The European Commission's science and knowledge service

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Screening methods in sensitivity analysis

M. Ratto DYNARE Summer School Paris, June 14th 2018



Screening methods

Screening designs can be considered as the development of Design of Experiments (DOE)

DOE determines how much the variables involved in a physical experiment affect one or more measurements

The setup for sensitivity analysis of simulation results is similar to that of physical experimentation but...



Screening methods

.... simulations allows to explore more complex system with many more variables

screening designs

able to "screen" a subset of few important input variables among the many (hundreds, thousands) often contained in models

Goal: Model simplification / Model lumping / Pre-calibration



Screening methods

How much information sensitivity analysis reveals depends on:

- > the number of sample points simulated
- where they are located

Screening methods aim to extract sensitivity information with a small number of sample points (low computational cost)

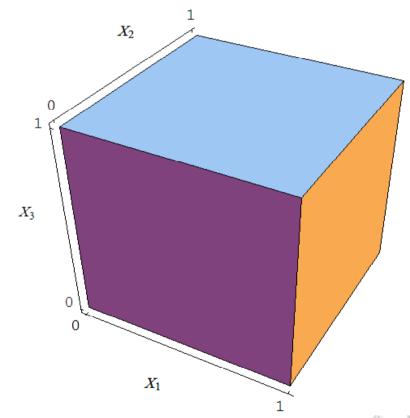


Fractional factorial sampling

The Full Factorial Design

A 2-Level Full Factorial Design for 3 parameters

X_1	X_2	X_3
1	1	1
-1	1	1
1	-1	1
-1	-1	1
1	1	-1
-1	1	-1
1	-1	-1
-1	-1	-1





Fractional factorial sampling

A disadvantage of a factorial design is the enormous number of simulations required

Using 2 levels: 10 parameters \rightarrow 2¹⁰ = 1024 simulations

20 parameters \rightarrow more than a million!!

Solution

To select only a fraction of these simulations to generate a smaller design that can still produce valuable results



Fractional factorial sampling

A Fractional Factorial Design for 7 Parameters

X_1	X_2	$X_3 = X_1 X_2$	X_4	$X_5 = X_1 X_4$	$X_6 = X_2 X_4$	$X_7 = X_1 X_2 X_4$
1	1	1	1	1	1	1
-1	1	-1	1	-1	1	-1
1	-1	-1	1	1	-1	-1
-1	-1	1	1	-1	-1	1
1	1	1	-1	-1	-1	-1
-1	1	-1	-1	1	-1	1
1	-1	-1	-1	-1	1	1
-1	-1	1	-1	1	1	-1



(Morris, 1991)

The EE method can be seen as an extension of a derivative-based analysis

Problems related to a derivative-based approach:

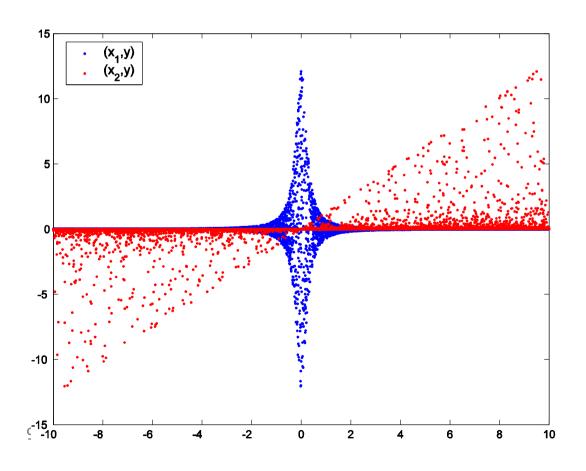
- > small perturbation around base values
- > local measure

Derivative = 0 only implies that a factor is locally non influent



Example

$$y = x_2 * \left\{ \frac{\pi}{4} * \left[1 + \left(4 * x_1 \right)^2 \right] \right\}^{-1}$$



Derivatives

$$\left. \frac{\partial y}{\partial x_1} \right|_{x_1 = x_2 = 0} = 0$$

$$\frac{\partial y}{\partial x_2}\bigg|_{x_1=x_2=0} = \frac{4}{\pi}$$

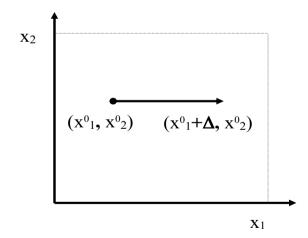


(Morris, 1991)

Model
$$y = y(X_1,...,X_k)$$

Elementary Effect for the ith input factor in a point X^o

$$EE_{i}(X_{1}^{0},...,X_{k}^{0}) = \frac{y(X_{1}^{0},X_{2}^{0},...,X_{i-1}^{0},X_{i}^{0} + \Delta,X_{i+1}^{0},...,X_{k}^{0}) - y(X_{1}^{0},...,X_{k}^{0})}{\Delta}$$



 Δ is larger than in local methods



Each input varies across *l* possible values (levels) within its range of variation

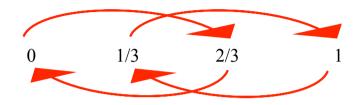
$$x_i$$
 U(0,1) $l = 4 \rightarrow l_1 = 0$ $l_2 = 1/3$ $l_3 = 2/3$ $l_4 = 1$

Distribution not uniform \rightarrow levels correspond to distribution quantiles

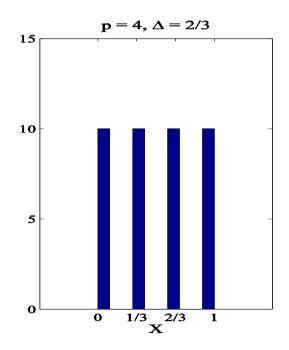
The value of Δ (sampling step) is a function of l

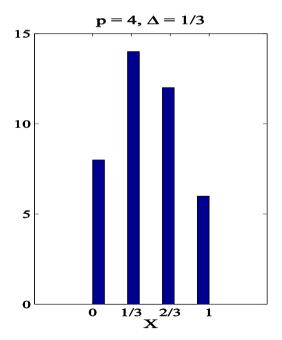
Optimal choice for Δ is $\Delta = l / 2(l-1)$







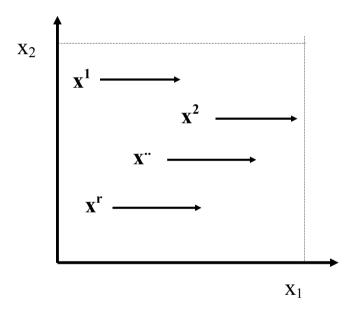






The EE_i is still a local measure

Solution: take the average of several EE



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r elem. effects \mathrm{EE^1}_i \mathrm{EE^2}_i ... \mathrm{EE^r}_i are computed at \mathbf{X}^1 , ... , \mathbf{X}^r and then averaged
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Average of $|EE_i|'s \rightarrow \mu^*(x_i)$

μ*(x_i) is effective in identifying irrelevant inputs

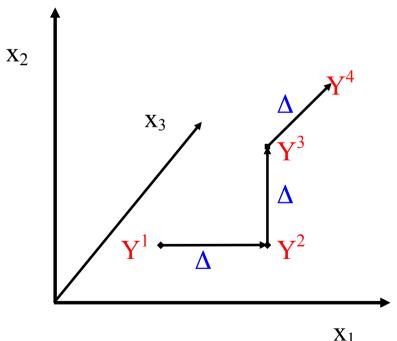


Implementing the EE method

(Morris, 1991)

Goal: estimate r EE's per input

Morris builds *r* trajectories of (k+1) sample points each providing one EE per input



$$\mathsf{EE_1}_1 = (\mathsf{Y^2} - \mathsf{Y^1}) \ / \ \Delta$$

$$EE_2^1 = (Y^3 - Y^2) / \Delta$$

$$\mathsf{EE}^{1}_{3} = (\mathsf{Y}^{4} - \mathsf{Y}^{3}) / \Delta$$

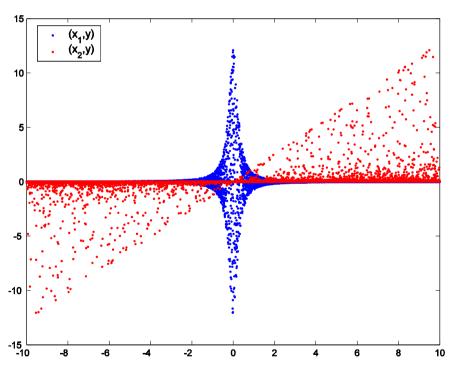
Total cost = r(k + 1)r is in the range 4 -20

A trajectory of the EE design



The example

$$y = x_2 * \left\{ \frac{\pi}{4} * \left[1 + \left(4 * x_1 \right)^2 \right] \right\}^{-1}$$



Derivatives

$$\frac{\partial y}{\partial X_1}(0,0) = 0 - \frac{\partial y}{\partial X_2}(0,0) = \frac{4}{\pi}$$

$$EE (l=4, r=10)$$

$$\mu * (x_1) = 0.070$$

$$\mu * (x_2) = 0.024$$





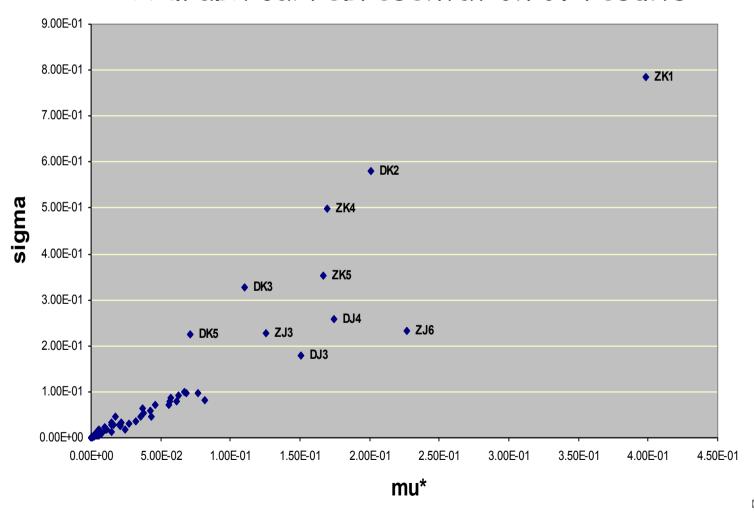
May I gain additional sensitivity information from the EE_i's?

What type of information I gain from the st. dev. σ of the EE_i's?

 σ is a measure of the sum of all interactions of x_i with other factors and of all its nonlinear effects



A graphical representation of results



nmission

An analytical example (Morris, 1991)

$$y = \beta_0 + \sum_{i=1}^{20} \beta_i w_i + \sum_{i< j}^{10} \beta_{i,j} w_i w_j + \sum_{i< j< l}^{10} \beta_{i,j,l} w_i w_j w_l$$

$$w_1, w_2, ..., w_{10}$$
 in [-1,1]

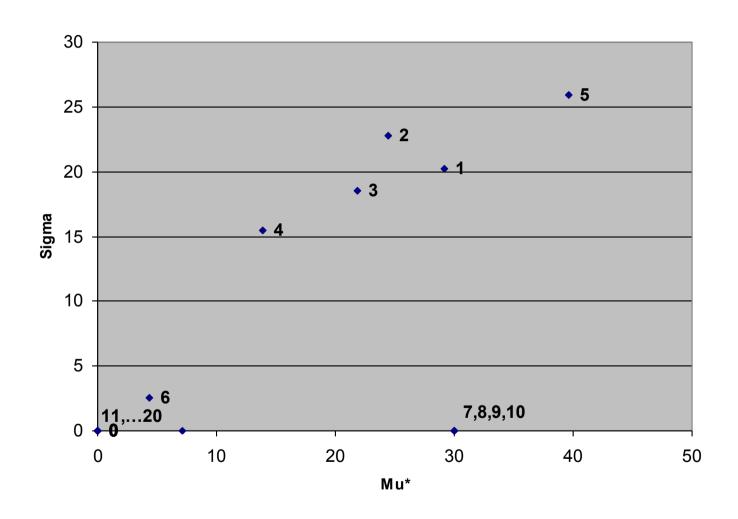
$$w_i = 2 (x_i - 0.5)$$
 for $i \neq 3$
 $w_3 = 2 (1.1x_3/(x_3 + 0.1) - 0.5)$
 $x_i \sim U[0; 1]$

$$\beta_i = -15;$$
 $i = 1, 2$
 $\beta_{i,j} = 30;$
 $i, j = 3, 4$
 $\beta_{i,j,l} = 10;$
 $i, j, l = 1, ..., 4$

Other coefficients $\sim N(0,1)$



An analytical example



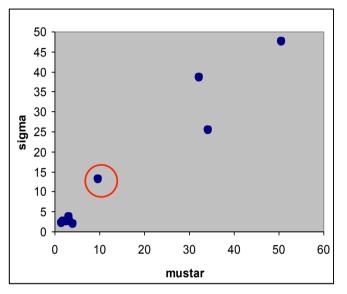
$$r=4$$

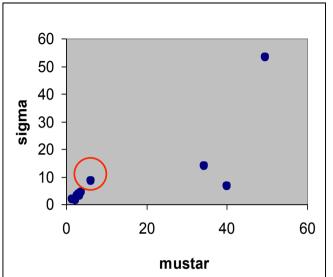
$$l=4$$

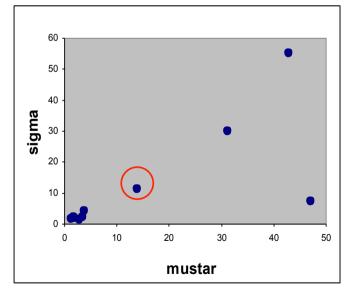
$$\Delta = 2/3$$

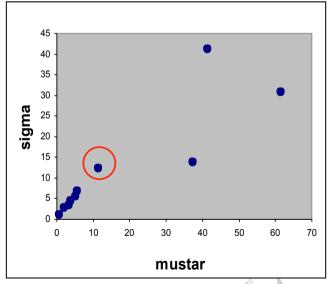


"missed" factors, r=4



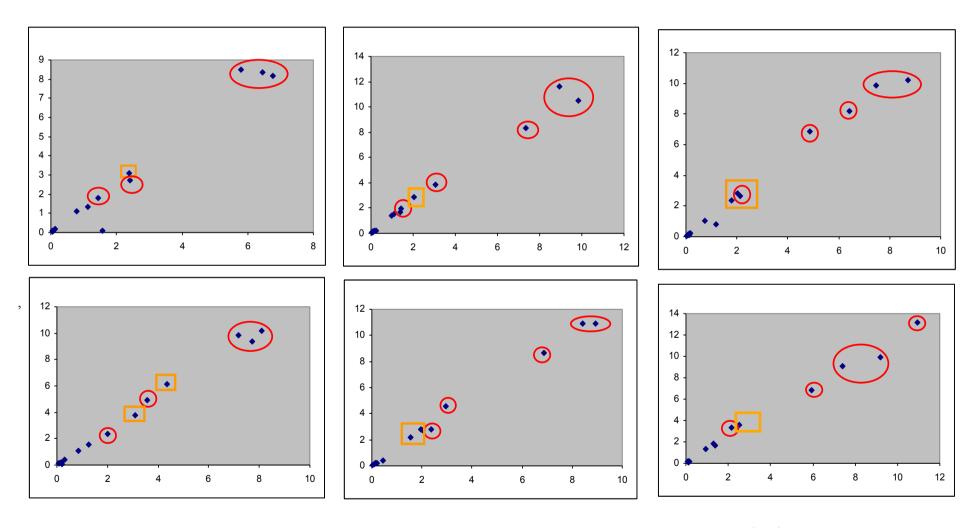








Test case 3





Ex-ante identification screening ...

Lacks the collinearity component (only sensitivity effect).

Potential for very expensive ABM models?



Covariance/autocovariance matrices among observed variables y_t:

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corr(y_t); corr(y_t, y_{t-k});
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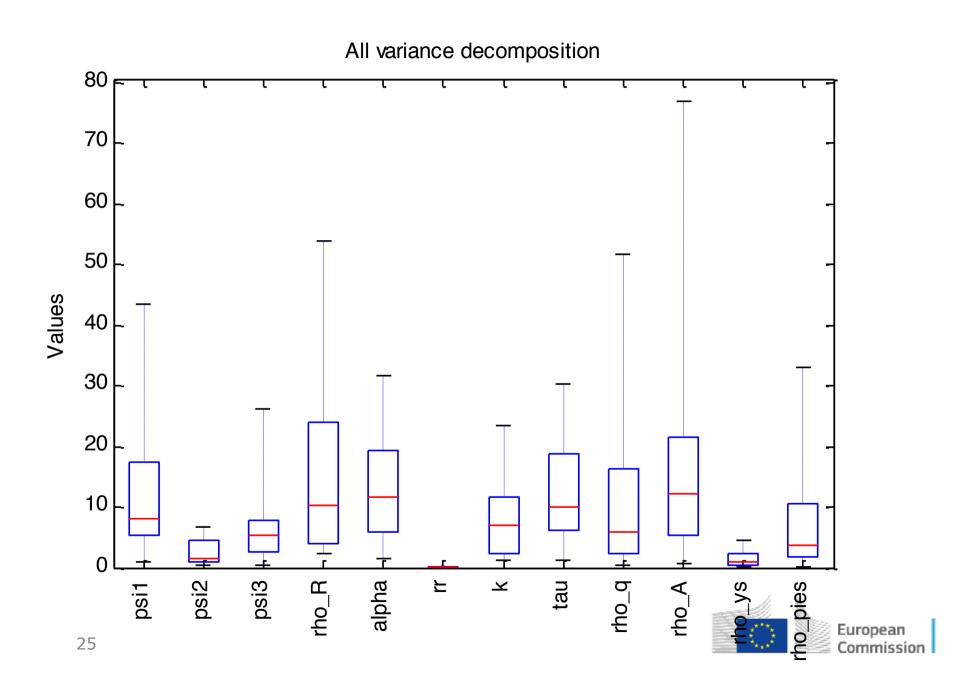
[nobs x (nobs-1)/2];

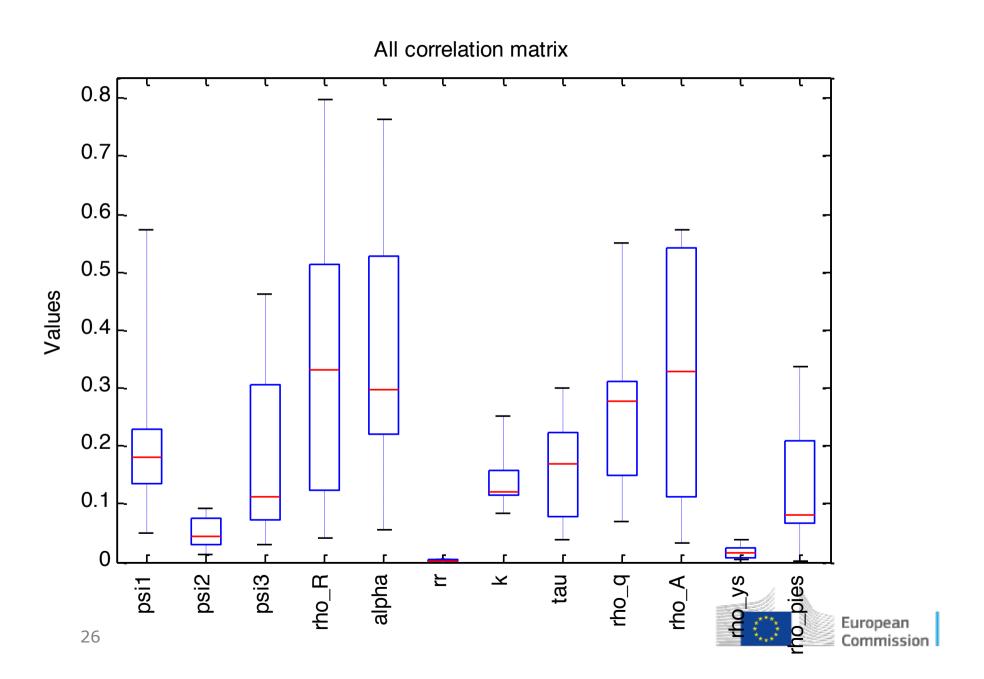
[nobs x nobs]

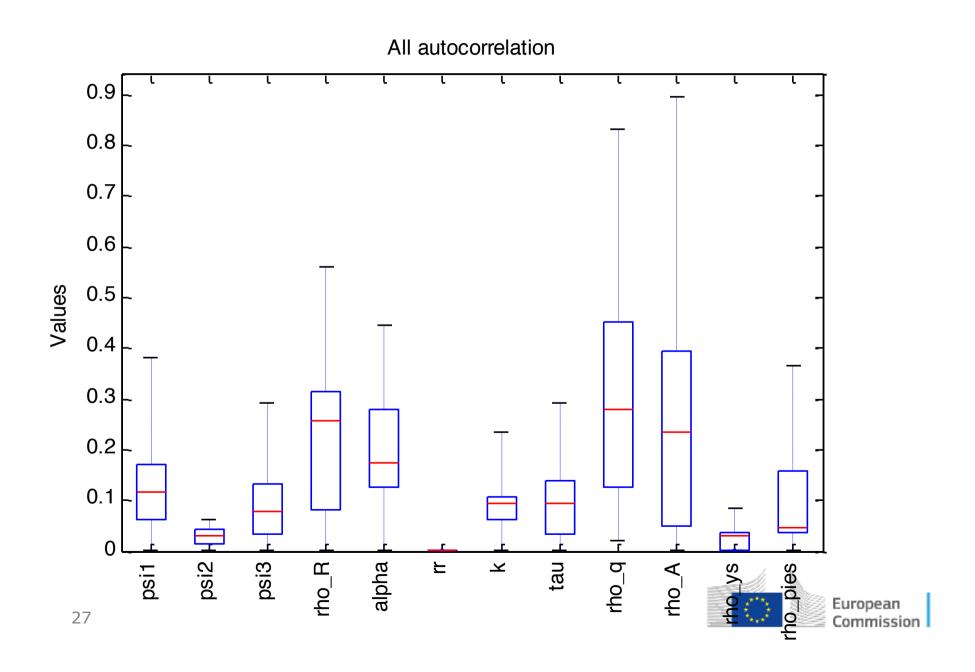


Under Gaussian hypotheses, first and second moments contain all information that can be used for the estimation of model parameters









Conclusions

Screening designs are useful to "screen" a subset of few important input variables among the many contained in models

Often they rely on the assumption that the number of important parameters is small

Their feature is the low computational cost (low number of model evaluations)



Conclusions

Quick screening tests for ex-ante identification (sensitivity component) of DSGE models



Mapping the reduced form of RE models

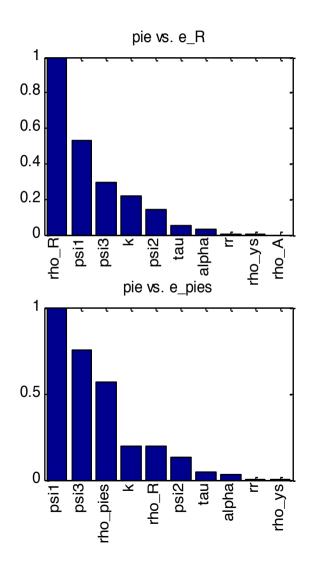
Relationship between the reduced form of a rational expectation model and the structural coefficients.

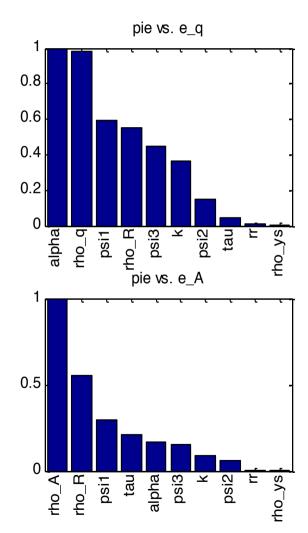
let the reduced form be $y_t=Ty_{t-1}+Bu_t$,

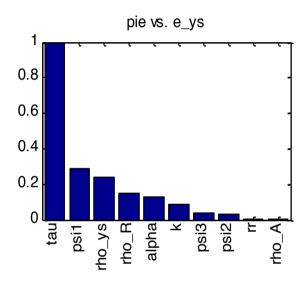
'outputs' Y of our analysis will be the entries in the transition matrix $T(X_1,...,X_k)$ or in the matrix $B(X_1,...,X_k)$.



LS 2005: pie vs. shocks

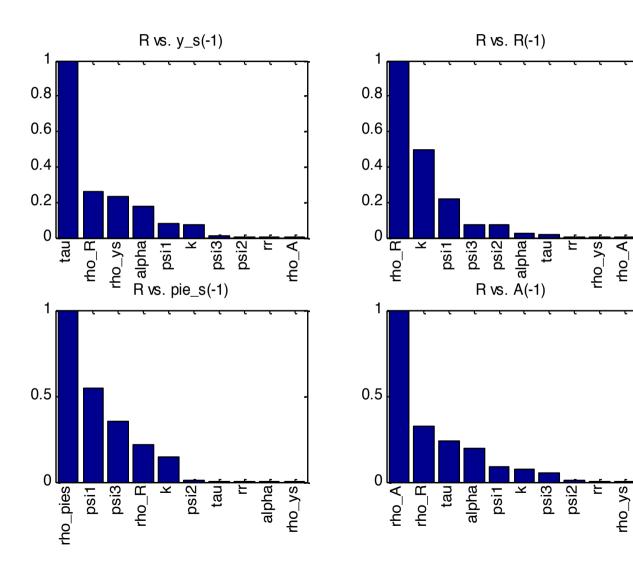


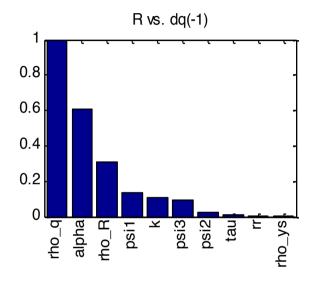






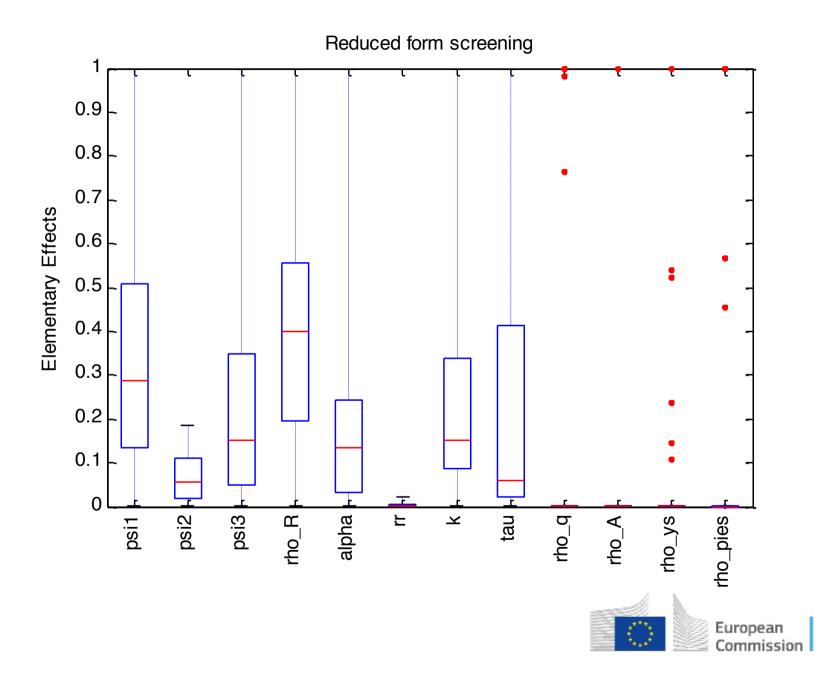
LS 2005: pie vs. lags







LS 2005: overall picture



References

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Saltelli, A., Tarantola, S., Campolongo, F., and Ratto, M., 2005, Sensitivity Analysis for Chemical Models, Chemical Reviews, 105(7), pp 2811 - 2828

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