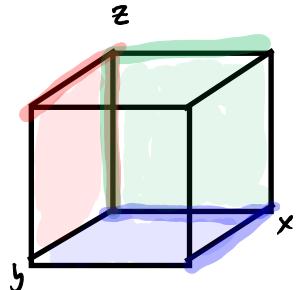


# 1) Vektorfeld

$$\vec{v} = \underbrace{4x^2y\hat{i}}_{\text{pink}} + \underbrace{xyz\hat{j}}_{\text{green}} + \underbrace{yz^2\hat{k}}_{\text{blue}}$$

a) integriert über:

$$0 \leq x \leq 1, 0 \leq y \leq 1, 0 \leq z \leq 1.$$



$$= \int_0^1 \int_0^1 4x^2 y \, dy \, dz$$

$$\bullet = 4 \int_0^1 y \int_0^1 x^2 \, dz \, dy = 4 \int_0^1 y [xz]_0^1 \, dy = 4 \int_0^1 y = 4 \left[ \frac{y^2}{2} \right]_0^1 = 2$$

$$\bullet \int_0^1 \int_0^1 x^2 y z \, dx \, dz = \int_0^1 x \int_0^1 y z \, dz \, dx = \int_0^1 x \left[ \frac{z^2}{2} \right]_0^1 = \frac{1}{2} \left[ \frac{x^2}{2} \right]_0^1 = \frac{1}{4}$$

$$\bullet \int_0^1 \int_0^1 y^2 z \, dx \, dy = \int_0^1 y \int_0^1 z \, dx \, dy = \left[ \frac{y^2}{2} \right]_0^1 = \frac{1}{2}$$

$$\int_0^1 \int_0^1 -4xyz \, dx \, dy = 0$$

$$\int_0^1 \int_0^1 -xyz^2 \, dx \, dz = 0$$

$$\int_0^1 \int_0^1 -yz^2 \, dx \, dy = 0$$

$$2 + \frac{1}{4} + \frac{1}{2} = \frac{6}{4} + \frac{1}{4} + \frac{2}{4} = \frac{11}{4}$$

R

2 prove Gauß

$$\nabla \cdot \vec{v} = \frac{\partial \bar{v}_x}{\partial x} \hat{i} + \frac{\partial \bar{v}_y}{\partial y} \hat{j} + \frac{\partial \bar{v}_z}{\partial z} \hat{k}$$

$$\frac{\partial}{\partial x} 4x^2y = 8xy$$

$$\frac{\partial}{\partial y} xyz = xz$$

$$\frac{\partial}{\partial z} yz^2 = 2yz$$

$$\underline{\nabla \cdot \vec{v}} = 8xy + xz + 2yz$$

$$\iiint_0^1 8xy + xz + 2yz \, dx \, dy \, dz$$

$$\iiint_0^1 8xy \, dx \, dy \, dz = \int_0^1 8xy [z]_0^1 = \int_0^1 8x \int_0^1 y \, dy \, dx = \int_0^1 8x \cdot \frac{1}{2}$$

$$= 4 \int_0^1 x \, dx = 4 \cdot \frac{1}{2} = \underline{\underline{1}}$$

$$\cancel{\iiint_0^1 yz \, dx \, dy \, dz} = \int_0^1 y \int_0^1 z \, dz \, dy = 1 \cdot \frac{1}{2} \cdot \frac{1}{2} = \underline{\underline{\frac{1}{4}}}$$

$$\cancel{\iiint_0^1 2yz \, dx \, dy \, dz} = 2 \int_0^1 y \int_0^1 z \, dz \, dy = 2 \cdot \frac{1}{2} \cdot \frac{1}{2} = \underline{\underline{\frac{1}{2}}}$$

$$2 + \frac{1}{4} + \frac{1}{2} = \underline{\underline{\frac{11}{4}}} \sim \text{Gauß'satz}$$

$$L \quad -a \leq x \leq a, \quad -h \leq z \leq 0$$

$$\bar{v} = \frac{U(z+h)}{h} \hat{j}$$

$v$  er vanntet berøringstet:

vanntrepletter

$$z=0 \quad \text{og} \quad n = \rho_0$$

$n = \text{dy bader}$

$\rho$  vanntet tettsat

$2a \approx \text{bredde}$

$$g = -g \bar{k} \quad \text{Brygdehast}$$

1a) Finn ut om det er et potensial og innfall finn det

$$\boxed{\nabla \times \bar{F} = 0, \text{ innfall er et potensial}}$$

$$\boxed{\left( \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \bar{i} + \left( \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \bar{j} + \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \bar{k}}$$

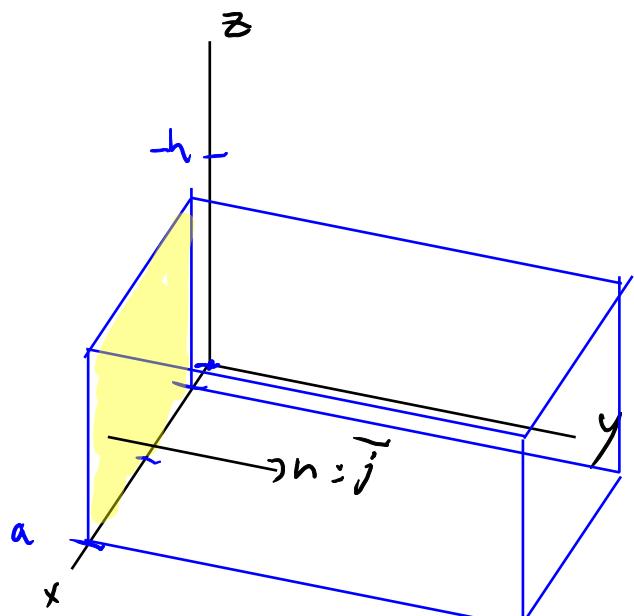
$$-\frac{d}{dz} \frac{U(z+h)}{h} \bar{i} + \frac{d}{dx} \frac{U(z+h)}{h} \bar{k}$$

$$\left\{ \begin{array}{l} -\left( \frac{d}{dz} U h^{-1} z + h \bar{z} \bar{h}^{-1} \right) = -\left( \frac{U}{h} + 1 \right) \bar{i} \\ \frac{d}{dx} \frac{U(z+h)}{h} \bar{k} = 0 \end{array} \right.$$

$$\nabla \times \bar{F} = \left( \frac{U}{h} + 1 \right) \bar{i}$$

l) transitt  $y=0$

$$\bar{v} = \frac{V(z+h)}{h} \bar{j}$$



$$\int_0^h \int_0^a \frac{V(z+h)}{h} \bar{j} \cdot \bar{j} dx dz$$

$$\begin{aligned} & \int_0^h \left( \frac{Vz + V}{h} \right) \Big|_0^a dx dz = \frac{V}{h} \int_0^h (z+h) \cdot 2a dz \\ & = \frac{1}{h} Va \int_0^h z dz = \frac{1}{h} Va \left[ \frac{z^2}{2} \right]_0^h = \underline{\underline{Va h}} \end{aligned}$$

2c) Kontinuitätsbedingungen

$$\frac{\partial p}{\partial t} = -\rho \nabla \cdot \bar{v}$$

$$\frac{\partial p}{\partial t} + (\nabla \cdot \bar{v}) = 0$$

$\cancel{\rho}, \nabla \cdot \bar{v} = 1 \text{ (1)}$

(?)

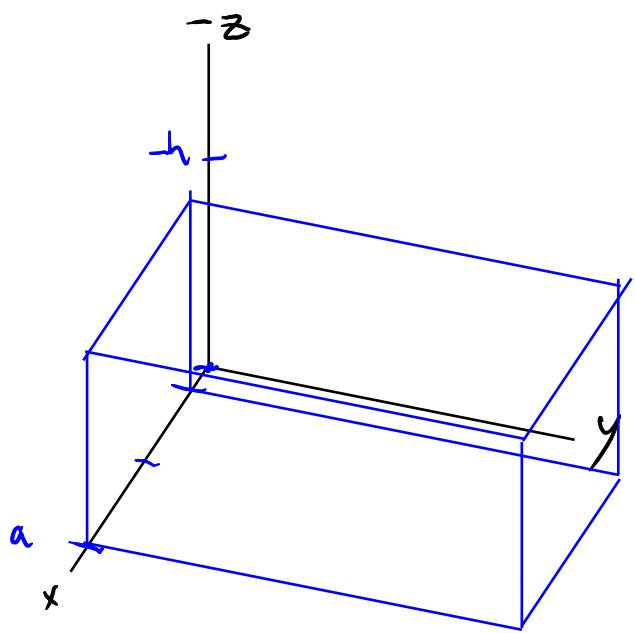
in a closed system  $\nabla \cdot \bar{v} = 0$

$$\frac{\partial v_y}{\partial y} = 0$$

Då ned w kontinuerlig virga opplyst

1d) 13 med Eulers ligning

c)



# Oppgave 3

En karusell i en fornøyelsespark roterer med konstant vinkelhastighet  $\omega = \omega \mathbf{k}$ . Omdreiningsaksen sammenfaller med  $z$ -aksen som peker oppover,  $\mathbf{k}$  er enhets-koordinatvektor i  $z$ -retning,  $xy$ -planet er horisontalt,  $r$  er radiell horisontal avstand fra omdreiningsaksen,  $\theta$  er vinkelen i  $xy$ -planet slik at  $x = r \cos \theta$  og  $y = r \sin \theta$ .

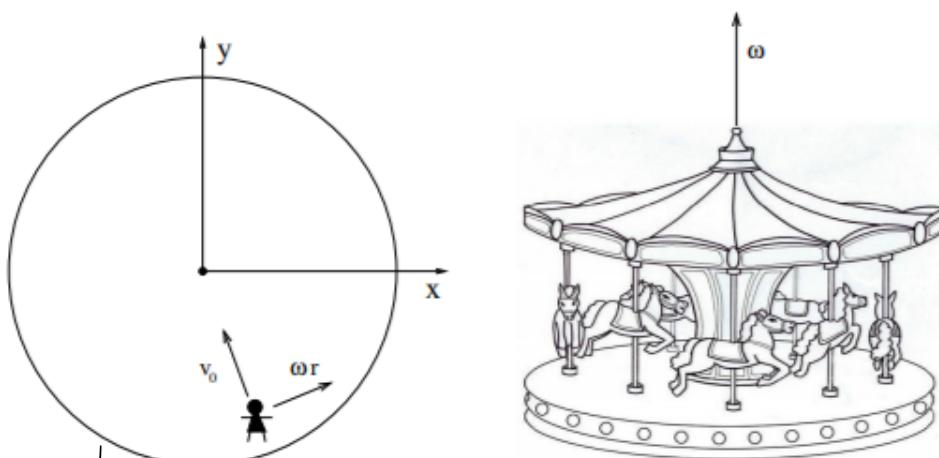
En person på karusellen flytter seg innover mot sentrum med konstant fart  $v_0$  i radiell retning, samtidig som hun roterer med karusellens bevegelse i vinkelretning, hun beveger seg derfor i henhold til hastighetsfeltet

$$\mathbf{v} = \omega r \mathbf{i}_\theta - v_0 \mathbf{i}_r$$

Eksamens i MEK 1100, Torsdag 1 juni 2017.

Side 3

hvor  $\mathbf{i}_r$  er enhets-koordinatvektor i radiell retning og  $\mathbf{i}_\theta$  er enhets-koordinatvektor i vinkelretning.



Illustrasjon fra <http://www.imgur.com/a/dibujo-de-feria-iRRjA8xLx>

Merk: Dersom du prøver dette på en karusell som roterer fritt vil du oppleve at vinkelhastigheten øker. I denne oppgaven antar vi derimot at karusellen ikke roterer fritt, men at vinkelhastigheten holdes konstant!

I følgende deloppgaver ønsker vi svarene presentert i cylinderkoordinater:

## 3a

Regn ut divergensen til  $\mathbf{v}$ .

## 3b

Regn ut virvinga til  $\mathbf{v}$ .

## 3c

Vi skal finne akselerasjonen til personen ved å regne ut den partikkelderiverte av hastighetsfeltet  $\mathbf{v}$ : Regn ut lokalakselerasjonen og den konvektive akselerasjonen.

3 Rotasjon  $\bar{w} = wh$        $x = r \cos(\theta), y = r \sin \theta$   
 Radiall avstand =  $r$   
 Vinkel i xy-planet =  $\theta$   
 en person beveger seg mot  
 sentrum (radius  $r$ ) med en  
 hastighet:  $v_0$

a) Regn ut divergensen til  $\vec{v}$

$$\nabla \cdot \vec{V} = \frac{1}{r} \left( \frac{d}{dr} (r A_r) + \frac{d A_\theta}{d\theta} \right) + \frac{d A_z}{dz}$$

$$\bar{V} = wr_{i_0} - V_{r_i i_r}$$

$$\nabla \cdot \vec{v} = \frac{1}{r} \left( \frac{d}{dr} r(-v_r) + \frac{d}{ds} w_s \right)$$

$$= \frac{1}{r} (-V_0 + 0) = \frac{-V_0}{r}$$

b) Räkna ut virulensa

$$r \times \bar{v} = \left( \frac{1}{r} \cancel{\frac{dA_\theta}{d\theta}} - \cancel{\frac{dA_r}{dr}} \right) \bar{i}_r + \left( \cancel{\frac{dA_r}{dr}} - \cancel{\frac{dA_\theta}{d\theta}} \right) \bar{i}_\theta + \frac{1}{r} \left( \frac{d}{dr} (r A_\theta) - \cancel{\frac{dA_r}{d\theta}} \right) \bar{h}$$

$$\nabla \times \vec{v} = \frac{1}{r} \left( \frac{d}{dr} (r A_\theta) \right) \hat{k} = \frac{1}{r} \frac{d}{dr} r \cdot (w_r)$$

$$= \frac{1}{f} 2\pi w = 2\pi$$

3c

$$(\vec{v}, \vec{\omega})$$

$$(w r i_\theta - v_0 i_r) \cdot \left( \vec{i}_r \frac{\partial}{\partial r} + \vec{i}_\theta \frac{\partial}{\partial \theta} \right)$$

$$\left. \begin{aligned} \vec{i}_r \cdot \frac{\partial}{\partial r} w r \vec{i}_\theta &= 0 \\ w r i_\theta \frac{i_\theta \partial}{r \partial \theta} &= \cancel{w r \cdot 1 \cdot \frac{\partial}{\partial \theta}} = \underline{w \frac{\partial}{\partial \theta}} \\ -v_0 i_r \cdot \vec{i}_r \frac{\partial}{\partial r} &= \underline{-v_0 \frac{\partial}{\partial r}} \\ -v_0 i_r \cdot \vec{i}_\theta \frac{\partial}{r \partial \theta} &= 0 \\ = \left( \underline{w \frac{\partial}{\partial \theta}} - \underline{v_0 \frac{\partial}{\partial r}} \right) &\mid (w r \vec{i}_\theta - v_0 \vec{i}_r) \\ = w \frac{\partial (w r \vec{i}_\theta)}{\partial \theta} - w \frac{\partial (v_0 \vec{i}_r)}{\partial \theta} - v_0 \frac{\partial (w r \vec{i}_\theta)}{\partial r} - v_0 \frac{\partial (v_0 \vec{i}_r)}{\partial r} & \end{aligned} \right\}$$

$$\frac{d}{dt} \vec{i}_\theta = -\vec{i}_r$$

$$-w^2 r \vec{i}_r - w v_0 \vec{i}_\theta - v_0 w \vec{i}_\theta - v_0 \cdot 0$$

$$-w r \vec{i}_r - 2 w v_0 \vec{i}_\theta$$

$$w: \frac{1}{t} \quad \left(\frac{1}{t}\right)^2 \cdot m \frac{m}{r^2} \quad \frac{1}{t} \approx \frac{1}{t}$$

r: Länge(m)

t: t

$$\bar{V} = \left( \frac{\sqrt{z}}{h} + V \right) \hat{j}$$

$$\nabla \times \bar{V} = \begin{vmatrix} i & j & h \\ \frac{d}{dx} & \frac{d}{dy} & \frac{d}{dz} \\ 0 & \bar{j} & 0 \end{vmatrix} = i \cdot \left( 0 - \frac{d}{dz} \frac{Vz + V}{h} \right) = -\frac{V}{h} i$$

$$x=0, \bar{i} : \int_0^b -\frac{V}{h} \dots = \frac{V}{h} \cdot b \cdot -h = -Vb$$

