

# Teminal 9 A-G

## Forme biliniare. Forme pătratice Formă conică) normală

Def  $g: V \times V \rightarrow K$  s.m. formă biliniară

$$(\Rightarrow) 1) g(ax + by, z) = ag(x, z) + bg(y, z)$$

$$2) g(x, ay + bz) = ag(x, y) + bg(x, z), \quad \forall x, y, z \in V, \quad \forall a, b \in K$$

$g$  este simetrică  $(\Rightarrow) g(x, y) = g(y, x)$  (multimea  
formelor  
biliniare)

$B = \{e_1, e_2, \dots, e_n\}$  bază în  $V$

$$g \in L(V, V, K)$$

$$(\Rightarrow) g(x, y) = \sum_{i,j=1}^n g_{ij} x_i y_j$$

Notatie  
 $g(e_i, e_j) = g_{ij}$

$$Q: V \rightarrow K$$

s.m. formă pătratică  $(\Rightarrow) \exists g \in L(V, V, K)$

$$Q(x) = g(x, x) = \sum_{i,j=1}^n g_{ij} x_i x_j$$

$$Q(x) = \sum_{i=1}^n g_{ii} x_i^2 + 2 \sum_{i < j} g_{ij} x_i x_j$$

$$Rg \ G = Q$$

$$Q = a_1 x_1'^2 + \dots + a_n x_n'^2$$

$$Q: \mathbb{R}^4 \rightarrow \mathbb{R}$$

$$Q(x) = x_1^2 + x_2^2 + x_3^2 - 2x_4^2 - 2x_1x_2 + 2x_1x_3 - 2x_1x_4 + 2x_2x_3 - 4x_2x_4$$

$$a) \quad G = \begin{pmatrix} 1 & -1 & 1 & -1 \\ -1 & 1 & 1 & -2 \\ 1 & 1 & 1 & 0 \\ -1 & -2 & 0 & -2 \end{pmatrix}$$

b)  $Q \rightarrow$  formă canonică

Metoda Jacobi nu se poate aplica în acest caz

~~$$Q(x) = x_1^2 + x_2^2 + x_3^2 - 2x_4^2 - 2x_1x_2 + 2x_1x_3 - 2x_1x_4 + 2x_2x_3 - 4x_2x_4$$~~

$$Q(x) = x_1^2 + x_2^2 + x_3^2 - 2x_4^2 - 2x_1x_2 + 2x_1x_3 - 2x_1x_4 + 2x_2x_3 - 4x_2x_4$$

$$= (x_1 - x_2 + x_3 - x_4)^2 - x_2^2 - x_3^2 - x_4^2 + 2x_1x_3 - 2x_2x_4 + 2x_2x_3 - 4x_2x_4$$

$$= (x_1 - x_2 + x_3 - x_4)^2 - 3x_4^2 + 4x_2x_3 - 6x_2x_4 + 2x_3x_4$$

fie schimbarea  $y_1 = (x_1 - x_2 + x_3 - x_4)$

$$\begin{cases} x_2' = x_2 + x_3 \\ x_3' = x_2 - x_3 \\ x_1' = x_1 \\ x_4' = x_4 \end{cases}$$

$$\begin{cases} x_1 = x_1' \\ x_2 = \frac{1}{2}(x_2' + x_3') \\ x_3 = \frac{1}{2}(x_2' - x_3') \\ x_4 = x_4' \end{cases}$$



$$Q(x) = (x_1' - x_3' - x_4')^2 + x_2'^2 - x_3'^2 - 3x_2'x_4' - 3x_3'x_4'$$

$$Q(x) = (x_1' - x_3' - x_4')^2 + \left(x_2' - \frac{3}{2}x_4'\right)^2 + \left(x_2' - \frac{3}{2}x_4'\right)^2 - \frac{2}{4}x_4'^2 - x_3'^2 - 3x_3'x_4' - 3x_4'^2$$

$$Q(x) = (x_1' - x_3' - x_4')^2 + \left(x_2' - \frac{3}{2}x_4'\right)^2 - \left(x_3' + \frac{1}{2}x_4'\right)^2 - x_4'^2$$

$$\Rightarrow \begin{cases} x_1'' = x_1' - x_3' - x_4' \\ x_2'' = x_2' - \frac{3}{2}x_4' \\ x_3'' = x_3' + \frac{1}{2}x_4' \\ x_4'' = x_4' \cdot \sqrt{3} \end{cases}$$

$$\Rightarrow Q(x) = x_1''^2 + x_2''^2 - x_3''^2 - x_4''^2$$

4 pătrate =  $\text{rg}(G)$   
 semnatura (2, 2)

pozitiv definită (0)  
 semnatura (4, 0)

$$Q: \mathbb{R}^4 \rightarrow \mathbb{R}$$

a)  $Q = ?$

b) să se diagonalizeze (forma canonică)

$$G = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 1 & 2 \\ 1 & 2 & 1 \end{pmatrix}$$

$$\textcircled{a} Q = x_1^2 + x_2^2 + x_3^2 + 4x_1x_2 + 2x_1x_3 + 4x_2x_3$$

b) Metoda Jacobi  $\Delta_1 = 1$   
 $\Delta_2 = \begin{vmatrix} 1 & 2 \\ 2 & 3 \end{vmatrix} = -1 < 0$   
 $\Delta_3 = \begin{vmatrix} 1 & 2 & 1 \\ 2 & 3 & 2 \\ 1 & 2 & 1 \end{vmatrix} = 3 + 4 + 4 - 3 - 4 - 3 = 0$   
 $\Rightarrow$  nu merge Jacobi

$$\begin{aligned} Q(x) &= x_1^2 + 3x_2^2 + x_3^2 + 4x_1x_2 + 2x_1x_3 + 4x_2x_3 \\ &= (x_1 + 2x_2 + x_3)^2 - 4x_2x_3 - 4x_2^2 - x_3^2 + 3x_2^2 + x_3^2 + 4x_2x_3 \\ &= \underbrace{(x_1 + 2x_2 + x_3)^2}_{x_1'^2} - \underbrace{x_2^2}_{x_2'^2} \end{aligned}$$

$\Rightarrow Q(x) = x_1'^2 - x_2'^2$

nu e pozitivă definită

$$\begin{cases} x_1' = x_1 + 2x_2 + x_3 \\ x_2' = x_2 \\ x_3' = x_3 \end{cases}$$

signatura (1,1)

$\Rightarrow B' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$  e diagonalizabilă