

RECOMMENDATION AND STARFISH

Shripad Deshmukh



Watch, read, and listen. All of your entertainment in one place.



170,000+ films & TV shows



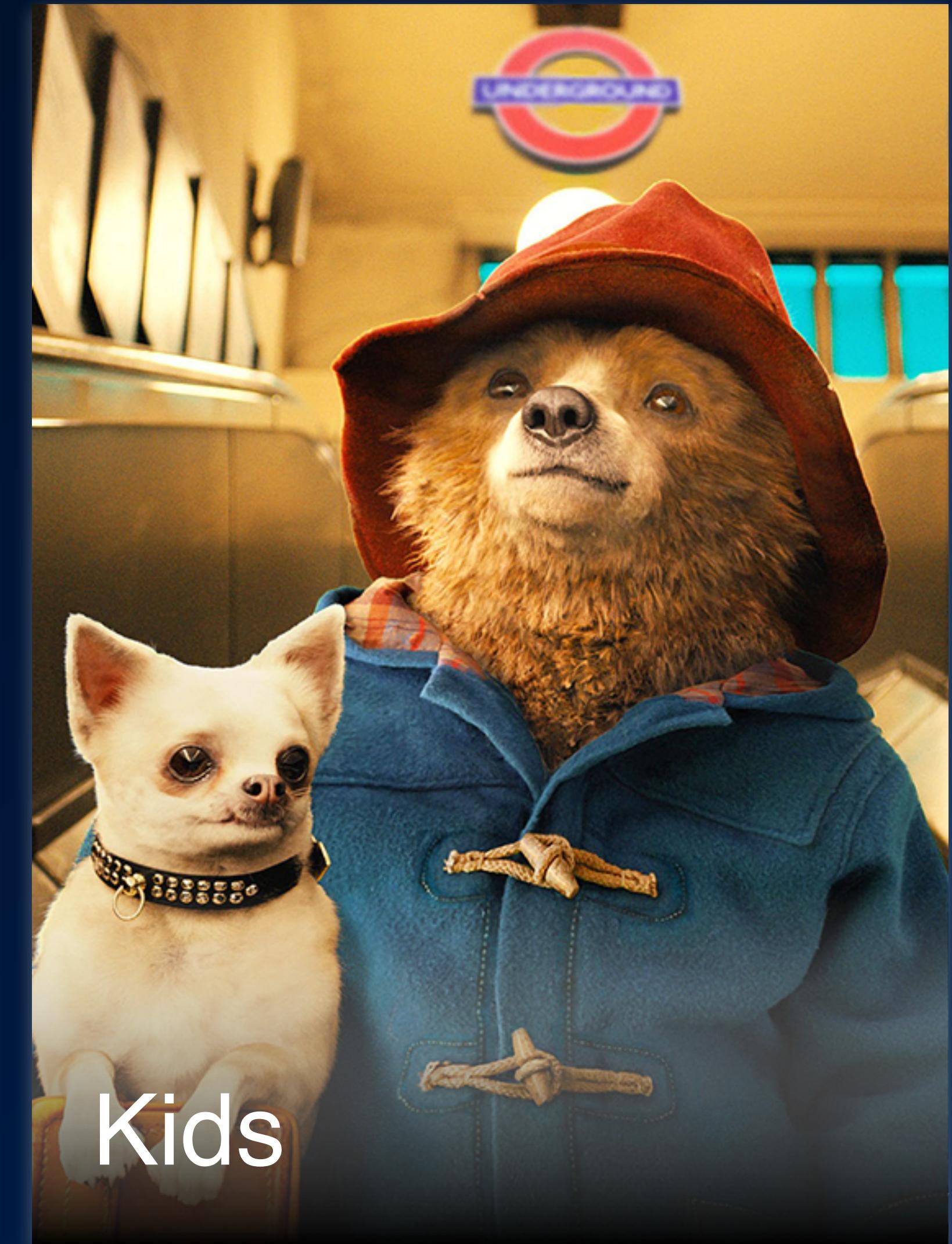
170,000+ films & TV shows



TV Shows (JP)



Anime

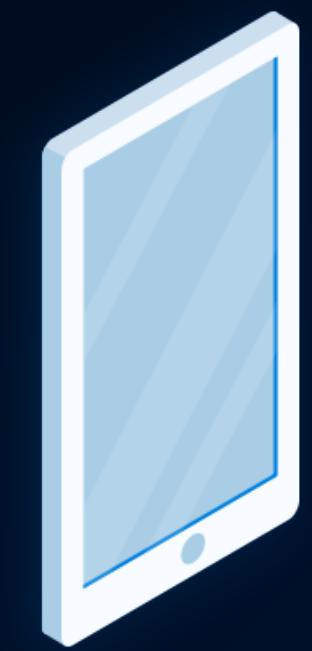


Kids

To all platforms



TVs



Smart
devices



Gaming
consoles

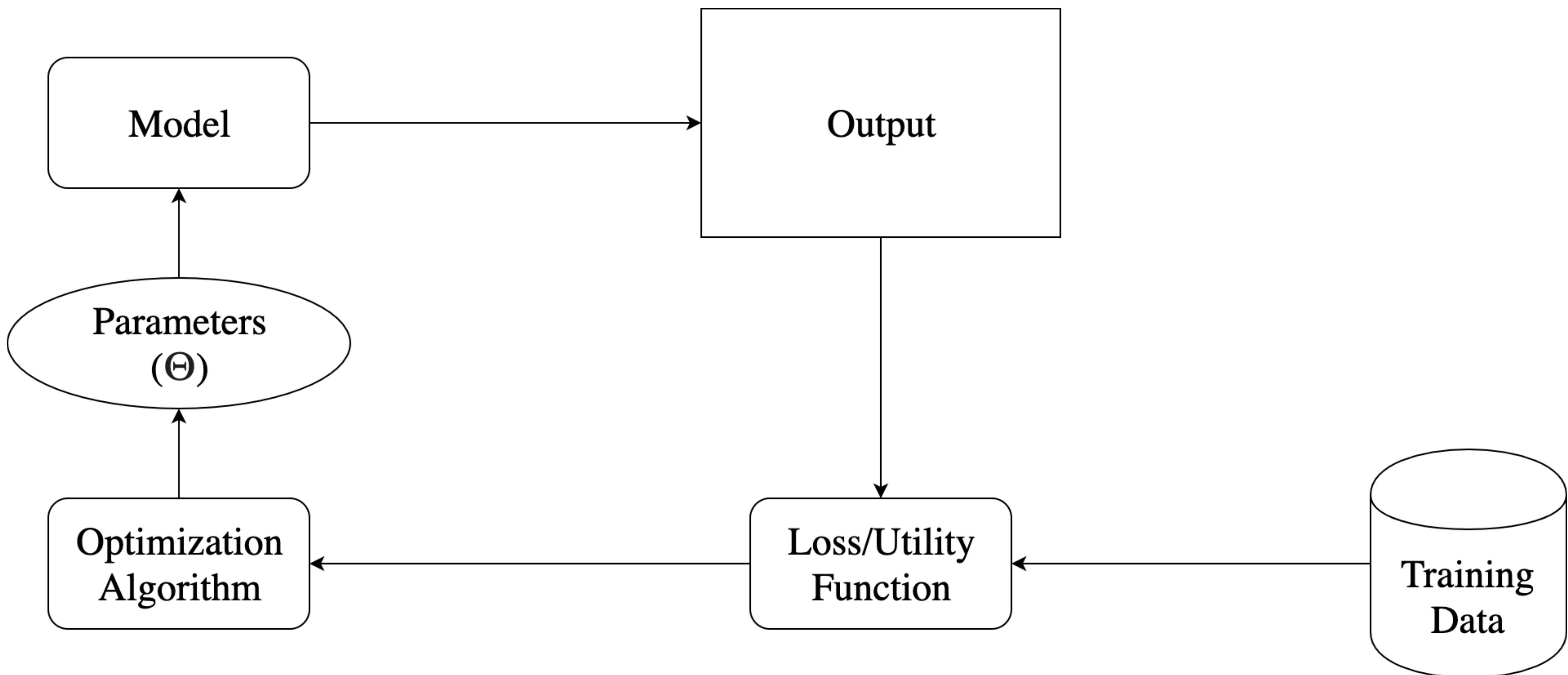


PCs

IMPLICIT DATA

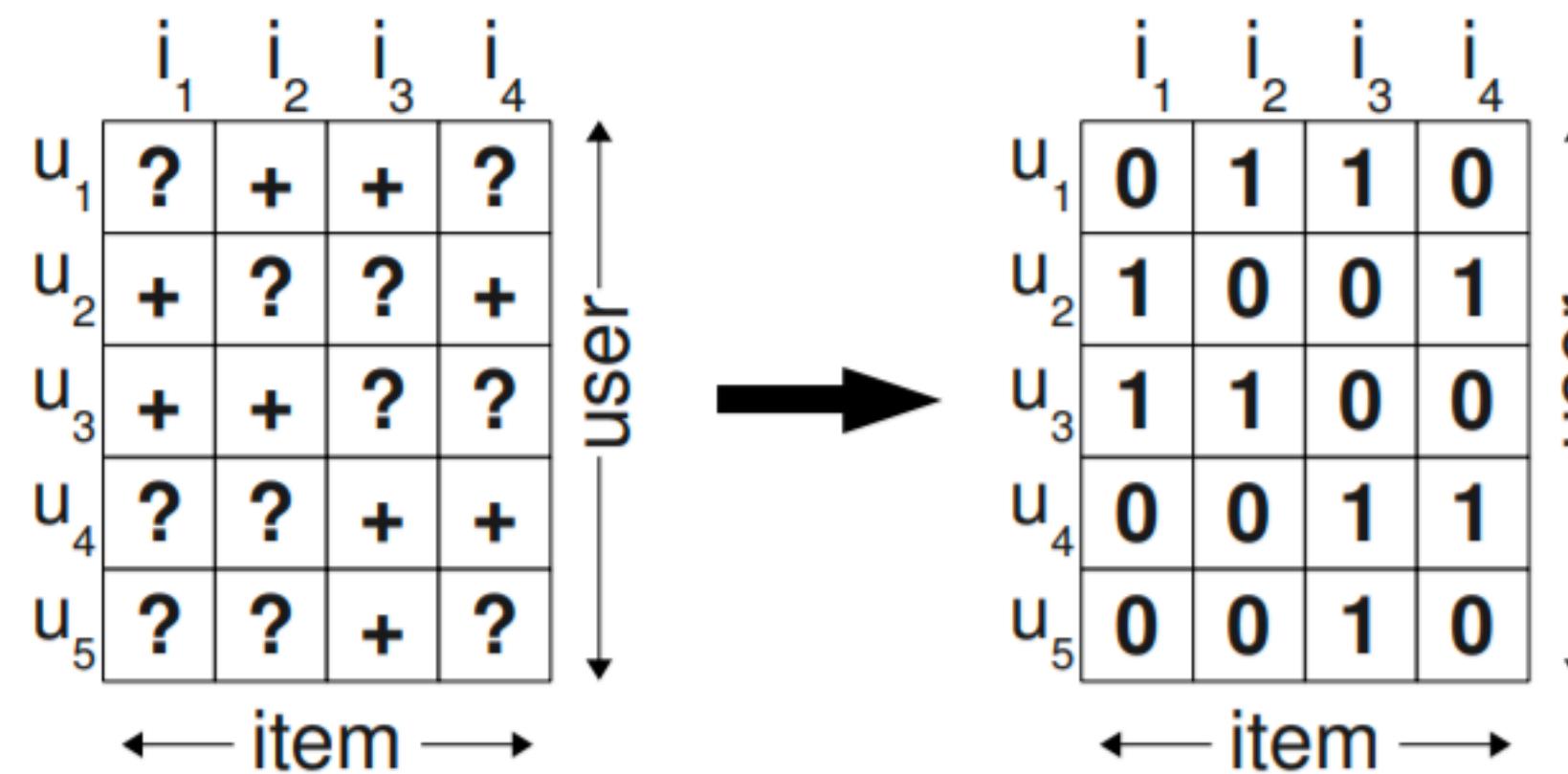
- Implicit Data:
 - No negative feedback
 - Inherently noisy
 - Preference vs Confidence

LEARNING RECOMMENDER SYSTEM



TRAINING DATA

X_{ui} -> Score for an item that reflects
Users preference for that item



TRAINING DATA

x_{ui} -> Score for an item that reflects
Users preference for that item

	i_1	i_2	i_3	i_4
u_1	?	+	+	?
u_2	+	?	?	+
u_3	+	+	?	?
u_4	?	?	+	+
u_5	?	?	+	?



	i_1	i_2	i_3	i_4
u_1	0	1	1	0
u_2	1	0	0	1
u_3	1	1	0	0
u_4	0	0	1	1
u_5	0	0	1	0

↑ user ↓

↑ user ↓

	i_1	i_2	i_3	i_4
u_1	?	+	+	?
u_2	+	?	?	+
u_3	+	+	?	?
u_4	?	?	+	+
u_5	?	?	+	?

↑ user ↓

↑ user ↓

$$(u, i, j) \in D_S$$

$u_1: i >_{u_1} j$				
j_1	i_1	i_2	i_3	i_4
-	+	+	?	
-		?	-	
?		-	-	
?	+	+		-

...

$u_5: i >_{u_5} j$				
j_1	i_1	i_2	i_3	i_4
?	?	+	?	
?		+	?	
-	-		-	
?	?	+		-

BAYESIAN OPT

The Bayesian formulation of finding the correct personalized ranking for all items $i \in I$ is to maximize the following posterior probability where Θ represents the parameter vector of an arbitrary model class (e.g. matrix factorization).

$$p(\Theta | >_u) \propto p(>_u | \Theta) p(\Theta)$$

$>_u$ is the desired but latent preference structure for user u
 $p(>_u | \Theta)$ is a user specific likelihood function

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All users are presumed to act independently of each other. We also assume the ordering of each pair of items (i, j) for a specific user is independent of the ordering of every other pair, we can formulate the individual probability that a user prefers item i to item j as follows

$$p(i >_u j | \Theta) := \sigma(\hat{x}_{uij}(\Theta))$$

where σ is the logistic sigmoid:

$$\sigma(x) := \frac{1}{1 + e^{-x}}$$

$$p(\Theta) \sim N(0, \Sigma_\Theta)$$

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$$\text{BPR-Opt} := \ln p(\Theta | >_u)$$

$$= \sum_{(u,i,j) \in D_S} \ln \sigma(\hat{x}_{uij}) - \lambda_\Theta \|\Theta\|^2$$

where λ_Θ are model specific regularization parameters.

$$p(\Theta) \sim N(0, \Sigma_\Theta)$$

ANALOGIES TO AUC OPTIMIZATION

$$\text{BPR-OPT} := \sum_{(u,i,j) \in D_S} \ln \sigma(\hat{x}_{uij}) - \lambda_\Theta \|\Theta\|^2$$

$$\text{AUC}(u) = \sum_{(u,i,j) \in D_S} z_u \delta(\hat{x}_{uij} > 0)$$

The analogy between BPR-Opt and (1) is obvious. Besides the normalizing constant z_u they only differ in the loss function. The AUC uses the non-differentiable loss $\delta(x > 0)$ which is identical to the Heaviside function:

$$\delta(x > 0) = H(x) := \begin{cases} 1, & x > 0 \\ 0, & \text{else} \end{cases}$$

Optimizing for BPR-OPT criterion will be similar to optimizing for AUC which is a rank based metric as we can see from the above equation.

STOCHASTIC GRADIENT DESCENT USING BOOTSTRAPPING

$$\frac{\partial \text{BPR-OPT}}{\partial \Theta} = \sum_{(u,i,j) \in D_S} \frac{\partial}{\partial \Theta} \ln \sigma(\hat{x}_{u i j}) - \lambda_\Theta \frac{\partial}{\partial \Theta} \|\Theta\|^2$$

$$\propto \sum_{(u,i,j) \in D_S} \frac{-e^{-\hat{x}_{u i j}}}{1 + e^{-\hat{x}_{u i j}}} \cdot \frac{\partial}{\partial \Theta} \hat{x}_{u i j} - \lambda_\Theta \Theta$$

$$\Theta \leftarrow \Theta + \alpha \left(\frac{e^{-\hat{x}_{u i j}}}{1 + e^{-\hat{x}_{u i j}}} \cdot \frac{\partial}{\partial \Theta} \hat{x}_{u i j} + \lambda_\Theta \Theta \right)$$

STOCHASTIC GRADIENT DESCENT USING BOOTSTRAPPING

$$\begin{aligned}\frac{\partial \text{BPR-OPT}}{\partial \Theta} &= \sum_{(u,i,j) \in D_S} \frac{\partial}{\partial \Theta} \ln \sigma(\hat{x}_{u i j}) - \lambda_\Theta \frac{\partial}{\partial \Theta} \|\Theta\|^2 \\ &\propto \sum_{(u,i,j) \in D_S} \frac{-e^{-\hat{x}_{u i j}}}{1 + e^{-\hat{x}_{u i j}}} \cdot \frac{\partial}{\partial \Theta} \hat{x}_{u i j} - \lambda_\Theta \Theta \\ \Theta &\leftarrow \Theta + \alpha \left(\frac{e^{-\hat{x}_{u i j}}}{1 + e^{-\hat{x}_{u i j}}} \cdot \frac{\partial}{\partial \Theta} \hat{x}_{u i j} + \lambda_\Theta \Theta \right)\end{aligned}$$

```
1: procedure LEARNBPR( $D_S, \Theta$ )
2:   initialize  $\Theta$ 
3:   repeat
4:     draw  $(u, i, j)$  from  $D_S$ 
5:      $\Theta \leftarrow \Theta + \alpha \left( \frac{e^{-\hat{x}_{u i j}}}{1 + e^{-\hat{x}_{u i j}}} \cdot \frac{\partial}{\partial \Theta} \hat{x}_{u i j} + \lambda_\Theta \cdot \Theta \right)$ 
6:   until convergence
7:   return  $\hat{\Theta}$ 
8: end procedure
```

LEARNING MODELS WITH BPR

Matrix Factorization and learned k-nearest-neighbor both try to model the hidden preferences of a user on an item but Matrix factorization shows better result.

$$\hat{x}_{uij} := \hat{x}_{ui} - \hat{x}_{uj}$$

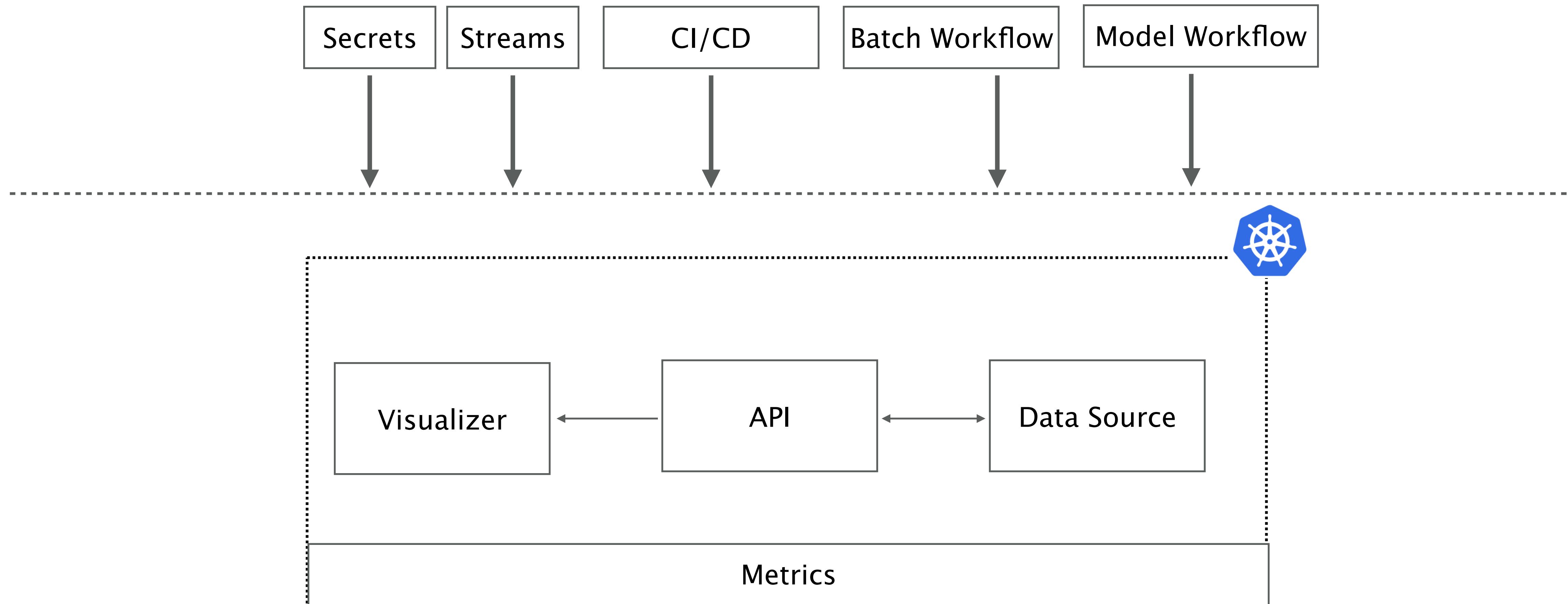
PAIN POINTS

End-to-end orchestration of idea to production

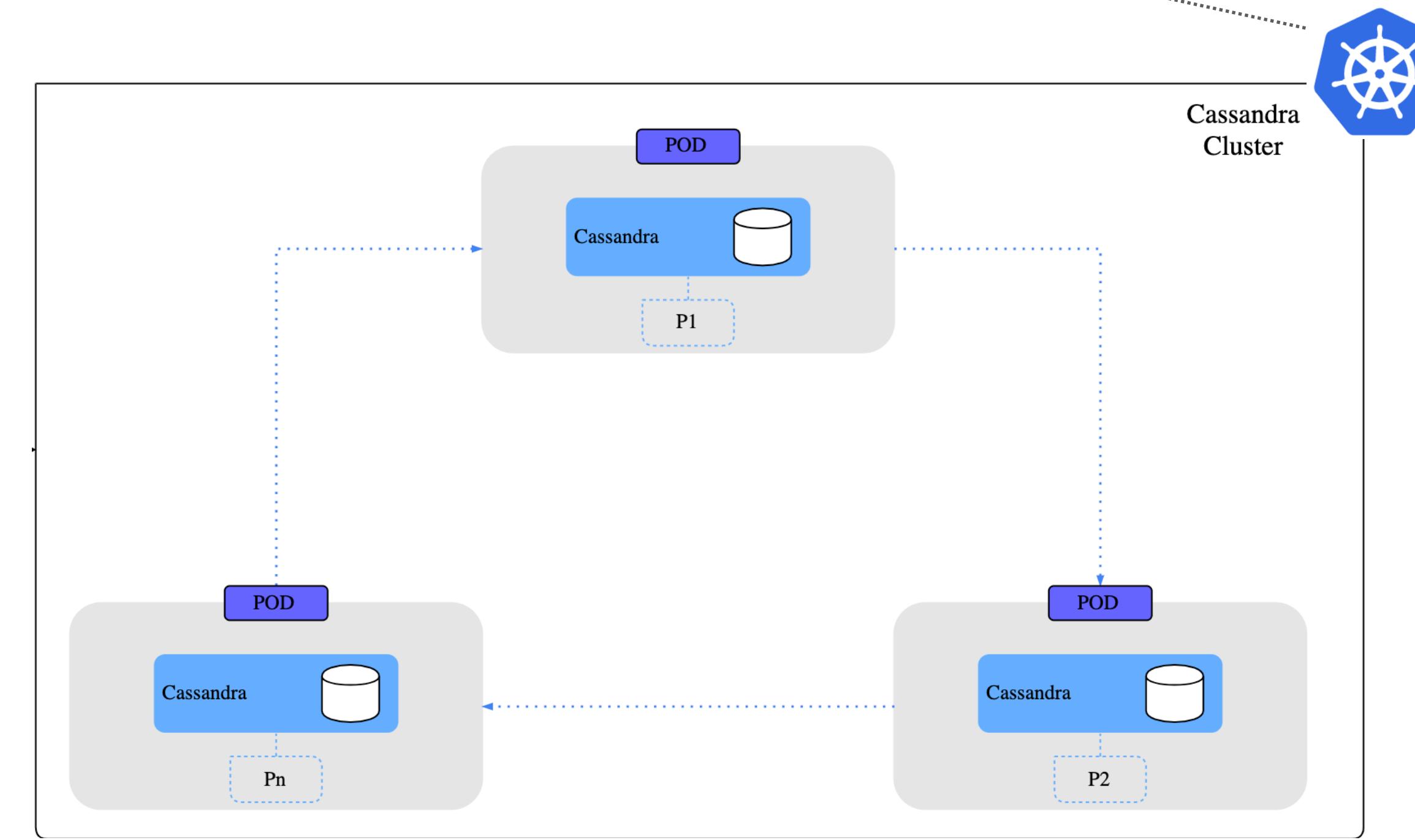
- Easier experimentation
- Scaling backend computation
- Serving precomputed data
- Serving model in real-time

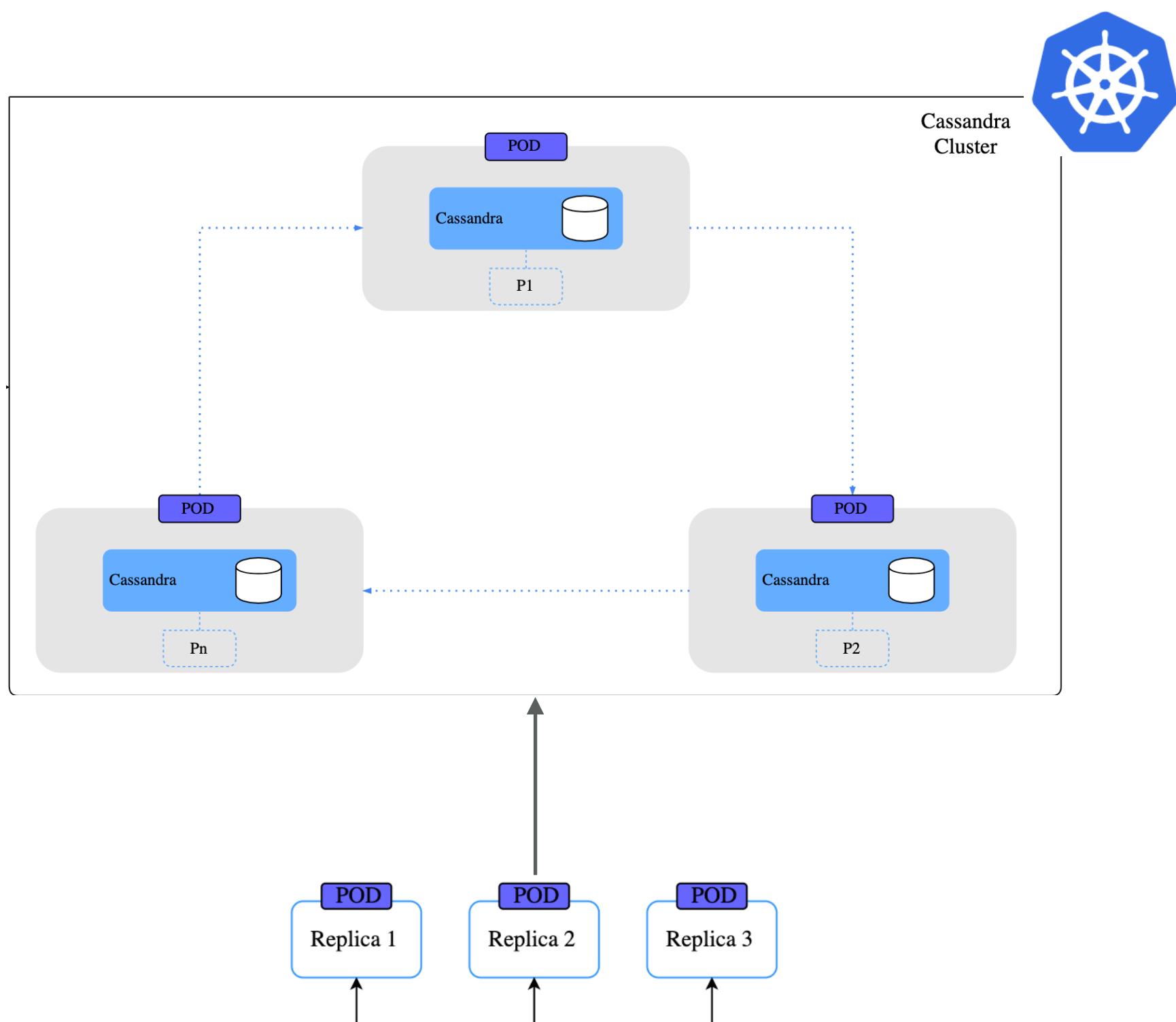
STARFISH

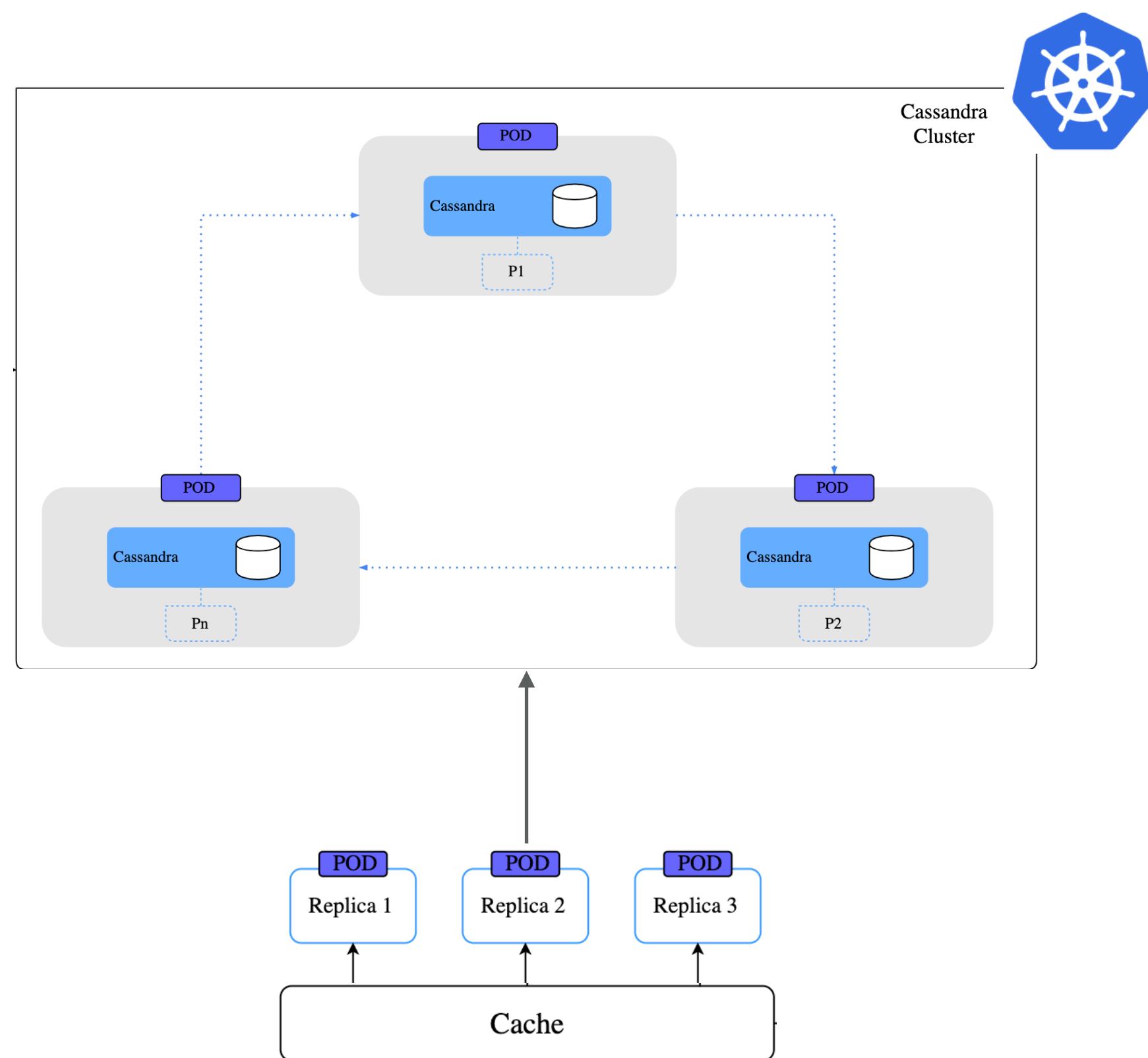
- Platform of Data Science services
- Supports:
 - Precomputed big data
 - Support realtime models
 - A/B

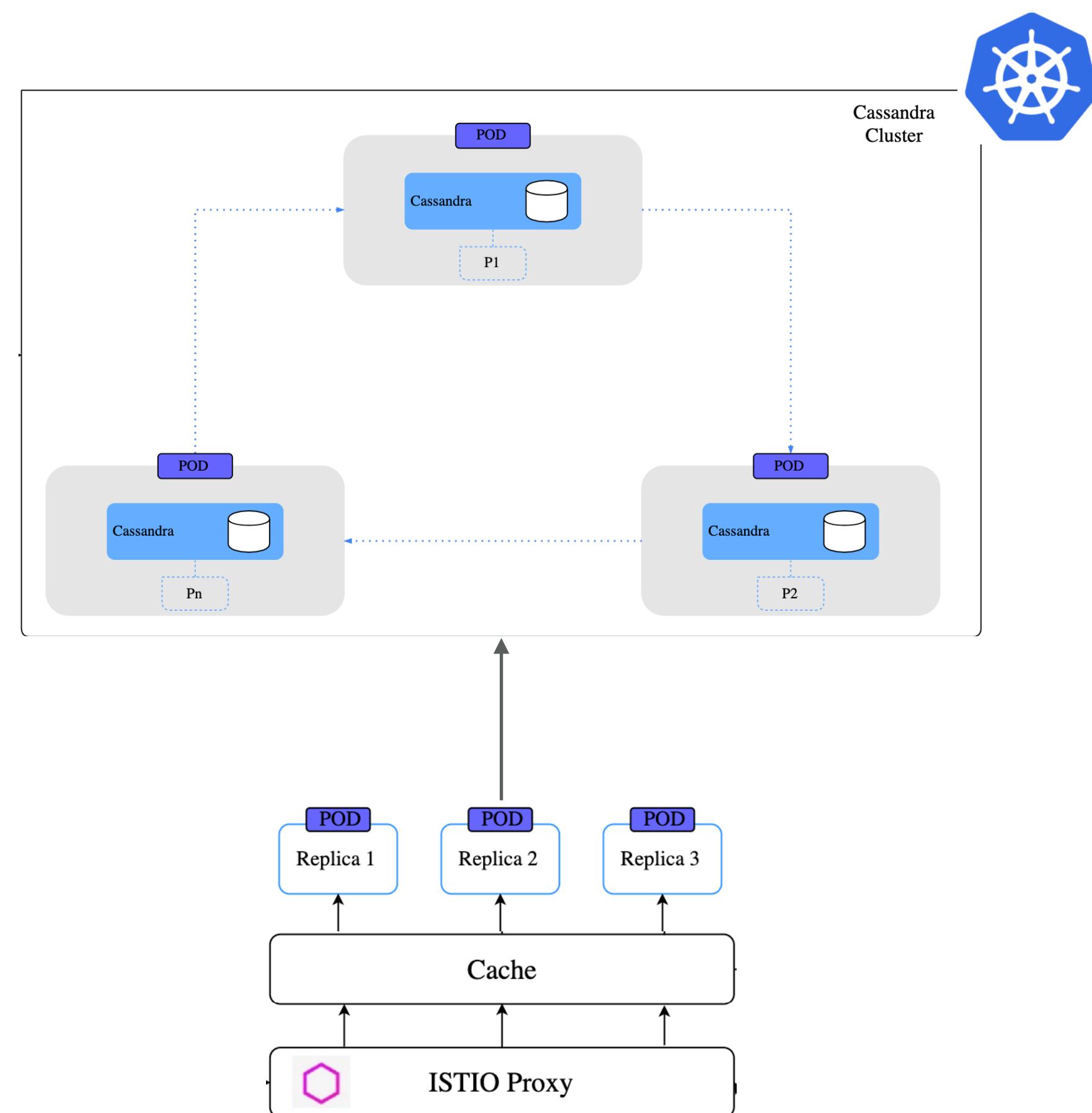


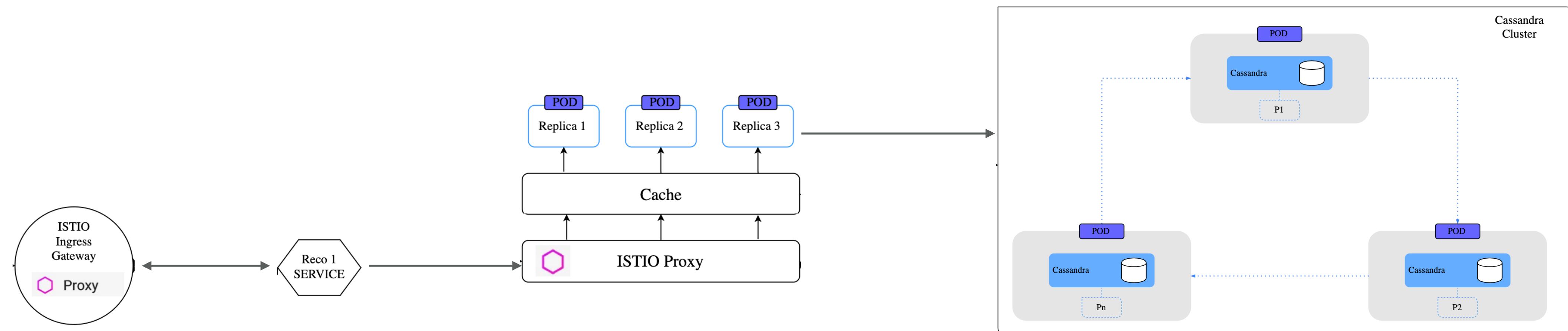
Data Source

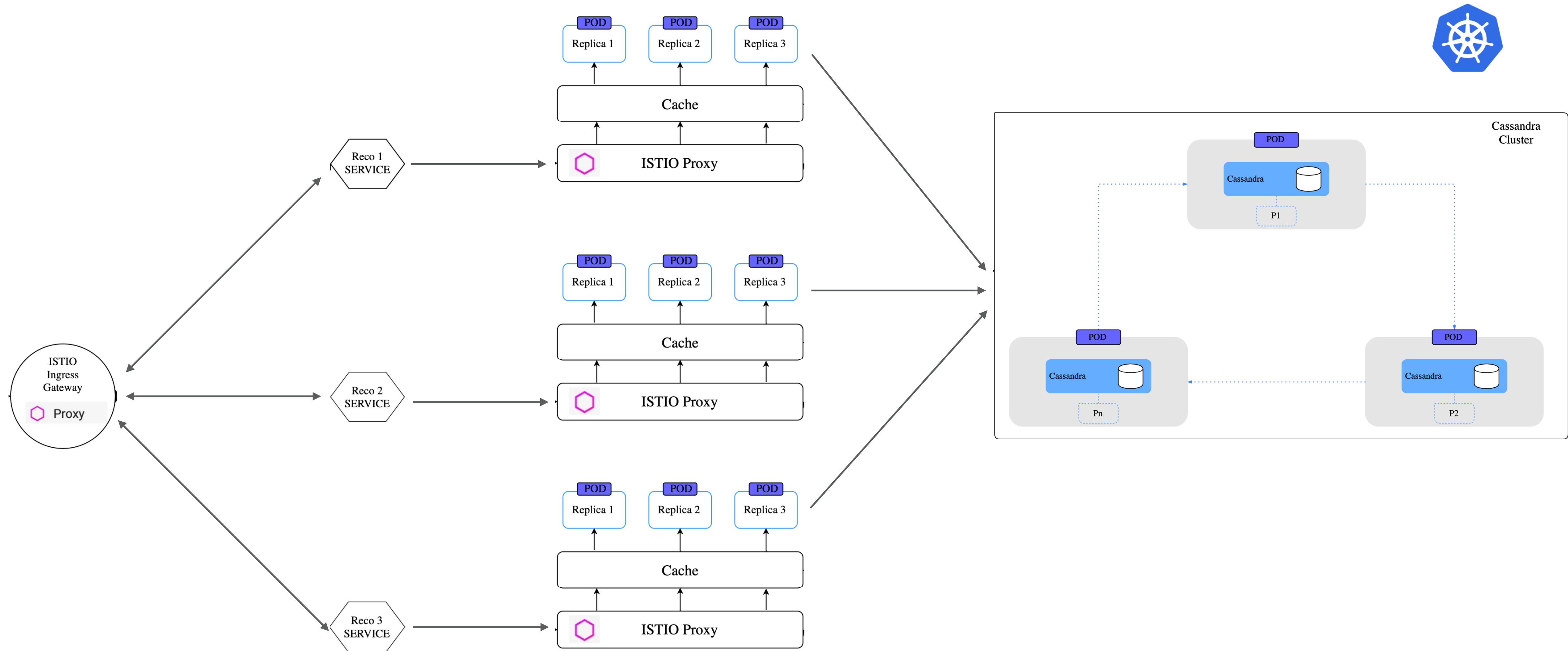


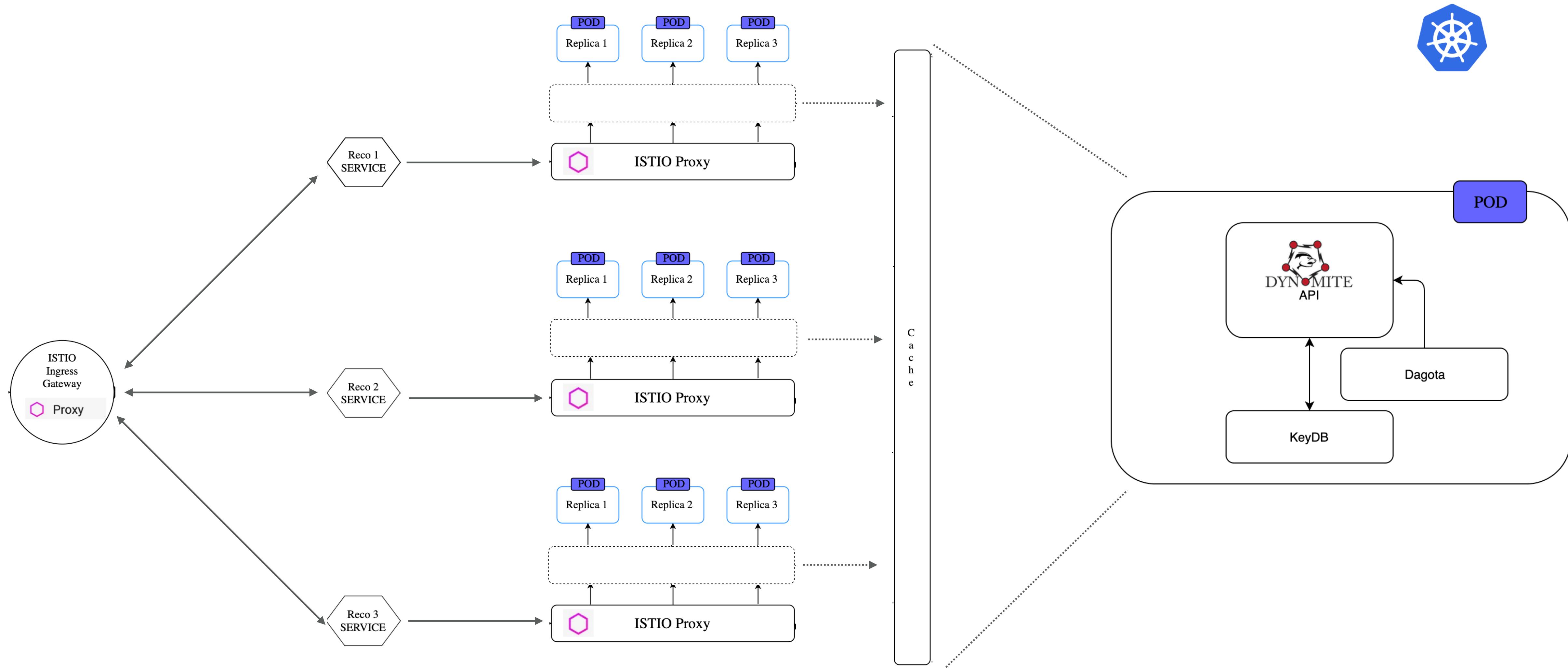


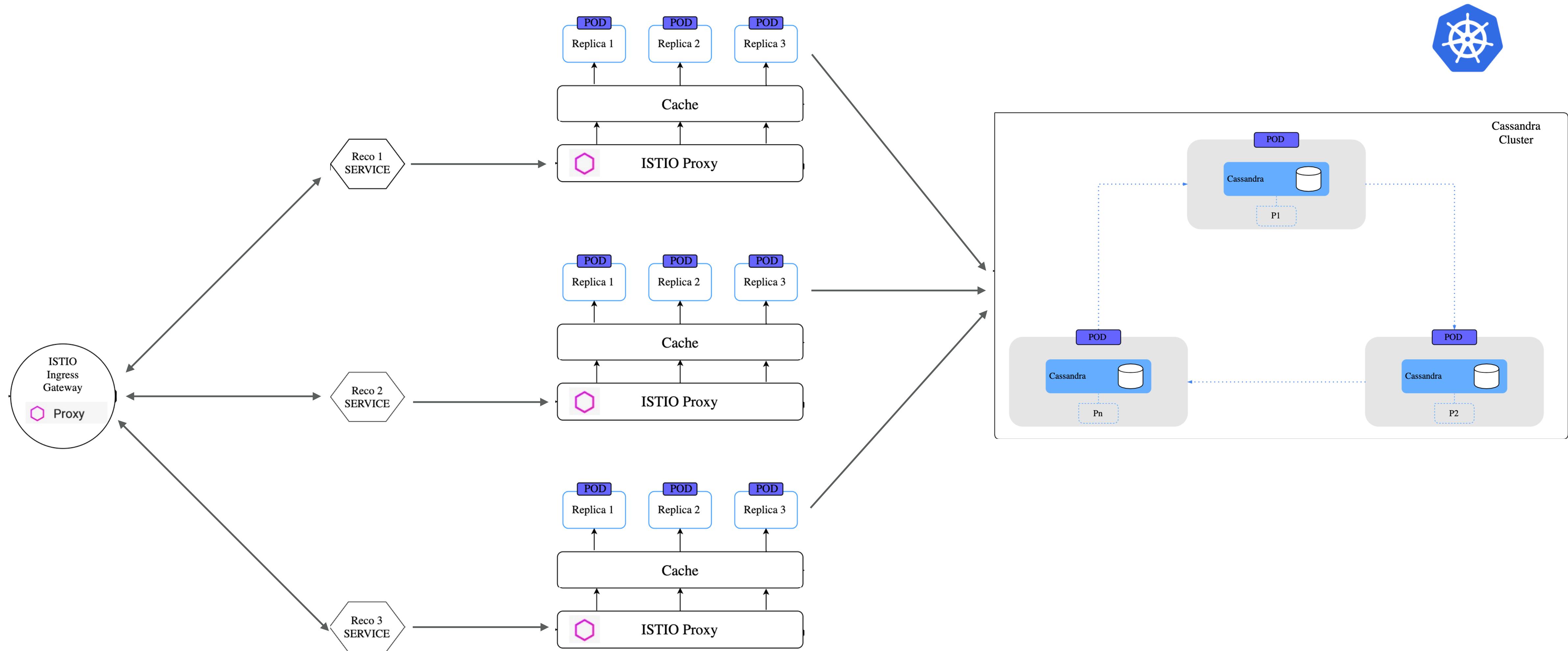


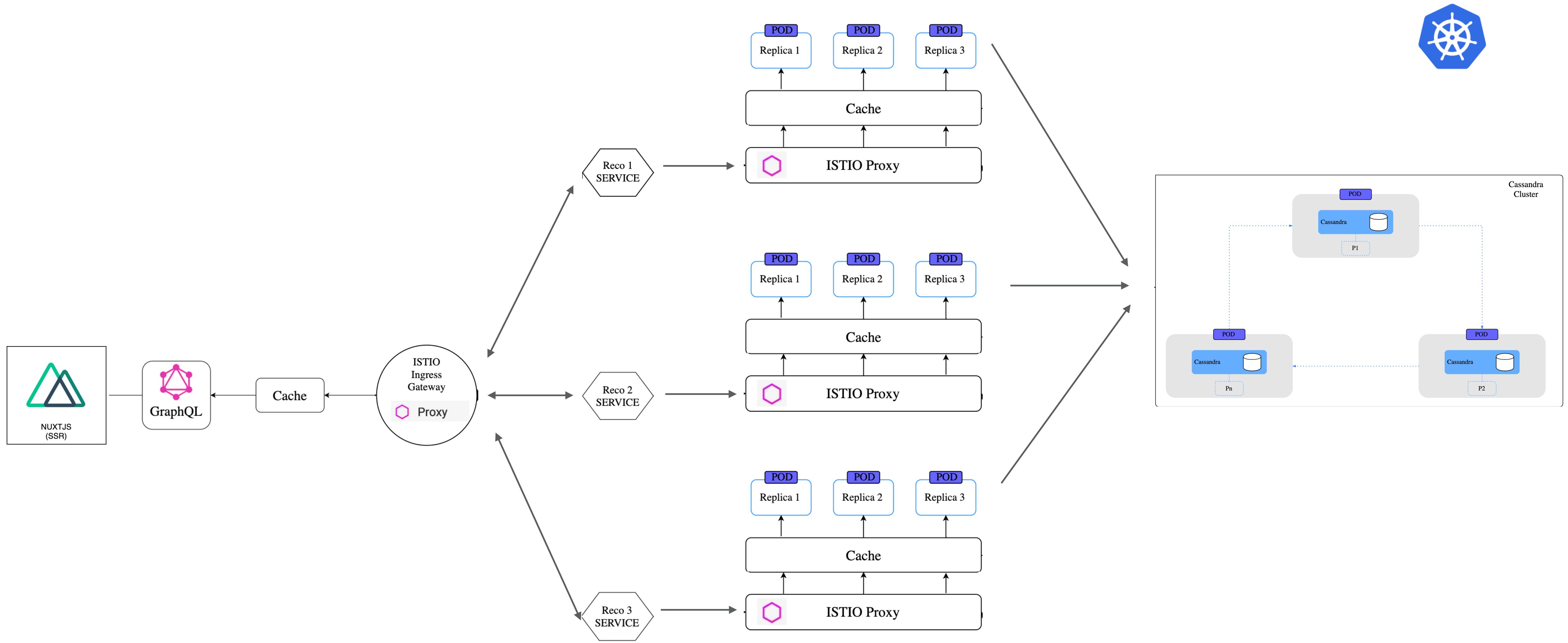


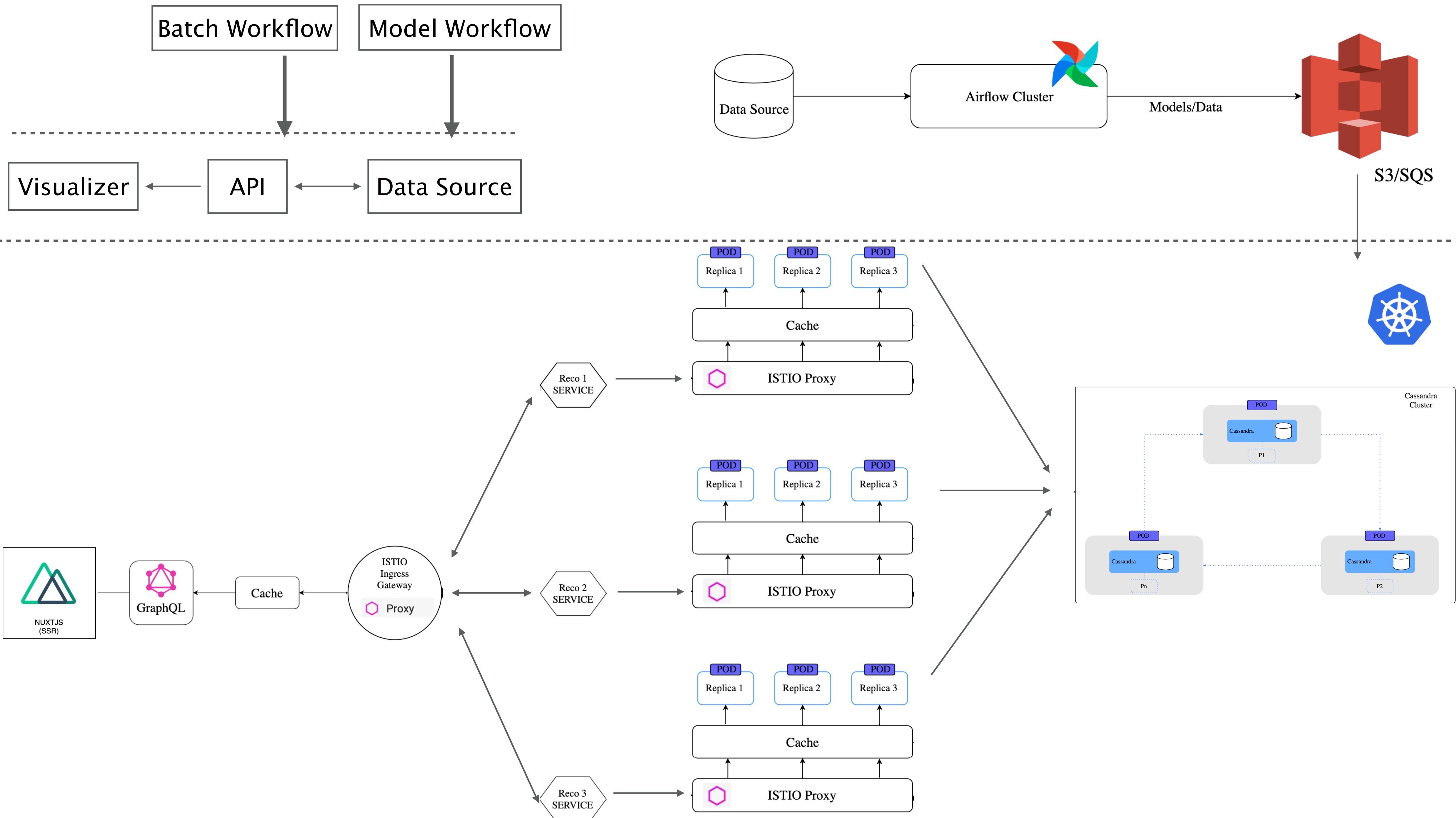






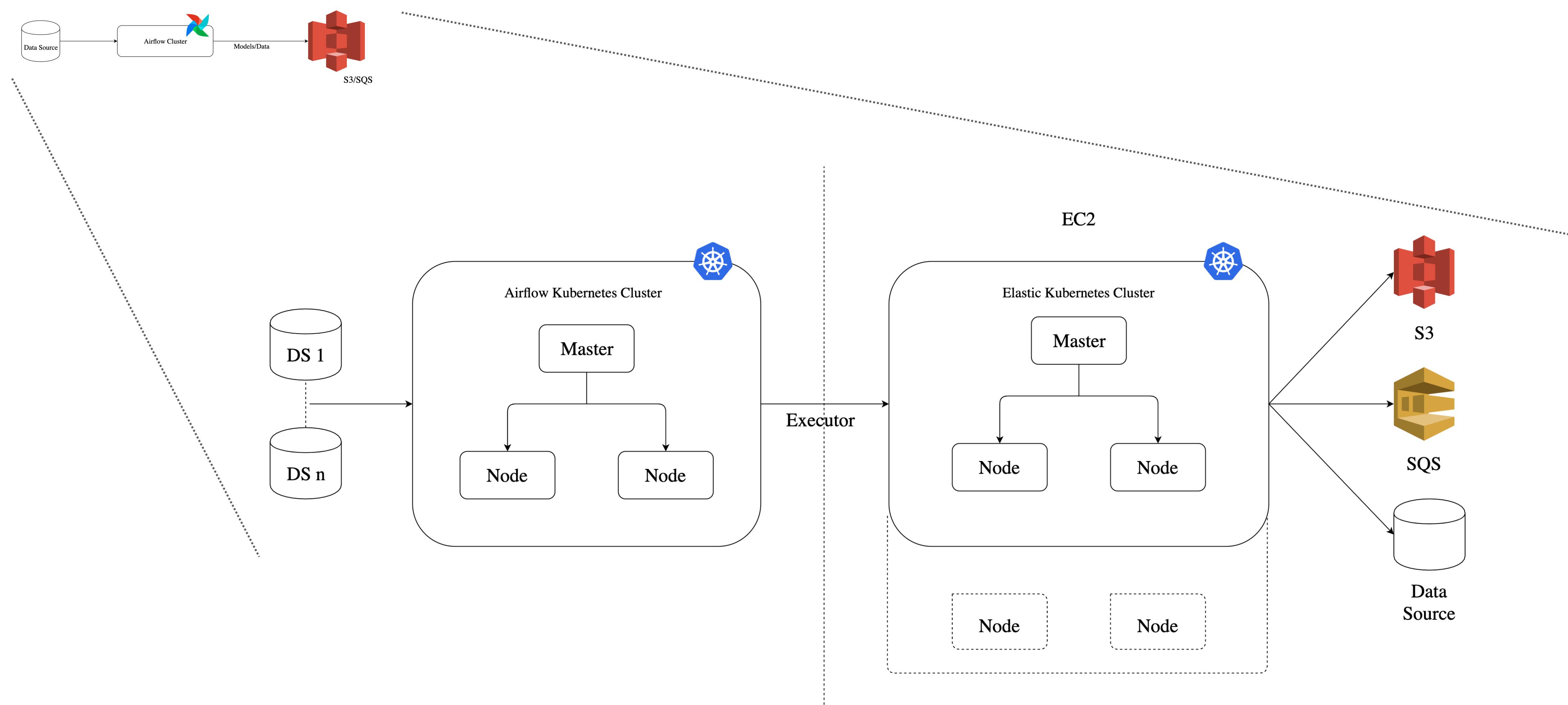


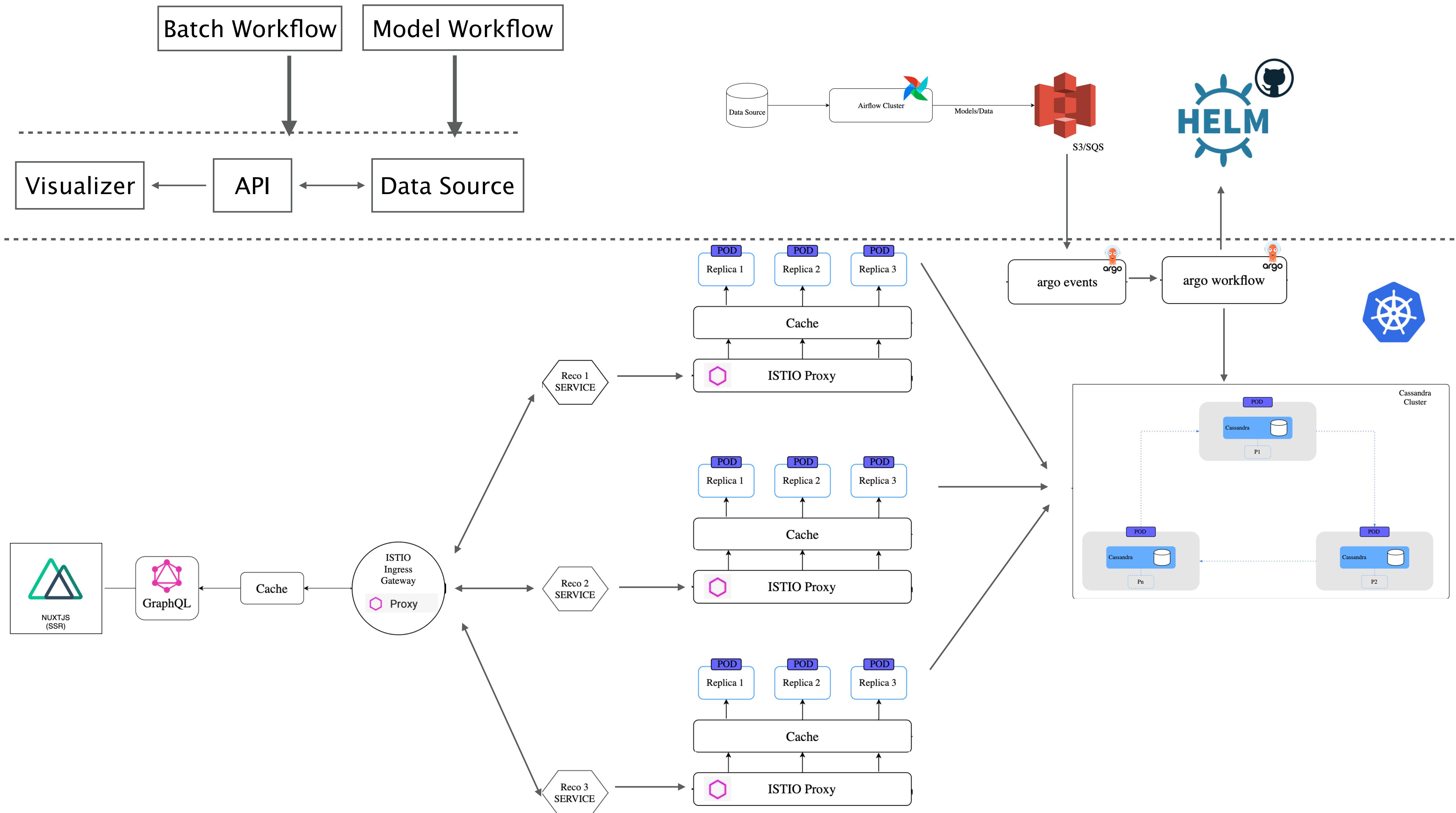


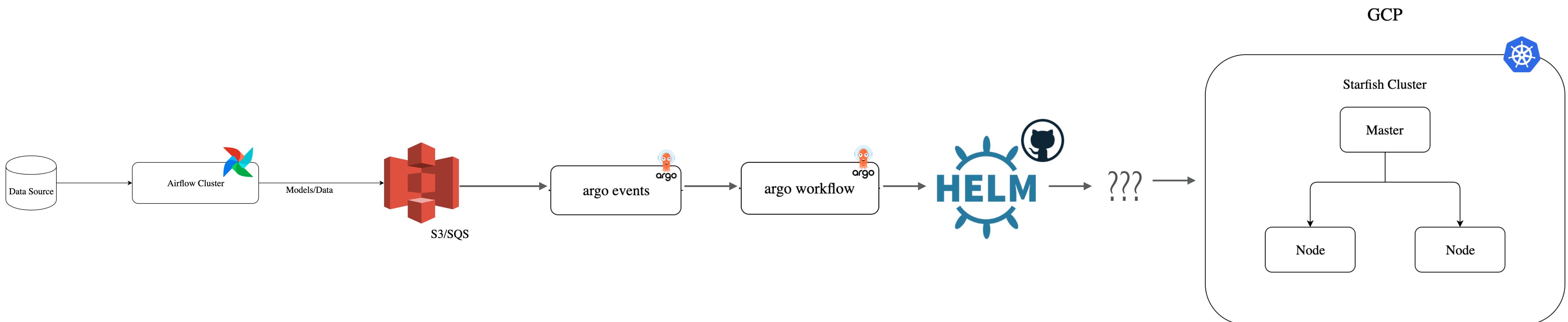
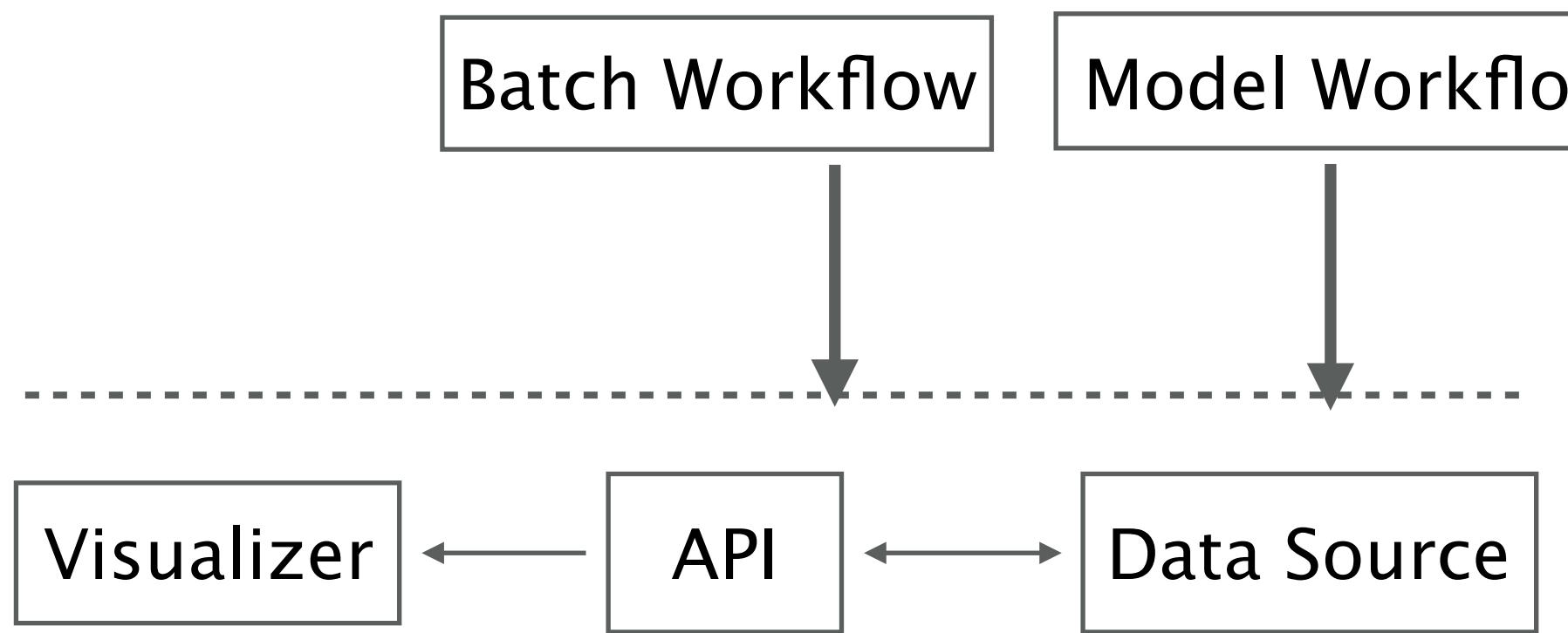


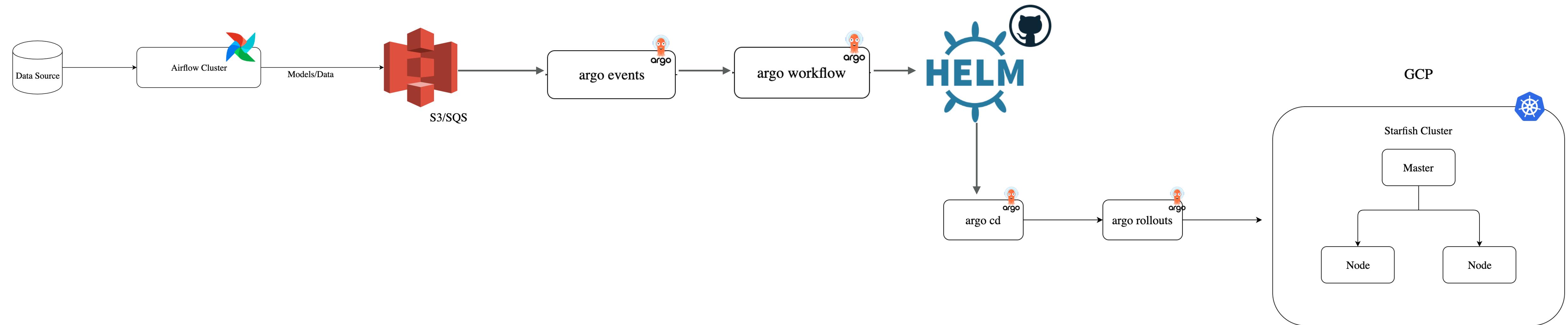
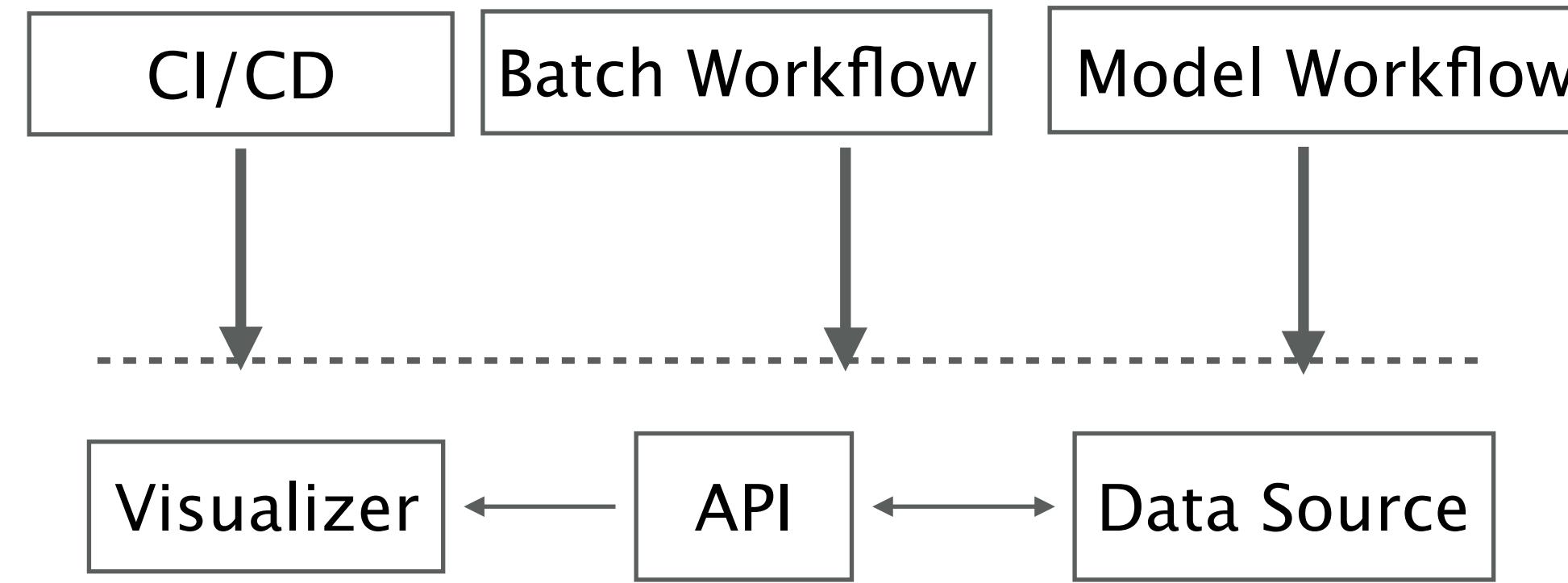
Batch Workflow

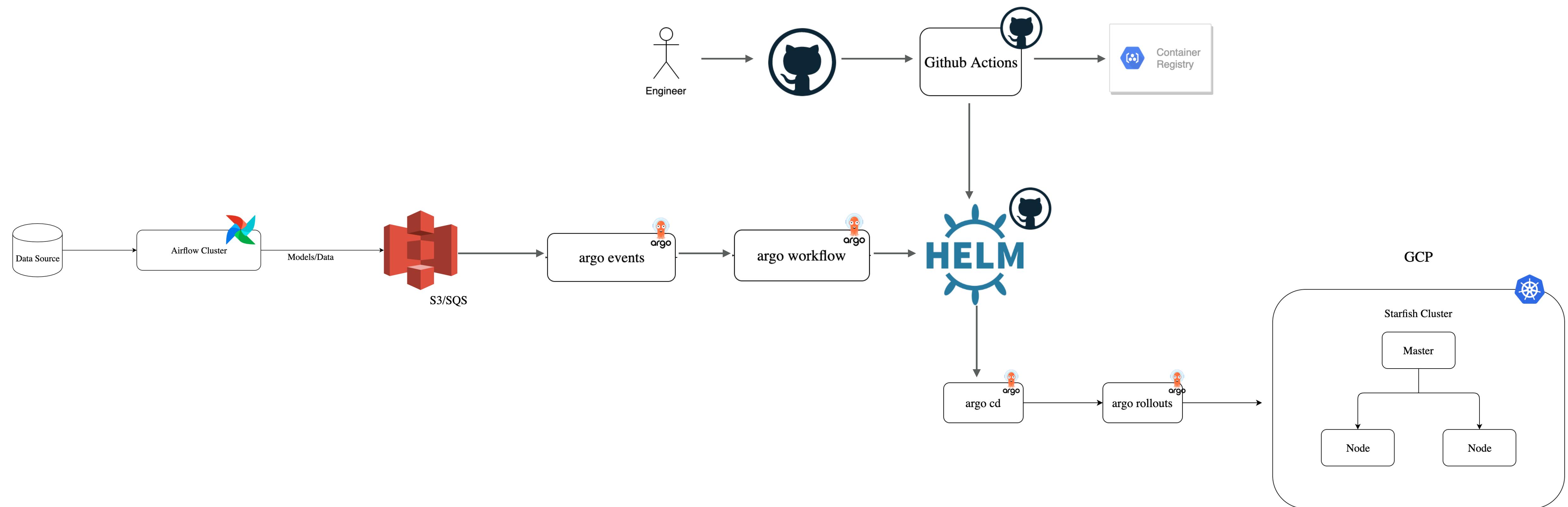
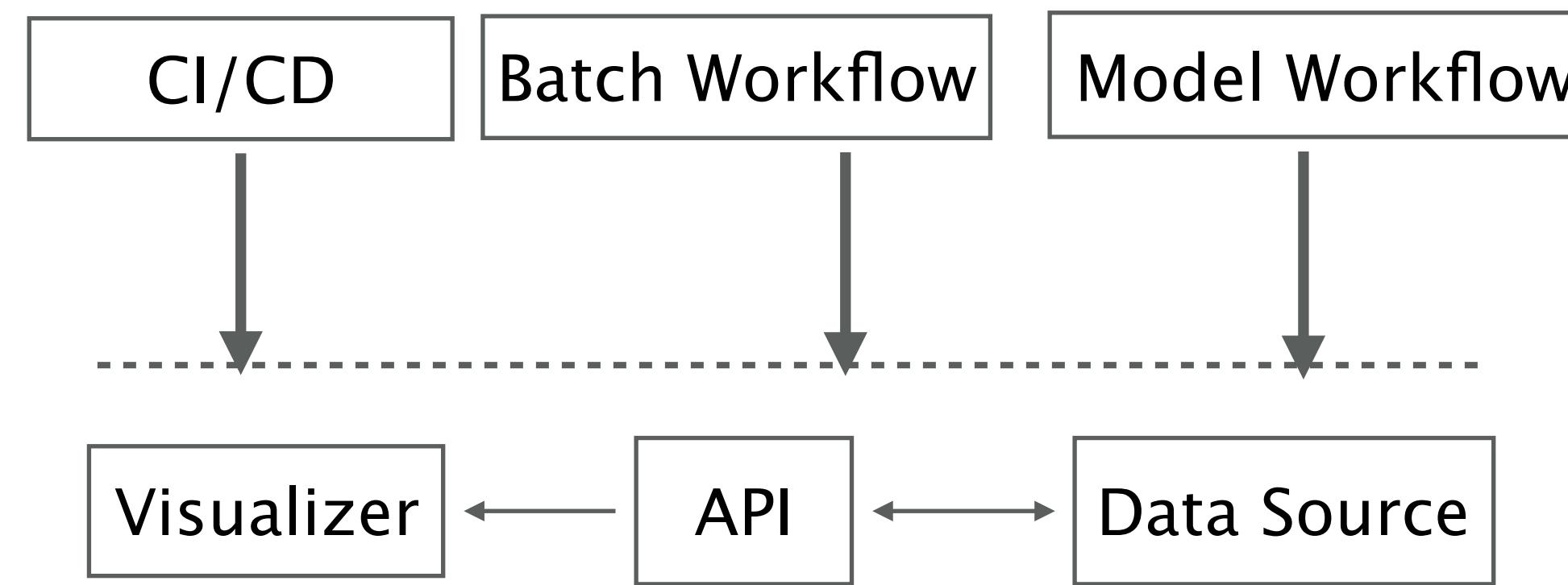
Model Workflow

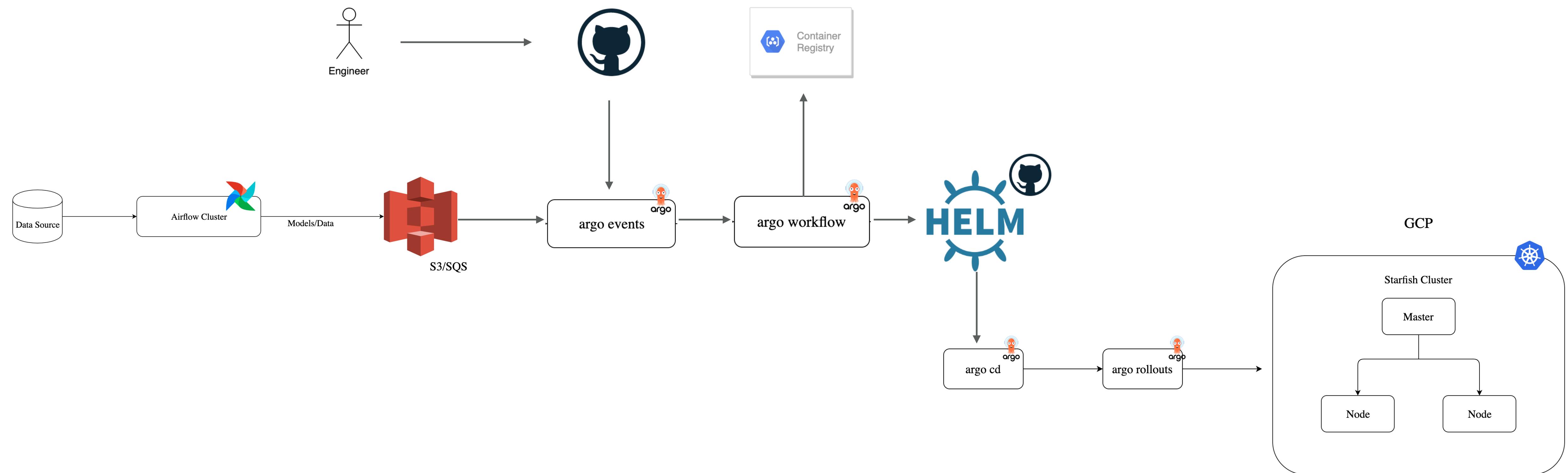
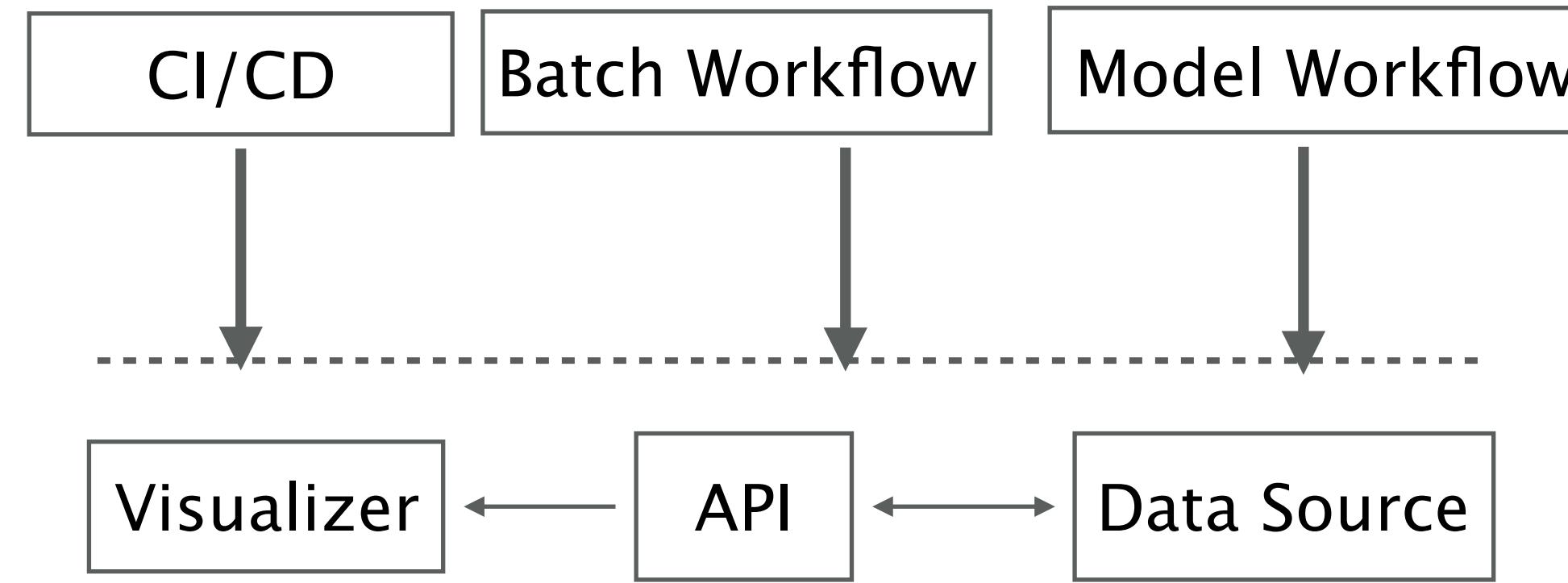


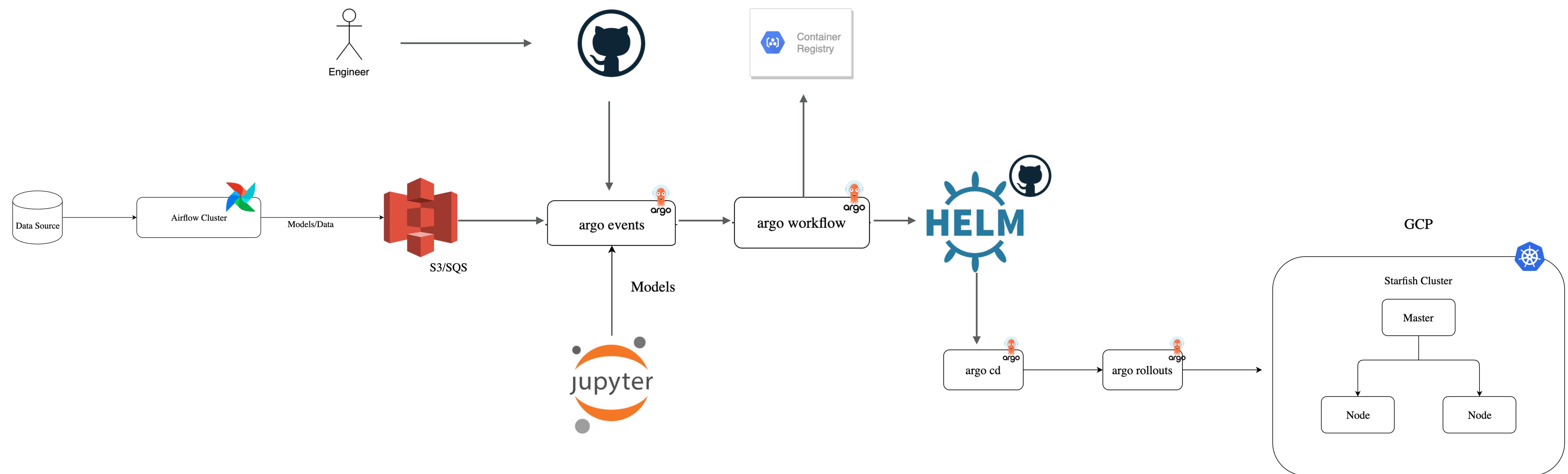
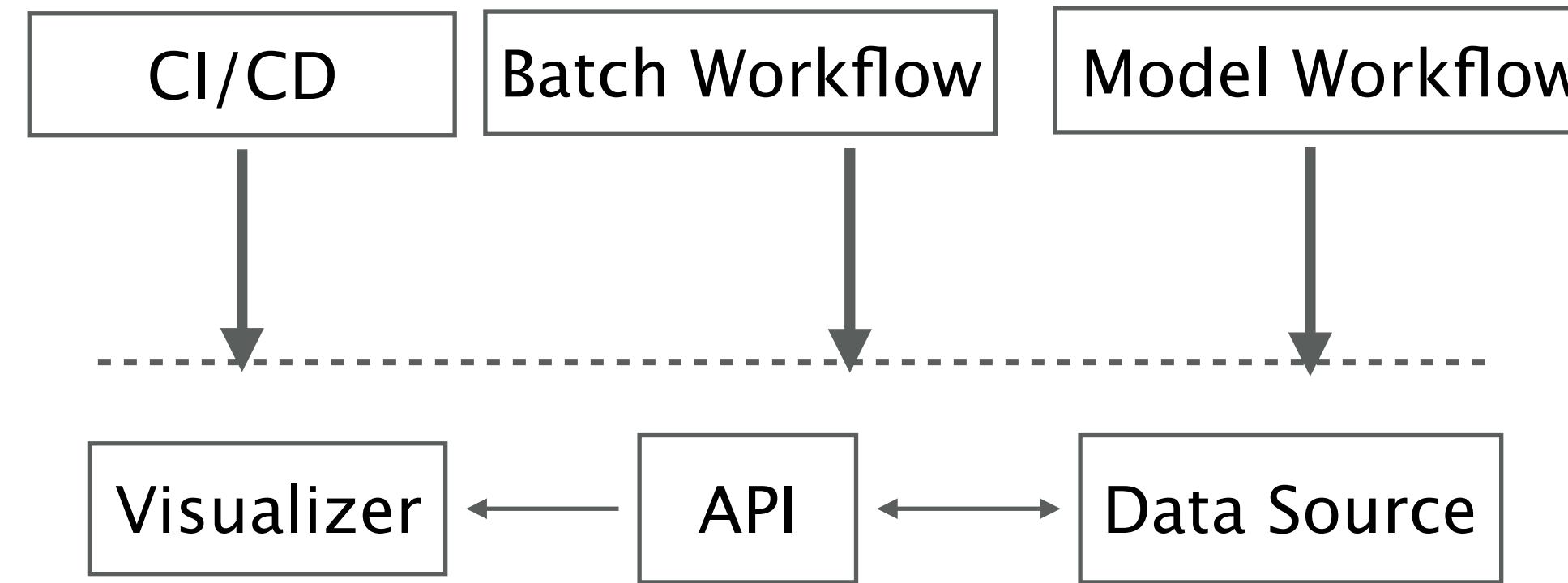


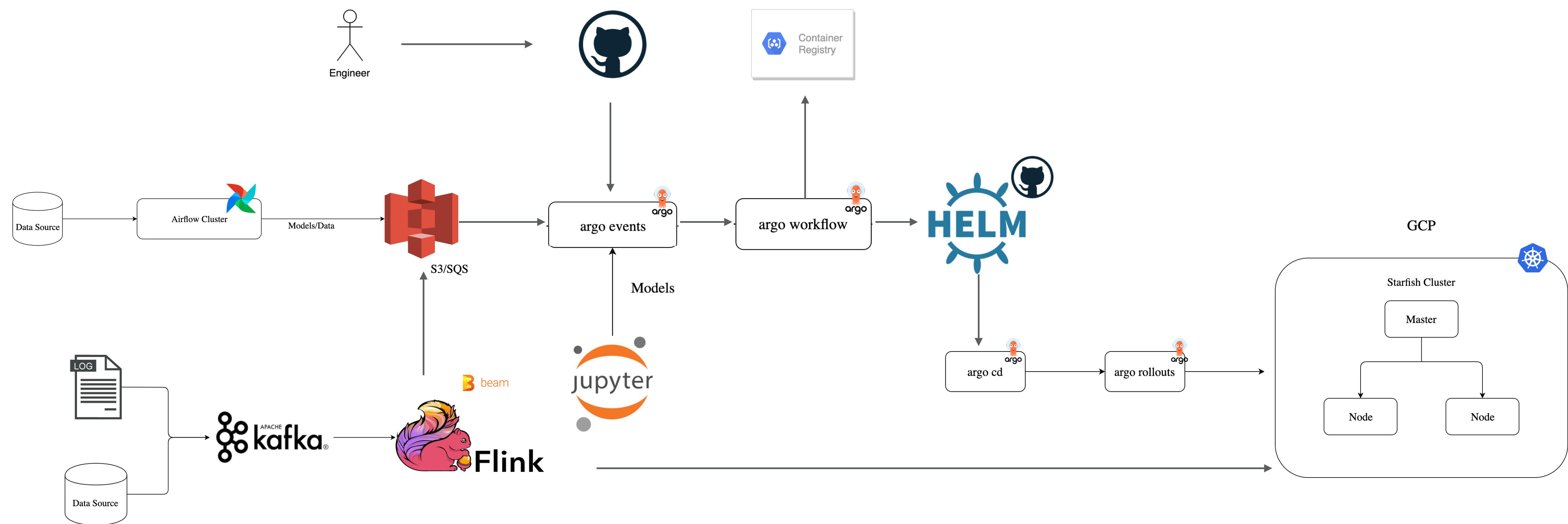












Thank You