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# Machine learning overview

MLST presentation

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GIPSA-lab

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# Outline

History

Topics

Methods

Examples

- K-means

- Gaussian mixture

- PhD-related example

Machine learning tools

Deep learning basics

- Basic architecture

- Weights and biases

- Activation function

- Gradient descent and back propagation

- Different types of neural networks



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- 2001 • **L. Breiman** Random Forest
- 2005 • New era of Deep Learning : CNN, AE, GD, ...



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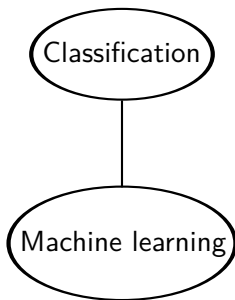
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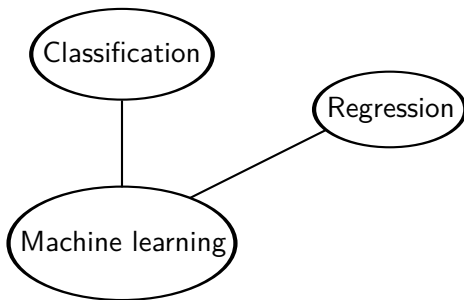
Machine learning



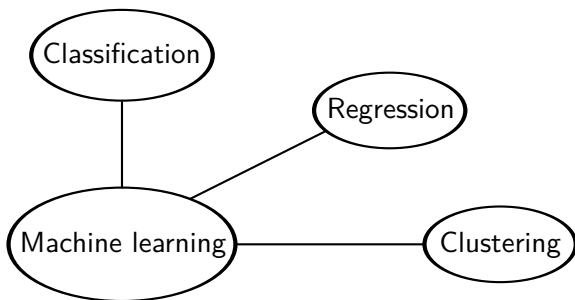
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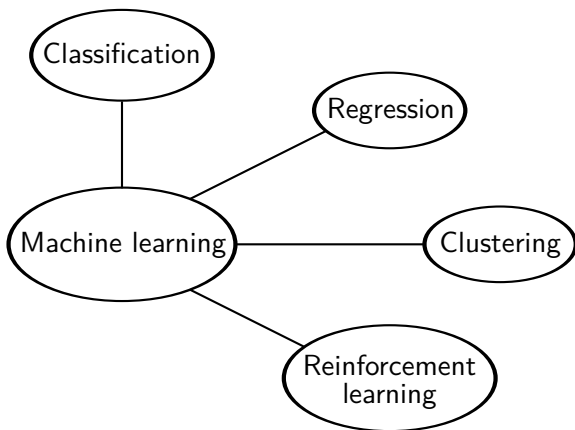
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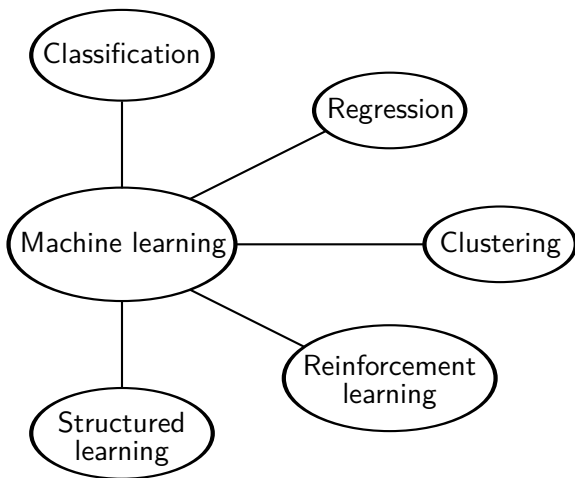
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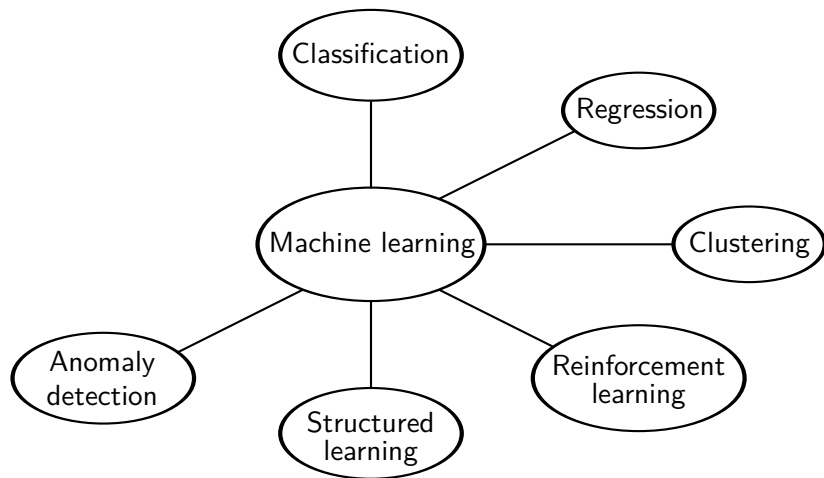
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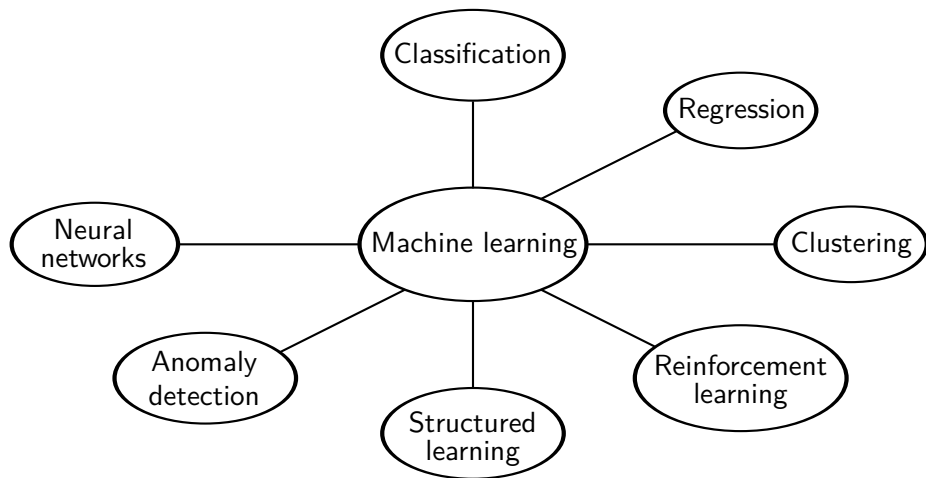
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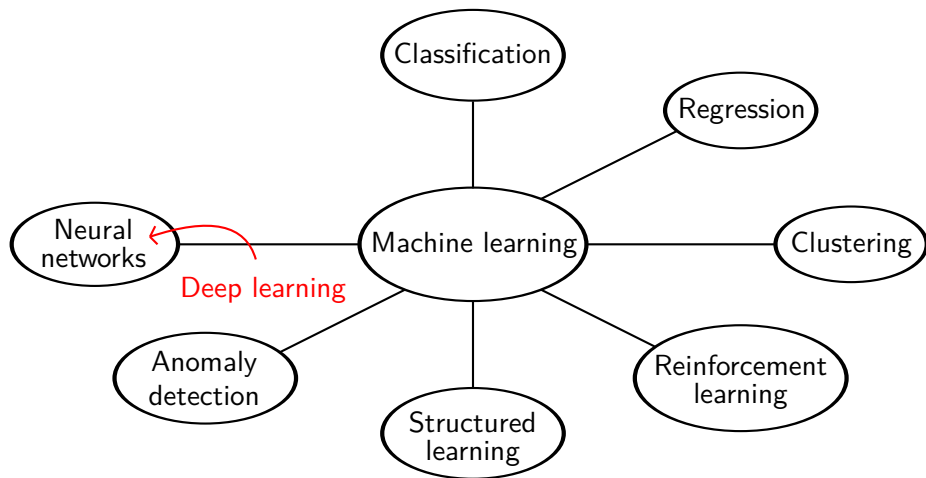




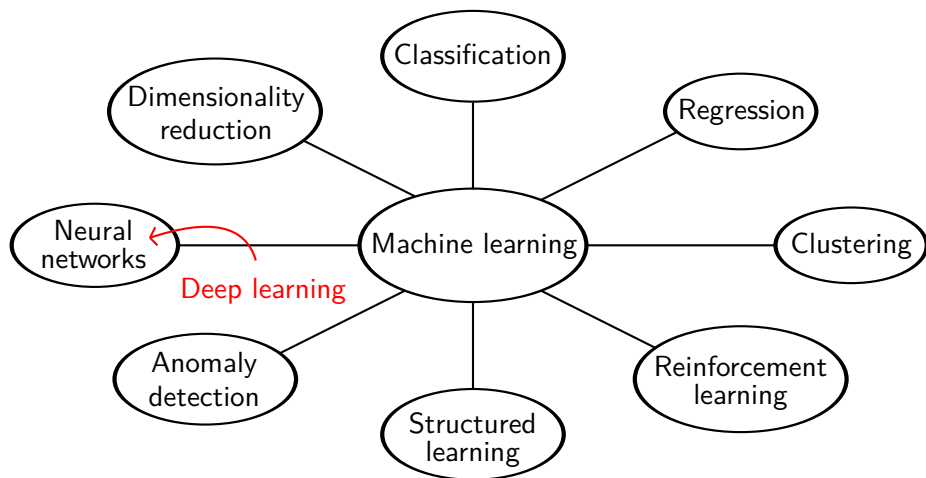


# Topics





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# Methods (1)

## Classification - Regression (Supervised learning)

- ▶ Decision trees
- ▶ Ensemble learning
- ▶ k-Nearest Neighbors
- ▶ Support/Relevance Vector Machine

## Clustering (Unsupervised learning)

- ▶ k-means
- ▶ Expectation-Maximization
- ▶ Mean-shift



# Methods (2)

## Dimensionality reduction

- ▶ Principal Component Analysis
- ▶ Independent Component Analysis
- ▶ Linear Discriminant Analysis
- ▶ t-distributed Stochastic Neighbor Embedding

## Structured prediction

- ▶ Bayesian network
- ▶ Conditional Random Field
- ▶ Hidden Markov Model



# Methods (3)

## Anomaly detection

- ▶ k-Nearest Neighbors
- ▶ Local outlier factor

## Neural network learning

- ▶ Auto-encoder
- ▶ Multi-Layer Perceptron
- ▶ Recurrent Neural Network
- ▶ Convolutional Neural Network





# Methods (4)

## Reinforcement learning

- ▶ Q-learning
- ▶ Temporal Difference



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# K-means (1)

## Goal

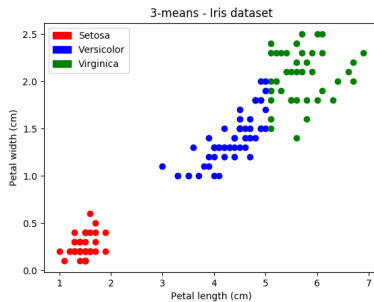
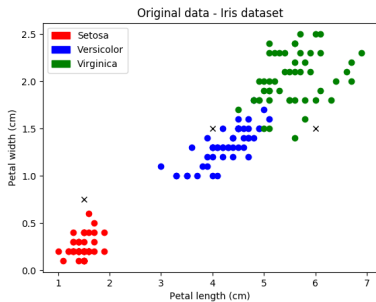
Iteratively divide data into  $K$  *clusters* so that the distance between each point within each cluster is minimal

## Two steps

- ▶ Assign each data point to an only cluster
- ▶ Update the centroid of each cluster



# K-means (2)



# Gaussian mixture (1)

## Goal

Estimate the mean and covariance of the multivariate Gaussians representing the data

## Expectation-Maximization algorithm

- Expectation

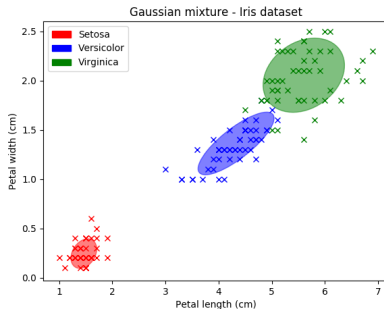
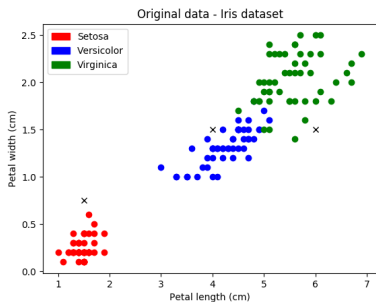
Compute expected value of likelihood function with respect to current parameters estimate

- Maximization

Estimate the parameters which maximize the expected value



# Gaussian mixture (2)



# PhD-related example

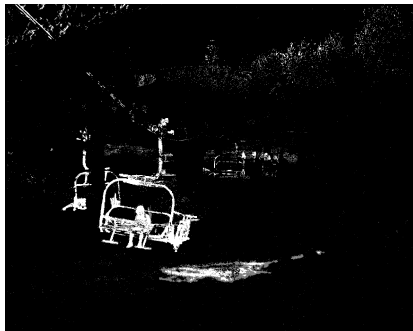


FIGURE – Foreground/Background/Shadow separation (Avoriaz - Lindarets)



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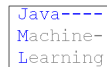
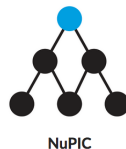
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# Machine learning tools



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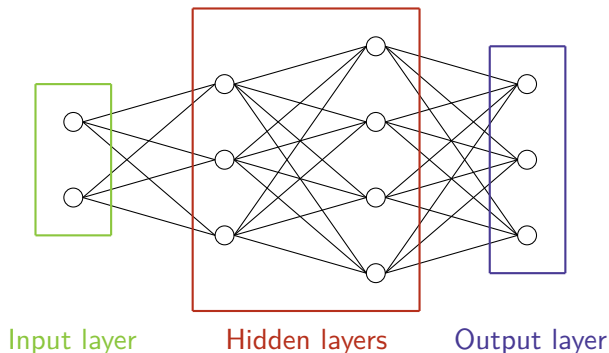
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# Basic architecture

- ▶ Inspired from the human brain
- ▶ Structure made up of layers of neurons
- ▶ Each neuron contain a value called **activation**



# Weights and biases

A **weight** is associated to each connection between neurons of two consecutive layers. This represents the influence of one neuron on another neuron.



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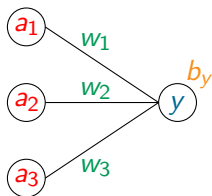
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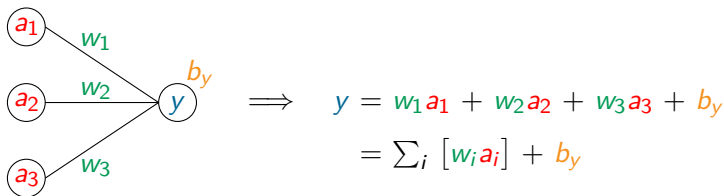
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⇒ solution : include an **activation function**  $\sigma$

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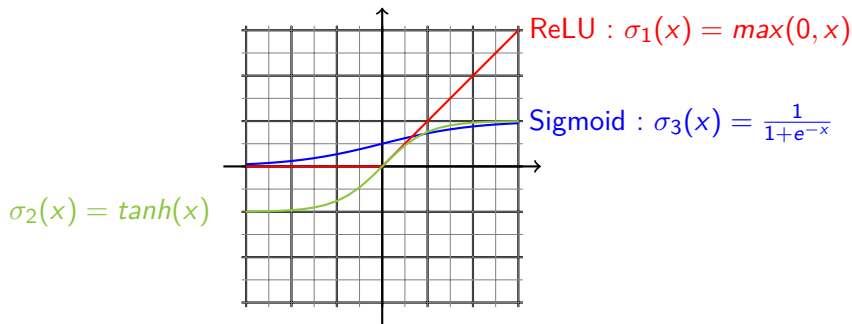


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# Gradient descent and back propagation (1)

Three steps when working with neural networks : (a) **training**, (b) **validation** and (c) **testing**. That means one set for each step.

- (a) The network is trained in a supervised way, *i.e.* with data for which groundtruth is available. The optimal weights are subsequently determined.
- (b) The network parameters are precisely computed : number of layers, size of each layer, ...
- (c) The network is tested with "real" data and its power is confirmed (or invalidated).



# Gradient descent and back propagation (2)

## Question

How to train a neural network ?

## Answer

Gradient descent algorithm alongside backpropagation

## Workflow

### I Propagation

- i Forward propagation (input → output)
- ii Error calculation according to known output by means of a *loss function*
- iii Backward error propagation in order to compute gradients (output → input)

### II Weights update

- i Weights modification according to gradients



# Different types of neural networks

- Convolutional Neural Network [CNN]
- Recurrent Neural Network [RNN]
- Long Short-Term Memory [LSTM]
- Auto-Encoder [AE]
- Multi-Layer Perceptron [MLP]



Thank you all for your  
attention !

