

# Foundations of Machine Learning in Python

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#### **Overview**

Neural networks

Estimation, Overfitting and Regularization

Classification

# Neural networks

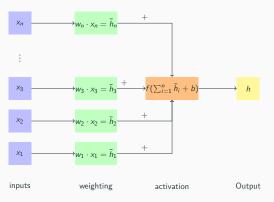
#### The wonders of the human visual system



Figure: Most humans effortlessly recognize the digits 5 0 4 1 9 2 1 3.

### The perceptron

Can computers recognize digits? Mimic biological neurons,



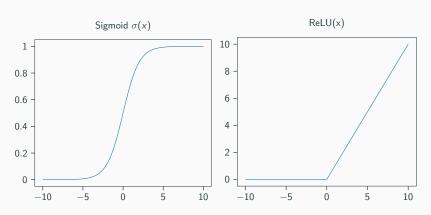
Formally a single perceptron is defined as

$$f(\mathbf{w}^{\mathsf{T}}\mathbf{x}) = h \tag{1}$$

with  $\mathbf{w} \in \mathbb{R}^n$ .  $\mathbf{x} \in \mathbb{R}^n$  and  $h \in \mathbb{R}$ .

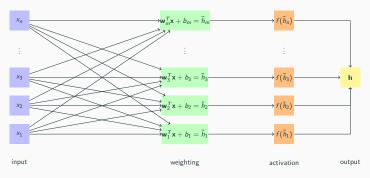
#### The activation function f

Two popular choices for the activation function f.



## Arrays of perceptrons

Let's extend the definition to cover an array of perceptrons:



Every input is connected to every neuron. In matrix language, this turns into

$$\bar{\mathbf{h}} = \mathbf{W}\mathbf{x} + \mathbf{b}, \qquad \qquad \mathbf{h} = f(\bar{\mathbf{h}}).$$
 (2)

With  $\mathbf{W} \in \mathbb{R}^{m,n}$ ,  $\mathbf{x} \in \mathbb{R}^n$ ,  $\mathbf{b} \in \mathbb{R}^m$ , and  $\mathbf{h}, \bar{\mathbf{h}} \in \mathbb{R}^m$ .

#### The loss function

To choose weights for the network, we require a quality measure. We already saw the mean squared error cost function,

$$C_{\text{mse}} = \frac{1}{2} \sum_{k=1}^{n} (\mathbf{y}_k - \mathbf{h}_k)^2 = \frac{1}{2} (\mathbf{y} - \mathbf{h})^T (\mathbf{y} - \mathbf{h})$$
 (3)

This function measures the squared distance from each desired output.  $\mathbf{y}$  denotes the desired labels, and  $\mathbf{h}$  represents network output.

#### The gradient of the mse-cost-function

Both the mean squared error loss function and our dense layer are differentiable.

$$\frac{\partial C_{\text{mse}}}{\partial \mathbf{h}} = \mathbf{h} - \mathbf{y} = \triangle_{\text{mse}} \tag{4}$$

The  $\triangle$  symbol will re-appear. It always indicates incoming gradient information from above. If the labels are a vector of shape  $\mathbb{R}^m$ ,  $\triangle$  and the network output  $\mathbf{h}$  must share this dimension.

#### The gradient of a dense layer

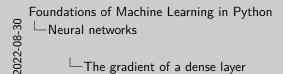
The chain rule tells us the gradients for the dense layer [Nie15]

$$\delta \mathbf{W} = [f'(\bar{\mathbf{h}}) \odot \triangle] \mathbf{x}^T, \qquad \delta \mathbf{b} = f'(\bar{\mathbf{h}}) \odot \triangle, \qquad (5)$$

$$\delta \mathbf{x} = \mathbf{W}^{\mathsf{T}}[f'(\bar{\mathbf{h}}) \odot \triangle], \tag{6}$$

where  $\odot$  is the element-wise product.  $\delta$  denotes the cost function gradient for the value following it [Gre+16].

Good news! Jax can take care of these computations for you! You can choose to verify these equations by completing the optional deep learning project.



☐ The gradient of a dense layer

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The gradient of a dense layer

On the board, derive: Recall the chain rule  $(g(h(x)))' = g'(h(x)) \cdot h'(x)$ . For the activation function, we have,

$$\bar{\mathbf{h}} = f(\bar{\mathbf{h}}) \tag{7}$$

$$\Rightarrow \delta \bar{\mathbf{h}} = f'(\bar{\mathbf{h}}) \odot \triangle \tag{8}$$

For the weight matrix,

$$\bar{\mathbf{h}} = \mathbf{W}\mathbf{x} + \mathbf{b}$$
 (9)

$$\Rightarrow \delta \mathbf{W} = \delta \bar{\mathbf{h}} \mathbf{x}^T = [f'(\bar{\mathbf{h}}) \odot \triangle]^T \mathbf{x}$$
 (10)

For the bias.

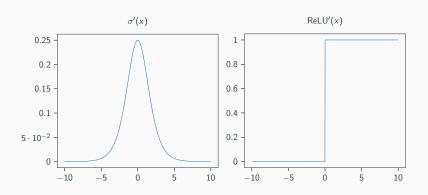
$$\bar{\mathbf{h}} = \mathbf{W}\mathbf{x} + \mathbf{b} \tag{11}$$

$$\Rightarrow \delta \mathbf{b} = 1 \odot \delta \bar{\mathbf{h}} = [f'(\bar{\mathbf{h}}) \odot \triangle]$$
 (12)

#### **Derivatives of our activation functions**

$$\sigma'(x) = \sigma \cdot (1 - \sigma(x)) \tag{13}$$

$$ReLU' = H(x) \tag{14}$$



## Perceptrons can learn functions

# Multi-layer networks

# Backpropagation

# Estimation, Overfitting and

Regularization

# Denoising a signal

# Classification

# The cross-entropy loss

### MNIST digit

Modified National Institute of Standards and Technology database [dumoulin2016guide]

#### Literature

#### References

- [Gre+16] Klaus Greff, Rupesh K Srivastava, Jan Koutnik, Bas R Steunebrink, and Jürgen Schmidhuber. "LSTM: A search space odyssey." In: IEEE transactions on neural networks and learning systems 28.10 (2016), pp. 2222–2232.
- [Nie15] Michael A Nielsen. Neural networks and deep learning. Vol. 25. Determination press San Francisco, CA, USA, 2015.