UNIVERSITÄT BONN

Foundations of Machine Learning in Python

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High-Performance Computing and Analytics Lab

Overview

Neural networks

Classification with neural networks

Neural networks

The wonders of the human visual system

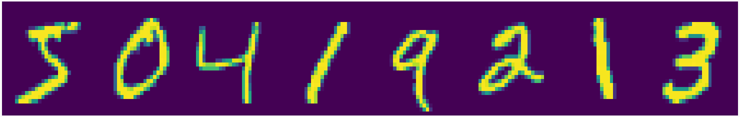
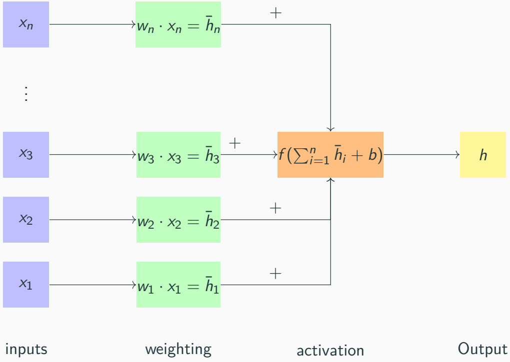


Figure: Most humans effortlessly recognize the digits 5 0 4 1 9 2 1 3.

The perceptron

Can computers recognize digits? Mimic biological neurons,



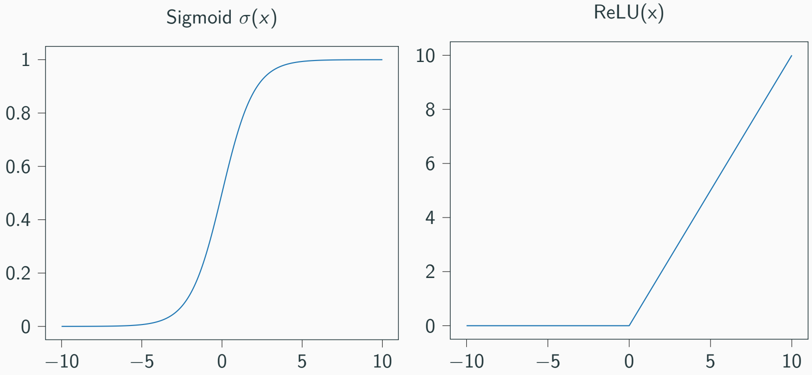
Formally a single perceptron is defined as

$$f(\mathbf{w}^T \mathbf{x}) = h \tag{1}$$

with $\mathbf{w} \in \mathbb{R}^n$, $\mathbf{x} \in \mathbb{R}^n$ and $h \in \mathbb{R}$.

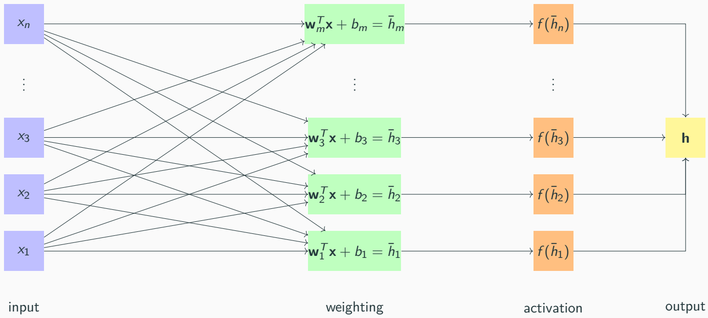
The activation function f

Two popular choices for the activation function f.



Arrays of perceptrons

Let's extend the definition to cover an array of perceptrons:



Every input is connected to every neuron. In matrix language, this turns into

$$\bar{\mathbf{h}} = \mathbf{W}\mathbf{x} + \mathbf{b}, \qquad \mathbf{h} = f(\bar{\mathbf{h}}). \tag{2}$$

With $\mathbf{W} \in \mathbb{R}^{m,n}$, $\mathbf{x} \in \mathbb{R}^n$, $\mathbf{b} \in \mathbb{R}^m$, and $\mathbf{h}, \bar{\mathbf{h}} \in \mathbb{R}^m$.

The loss function

To choose weights for the network, we require a quality measure. We already saw the mean squared error cost function,

$$C_{\text{mse}} = \frac{1}{2}\sum_{k=1}^{n}(\mathbf{y}_k - \mathbf{h}_k)^2 = \frac{1}{2}(\mathbf{y} - \mathbf{h})^T(\mathbf{y} - \mathbf{h}) \tag{3}$$

This function measures the squared distance from each desired output. **y** denotes the desired labels, and **h** represents network output.

The gradient of the mse-cost-function

Both the mean squared error loss function and our dense layer are differentiable.

$$\frac{\partial C_{\text{mse}}}{\partial \mathbf{h}} = \mathbf{h} - \mathbf{y} = \triangle_{\text{mse}} \tag{4}$$

The $\triangle$ symbol will re-appear. It always indicates incoming gradient information from above. If the labels are a vector of shape $\mathbb{R}^m$, $\triangle$ and the network output $\mathbf{h}$ must share this dimension.

The gradient of a dense layer

The chain rule tells us the gradients for the dense layer [Nie15]

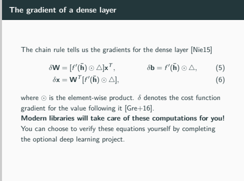
$$\delta \mathbf{W} = [f'(\bar{\mathbf{h}}) \odot \triangle]\mathbf{x}^T, \qquad \delta \mathbf{b} = f'(\bar{\mathbf{h}}) \odot \triangle, \tag{5}$$

$$\delta \mathbf{x} = \mathbf{W}^T [f'(\bar{\mathbf{h}}) \odot \triangle], \tag{6}$$

where $\odot$ is the element-wise product. δ denotes the cost function gradient for the value following it [Gre+16].

Modern libraries will take care of these computations for you!

You can choose to verify these equations yourself by completing the optional deep learning project.



On the board, derive: Recall the chain rule $(g(h(x)))' = g'(h(x)) \cdot h'(x)$. For the activation function, we have,

$$\bar{\mathbf{h}} = f(\bar{\mathbf{h}}) \tag{7}$$

$$\Rightarrow \delta\bar{\mathbf{h}} = f'(\bar{\mathbf{h}}) \odot \triangle \tag{8}$$

For the weight matrix,

$$\bar{\mathbf{h}} = \mathbf{W}\mathbf{x} + \mathbf{b} \tag{9}$$

$$\Rightarrow \delta\mathbf{W} = \delta\bar{\mathbf{h}}\mathbf{x}^T = [f'(\bar{\mathbf{h}}) \odot \triangle]^T\mathbf{x} \tag{10}$$

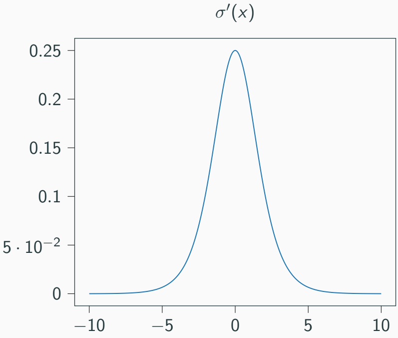
For the bias,

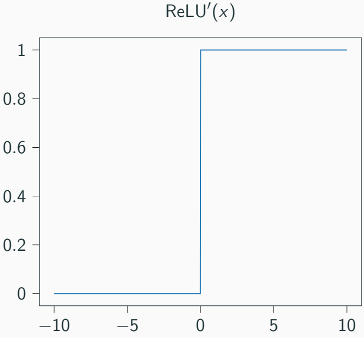
$$\bar{\mathbf{h}} = \mathbf{W}\mathbf{x} + \mathbf{b} \tag{11}$$

$$\Rightarrow \delta\mathbf{b} = 1 \odot \delta\bar{\mathbf{h}} = [f'(\bar{\mathbf{h}}) \odot \triangle] \tag{12}$$

Derivatives of our activation functions

$$\sigma'(x) = \sigma \cdot (1 - \sigma(x)) \tag{13}$$
$$\mathrm{ReLU}' = H(x) \tag{14}$$





Perceptrons for functions

The network components described this far already allow function learning. Given a noisy input signal $x \in \mathbb{R}^m$ and a ground through output $y \in \mathbb{R}^m$, define,

$$\mathbf{h} = \sigma(\mathbf{W}\mathbf{x} + \mathbf{b}) \tag{15}$$

$$\mathbf{y}_{\text{net}} = \mathbf{W}_y\mathbf{h} \tag{16}$$

With $\mathbf{W} \in \mathbb{R}^{m,n}$, $\mathbf{x} \in \mathbb{R}^n$ and $\mathbf{b} \in \mathbb{R}^m$. m and n denote the number of neurons and the input signal length. For signal denoising, input and output have the same length. Therefore $\mathbf{W}_y \in \mathbb{R}^{n,m}$.

Denoising a cosine

Training works by iteratively descending along the gradients. For $\mathbf{W}$ the weights at the next time step τ are given by,

$$\mathbf{W}_{\tau+1} = \mathbf{W}_{\tau} + \epsilon \cdot \delta \mathbf{W}_{\tau}. \tag{17}$$

The step size is given by ϵ. At $\tau = 0$ matrix entries are random. $\mathcal{U}[-0.1, 0.1]$ is a reasonable choice here. The process is the same for all other network components.

Denoising a cosine

Optimization for 500 steps leads to the output below:

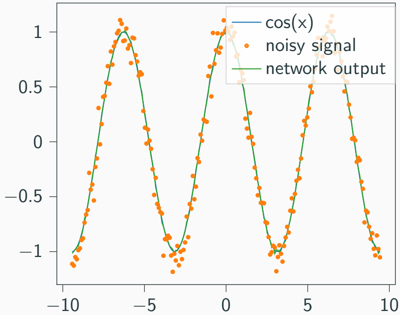


Figure: The cosine function is shown in blue. A noisy network input in orange, and a denoised network output in green.

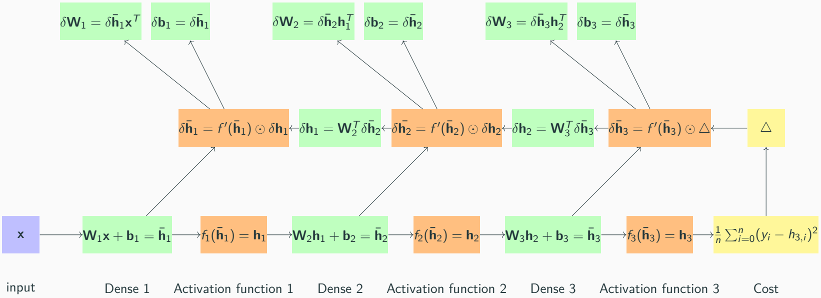
Classification with neural networks

Deep multi-layer networks

Stack dense layers and activations to create deep networks.

$\mathbf{x}$ $\rightarrow$	$\mathbf{W}_1\mathbf{x} + \mathbf{b}_1 = \bar{\mathbf{h}}_1$ $\rightarrow$	$f_1(\bar{\mathbf{h}}_1) = \mathbf{h}_1$ $\rightarrow$	$\mathbf{W}_2\mathbf{h}_1 + \mathbf{b}_2 = \bar{\mathbf{h}}_2$ $\rightarrow$	$f_2(\bar{\mathbf{h}}_2) = \mathbf{h}_2$ $\rightarrow$	$\mathbf{W}_3\mathbf{h}_2 + \mathbf{b}_3 = \bar{\mathbf{h}}_3$ $\rightarrow$	$f_3(\bar{\mathbf{h}}_3) = \mathbf{h}_3$ $\rightarrow$	$\frac{1}{n}\sum(\mathbf{y} - \mathbf{h}_3)^2$
input	Dense 1	Activation function 1	Dense 2	Activation function 2	Dense 3	Activation function 3	Cost

Backpropagation



The cross-entropy loss

The cross entropy loss function is defined as [Nie15; Bis06]

$$C_{\text{ce}}(\mathbf{y}, \mathbf{o}) = -\sum_{k}^{n_o}(\mathbf{y}_k \ln \mathbf{o}_k) + (\mathbf{1} - \mathbf{y}_k) \ln(\mathbf{1} - \mathbf{o}_k). \tag{18}$$

If a sigmoidal activation function produced $\mathbf{o}$ the gradients can be computed using [Nie15; Bis06]

$$\frac{\partial C_{ce}}{\partial \mathbf{h}} = \sigma(\mathbf{o}) - \mathbf{y} = \triangle_{\text{ce}} \tag{19}$$

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TODO: find the proof.

The MNIST-Dataset

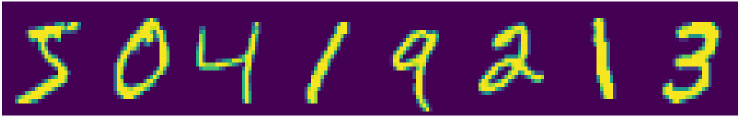


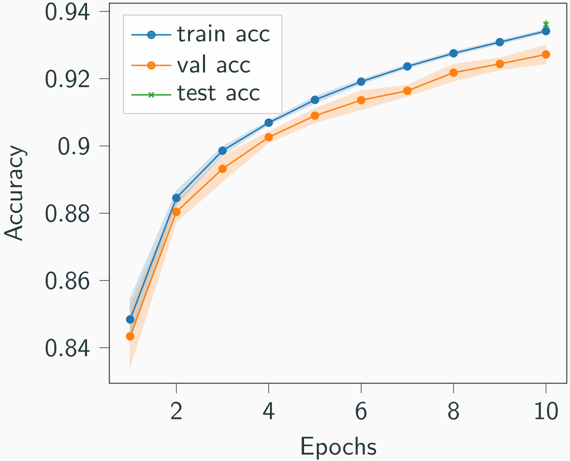
Figure: The MNIST-dataset contains 70k images of handwritten digits.

Validation and Test data splits

- To ensure the correct operation of the systems we devise, it is paramount to hold back part of the data for validation and testing.
- Before starting to train, split off validation and test data.
- The 70k MNIST samples could, for example, be partitioned into 59k training images. 1k validation images and 10k test images.

MNIST-Classification

Training a three-layer dense network on mnist for five runs leads to:



Conclusion

- Artificial neural networks enable computers to make sense of images.
- The optimization result depends on the initialization.
- The initialization depends on the pseudo-randomness-seed.
- Seed-values must be recorded.

References

[Bis06] Christopher M Bishop. *Pattern recognition and machine learning*. springer, 2006.

[Gre+16] Klaus Greff, Rupesh K Srivastava, Jan Koutnik, Bas R Steunebrink, and Jürgen Schmidhuber. "LSTM: A search space odyssey." In: *IEEE transactions on neural networks and learning systems* 28.10 (2016), pp. 2222–2232.

[Nie15] Michael A Nielsen. *Neural networks and deep learning*. Vol. 25. Determination press San Francisco, CA, USA, 2015.