

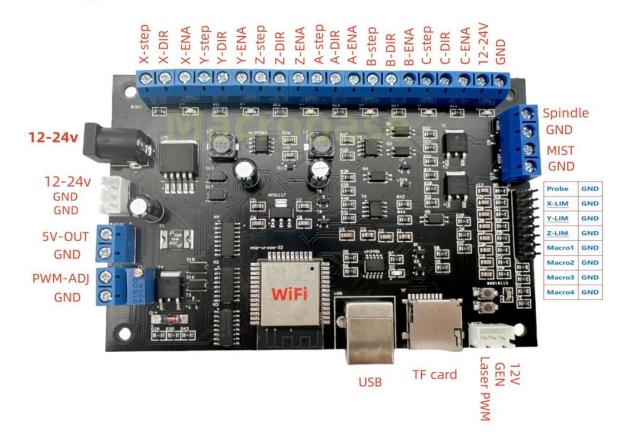
#### **Features**

- ❖ Adopting dual-core ESP32 16-bit high-speed processor
- Compatible with GRBL software, Such as Candle, Bcnc, CNC3D COMMANDER...
- Support six stepper drivers
- Support Homing, software/hardware endstop, Z probe.
- Support hotspot, Wifi to control
- Support 3pin laser.Adjustable voltage PWM output.
- Support 12-24V DC

Auto-cut off power when voltage exceeding 30V.

Automatically select external power supply as the main control input power, and prevent reverse power transmission, protect USB port.

# Wiring



PROBE Z-probe

X-LIM X limit, Always on

Y-LIM Y limit, Always on

Z-LIM Z limit, Always on

GND XYZ axis com, probe

PWM-OUT PWM output

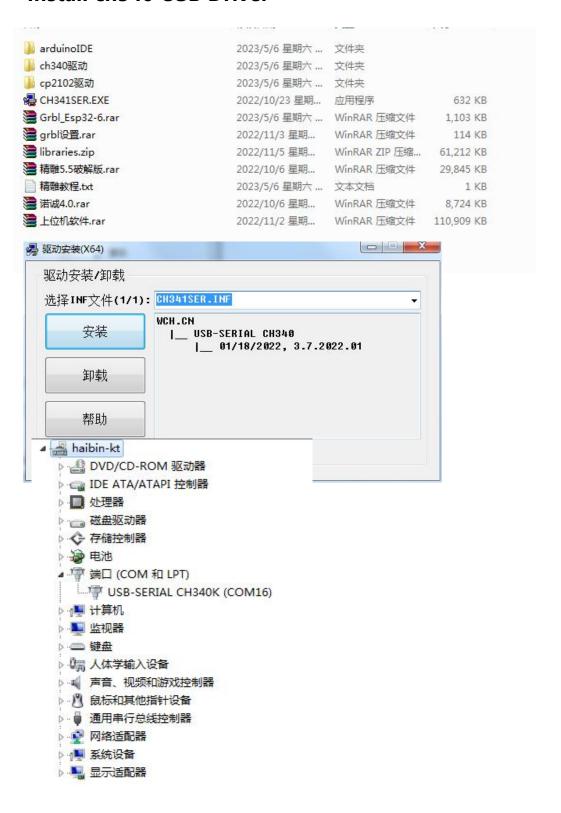
GND PWM ground

PWM-ADJ PWM adjustable

GND All drivers PUL-,EAN-,DIR-

X-STEP X-PUL+ X-EAN X-ENA+ X-DIR X-DIR+

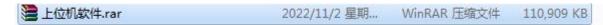
#### Install ch340 USB Driver



See CH340K, successfully install.

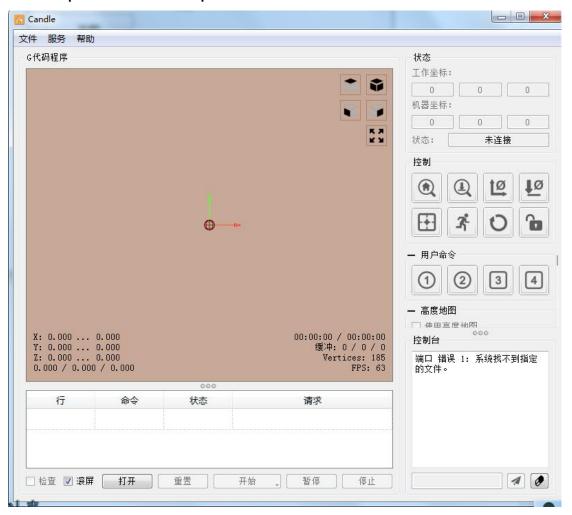
### **Software**

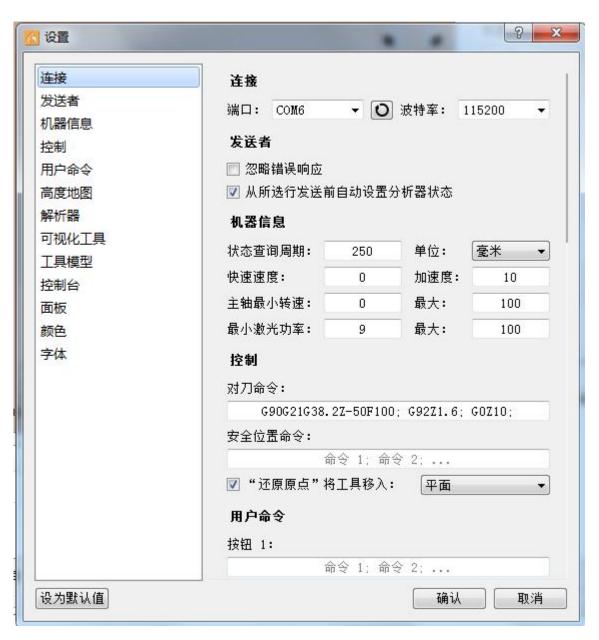
Candle, CNC3dCommander and Bcnc.

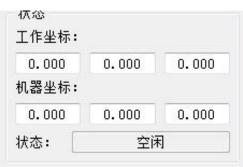


#### 1.Candle

Unzip candle and open candle.exe







#### 2.BCNC

Plug control board to PC via USB cable, and enter bcnc.exe



### Click CAM, select language.

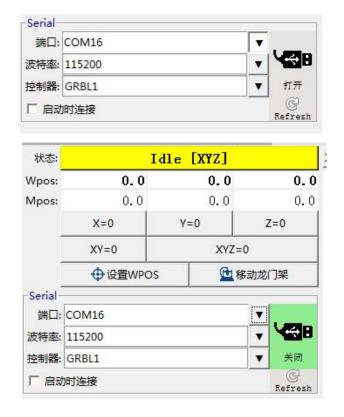


### Enable 6 axis display, then reboot software.



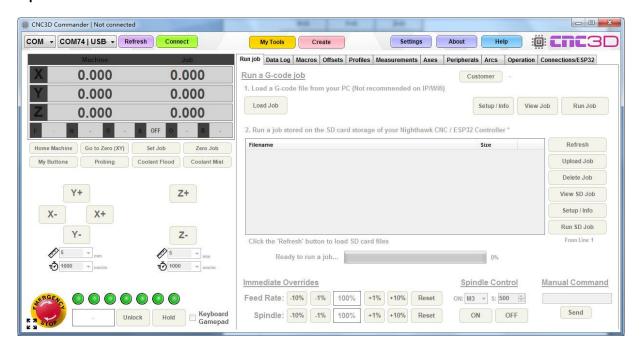
### Click file, select COM and open it.





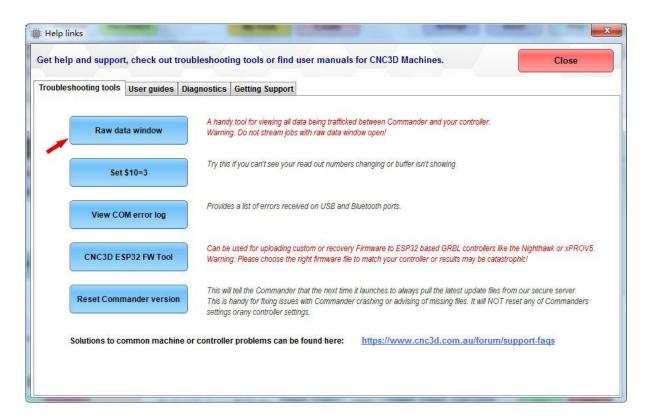
#### 3.CNC3d Commander

### Open CNC3dcommander as below



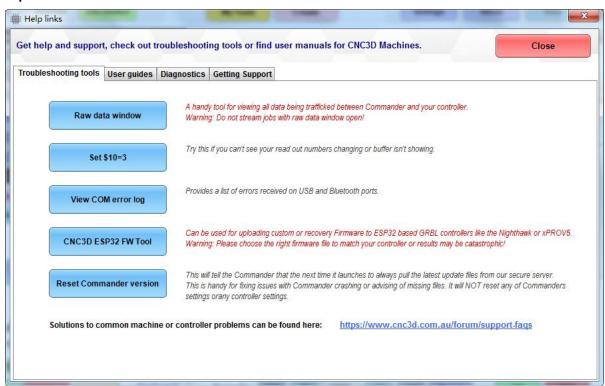
#### Connect control board and reflash.







## Update and connect



#### Raw data window



**Enter below** 

\$sta/ssid=wifi

\$sta/password=wifi

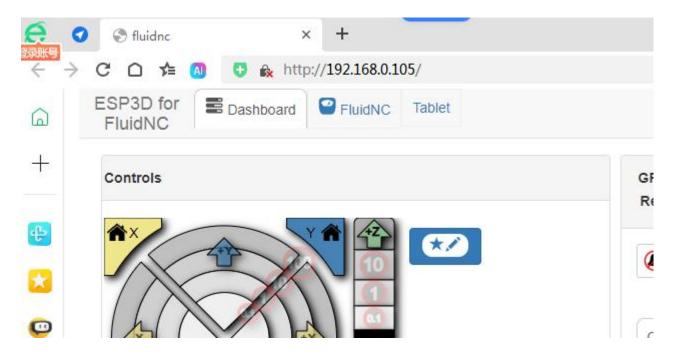
\$bye

```
<< $sta/ssid=haibin-kt
>> ok
<< $sta/password=hxtbc13363258373
>> ok
<< $bye</pre>
```

# Find wifi ip

```
>> [MSG:INFO: Connected = IP is 192.168.0.105]
>> [MSG:INFO: WiFi on]
>> [MSG:INFO: Start mDNS with hostname:http://fluidnc.local/]
>> [MSG:INFO: SSDP Started]
>> [MSG:INFO: HTTP started on port 80]
>> [MSG:INFO: Telnet started on port 23]
>> Grbl 3.0 [FluidNC v3.0.x (noGit) (wifi) '$' for help]
```

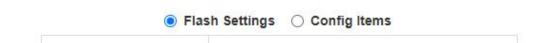
# Open Browser and enter the ip.

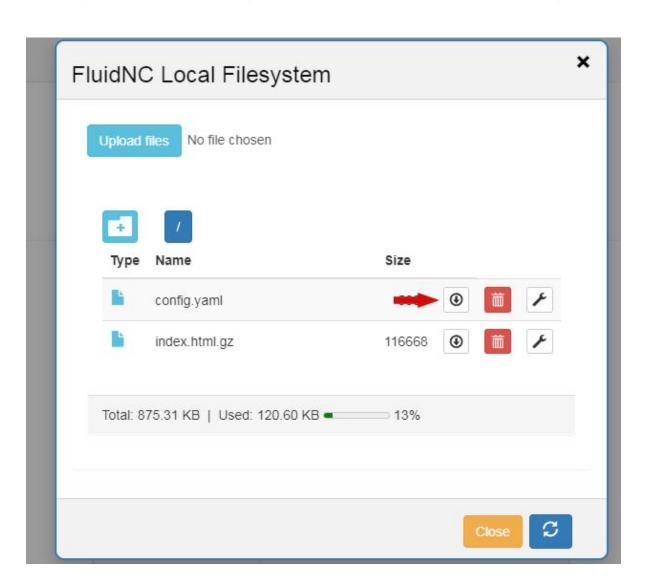


### Fluidnc

# FluidNC Settings







```
board: 6 Pack₽
name: 6 Pack StepStick XYZABC↔
stepping:⊬
engine: I2S_STREAM₽
idle_ms: 250₽
 pulse_us: 4₽
 dir_delay_us: 6€
 disable_delay_us: 0₽
axes:⊬
 shared_stepper_disable_pin: NO_PIN↔
  steps_per_mm: 800.000
   max_rate_mm_per_min: 5000.000 &
   acceleration_mm_per_sec2: 100.000 ₽
   max_travel_mm: 300.000 +
   soft_limits: false
   homing:
    cycle: 1
    positive_direction: false +
    mpos_mm: 0.000 ↔
    feed_mm_per_min: 100.000 +
    seek_mm_per_min: 200.000 🕡
     settle_ms: 500 ↔
     seek_scaler: 1.100 +
     feed_scaler: 1.100 ↔
   motorO:⊬
     limit_neg_pin: NO_PIN +
```

#### More refer to

http://wiki.fluidnc.com/en/config/overview