

# Computer Networks - UE20CS253

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## Assignment - Socket programming

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## Project title - Simple video chat application using socket programming

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### Abstract

The application aims to create a peer-to-peer connection and relay video feed between the two peers. This is achieved by establishing two socket connections, by the use of `client` and `server` programs running simultaneously, which is achieved by multithreading. The `server` program transmits the video feed of a user while the `client` program receives the incoming data.

The connection created follows TCP, as the socket is created with the parameter `SOCK_STREAM`

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### Server side

1. the socket is created and bound with the hostname and the IP address of the system using

```
socket.gethostname()    # provides hostname
socket.gethostbyname(hostname) # provides IP address
socket.bind()
```

2. the socket begins listening at the designated port (given as 1235)
3. the socket accepts the connection using

```
socket.accept()
```

4. the video feed is captured using OpenCV

```
cv2.VideoCapture()
```

5. the captured video is serialised, packed into frames and sent to the client socket

```
pickle.dumps(frame) # serialisation of object
struct.pack("Q",len) # packing of data in segments of size long long int
socket.sendall() # transmission of packets
```

6. the server continues to send video packets until the connection is closed

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## Client side

1. the socket is created and the connection is established
2. the data variable is created and the payload size is calculated

```
socket.connect(host_ip,port)
struct.calcsize("Q") # payload size equal to long long int
```

3. the socket begins accepting packets and the data variable begins slicing the data based on the payload size

```
socket.recv() # receiving packets from server
struct.unpack() # unpacking received data
```

4. the frames are loaded and displayed until the connection is closed

```
pickle.loads() # loading data onto frames
cv2.imshow() # display of frames
```

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## Source code

### Server.py

```
# server side program
# libraries
import socket # library to manage socket
import cv2 # library to capture video
import pickle # library to implement 'pickling' ie serialisation of a python object
import struct # library to pack and unpack data

def server():
    server_socket = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
    host_name = socket.gethostname()
```

```

host_ip = socket.gethostbyname(host_name)
print("HOST IP:", host_ip)

port = 1235
socket_address = ("192.168.43.6", port)
print("Socket Created Successfully")

server_socket.bind(socket_address)
print("Socket Bind Successfully")

server_socket.listen(5)
print("LISTENING AT:", socket_address)

print("Socket Accept")

while True:
    client_socket, addr = server_socket.accept()
    print("GOT CONNECTION FROM:", addr)
    if client_socket:
        vid = cv2.VideoCapture(0)

        while vid.isOpened():
            print("Server running      |")
            img, frame = vid.read()
            a = pickle.dumps(frame)
            message = struct.pack("Q", len(a)) + a
            client_socket.sendall(message)

            cv2.imshow("TRANSMITTING VIDEO", frame)
            key = cv2.waitKey(1) & 0xFF
            if key == ord("q"):
                client_socket.close()

# server()

```

## Client.py

```

# client side program
# libraries
import socket # library to manage socket
import cv2 # library to capture video
import pickle # library to implement 'pickling' ie serialisation of a
python object
import struct # library to pack and unpack data

def client():
    # creation of socket
    client_socket = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
    host_ip_server = "192.168.43.162"

```

```
port = 1234
print("Socket Created Successfully")

# establishment of connection
client_socket.connect((host_ip_server, port))
data = b""
payload_size = struct.calcsize("Q")
print("Socket Accepted")

# data transmission loop
while True:
    print("CLIENT:")
    # loop to receive new packet
    while len(data) < payload_size:
        packet = client_socket.recv(2160)
        if not packet:
            break # error condition
        data += packet
    # slice packet based on payload size and store separately
    packed_msg_size = data[:payload_size]
    data = data[payload_size:]
    # unpack the received data
    msg_size = struct.unpack("Q", packed_msg_size)[0]

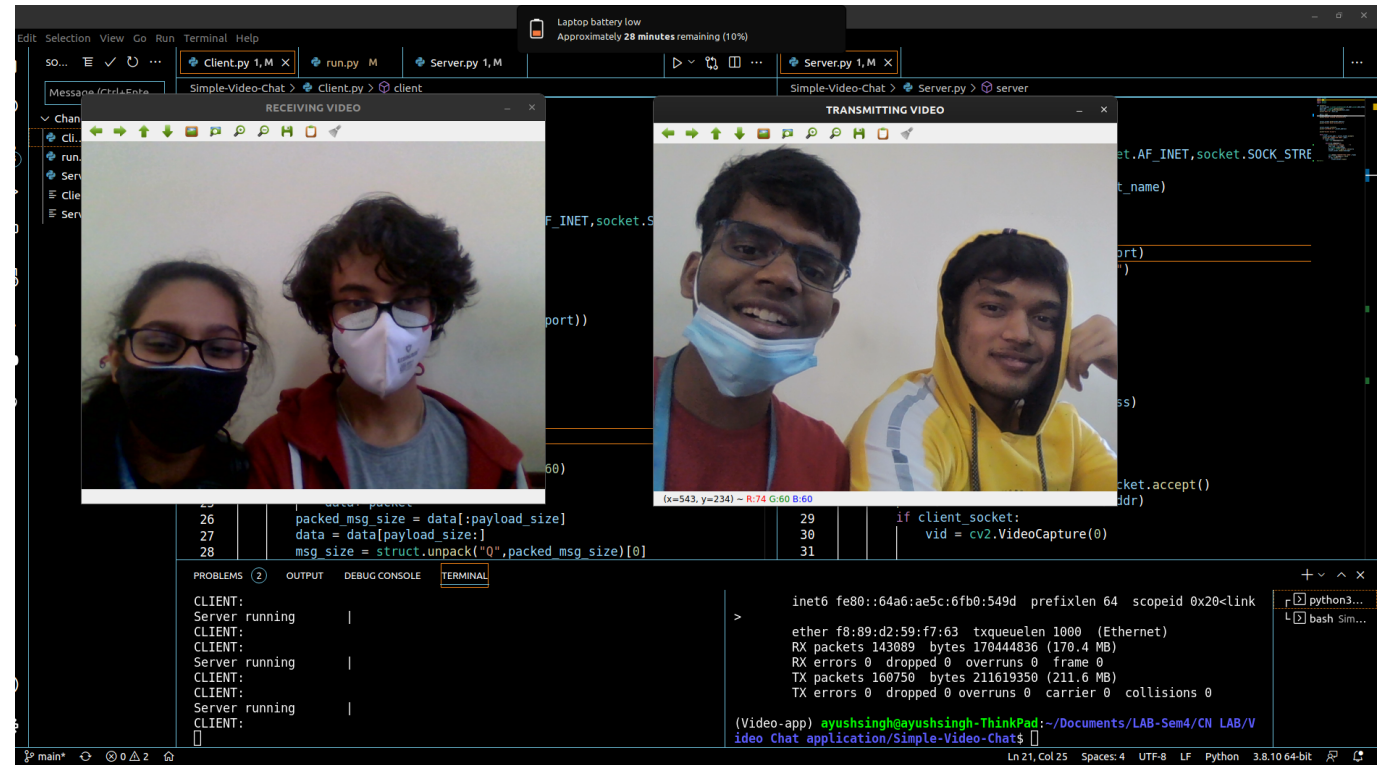
    # loop to receive more data
    while len(data) < msg_size:
        data += client_socket.recv(2160)
    # dividing data into frames
    frame_data = data[:msg_size]
    data = data[msg_size:]
    # loading and display of frames
    frame = pickle.loads(frame_data)
    cv2.imshow("RECEIVING VIDEO", frame)
    key = cv2.waitKey(1) & 0xFF
    if key == ord("q"):
        break
    # closing of connection
    client_socket.close()

# client()
```

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## Output screenshots

Peer 1



Peer 2

