

$$\underline{v} = w \underline{k} \times r$$

Regne ut sirkelavstanden rundt en sirkel med radius  $a$

$$r(\theta) = a \cos \theta \underline{i} + a \sin \theta \underline{j}$$

$$\underline{v}(\theta) = -w a \sin \theta \underline{i} + w a \cos \theta \underline{j}$$

$$d\underline{r} = (-a \sin \theta \underline{i} + a \cos \theta \underline{j}) d\theta$$

$$\underline{v} \cdot d\underline{r} = (w a^2 \sin^2 \theta + w a^2 \cos^2 \theta) d\theta$$

$$\text{Sirkelavstanden } C = \oint_C \underline{v} \cdot d\underline{r} = \int_0^{2\pi} w a^2 d\theta$$

Areal til sirkelen  $A = \pi a^2$

$$\frac{C}{A} = \frac{2\pi w a^2}{\pi a^2} = 2w$$

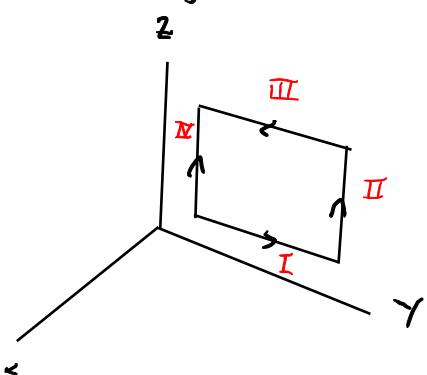
$$w = \frac{C}{2A}$$

# Definition von viskosität

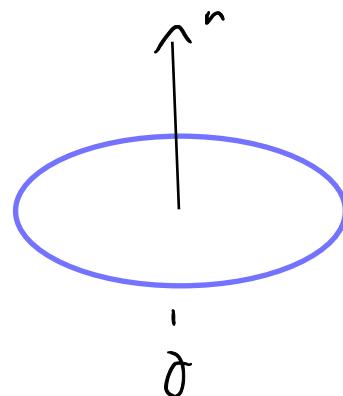
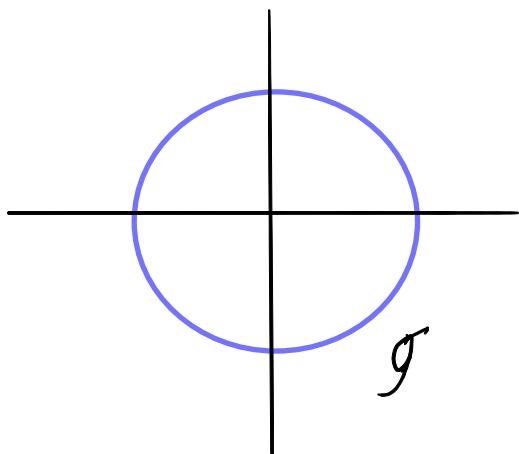
$$n \cdot \text{Curl } \underline{v} = \lim_{A \rightarrow 0} \frac{1}{A} \oint \underline{v} \cdot d\underline{r}$$

$(x_0, y_0, z_0)$

rechteck mete sich  $\Delta y, \Delta z$



$\underline{n} = \underline{i}$



side	$r(t)$	$dr$	$\underline{v} \cdot dr$	$\int \underline{v} \cdot dr$
I	$x_0 \underline{i} + (y_0 + t) \underline{j} + (z_0 - \frac{\Delta z}{2}) \underline{k}$ for $\frac{\Delta y}{2} < t < \frac{\Delta y}{2}$	$\underline{j} dt$	$v_y dt$	$\int_{-\frac{\Delta y}{2}}^{\frac{\Delta y}{2}} v_y dt \approx v_y (y_0, z_0 - \frac{\Delta z}{2}) \Delta y$
II	$x_0 \underline{i} + (y_0 - t) \underline{j} + (z_0 + \frac{\Delta z}{2}) \underline{k}$ for $-\frac{\Delta y}{2} < t < \frac{\Delta y}{2}$	$-\underline{j} dt$	$-v_y dt$	$\int_{-\frac{\Delta y}{2}}^{\frac{\Delta y}{2}} -v_y dt \approx -v_y (x_0, y_0, z_0 + \frac{\Delta z}{2}) \Delta y$
.				

$$\left( \int_{\text{I}} + \int_{\text{II}} \right) \nabla \cdot \underline{dr} = \left\{ V_y(x_0, y_0, z_0 - \frac{\Delta z}{2}) - V_y(x_0, y_0, z_0 + \frac{\Delta z}{2}) \right\}$$

$$\approx - \frac{\partial V_y}{\partial z} \left( A y \Delta z \right)_{(x_0, y_0, z_0)}$$

$$\left( \int_{\text{II}} \int_{\text{IV}} \right) \nabla \cdot \underline{dr} \approx + \frac{\partial V_z}{\partial y} A y \Delta z$$

$V$ : har formet

$$C: \oint \nabla \cdot \underline{dr} \approx \left( \frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z} \right) A y \Delta z$$

$$A = \Delta y \Delta z$$

$$\frac{C}{A} \approx \frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z}$$

$$\text{i} \text{ const } V = \lim_{A \rightarrow 0} \frac{1}{A} \oint \nabla \cdot \underline{dr} = \frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z}$$

$$\text{curl } \underline{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{h} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix} = \nabla \times \underline{v}$$

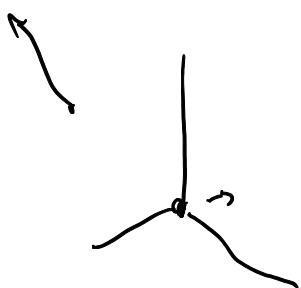
Konstant Strom

v konstant

$$\nabla \cdot \underline{v} = 0 \quad , \quad \nabla \times \underline{v} = \underline{0}$$

Beispiel: positionswertes

$$\underline{r} = x \hat{i} + y \hat{j} + z \hat{h} \quad , \quad \underline{v} = \underline{r}$$



$$\nabla \cdot \underline{r} = \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} = 1+1+1=3>0$$

ausgew.  $\rightarrow$

$$\nabla \times \underline{r} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{h} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix} = \underline{0} \quad \text{vischmitt}$$



Eksponentiell hastighetsfall

$$\underline{w} = w \underline{k}$$

$$\underline{v} = w \underline{k} \times r = -w y \underline{i} + w \underline{j}$$

$$\nabla \cdot \underline{v} = 0 \quad \text{ikke eksplosjon}$$

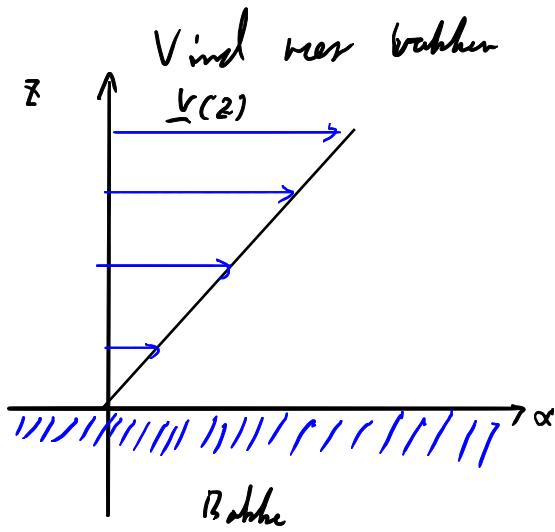
$$\nabla \times \underline{v} = \frac{\underline{i}}{\frac{\partial}{\partial x}} \frac{\underline{j}}{\frac{\partial}{\partial y}} \frac{\underline{k}}{\frac{\partial}{\partial z}}$$
$$-w_y \quad w_x \quad 0$$

$$= \underline{k} \left( \frac{d(w_x)}{dx} - \left( -\frac{d(w_y)}{dy} \right) \right)$$
$$= 2w \underline{k} = 2\underline{w}$$

$$\underline{w} = \frac{1}{2} \nabla \times \underline{v}$$

Gjelder for rotasjon  
som et fast legeme

Eksponentiell:



$$\underline{v}(z) = \alpha z \underline{i}$$

$$\nabla \times \underline{v} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \alpha z & 0 & 0 \end{vmatrix} = \underline{j} \alpha$$

Dersom den berørtekoso  
roterer med vindet som et  
fast legeme, så kan vi formule

$$\underline{w} = \frac{1}{2} \nabla \times \underline{v} = \frac{1}{2} \times \underline{j}$$

Rør sprosul-  
asjona

Ergebnis: Komponenten  $\underline{w} = w_x \underline{i} + w_y \underline{j} + w_z \underline{k}$

$$\underline{v} = \underline{w} \times \underline{r}$$

$$\nabla \times (\underline{w} \times \underline{r})$$

$$= \underline{w} \underbrace{\nabla \cdot \underline{r}}_{\{ } - \underline{r} (\nabla \cdot \underline{w}) \underbrace{\} }$$

$$= 3\underline{w} - \underline{w} \cdot \nabla \underline{r}$$

$$\nabla \cdot \underline{v} = \nabla \cdot (\underline{w} \times \underline{r})$$

$$= \underline{r} \cdot (\nabla \times \underline{w})$$

$$= \underline{w} \cdot (\underline{r} \times \nabla)$$

$$= \underline{w} \cdot (-\nabla \times \underline{r})$$

$$= 0$$

Rechnet  $(\underline{w} \cdot \nabla) \underline{r}$

$$\begin{aligned} \underline{w} \cdot \nabla &= (w_x \underline{i} + w_y \underline{j} + w_z \underline{k}) \cdot \left( \underline{i} \frac{d}{dx} + \underline{j} \frac{d}{dy} + \underline{k} \frac{d}{dz} \right) \\ &= w_x \frac{d}{dx} + w_y \frac{d}{dy} + w_z \frac{d}{dz} \end{aligned}$$

$$\begin{aligned} (\underline{w} \cdot \nabla) \underline{r} &= w_x \frac{dr}{dx} + w_y \frac{dr}{dy} + w_z \frac{dr}{dz} \\ &= w_x \underline{i} + w_y \underline{j} + w_z \underline{k} = \underline{w} \end{aligned}$$

$$\nabla \times (\underline{w} \times \underline{r})$$

$$= 3\underline{w} - \underline{w} = 2\underline{w}$$

$$\underline{w} = \frac{1}{2} \nabla \times \underline{r}$$

Kom für rotationen um  
einen Winkel







