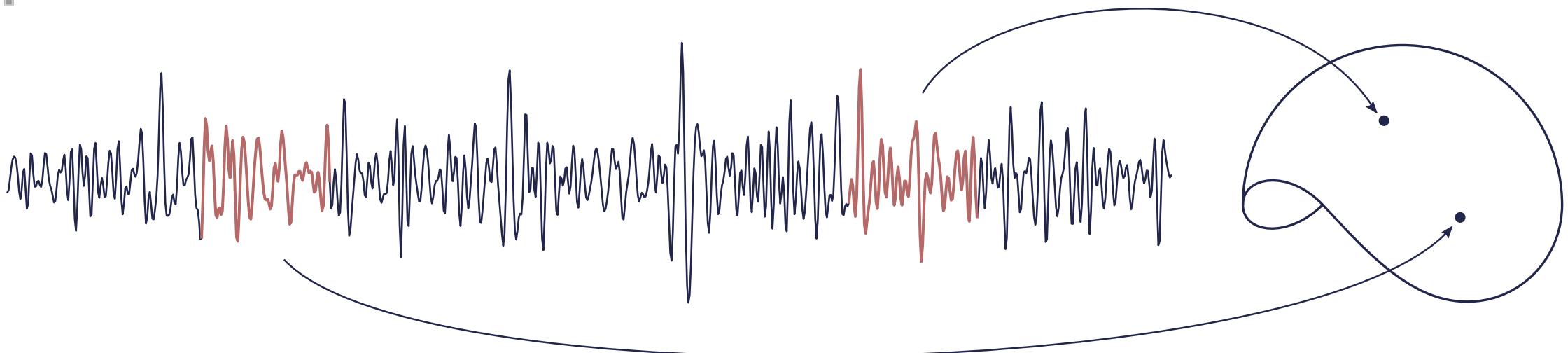


# Riemannian Procrustes Analysis

## Transfer Learning for Brain Computer Interfaces



Pedro L. C. Rodrigues Marco Congedo Christian Jutten



*Presentation for the Machine Learning group at GIPSA-lab*  
22th May 2018, Grenoble, France

# Outline

Introduction

Procrustes Analysis

Results

Concluding remarks

# Outline

Introduction

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Procrustes Analysis

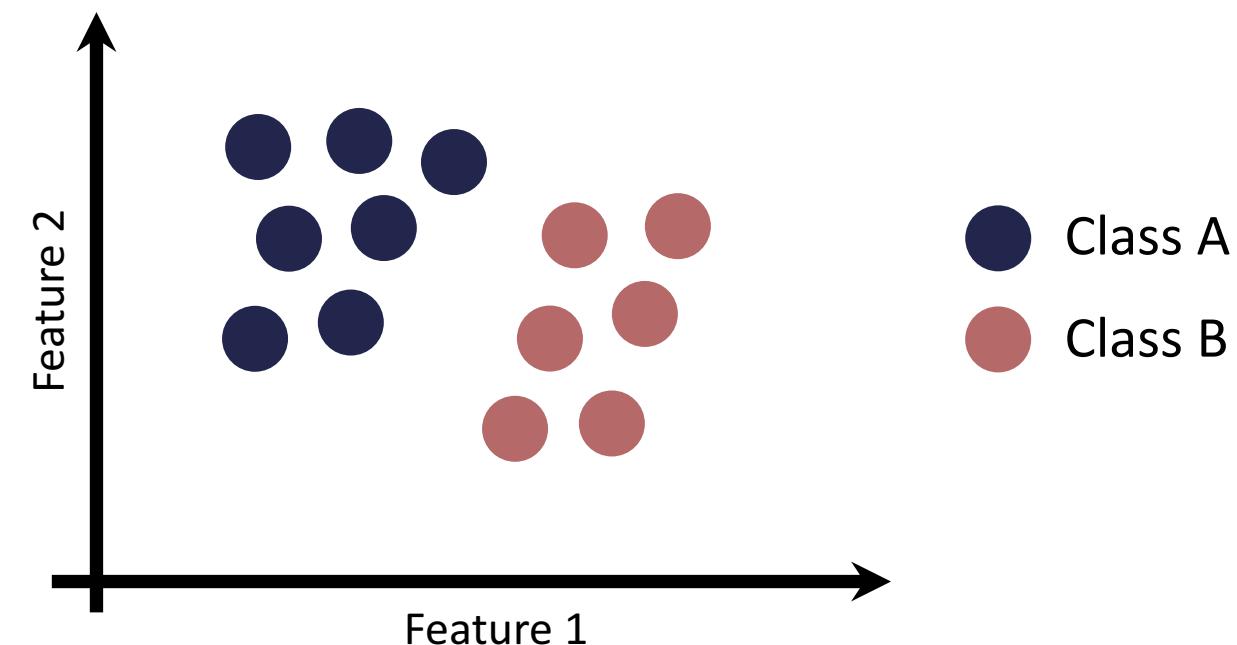
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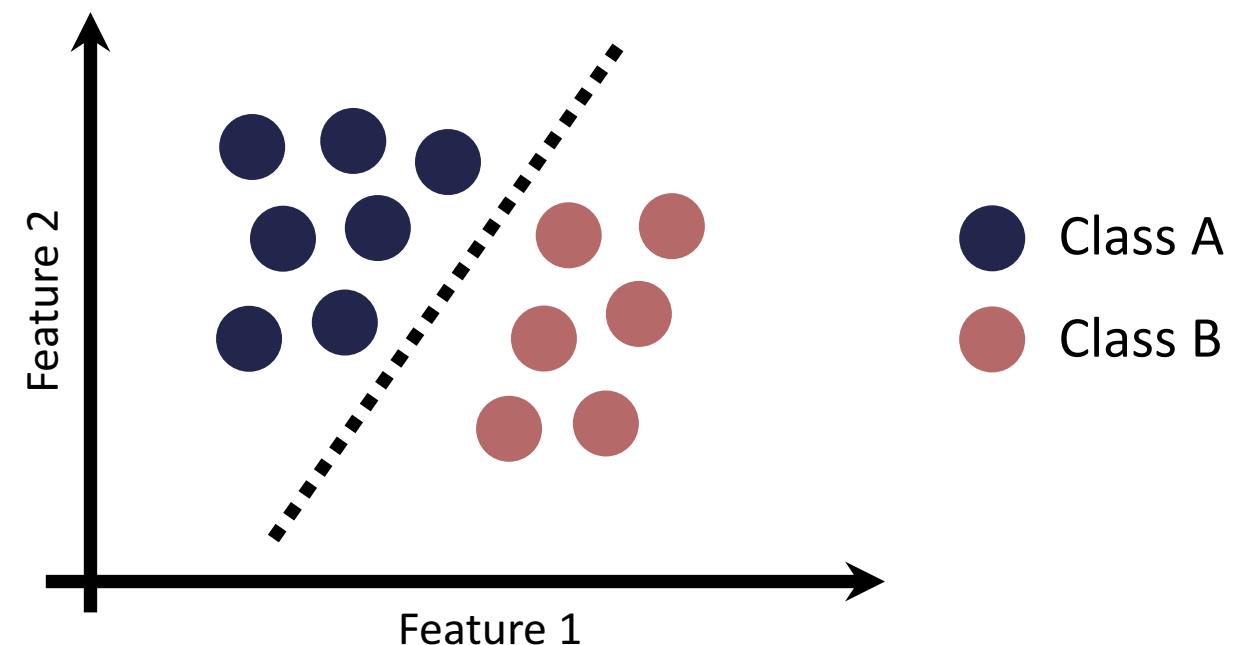
Classification of BCI signals always relies on an appropriate choice of **discriminant features**



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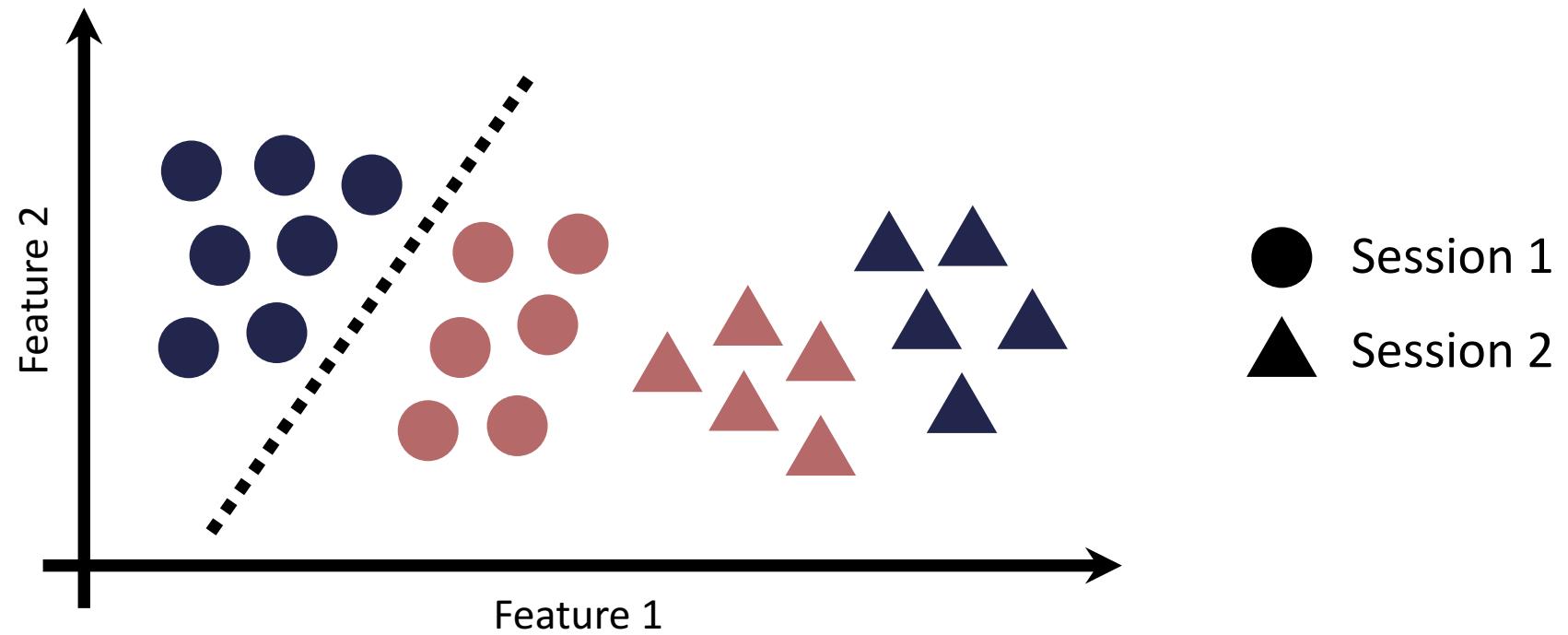


Classification of BCI signals always relies on an appropriate choice of **discriminant features**



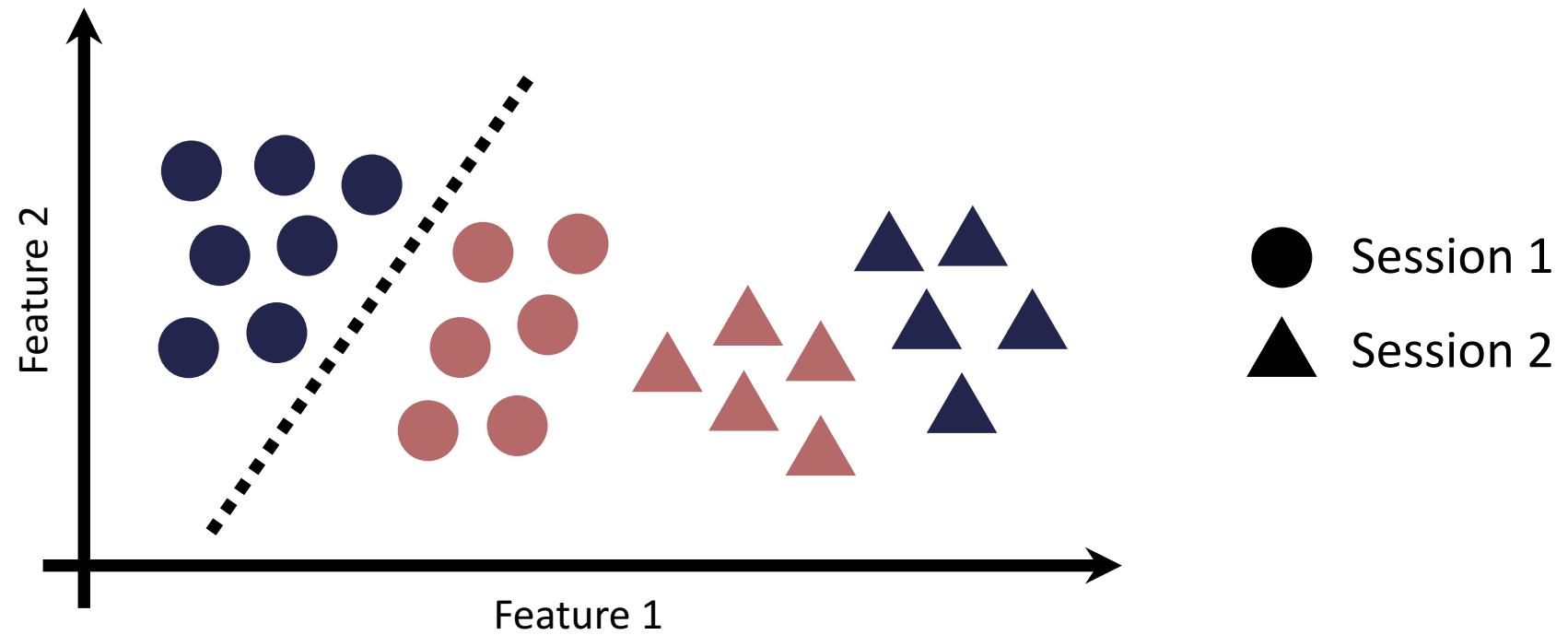
The **statistical distribution** of features may not be the same on different sessions

Covariate Shift



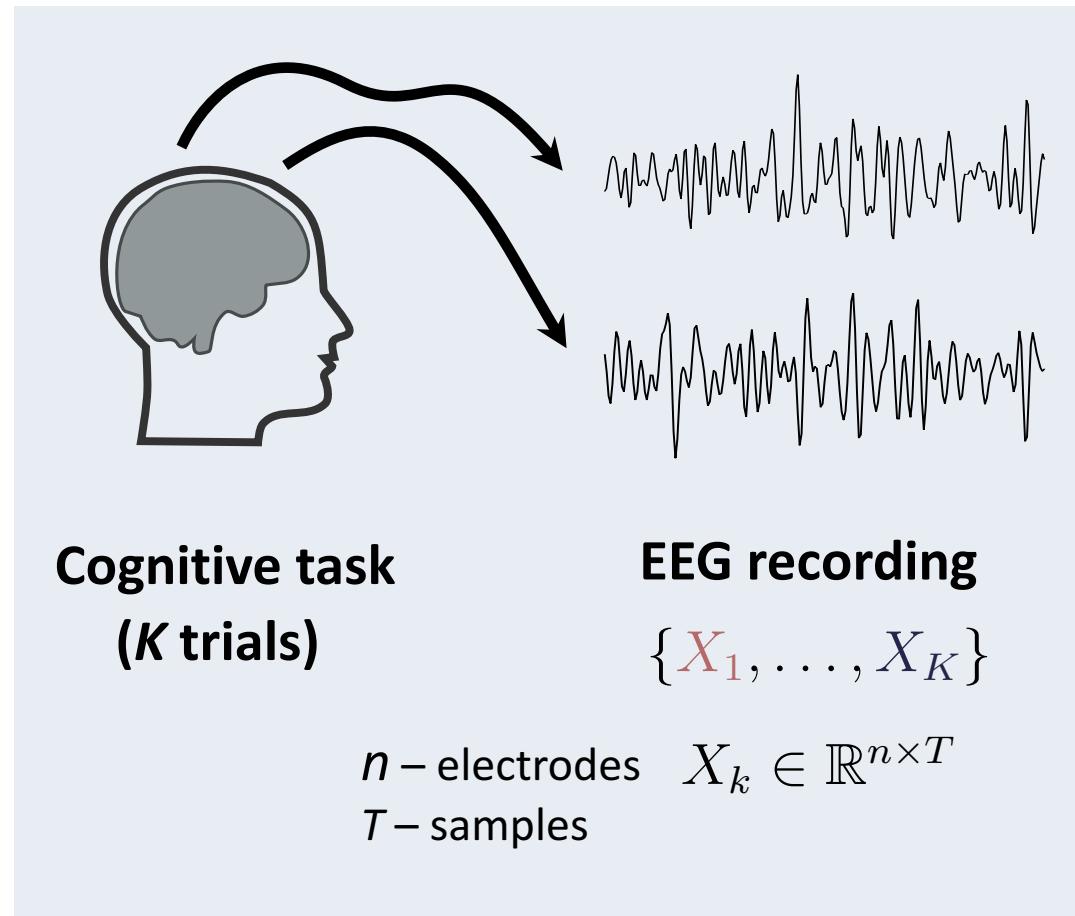
The **statistical distribution** of features may not be the same on different sessions

Covariate Shift



Transfer Learning aims at using the data from Session 1 to improve the classification of Session 2

## The BCI paradigm – classification of EEG epochs

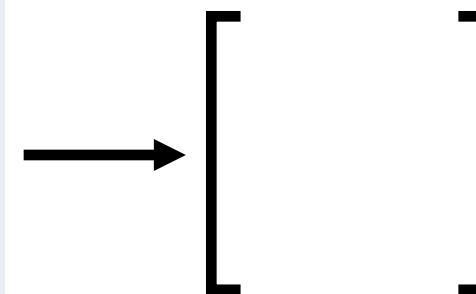
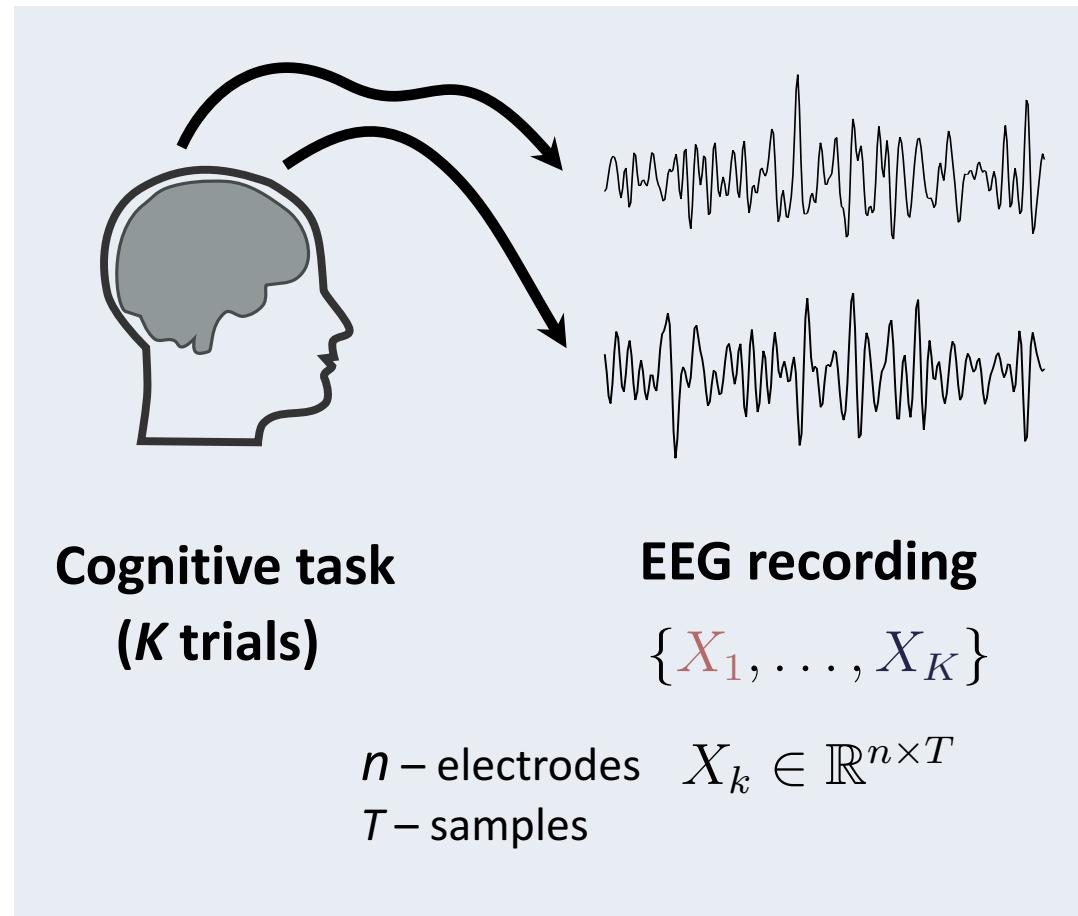


### FEATURE ENGINEERING

Many features can be used to **describe** and **discriminate** the signals of each class

- Waveforms
- Spectra
- Neural connectivity
- Etc.

## The BCI paradigm – classification of EEG epochs



Describes the instantaneous **correlations** between pairs of recorded signals

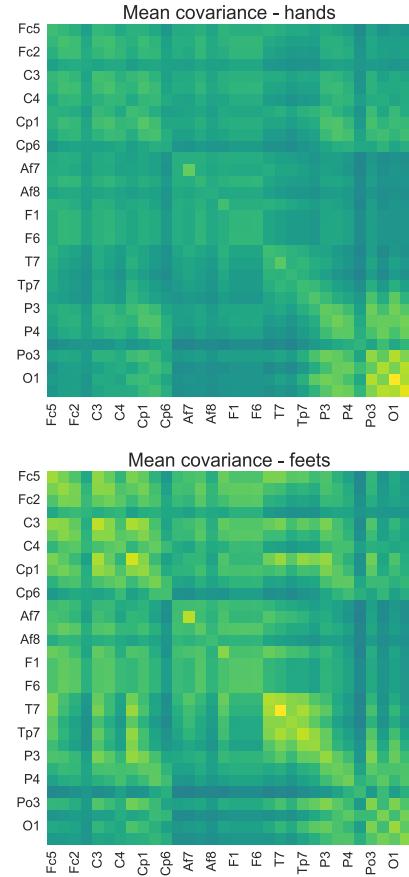
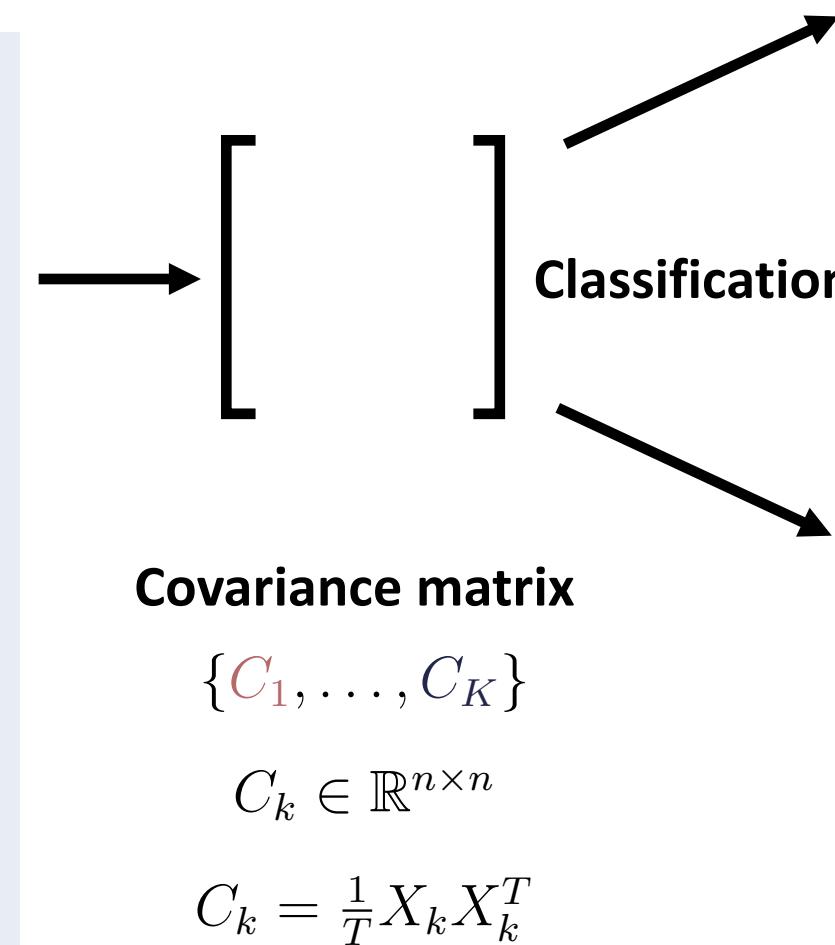
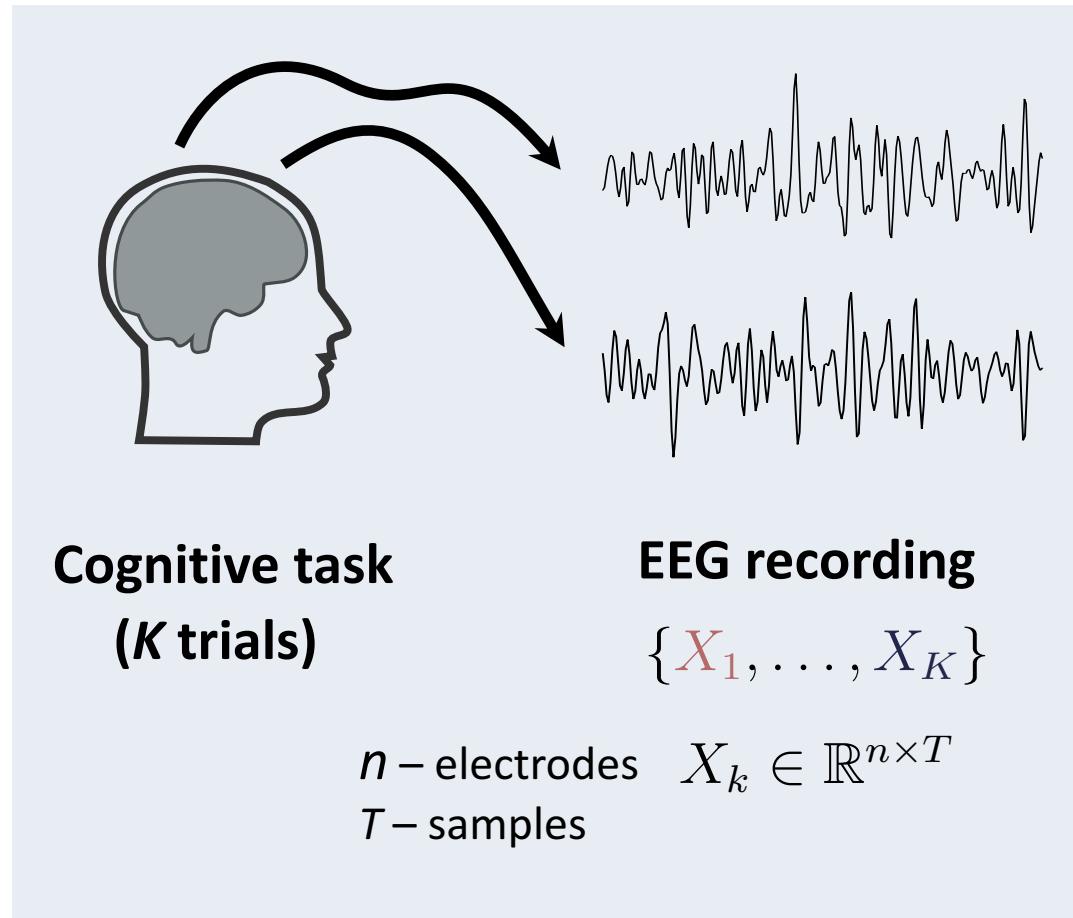
### Covariance matrix

$$\{C_1, \dots, C_K\}$$

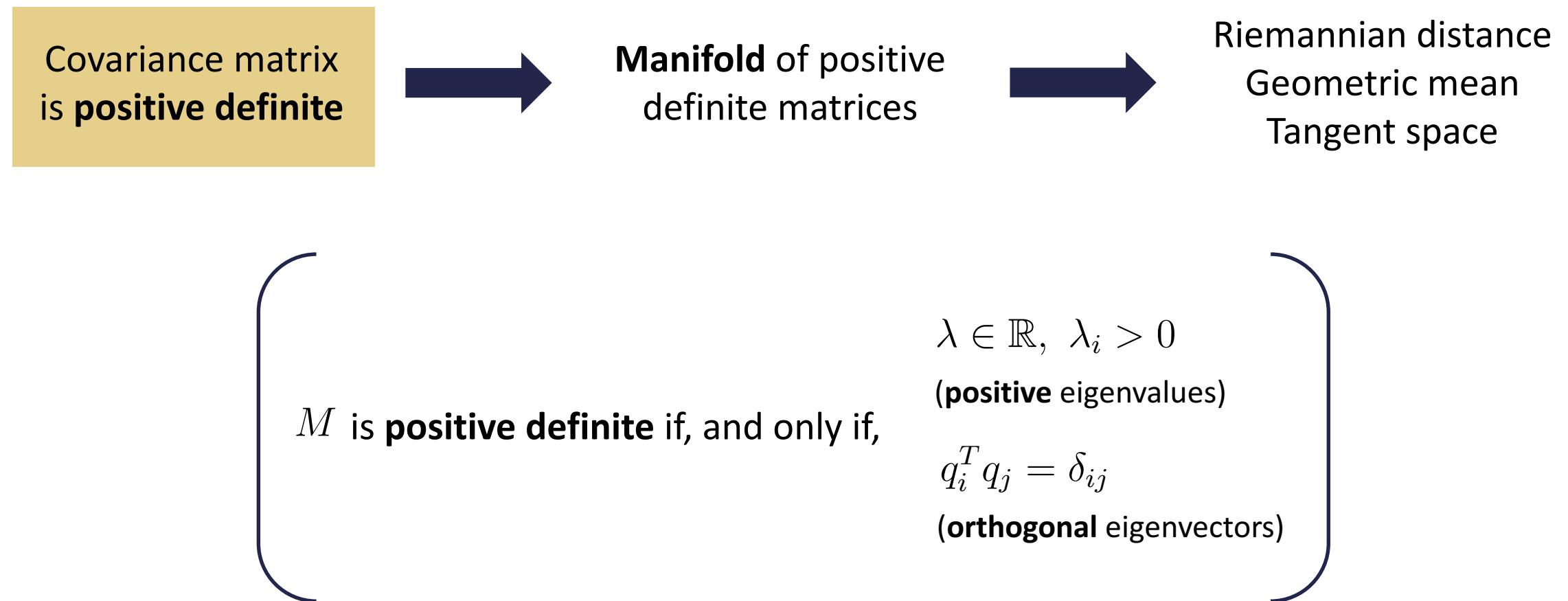
$$C_k \in \mathbb{R}^{n \times n}$$

$$C_k = \frac{1}{T} X_k X_k^T$$

## The BCI paradigm – classification of EEG epochs



# The Symmetric Positive Definite (SPD) manifold



# The Symmetric Positive Definite (SPD) manifold

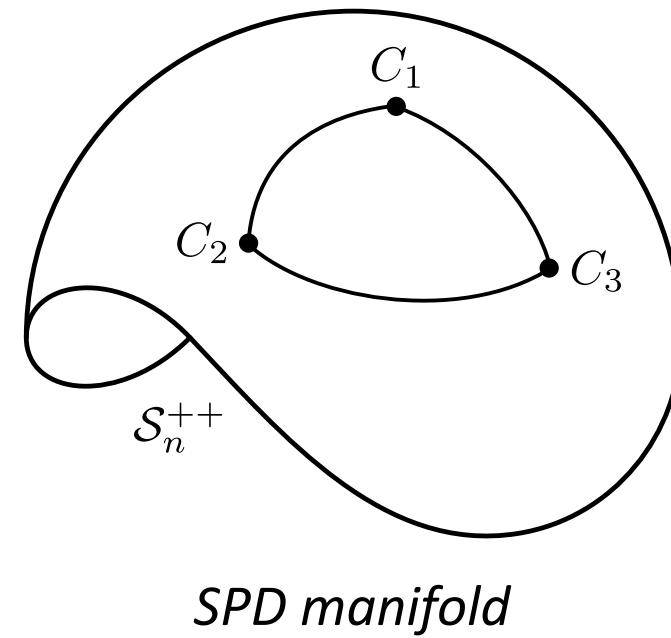
Covariance matrix  
is **positive definite**



Manifold of positive  
definite matrices



Riemannian distance  
Geometric mean  
Tangent space



# The Symmetric Positive Definite (SPD) manifold

Covariance matrix  
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**Geodesic** distances between  
points on the globe

# The Symmetric Positive Definite (SPD) manifold

Covariance matrix  
is **positive definite**



**Manifold of positive  
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*Riemannian Geometry*

Riemannian distance  
Geometric mean  
Tangent space

- Natural distance between SPD matrices

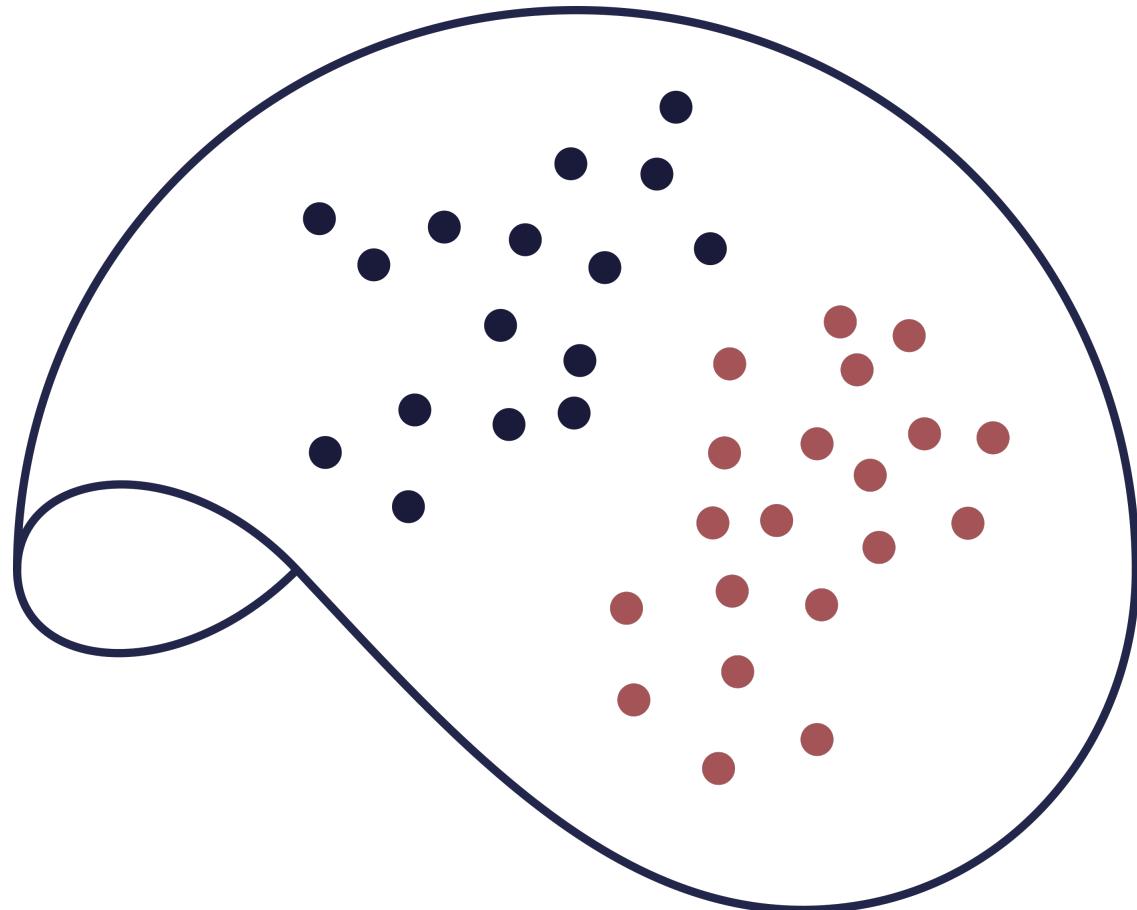
$$\delta_R^2(C_i, C_j) = \left\| \text{Log}(C_i^{-1/2} C_j C_i^{-1/2}) \right\|_F^2 = \sum_{k=1}^n \log^2(\lambda_k)$$

- Center of mass of  $K$  SPD matrices

$$M = \underset{M \in \mathcal{S}_n^{++}}{\operatorname{argmin}} \sum_{k=1}^K \delta_R^2(M, C_k)$$

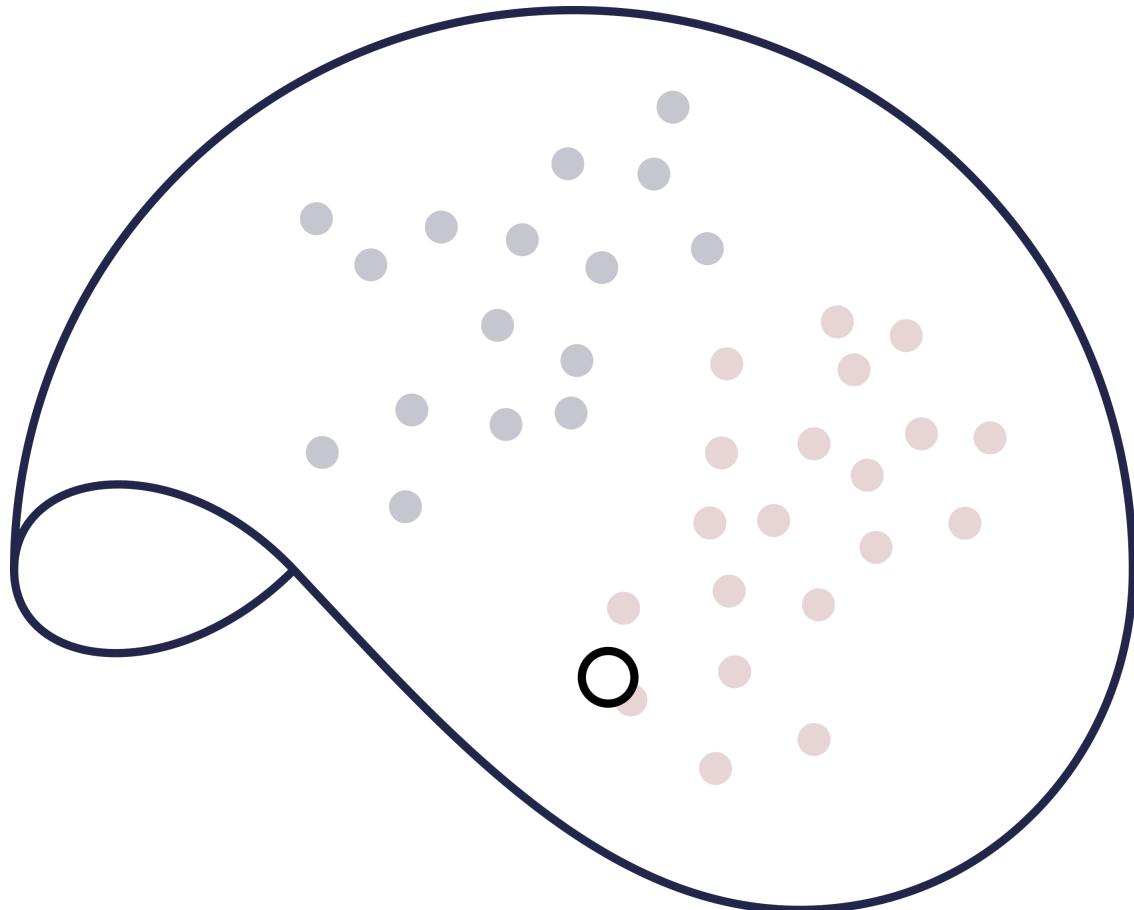
A very simple **classifier** using the geometry of the SPD manifold

$$\{C_1^{(a)}, \dots, C_{K_a}^{(a)}\} \quad \{C_1^{(b)}, \dots, C_{K_b}^{(b)}\}$$



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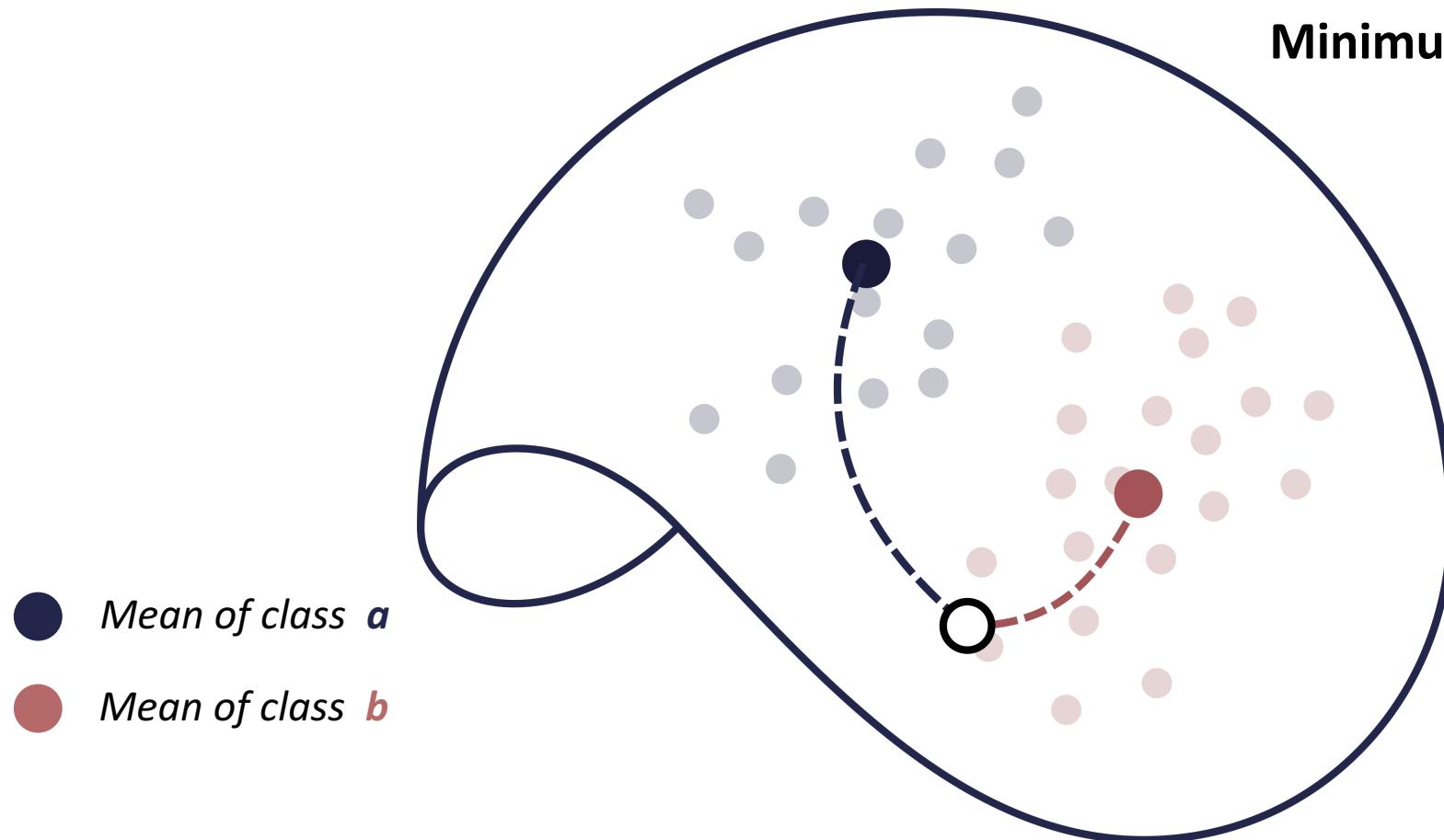
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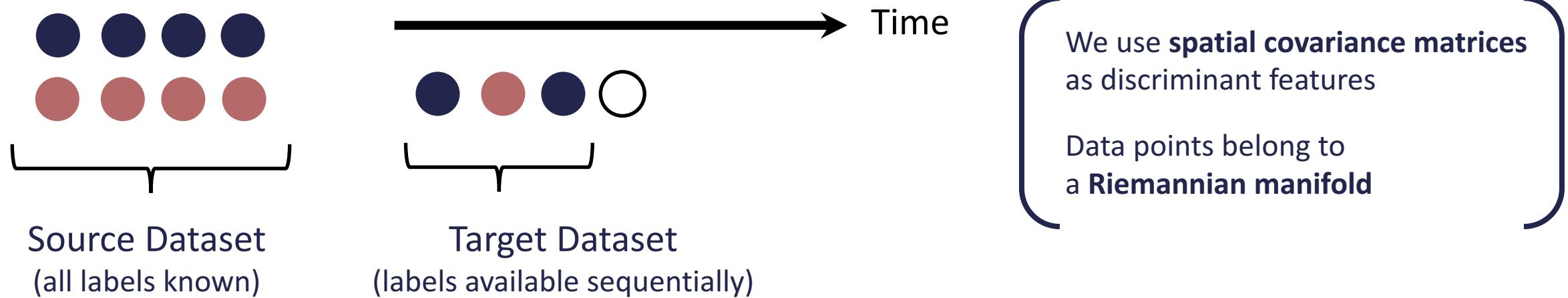
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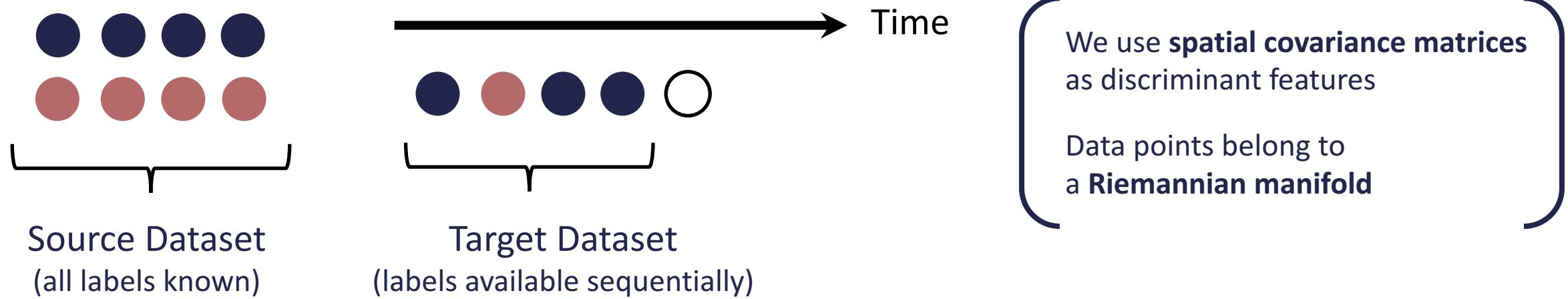
Classification based on the  
**Minimum Distance to Mean (MDM)**



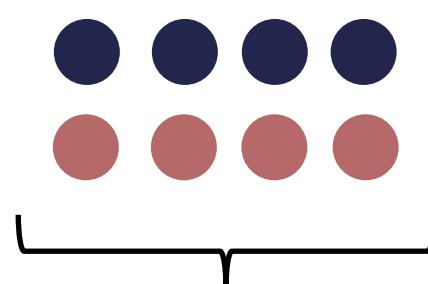
Use data from the **source dataset** to classify the trials from the **target dataset**



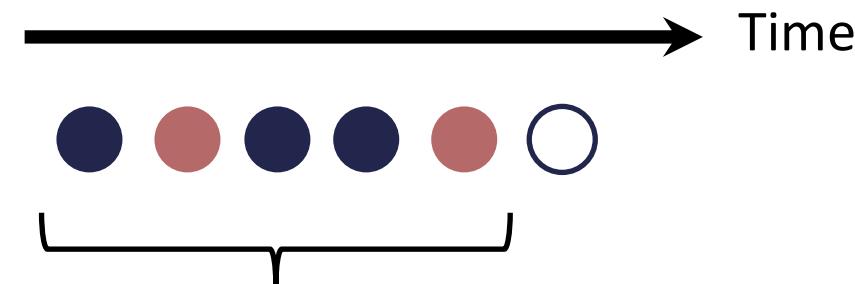
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Use data from the **source dataset** to classify the trials from the **target dataset**



Source Dataset  
(all labels known)



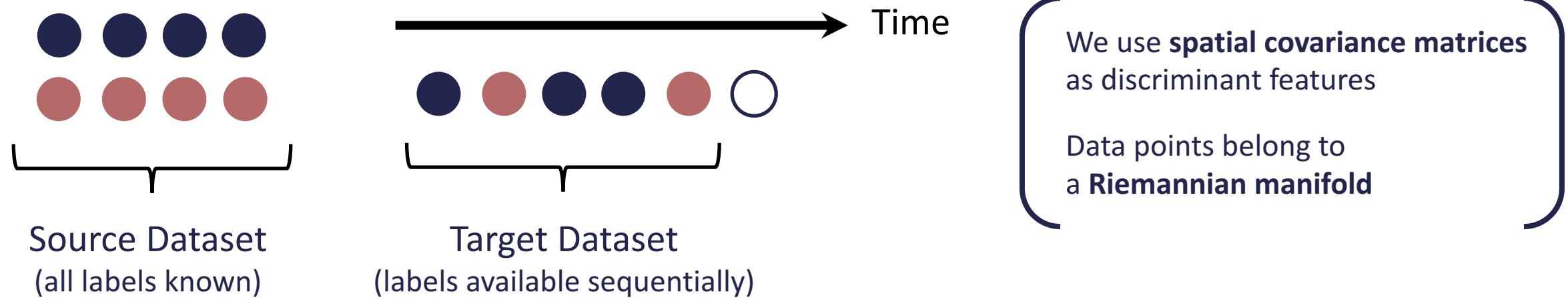
Target Dataset  
(labels available sequentially)

Time

We use **spatial covariance matrices** as discriminant features

Data points belong to a **Riemannian manifold**

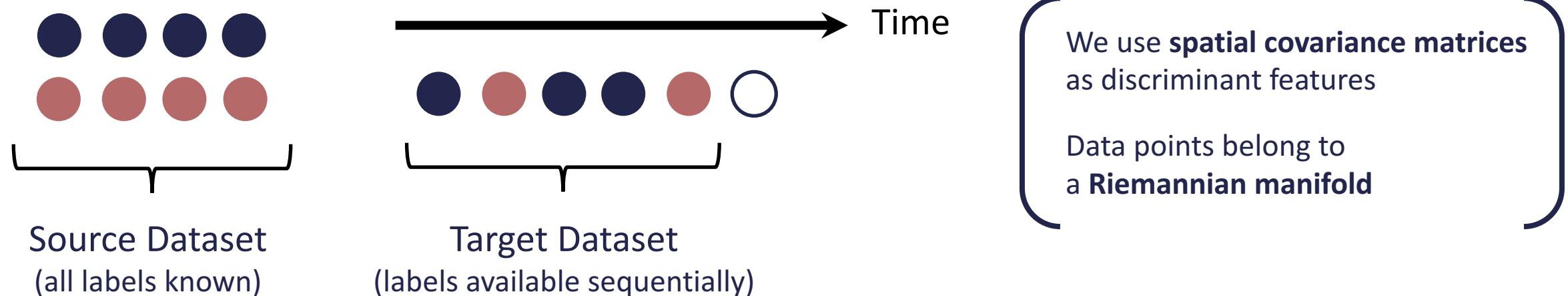
Use data from the **source dataset** to classify the trials from the **target dataset**



We do Transfer Learning via **distribution matching**

- 1) Fit classifier  $C$  to source dataset
- 2) Match target and source distributions
- 3) Classify unknown trial using  $C$

Use data from the **source dataset** to classify the trials from the **target dataset**



We do Transfer Learning via **distribution matching**

- 1) Fit classifier  $C$  to source dataset
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Match statistical distributions by applying geometrical **transformations** to the data points !

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The Procrustes bed appears in Greek mythology

(The word *Procrustean* is used to describe situations where different lengths or sizes or properties are **fitted to a standard**)

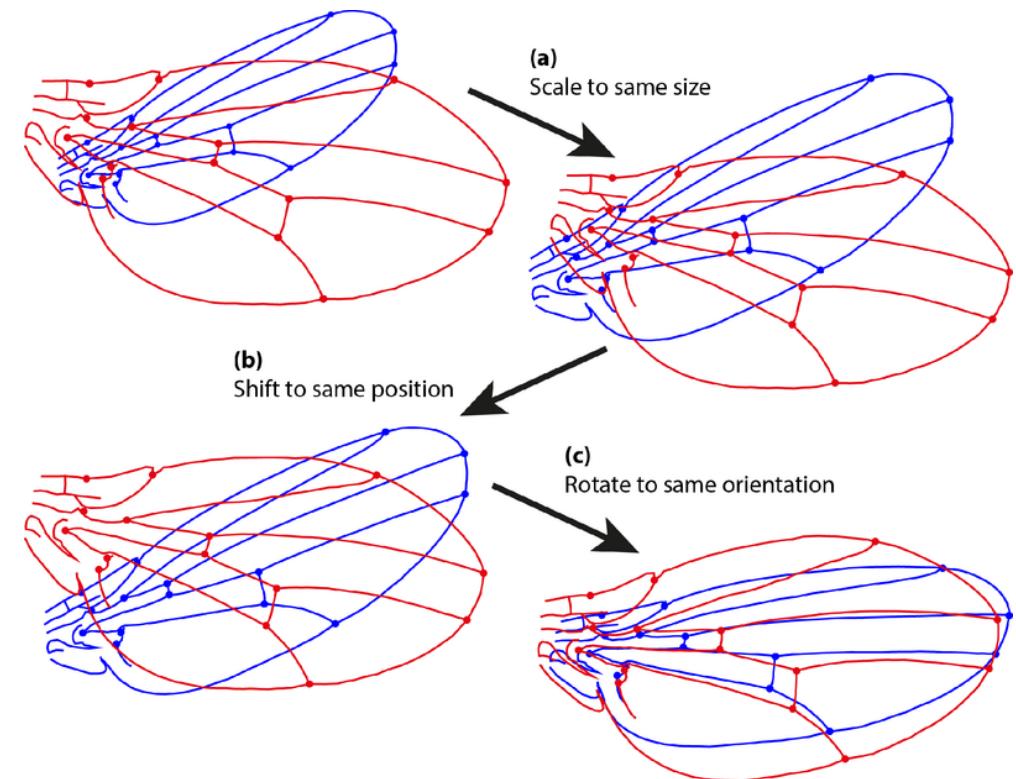


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Procrustes **analysis** is commonly used in statistical shape analysis to and consists of matching shapes via

- Translation
- Stretching
- Rotation



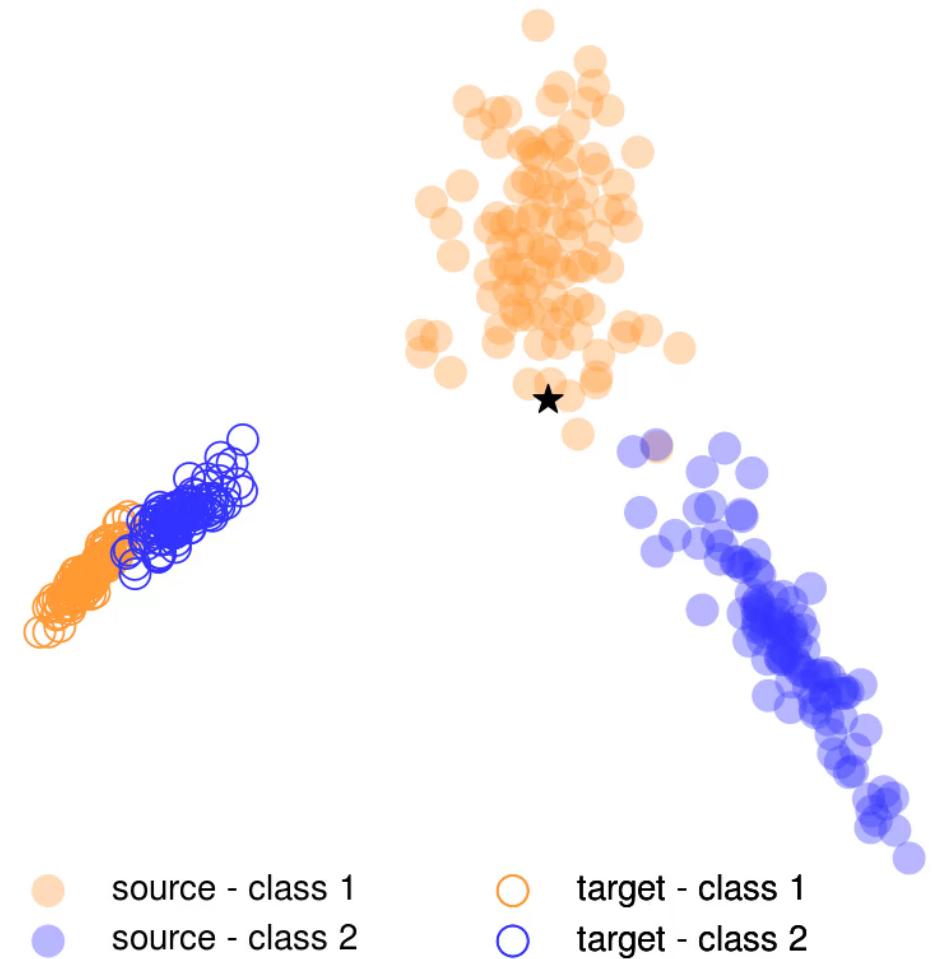
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We propose a PA in the SPD manifold to **match the shape of the statistical distributions** of sessions

Each dot represents a **trial** in the dataset

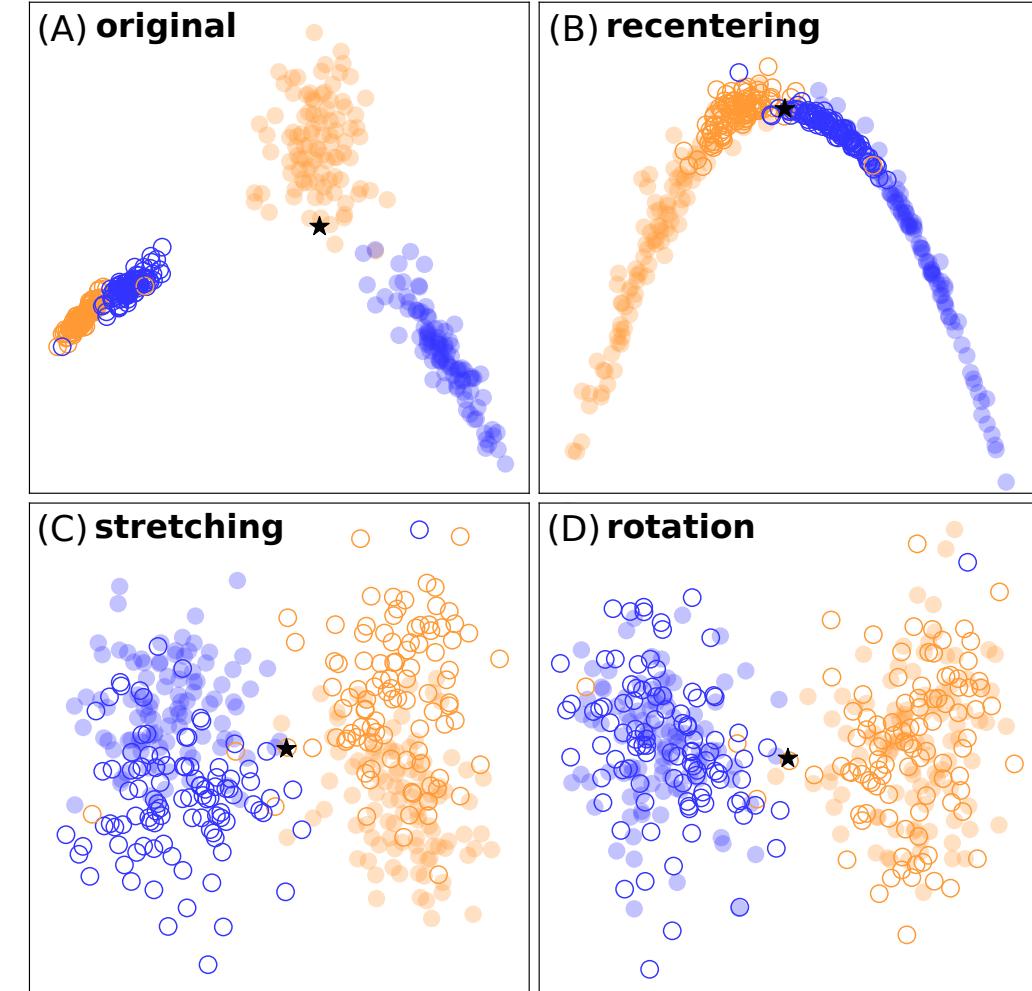


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We propose a PA in the SPD manifold to **match the shape** of the statistical **distributions** of sessions



The transformations have to respect the **intrinsic geometry** of the SPD manifold

Suppose we have a set of  $K$  matrices  $\{C_1, \dots, C_K\}$  and their geometric mean is  $M$

**RECENTERING**

$$C_i^{(\text{rct})} = M^{-1/2} C_i M^{-1/2}$$

**STRETCHING**

$$C_i^{(\text{str})} = \left( C_i^{(\text{rct})} \right)^p$$

**ROTATION**

$$C_i^{(\text{rot})} = U C_i^{(\text{str})} U^T \quad \text{with } UU^T = \mathbf{I}$$

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## Four datasets on three BCI paradigms

Publicly Available

Physionet EEG MI database

( 109 subjects, 40 trials, 2 classes )

GigaDB EEG MI database

( 37 subjects, 200 trials, 2 classes )

SSVEP Chevallier database

( 12 subjects, 24 trials, 3 classes, 2 sessions )

P300 Brain Invaders database

( 24 subjects, 576 trials, 2 classes)

For each dataset, Transfer Learning was always done in the **cross-subject** case

## Cross-subject accuracy

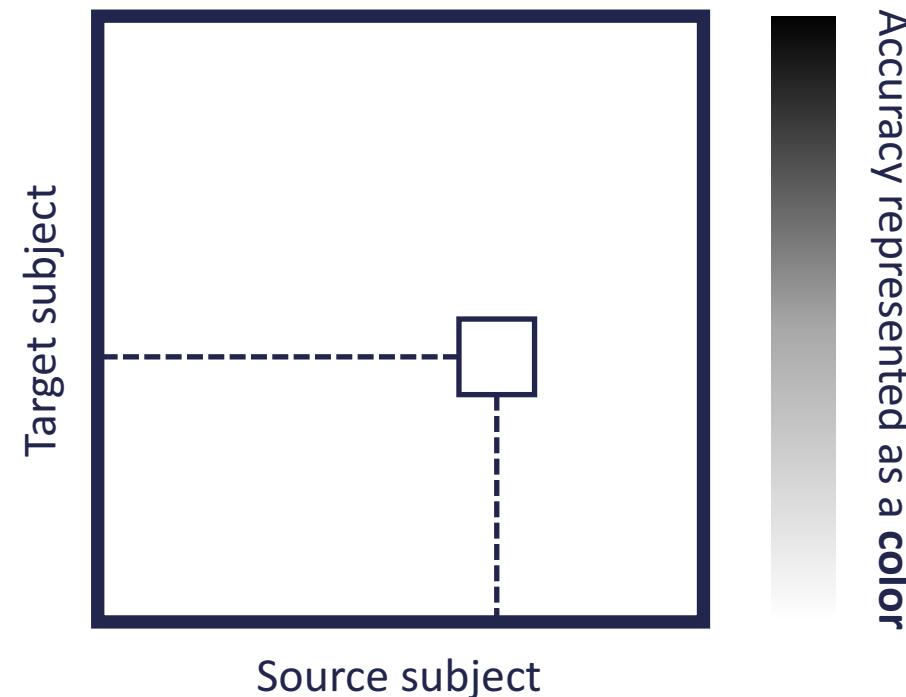
Get the accuracies in classification when :

(Consider an **increasing** number of available points in the target dataset)

Compare the results for **three** methods :

ORIGINAL  
RECENTERING  
RPA

- 1) Classifier C is fitted to **source** subject dataset
- 2) Match target and source statistical distributions
- 3) Classify unknown trials from **target** dataset

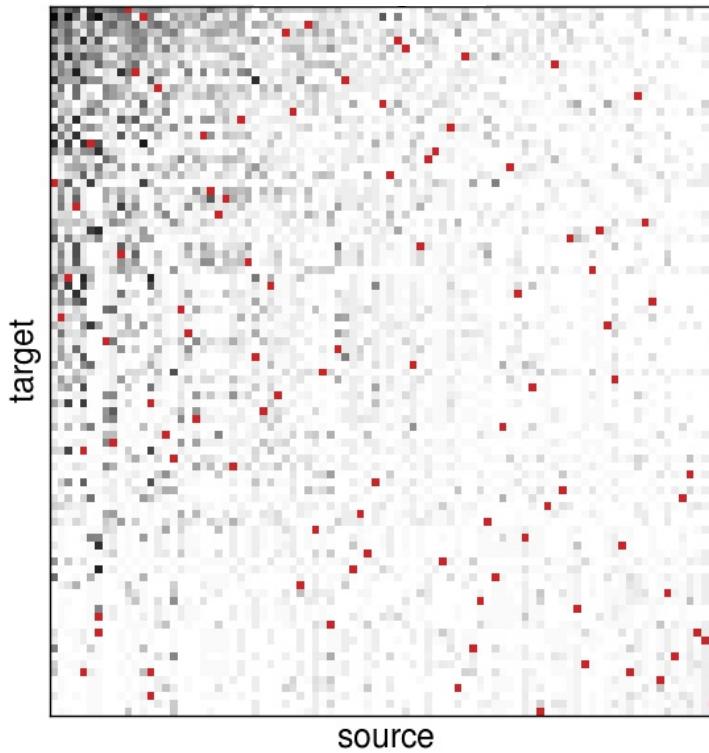


## Cross-subject accuracy – Physionet MI

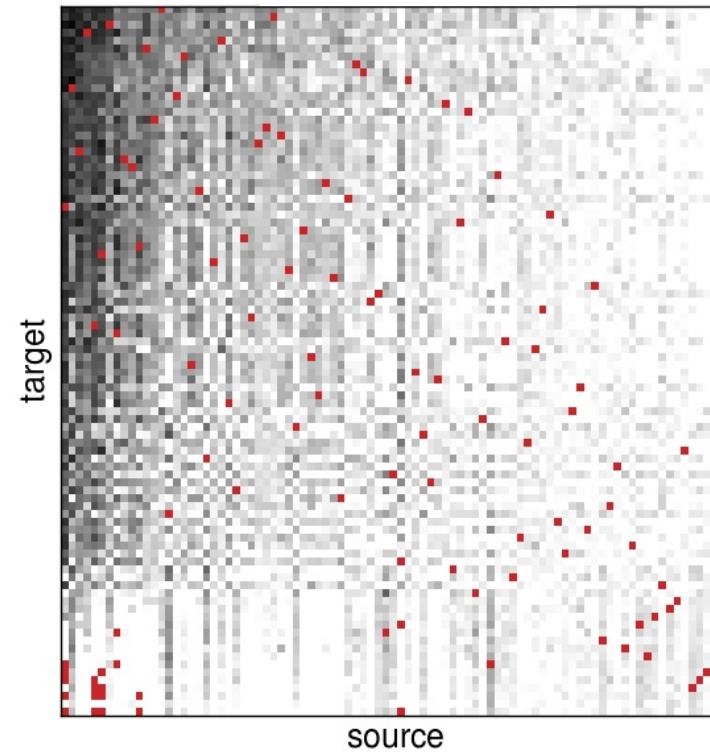
# of data points in the target dataset :

1

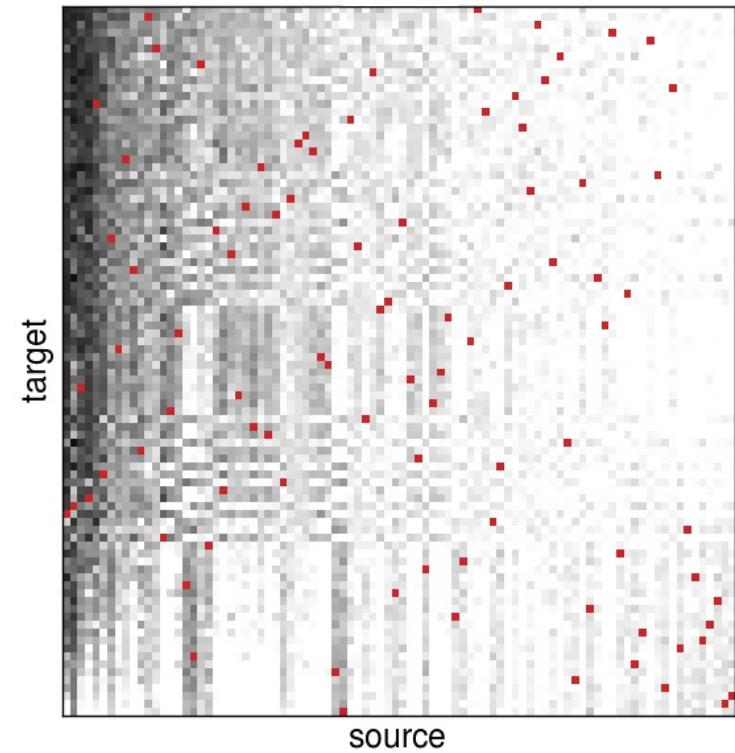
ORIGINAL



RECENTERING



RPA



( Colormap : **white** indicates 0.5 accuracy and **black** is 1.0 )



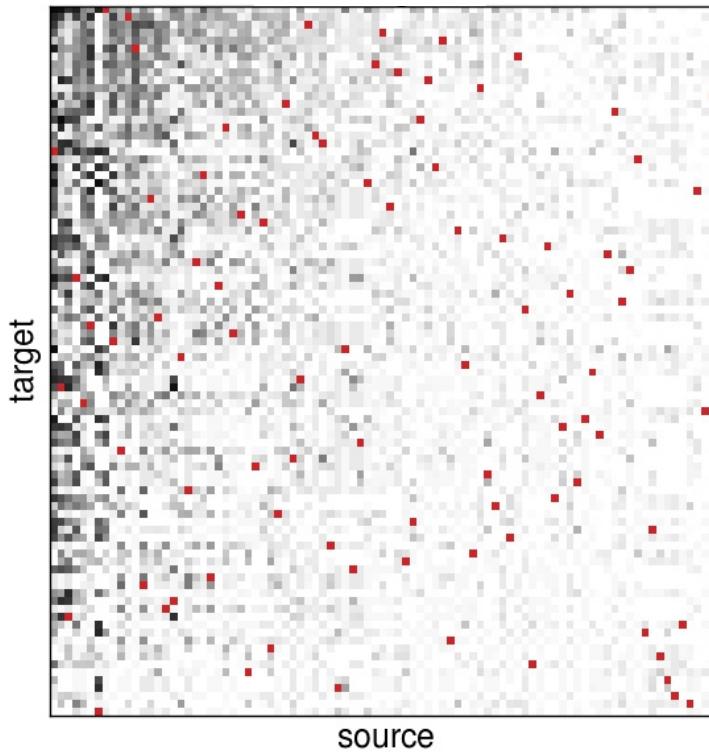
Source subject = Target subject

# Cross-subject accuracy – Physionet MI

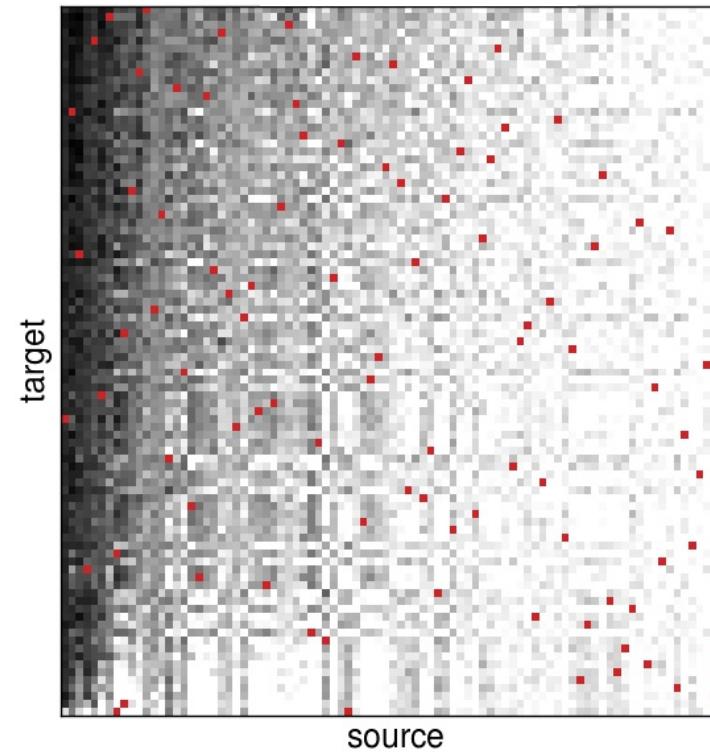
# of data points in the target dataset :

5

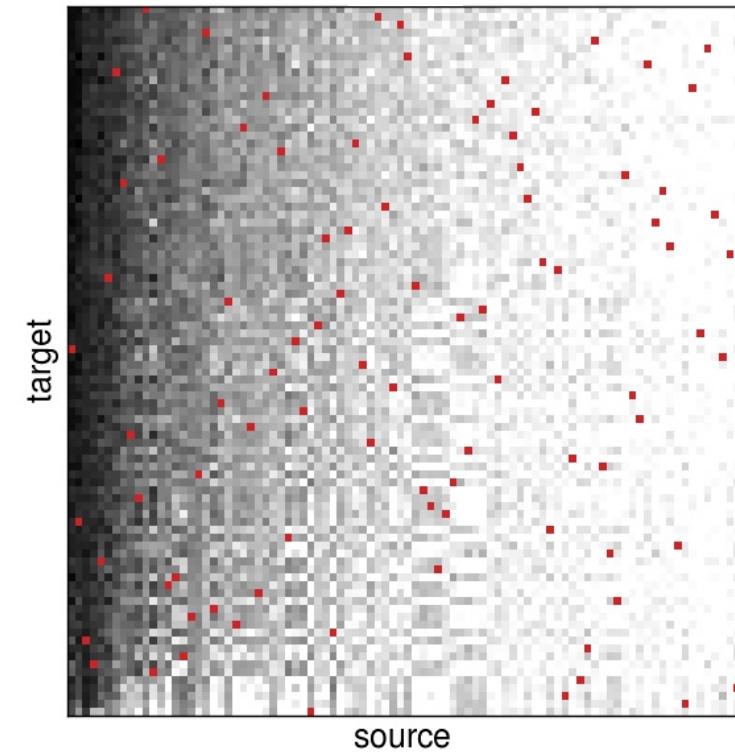
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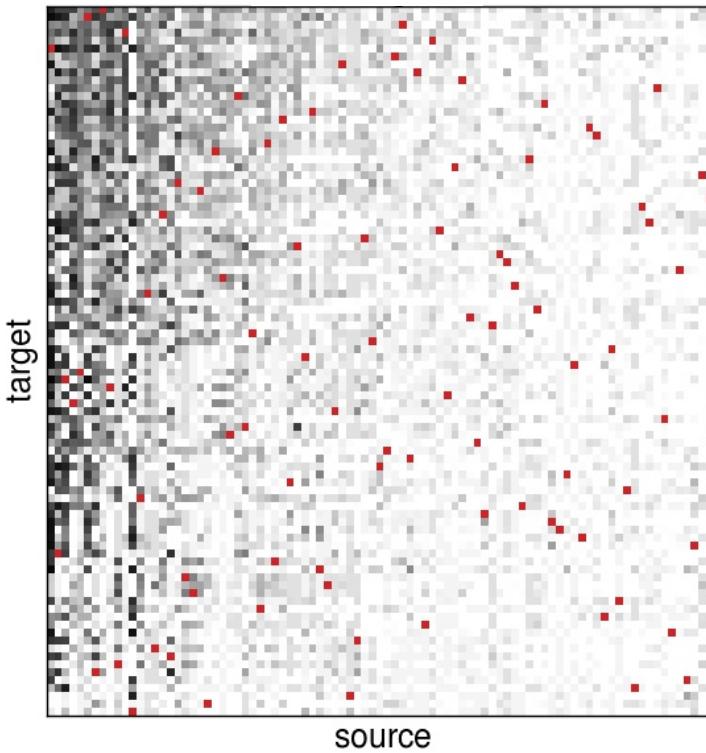
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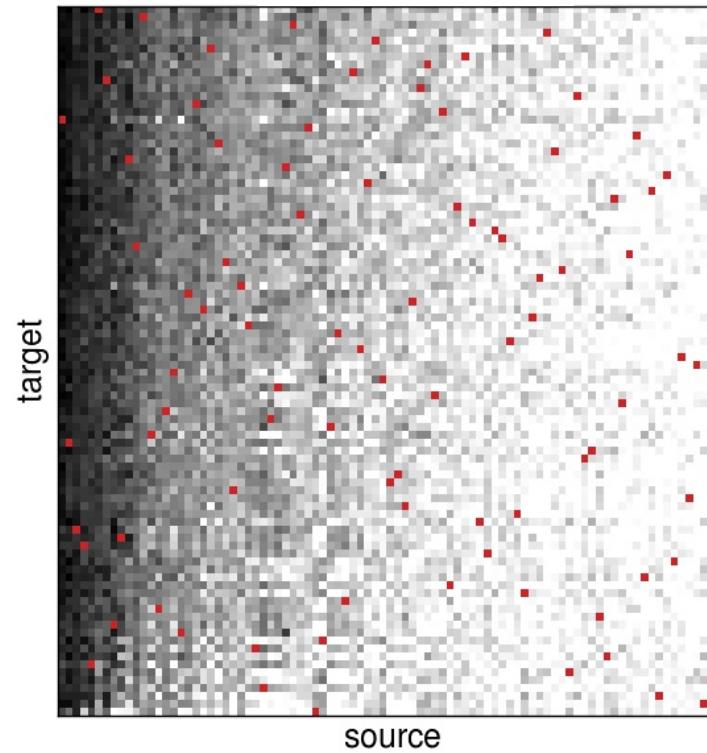
# of data points in the target dataset :

10

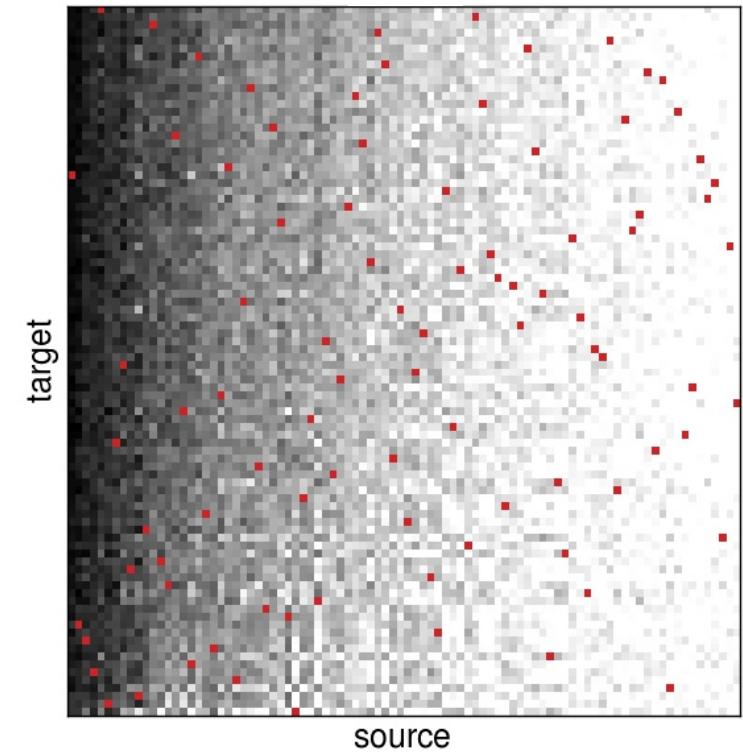
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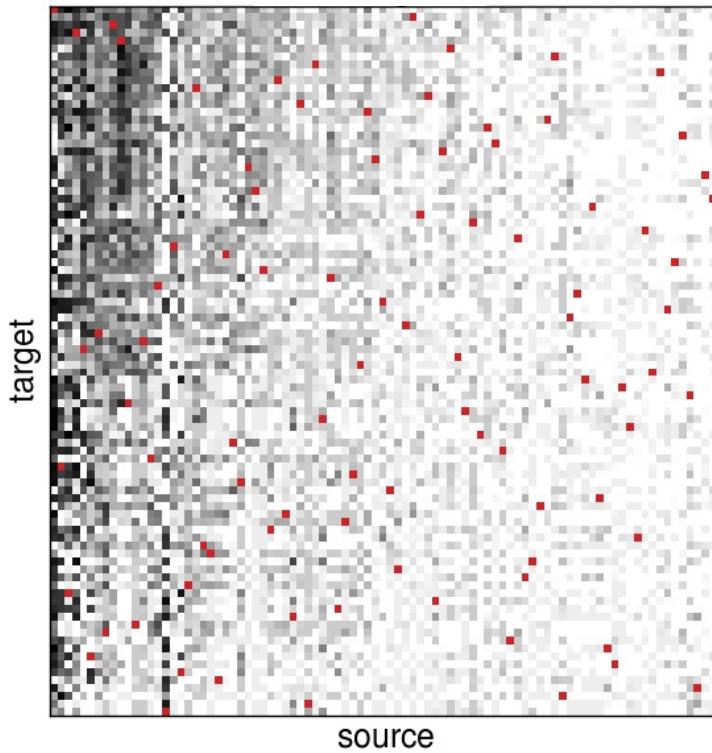
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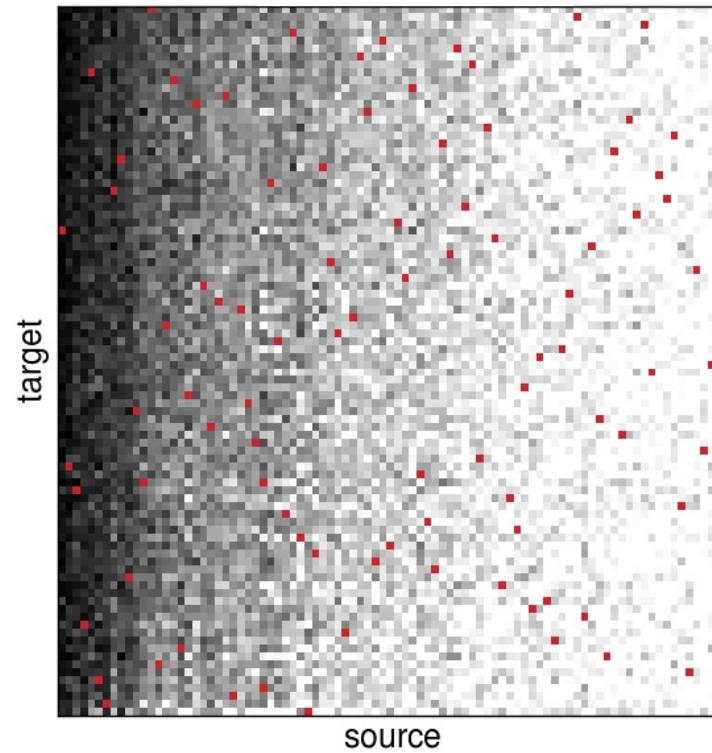
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15

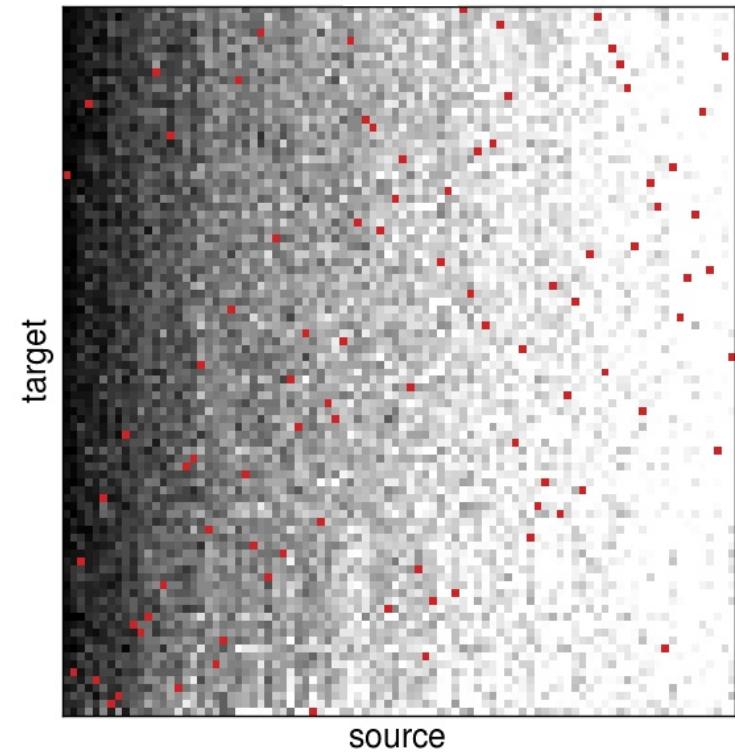
ORIGINAL



RECENTERING



RPA



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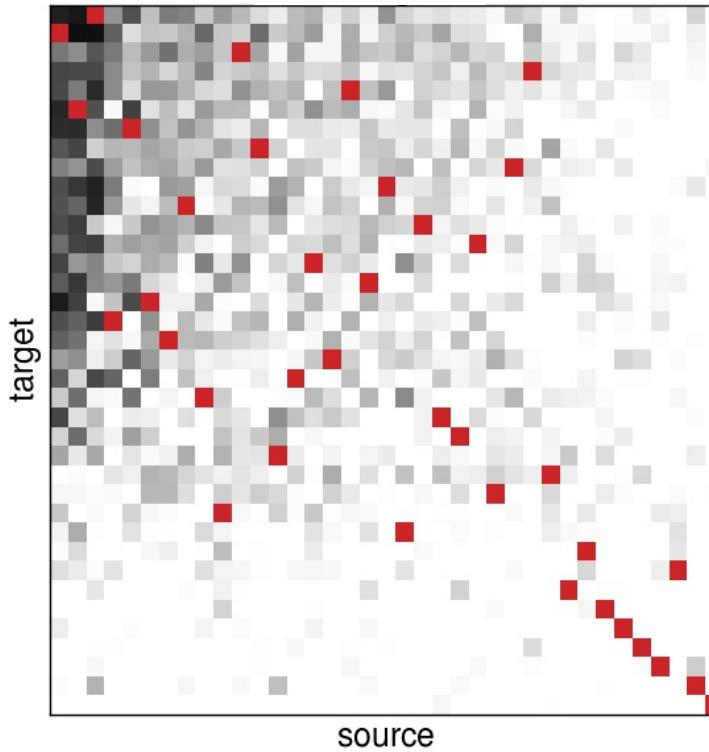
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## Cross-subject accuracy – GigaDB MI

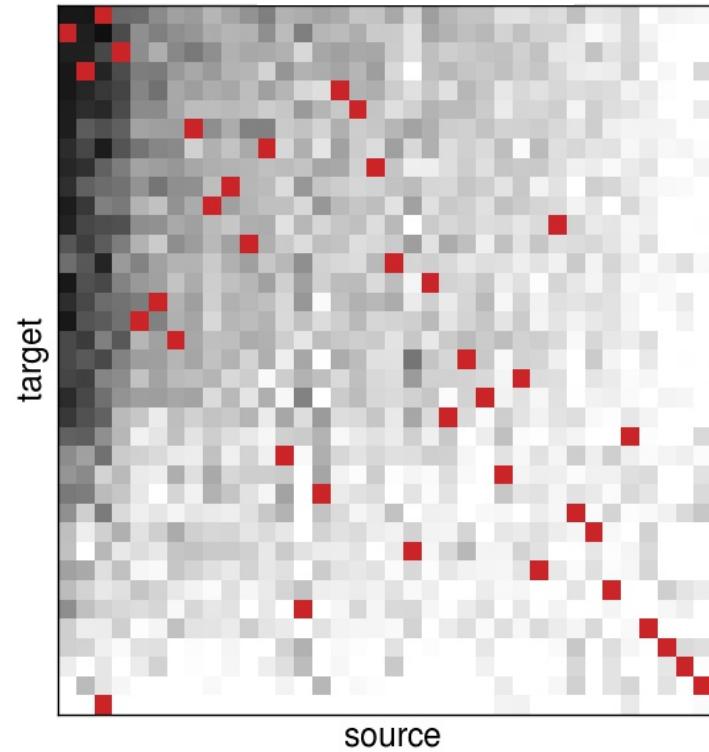
# of data points in the target dataset :

1

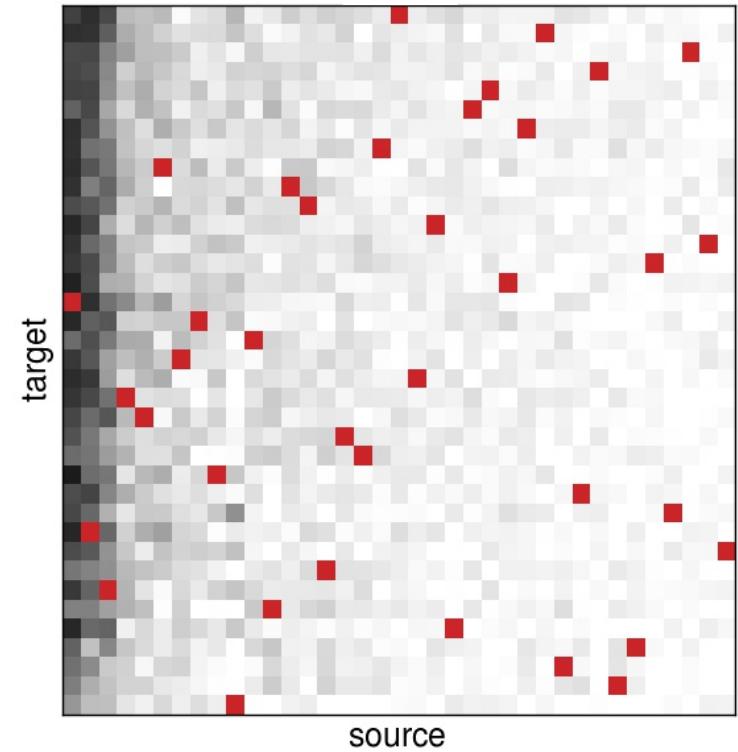
ORIGINAL



RECENTERING



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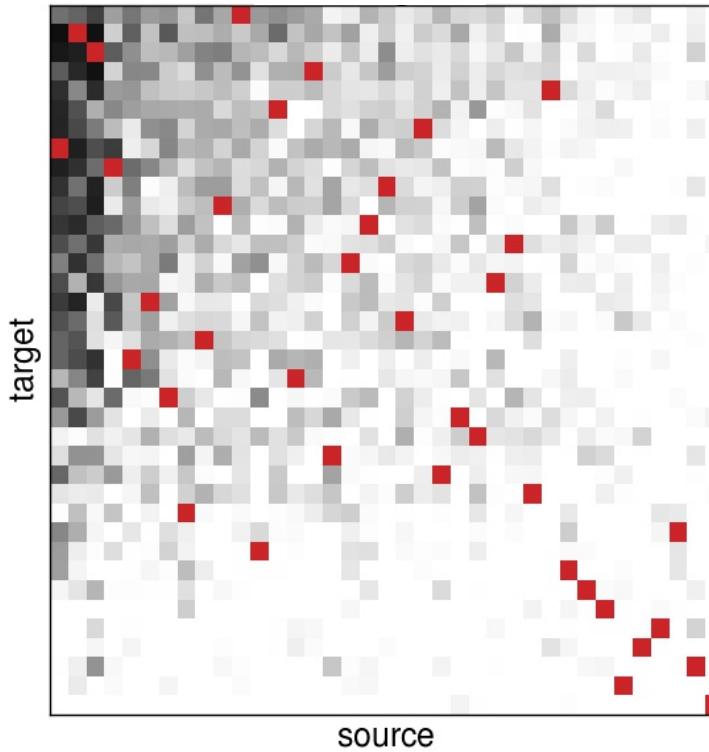
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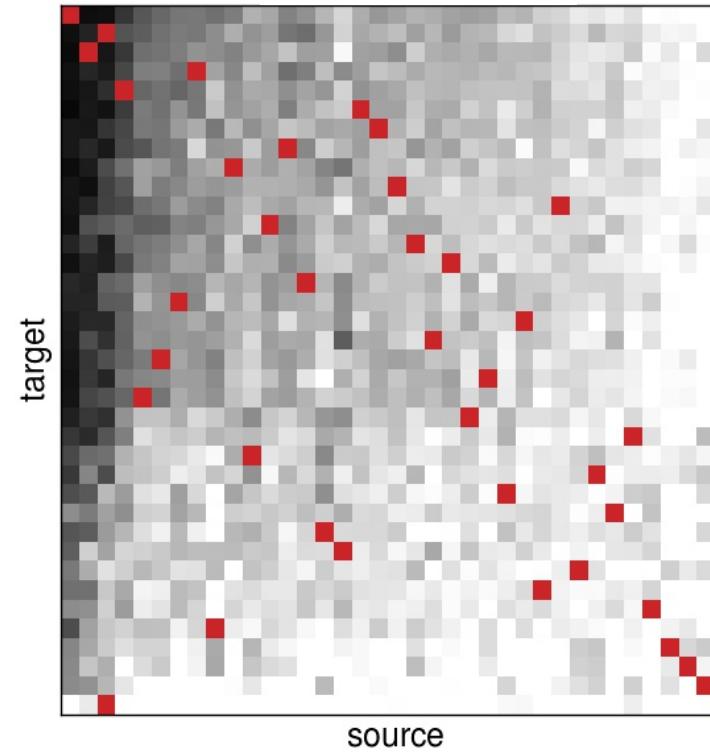
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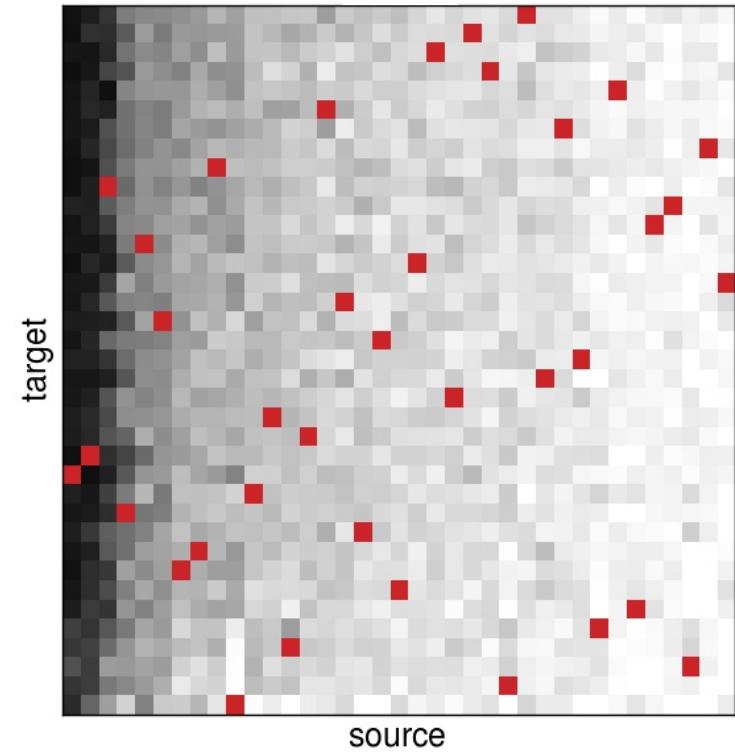
ORIGINAL



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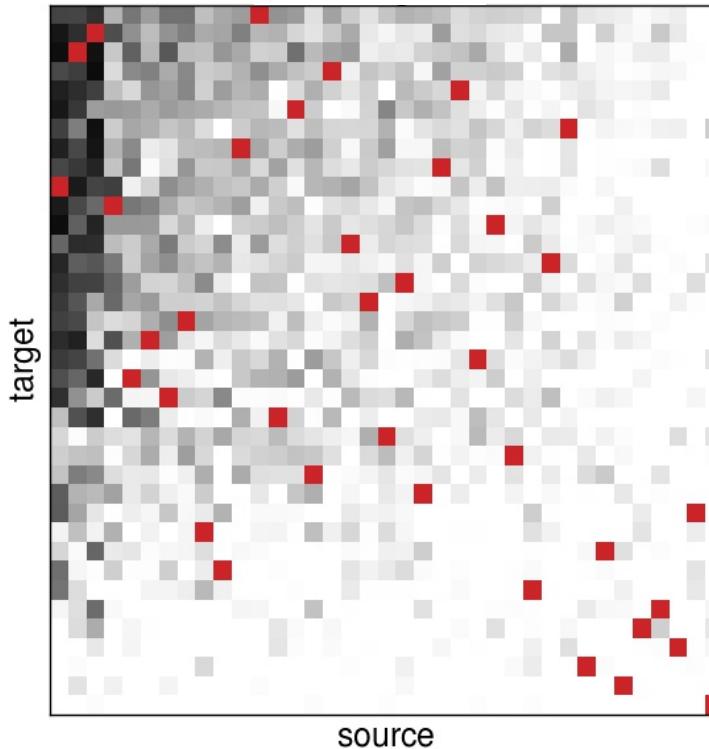
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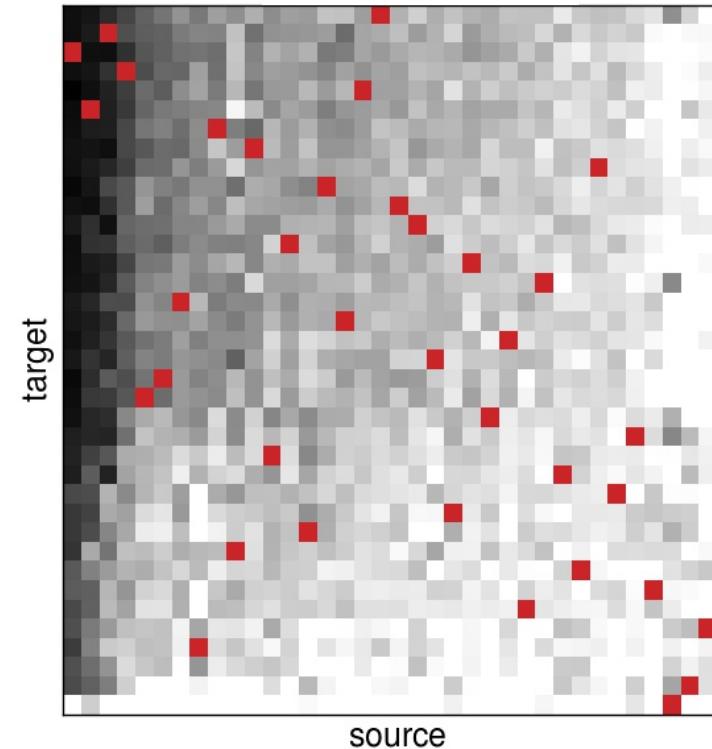
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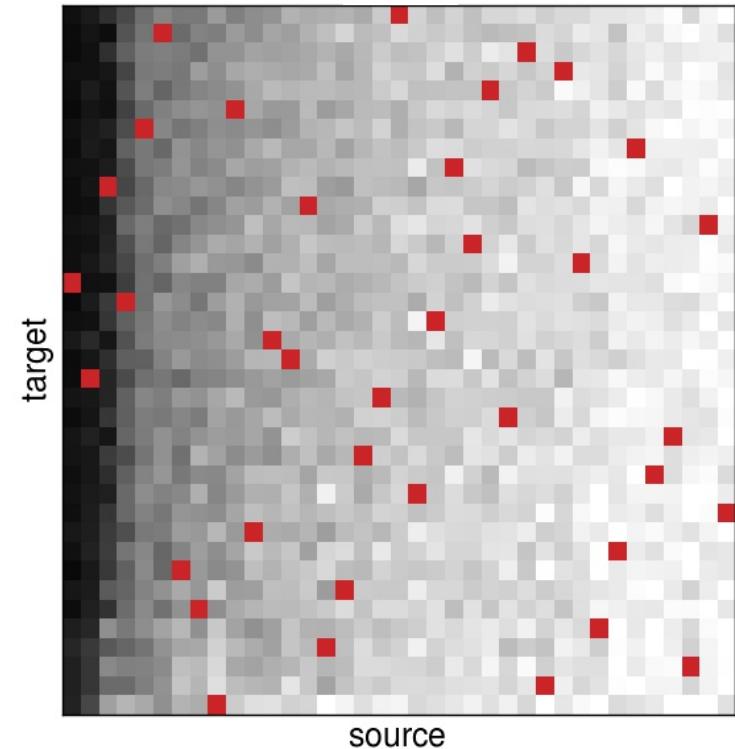
ORIGINAL



RECENTERING



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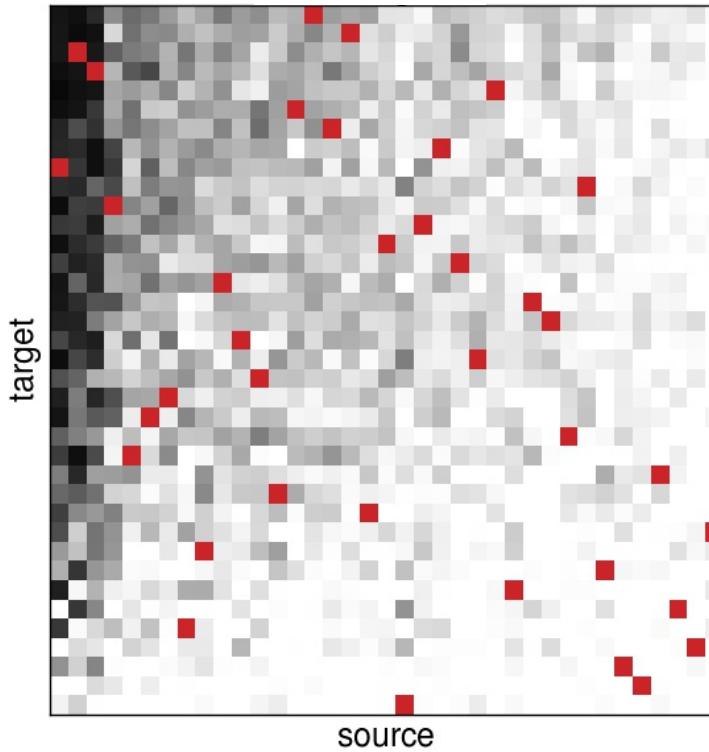
Source subject = Target subject

# Cross-subject accuracy – GigaDB MI

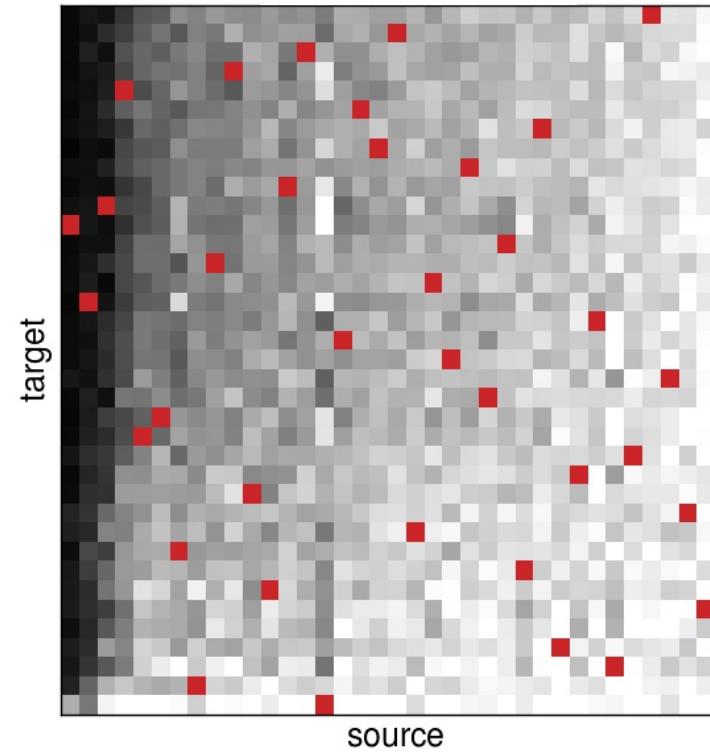
# of data points in the target dataset :

25

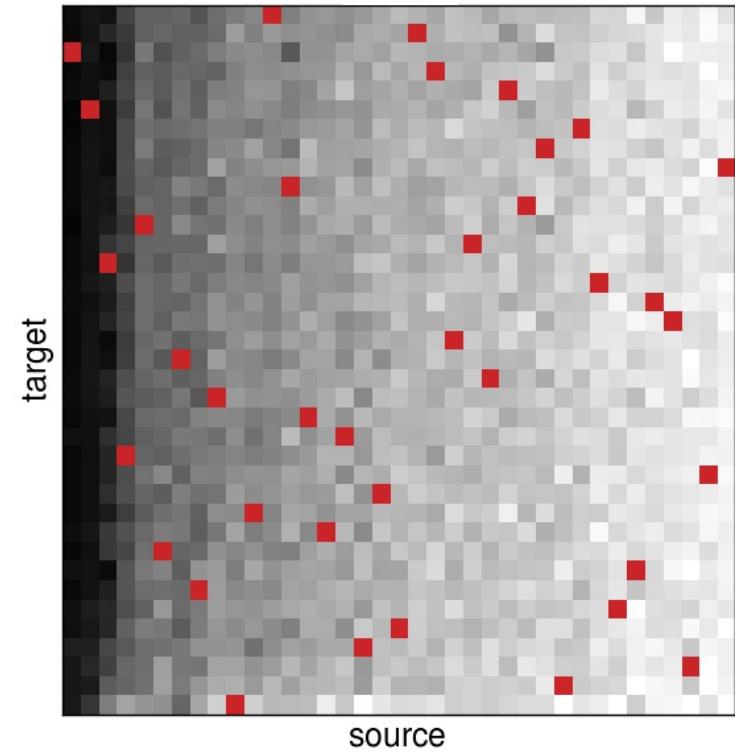
ORIGINAL



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Source subject = Target subject

## Cross-subject accuracy

<i>MI-Physionet</i>	N	MEAN ACCURACY		
		direct	recent.	RPA
1	0.52	0.55	0.55	
5	0.53	0.59	0.61	
10	0.54	0.61	0.63	
15	0.55	0.63	0.64	

<i>MI-GigaDB</i>	N	MEAN ACCURACY		
		direct	recent.	RPA
1	0.55	0.58	0.55	
5	0.55	0.60	0.61	
10	0.56	0.62	0.64	
25	0.58	0.65	0.67	

<i>SSVEP</i>	N	MEAN ACCURACY		
		direct	recent.	RPA
1	0.59	0.59	0.61	
2	0.64	0.65	0.68	
4	0.71	0.72	0.76	
6	0.75	0.77	0.80	

<i>P300</i>	N	MEAN AUC		
		direct	recent.	RPA
6	0.49	0.59	0.55	
12	0.50	0.57	0.57	
32	0.52	0.54	0.57	
48	0.53	0.54	0.56	

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Our method works for **any** BCI paradigm : it depends only on the choice of SPD matrices

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In every dataset there are **good** and **bad** source subjects. How to deal with this ?

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Our method could be used with **boosting** and other strategies for **combining** classifiers

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Some **interesting** works related to ours

Zanini et al. – “*Transfer Learning: a Riemannian geometry framework with applications to Brain-Computer Interfaces*” (2018)

Gayraud et al. – “*Optimal Transport Applied to Transfer Learning*” (2017)

Arvaneh et al. – “*EEG data space to reduce intersession nonstationarity in brain-computer interface*” (2013)

Thank you for your attention :-)

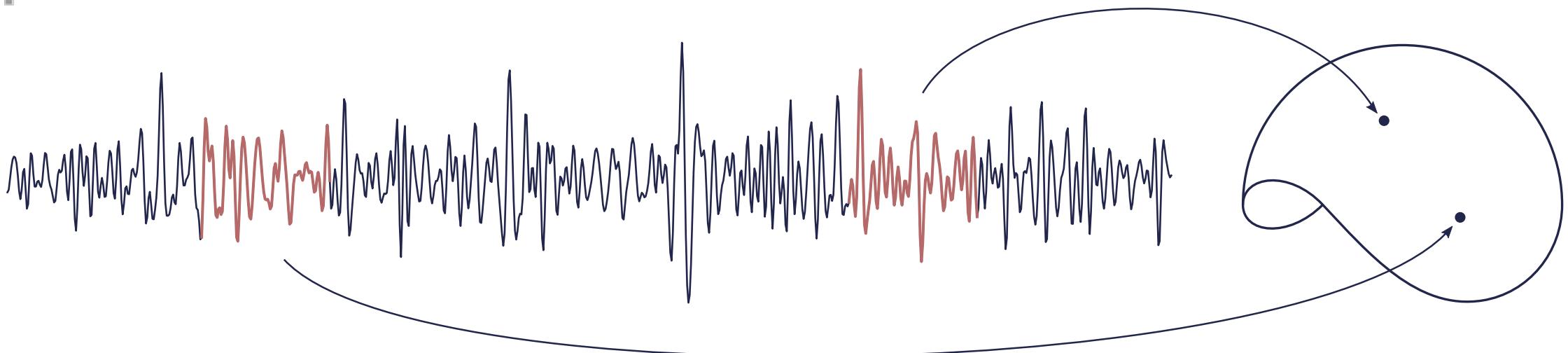
*Questions ?*

# Riemannian Procrustes Analysis

## Transfer Learning for Brain Computer Interfaces



Pedro L. C. Rodrigues Marco Congedo Christian Jutten



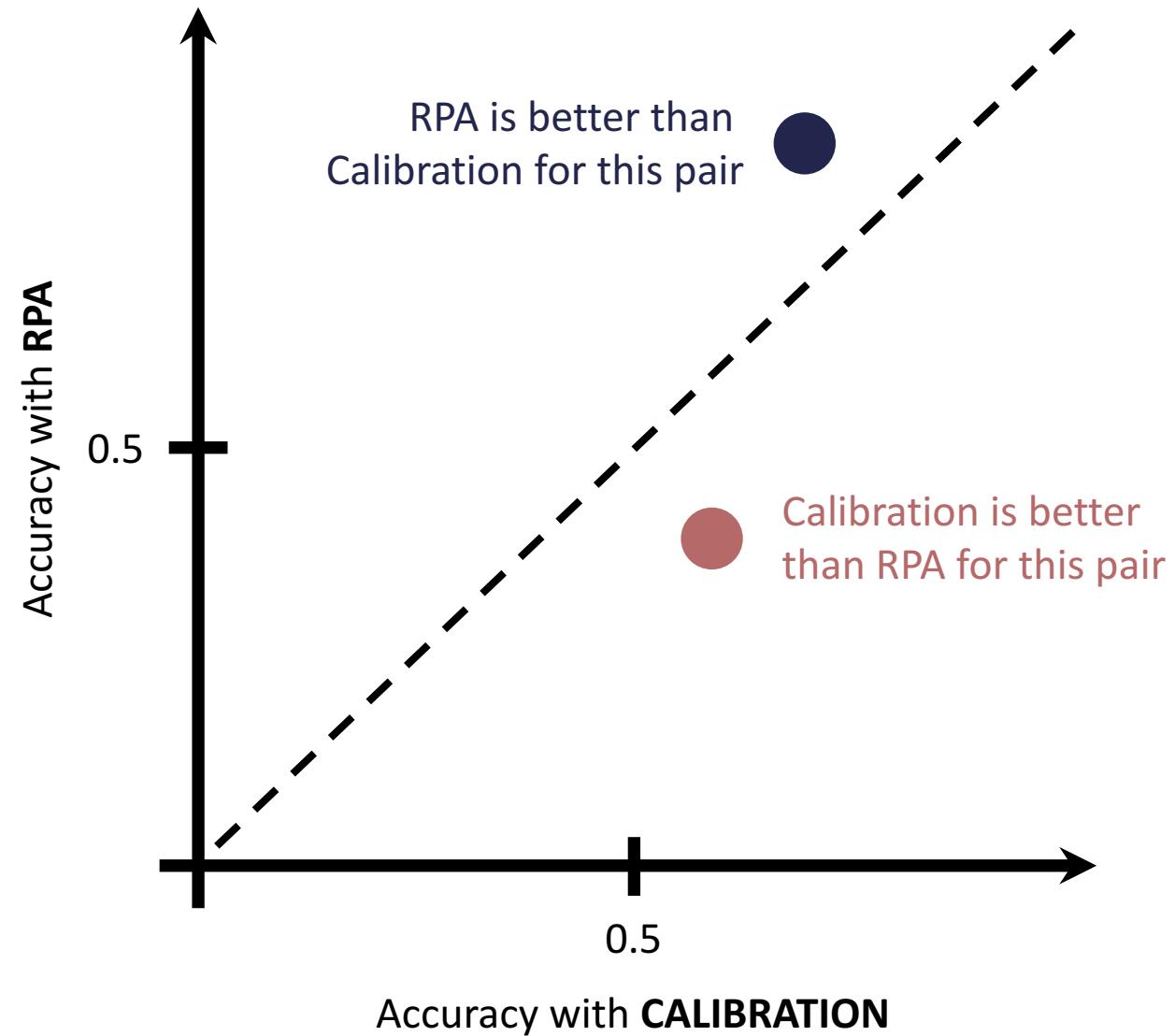
*Presentation for the Machine Learning group at GIPSA-lab*  
22th May 2018, Grenoble, France

# Better than calibration ?

Compare RPA to Calibration

(Consider an **increasing** number of available points in the target dataset)

Use the Wilcoxon Paired statistical test to check if one method is **superior** to the other in **average** (for all pairs of subjects)

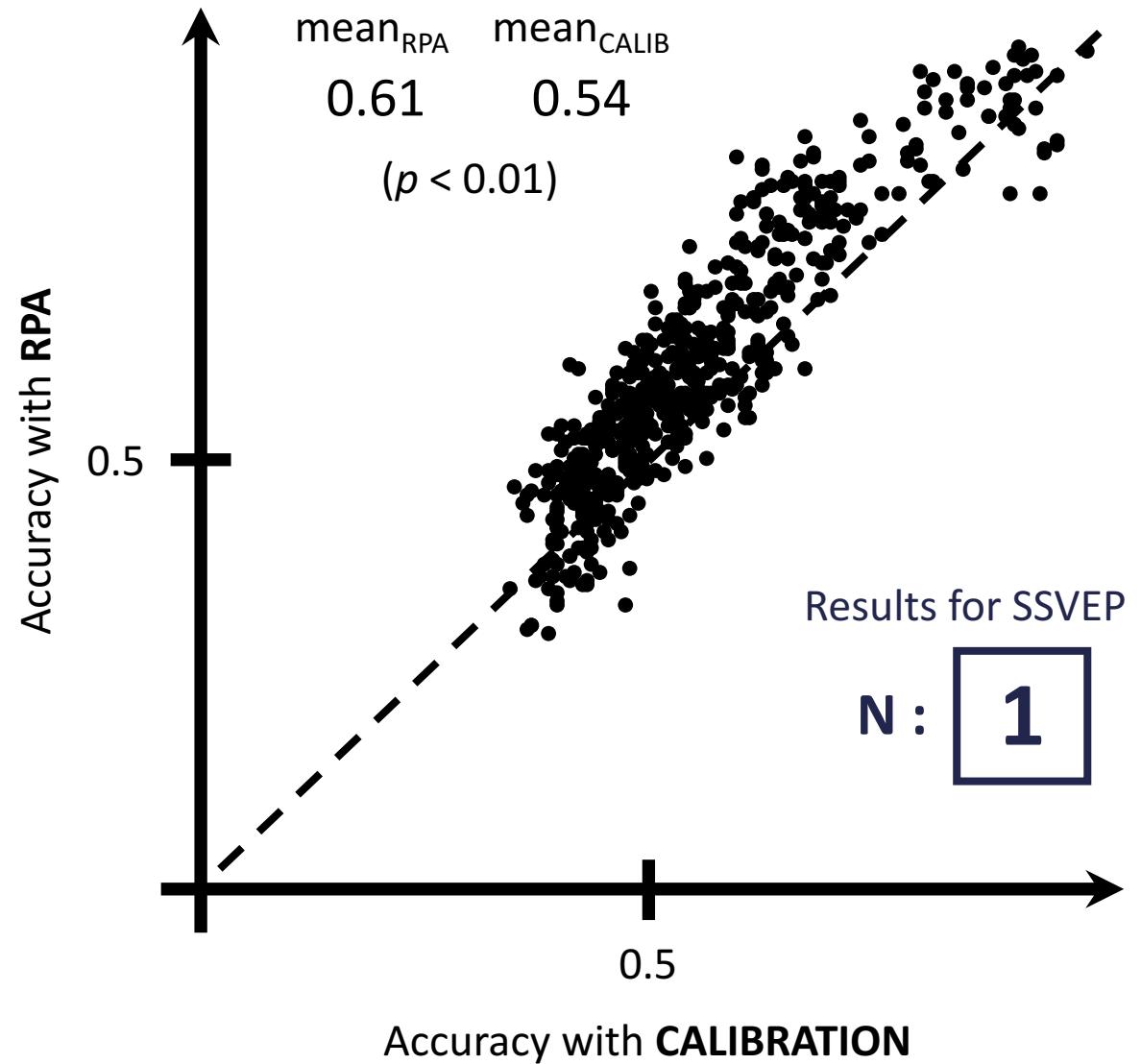


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