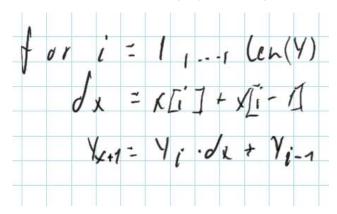
Oppg1

a) Bruker numeric division.

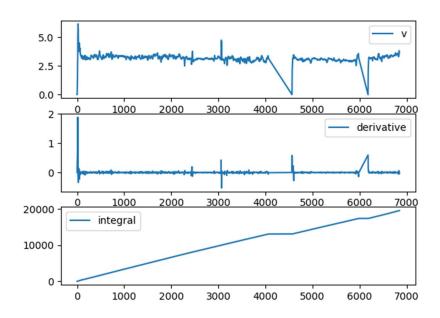
Er også vist I koden nederst I dokumentet.

b) Bruker numerisk integrasjon. Med algoritmen



Der Y[i] er integrasjonen fra 0 til i av Y. også vist i koden.

c) Framgangsmåte i koden.



Integralet viser lengden, derivate viser akselerasjonen, og V viser farten.

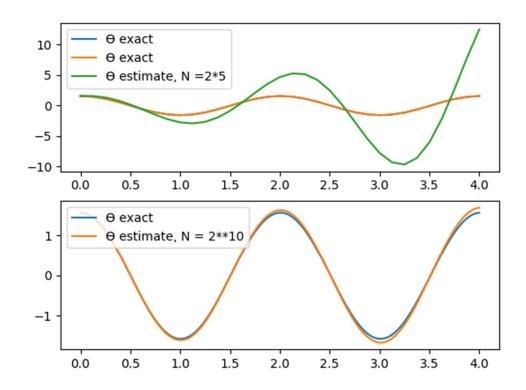
Framgangsmåte ligger i koden.

$$\frac{\int^2 \theta}{\int t^2} (t) = -\frac{9}{2} \sin(\theta(t))$$

$$\frac{d^2\theta}{dt} + \frac{1}{L} - \frac{9}{L} \sin(\theta(t)) / \cdot L$$

C) I python koden

d)



Ser at estimatet blir mer nøyaktig når vi øker N, og at ved liten N så blir estimatetr mer og mer usikkert jo lengere fra x=0 vi kommer.

e) Estimatet er

N = 16

err[1] = 0.00011756377981275712

err[103] = 0.0038099404835139072

err[205] = 0.019454896734367066

err[307] = 0.030003221985847484

err[409] = 0.013649685114557941

err[511] = 0.0611889219864572

err[613] = 0.026145718107934424

err[715] = 0.06684992331497353

err[817] = 0.08377880498442503

err[919] = 0.026552753305578047

```
err[1021] = 0.12430267382042826
 N = 32
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
 N = 64
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
 N = 128
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
```

```
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
 N = 256
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
 N = 512
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
 N = 1024
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
```

```
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
    f) Erikoden
    g) Erikoden
Koden
import numpy as np
import matplotlib.pyplot as plt
#c)
def lin_pendel_euler(v0, theta0, g, L, N, T, h=None):
  if h is None:
    h = T/N
  v, theta = [0]*(N+1), [0]*(N+1)
  v[0], theta[0] = v0, theta0
  for k in range(N):
    v(k+1) = v(k) - g*h*theta(k)
    theta[k+1] = theta[k] + h*(v[k]/L)
  return v, theta
```

return theta0 * np.cos(np.sqrt(g/L)*t) + v0 * np.sin(np.sqrt(g/L)*t)

#d)

def lin_pendel(t, v0, theta0, g, L):

```
g, L, v0, theta0, T, N1 = 9.81, 1, 0, np.pi/2, 4, 2**5
v_hat, theta_hat = lin_pendel_euler(v0, theta0, g, L, N1, T)
t1 = np.linspace(0,T,N1+1) #[h*k for k in range(N)]
theta1 = lin_pendel(t1, v0, theta0, g, L)
plt.subplot(2, 1, 1)
plt.plot(t1,theta1, label='\text{\theta} exact')
plt.plot(t1,theta_hat, label='Θ estimate, N =2*5')
plt.legend()
plt.subplot(2, 1, 2)
N2 = 2**10
v_hat, theta_hat = lin_pendel_euler(v0, theta0, g, L, N2, T)
t2 = np.linspace(0,T,N2+1) #[h*k for k in range(N)]
theta2 = lin_pendel(t2, v0, theta0, g, L)
plt.plot(t2,theta2, label='Θ exact')
plt.plot(t2,theta_hat, label='Θ estimate, N = 2**10')
plt.legend()
plt.show()
#e)
def epsilon(N, h=None):
  t = np.linspace(0,T,N+1)
  theta = lin_pendel(t, v0, theta0, g, L)
  theta_hat = np.asarray(lin_pendel_euler(v0, theta0, g, L, N, T, h)[-1])
```

```
err = np.absolute(theta-theta_hat)
  return err
n = [2**i for i in range(4,10+1)]
for N in n:
  err = epsilon(2**10)
  print(""-----
  N = {}'''.format(N))
  for i in range(1, len(err), int(len(err)/10)):
    print('err[{}] = {}'.format(i, err[i]))
#f)
def p(epsilon):
  N = 2**4
  h2 = (T/N)/2
  h1 = T/N
  return (np.log(epsilon(N)/epsilon(N)))/np.log(h1/h2)
print(p(epsilon))
#g
def pendel_euler(v0, theta0, g, L, N, h):
  v = theta =np.zeros(N+1)
  v[0], theta[0] = v0, theta[0]
  for k in range(N):
    v[k+1] = v[k] - g*h*np.sin(theta[k])
    theta[k+1] = theta[k] + h * v[k]/L
```

```
return v, theta
```

```
h1 = T/N1
h2 = T/N2
v_pen1, theta_pen1 = pendel_euler(v0, theta0, g, L, N1, h1)
v_pen2, theta_pen2 = pendel_euler(v0, theta0, g, L, N2, h2)
plt.subplot(2, 1, 1)
plt.plot(t1,theta1, label='\text{\theta} exact')
plt.plot(t1,theta_hat, label='Θ estimate, N =2*5')
plt.plot(t1,theta_pen1, label = '\text{\text{theta_pen}}, N = 2*5')
plt.legend()
plt.subplot(2, 1, 2)
N2 = 2**10
v_hat2, theta_hat2 = lin_pendel_euler(v0, theta0, g, L, N2, T)
theta = lin_pendel(t2, v0, theta0, g, L)
plt.plot(t2,theta2, label='\text{\theta} exact')
plt.plot(t2,theta_hat2, label='Θ estimate, N = 2**10')
plt.plot(t2,theta_pen2, label = '\text{\text{theta_pen}}, N = 2*10')
plt.legend()
plt.show()
```

Kjøreeksempel

```
N = 16

err[1] = 0.00011756377981275712

err[103] = 0.0038099404835139072

err[205] = 0.019454896734367066

err[307] = 0.030003221985847484

err[409] = 0.013649685114557941

err[511] = 0.0611889219864572

err[613] = 0.026145718107934424
```

```
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
   N = 32
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
    N = 64
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
    N = 128
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835<u>139072</u>
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[511] = 0.0611889219864572
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
err[1021] = 0.12430267382042826
```

```
N = 1024
err[1] = 0.00011756377981275712
err[103] = 0.0038099404835139072
err[205] = 0.019454896734367066
err[307] = 0.030003221985847484
err[409] = 0.013649685114557941
err[613] = 0.026145718107934424
err[715] = 0.06684992331497353
err[817] = 0.08377880498442503
err[919] = 0.026552753305578047
alue encountered in true_divide
 return (np.log(epsilon(N)/epsilon(N)))/np.log(h1/h2)
Traceback (most recent call last):
 File "D:\OneDrive - Universitetet i Oslo\UIO\MAT-INF1100\Oblig2\oppg2.py", line 93, in <module
   plt.plot(t1,theta_hat, label='\u03f4 estimate, N =2*5')
 File "C:\Users\SKJSA\AppData\Local\Programs\Python\Python37\lib\site-packages\matplotlib\pyplo
t.py", line 2749, in plot

*args, scalex=scalex, scaley=scaley, data=data, **kwargs)
 File "C:\Users\SKJSA\AppData\Local\Programs\Python\Python37\lib\site-packages\matplotlib\ ini
 File "C:\Users\SKJSA\appData\Local\Programs\Python\Python37\lib\site-packages\matplotlib\axes\
    for line in self._get_lines(*args, **kwargs):
 File "C:\Users\SKJSA\AppData\Local\Programs\Python\Python37\lib\site-packages\matplotlib\axes\
_base.py", line 393, in _grab_next_args
yield from self._plot_args(this, kwargs)
 File "C:\Users\SKJSA\AppData\Local\Programs\Python\Python37\lib\site-packages\matplotlib\axes\
_base.py", line 370, in _plot_args
 x, y = self._xy_from_xy(x, y)
File "C:\Users\SKJSA\AppData\Local\Programs\Python\Python37\lib\site-packages\matplotlib\axes\
ValueError: x and y must have same first dimension, but have shapes (33,) and (1025,)
[Finished in 2.176s]
```