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1  /**-----
2      \file UART_poll.cpp
3
4  --
5      ECEN 5803 Mastering Embedded System Architecture
6      Project 1 Module 3
7      Microcontroller Firmware
8      UART_poll.c
9  --
10 -----
11 --
12 -- Designed for: University of Colorado at Boulder
13 --
14 --
15 -- Designed by: Tim Scherr
16 -- Revised by: David James & Ismail Yesildirek
17 --
18 -- Version: 2.0.1
19 -- Date of current revision: 2018-10-03
20 -- Target Microcontroller: Freescale MKL25ZVMT4
21 -- Tools used: ARM mbed compiler
22 --              ARM mbed SDK
23 --              Keil uVision MDK v.5
24 --              Freescale FRDM-KL25Z Freedom Board
25 --
26 --
27 -- Functional Description: This file contains routines that support messages
28 -- to and from the UART port. Included are:
29 --     Serial() - a routine to send/receive bytes on the UART port to
30 --                 the transmit/receive buffers
31 --     UART_put() - a routine that puts a character in the transmit buffer
32 --     UART_get() - a routine that gets the next character from the receive
33 --                 buffer
34 --     UART_msg_put() - a routine that puts a string in the transmit buffer
35 --     UART_direct_msg_put() - routine that sends a string out the UART port
36 --     UART_input() - determines if a character has been received
37 --     UART_hex_put() - a routine that puts a hex byte in the transmit buffer
38 --     UART_direct_hex_put - a routine that puts a hex byte directly to the UART port
39 --
40 -- NEW TO VERSION 2.0.1:
41 --     UART_low_nibble_direct_put() - puts the low nibble of a byte in hex directly
42 --                                     (no ram buffer) to the UART.
43 --     UART_direct_word_hex_put() - puts a word in hex directly to the UART
44 -- Copyright (c) 2015 Tim Scherr All rights reserved.
45 --
46 */
47
48
49
50 /*****/
51 /* Configurations */
52 /*****/
53 /*
54
55 */
56
57 #include <stdio.h>
58 #include "shared.h"
59 #include "MKL25Z4.h"
60
61 // NOTE: UART0 is also called UARTLP in mbed
62 #define OERR (UART0->S1 & UARTLP_S1_OR_MASK) // Overrun Error bit
63 #define CREN (UART0->C2 & UARTLP_C2_RE_MASK) // continuous receive enable bit
64 #define RCREG UART0->D // Receive Data Register
65 #define FERR (UART0->S1 & UARTLP_S1_FE_MASK) // Framing Error bit
66 #define RCIF (UART0->S1 & UARTLP_S1_RDRF_MASK) // Receive Interrupt Flag (full)
67 #define TXIF (UART0->S1 & UARTLP_S1_TDRE_MASK) // Transmit Interrupt Flag (empty)
68 #define TXREG UART0->D // Transmit Data Register
69 #define TRMT (UART0->S1 & UARTLP_S1_TC_MASK) // Transmit Shift Register Empty
70
71 /*****/

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72      *          Start of code          *
73      *****/
74
75      UCHAR error_count = 0; //<! variable for error counter
76      *****/
77      /// \fn void serial(void)
78      /// @brief function polls the serial port for Rx or Tx data
79      *****/
80      void serial(void)          // The serial function polls the serial port for
81                                // received data or data to transmit
82      {
83                                // deals with error handling first
84      if ( OERR )                // if an overrun error, clear it and continue.
85      {
86          error_count++;
87                                // resets and sets continous receive enable bit
88          UART0->C2 = UART0->C2 & (!UARTLP_C2_RE_MASK);
89          UART0->C2 = UART0->C2 | UARTLP_C2_RE_MASK;
90      }
91
92      if ( FERR){                // if a framing error, read bad byte, clear it and continue.
93          error_count++;
94          RCREG;                 // This will also clear RCIF if only one byte has been
95                                // received since the last int, which is our assumption.
96
97                                // resets and sets continous receive enable bit
98          UART0->C2 = UART0->C2 & (!UARTLP_C2_RE_MASK);
99          UART0->C2 = UART0->C2 | UARTLP_C2_RE_MASK;
100      }
101      else                        // else if no frame error,
102      {
103          if ( RCIF )            // Check if we have received a byte
104          {                      // Read byte to enable reception of more bytes
105                                // For PIC, deb
106                                //RCIF automatically cleared when RCREG is read
107                                // Also true of Freescale KL25Z
108                                *rx_in_ptr++ = RCREG;          /* get received character */
109                                if( rx_in_ptr >= RX_BUF_SIZE + rx_buf )
110                                {
111                                    rx_in_ptr = rx_buf;          /* if at end of buffer, circles rx_in_ptr
112                                                                    to top of buffer */
113                                }
114          }
115      }
116
117      if (TXIF)                  // Check if transmit buffer empty
118      {
119          if ((tx_in_ptr != tx_out_ptr) && (display_mode != QUIET))
120          {
121              TXREG = *tx_out_ptr++;          /* send next char */
122              if( tx_out_ptr >= TX_BUF_SIZE + tx_buf )
123              {
124                  tx_out_ptr = tx_buf;          /* 0 <= tx_out_idx < TX_BUF_SIZE */
125                  tx_in_progress = YES;          /* flag needed to start up after idle */
126              }
127          }
128          else
129          {
130              tx_in_progress = NO;              /* no more to send */
131          }
132      }
133      // serial_count++;          // increment serial counter, for debugging only
134      serial_flag = 1;           // and set flag
135
136      *****/
137      /// @brief UART_direct_msg_put puts a null terminated string directly
138      /// (no ram buffer) to the UART in ASCII format.
139      *****/
140      void UART_direct_msg_put(const char *str)
141      {
142          while( *str != '\0' )

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143     {
144         TXREG = *str++;
145         while( TXIF == 0 || TRMT == 0 ); // waits here for UART transmit buffer
146     }
147 }
148
149 /*****
150 /// @brief UART_direct_msg_put puts a character directly
151 /// (no ram buffer) to the UART in ASCII format.
152 *****/
153 void UART_direct_put(UCHAR chr)
154 {
155     TXREG = chr;
156     while( TXIF == 0 )
157     {
158         // __clear_watchdog_timer();
159     }
160 }
161
162 /*****
163 /// \fn UART_put(UCHAR)
164 /// @brief Puts a byte into the transmit buffer
165 ///
166 /// Puts a byte, to the transmit buffer at the location
167 /// pointed to by tx_in_idx. The pointer is incremented circularly as described
168 /// previously. If the transmit buffer should wrap around (should be designed
169 /// not to happen), data will be lost. The serial interrupt must be temporarily
170 /// disabled since it reads tx_in_idx and this routine updates tx_in_idx which is
171 /// a 16 bit value.
172 *****/
173 void UART_put(UCHAR c)
174 {
175     *tx_in_ptr++ = c; /* save character to transmit buffer */
176     if( tx_in_ptr >= TX_BUF_SIZE + tx_buf )
177         tx_in_ptr = tx_buf; /* 0 <= tx_in_idx < TX_BUF_SIZE */
178 }
179
180 /*****
181 /// \fn UART_get
182 /// @brief Gets the next byte available in the RX buffer.
183
184 /// UART_get gets the next byte if one is available from the receive
185 /// buffer at the location pointed to by rx_out_idx. The pointer is circularly
186 /// incremented and the byte is returned in R7. Should no byte be available the
187 /// function will wait until one is available. There is no need to disable the
188 /// serial interrupt which modifies rx_in_idx since the function is looking for a
189 /// compare only between rx_in_idx & rx_out_idx.
190 *****/
191 UCHAR UART_get(void)
192 {
193     UCHAR c;
194     while( rx_in_ptr == rx_out_ptr ); /* wait for a received character,
195                                     indicated */
196                                     // when pointers are different
197                                     // this could be an infinite loop, but
198                                     // is not because of UART_input check
199     c = *rx_out_ptr++;
200     if( rx_out_ptr >= RX_BUF_SIZE + rx_buf ) // if at end of buffer
201     {
202         rx_out_ptr = rx_buf; /* 0 <= rx_out_idx < RX_BUF_SIZE */
203                             // return byte from beginning of buffer
204     }
205     return(c);
206 }
207
208 /*****
209 /// @brief Checks if characters are sitting in the UART input buffer.
210
211 ///
212 /// UART_input returns a 1 if 1 or more receive byte(s) is(are)
213 /// available and a 0 if the receive buffer rx_buf is empty. There is no need to

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214  /// disable the serial interrupt which modifies rx_in_idx since function is
215  /// looking for a compare only between rx_in_idx & rx_out_idx.
216  /*****
217  UCHAR UART_input(void)
218  {
219      if( rx_in_ptr == rx_out_ptr )
220          return(0);                      /* no characters in receive buffer */
221      else
222          return(1);                      /* 1 or more receive characters ready */
223  }
224
225  /****
226  /// @brief UART_msg_put puts a null terminated string through the transmit
227  /// buffer to the UART port in ASCII format.
228  /****
229  void UART_msg_put(const char *str)
230  {
231      while( *str != '\0' )
232      {
233          *tx_in_ptr++ = *str++;          /* save character to transmit buffer */
234          if( tx_in_ptr >= TX_BUF_SIZE + tx_buf)
235              tx_in_ptr = tx_buf;        /* 0 <= tx_in_idx < TX_BUF_SIZE */
236      }
237  }
238
239  /****
240  /// @brief HEX_TO_ASCII Function
241  /// Function takes a single hex character (0 thru Fh) and converts to ASCII.
242  /****
243  UCHAR hex_to_asc(UCHAR c)
244  {
245      if( c <= 9 )
246          return( c + 0x30 );
247      return( ((c & 0x0f) + 0x37) );    /* add 37h */
248  }
249
250  /****
251  /// @brief Takes a single ASCII character and converts to hex.
252  /****
253  UCHAR asc_to_hex(UCHAR c)
254  {
255      if( c <= '9' )
256          return( c - 0x30 );
257      return( (c & 0xdf) - 0x37 );    /* clear bit 5 (lower case) & subtract 37h */
258  }
259
260
261  /****
262  /// @brief UART_low_nibble_put puts the low nibble of a byte in hex directly
263  /// (no ram buffer) to the UART.
264  /****
265  void UART_low_nibble_direct_put(UCHAR c)
266  {
267      TXREG = hex_to_asc( c & 0x0f );
268      while( TXIF == 0 );
269  }
270
271  /****
272  /// @brief UART_high_nibble_put puts the high nibble of a byte in h
273  /// UART port. (currently commented out)
274  /****
275  //void UART_high_nibble_put(unsigned char c)
276  //{
277  //    UART_put( hex_to_asc( (c>>4) & 0x0f ));
278  //}
279
280  /****
281  *! \brief UART_hex_put puts 1 byte in hex through the transmit buffer to
282  * the UART port.
283  ****
284  void UART_hex_put(unsigned char c)

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285 {
286     UART_put( hex_to_asc( (c>>4) & 0x0f )); // could eliminate & as >> of UCHAR
287                                           // by definition clears upper bits.
288     UART_put( hex_to_asc( c & 0x0f ));
289 }
290
291 /*****
292 /// @brief UART_direct_hex_put puts 1 byte in hex directly (no ram buffer)
293 /// to the UART.
294 *****/
295 void UART_direct_hex_put(unsigned char c)
296 {
297     TXREG = hex_to_asc( (c>>4) & 0x0f );
298     while( TXIF == 0 )
299     {
300         // __clear_watchdog_timer();
301     }
302     TXREG = hex_to_asc( c & 0x0f );
303     while( TXIF == 0 )
304     {
305         // __clear_watchdog_timer();
306     }
307 }
308 /*****
309 /// @brief UART_direct_hex_put puts 4 bytes in hex directly (no ram buffer)
310 /// to the UART.
311 *****/
312 void UART_direct_word_hex_put(uint32_t word)
313 {
314     UART_direct_hex_put((word>>24)&0xFF);
315     UART_direct_hex_put((word>>16)&0xFF);
316     UART_direct_hex_put((word>>8)&0xFF);
317     UART_direct_hex_put(word&0xFF);
318 }
319
```