

# Foundations of Machine Learning in Python

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#### **Overview**

Neural networks

Classification with neural networks

# Neural networks

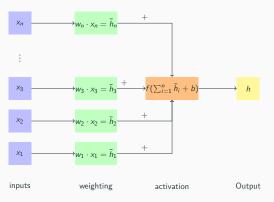
### The wonders of the human visual system



Figure: Most humans effortlessly recognize the digits 5 0 4 1 9 2 1 3.

# The perceptron

Can computers recognize digits? Mimic biological neurons,



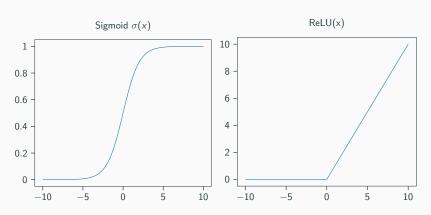
Formally a single perceptron is defined as

$$f(\mathbf{w}^{\mathsf{T}}\mathbf{x}) = h \tag{1}$$

with  $\mathbf{w} \in \mathbb{R}^n$ .  $\mathbf{x} \in \mathbb{R}^n$  and  $h \in \mathbb{R}$ .

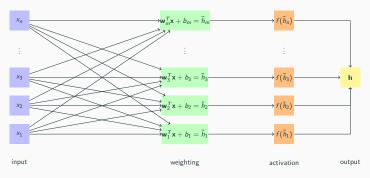
#### The activation function f

Two popular choices for the activation function f.



# Arrays of perceptrons

Let's extend the definition to cover an array of perceptrons:



Every input is connected to every neuron. In matrix language, this turns into

$$\bar{\mathbf{h}} = \mathbf{W}\mathbf{x} + \mathbf{b}, \qquad \qquad \mathbf{h} = f(\bar{\mathbf{h}}).$$
 (2)

With  $\mathbf{W} \in \mathbb{R}^{m,n}$ ,  $\mathbf{x} \in \mathbb{R}^n$ ,  $\mathbf{b} \in \mathbb{R}^m$ , and  $\mathbf{h}, \bar{\mathbf{h}} \in \mathbb{R}^m$ .

#### The loss function

To choose weights for the network, we require a quality measure. We already saw the mean squared error cost function,

$$C_{\text{mse}} = \frac{1}{2} \sum_{k=1}^{n} (\mathbf{y}_k - \mathbf{h}_k)^2 = \frac{1}{2} (\mathbf{y} - \mathbf{h})^T (\mathbf{y} - \mathbf{h})$$
 (3)

This function measures the squared distance from each desired output.  $\mathbf{y}$  denotes the desired labels, and  $\mathbf{h}$  represents network output.

## The gradient of the mse-cost-function

Both the mean squared error loss function and our dense layer are differentiable.

$$\frac{\partial C_{\text{mse}}}{\partial \mathbf{h}} = \mathbf{h} - \mathbf{y} = \triangle_{\text{mse}} \tag{4}$$

The  $\triangle$  symbol will re-appear. It always indicates incoming gradient information from above. If the labels are a vector of shape  $\mathbb{R}^m$ ,  $\triangle$  and the network output  $\mathbf{h}$  must share this dimension.

### The gradient of a dense layer

The chain rule tells us the gradients for the dense layer [Nie15]

$$\delta \mathbf{W} = [f'(\bar{\mathbf{h}}) \odot \triangle] \mathbf{x}^T, \qquad \delta \mathbf{b} = f'(\bar{\mathbf{h}}) \odot \triangle, \qquad (5)$$

$$\delta \mathbf{x} = \mathbf{W}^{\mathsf{T}}[f'(\bar{\mathbf{h}}) \odot \triangle], \tag{6}$$

where  $\odot$  is the element-wise product.  $\delta$  denotes the cost function gradient for the value following it [Gre+16].

Modern libraries will take care of these computations for you! You can choose to verify these equations yourself by completing the optional deep learning project.

The chain rule talls us the gradients for the dense layer [Niis15]  $\delta W = [I'(\hat{b}) \otimes \triangle_i \hat{x}^T, \qquad \delta b = I'(\hat{b}) \otimes \triangle_i \qquad (5) \\ \delta x = W^T [I'(\hat{b}) \otimes \triangle_i], \qquad (6)$  where  $\hat{b}$  is the element-wise product.  $\delta$  denotes the coof function gradient for the value following it [Cor+16]. Moderns Brainies with take care of these computations for youl You can choose to verify these equations yourself by completing the optional depth saming project.

The gradient of a dense layer

On the board, derive: Recall the chain rule  $(g(h(x)))' = g'(h(x)) \cdot h'(x)$ . For the activation function, we have,

$$\bar{\mathbf{h}} = f(\bar{\mathbf{h}}) \tag{7}$$

$$\Rightarrow \delta \bar{\mathbf{h}} = f'(\bar{\mathbf{h}}) \odot \triangle \tag{8}$$

For the weight matrix,

$$\bar{\mathbf{h}} = \mathbf{W}\mathbf{x} + \mathbf{b} \tag{9}$$

$$\Rightarrow \delta \mathbf{W} = \delta \bar{\mathbf{h}} \mathbf{x}^{T} = [f'(\bar{\mathbf{h}}) \odot \triangle]^{T} \mathbf{x}$$
 (10)

For the bias,

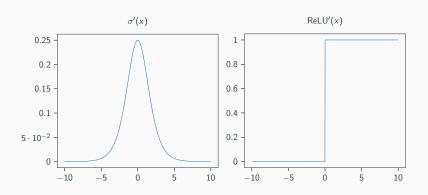
$$\bar{\mathbf{h}} = \mathbf{W}\mathbf{x} + \mathbf{b} \tag{11}$$

$$\Rightarrow \delta \mathbf{b} = 1 \odot \delta \bar{\mathbf{h}} = [f'(\bar{\mathbf{h}}) \odot \triangle]$$
 (12)

#### **Derivatives of our activation functions**

$$\sigma'(x) = \sigma \cdot (1 - \sigma(x)) \tag{13}$$

$$ReLU' = H(x) \tag{14}$$



### **Perceptrons for functions**

The network components described this far already allow function learning. Given a noisy input signal  $x \in \mathbb{R}^m$  and a ground through output  $y \in \mathbb{R}^m$ , define,

$$\mathbf{h} = \sigma(\mathbf{W}\mathbf{x} + \mathbf{b}) \tag{15}$$

$$\mathbf{y}_{\mathsf{net}} = \mathbf{W}_{y} \mathbf{h} \tag{16}$$

With  $\mathbf{W} \in \mathbb{R}^{m,n}$ ,  $\mathbf{x} \in \mathbb{R}^n$  and  $\mathbf{b} \in \mathbb{R}^m$ . m and n denote the number of neurons and the input signal length. For signal denoising, input and output have the same length. Therefore  $\mathbf{W}_y \in \mathbb{R}^{n,m}$ .

## Denoising a cosine

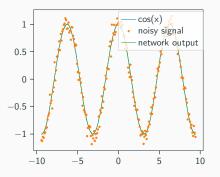
Training works by iteratively descending along the gradients. For  ${\bf W}$  the weights at the next time step  $\tau$  are given by,

$$\mathbf{W}_{\tau+1} = \mathbf{W}_{\tau} + \epsilon \cdot \delta \mathbf{W}_{\tau}. \tag{17}$$

The step size is given by  $\epsilon$ . At  $\tau=0$  matrix entries are random.  $\mathcal{U}[-0.1,0.1]$  is a reasonable choice here. The process is the same for all other network components.

# Denoising a cosine

Optimization for 500 steps leads to the output below:



**Figure:** The cosine function is shown in blue. A noisy network input in orange, and a denoised network output in green.

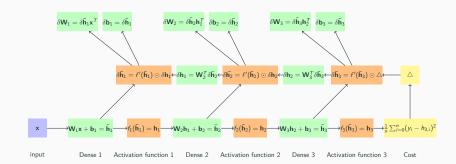
Classification with neural networks

### Deep multi-layer networks

Stack dense layers and activations to create deep networks.



# **Backpropagation**



## The cross-entropy loss

The cross entropy loss function is defined as [Nie15; Bis06]

$$C_{ce}(\mathbf{t}, \mathbf{o}) = -\sum_{k}^{n_o} (\mathbf{t}_k \ln \mathbf{o}_k) + (\mathbf{1} - \mathbf{t}_k) \ln(\mathbf{1} - \mathbf{o}_k). \tag{18}$$

If a sigmoidal activation function produced  $\bf o$  the gradients can be computed using [Nie15; Bis06]

$$\frac{\partial C_{ce}}{\partial \mathbf{h}} = \sigma(\mathbf{h}) - \mathbf{y} = \triangle_{ce}$$
 (19)

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The cross-entropy loss

TODO: find the proof.



# Validation and Test data splits

TODO

#### **MNIST-Classification**

TODO

#### Literature

#### References

- [Bis06] Christopher M Bishop. *Pattern recognition and machine learning*. springer, 2006.
- [Gre+16] Klaus Greff, Rupesh K Srivastava, Jan Koutnik, Bas R Steunebrink, and Jürgen Schmidhuber. "LSTM: A search space odyssey." In: IEEE transactions on neural networks and learning systems 28.10 (2016), pp. 2222–2232.
- [Nie15] Michael A Nielsen. Neural networks and deep learning. Vol. 25. Determination press San Francisco, CA, USA, 2015.