Processes Management

Sistemas de Computadores 2017/2018

Processes

Instance of execution of a program

- Program != Process
 - Program: code + static data
 - Process: dynamic instantiation of code + data + state
- Program and process
 - Process > program: more than code and data
 - Program > process: one program can create several processes

Process

- From the point of view of the operating system, a process is the entity to which resources are given
 - CPU time, memory, files, I/O devices, etc.

- Processes are isolated from each other
 - Sequential execution has well defined interactions
 - By default, no memory sharing between processes

OS process management

Identify and represent processes internally

Create/remove processes of user and of system

Schedule processes access to the CPU

Provide communication and synchronization mechanisms

Processes identification

 A process is identified through um unique value, names Process ID (PID)

- PIDs are usually given by OS sequentially until the limit of the data type
 - In that case, PID numbers are recycled from older processes that have already finished (lower values first)

Process creation

- A process is created ...
 - O By action of the OS
 - By action of the user
 - By another process

```
#include <sys/types.h>
#include <unistd.h>
pid t fork()
```

Process hierarchy

- The process that invoques the fork system call is named the parent
- The newly created process is the child
- Each one can create more processes, leading to a process tree
 - Each process has exactly one parent and zero or more children

Process hierarchy

```
$ pstree | more
init-+-acpid
|-avahi-daemon---avahi-daemon
|-bonobo-activati---{bonobo-activati}
l-cron
|-cupsd
-gdm---gdm-+-Xorg
       `-x-session-manag-+-gnome-panel---{gnome-panel}
                 |-gnome-settings--+-pulseaudio-+-gconf-helper
                                   `-2*[{pulseaudio}]
                           `-{gnome-settings-}
                  -konsole---3*[bash]
                  -metacity
                  -ssh-agent
                 `-{x-session-manag}
-getty
|-konsole-+-2*[bash]
      |-bash---vim
```

getpid and getppid

```
#include <sys/types.h>
#include <unistd.h>

pid_t getpid();
pid_t getppid();
```

getpid returns the PID of the process

getppid returns the PID of the parent process

Process creation

- The Child process is a copy of the parent
 - The only differences are the PID (remember it is unique), and certain resources (e.g. signals are not inherited) and stats
 - Child and parent are independent processes and both compete for the CPU time
- After fork, both processes execute the same code, in the instruction immediately after the fork function call
 - Order of execution is not known
 - There needs to be a way to distinguish them

fork return values

- -1, in case of error
 - It was not possible to create the child, so a single process still exists
- The PID of the child (> 0) is returned in the parent process
 - Parent may need this PID to communicate or synchronize with the child
- The child process receives from fork the value zero
 - The fork was not executed by the child
- The different values received by parent and child allows to separate the code each one will execute

Example – fork returned values

```
pid = fork();
if(pid == -1){
  perror("Fork failed"); exit(1);
if(pid > 0)
  printf("Luke, I'm your father\n");
else
  printf("I am the son\n'');
printf("Who executes this line?");
```

Process creation

- We can think of fork as a cloning function
 - It creates a copy of the original process, with the same code and data
- In the child process, the new variables have the same value as the original ones had in the parent in the instant of execution of the fork

 However, any change made in any of the processes after the fork, is independent and does not affect the other process

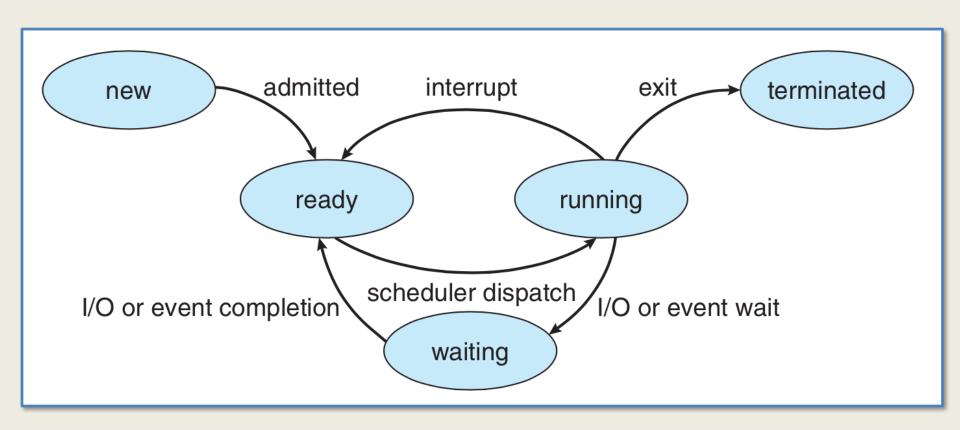
Example – changes after fork

```
int x = 10;
pid = fork();
if(pid > 0){
  printf("Luke, I'm your father\n");
else{
  printf("I am the son\n");
  X++;
printf("x = %d\n'', x);
```

Concurrent execution

- Only one process may, at a given instant, be executing in the core of a CPU...
- ... but multiple processes can be loaded to memory and be executed concurrently
- The goal of the OS is to have always a process executing, maximizing resource usage
 - Decision based in metrics of performance and load (scheduling)

States of a process



sleep

```
#include <unistd.h>
int sleep(int seconds);
```

- Suspends execution of the process during (at least) n seconds
 - If a process receives a signal while it is sleeping, it may waken before time
- Sleep can be used to try to obtain a order between processes
 - But it is not guaranteed, so use it only for testing, not to guarantee order and synchronization!

Process termination

- A process terminates when ...
 - Executes the last instruction
 - Invokes the exit system call
 - voluntarily in an error
 - Involuntarily in an error
 - By action of a user or another process

Process termination

```
#include <stdlib.h>
void exit(int status);
```

- Terminates the process, providing a status value to the operating system
 - A single byte of status is used so values are 0 255
- Two contants are used, EXIT_SUCCESS and EXIT_FAILURE, to indicate success or failure in the execution

Process termination

- When a process terminates, the parent is informed by the OS using the SIGCHLD signal
- This event is asynchronous the parent can receive it at any time
 - The parent can ignore the signal (the default behavior) or provide a function to be executed when the signal is received (a handler)

Zombie Processes

- If the child terminates before the parent
 - It becomes a zombie cannot execute but the OS still has to keep the information of its termination
- OS cannot remove the process from the process table, but can free all process resources
 - Parent has to acknowledge the termination for the entry to be removed
 - Acknowledgement is with wait/waitpid functions
 - After acknowledgement, process disappears and is no longer zombie

Orphan Processes

- If the parent terminates before the child
 - Child become orphan
- In that case, it is necessary the process to be adopted by another process to maintain hierarchy
- In UNIX, orphan processes are adopted by the init process that periodicall invokes wait to all its children

wait and waitpid

```
#include <sys/wait.h>
pid_t wait(int *status);
```

- wait blocks until any of the process children terminates
 - Returns the PID of the terminated child, or -1 in case of error
- status should be initialized with the address of a variable that will receive the exit value of the child
 - The exit value also includes some extra information by the OS

wait and waitpid

```
pid_t waitpid(pid_t pid, int *status,
   int options);
```

- waitpid blocks until the specified child terminates
 - pid = -1 means it will wait for any children, as wait
- options may be 0 (blocks), WNOHANG (does not block) and WUNTRACED (children in the STOPPED state)

wait and waitpid

- When invoking wait or waitpid, the process may:
 - Be blocked until the child terminates
 - Return immediately if the child has already terminated
 - Return immediately with an error, if there are no children

Example – synchronizing with wait

```
pid = fork();
if(pid > 0){
  printf("Luke, I'm your father\n");
  wait(NULL);
  printf("The child has terminated");
else{
  printf("I'm the son\n");
  Some code();
  exit(0);
```

Process exit information

- The OS also stores some information related to the way a process terminates:
 - The exit value
 - The signal that caused the abnormal termination (if any)
 - If the process originated a core dump
 - o etc
- There are several macros that can be used to obtain that information from the status obtained in wait/waitpid

Process exit information

- WIFEXITED(status)
 - Checks if the child terminated normally
- WEXITSTATUS(status)
 - Exit value (1 byte) given in the exit function
- WIFSIGNALED(status)
 - Checks if the child terminated due to a nontreated signal

Process exit information

- WTERMSIG(status)
 - Gets the number of the signal that terminated the child
- WCOREDUMP(status)
 - Checks if a core dump was generated
- WIFSTOPPED(status)
 - Checks if the child is in the STOPPED state
- WIFCONTINUED(status)
 - Checks if the process was continued

Example – process exit information

```
pid t pid1, pid2;
  int status;
  pid1 = fork();
  if(pid1 > 0){
     pid2 = waitpid(pid1, &status, 0);
     if (WIFEXITED (status))
       printf("Parent: child %d returned
%d\n", pid2, WEXITSTATUS(status));
  else
     exit(10);
```

Exercise

- Implement a program that creates 2 new processes, with the following behaviour
 - Child 1 sleeps 5 seconds, prints its PID and terminates wirth value 1
 - Child 2 prints its PID and the parent PID and terminates with value 2
- Independently of the order of execution and termination, parent waits first for child 1 and then child 2, printing their PIDs and exit values
 - But guarantee that both children execute concurrently