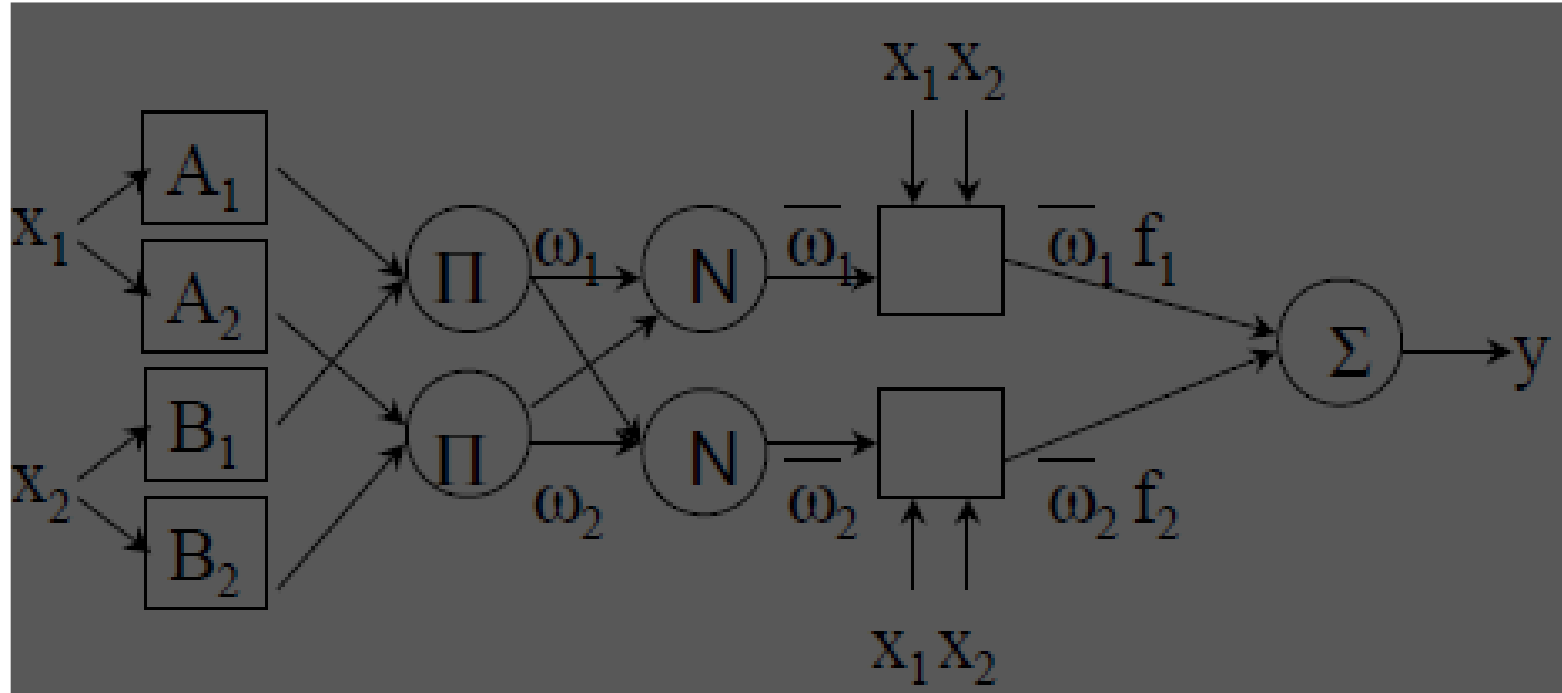


ANFIS

- L_0 : State variables are nodes in ANFIS inputs layer
- L_1 : Termsets of each state variable are nodes in ANFIS values layer, computing the membership value
- L_2 : Each rule in FC is a node in ANFIS rules layer using soft-min or product to compute the rule matching factor ω_i
- L_3 : Each ω_i is scaled into $\overline{\omega}_i$ in the normalization layer
- L_4 : Each $\overline{\omega}_i$ weights the result of its linear regression f_i in the function layer generating the rule output
- L_5 : Each rule output is added in the output layer

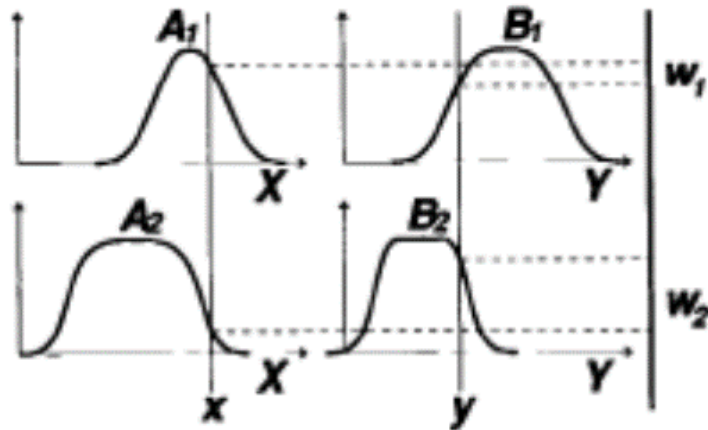


ANFIS Architecture





ANFIS Architecture



$$f_1 = p_1x + q_1y + r_1$$

$$f_2 = p_2x + q_2y + r_2$$



$$f = \frac{w_1 f_1 + w_2 f_2}{w_1 + w_2}$$
$$= \bar{w}_1 f_1 + \bar{w}_2 f_2$$



Layer 1

Calculate the membership value for premise parameters

$$O_{1,i} = \mu_{A,i}(x_1) \text{ for } i=1,2$$

$$O_{1,i} = \mu_{B,i-2}(x_2) \text{ for } i=3,4$$

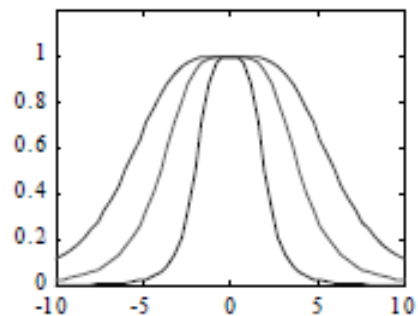
where A, B are linguistic labels

$$\mu_A(x_1) = \frac{1}{1 + \left| \frac{x_1 - c_i}{a_i} \right|^{2b}}$$

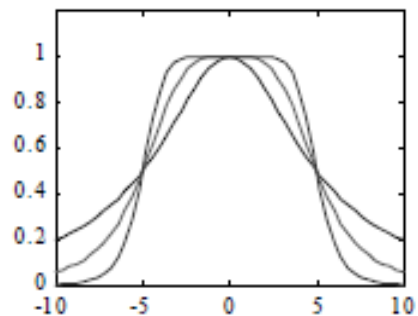
The output is the membership value of the inputs



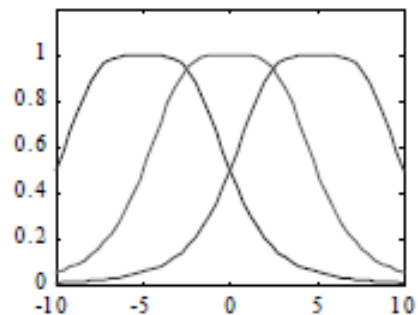
(a) Changing 'a'



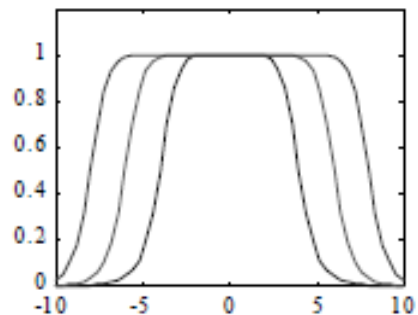
(b) Changing 'b'



(c) Changing 'c'



(d) Changing 'a' and 'b'





Layer 2: Rule Firing Strength

Use *T-norm* (min, product, etc.)

$$O_{2,i} = w_i = \mu_{A,i}(x_1) \mu_{B,i}(x_2)$$

Node output: firing strength of the rule



Layer 3: Normalized Firing Strength

Ratio of i-th rule firing strength vs all rules firing strength

$$O_{3,1} = \overline{w_i} = \frac{w_1}{w_1 + w_2}$$

Node output: Normalized firing strength



Layer 4: Consequent Parameters

Takagi-Sugeno type output

$$O_{4,i} = \overline{w}_i f_i = \overline{w}_i (p_i x_1 + q_i x_2 + r_i)$$

Consequent parameters (p_i, q_i, r_i)



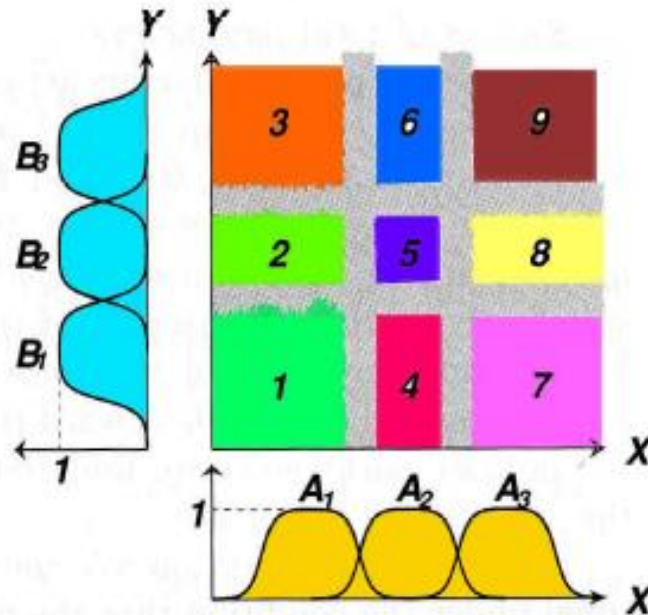
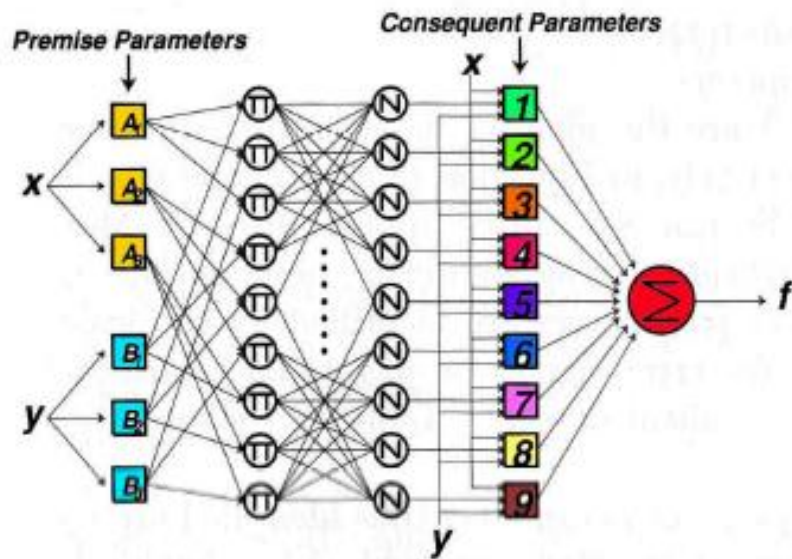
Layer 5: Overall Output

$$O_{5,1} = \sum_i \overline{w_i} f_i = \frac{\sum_i w_i f_i}{\sum_i w_i}$$

Node Output: Weighted Evaluation of RHS polynomials



ANFIS Architecture with Two Inputs





Example

Rule 1: IF x is small (A1) AND y is small (B1) THEN f1=small

Rule 2: IF x is large (A2) AND y is large (B2) THEN f2=large

$$A1: \mu_{A1}(x) = \frac{1}{1 + \left| \frac{x-1}{2} \right|^2}$$

$$B1: \mu_{B1}(y) = \frac{1}{1 + \left| \frac{y-2}{2} \right|^2}$$

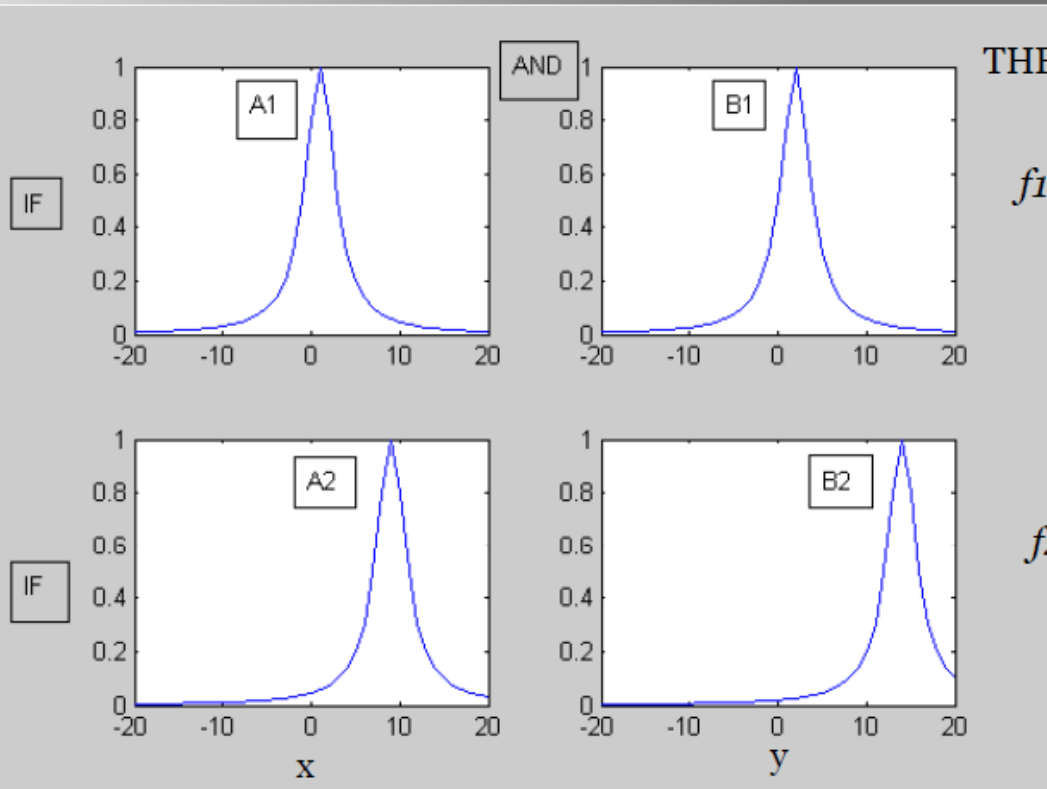
$$f1 = 0.1x + 0.1y + 0.1$$

$$A2: \mu_{A2}(x) = \frac{1}{1 + \left| \frac{x-9}{2} \right|^2}$$

$$B2: \mu_{B2}(y) = \frac{1}{1 + \left| \frac{y-14}{2} \right|^2}$$

$$f2 = 10x + 10y + 10$$

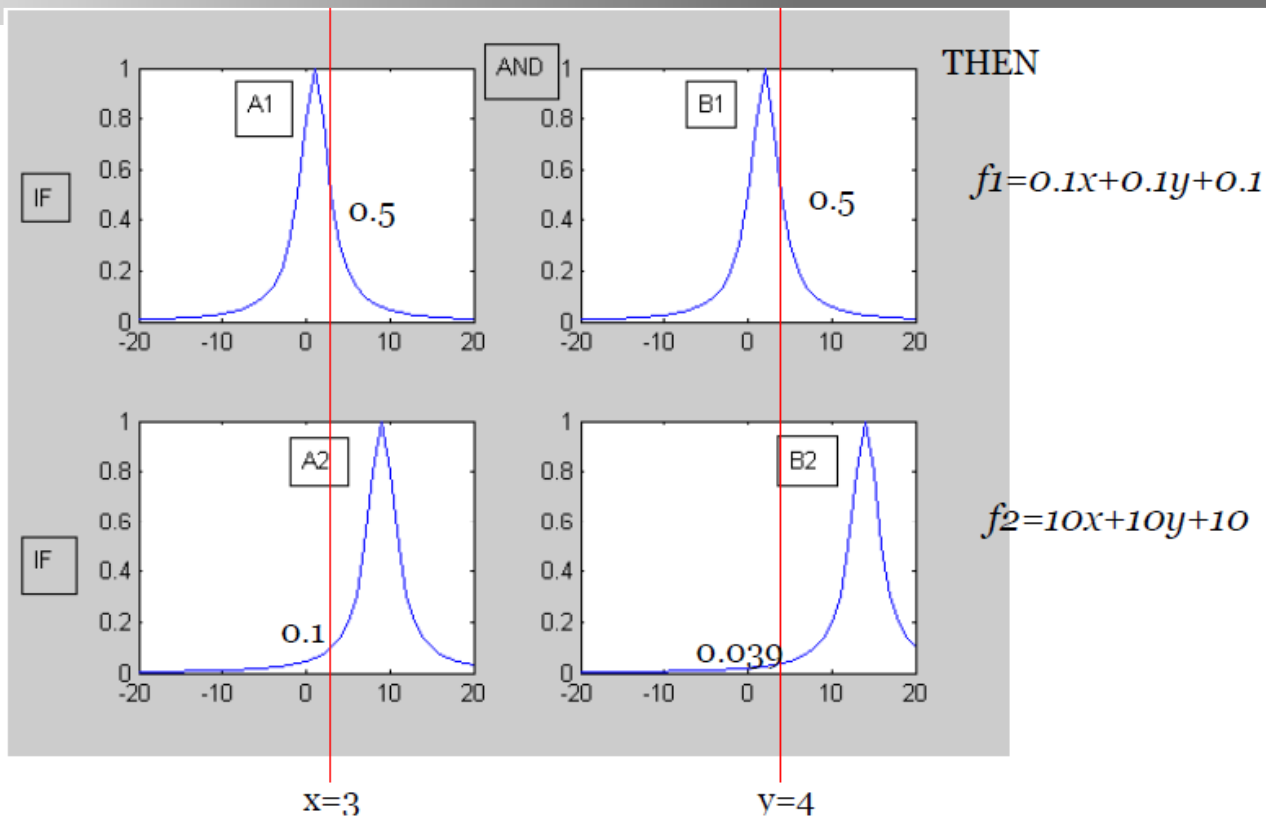
Given the trained fuzzy system above and input values of $x=3$ and $y=4$, find output of the Sugeno fuzzy system



THEN

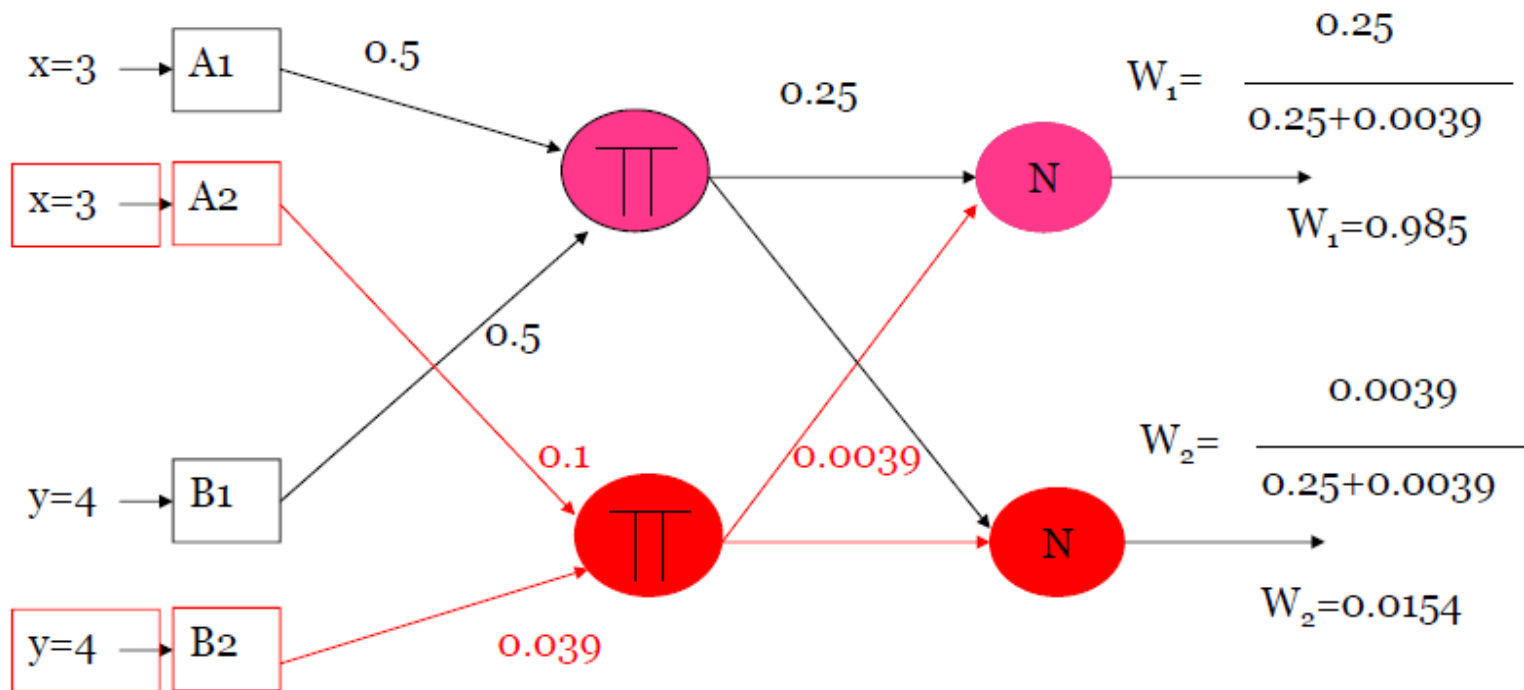
$$f1 = 0.1x + 0.1y + 0.1$$

$$f2 = 10x + 10y + 10$$



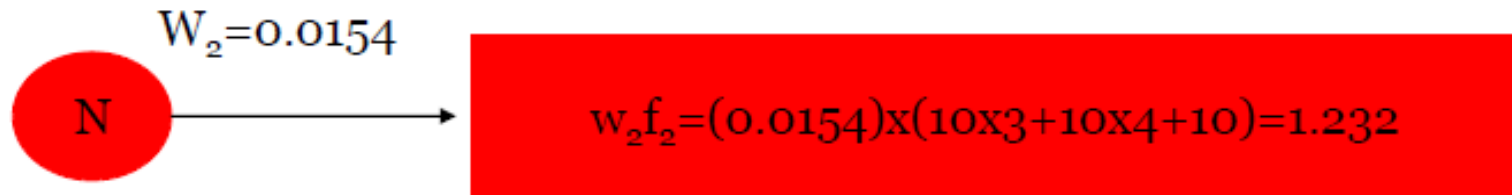
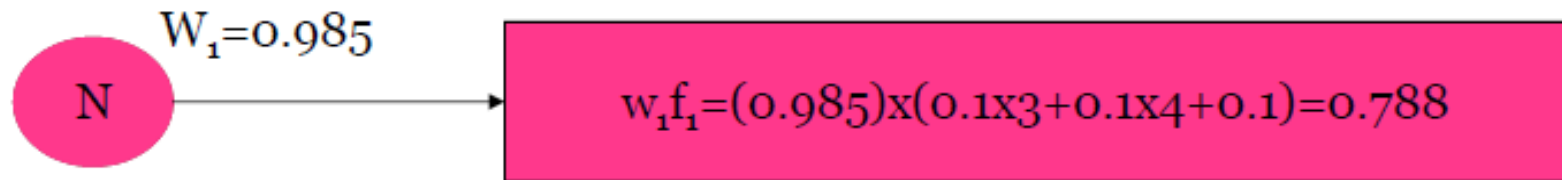


Example 1



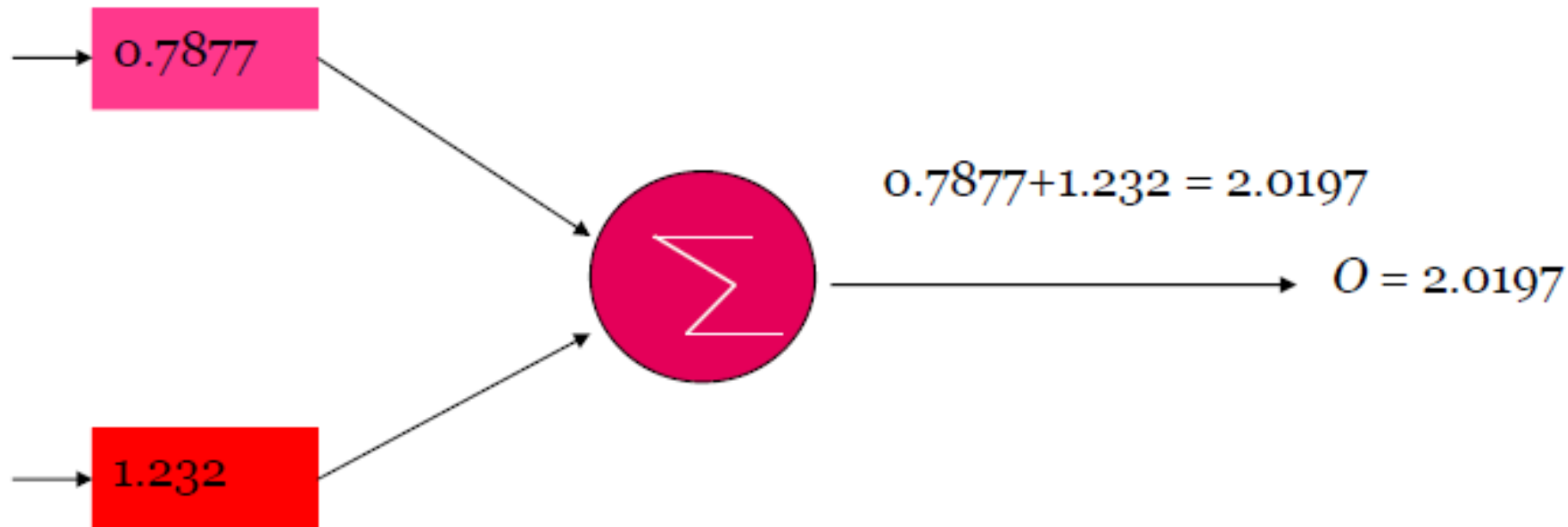


Example 1



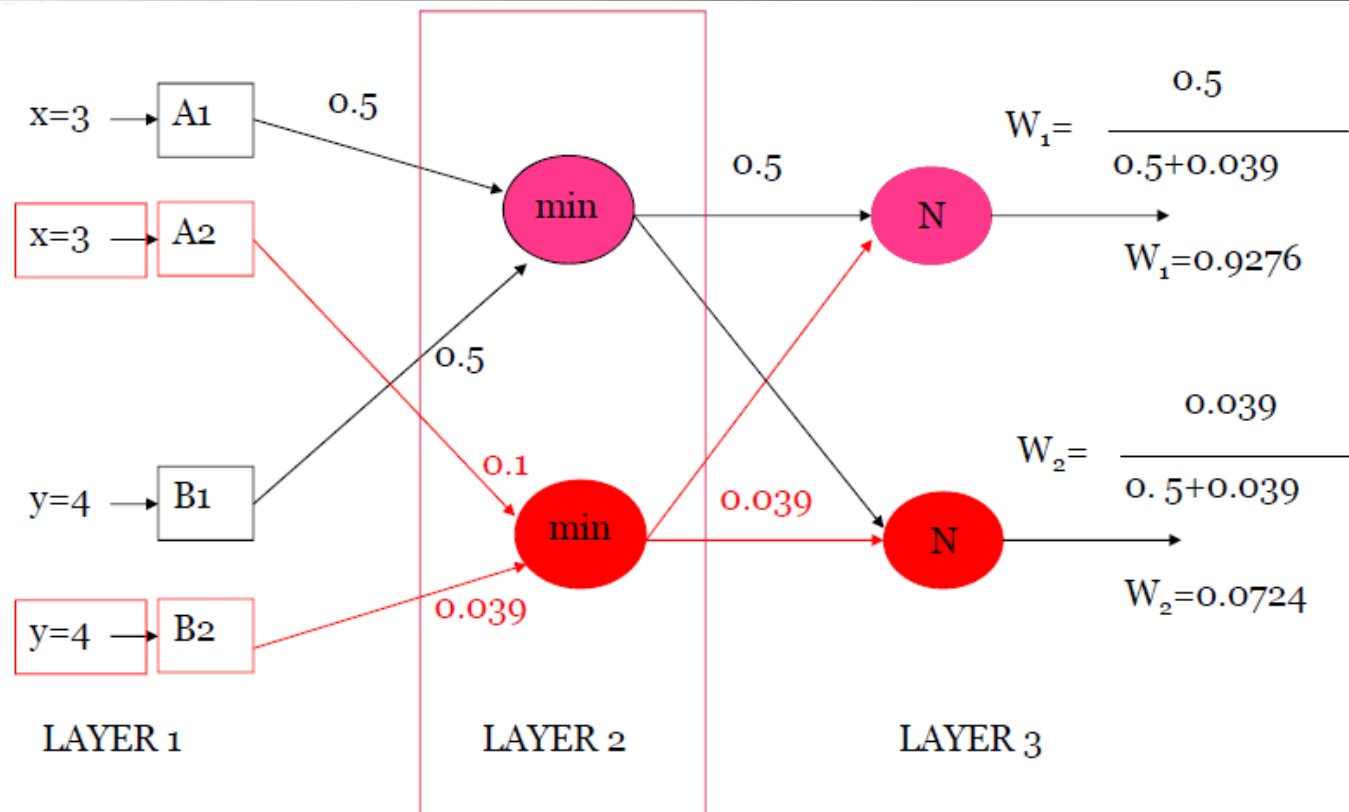


Example 1



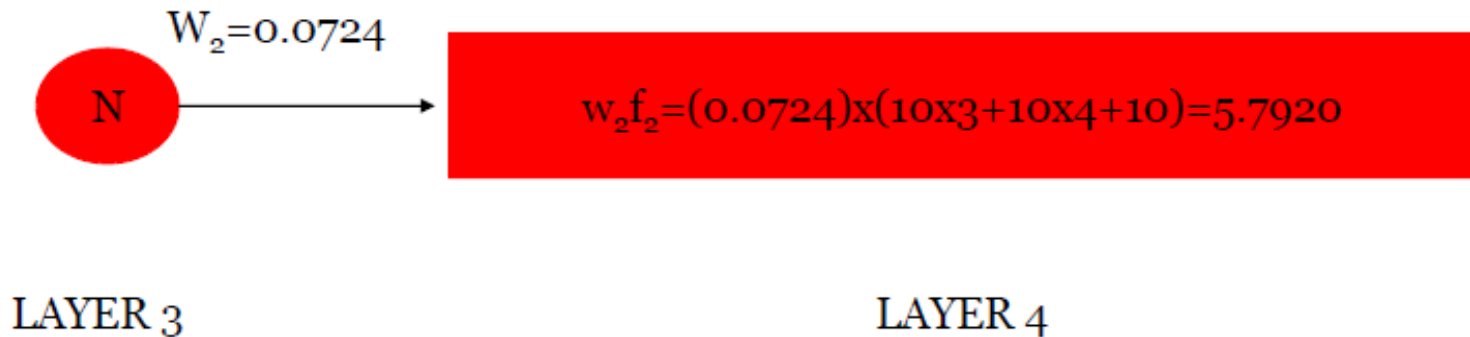
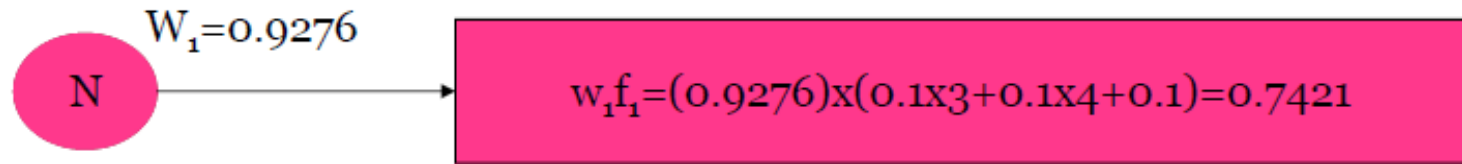


Example 2



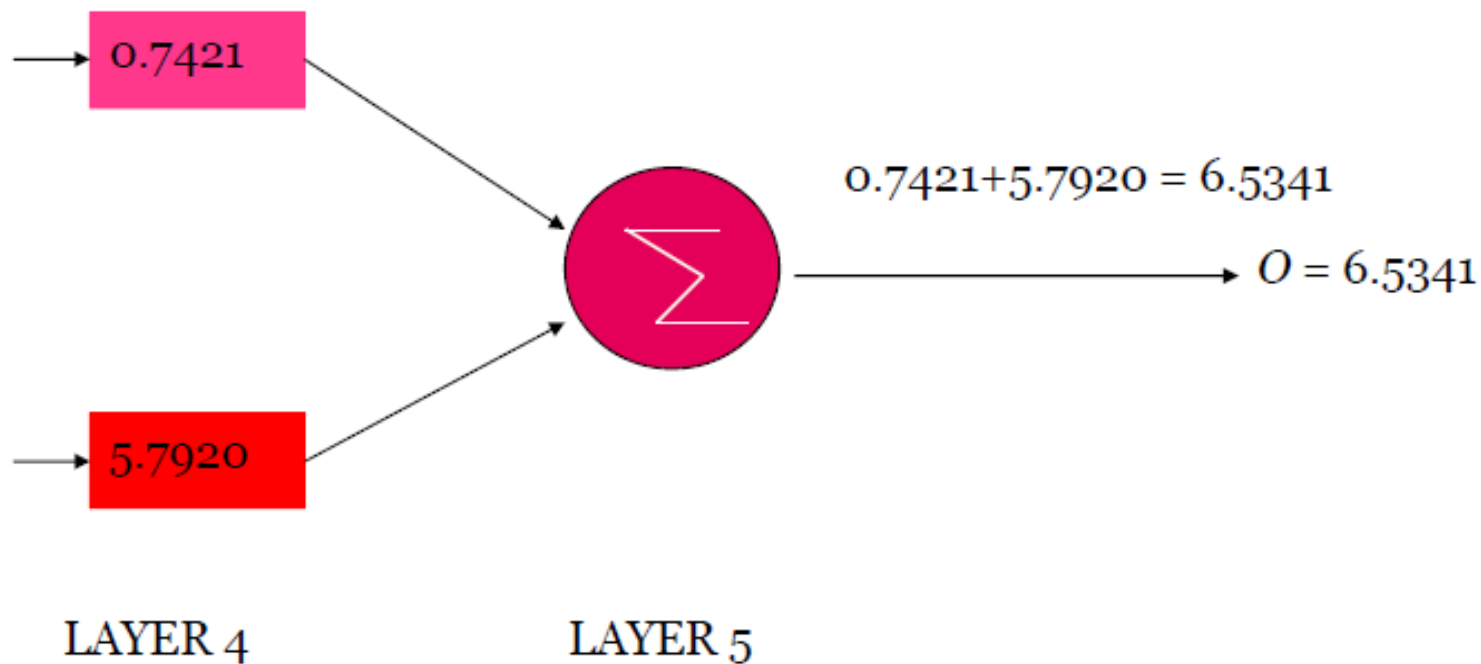


Example 2





Example 2





ANFIS: Parametric Representation

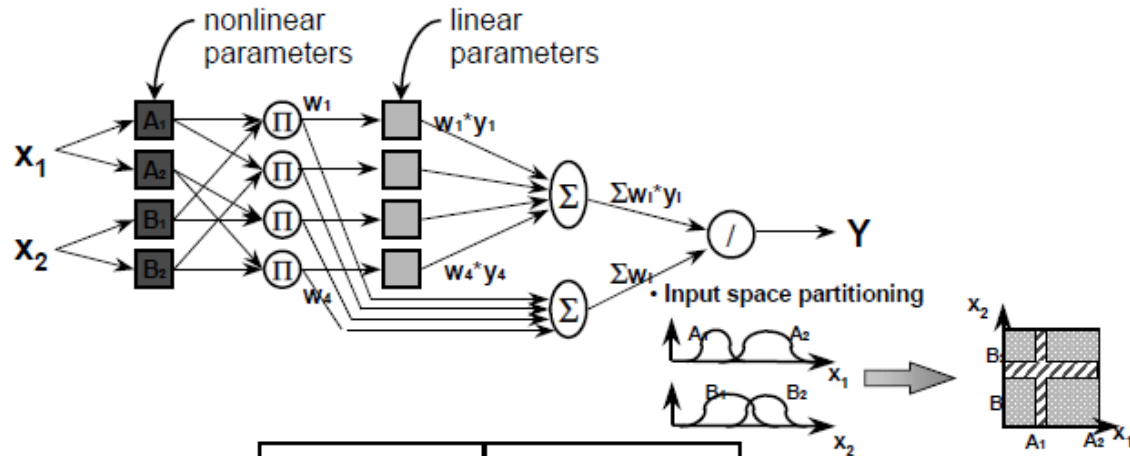
- ANFIS uses two sets of parameters: S1 and S2
 - S1 represents the fuzzy partitions used in the rule LHS
 - S2 represents the coefficients of the linear functions in the rules RHS

<u>Layer #</u>	<u>L-Type</u>	<u># Nodes</u>	<u># Param</u>
L ₀	Inputs	n	0
L ₁	Values	$(p \cdot n)$	$3 \cdot (p \cdot n) = S1 $
L ₂	Rules	p^n	0
L ₃	Normalize	p^n	0
L ₄	Lin. Funct.	p^n	$(n+1) \cdot p^n = S2 $
L ₅	Sum	1	0



ANFIS Learning Algorithm

Hybrid training method



	Forward stroke	Backward stroke
MF param. (nonlinear)	fixed	steepest descent
Coef. param. (linear)	least-squares	fixed

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ANFIS Least Square Algorithm

- For given values of S1, using K training data, we can transform the output expression of ANFIS to be $B = AX$ where X contains the elements of S2 and B denotes the target data
- This is solved as $X = (A^T A)^{-1} A^T B$ where $(A^T A)^{-1} A^T$ is called pseudo inverse of A (if $(A^T A)^{-1}$ is non-singular)
- The LSE minimizes the error $||AX - B||^2$



ANFIS Least Square Algorithm

- It can be solved iteratively as follows:

$$S_{i+1} = S_i - \frac{S_i a_{i+1} a_{i+1}^T S_i}{1 + a_{i+1}^T S_i a_{i+1}}$$
$$X_{i+1} = X_i + S_{i+1} a_{i+1} (b_{i+1}^T - a_{i+1}^T X_i), S_0 = \gamma I$$



ANFIS Back-propagation Algorithm

Error measure

$$E_k = \sum_{i=1}^{N(L)} (d_i - x_{L,i})^2$$

Overall error measure

$$E = \sum_{k=1}^K E_k$$



ANFIS Back-propagation Algorithm

$$\Delta\alpha_i = -\beta_i \frac{\partial E}{\partial \alpha_i}$$
$$\beta = \frac{\kappa}{\sqrt{\sum_i \left(\frac{\partial E}{\partial \alpha_i}\right)^2}}$$



Summary

$$F = \sum_i \bar{w}_i f_i = \frac{\sum_i w_i f_i}{\sum_i w_i}$$

$i=1,2,3, \dots R$ # of rules

F is the calculated/estimated output value
(by ANFIS)

$$\text{Error} = e = (d - F)^2$$

d = Actual/Real Output

$$\frac{\partial e}{\partial(x, y, \dots)}$$

Gradient of ANFIS's output: Making
ANFIS's output (O) closer to actual
output (AO)

$$a(n+1) = a(n) - \eta \frac{\partial e}{\partial a}$$

This can be done by updating values of
the parameters (e.g., a, c,...) over n
(iteration/step)

η : learning rate



ANFIS vs RBFN

- Under certain conditions, ANFIS is functionally equivalent to RBFN
- There are a variety of learning methods that can be used for both
- ANFIS consists of two parts
 - Antecedent part
 - Consequent part
- These two parts can be tuned using different optimization methods
- These learning schemes are also applicable to RBFN



ANFIS vs RBFN

- A typical scheme is to fix the receptive fields first and then adjusts the weights of the output layer
- There are several schemes proposed to determine the center positions of the receptive fields μ_i
 - Based on the standard deviations of training data
 - By means of vector quantization or clustering technique
- Then, the width parameters σ_i are determined by taking the average distance to the first several nearest neighbors of μ_i
- Once the parameters are fixed and the receptive fields are frozen, the linear parameters can be updated by either the least square method or gradient descent



ANFIS as Universal Approximator

- When the number of rules is not restricted, a zero-order Sugeno model has unlimited approximation power for matching any nonlinear function arbitrarily well on a compact set.
- However, to give a mathematical proof, we need to apply the Stone-Weierstrass theorem