STM32 CNC 6 Axis Card

Features

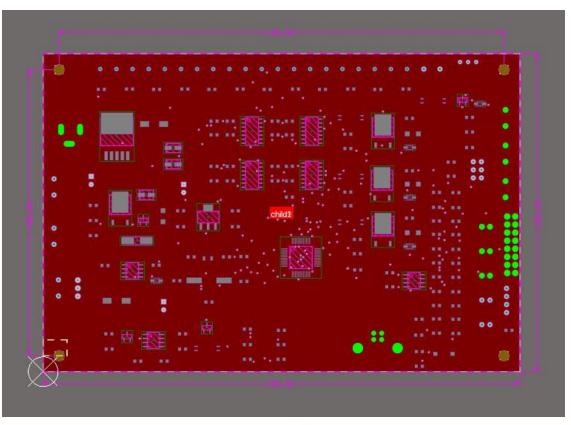
- ❖ Adopt STM32 32 bits high-speed processor, Arm-cortex-m.
- Compatible with Fluidnc, Candle, Bcnc, CNC3D COMMANDER...

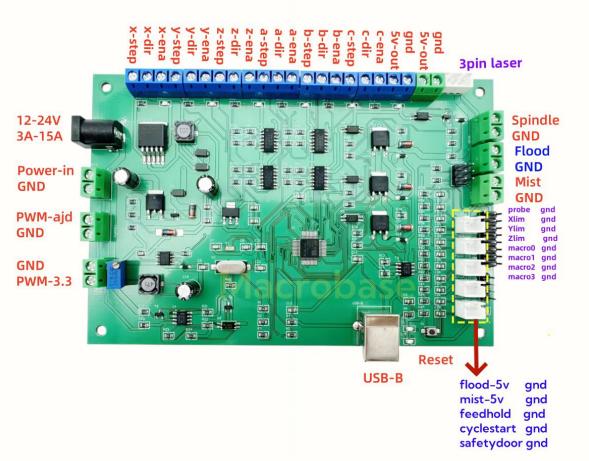
(GRBL only 1.1f is available)

- Support XYZABC six stepper drivers.
- Support Homing, software/hardware endstop, Z probe.
- Support 3pin laser.Adjustable voltage PWM output.
- Support 12V-24V DC

Auto-cut off power when voltage exceeding 30V.

Automatically select external power supply as the main control input power, and prevent reverse power transmission, protect USB port.





PROBE Z-probe
X-LIM X limit, On
Y-LIM Y limit, On
Z-LIM Z limit, On
GND XYZ axis lin

GND XYZ axis limit com, Z-probe PWM-ADJ PWM voltage adjustment

COM PUL-,EAN-,DIR- of stepper drivers

X-PUL X-PUL+
X-ENA X-ENA+
X-DIR X-DIR+

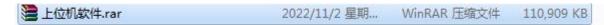
PWM3.3 Output 3.3v PWM

Install STM32 USB Driver



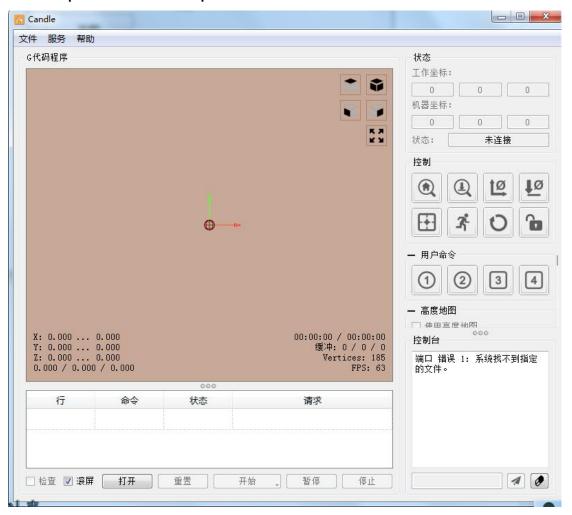
Software

Candle, CNC3dCommander and Bcnc.

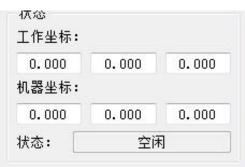


1.Candle

Unzip candle and open candle.exe







2.BCNC

Plug control board to PC via USB cable, and enter bcnc.exe



Click CAM, select language.

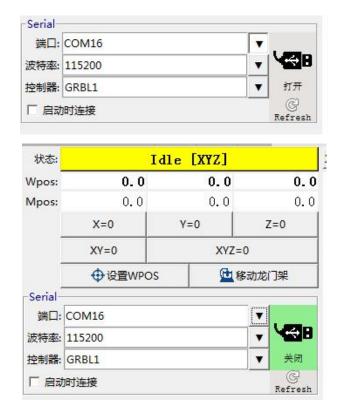


Enable 6 axis display, then reboot software.



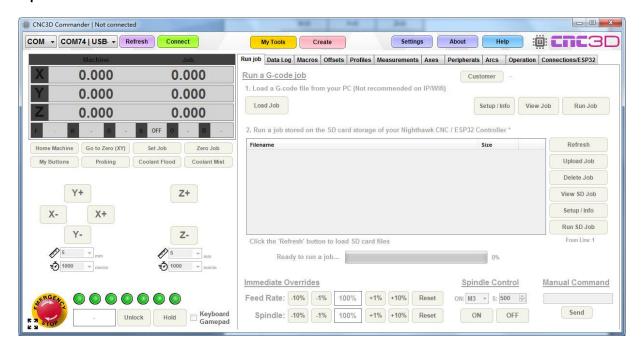
Click file, select COM and open it.





3.CNC3d Commander

Open CNC3dcommander as below



Connect control board and reflash.



Parameters configuration

You can use PC software such as GRBLaser to config the parameters by sending commands, here is the list:

COMMANDS	PARAMETERS	DESCRIPTION
\$0	10	Sets time length per step. Minimum 3usec.
\$1	5	Sets a short hold delay when stopping to let dynamics settle before disabling steppers. Value 255 keeps motors enabled with no delay.
\$2	0	Inverts the step signal. Set axis bit to invert (00000ZYX). The details can refer to XYZ-TABLE
\$3	1	Inverts the direction signal. Set axis bit to invert (00000ZYX). The details can refer to XYZ-TABLE
\$4	0	Inverts the stepper driver enable pin signal.
\$5	1	Inverts the all of the limit input pins.
\$6	0	Inverts the probe input pin signal.
\$10	1	Alters data included in status reports.
\$11	0.01	Sets how fast Grbl travels through consecutive motions. Lower value slows it down.
\$12	0.002	Sets the G2 and G3 arc tracing accuracy based on radial error. Beware: A very small value may effect performance.
\$13	0	Enables inch units when returning any position and rate value that is not a settings value.
\$20	0	Enables soft limits checks within machine travel and sets alarm when exceeded. Requires homing.
\$21	0	Enables hard limits. Immediately halts motion and throws an alarm when switch is triggered.
\$22	0	Enables homing cycle. Requires limit switches on al axes.
\$23	0	Homing searches for a switch in the positive direction. Set axis bit (00000ZYX) to search in negative direction. The details can refer to XYZ-TABLE
\$24	300	Feed rate to slowly engage limit switch to determine its location accurately.
\$25	1000	Seek rate to quickly find the limit switch before the slower locating phase.
\$26	250	Sets a short delay between phases of homing cycle to let a switch debounce.
\$27	1	Retract distance after triggering switch to disengage it. Homing will fail if switch isn't cleared.
\$28	1000	Modify the output frequency of the spindle, the input range is 0-100000
\$30	1000	Maximum spindle speed. Sets PWM to 100% duty cycle.
\$31	0	Minimum spindle speed. Sets PWM to 0.4% or lowest duty cycle.
\$32	1	Enables laser mode. Consecutive G1/2/3 command will not halt when spindle speed is changed.
\$100	80	X-axis travel resolution in steps per millimeter.
\$101	80	Y-axis travel resolution in steps per millimeter.
\$102	80	Z-axis travel resolution in steps per millimeter.
\$110	6000	X-axis maximum rate. Used as G0 rapid rate.
\$111	6000	Y-axis maximum rate. Used as G0 rapid rate.
\$112	6000	Z-axis maximum rate. Used as G0 rapid rate.
\$120	500	X-axis acceleration. Used for motion planning to not exceed motor torque and lose steps.
\$121	500	Y-axis acceleration. Used for motion planning to not exceed motor torque and lose steps.
\$122	500	Z-axis acceleration. Used for motion planning to not exceed motor torque and lose steps.
\$130	285	Maximum X-axis travel distance from homing switch. Determines valid machine space for soft- limits and homing search distances.
\$131	272	Maximum Y-axis travel distance from homing switch. Determines valid machine space for soft- limits and homing search distances.
\$132	80	Maximum Z-axis travel distance from homing switch. Determines valid machine space for soft- limits and homing search distances.

XYZ TABLE

∃ README.md

Directions	Parameters
X+ Y+ Z+	0
X- Y+ Z+	1
X+ Y- Z+	2
X- Y- Z+	3
X+ Y+ Z-	4
X- Y+ Z-	5
X+ Y- Z-	6
X- Y- Z-	7