

1 Forward Equations

For an incompressible fluid, the equations governing the conservation of mass and momentum are

$$\frac{\partial u_j}{\partial x_j} = 0, \quad (1.1)$$

$$\frac{\partial u_i}{\partial t} = -\frac{\partial u_i u_j}{\partial x_j} - \frac{1}{\rho} \frac{\partial p}{\partial x_i} + B_i, \quad (1.2)$$

respectively, where ρ is the constant fluid density, u_i is the i^{th} velocity component, and p is the hydrodynamic pressure. Summation over repeated indices is implied. The viscous flux is

$$B_i \equiv \frac{\mu}{\rho} \frac{\partial}{\partial x_j} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{1}{3} \frac{\partial u_k}{\partial x_k} \delta_{ij} \right), \quad (1.3)$$

in which μ is the constant viscosity and δ_{ij} is the Kronecker delta. Note that the assumption of constant ρ and μ is not strictly necessary for an incompressible fluid.

1.1 Temporal Discretization

The governing equations are solved using Chorin's fractional-step scheme. The system is discretized in time using the explicit Euler method. In the fractional-step scheme, a "predicted" velocity field u_i^* is computed according to Eq. (1.2) without the pressure derivative, *i.e.*,

$$u_i^* = u_i^t - \Delta t \left(\frac{\partial u_i u_j}{\partial x_j} - B_i \right) + \mathcal{O}(\Delta t). \quad (1.4)$$

A Poisson equation is solved to obtain a pressure field that enforces the divergence-free condition on the velocity field [Eq. (1.1)],

$$\frac{\partial^2 p^*}{\partial x_j^2} = \frac{\rho}{\Delta t} \frac{\partial u_j^*}{\partial x_j}. \quad (1.5)$$

Finally, a "corrected" velocity field is obtained by applying the pressure correction:

$$u_i^{t+1} = u_i^* - \frac{\Delta t}{\rho} \frac{\partial p^*}{\partial x_i} + \mathcal{O}(\Delta t). \quad (1.6)$$

1.2 Spatial Discretization

The system is discretized in space using a fully-staggered grid, in which the velocity components are located at cell faces and the pressure is located at cell centers. A uniform mesh is assumed.

Convective terms are discretized in "divergence form," as they appear in Eq. (1.2), due to several desirable conservation properties on the staggered grid (Morinishi *et al.*, *JCP* 143, 1998). Let us denote the x, y, z components of velocity as $u_1, u_2, u_3 = u, v, w$, respectively. No longer implying summation over repeated indices, we can write the discretized convective terms for the $u_1 = u$ velocity component at a point (i, j, k)

as

$$\begin{aligned}
\left(\frac{\partial uu}{\partial x} + \frac{\partial uv}{\partial y} + \frac{\partial uw}{\partial z} \right)_{i,j,k} &= (\text{Conv}_{11} + \text{Conv}_{12} + \text{Conv}_{13})_{i,j,k} \\
&= (\text{grad_x}) \left[u_{i,j,k}^{I,xm} u_{i,j,k}^{I,xm} - u_{i-1,j,k}^{I,xm} u_{i-1,j,k}^{I,xm} \right] \\
&\quad + (\text{grad_y}) \left[u_{i,j+1,k}^{I,y} v_{i,j+1,k}^{I,x} - u_{i,j,k}^{I,y} v_{i,j,k}^{I,x} \right] \\
&\quad + (\text{grad_z}) \left[u_{i,j,k+1}^{I,z} w_{i,j,k+1}^{I,x} - u_{i,j,k}^{I,z} w_{i,j,k}^{I,x} \right],
\end{aligned} \tag{1.7}$$

where interpolated velocities are defined as

$$\begin{aligned}
u_{i,j,k}^{I,xm} &= \frac{1}{2} (u_{i+1,j,k} + u_{i,j,k}), \\
u_{i,j,k}^{I,y} &= \frac{1}{2} (u_{i,j,k} + u_{i,j-1,k}), \\
u_{i,j,k}^{I,z} &= \frac{1}{2} (u_{i,j,k} + u_{i,j,k-1}), \\
v_{i,j,k}^{I,x} &= \frac{1}{2} (v_{i,j,k} + v_{i-1,j,k}), \\
w_{i,j,k}^{I,x} &= \frac{1}{2} (w_{i,j,k} + w_{i-1,j,k}),
\end{aligned}$$

and (grad_x), etc., contain the denominators of the derivative operators. The order of interpolation and differentiation in the discretized convective terms will be important in the derivation of the discrete-exact adjoint equations.

2 Adjoint Equations

A loss function $\mathcal{L} = g(u^T, v^T, w^T)$ may be defined, where the superscript $(\cdot)^T$ denotes the solution at a final time T . A typical loss function is the mean-squared error (MSE). The adjoint of the velocity field at an intermediate time t is then defined as the gradient of the loss function with respect to the forward solution at time t :

$$\hat{u}^t \equiv \frac{\partial \mathcal{L}}{\partial u^t}, \quad \hat{v}^t \equiv \frac{\partial \mathcal{L}}{\partial v^t}, \quad \hat{w}^t \equiv \frac{\partial \mathcal{L}}{\partial w^t}. \tag{2.1}$$

2.1 Temporal Discretization

The adjoint field is advanced in reverse time over the range $t \in [T - 1, 0]$. Using dummy indices $(m, n, p) \in (N_x, N_y, N_z)$, the adjoint of the u -component of velocity at a point $(i, j, k) \in (N_x, N_y, N_z)$ is written using the chain rule on \mathcal{L} and substituting Eq. (2.1):

$$\hat{u}_{i,j,k}^t = \sum_{m,n,p} \left(\hat{u}_{m,n,p}^{t+1} \frac{\partial u_{m,n,p}^{t+1}}{\partial u_{i,j,k}^t} + \hat{v}_{m,n,p}^{t+1} \frac{\partial v_{m,n,p}^{t+1}}{\partial u_{i,j,k}^t} + \hat{w}_{m,n,p}^{t+1} \frac{\partial w_{m,n,p}^{t+1}}{\partial u_{i,j,k}^t} \right). \tag{2.2}$$

We will defer the substitution of $u_{m,n,p}$, etc., until the next sub-section on the discrete-exact adjoint formulation, as the form of the equations depends on the spatial discretization of the forward equations.

Due to the reverse-time nature of the adjoint update, the analog of the Poisson equation [Eq. (1.5)] is solved first to obtain the adjoint pressure,

$$\frac{\partial^2 \hat{p}}{\partial x_j^2} = \frac{\rho}{\Delta t} \frac{\partial \hat{u}_j^{t+1}}{\partial x_j}, \quad (2.3)$$

where summation over repeated indices is implied. The “corrected” adjoint field is then obtained by applying the adjoint pressure correction:

$$\hat{u}_i^* = \hat{u}_i^{t+1} - \frac{\Delta t}{\rho} \frac{\partial \hat{p}}{\partial x_i} + \mathcal{O}(\Delta t). \quad (2.4)$$

Finally, the adjoint field at time t is obtained by advancing the convective and viscous terms,

$$\hat{u}_i^t = \hat{u}_i^* - \Delta t \left(\text{AdjConv}_i(u_j^t; \hat{u}_j^*) - \hat{B}_i \right) + \mathcal{O}(\Delta t), \quad (2.5)$$

where we leave the definition of the adjoint convective operator $\text{AdjConv}_i(u_j^t; \hat{u}_j^*)$ to the next sub-section. The pressure operator and viscous flux are self-adjoint; therefore, we have written these terms in continuous space. The nonlinear convective terms are not self-adjoint and require consideration of the spatial discretization of the forward equations.

2.2 Discrete-exact Adjoint

We now return to the definition of the adjoint convective operator. Note that all subsequent derivations assume a uniform mesh. Substituting the forward predictor equations [Eq. (1.4)] and discretized convective terms [Eq. (1.7)] into the expanded expression for $\hat{u}_{i,j,k}^t$ [Eq. (2.2)] and neglecting the self-adjoint viscous terms, we obtain the adjoint convective operator appearing in the $\hat{u} = \hat{u}_1$ equation,

$$\begin{aligned} \text{AdjConv}_1(u^t, v^t, w^t; \hat{u}^*, \hat{v}^*, \hat{w}^*)_{i,j,k} &= \sum_{m,n,p} \hat{u}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} [\text{Conv}_{11}^t + \text{Conv}_{12}^t + \text{Conv}_{13}^t]_{m,n,p} \\ &+ \sum_{m,n,p} \hat{v}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} [\text{Conv}_{21}^t]_{m,n,p} \\ &+ \sum_{m,n,p} \hat{w}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} [\text{Conv}_{31}^t]_{m,n,p}, \end{aligned} \quad (2.6)$$

where Conv_{21} and Conv_{31} originate from the forward v - and w -equations, respectively.

Expanding terms in Eq. (2.6), we obtain the discrete-exact convective contributions to the \hat{u} -equation at a point (i, j, k) . For the Conv_{11} term,

$$\begin{aligned} \sum_{m,n,p} \hat{u}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} [\text{Conv}_{11}^t]_{m,n,p} &= (\text{grad}_x) \sum_{m,n,p} \hat{u}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} \left[u_{m,n,p}^{I,xm,t} u_{m,n,p}^{I,xm,t} - u_{m-1,n,p}^{I,xm,t} u_{m-1,n,p}^{I,xm,t} \right] \\ &= \frac{1}{4} (\text{grad}_x) \sum_{m,n,p} \hat{u}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} \left[(u_{m+1,n,p}^t)^2 + 2u_{m,n,p}^t u_{m+1,n,p}^t - 2u_{m-1,n,p}^t u_{m,n,p}^t - (u_{m-1,n,p}^t)^2 \right] \\ &= \frac{1}{2} (\text{grad}_x) \left[\hat{u}_{i-1,j,k}^* u_{i-1,j,k}^t + \hat{u}_{i-1,j,k}^* u_{i,j,k}^t + \hat{u}_{i,j,k}^* u_{i+1,j,k}^t - \hat{u}_{i,j,k}^* u_{i-1,j,k}^t - \hat{u}_{i+1,j,k}^* u_{i,j,k}^t - \hat{u}_{i+1,j,k}^* u_{i+1,j,k}^t \right] \\ &= (\text{grad}_x) \left[(\hat{u}_{i-1,j,k}^* - \hat{u}_{i,j,k}^*) u_{i-1,j,k}^{I,xm,t} + (\hat{u}_{i,j,k}^* - \hat{u}_{i+1,j,k}^*) u_{i,j,k}^{I,xm,t} \right]. \end{aligned}$$

Several additional terms are present in the discrete-exact adjoint formulation of the convective operator, due to the order of interpolation and differentiation operations, that do not appear in the continuous adjoint formulation.

Similarly, for the Conv_{12} and Conv_{13} terms, respectively,

$$\begin{aligned} & \sum_{m,n,p} \hat{u}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} [\text{Conv}_{12}^t]_{m,n,p} \\ &= (\text{grad}_y) \sum_{m,n,p} \hat{u}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} \left[u_{m,n+1,p}^{I,y,t} v_{m,n+1,p}^{I,x,t} - u_{m,n,p}^{I,y,t} v_{m,n,p}^{I,x,t} \right] \\ &= \frac{1}{2} (\text{grad}_y) \left[(\hat{u}_{i,j-1,k}^* - \hat{u}_{i,j,k}^*) v_{i,j,k}^{I,x,t} + (\hat{u}_{i,j,k}^* - \hat{u}_{i,j+1,k}^*) v_{i,j+1,k}^{I,x,t} \right] \end{aligned}$$

and

$$\begin{aligned} & \sum_{m,n,p} \hat{u}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} [\text{Conv}_{13}^t]_{m,n,p} \\ &= (\text{grad}_z) \sum_{m,n,p} \hat{u}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} \left[u_{m,n,p+1}^{I,z,t} w_{m,n,p+1}^{I,x,t} - u_{m,n,p}^{I,z,t} w_{m,n,p}^{I,x,t} \right] \\ &= \frac{1}{2} (\text{grad}_z) \left[(\hat{u}_{i,j,k-1}^* - \hat{u}_{i,j,k}^*) w_{i,j,k}^{I,x,t} + (\hat{u}_{i,j,k}^* - \hat{u}_{i,j,k+1}^*) w_{i,j,k+1}^{I,x,t} \right]. \end{aligned}$$

From the contributions of the v - and w - equations to the \hat{u} -equation [the last two terms in Eq. (2.6)], two new terms appear. In the v -equation, the term Conv_{21} is written

$$\left. \frac{\partial v u}{\partial x} \right|_{i,j,k} = [\text{Conv}_{21}]_{i,j,k} = (\text{grad}_x) \left[v_{i+1,j,k}^{I,x} u_{i+1,j,k}^{I,y} - v_{i,j,k}^{I,x} u_{i,j,k}^{I,y} \right], \quad (2.7)$$

making use of the interpolation operators

$$\begin{aligned} u_{i,j,k}^{I,y} &= \frac{1}{2} (u_{i,j,k} + u_{i,j-1,k}), \\ v_{i,j,k}^{I,x} &= \frac{1}{2} (v_{i,j,k} + v_{i-1,j,k}). \end{aligned}$$

Note that the derivative in Eq. (2.7) is evaluated at y -faces, as is required for terms in the v -equation.

Upon substituting the expression for Conv_{21} [Eq. (2.7)] into the \hat{v} -contribution to the \hat{u} -equation [in Eq. (2.6)], we obtain

$$\begin{aligned} & \sum_{m,n,p} \hat{v}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} [\text{Conv}_{21}^t]_{m,n,p} \\ &= (\text{grad}_x) \sum_{m,n,p} \hat{v}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} \left[v_{m+1,n,p}^{I,x,t} u_{m+1,n,p}^{I,y,t} - v_{m,n,p}^{I,x,t} u_{m,n,p}^{I,y,t} \right] \\ &= \frac{1}{2} (\text{grad}_x) \left[(\hat{v}_{i-1,j,k}^* - \hat{v}_{i,j,k}^*) v_{i,j,k}^{I,x,t} + (\hat{v}_{i-1,j+1,k}^* - \hat{v}_{i,j+1,k}^*) v_{i,j+1,k}^{I,x,t} \right]. \end{aligned}$$

Now, note that this derivative is evaluated at x -faces, as is required for terms in the \hat{u} -equation! Similarly, for the contribution of Conv_{31} to the \hat{u} -equation, we obtain

$$\begin{aligned} & \sum_{m,n,p} \hat{w}_{m,n,p}^* \frac{\partial}{\partial u_{i,j,k}^t} [\text{Conv}_{31}^t]_{m,n,p} \\ &= \frac{1}{2} (\text{grad}_x) \left[(\hat{w}_{i-1,j,k}^* - \hat{w}_{i,j,k}^*) w_{i,j,k}^{I,x,t} + (\hat{w}_{i-1,j,k+1}^* - \hat{w}_{i,j,k+1}^*) w_{i,j,k+1}^{I,x,t} \right]. \end{aligned}$$

As before, note that this derivative is evaluated at x -faces.

The discrete-exact convective terms appearing in the \hat{v} - and \hat{w} -equations can be derived by repeating the steps above for these equations. These terms are implemented in the `adjoint.py` module of *PyFlow* but are omitted here for brevity.

3 Adjoint Verification

3.1 Methodology

1. Advance NS equations n_{iter} time steps of size Δt to obtain solution u_n and objective function \mathcal{L}

$$\begin{aligned}\mathcal{L} &= g(u_n, v_n, w_n) \\ &= \text{mean} \left[(u_n - u_{\text{target}})^2 \right]\end{aligned}$$

2. Advance *PyFlow* adjoint n_{iter} steps in reverse to obtain \hat{u}_0
3. Perturb the initial velocity field $u_0^* = u_0 + \Delta u$, then advance n_{iter} steps, size Δt , to obtain u_n^* and \mathcal{L}^*
4. Approximate the perturbation-based adjoint using finite differences:

$$\hat{u}_0^* = \frac{\partial \mathcal{L}}{\partial u_0} = \frac{\mathcal{L}^* - \mathcal{L}}{\Delta u} + \mathcal{O}(\Delta u)$$

5. Compute the convergence of the perturbation-based adjoint to the *PyFlow* adjoint as the relative error:

$$\epsilon_{\text{rel}} = \text{abs} \left(1 - \frac{\hat{u}_0^*}{\hat{u}_0} \right)$$

3.2 Notes

- The magnitude of the adjoint \hat{u}_0 is $\mathcal{O}(10^{-5})$, so truncation-error saturation can be expected for $\epsilon_{\text{rel}} \lesssim 10^{-10}$.
- The continuous versions of the self-adjoint viscous diffusion and pressure terms are implemented, and these terms converge as expected. The range of convergence is insensitive to both n_{iter} and Δt .
- The adjoint converges as expected when the discrete-exact convective terms are implemented. Again, the range of convergence is insensitive to both n_{iter} and Δt .
- The pressure correction reduces the error marginally within the asymptotic range of convergence.

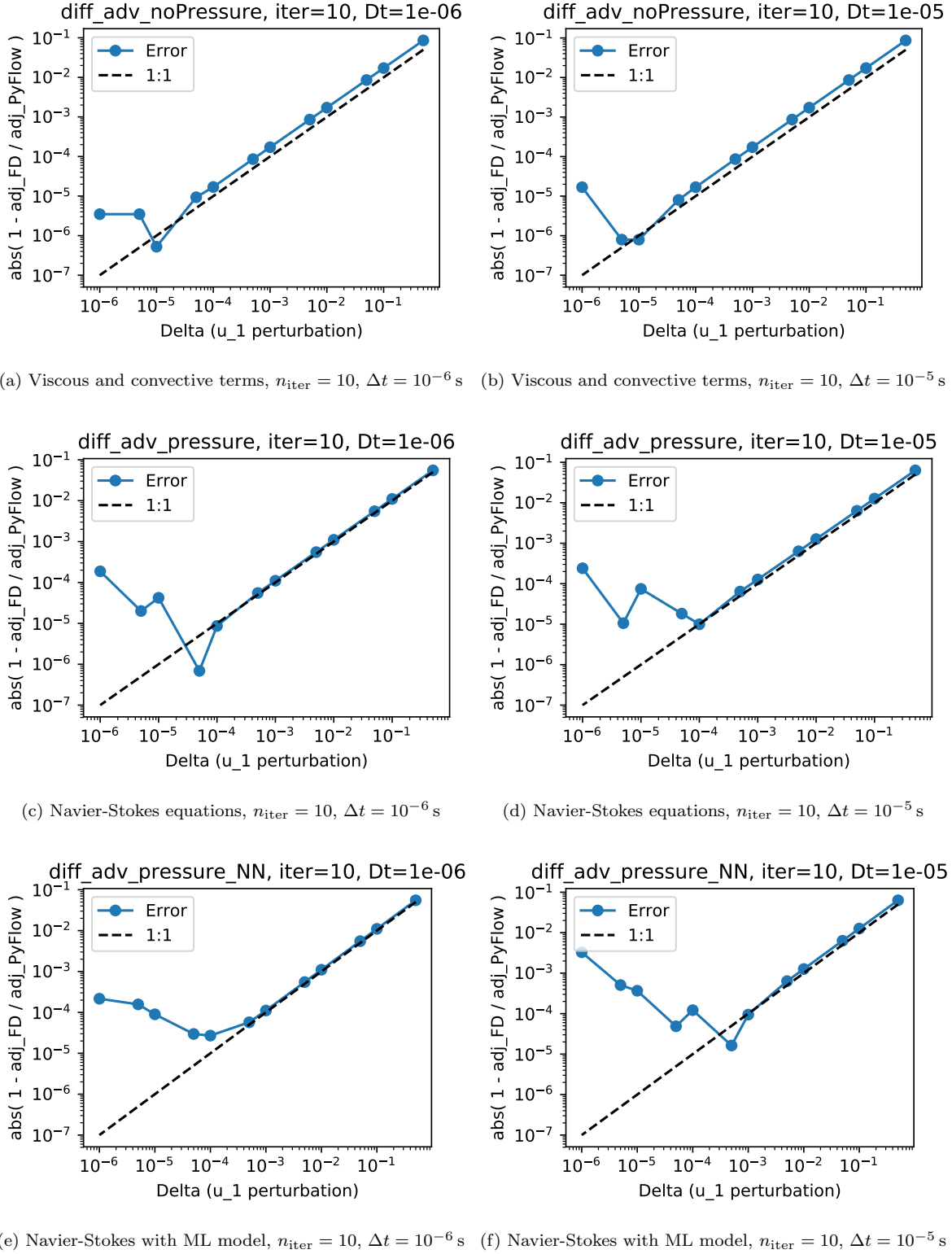


Figure 1: Convergence of the adjoint solution. The pressure solver is omitted in the top row and included in the bottom row. The total solution time ($n_{\text{iter}} \cdot \Delta t$) is increased by a factor of 10 in the right column.