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MULTI-STAGE ACTION RECOGNITION CLASIFICATION

Goal: Improve action recognition using keypoints guidance

- Problem Recognise specific actions:
 - Jump
 - Pullup
 - Pushup
 - Wave
 - Sit
- We believed that keypoints might be helpfull











Why did we choose it?

Interested in computer vision

Found great database

Interesting use cases (cinect, CCTV)

HMDB51 Dataset

Przykładowe 16 klatek z jednego wideo Klasa: 'pullup' (etykieta: 26)



```
class ActionsBaselineModel(nn.Module):
    def init (self, num actions=5):
        super(). init ()
       base_model = models.resnet18(pretrained=True)
        self.cnn_backbone = nn.Sequential(*list(base_model.children())
        self.feature_dim = base_model.fc.in_features
        for param in self.cnn backbone.parameters():
            param.requires_grad = False
        self.classifier = nn.Sequential(
            nn.Linear(self.feature_dim, 1024),
            nn.BatchNorm1d(1024),
            nn.ReLU(),
            nn.Dropout(0.5),
            nn.Linear(512, 256),
            nn.ReLU(),
            nn.Linear(256, num_actions)
```

Baseline

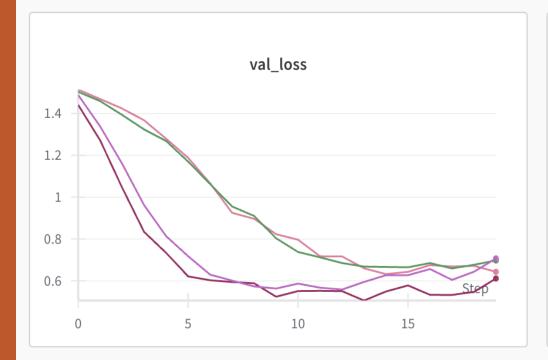
- Pretrained ResNet18 backbone
- Dense Linear layers for classifier
- Cross Entropy Loss
- Adam optimizer
- Input data Resized and Normalized
- Optional augmentation:
 - Blur, Grayscale, Jitter, Sharpness

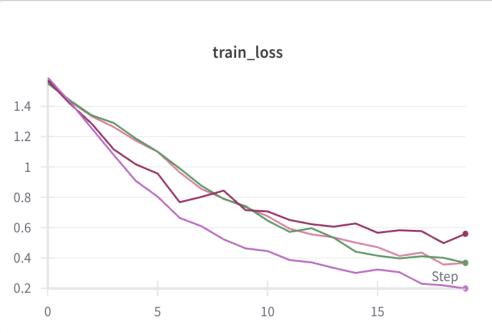
```
class ActionsFusionModel(nn.Module):
   def __init__(self, num_keypoints=NUM_KEYPOINTS, num_actions=10):
       super().__init__()
       base model = models.resnet18(pretrained=True)
       self.cnn_backbone = nn.Sequential(*list(base_model.children())[:-1])
       self.feature_dim_img = base_model.fc.in_features
       for param in self.cnn backbone.parameters():
           param.requires_grad = False
       self.keypoint_dim = num_keypoints * 2
       self.keypoint_mlp = nn.Sequential(
           nn.Linear(self.keypoint_dim, 128),
           nn.ReLU(),
           nn.Dropout(0.3),
           nn.Linear(128, 128),
           nn.ReLU()
       self.classifier = nn.Sequential(
           nn.Linear(self.feature_dim_img + 128, 512),
           nn.BatchNorm1d(512),
           nn.ReLU(),
           nn.Dropout(0.5),
           nn.Linear(512, 256),
           nn.ReLU(),
           nn.Linear(256, num_actions)
```

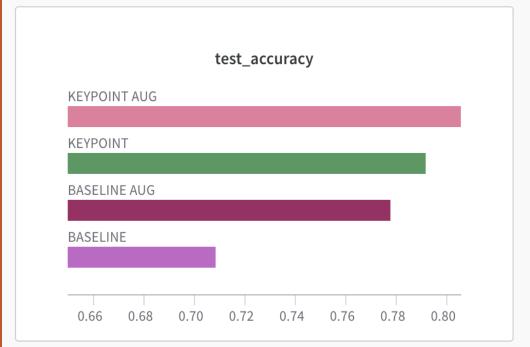
Keypoint Based

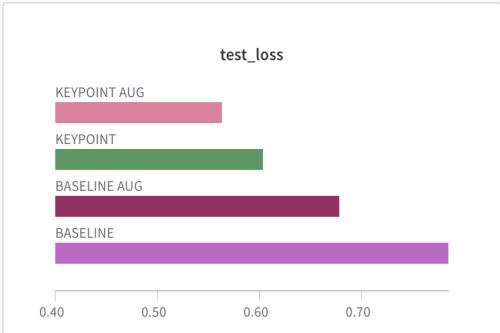
- Pretrained ResNet18 for images
- Dense layers for keypoints
- Both outputs combined with Dense Layers

Action Detection Comparison









Additionally... we trained keypoints

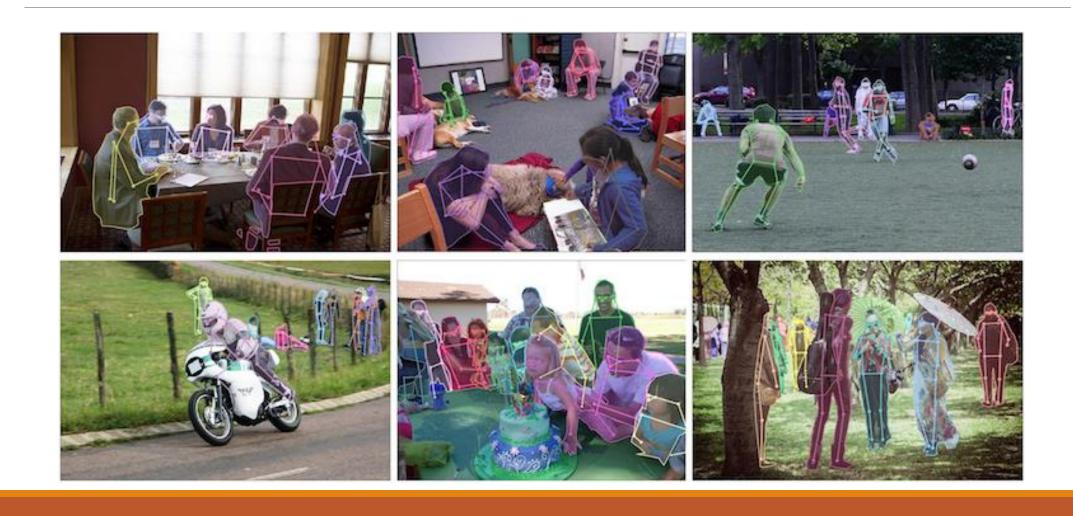
BASELINE

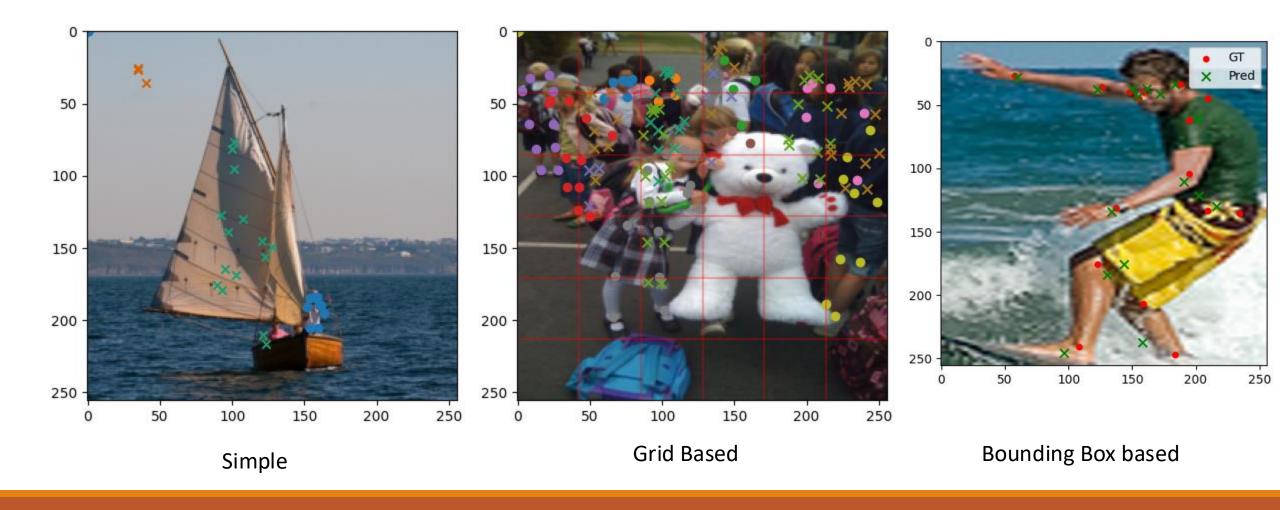
- Detect the keypoints of each person
- Directly on entire image
- Improve model with yolo style grid

IMPROVED VERSION

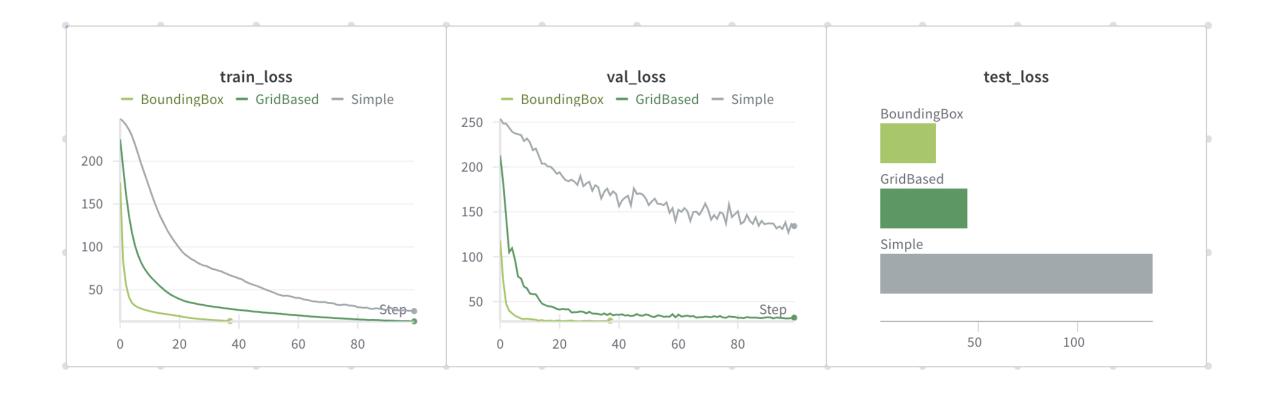
- Detect the bounding box of each person
- Train the model to predict keypoints on the cropped image
- Focused only on the person).

COCO Dataset





Keypoint Detection Comparison



Conclusions

What have you learned

Experience in computer vision problems and transfer learning.

What was good or bad

Model performed well and achieved higher accuracy than expected.

What could have been different

Utilizing models with more complex architecture and usage of more compute power.

What could you do next?

We could use RNN architecture to implement it in real-time action detection.

Links

- -Github: https://github.com/MaciejDengusiak/NN-Project
- -Dataset download: https://github.com/MaciejDengusiak/NN-Project/tree/main/data
- -Wandb report: https://api.wandb.ai/links/fejowo5522-/aai2ttsd