# Madhav Rapelli

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#### **Education**

**Stony Brook University** – BS in Computer Science

**Expected May 2028** 

- Relevant Coursework: Data Structures and Algorithms, Applied Linear Algebra, Foundations of Computer Science
- Expected Coursework: Introduction to the Theory of Computation, Computer Networks, Fundamentals of Software Development, Systems Fundamentals II, Analysis of Algorithms, Machine Learning, Fundamentals of Computer Vision, Natural Language Processing.

### **Experience**

**Nylock Nuts Robotics** 

March 2024 - Present

Robotics Instructor

Jericho, NY (Hybrid)

- Teaching a new competitive VEX Robotics team to design, build, program and document robots focusing on Design, C++ Programming involving motion control and position tracking.
- Led the team to be ranked 13 in their division in the Middle School VEX Worlds Championship in their first season competing (Top 0.01% of all Middle School VEX Robotics teams **worldwide**).

## **Competitive VEX Robotics**

September 2021-May 2024

Lead Programmer

Farmingdale, NY

- Developed a robotics program utilizing C++ and the PROS (Purdue Robotics Operating System) framework. Implemented features including motion control algorithms, real-time position tracking, robot localization using distance sensors, and multi-threaded operations to enhance robot performance.
- Led my team to win a dozen awards over our high school career ranging from regional to the international level. We also ranked in the top 0.005% of VEX Robotics teams **worldwide** in 2024.

# **Projects**

MazeSolver

September 2024 – Present

- Developing an adaptive maze-solving agent using Python, Utilizing Gymnasium for custom dynamic environments and PyTorch for implementing a Deep Q-Network (DQN) model with experience replay, epsilon-greedy exploration, and target networks for improved stability.
- Utilizing various libraries such as NumPy for efficient computations, Matplotlib for real-time metric visualization, Pygame for environment rendering, and PyQt5 for an interactive GUI, enabling real-time adjustments to the maze environment

DocSage July 2024 – Present

- Developing a web application for intelligent document analysis, featuring PDF upload (up to 10MB) and storage in AWS S3, with a interface for document management and interaction.
- Implementing a text processing pipeline, integrating embedding with OpenAI's embedding models as well as document chunking and vectorization techniques with PineconeDB for efficient storage and retrieval of processed data.
- Utilizing OpenAI's language models to create a chatbot capable of understanding and responding to document-specific queries, enabling users to better understand their documents.

**Robot Tour** 

January 2024 - February 2024

- Worked in a two-person team to design and build a custom robot from scratch for Science Olympiad, utilizing CAD software and 3D printing for the robot chassis.
- Used an Arduino Uno board as the base and servo motors for the wheels.
- Implemented a PID algorithm for accurate path following.
- Placed in the top 15% at our regional competition.

### **Skills**

**Programming Languages:** Python, C++, Java, Javascript, Typescript, CSS, LaTeX **Technologies and Frameworks:** Git, Linux, PROS, Next.js, React, Tailwind, Drizzle ORM, AWS S3, Arduino, PyTorch